

Introduction to VEX Hardware

By MathWorks Student Competition team





The Hardware – VEX EDR V5 and Cortex

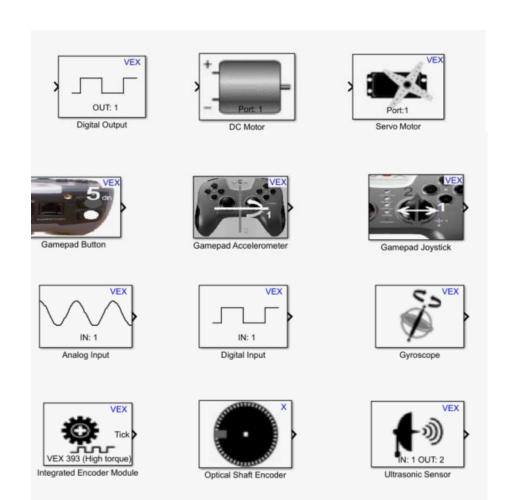
- VEX Based
 Microcontroller (Brain)
- Gamepad Controller
- Actuators (Motors)
- Sensors

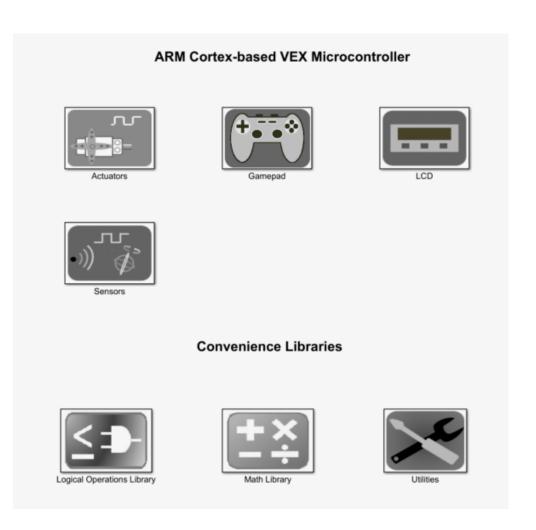




Simulink Library

Blocks for all supported functionality

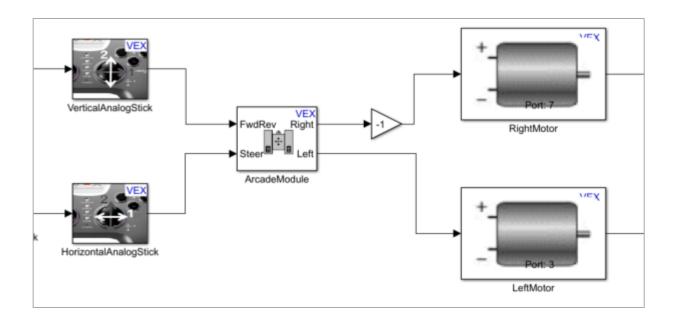




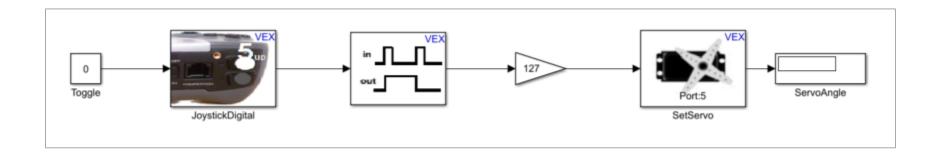


Examples using VEX Blocks

Arcade Control



Single Button Motor Control

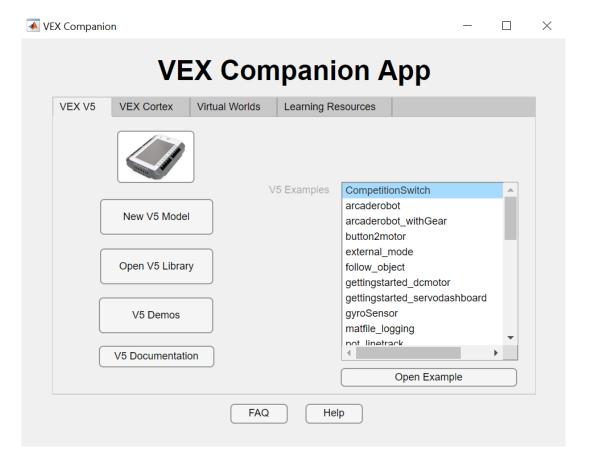




VEX Companion App

- All Resources in one place
- Install after support package installation
- Extensive list of examples









MATLAB and Simulink Robotics Arena



- Video tutorials
- Facebook group
 - Robotics and product news
 - Forum
- Support
 - roboticsarena@mathworks.com

Most Recent Videos



MATLAB and Simulink PASS
Competitions Hub:
Introduction to Stateflow for
Student Competition Teams



MATLAB and Simulink PASS Competitions Hub: Simulink Quick Start for Student Competition Teams



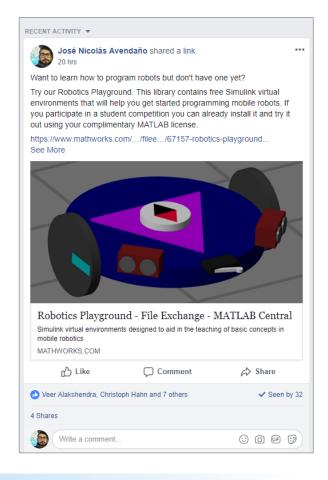
MATLAB and Simulink PASS Competitions Hub: Using MATLAB and Simulink with VEX ARM Cortex Support Package



MATLAB and Simulink PASS Competitions Hub: Installing a Support Package Using Add-On Explorer



MATLAB and Simulink PASS
Competitions Hub: Path
Navigation Using the VEX
Robotics Motor Encoders





Resources – FREE Training on Mobile Robotics

Student Competition: Mobile Robotics Training

The training materials in this video series will enable your team to get started with designing and simulating common mobile robotics algorithms in MATLAB and Simulink. You will learn how to design open and closed loop feedback control systems for your robot to perform tasks like dead reckoning, line following and obstacle detection. You will also understand how to use the custom simulation tools to test your algorithms within Simulink before deploying them to an actual robot.

- Part 1: Controlling Robot Motion
- Part 2: Using PID Controllers
- · Part 3: Line Following Algorithms
- Part 4: Obstacle Detection Algorithms
- Part 5: Path Navigation
- » See detailed outline



Student Competition: Mobile Robotics
Training: Overview



Resources – BEST Robotics

MathWorks Competition Webpage
 https://mathworks.com/best-robotics



BEST Robotics

BEST Robotics is an annual middle-school and high-school competition that engages students in the study of engineering, science, and technology as they create remotely operated machines. Students build a robot from scratch and program the VEX ARM Cortex Microcontroller for the BEST Robotics mission. Applying Model-Based Design with MATLAB and Simulink lets your team efficiently design and build a functioning robot for the competition.

Student Home MATLAB Student + Examples Student Competitions + Books Hardware Support

MathWorks presents the Simulink Design Award at the BEST Robotics Regional Championships to the teams that make the best use of MATLAB and Simulink to program their robots.

- » View past winning videos
- » Apply for the BEST Robotics Simulink Design Award



BEST Robotics Kickoff: Simulink Support for VEX Cortex Microcontroller

MathWorks provides BEST Robotics teams complimentary access to MATLAB and Simulinik, as well as training and technical support. Teams can use MATLAB and Simulinik, on a PC or a Mac, to design, test, and download the control algorithms to your BEST r...







Simulink Design Award

- Award prizes include \$1000 dollars for your team! BEST Robotics
- Apply: http://www.bestinc.org/b_simulink_award.php

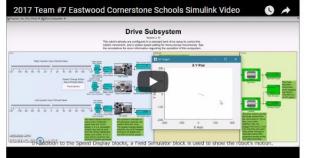
2017 Winners



Texas BEST Regionals

Ereckson Middle School CoCo BEST

This model shows a Stateflow chart that implements custom joystick controls for the robot. The team also implemented a redundant firing mechanism with two buttons to prevent unwanted firing.



South's BEST Regionals

Eastwood/Cornerstone Schools War Eagle BEST

This team implemented Simulink simulations with two different inputs using dashboard buttons and a gamepad, as well as dynamic controls to change between left-handed and right-handed drivers seamlessly.



Frontier Trails BEST Regionals

Council Grove High School Kansas BEST

The Simulink model takes advantage of dead bands to improve the drivability of their robot. The team was also able to verify their logic with simulations before programming the robot hardware.