Learning Hierarchical Priors in VAEs

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Abstract

We address the problem of learning informative latent representations in the context of variational autoencoders. To do this we

- use a hierarchical prior to avoid the over-regularisation resulting from a standard normal prior distribution.
- formulate the learning problem as a constrained optimisation problem.
- introduce a graph-based interpolation method to evaluate the learned latent representation.

Variational Autoencoders as a Constrained Optimisation Problem

Rezende and Viola (2018) reformulate the VAE objective as the Lagrangian

$$\mathcal{L}(\theta,\phi;\lambda) \equiv \mathbb{E}_{p_\mathcal{D}(\mathbf{x})}\Big[\mathrm{KL}\big(q_\phi(\mathbf{z}|\mathbf{x})\|\, p_0(\mathbf{z})\big) + \lambda\big(\mathbb{E}_{q_\phi(\mathbf{z}|\mathbf{x})}[\mathcal{C}_\theta(\mathbf{x},\mathbf{z})] - \kappa^2\big)\Big]$$

of a constrained optimisation problem

$$\min_\theta \max_\lambda \min_\phi \ \mathcal{L}(\theta,\phi;\lambda) \quad \text{s.t.} \quad \lambda \geq 0.$$

$\mathcal{C}_\theta(\mathbf{x},\mathbf{z})$ is defined as the reconstruction-error-related term in $-\log p_\theta(\mathbf{x}|\mathbf{z})$. Thus, $\min_\theta \mathcal{L}$ and $\max_\lambda \min_\phi \mathcal{L}$ can be interpreted as M- and E-step, respectively, of the original EM-algorithm for training VAEs. Optimisation is performed by a quasi-gradient ascent/descent algorithm (GECO):

$$\lambda_t = \lambda_{t-1} \cdot \exp\big(\nu \cdot (\mathcal{C}_t - \kappa^2)\big) \quad \text{and} \quad (\theta_t,\phi_t) = (\theta_{t-1},\phi_{t-1}) - \eta_t\, \partial_{(\theta,\phi)} \mathcal{L},$$

where $\Delta\lambda_t \cdot \partial_\lambda \mathcal{L} \geq 0$ and ν the update's learning rate. We obtain the ELBO iff $\lambda = 1$; or if $0 \leq \lambda < 1$, a lower bound on the ELBO.

Hierarchical Priors for Learning Informative Latent Representations

The optimal empirical Bayes prior is the aggregated posterior distribution $p^*(\mathbf{z}) = \mathbb{E}_{p_\mathcal{D}(\mathbf{x})}\big[q_\phi(\mathbf{z}|\mathbf{x})\big]$. In order to approximate it, we use a hierarchical prior/two-layer stochastic model

$$p_0(\mathbf{z}) \equiv p_\Theta(\mathbf{z}) = \int p_\Theta(\mathbf{z}|\zeta)\, p(\zeta)\, \mathrm{d}\zeta$$

and apply an importance-weighted bound:

$$\begin{aligned}&\mathbb{E}_{p_\mathcal{D}(\mathbf{x})}\mathrm{KL}\big(q_\phi(\mathbf{z}|\mathbf{x})\|\, p_\Theta(\mathbf{z})\big) \leq \mathcal{F}(\phi,\Theta,\Phi)\\ &\equiv \mathbb{E}_{p_\mathcal{D}(\mathbf{x})}\mathbb{E}_{q_\phi(\mathbf{z}|\mathbf{x})}\Big[\log q_\phi(\mathbf{z}|\mathbf{x}) - \mathbb{E}_{\zeta_{1:K}\sim q_\Phi(\zeta|\mathbf{z})}\Big[\log \frac{1}{K}\sum_{k=1}^{K} \frac{p_\Theta(\mathbf{z},\zeta_k)}{q_\Phi(\zeta_k|\mathbf{z})}\Big]\Big].\end{aligned}$$

This introduces a new objective

$$\mathcal{L}_{\mathrm{VHP}}(\theta,\phi,\Theta,\Phi;\lambda) \equiv \mathcal{F}(\phi,\Theta,\Phi) + \lambda\big(\mathbb{E}_{p_\mathcal{D}(\mathbf{x})}\mathbb{E}_{q_\phi(\mathbf{z}|\mathbf{x})}[\mathcal{C}_\theta(\mathbf{x},\mathbf{z})] - \kappa^2\big).$$

The constrained optimsation problem is formulated as

$$\min_{\Theta,\Phi}\min_\theta\max_\lambda\min_\phi \ \mathcal{L}_{\mathrm{VHP}}(\theta,\phi,\Theta,\Phi;\lambda) \quad \text{s.t.} \quad \lambda \geq 0$$

and leads to the following double-loop method: (i) update the upper bound via (Θ,Ψ); (ii) solve the constrained optimisation problem w.r.t. (θ,λ,ψ).

Optimisation: to be in line with previous literature and to facilitate the comparison with the original VAE framework, we use the β-parameterisation

$$\beta = \frac{1}{\lambda}.$$

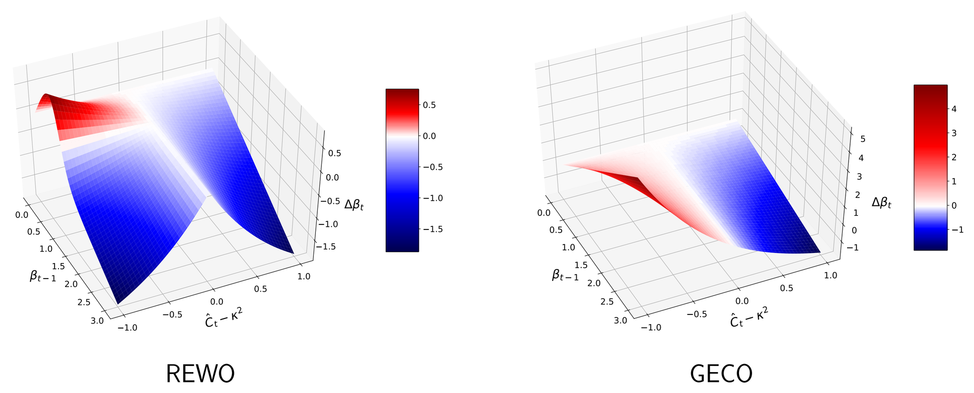
We want to obtain a tight lower bound on the log-likelihood This holds when $\beta = 1$ (ELBO). To guarantee that the optimisation process finishes at $\beta = 1$—provided the constraint is fulfilled—we propose the following update:

$$\beta_t = \beta_{t-1} \cdot \exp\big[\nu \cdot f_\beta(\beta_{t-1}, \mathcal{C}_t - \kappa^2; \tau) \cdot (\mathcal{C}_t - \kappa^2)\big],$$

where

$$f_\beta(\beta,\delta;\tau) = \big(1 - H(\delta)\big) \cdot \tanh\big(\tau \cdot (\beta - 1)\big) - H(\delta).$$

Here, H is the Heaviside function and τ a slope parameter.



Comparison of β-update schemes: $\Delta\beta_t = \beta_t - \beta_{t-1}$ as a function of β_{t-1} and $\mathcal{C}_t - \kappa^2$ for $\nu = 1$ and $\tau = 3$.

We experienced that the double-loop method behaves as a layer-wise pre-training. Thus, we implemented this pre-training in form of an optimisation algorithm (REWO):

- Initial phase: we start with $\beta \ll 1$ to enforce a reconstruction optimisation and keep β, Θ, Φ constant until $\mathcal{C}_t < \kappa^2$.
- Main phase: after $\mathcal{C}_t < \kappa^2$ is fulfilled, we optimise $\Theta, \Phi, \theta, \phi$ jointly, and update β.

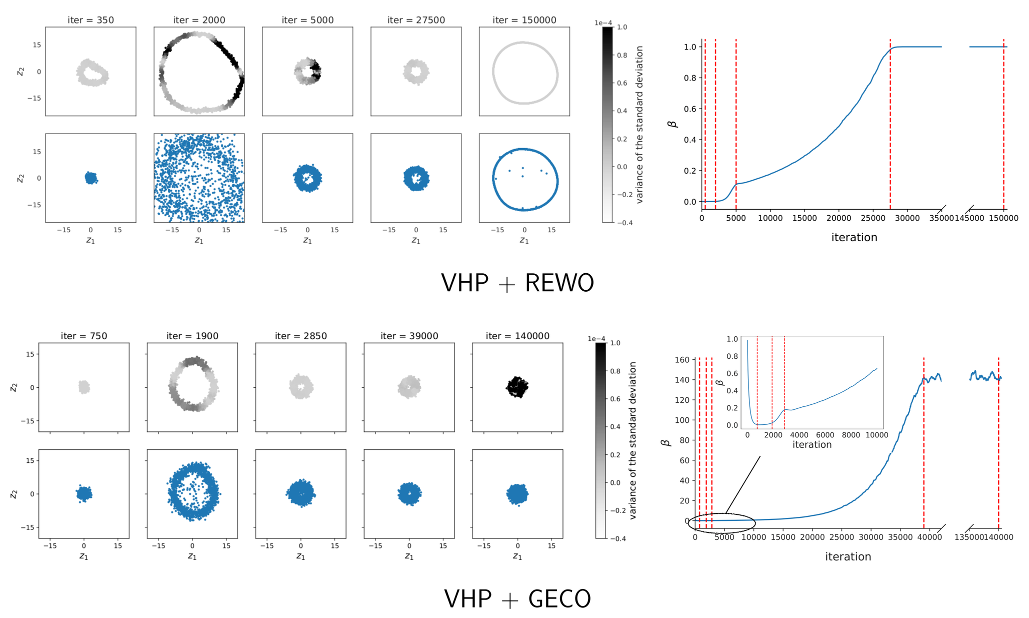
Graph-Based Interpolation

The nodes of the graph $\mathbf{Z} = \{\mathbf{z}_1, \ldots, \mathbf{z}_N\}$ are obtained by randomly sampling N samples from the prior distribution:

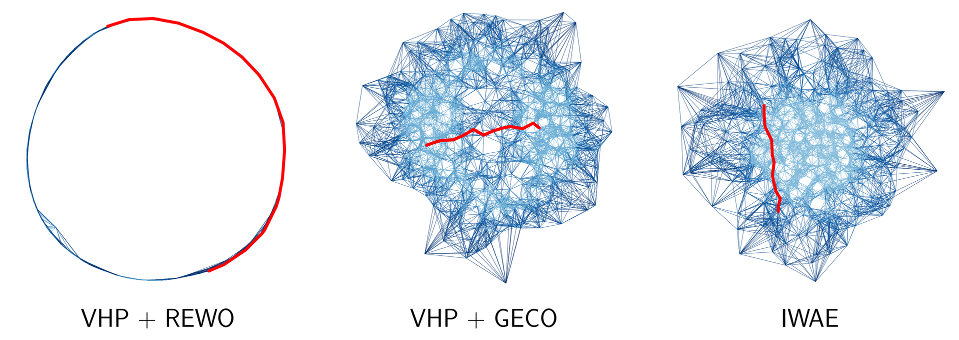
$$\mathbf{z}_n, \zeta_n \sim p_\Theta(\mathbf{z}|\zeta)\, p(\zeta), \quad n = 1, \ldots, N.$$

The graph is constructed by connecting each node by undirected edges to its k-nearest neighbours. The edge weights are the Euclidean distances (latent space) between the node pairs.

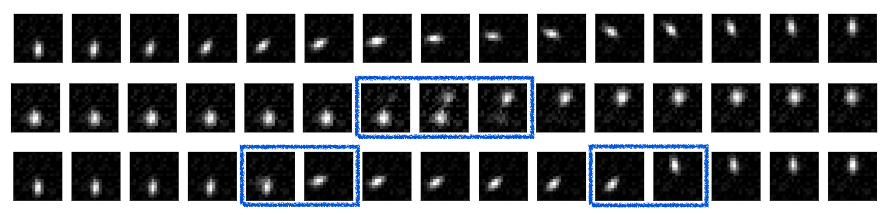
Artificial Pendulum



Latent representation of the pendulum data at different iteration steps when optimising $\mathcal{L}_{\mathrm{VHP}}(\theta,\phi,\Theta,\Phi;\beta)$ with REWO and GECO, respectively. The top row shows the approximate posterior; the greyscale encodes the variance of its standard deviation. The bottom row shows the hierarchical prior.



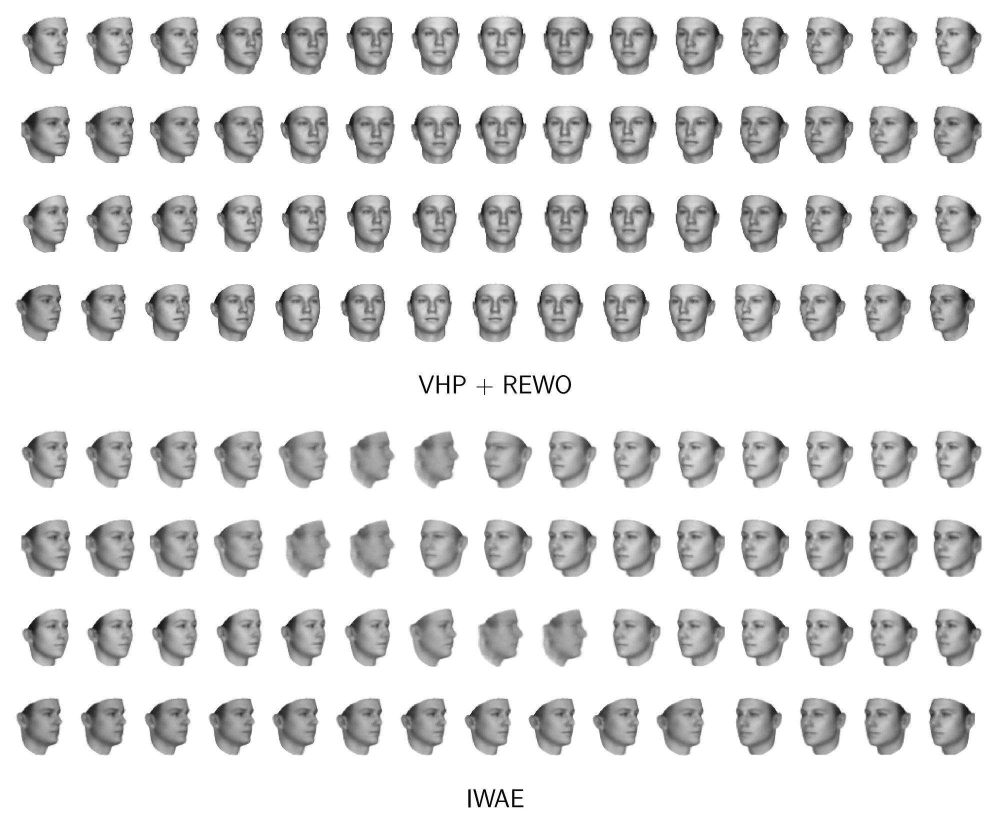
Graph-based interpolation of the pendulum movement. The graph is based on the respective prior. The red curves depict the interpolations, the bluescale indicates the edge weight.



top: VHP + REWO, middle: VHP + GECO, bottom: IWAE

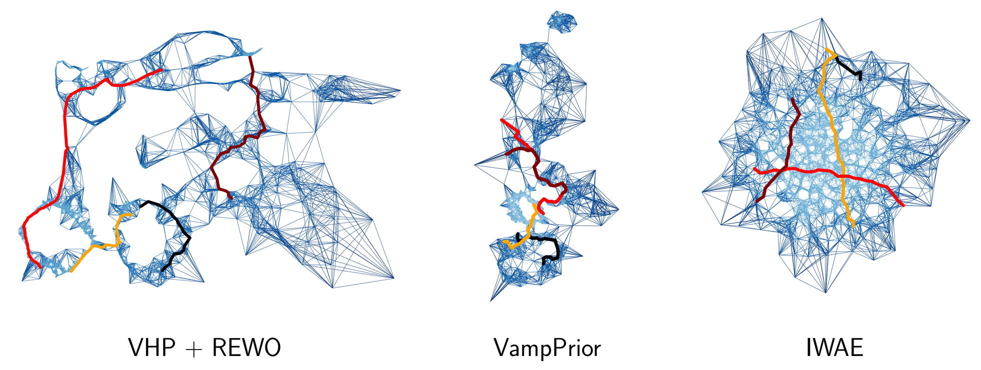
Pendulum reconstructions of the graph-based interpolations (red curve). Discontinuities are marked by blue boxes.

3D Faces

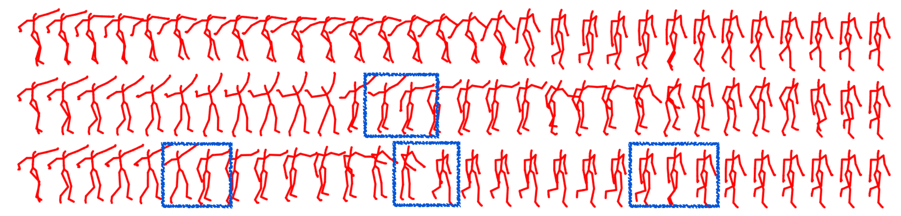


Graph-based interpolations along the learned 32-dimensional latent manifold. The graph is based on samples from the respective prior distribution.

Human Motion

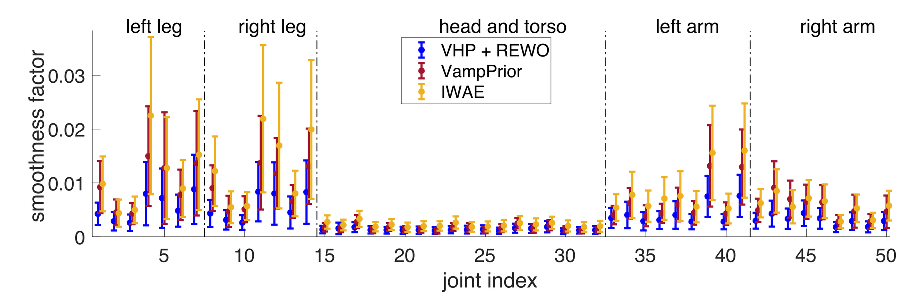


Graph-based interpolation of human motions. The graphs are based on the (learned) prior distributions. The bluescale indicates the edge weight. The coloured lines represent four interpolated movements.



top: VHP + REWO, middle: VampPrior, bottom: IWAE

Human-movement reconstructions of the graph-based interpolations (red curve). Discontinuities are marked by blue boxes.



Smoothness measure of the human-movement interpolations. For each joint, the mean and standard deviation of the smoothness factor are displayed. Smaller values correspond to smoother movements.

MNIST, Fashion-MNIST, & OMNIGLOT

Negative test log-likelihood estimated with 5,000 importance samples

	Dynamic MNIST	Static MNIST	Fashion-MNIST	OMNIGLOT
VHP + REWO	78.88	82.74	225.37	101.78
VHP + GECO	95.01	96.32	234.73	108.97
VampPrior	80.42	84.02	232.78	101.97
IWAE (L=1)	81.36	84.46	226.83	101.57
IWAE (L=2)	80.66	82.83	225.39	101.83

References

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