view_frames Result

Recorded at time: 1704674893.437

panda_link0

Broadcaster: /robot_state_publisher
Average rate: 30.202 Hz
Most recent transform: 1704674893.406 (0.031 sec old)
Buffer length: 4.967 sec

camera_link

Broadcaster: /camera/realsense2_camera_manager
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1704674893.437 sec old)
Buffer length: 0.000 sec

Broadcaster: /camera/realsense2_camera_manager
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1704674893.437 sec old)
Buffer length: 0.000 sec

Broadcaster: /camera/realsense2_camera_manager
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1704674893.437 sec old)
Buffer length: 0.000 sec

panda_link1

camera_depth_frame

camera_color_frame

camera_aligned_depth_to_color_frame

Broadcaster: /robot_state_publisher
Average rate: 30.202 Hz
Most recent transform: 1704674893.406 (0.031 sec old)
Buffer length: 4.967 sec

Broadcaster: /camera/realsense2_camera_manager
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1704674893.437 sec old)
Buffer length: 0.000 sec

Broadcaster: /camera/realsense2_camera_manager
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1704674893.437 sec old)
Buffer length: 0.000 sec

panda_link2

camera_depth_optical_frame

camera_color_optical_frame

Broadcaster: /robot_state_publisher
Average rate: 30.202 Hz
Most recent transform: 1704674893.406 (0.031 sec old)
Buffer length: 4.967 sec

panda_link3

Broadcaster: /robot_state_publisher
Average rate: 30.202 Hz
Most recent transform: 1704674893.406 (0.031 sec old)
Buffer length: 4.967 sec

panda_link4

Broadcaster: /robot_state_publisher
Average rate: 30.202 Hz
Most recent transform: 1704674893.406 (0.031 sec old)
Buffer length: 4.967 sec

panda_link5

Broadcaster: /robot_state_publisher
Average rate: 30.202 Hz
Most recent transform: 1704674893.406 (0.031 sec old)
Buffer length: 4.967 sec

panda_link6

Broadcaster: /robot_state_publisher
Average rate: 30.202 Hz
Most recent transform: 1704674893.406 (0.031 sec old)
Buffer length: 4.967 sec

panda_link7

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1704674893.437 sec old)
Buffer length: 0.000 sec

panda_link8

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1704674893.437 sec old)
Buffer length: 0.000 sec

Broadcaster: /franka_control
Average rate: 29.620 Hz
Most recent transform: 1704674893.417 (0.020 sec old)
Buffer length: 4.963 sec

panda_hand

panda_EE

Broadcaster: /robot_state_publisher
Average rate: 30.202 Hz
Most recent transform: 1704674893.406 (0.031 sec old)
Buffer length: 4.967 sec

Broadcaster: /robot_state_publisher
Average rate: 30.202 Hz
Most recent transform: 1704674893.406 (0.031 sec old)
Buffer length: 4.967 sec

Broadcaster: /franka_control
Average rate: 29.620 Hz
Most recent transform: 1704674893.417 (0.020 sec old)
Buffer length: 4.963 sec

panda_leftfinger

panda_rightfinger

panda_K