Demonstrating the Equivalence and Efficiency of the Nested Model Compared to a Single GE Model

Introduction

This document demonstrates that:

- The nested model is an equivalent and efficient alternative to a single n-period GE model with embedded climate policy
- 2. Solving the entire problem within a single GE model is computationally infeasible

Overview of the Two Approaches

1. Nested Model (Current Approach)

- Outer Loop: Policy maker uses MCTS to optimize climate policy over n periods
- Inner Loop: Two-period GE model solves for equilibrium at each node
- State Transitions: States update based on GE outcomes, damages, and learning

2. Single GE Model with Embedded Climate Policy

- Objective Function: Incorporates policy maker's objective directly over n periods
- Agents and Firms: Optimize over entire n-period horizon with endogenous policy
- Equilibrium Concept: DSGE model with embedded policy maker optimization

Theoretical Equivalence

Dynamic Programming Framework

Both approaches solve:

$$\max_{\{a_t\}} \mathbb{E}\left[\sum_{t=0}^n eta^t \left(u(S_t) - D(E_t, heta_t) Y_t
ight)
ight]$$

subject to:

$$S_{t+1} = f(S_t, a_t, \epsilon_t)$$

Both models satisfy the Bellman equation, ensuring theoretical equivalence.

Computational Efficiency Analysis

Dimensionality Comparison

Nested Model

• State Space: Managed efficiently by MCTS

Action Space: Explored selectively through MCTS

Computation: Solves smaller problems sequentially

Single GE Model

• State Space: All variables over n periods

Action Space: Combined space of all controls

• Computation: Must solve everything simultaneously

Mathematical Complexity

Let:

- m: Economic variables per period
- k: Number of agents
- a: Actions per agent per period

Single GE model complexity:

Total Variables =
$$n \times (k \times m + \text{Policy Variables})$$

Computational Complexity = $O(a^{kn})$

Demonstrating Unsolvability of Single GE Model

Theoretical Barriers

1. Fixed-Point Problems

- High-dimensional space proportional to n
- Nonlinear dynamics make finding contractions difficult

2. Expectations Formation

- Agents must form expectations over entire horizon
- Interdependent optimization problems due to endogenous policy

3. Computational Limits

- Bellman's curse of dimensionality
- Nonlinear equation systems grow exponentially

Single GE Model Formulation

Attempts to solve:

$$\max_{\{C_t, L_t, I_t, K_t^i, heta_t^i, au_t\}_{t=0}^n} \mathbb{E} \left[\sum_{t=0}^n eta^t \left(rac{C_t^{1-\sigma}}{1-\sigma} - \chi rac{L_t^{1+
u}}{1+
u} - D(E_t, heta_t) Y_t
ight)
ight]$$

Subject to:

- Economic constraints
- Policy constraints
- Expectations formation
- Market clearing conditions

Key Infeasibility Factors

1. High Dimensionality

- · Variables and constraints grow exponentially with n
- Non-convexities from technology choices and adjustment costs

2. Interdependencies

- Agents' expectations depend on future policy
- · Policy depends on agents' behavior

3. Computational Resources

- · Memory and processing requirements exceed practical limits
- No known algorithms for efficient solution

Advantages of Nested Model

1. Problem Decomposition

- Separates policy optimization from equilibrium computation
- Maintains theoretical optimality through Bellman equation

2. Computational Efficiency

- MCTS scales logarithmically with simulations
- · Parallel processing possible
- · Results can be cached and reused

Conclusion

The nested model:

- Is theoretically equivalent to the single GE model
- Provides the only computationally feasible solution approach
- · Maintains optimality while managing complexity

The single GE model is demonstrably unsolvable due to:

- Computational complexity
- High-dimensional state space
- Interdependent expectations