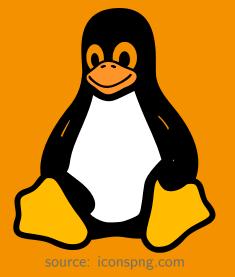




Prof. Dr. Florian Künzner

Technical University of Applied Sciences Rosenheim, Computer Science





The lecture is based on the work and the documents of Prof. Dr. Ludwig Frank

Goal



Goal



Computer Science





- Scheduling theory and terms
- Scheduling strategies
- Scheduling on Linux





Scheduling

Scheduling is a technique to distribute computing resources like processor time, bandwidth, memory, or device I/O to the processes on a computer system.



Scheduler

The **scheduler** is such a **program** that **distributes** the **resources** to the processes.

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Scheduling time frame



Scheduling time frame

Long term scheduling

Determines which processes (jobs) are admitted to the system for processing.



Scheduling time frame

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Mid term scheduling

Allocation of bandwidth, memory, or device I/O to a process/thread.



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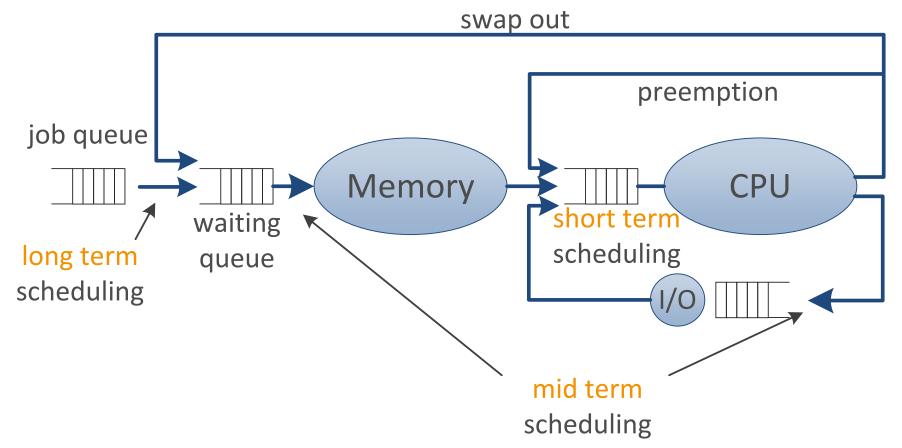
Short term scheduling

Allocation of a process/thread to a CPU core.



Scheduling on Linux

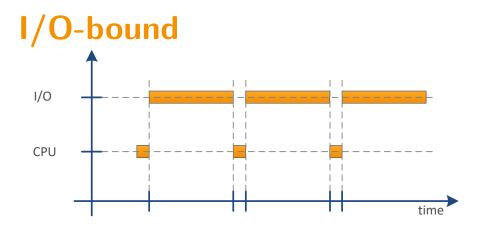
Scheduling time frame overview



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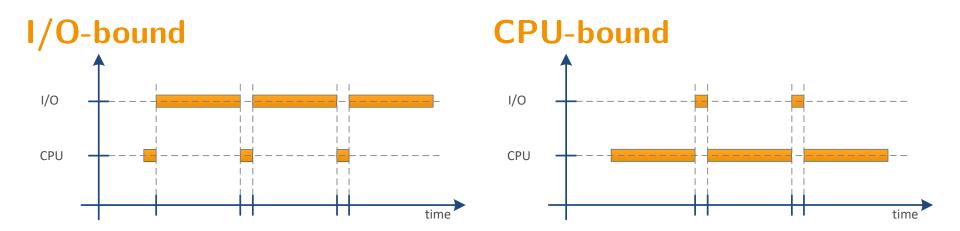
I/O-bound vs CPU-bound



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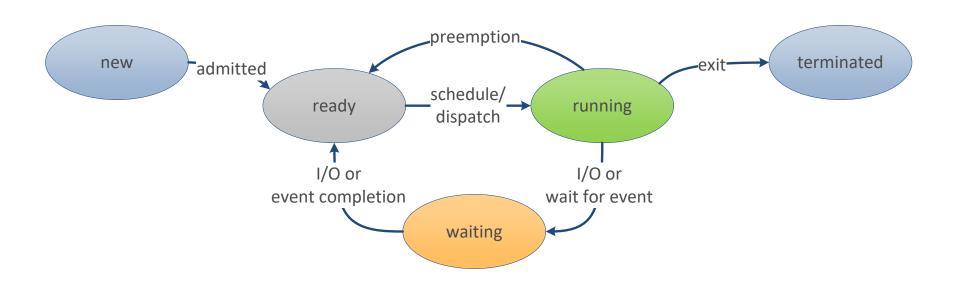
I/O-bound vs CPU-bound



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Process states

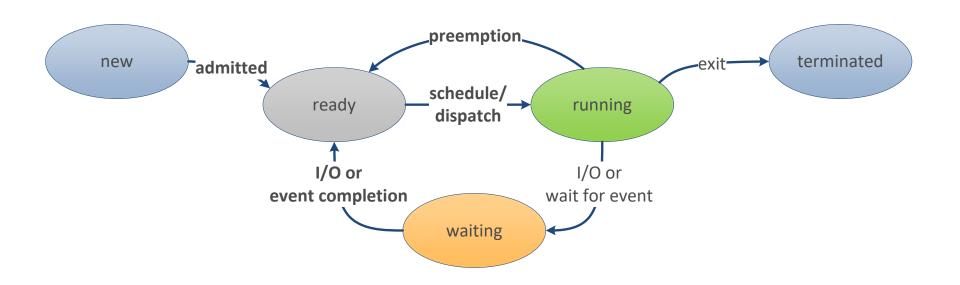




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Process states





Scheduling terms

Term
CPU usage

Description

CPU usage up to 100% if possible.

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Scheduling terms

Term CPU usage throughput

Description

CPU usage up to 100% if possible.

The number of completed processes in a time frame. Should be as high as possible.



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Scheduling terms

Term	Description
CPU usage	CPU usage up to 100% if possible.
throughput	The number of completed processes in a time frame. Should
	be as high as possible.
arrival time	The point in time at which a process arrives for execution in
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CPU usage CPU usage up to 100% if possible.

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waiting time The time a process has to wait until it can run.



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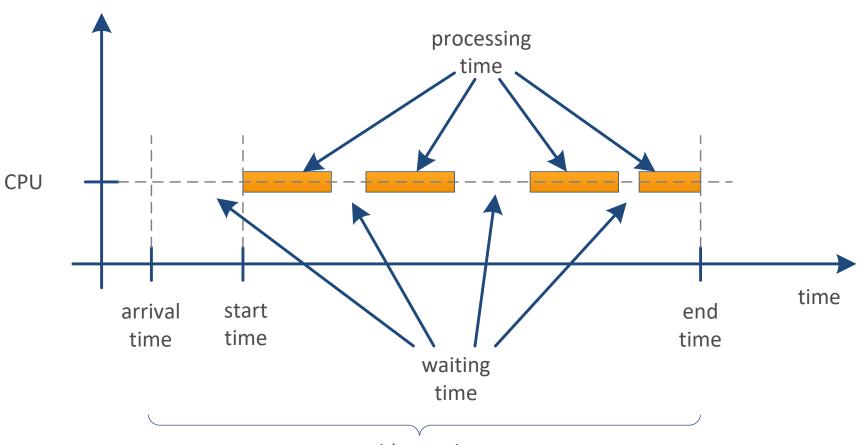
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waiting time	The time a process has to wait until it can run.
residence time	The total time a process takes to finish ($=$ processing time $+$
	waiting time).

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Time aspects



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System categories

System type

Description

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System categories

System type Job processing system

Description

Job processing system Typically users submit jobs (programs with its parameters) to a system. The job scheduler decides when the job starts.

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System categories

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With an interactive system, the users work directly: a PC (terminal, desktop), smartphone, ...

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Real-time system

A real-time system usually observes and controls a physical process in the real world. It must guarantee that it reacts fast enough.

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Scheduling Goals

All systems

fairness - Every process can run on the CPU.

policy enforcement The system's policy is enforced.

balance - All parts of the system are busy.



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proportionality - Consider the requirements for all users

Real-time system

meet deadline - Meet always the deadline of all processes.

predictability - Always guarantee the same periodic execution (small jitter)

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Summary

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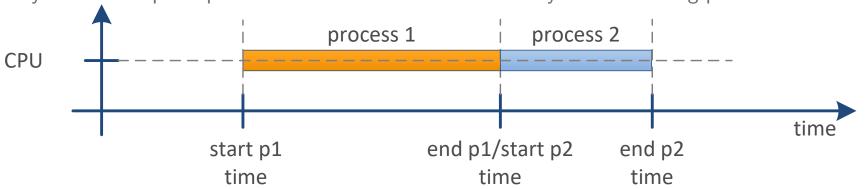
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Preemption

Non-preemptive system

A system is non-preemptive if the CPU cannot be taken away from a running process.



Preemptive system

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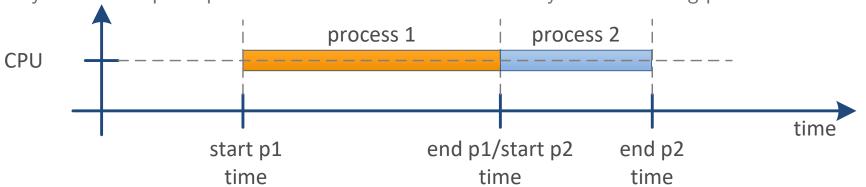
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Preemption

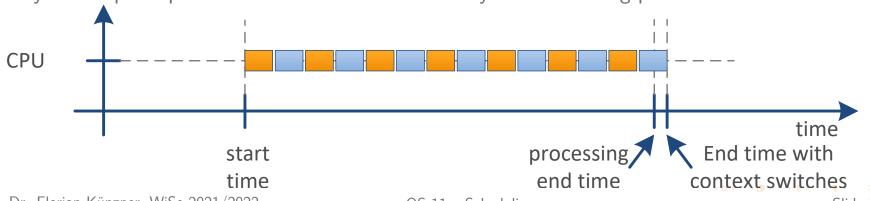
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OS 11 - Scheduling



Context switch

A context switch **changes the active process or thread** on the CPU. This may be expensive (takes some time).

Procedure:

Time for context switches:





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- Select a new process to run
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- Load/restore the register content of the new process from its PCB.

Time for context switches:

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Slide 15 of 30



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Time for context switches:

- \blacksquare Time to switch processes: pprox 3600ns per context switch (Intel E5440 CPU)
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Scheduling: single vs multi core CPU

Single core CPU

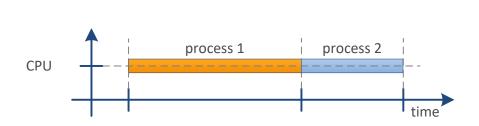




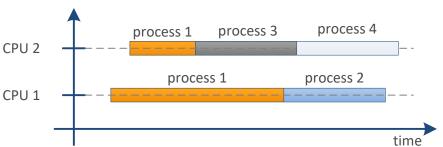
Scheduling: single vs multi core CPU

Scheduling strategies

Single core CPU



Multi core CPU



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Questions?

All right? \Rightarrow

Question? \Rightarrow

4

and use chat

speak after I ask you to



Scheduling strategies

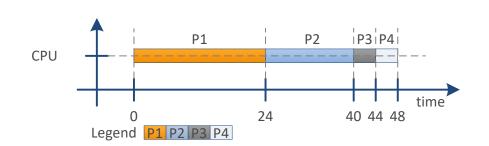
How would you schedule processes on your computer?

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FCFS - first come first served

The arrival order (time) in the waiting queue is the scheduling order.



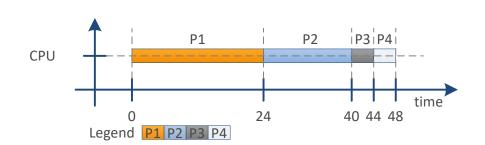
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FCFS - first come first served

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Or.	ar. time	Process	proc. time	res. time
1	0	P1	24	24
2	0	P2	16	
3	0	P3	4	
4	0	P4	4	



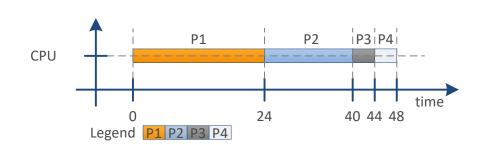
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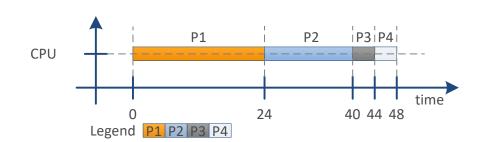
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Or.	ar. time	Process	proc. time	res. time
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3	0	P3	4	44
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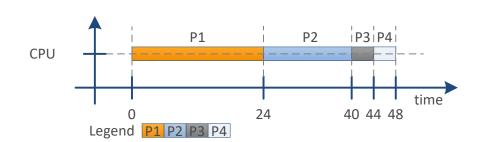




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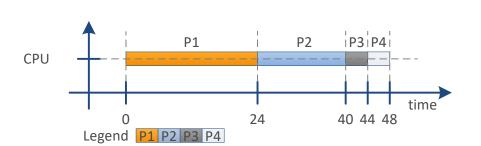
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Mean	res. time	=(24+4)	40 + 44 + 48	/4 = 39



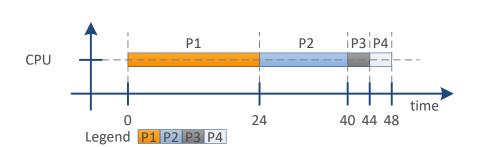
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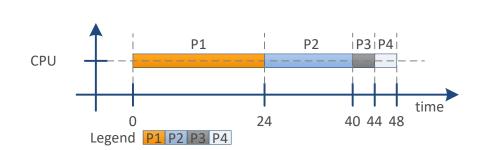
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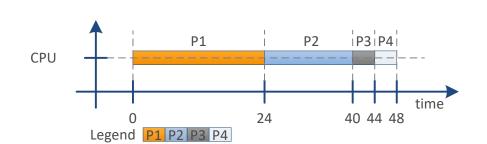
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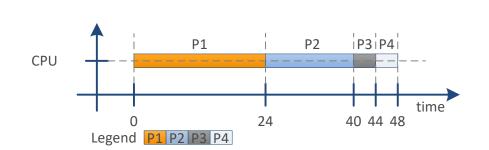
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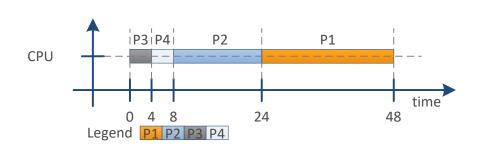
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SJF - shortest jobs first

The job with the smallest processing time is scheduled first.

Or.	ar. time	Process	proc. time	res. time
1	0	P1	24	48
2	0	P2	16	24
3	0	P3	4	4
4	. 0	P4	4	8
Mean	res. time	=(48+2)	(24+4+8)/4	= 21



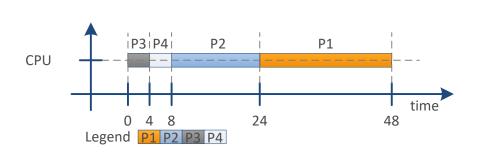
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4	0	P4			4		8
Mean	res. time	e = (4	48 + 2	24 + 4 -	+8)/4	= 21	



- SJF optimises the throughput.
- The processing time is often not available (prediction also hard).
- Processing time is predicted: by user, automatically?
- Jobs with a long processing time may not get scheduled (starvation).

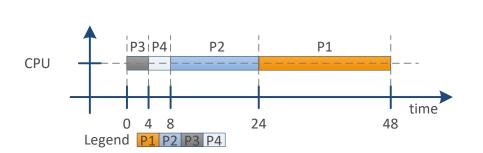
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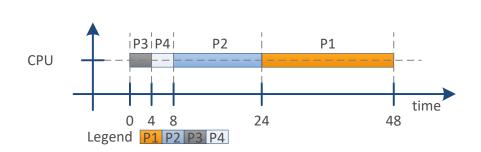
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Mean	res. tim	e = (4	8 + 2	24+4-	+8)/4	= 21	



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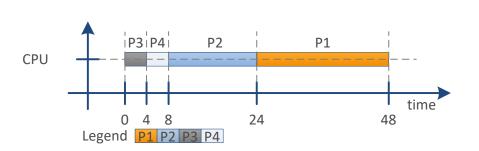
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0	P2	16	24
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res. time	= (48 + 2)	(24+4+8)/4=2	1
	0 0 0	0 P1 0 P2 0 P3 0 P4	0 P2 16 0 P3 4



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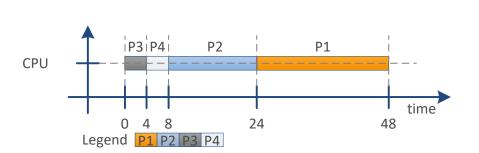
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Or.	ar. 1	time	Process	proc. tim	e res.	time
1		0	P1	2	4	48
2		0	P2	1	6	24
3		0	P3		4	4
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Mean	res.	time	= (48 + 2)	(24+4+8)	/4 = 21	



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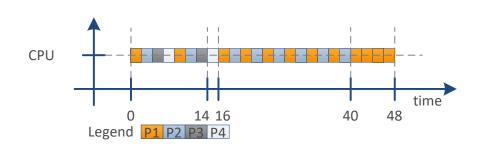


RR - round robin

Every process in the queue get the required resource for a limited amount of time (time slice). Then the preempted process is placed to the last position in the waiting queue.

Here: time slice = 2

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Mean	res. time	e = (48)	3 + 40 + 14	+16)	/4 = 29.5



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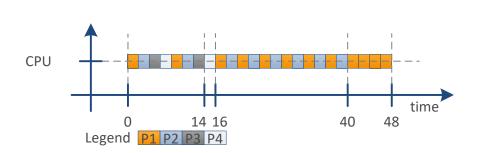


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Mean	res. time	= (48 + 4)	40 + 14 + 16	/4 = 29.5



Properties

- Good for interactive systems
- Too many process switches causes context switches—and that are expensive.
- The average waiting time is often longer than with other scheduling

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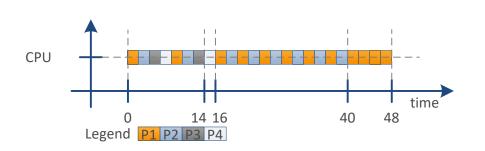


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Mean	res. time	= (48 + 4)	40 + 14 + 16	/4 = 29.5



Properties

- Good for interactive systems.
- Too many process switches causes context switches—and that are expensive.
- The average waiting time is often longer than with other scheduling

Prof. Dr. Florian Künzner, WiSe 2021/2022

Computer Science

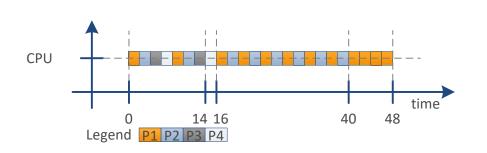


RR - round robin

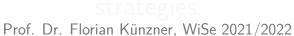
Every process in the queue get the required resource for a limited amount of time (time slice). Then the preempted process is placed to the last position in the waiting queue.

Here: time slice = 2

Or.	ar. time	Process	proc. time	res. time
1	0	P1	24	48
2	0	P2	16	40
3	0	P3	4	14
4	0	P4	4	16
Mean	res. time	= (48 + 4)	40 + 14 + 16)/4 = 29.5



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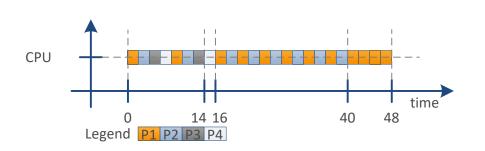


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Mean	res. time	= (48 + 4)	40 + 14 + 16	(6)/4 = 29.5



- Good for interactive systems.
- Too many process switches causes context switches—and that are expensive.
- The average waiting time is often longer than with other scheduling strategies.

Computer Science



EDF - earliest deadline first

The process whose deadline ends first is processed first.

Or.	ar. time	Process	proc. time	deadl.	res. time
1	0	P1	24	60	48
2	0	P2	16	20	20
3	0	P3	4	28	24
4	0	P4	4	4	4
Mean	res. time	= (48 + 2)	20 + 24 + 4)/	$^{\prime}4 = 24$	



Computer Science

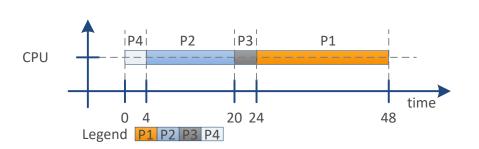


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1	0	P1	24	60	48
2	0	P2	16	20	20
3	0	P3	4	28	24
4	0	P4	4	4	4
B //		(40	0 . 0 4 . 4) /	4 0 4	

Mean res. time = (48 + 20 + 24 + 4)/4 = 24



- Used in real-time systems:
- Is not always optimal on multi-core CPUs.

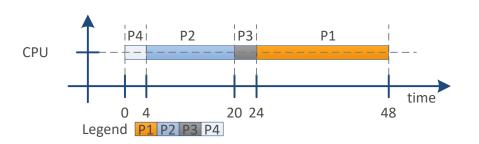
Computer Science



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1	0	P1	24	60	48
2	0	P2	16	20	20
3	0	P3	4	28	24
4	0	P4	4	4	4
Mean	res. time	=(48+2)	20 + 24 + 4)/	4 = 24	



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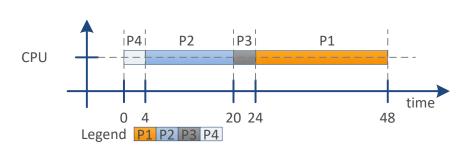
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4	0	P4	4	4	4
Mean	res. time	= (48 + 2)	(20+24+4)/	4 = 24	



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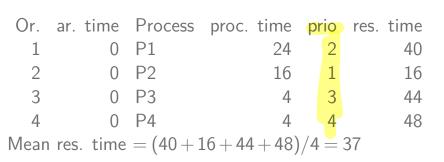


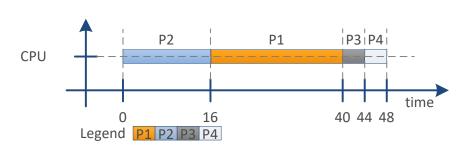
Priority based

External priority

The process with the highest priority is scheduled first. The user can define the priority on startup or change it during execution.

Here: 1 = highest priority, 4 = lowest priority (depends on OS definition)





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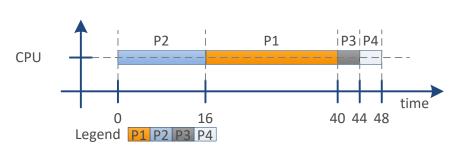
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Or.	ar. time	Process	proc. time	prio	res. time
1	0	P1	24	2	40
2	0	P2	16	1	16
3	0	P3	4	3	44
4	0	P4	4	4	48
Mean	res. time	= (40 + 1)	16 + 44 + 48	/4 = 3	37



- The important processes are scheduled first.
- Long-running processes with a high priority can cause low priority processes to be kept away from the CPU for a long time.

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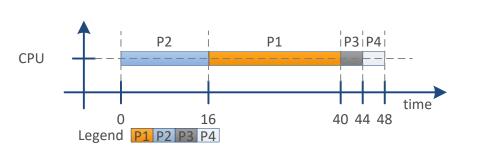
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2	0	P2		16	1		16	
3	0	P3		4	3		44	
4	0	P4		4	4		48	
Mean res. time = $(40+16+44+48)/4 = 37$								



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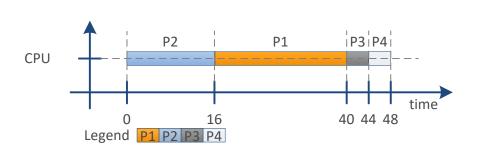
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Mean	res. time	= (40 + 1)	16 + 44 + 48	/4 = 3	37



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Priority based

Internal priority

After a process runs for a while, its priority is automatically lowered. After some long waiting time, the priority can automatically be increased again.



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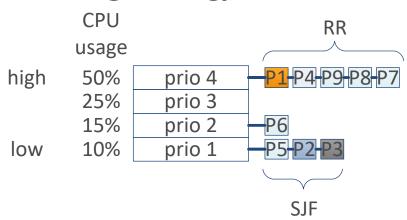
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Multilevel queue scheduling

There exist multiple queues, whereas each can have its own scheduling strategy.



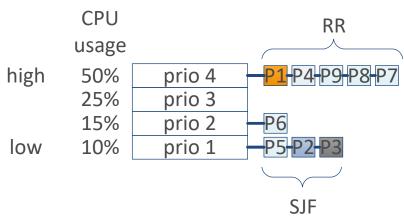
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Scheduling on Linux

Multilevel queue scheduling

There exist multiple queues, whereas each can have its own scheduling strategy.



Properties

- Combination of different strategies
- Each queue can have its own CPU usage.
- Improves response time while taking priorities into account

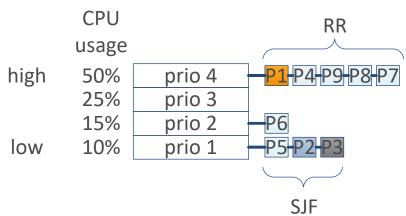
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Scheduling on Linux

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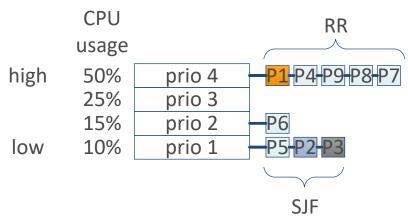
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Scheduling on Linux

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Properties

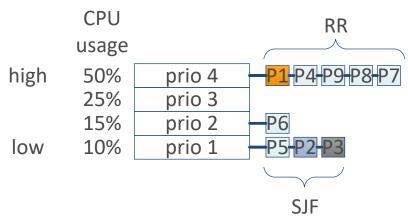
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Questions?

All right? \Rightarrow





and use chat

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Linux priorities

Supports 140 different priority classes (0...139) The lower the value, the higher the priority.

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Linux priorities

Supports 140 different priority classes (0...139) The lower the value, the higher the priority.

Normal processes: 100...139 [0...39]

Parameter	Definition	Description
NI	NI = -20 + 19	Nice value ranges from −20 +19. Users can only increase the
		nice value, but not lower it.
PR	PR = 20 + NI	The priority PR ranges from 039. Default user processes usually
		submitted with $NI = 0 = PR = 20$.

Real-time processes: 0....99 [-100...-1]

Parameter Definition Description RT = 1...99 The real-time priority RT ranges from 1...9 RT = 1...97 The priority RT ranges from RT = 1...91

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Linux priorities

Supports 140 different priority classes (0...139)

The lower the value, the higher the priority.

Normal processes: 100...139 [0...39]

Parameter	Definition	Description
NI	NI = -20 + 19	Nice value ranges from $-20+19$. Users can only increase the
		nice value, but not lower it.
PR	PR = 20 + NI	The priority <i>PR</i> ranges from 039. Default user processes usually
		submitted with $M=0 \Rightarrow PR=20$

Real-time processes: 0...99 [-100...-1]

Parameter	Definition	Description
RT	RT = 199	The real-time priority <i>RT</i> ranges from 199
PR	PR = -1 - RT	The priority PR ranges from -1001 .

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Linux commands

Command

top

htop

ps ax -o pid, rtprio, pri, ni, cmd

nice -n 15 make -j

nice -n -5 make -j

renice -n 15 -p 1000

renice -n -5 -p 1000

Description

Shows processes in live view.

Shows processes in live view.

Shows processes with pid, rtprio, pri, ni, and its cmd.

Starts a parallel build with Nl = 15

Starts a parallel build with NI = -5

Change Nl = 15 of process with PID 1000.

Change NI = -5 of process with PID 1000.



Questions?

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Summary and outlook

Summary

- Scheduling theory and terms
- Scheduling strategies
- Scheduling on Linux

Outlook

Memory management

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Scheduling on Linux

Summary and outlook

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