



Chapter 02 – Basic Classification

Lecture A2I2

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Classification

- ♦ A system that can map a vector of property values onto a discrete number of classes is called a **classifier**.



measure



Sample	Size	Color
1	8	2
2	7	2
3	5	2
4	8	1
5	9	1
6	7	2
..



Classifier

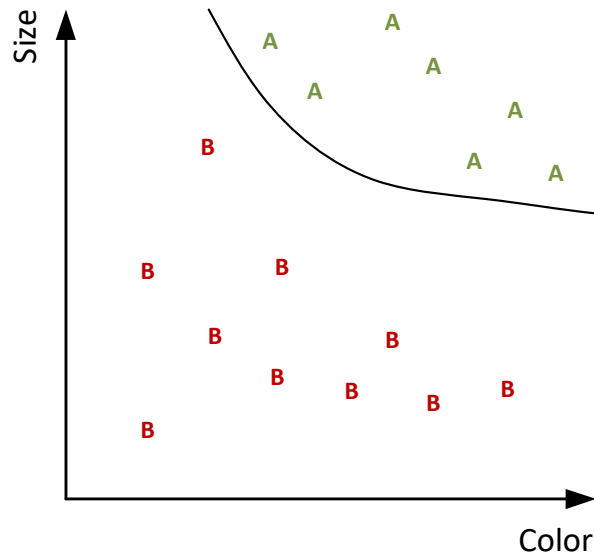
classify



Sample	Class
1	A
2	A
3	B
4	B
5	B
6	A
..	..




Classification is an approximation problem



- ◆ The separating line in the apple example classifies apples in two classes A and B.
- ◆ Such a (one-dimensional) line is a goal function of the classification.
- ◆ If there are n properties as input, the goal function is $n-1$ - dimensional and called a hyperplane
- ◆ A generative model uses a probability distribution between the input and output variables.

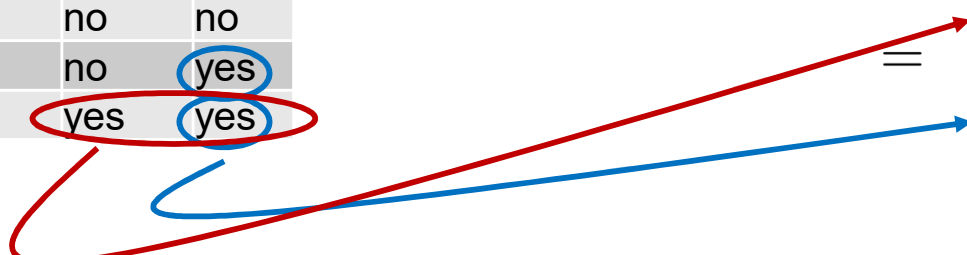


The Golf Problem



#	Outlook	Temp	Humidity	Windy	Play
1	overcast	hot	high	yes	yes
2	overcast	cool	normal	no	yes
3	overcast	mild	high	yes	yes
4	overcast	hot	normal	no	yes
5	rainy	mild	high	no	yes
6	rainy	cool	normal	no	yes
7	rainy	cool	normal	yes	no
8	rainy	mild	normal	no	yes
9	rainy	mild	high	yes	no
10	sunny	hot	high	no	no
11	sunny	hot	high	yes	no
12	sunny	mild	high	no	no
13	sunny	cool	normal	no	yes
14	sunny	mild	normal	yes	yes

- ◆ We want to play golf and a system that supports us in making this decision using some sample data about recent decisions we made.
- ◆ What can we see in the table to support our decision?

$$P(windy|play) = \frac{P(windy \wedge play)}{P(play)}$$
$$= \frac{\frac{3}{14}}{\frac{9}{14}} = \frac{3}{9}$$




Conditional Probabilities of the Golf Problem



		Play	
		Yes	No
Outlook	overcast	0,44	0,00
	rainy	0,33	0,40
	sunny	0,22	0,60
Temperature	hot	0,22	0,40
	cold	0,33	0,20
	mild	0,44	0,40
Humidity	high	0,33	0,80
	normal	0,67	0,20
windy	yes	0,33	0,60
	no	0,67	0,40

- ◆ So, we can calculate all probabilities under the condition that we played or that we have not played a golf match.

- ◆ But we want to know

$$P(play|rainy \wedge hot \wedge normal \wedge windy)$$

$$\begin{aligned} P(windy|play) &= \frac{P(windy \wedge play)}{P(play)} \\ &= \frac{\frac{3}{19}}{\frac{9}{19}} = \frac{1}{3} \end{aligned}$$



What do we need for classification?

- ♦ Or more precisely, we want to know if

$$P(\text{play}|\text{rainy} \wedge \text{hot} \wedge \text{normal} \wedge \text{windy}) \geq P(\text{rest}|\text{rainy} \wedge \text{hot} \wedge \text{normal} \wedge \text{windy})$$

$$\frac{P(\text{play}) \cdot P(r, h, n, w|\text{play})}{P(r, h, n, w)} \geq \frac{P(\text{rest}) \cdot P(r, h, n, w|\text{rest})}{P(r, h, n, w)}$$

$$P(\text{play}) \cdot P(r, h, n, w|\text{play}) \geq P(\text{rest}) \cdot P(r, h, n, w|\text{rest})$$

$$P(\text{play}) \cdot \frac{P(r, h, n, w, \text{play})}{P(\text{play})} \geq P(\text{rest}) \cdot \frac{P(r, h, n, w, \text{rest})}{P(\text{rest})}$$

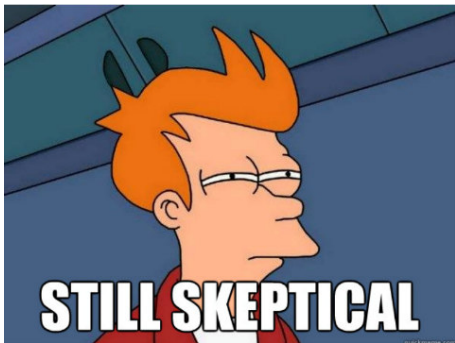
$$P(r, h, n, w, \text{play}) \geq P(r, h, n, w, \text{rest})$$



So, what's the big whoop?

$$\begin{aligned} & P(r, h, n, w, \text{play}) \\ = & P(r|h, n, w, \text{play}) \cdot P(h, n, w, \text{play}) \\ = & P(r|h, n, w, \text{play}) \cdot P(h|n, w, \text{play}) \cdot P(n, w, \text{play}) \\ = & \dots \\ = & P(r|h, n, w, \text{play}) \cdot P(h|n, w, \text{play}) \cdot P(n|w, \text{play}) \cdot P(w|\text{play}) \cdot P(\text{play}) \\ = & \frac{P(r, h, n, w, \text{play})}{P(h, n, w, \text{play})} \cdot \frac{P(h, n, w, \text{play})}{P(n, w, \text{play})} \cdot \frac{P(n, w, \text{play})}{P(w, \text{play})} \cdot P(w|\text{play}) \cdot P(\text{play}) \end{aligned}$$

Diagram illustrating the relationship between the full joint probability and the conditional probabilities used in the Naïve Bayes model. Arrows point from the fractions in the final equation to the corresponding terms in the previous lines of the derivation.



The right side we know, but for the left side, we need **all the cuts**!



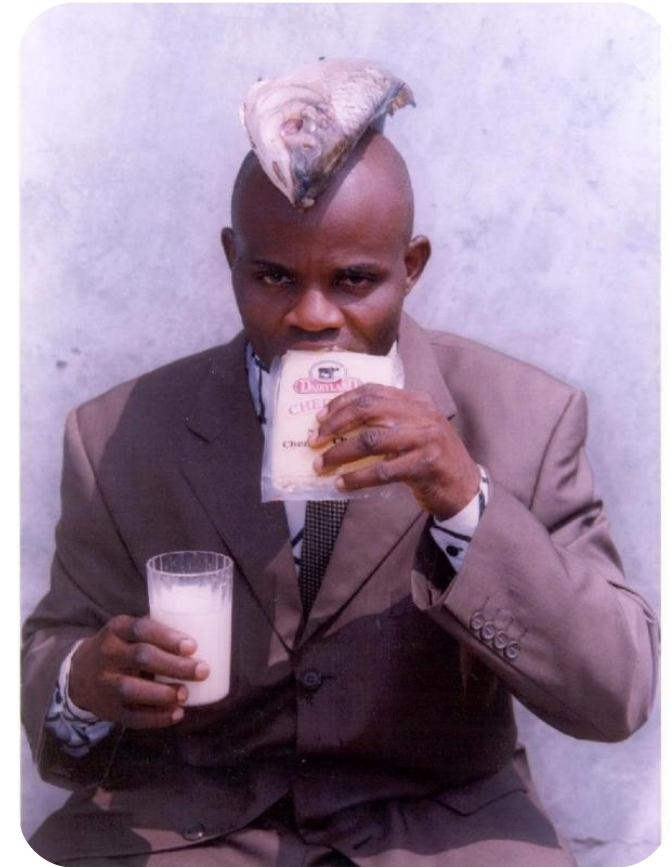


Where to get the cuts?

- ◆ Nowhere
- ◆ For the golf game, we need vastly more samples to calculate the probability that the sun is shining, its is windy and the humidity is low at the same time and so on. Measuring all the cuts would take ages.
- ◆ For **spam classification** its is the same: we can easily measure the probability for the word *lottery* and for the word *Nigeria* and all the other words that may or may not classify spam. But measuring all the cuts would require way too much data.

https://en.wikipedia.org/wiki/Advance-fee_scam

<https://www.youtube.com/watch?v=Q8l0Vip5YUw>



Funny picture from 'the nigeria connection' spam wave



Lets make a naïve assumption

- ◆ Well if we do not want to collect a lot of data that contains all the cuts of our variables so that we can measure the exact distribution, we can make the assumption, that all variable are independent from each other, **except for the dependent variable that we want to measure.**
- ◆ And it is pretty naïve to believe that humidity is totally independent from the outside temperature, right?
- ◆ But it makes our math much more easy, because with this assumption, it is

If A is independent from B, it is

$$P(A|B) = \frac{P(A \cap B)}{P(B)} = \frac{|A| \cdot |B|}{|B|} = P(A)$$

$$\begin{aligned} & P(r, h, n, w, play) \\ = & P(r|h, n, w, play) \cdot P(h|n, w, play) \cdot P(n|w, play) \cdot P(w|play) \cdot P(play) \\ \propto & P(r|play) \cdot P(h|play) \cdot P(n|play) \cdot P(w|play) \cdot P(play) \end{aligned}$$



Hurray, Naïve Bayes Classification!

$$P(\text{play}|r, h, n, w) \geq P(\text{rest}|r, h, n, w)$$

\Leftrightarrow

$$P(r|\text{play}) \cdot P(h|\text{play}) \cdot$$

$$P(n|\text{play}) \cdot P(w|\text{play}) \cdot P(\text{play}) \geq P(r|\text{rest}) \cdot P(h|\text{rest}) \cdot$$

$$0.33 \cdot 0.22 \cdot 0.67 \cdot 0.33 \cdot 0.64 \geq 0.4 \cdot 0.4 \cdot 0.2 \cdot 0.6 \cdot 0.36$$

$$0.0103 \geq 0.0069$$



*Lets play golf in
the rain on a hot
windy day!*



		Play	
		Yes	No
Outlook	overcast	0,44	0,00
	rainy	0,33	0,40
	sunny	0,22	0,60
Temperature	hot	0,22	0,40
	cold	0,33	0,20
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- ◆ So far, we used categorical data. But Naïve Bayes also works with numerical data such as *income*, *temperature* or *kph*:

$$P(X_i = x_k | C_i) = g(x_k; \mu_{i,j}, \sigma_{i,j}) = \frac{1}{\sqrt{2\pi} \cdot \sigma} \cdot e^{-\frac{(x_i - \mu)^2}{2\sigma^2}}$$

with

$$\mu = \frac{1}{n} \sum_{i=1}^n x_i$$

and

$$\sigma = \sqrt{\frac{1}{n-1} \sum_{i=1}^n (x_i - \mu)^2}$$