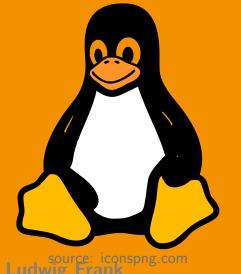


#### Prof. Florian Künzner

Message queue

OS 9 – Communication 2

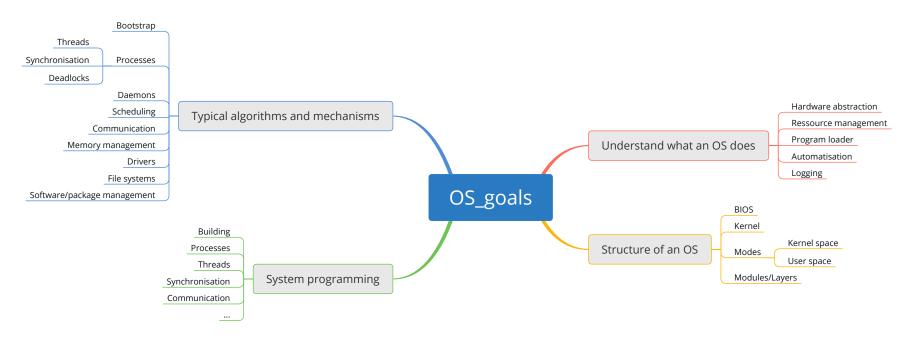


The lecture is based on the work and the documents of Prof. Dr. Ludwig Frank

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### Goal







### **OS::Communication**

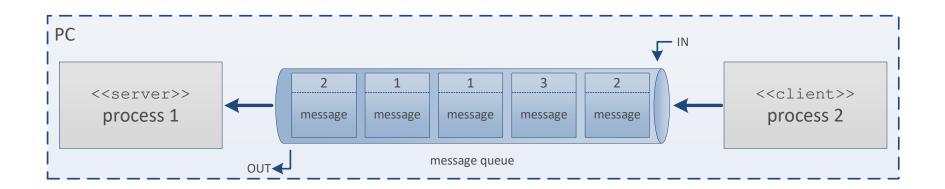
- Message queue
- Shared memory
- Process communication summary

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Summary

# Message queue





# Message queue

Message queue

#### Message queue concept

- Queue to store messages
- Inter-process communication (IPC) between processes on one PC.
- Messages have priority/type.
- Internal stored as a linked list.
- Send into queue does not require an active receiver
- Read from queue does not require an active sender
- Max queue size (default: 16 KiB on Linux).
- Max message size (default: 8 KiB on Linux).

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# Message queue

#### Message structure

```
1 struct message {
2    long priority;    //priority or type
3    char message[64]; //buffer for message bytes
4 };
```

#### Message priority/type

- The lower the number, the higher the priority
- The priority can be interpreted as a type (each type has its own number)

### Message queue usage scenarios (PRIO\_FETCH\_FLAG)

- Read message after message (FIFO principle) (priority == 0)
- Read only message with specific priority/type (priority == N)
- Read the messages with the highest priority/type first, up to a certain number (priority == -N)

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Summary

# Message queue: Pseudo C code

```
struct message { //structure for messages
     long priority;
     char message[64];
   };
                                                       void sender() {
   void receiver() {
     //create message queue
                                                         //open existing message queue
     msgget(...);
                                                   22
                                                         msgget(...);
                                                   23
9
                                                   24
                                                         //prepare message
                                                   25
10
                                                   26
11
     //receive message
                                                         //send message
12
     //blocks if message queue is empty
                                                   27
                                                         //blocks if message queue is full
     msgrcv(...);
                                                         msgsnd(...);
13
                                                   28
14
                                                   29
15
     //... work with message
                                                   30
                                                         //close not needed
16
                                                   31
                                                   32
17
     //remove message queue
     msgctl(...);
                                                   33
18
19 }
                                                   34
```

Message queue



# Message queue: Linux commands

#### Command Description

Show information on IPC facilities ipcs

Shows active message queues in the system ipcs -q

Make various IPC resources ipcmk

ipcmk -Q Create a message queue

Remove certain IPC resources ipcrm

ipcrm -q 1 Remove message queue with id 1

ipcrm -Q 2 Remove message queue with key 2

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# Message queue

# C example

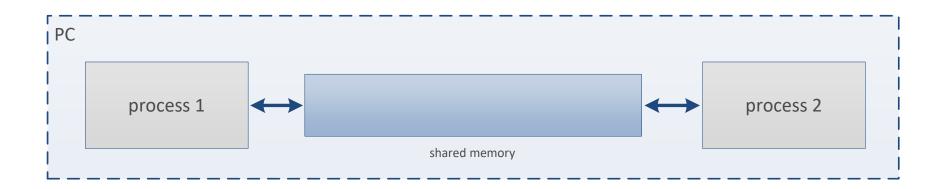
<sup>\*</sup>Please find the source file(s) in the repository.

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Summary

# Shared memory

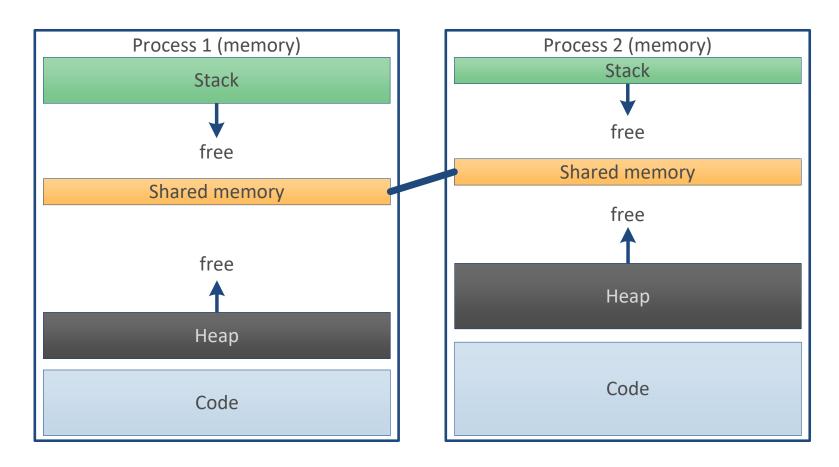


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Summary

# Shared memory





## **Shared memory**

#### **Shared memory concept**

- Shared memory area between processes
- Inter-process communication (IPC) between processes on one PC.
- It is a **plain memory area** with a certain size
- Access **needs to be synchronised** (e.g. semaphore)
- Access is very fast (comparable with own memory access)

//remove shared memory

shmctl(...);

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# Shared memory: Pseudo C code seminit(READY TO WRITE, 1); //declare and initialise semaphore

```
2 seminit(READY_TO_READ, 0); //declare and initialise semaphore
```

```
void receiver() {
                                                   25 void sender() {
                                                        //get existing shared memory
     //create shared memory
                                                   26
                                                        shmget(...);
     shmget(...);
                                                   27
     //attach the shared memory
                                                   28
                                                        //attach the shared memory
     shared mem address = shmat(...);
                                                        shared mem address = shmat(...);
                                                   29
                                                   30
                                                   31
                                                        //... prepare data
10
                                                   32
                                                        data = prepare data();
11
                                                   33
12
     //copy data from shared memory
                                                   34
                                                        //copy data into shared memory
     P(READY TO READ);
                                                   35
                                                        P(READY TO WRITE);
13
     copy(data, shared mem address); //data = sm36
                                                        copy(shared mem address, data); //sm = data
14
                                                        V(READY TO READ);
     V(READY TO WRITE);
15
                                                   37
                                                   38
16
     //... work with data
                                                   39
17
18
     work with(data);
                                                   40
19
                                                   41
20
     //detach shared memory
                                                   42
                                                        //detach shared memory
     shmdt(...);
                                                        shmdt(...);
                                                   43
```

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45

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OS 9 - Communication 2

Message queue



Process communication summary

# **Shared memory: Linux commands**

#### Command Description

Show information on IPC facilities ipcs

Shows active shared memory in the system ipcs -m

Make various IPC resources ipcmk

ipcmk -M 8 Create a shared memory with 8 bytes

Remove certain IPC resources ipcrm

ipcrm -m 1 Remove shared memory with id 1

ipcrm -M 2 Remove shared memory with key 2

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Summary

# **Shared memory**

# C example

<sup>\*</sup>Please find the source file(s) in the repository.



Summary

# Process communication summary

Mechanism	data	store	access contr.	remote	bidirect.	fast	prio.	sync req.
signal						X		
unix socket	X		X		X	X		
network socket	Χ			X	X			
pipe	Χ	_x_	X			Χ		
message queue	Χ	X	X			Χ	Χ	
shared memory	XX	XX	X		X	XX		X

Comparison of different communication mechanism: https://www.programering.com/a/MTOOAzMwATI.html

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# **Summary and outlook**

### **Summary**

- Message queue
- Shared memory
- Process communication summary

### Outlook

- Deadlocks
- Deadlock analysis
- Deadlock prevention