Machine Learning Kernels in Julia

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Let $k: \mathbb{R}^d \times \mathbb{R}^d \mapsto \mathbb{R}$ be a kernel function. There are several classes that can be identified. This focusses on kernels of the form:

$$k(\mathbf{x}, \mathbf{y}) = \kappa(z(\mathbf{x}, \mathbf{y}))$$

where $z: \mathbb{R}^d \times \mathbb{R}^d \mapsto \mathbb{R}$ and $\kappa: \mathbb{R} \mapsto \mathbb{R}$.

For the first derivatives:

$$\frac{\partial \kappa}{\partial \mathbf{x}} = \kappa'(z) \left[\frac{\partial z}{\partial \mathbf{x}} \right] \quad \text{and} \quad \frac{\partial \kappa}{\partial \mathbf{y}} = \kappa'(z) \left[\frac{\partial z}{\partial \mathbf{y}} \right]$$

Then, the mixed second derivatives are:

$$\frac{\partial \kappa^{2}}{\partial \mathbf{x} \partial \mathbf{y}} = \frac{\partial}{\partial \mathbf{x}} \left(\left[\frac{\partial \kappa}{\partial \mathbf{y}} \right] \right)
= \frac{\partial}{\partial \mathbf{x}} \left(\kappa'(z) \left[\frac{\partial z}{\partial \mathbf{y}} \right] \right)
= \left[\frac{\partial z}{\partial \mathbf{y}} \right] \left[\frac{\partial \kappa'(z)}{\partial \mathbf{x}} \right]^{\mathsf{T}} + \kappa'(z) \frac{\partial}{\partial \mathbf{x}} \left(\left[\frac{\partial z}{\partial \mathbf{y}} \right] \right)
= \kappa''(z) \left[\frac{\partial z}{\partial \mathbf{y}} \right] \left[\frac{\partial z}{\partial \mathbf{x}} \right]^{\mathsf{T}} + \kappa'(z) \left[\frac{\partial z^{2}}{\partial \mathbf{x} \partial \mathbf{y}} \right]$$

1 Scalar Product Kernel: $z(\mathbf{x}, \mathbf{y}) = \mathbf{x}^{\mathsf{T}} \mathbf{y}$

The Scalar Product kernel is of the form:

$$k(x,y) = \kappa \left(x^{\mathsf{T}} y \right)$$

where κ is a function unique to each Scalar Product kernel. For example, the the Sigmoid kernel instance of κ is defined to be:

$$\kappa_{\rm s}(z;a,c) = \tanh(az+c)$$

Let X and Y be data matrices with rows as data points. Then the kernel matrix K:

$$X = \begin{bmatrix} \mathbf{x}_1^\mathsf{T} \\ \mathbf{x}_2^\mathsf{T} \\ \vdots \\ \mathbf{x}_n^\mathsf{T} \end{bmatrix} \text{ and } Y = \begin{bmatrix} \mathbf{y}_1^\mathsf{T} \\ \mathbf{y}_2^\mathsf{T} \\ \vdots \\ \mathbf{y}_m^\mathsf{T} \end{bmatrix} \implies K = \begin{bmatrix} \kappa(\mathbf{x}_1^\mathsf{T}\mathbf{y}_1) & \cdots & \kappa(\mathbf{x}_1^\mathsf{T}\mathbf{y}_m) \\ \vdots & \ddots & \vdots \\ \kappa(\mathbf{x}_n^\mathsf{T}\mathbf{y}_1) & \cdots & \kappa(\mathbf{x}_n^\mathsf{T}\mathbf{y}_m) \end{bmatrix}$$

Given a set of vectors $S = \{\mathbf{z}_1, ..., \mathbf{z}_n\}$ the gramian is defined as $[\mathbf{G}]_{ij} = \mathbf{z}_i^{\mathsf{T}} \mathbf{z}_j$. Therefore, if we have two sets of vectors S_x and S_y with corresponding data matrices X and Y, then we can define the gramian between them as $\mathbf{G}(\mathbf{X}, \mathbf{Y}) = \mathbf{X}\mathbf{Y}^{\mathsf{T}}$. This is really the upper right-hand corner of the gramian of the set $S_x \cup S_y$.

Finally, we may define the kernel matrix as a function of the gramian:

$$[K]_{ij} = \kappa \left([G_{XY}]_{ij} \right)$$

Generally, the best approach to take for implementation is:

- 1. Calculate G_{XY} for matrix X and Y using GEMM or SYRK using BLAS (exploit symmetry of kernels). The option to use rows or columns as data points is left as an option (using trans = 'N' assumes rows are observations and 'T' assumes columns). This is $O(n^3)$ but is heavily optimized to reduce the coefficient.
- 2. Scan through the elements of G(X, Y) and apply the κ function to each element, overwrite G_{XY} in the process. This is $O(n^2)$.
- 3. Return K

2 Squared Distance Kernel

The Squared Distance kernel is of the form:

$$k(x,y) = \kappa \left((||x - y||^2) \right)$$

where κ is a function unique to each kernel. For example, the Gaussian kernel instance of κ is defined to be:

$$\kappa_{\Phi}(z;\sigma) = \exp\left(\frac{-z}{2\sigma^2}\right)$$

2.1 Kernel Matrix

Let X and Y be data matrices with rows as data points. Then the kernel matrix K:

$$\mathbf{X} = \begin{bmatrix} \mathbf{x}_1^\mathsf{T} \\ \mathbf{x}_2^\mathsf{T} \\ \vdots \\ \mathbf{x}_n^\mathsf{T} \end{bmatrix} \text{ and } \mathbf{Y} = \begin{bmatrix} \mathbf{y}_1^\mathsf{T} \\ \mathbf{y}_2^\mathsf{T} \\ \vdots \\ \mathbf{y}_m^\mathsf{T} \end{bmatrix} \implies \mathbf{K} = \begin{bmatrix} \kappa \left(||\mathbf{x}_1 - \mathbf{y}_1||^2 \right) & \cdots & \kappa \left(||\mathbf{x}_1 - \mathbf{y}_m||^2 \right) \\ \vdots & \ddots & \vdots \\ \kappa \left(||\mathbf{x}_n - \mathbf{y}_1||^2 \right) & \cdots & \kappa \left(||\mathbf{x}_n - \mathbf{y}_m||^2 \right) \end{bmatrix}$$

For a vector \mathbf{x} and \mathbf{y} , define the lag (alternatively, the error) between the two vectors to be:

$$lag(x, y) = x - y = \epsilon$$

Then we may define kernels of this form as:

$$k(x, y) = \kappa (\log(\mathbf{x}, \mathbf{y}) \cdot \log(\mathbf{x}, \mathbf{y})) = \kappa (\epsilon^{\mathsf{T}} \epsilon) = \kappa (||\mathbf{x} - \mathbf{y}||^2)$$

Given a set of vectors $S = \{\mathbf{z}_1, ..., \mathbf{z}_n\}$, the lagged gramian is defined as:

$$[\mathbf{G}_l]_{ij} = ||\mathbf{z}_i - \mathbf{z}_j||^2$$

Similarly, for two data matrices **X** and **Y**:

$$\left[\mathbf{G}_{l}\left(\mathbf{X},\mathbf{Y}\right)\right]_{ij} = ||\mathbf{x}_{i} - \mathbf{y}_{j}||^{2}$$

Where \mathbf{x}_i and \mathbf{y}_j are the data vectors in \mathbf{X} and \mathbf{Y} . The lagged gramian can be defined in terms of $\mathbf{G}(\mathbf{X}, \mathbf{Y})$, \mathbf{X} and \mathbf{Y} .

$$[\mathbf{G}_{l}(\mathbf{X}, \mathbf{Y})]_{ij} = [\operatorname{diag}(\mathbf{G}(\mathbf{X}))]_{i} - 2[\mathbf{G}]_{ij} + [\operatorname{diag}(\mathbf{G}(\mathbf{Y}))]_{j}$$

The function diag $(\mathbf{G}(\mathbf{X}))$ returns a vector of diagonal entries of \mathbf{G} . This is simply a vector where entry i is $\mathbf{x}_i^{\mathsf{T}}\mathbf{x}_i$.

2.2 Kernel Matrix Calculation - Implementation

Therefore, to compute the kernel matrix for a squared distance kernel:

- 1. Calculate G(X, Y) for matrix X and Y using GEMM or SYRK using BLAS (exploit symmetry of kernels). This is $O(n^3)$.
- 2. Transform G(X, Y) to $G_l(X, Y)$. This is $O(n^2)$.
- 3. Scan through the elements of $G_l(\mathbf{X}, \mathbf{Y})$ and apply the κ function to each element, overwrite $G_l(\mathbf{X}, \mathbf{Y})$ in the process. This is $O(n^2)$.
- 4. Return K

2.3 Kernel Derivative

$$\frac{\partial z}{\partial \mathbf{x}} = \frac{\partial ||\mathbf{x} - \mathbf{y}||^2}{\partial \mathbf{x}} = \frac{\partial}{\partial \mathbf{x}} (\mathbf{x}^\mathsf{T} \mathbf{x} - 2\mathbf{x}^\mathsf{T} \mathbf{y} + \mathbf{y}^\mathsf{T} \mathbf{y}) = 2(\mathbf{x} - \mathbf{y})$$
$$\frac{\partial z}{\partial \mathbf{y}} = \frac{\partial ||\mathbf{x} - \mathbf{y}||^2}{\partial \mathbf{y}} = \frac{\partial}{\partial \mathbf{y}} (\mathbf{x}^\mathsf{T} \mathbf{x} - 2\mathbf{x}^\mathsf{T} \mathbf{y} + \mathbf{y}^\mathsf{T} \mathbf{y}) = 2(\mathbf{y} - \mathbf{x})$$

Using the identity:

$$\left[\frac{\partial \mathbf{u}}{\partial \mathbf{v}}\right]_{ij} = \frac{\partial u_i}{\partial v_i}$$

The second mixed derivative is:

$$\frac{\partial z^2}{\partial \mathbf{x} \partial \mathbf{y}} = \frac{\partial ||\mathbf{x} - \mathbf{y}||^2}{\partial \mathbf{x} \partial \mathbf{y}} = \frac{\partial}{\partial \mathbf{x}} 2(\mathbf{y} - \mathbf{x}) = -2\mathbf{I}_d$$

Substituting in the above into the formula for kernel derivative:

$$\frac{\partial \kappa^2}{\partial \mathbf{x} \partial \mathbf{y}} = \kappa''(z) \left[\frac{\partial z}{\partial \mathbf{y}} \right] \left[\frac{\partial z}{\partial \mathbf{x}} \right]^{\mathsf{T}} + \kappa'(z) \left[\frac{\partial z^2}{\partial \mathbf{x} \partial \mathbf{y}} \right]$$
$$= -4\kappa''(z) (\mathbf{x} - \mathbf{y}) (\mathbf{x} - \mathbf{y})^{\mathsf{T}} - 2\kappa'(z) \mathbf{I}_d$$

Define $\boldsymbol{\epsilon} = \mathbf{x} - \mathbf{y}$, then this gives an element-wise formula of:

$$\left[\frac{\partial \kappa^2}{\partial \mathbf{x} \partial \mathbf{y}}\right]_{ij} = \begin{cases} -4\kappa''(\boldsymbol{\epsilon}^{\mathsf{T}} \boldsymbol{\epsilon}) \epsilon_i \epsilon_j & \text{if } i \neq j \\ -4\kappa''(\boldsymbol{\epsilon}^{\mathsf{T}} \boldsymbol{\epsilon}) \epsilon_i^2 - 2\kappa'(\boldsymbol{\epsilon}^{\mathsf{T}} \boldsymbol{\epsilon}) & \text{if } i = j \end{cases}$$