

/\* \*.fem the data file, contain mesh information, for FEM:

```
F_X.n, F_X.d, F_T.n
x, y, [z,] (i) (F_X.x: x[n],y[n],z[n])
: (i=0, F_X.n-1)
n, element type, (i)
material type, i1,i2,i3,[i4,[i5,i6,[i7,i8,]]] (j) (j=0, n-1)
: (i=0, F_T.n-1)
(end)
```

F\_X.n,F\_X.d,F\_T.n: The number of node, dimension, and type of element  
n: number of element for each type  
element type: plane ele(2001,2002,2003,2004), bar ele(2101,2102), beam  
ele(2201,2202), plane contact ele with slid property in  
0--1 direction(2501,2502,2503,2504), bar ele with slid  
property(2601,2602)  
material type: 1, 2, 3,... Start from one

This file will be created by mesh generator.

```
local coord num: 2001(2501) 2002(2502) 2003(2503) 2004(2504)
                  2          3 2          2          3 6 2
                  0 1          0 1          5 4          7 5
                  0 1          0 3 1          0 4 1
```

```
Bar ele 2101: 2102: Beam ele 2201: 2202:
0---1 0-2-1          0---1 0-2-1
Bar ele with slide property 2601: 2602:
2---3 3-5-4 steel bar
0 1 0 2 1 concrete node
```

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/\* \*.mat the data file, contain material property, for FEM:

```
n, ipl // (ipl: 0,plane stress; 1,plane strain; 3,3D)
id, material property, (i) //(i=0, n-1)
:
:
(end)
```

id: material property type.

```
id=1: isotropic material. E, V, T, px, py,alpha
id=2: orthotropic material. E11, v12/v21, G12, alpha1,
E22, v13/v31, G13, alpha2,
E33, v23/v32, G23, alpha3,
T, px, py
v12/v21: v12, when E11 > E22 (v12/E11 = v21/E22)
```

$v_{21}$ , when  $E_{11} < E_{22}$   
 material coordinate system is same as the element local coordinate.  
 id=3: for Bar element. E,A,I,px,py,pz,alpha  
 where A is the area of section, I is minimum of I1 and I2.  
 id=4: for Bar element with sliding property. E,G,A,I,px,py,pz,alpha

For example:

```

4, 0          //(n=3, ipl=0)
1, E, v, t, px, py, (1)
2, E1, v12, g12, alpha1,
E2, v13, g13, alpha2,
E3, v23, g23, alph3,
t, px, py, (2)
3, E, A, I, px, py, pz, alpha, (3)
4, Es, Gc, A, I, px, py, pz, alpha, (4)
  
```

After read in:

```

F_MAT= {
  n=4; ipl=0;
  Mats[0] = { id=1, n=5, e[6]=( E, v, t, px, py, alpha)};
  Mats[1] = { id=2, n=12, e[15]=( E11, v12/v21, G12,alpha1,
                                E22, v13/v31, G13,alpha2,
                                E33, v23/v32, G23,alpha3,
                                T, px, py )};
  Mats[2] = { id=3, n=5, e[7]=(E, A, I, px, py,pz,alpha)};
  Mats[3] = { id=4, n=6, e[8]=(Es,Gc,A,I,px,py,pz,alpha)};
}
*/
  
```

```

/* file *.pqu:
  np0, np,nu
  k, P0k, (i)  (k: dof)
  :           (i=1,np0)
  k, Pk, (i)
  :           (i=1,np)
  k, Uk, (i)
  :           (i=1,nu)
  (end)
  
```

np0,np,nu: number of dead load, live load and prescribed deformation in d.o.f

k: degree of freedom

P0k,Pk: dead load and live load in kth d.o.f

Uk: prescribed deformation in kth d.o.f

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