













# Writing a Tango class











- The hardware (Arduino)
- A basic class using Pogo
- A Python Tango class for the temperature sensor
- The same Tango class in Cpp



#### The hardware



- A temperature controller
  - Based on Arduino UNO board
    - http://arduino.cc/en/
  - Temperature sensor is a LM 35 chip from NI
  - Arduino UNO board connected to your PC using a USB port









#### The hardware

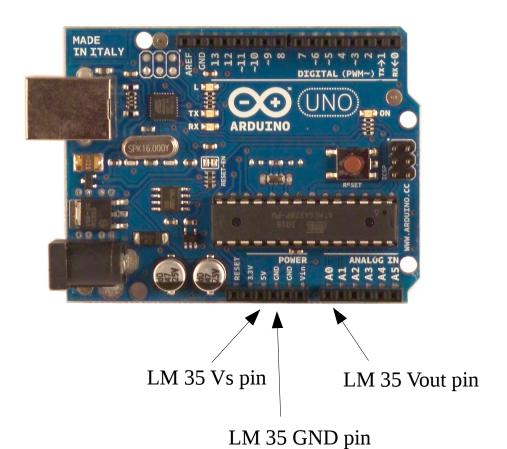


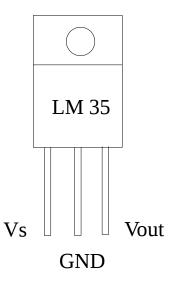
**USB** 











#### The hardware



#### Arduino UNO

- Atmega 38 microcontroller 8 bits
  - 16 Mhz 32 KB flash + 2KB SRAM + 1 KB EEPROM
- 14 digital I/O (6 PWM)
- 6 analog inputs
  - 10 bits / 0 5 Volts
- 1 Serial line
  - External or via USB



LM 35



10 mV / Celcius deg

#### The hardware









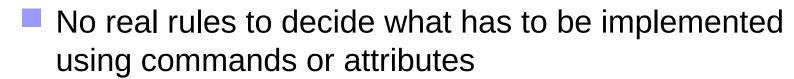


- A serial line is simulated in the USB connection
- A small program running in the Arduino controller chip has been written
  - If the Arduino receives the character 'T', it returns the temperature (in Celsius degree) coded as a float number in a string (eg: '22.34')
  - Protocol error' is returned for all other character

### Writing a Tango class



- Chat with the equipment responsible
  - Which device states?
  - Which commands?
  - Which attributes?









### Writing a Tango class



Writing Tango device class need some glue code. We are using a code generator with a GUI called POGO:
 Program Obviously used to Generate Object



 Following some simple rules, it's possible to use it during all the device class development cycle (not only for the first generation)



POGO generates



- C++, Python Tango device class glue code
- Makefile (C++)
- Basic Tango device class documentation (HTML)

### Writing a Tango class





- Give Tango class name
- Define Tango device state(s)
- Define Tango device command(s)
- Define Tango device attribute(s)
- Define Tango device state machine
- Define Tango device property(ies)
- Enter Tango device documentation







#### A simple Tango class

- Let's generate a SkiLift Tango class
  - 3 states: ON, OFF, FAULT
  - 3 commands

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Name	In	Out	Allowed
Reset	Void	Void	If FAULT
On	Void	Void	If OFF
Off	Void	Void	Always



3 attributes

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	3		

Name	Type	Format	Writable
Speed	double	scalar	read/write
Wind_speed	double	scalar	read
Seats_pos	long	spectrum	read



### The temperature sensor Tango class



- Tango class name: GrenobleTemp
- 2 states: **OFF, ON** (ALARM)
- 1 attribute:
  - Temp
    - Scalar, float, read
    - Label = Temperature, unit = deg
    - Quality factor invalid if state != ON, ALARM



- 2 commands
  - On allowed only if OFF state
  - Off allowed only in ON state



- 1 device property: SerialLine string
- Python as language
- Start "pogo-6" from a shell window

#### **Device server in database**

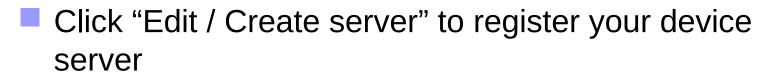


By default, POGO generates

- Device Server name = Tango class name
  - Server name = class name = "GrenobleTemp"

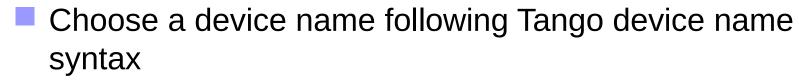


Start Jive to register device server process in database





Choose one instance name





domain/family/member



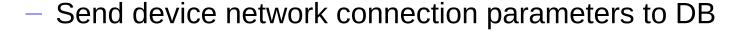
#### Device Server startup sequence



Connect to DB device using TANGO\_HOST env. variable (or /etc/tangorc)



- Send to DB device server executable name, instance name and Tango class
- DB returns device name list
- FOR each device(s)
  - Ask DB for device properties
  - Create device









#### Client create connection



Connect to DB device using TANGO\_HOST env. variable (or /etc/tangorc)



- Ask DB what are the network connection parameters for device "domain/family/member"
- Create direct connection to the device





#### **Coding a Tango class**



- Four things to do
  - Device creation
  - Implementing commands
  - Reading attribute(s)
  - Writing attribute(s)









### **Coding a Tango class**









- Which methods can I use within a Tango class?
  - Your class inherits from a Tango library class named
     Device\_<x>Impl
    - All methods from Device\_<x>Impl class (mapped to Python)
  - Some methods received a Attribute or Wattribute object
    - All the methods of these two classes wrapped to Python
- Doc available at http://www.tango-controls.org
  - Document/Tango kernel/PyTango for Python
  - Document/Tango kernel/Tango device server classes for C++

### Creating the device



- A init\_device() method to construct the device
  - GrenobleTemp.init\_device()
- A delete\_device() to destroy the device
  - GrenobleTemp.delete\_device()
- All resources acquired in init\_device() must be returned in delete\_device()









#### Creating the device

- The init\_device() method
  - Init state (and status if required)
  - Init (create) local data



```
# Device initialization

# def init_device(self):
    print "In ", self.get_name(), "::init_device()"
    self.set_state(PyTango.DevState.OFF)
    self.get_device_properties(self.get_device_class())

self.ser = serial.Serial(self.SerialLine,9600)
```



### Implementing a command



- A hook → always\_executed\_hook()
  - GrenobleTemp.always\_executed\_hook()



- If state management is needed, one is\_xxx\_allowed() method
  - bool GrenobleTemp.is\_On\_allowed()



- One method per command
  - GrenobleTemp.On()





### Implementing a command



GrenobleTemp.is\_On\_allowed()



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```
def is_On_allowed(self):
    if self.get_state() in [PyTango.DevState.ON]:
        End of Generated Code
        Re-Start of Generated Code
        return False
    return True
```



### Implementing a command



GrenobleTemp.On command coding



def On(self):
 print "In ", self.get\_name(), "::On()"

# Add your own code here
 self.set\_state(PyTango.DevState.ON)





### Reading attribute



- A hook → always\_executed\_hook()
  - GrenobleTemp.always\_executed\_hook()
- One method to read hardware
  - GrenobleTemp.read\_attr\_hardware(data)
- If state management is needed, one is\_xxx\_allowed() method
  - bool GrenobleTemp.is\_Temp\_allowed(req\_type)
- One method per attribute
  - GrenobleTemp.read\_Temp(Attribute)









### Reading attribute



read\_attr\_hardware() method



#-----# Read Attribute Hardware
#-----def read\_attr\_hardware(self,data):
 print "In ", self.get\_name(), "::read\_attr\_hardware()"







### Reading attribute



read\_Temp() method

def read\_Temp(self, attr):

```
print "In ", self.get name(), "::read Temp()"
         Add your own code here
sta = self.get state()
if sta in [PyTango.DevState.ON,PyTango.DevState.OFF]
  self.ser.write('T')
  answer = self.ser.readline()
  stripped_answer = answer.rstrip()
  self.debug stream("Temperature returned by arduino = ",stripped answer
  try:
     attr Temp_read = float(stripped_answer)
     attr.set_value(attr_Temp_read)
  except ValueError:
     PyTango.Except.throw_exception("GrenobleTemp_WrongAnswer",
     "Wrong answer from Arduino. Can't be converted to float", "GrenobleTemp.read_Temp")
else:
  attr.set_quality(PyTango.AttrQuality.ATTR_INVALID)
```

#### Writing attribute



- A hook → always\_executed\_hook()
  - GrenobleTemp.always\_executed\_hook()



- If state management is needed, one is\_xxx\_allowed() method
  - bool GrenobleTemp.is\_Temp\_allowed(req\_type)



- One method per attribute
  - GrenobleTemp.write\_xxx(WAttribute)





### Writing attribute



write\_xxx() method



```
def write_xxxx(self, attr):
    print "In ", self.get_name(), "::write_Speed()"
    data = attr.get_write_value()
    .....
```







#### Tango class in C++



- Use POGO 7 (latest release) to generate C++ Tango class
- Support Tango class inheritance Support Multi-Tango class device server
  - Based on a DSL (Xtext Xpand)









#### **GrenobleTemp in C++**



Use the already existing Tango class to control serial line.



Available in SourceForge tango-ds project



Module name = SerialLine



 Doc not available in pink site due to actual migration / merging task between CVS and SVN





#### **GrenobleTemp in C++**



 GrenobleTemp uses a SerialLine Tango device to control the serial line



- Use Pogo "Tools/Multi Classes Manager" to create the device server embedding 2 Tango classes
- GrenobleTemp device property is now SerialDevice and initialized to the Serial line Tango device name



GrenobleTemp Tango class is a client of the serial line Tango device.

