6.854 Advanced Algorithms

Problem Set 9

John Wang Collaborators:

Problem 1: Give a polynomial time 2-approximation for the SONET-ring loading problem.

Solution: First, we will formulate an integer linear program for the problem, then relax the conditions. then round the answer to obtain a 2-approximation. The integer linear program will have variables p_l^k and p_r^k denote the result from the kth call. If $p_l^k = 1$, then $p_r^k = 0$ and we will go to the left (counterclockwise) on the kth call. If $p_r^k = 1$, then $p_l^k = 0$ and we will go to the right (clockwise) on the kth call to get from i to j. If we set l(i) as the load on vertex i, then we have the following problem:

$$\min \max_{i \in V} l(i)$$

(2) s.t.
$$p_l^k + p_r^k = 1$$

$$(3) p_l^k, p_r^k \in \{0, 1\}$$

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$$\min \max_{i \in V} l(i)$$
(2)
$$\text{s.t.} \quad p_l^k + p_r^k = 1$$
(3)
$$p_l^k, p_r^k \in \{0, 1\}$$
(4)
$$\sum_k u_l(k, i) p_l^k + u_r(k, i) p_r^k \leq L$$

Where $u_l(k,i) = 1$ if the left (counterclockwise) path on the kth call uses vertex i and $u_r(k,i) = 1$ if the right path on the kth call uses vertex i. Otherwise, $u_l(k,i)=0$ and $u_r(k,i)=0$ if the vertex i is not on the respective path for call k. Relaxing the conditions, we just need to change the condition $p_k^k, p_k^k \in \{0,1\}$ to $x_{l}^{k}, x_{r}^{k} \in [0, 1].$

We can solve this problem in polynomial time by using the ellipsoid algorithm. However, this will give us a result where x_l^k and x_r^k are not necessarily integers. In order to make them integers, we will round them. So if $x_l^k \ge \frac{1}{2}$, then we will set $p_l^k = 1$ and $p_r^k = 0$. Otherwise, we will set $p_l^k = 0$ and $p_r^k = 1$. Notice that this $p_L^k + p_r^k = 1$, so this gives us all the cases.

To show that this is a 2-approximation, we will extend the definition of u_r and u_l to incorporate fractional amounts of load on vertex i. We have, for any i:

(5)
$$\sum_{k} u_{l}(k,i)p_{l}^{k} + u_{r}(k,i)p_{r}^{k} \leq \sum_{k} 2(u_{l}(k,i)x_{l}^{k} + u_{l}(k,i)x_{r}^{k})$$

$$(6) \leq 2l(i)$$

Thus, since the load on any edge increases by at most 1 more than in the optimal case on each path, we can see that the load given by the p_t^l and p_r^k will give a maximum edge load of 2 times more than the actual maximum. Thus, we have a 2-approximation algorithm that runs in polynomial time. \Box

Problem 3-a: Show that a minimum cycle cover can be found in polynomial time.

Solution: For each vertex $u \in V$, we create two nodes u_{in} and u_{out} which correspond to the entry and exit nodes respectively of u. All edges going into u_{in} correspond to edges that will enter u and all edges in u_{out} correspond to edges leaving u.

We know from lecture that, given a complete graph G with non-negative edge weights and an even number of vertices, we can compute a minimum weight perfect matching in G. Now, we place all entry vertices u_{in} into a set S_{in} , and all exit vertices u_{out} into a set S_{out} . We wish to find a minimum weight perfect matching of the entry vertices to exit vertices, where the connections between any vertex u_{out} and v_{in} will be given by the edges connecting node u and v. The costs will be given by the costs of this edge in the original graph.

Now, we can find a minimum weight perfect matching in polynomial time (since we have an even number of vertices due to doubling). This perfect matching will give us a minimum cycle cover. First, we show that no vertex u_{in} will be matched with its own u_{out} , simply because there is no edge connecting u_{in} and u_{out} in the graph. However, we are forced to have some u_{in} connect with the v_{out} of some different vertex. This constitutes a connection between nodes u and v in the original graph. Since we have a perfect matching, each u_{in} node is connected to exactly one other v_{out} node. Since each entry node is connected to the exit

node of a different vertex, we know vertex v must be connected to a different node. Moreover, since v_{out} is connected to somve vertex, there is another exit vertex which v is connected to. This argument follows for all vertices, which means that v must be part of some cycle.

Since the perfect matching was of minimum value, the cycle must also be of minimum value. Suppose this is not the case, and a minimum weight perfect matching let to some cycle cover which was not minimum. Then this cycle cover must have some cycle C which has a greater cost than the minimum weight cycle over the same vertices. However, this means we can find a matching between these vertices which has a lower cost than our original perfect matching, which is a contradiction.

Now, all we have to do is merge v_{in} and v_{out} back into a single node, and the result graph will be a minimum cycle cover, found in polynomial time. \Box

Problem 3-b: Suppose that given a cycle cover, you choose one representative node from each cycle. Prove that this set of representative nodes is at most half the total nodes, and that the optimum tour traversing only these representative nodes costs less than the original optimum.

Solution: Note that for any cycle, we must have at least one edge. Since there are no self-directed edges, this implies that each cycle has at least two vertices. Therefore, we can lower bound the number of vertices in each cycle by 2. Thus, in the worst case, there will be n/2 cycles, and picking a representative vertex from each cycle results in a set of n/2 vertices. If any cycles are longer than 2, then we see the number of representative vertices will be less than n/2. Thus, the set of representative nodes is at most half the total nodes.

Now, suppose by contradiction that the optimum tour traversing the representative nodes costs more than the original optimum. Then we can take the original optimum over the entire graph and construct a tour over the representative nodes. Take the nodes r in the set of representative nodes R, and identify them in the original optimum cycle cover and order them according to their appearance in the cycle (choosing some arbitrary vertex as the starting point). In the original cycle cover, we have some path from r_1 to r_2 which either goes directly from r_1 to r_2 , or passes over some intermediate nodes which are not in the set R. If the former occurs, then place the edge (r_1, r_2) into the new cycle cover we construct for the representative nodes. If we have the latter case, then we can choose the edge (r_1, r_2) , and know by the triangle inequality, that the cost of traversing (r_1, r_2) is less than or equal to the cost of traversing the previous path from r_1 to r_2 .

We do this for all of the cycles in the original optimum cycle cover. It is clear that the resulting set that we have built has cost which is less than or equal to the cost of the original optimum cycle cover. Moreover, we have constructed a cycle cover of the representative nodes with the resulting edges. This cycle cover has lower cost than the minimum cycle cover we proposed, which is a contradiction. Therefore, the optimum tour traversing only the representative nodes costs less than the original optimum. \Box

Problem 3-c: It follows that if you repeat this finding and selecting representatives from minimum cycle covers $O(\log n)$ times, you will get a one-vertex graph. Prove that you can unravel all the selections you've done, patching together the various cycles you found to produce a tour of the whole graph whose cost is $O(\log n)$ times the optimum.

Solution: Our algorithm will find $O(\log n)$ minimum cycle covers. We start with our original graph G and find a minimum cost cycle cover using the algorithm we developed in problem 3-a. Next, we select a representative node from each cycle that we obtained from that cover, and create a new graph G_1 . We find a minimum cycle cover of G_1 . We continue recursively until we have a single vertex left in graph $G_{\log n}$.

Once we have a single vertex, we begin to expand out the minimum cycles we have found. We go to the second to last graph with two cycles and connect the two representative vertices we have left using the minimum cycle that was computed. We recursively go down the levels and expand each representative node into the minimum cycles that they belong to. Once we reach the bottom level, we will have a tour over the original graph G of all vertices $v \in V$.

We know this algorithm will terminate because each time we select a set of representative elements, the size of G_i shrinks by a factor of 2, which also implies that the algorithm requires $O(\log n)$ shrinking steps.

It is clear that we end up with a tour at the end of the algorithm, we just need to show that this is an $O(\log n)$ approximation of the optimal TSP. Let x_i be the cost of the cycle cover in G_i . We will show that $x_i \leq OPT$. This follows because $x_i > x_{i+1}$, as we showed in problem 3-b. Moreover, we know that

 $x_1 \leq OPT$ by problem 3-b as well (i.e. the optimum tour traversing only the representative nodes costs less than the original optimum). Therefore, it is clear that $x_i \leq OPT$. Moreover, since there are $O(\log n)$ steps by the fact that the representative set shrinks by a factor of 2 each time, we see that the total cost of the tour that our algorithm outputs is $O(OPT \log n)$.

This is because each cycle in graph G_i adds at most x_i to the cost of the total tour. Since there are $O(\log n)$ of these, we see that our algorithm becomes a $O(\log n)$ approximation of the directed TSP. \square

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Problem Set 9

John Wang
Collaborators:

Problem 4-a: Give a 9-competitive deterministic algorithm for optimizing the total distance travelled up and downstream before you find the bridge. This is optimal for deterministic strategies.

Solution: We will do a galloping binary search. On the *i*th turn of our search, we will move to location $(-2)^i$ on the line. We will continue incrementing *i* for each turn until we find the bridge.

First, it is clear that we will eventually find the bridge. This is because we are sweeping left then right, then back again, and we are moving to cover the interval $[-2^{i-1}, 2^i]$ after i turns have elapsed. If we keep increasing i, it is clear that this interval will eventually expand to contain any point $x \in \mathbb{Z}$.

Now we will show this is 9 competitive. Suppose that the bridge is C distance away. Then the optimal offline algorithm would have been able to go directly from the origin to the bridge, which would cost C distance.

However, our algorithm must move back and forth each time. Notice that at each step, we add a distance of $2^{i-1}+2^i$ since we must first return to the origin in 2^{i-1} time, then cover our 2^i distance. We must continue for $\lceil \lg C \rceil < \lg C + 1$ steps until we find the bridge. However, we might be on the wrong side of the origin even after $\lg C + 1$ steps. We will therefore have to move back to bridge by moving $2^{\lg C + 1}$ distance to get to the origin, then C distance to finish off and get to the bridge. Therefore, we have a total distance of:

(7)
$$1 + 2^{\lg C + 1} + C + \sum_{i=1}^{\lceil \lg C \rceil} 2^i + 2^{i-1} < 1 + C + 2C + \sum_{i=1}^{\lg C + 1} 2^i + 2^{i-1}$$

$$= 1 + 3C + 2^{\lg C + 2} + 2^{\lg C + 1} - 3$$

$$= 3C + 4C + 2C + 1$$

$$(10) < 9C$$

Since our original optimum was a distance of C, we see that the algorithm provides a 9 competitive deterministic algorithm for optimizing the total distance travelled. \Box