NAME: ALI HASSAN HASHIM ALAYAFY

TASK #1- SERVO MOTOR

A servomotor is a linear actuator or rotary actuator that allows for precise control of linear or angular position, acceleration, and velocity

I make a circuit using **tinkercad,** servo motor circuit using both of Arduino uno and servo motor

For the power I use 5v and grd pins, and for the data pin I use pin 13

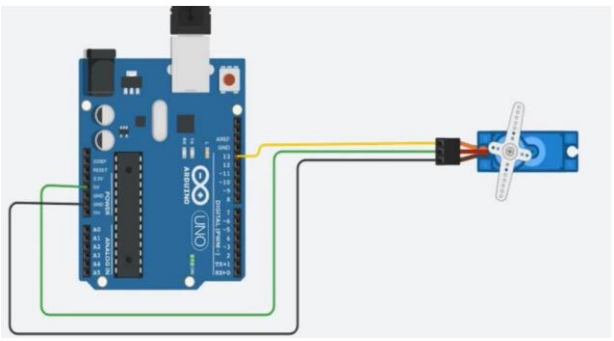

Figure 1 SERVO CIRCUIT DIAGRAM

CODE

```
#include<Servo.h>
Servo servo1;
int pos = 0;
void setup()
{
  servo1.attach(13); // because i have connected signal pin with 13
}

void loop()
{
  // rotate from 0 to 180 degree
  for(pos=0;pos<=180;pos++)
  {
    servo1.write(pos);
    delay(100);
  }

  delay(1000);

  for(pos=180;pos>=0;pos--)
  {
    servo1.write(pos);
    delay(100);
  }
  delay(1000);

}
```

Figure 2 CODE