Supervised Learning Linear Priority Dispatch Rules for Job-Shop Scheduling

Helga Ingimundardottir and Thomas Philip Runarsson

School of Engineering and Natural Sciences, University of Iceland

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Abstract

- Introduction to a framework in which dispatching rules for job-shop scheduling problems (JSSP) are discovered with supervised learning by analyzing characteristics of optimal solutions.
- Ordinal regression implemented to identify good choices from bad at each time step.
- Data-driven method.
- Robust towards scalability and different data distributions.
- Dispatching rules from this new framework outperform the most common single priority-based dispatching rules w.r.t. minimum makespan.
- Experiments on simulated data.



Job Shop Scheduling

- lacksquare Job shop scheduling consists of a set of n jobs that must be scheduled on a set of m machines.
- Each job consists of a number of operations which are processed on the machines in a predetermined order.
- Optimal schedule is the one where the time to complete all jobs is minimal (minimum makespan).

Classical methods for solving JSP

- NP hard problem
- Solved using ad-hoc dispatching rules. A summary of over 100 dispatching rules used in research can be found in [PI77].
- Most effective single priority based dispatch rules:
 - Most work remaining (MWRM)
 - Least work remaining (LWRM)
 - Shortest processing time (SPT)
 - Largest processing time (LPT)

Implementing dispatching rules

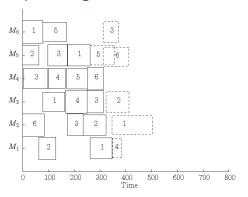


Figure: A schedule being built, the dashed boxes represent six different possible jobs that could be scheduled next using a dispatch rule.



Ordinal regression

- The ranking problem is specified by a set of point/rank pairs
- Mapping of points to ranks: $\{h(\cdot): X \mapsto Y\}$

$$\vec{x}_i \succ \vec{x}_j \quad \Leftrightarrow \quad h(\vec{x}_i) > h(\vec{x}_j)$$

- Ordinal regression: obtain function h^* that can for a given pair (\vec{x}_i, y_i) and (\vec{x}_i, y_i) distinguish between two different outcomes: $y_i > y_i$ and $y_i > y_i$.
- Problem of predicting the relative ordering of all possible pairs of examples

The surrogate considered may be defined by a linear function in the feature space:

$$h(\vec{x}) = \sum_{i=1}^{m} w_i \vec{x} = \langle \vec{w} \cdot \vec{x} \rangle. \tag{1}$$

Training and test data generation

- Determine the order (sequence) of jobs assigned, at the first available time slot (to the left)
- When job is assigned, new state occurs and features are updated
- At each time step, a good/bad ordinal data pair is only created if final makespan is different.
 - At least one or more optimal solution for each JSP
 - Sequence representation is not uniquely determined.



Training size and accuracy

Training size

- Data distributions
 - U(1,100)
 - U(50, 100)
- Size of data sets:

■ Training set: 200

■ Validation set: 100

■ Test set: 200

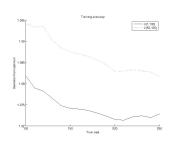


Figure: Deviation from optimal makespan as a function of size of training set. Solid line represents model $lin_{U(1,100)}$ and dashed line represents model $lin_{U(50,100)}$.

Training accuracy

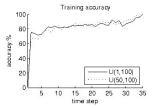


Figure: Training accuracy as a function of time. Solid line represents model $lin_{U(1,100)}$ and dashed line represents data distributions $lin_{U(50,100)}$

Experimental study

Comparing different dispatching rules

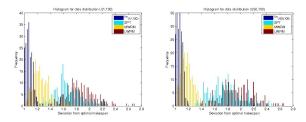


Figure: Histogram of deviation from optimal makespan for the dispatching rules $(lin_{U(R,100)})$, (SPT), (MWRM) and (LWRM). The figure on the left depicts model $lin_{U(1,100)}$, and the figure on the right is of model $lin_{U(50,100)}$.



Experimental study

Comparing different dispatching rules

Comparing different dispatching rules

U(1, 100)	mean	std	med	min	max
$lin_{U(1,100)}$	1.0842	0.0536	1.0785	1.0000	1.2722
SPT	1.6707	0.2160	1.6365	1.1654	2.2500
MWRM	1.2595	0.1307	1.2350	1.0000	1.7288
LWRM	1.8589	0.2292	1.8368	1.2907	2.6906

U(50, 100)	mean	std	med	mın	max
$lin_{U(50,100)}$	1.0724	0.0446	1.0713	1.0000	1.2159
SPT	1.7689	0.2514	1.7526	1.2047	2.5367
MWRM	1.1835	0.0994	1.1699	1.0217	1.5561
LWRM	1.9422	0.2465	1.9210	1.3916	2.6642

Table: Mean value, standard deviation, median value, minimum and maximum values using the test sets corresponding to data distributions U(1,100) (above) and U(50,100) (below) .



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Robustness towards data distribution

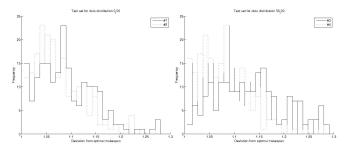


Figure: Histogram of deviation from optimal makespan for the dispatching rules using model trained on either U(1,100) or U(50,100) and tested on both U(1,100) (left) and U(50,100) (right).

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Robustness towards data distribution

	model	test set	mean	std	med	min	max
#1	$lin_{U(1,100)}$	U(1, 100)	1.0844	0.0535	1.0786	1.0000	1.2722
#2	$lin_{U(50,100)}$	U(1, 100)	1.0709	0.0497	1.0626	1.0000	1.2503
	$lin_{U(1,100)}$	U(50, 100)	1.1429	0.1115	1.1158	1.0000	1.5963
	$lin_{U(50,100)}$	U(50, 100)	1.0724	0.0446	1.0713	1.0000	1.2159

Table: Mean value, standard deviation, median value, minimum and maximum values for the test sets corresponding to data distributions U(1,100) and U(50,100), on both models $lin_{U(1,100)}$ and $lin_{U(50,100)}$.

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Feature selection

weight	$lin_{U(1,100)}$	$lin_{U(50,100)}$	description
$\bar{w}(1)$	-0.6712	-0.2220	processing time for job on machine
$\bar{w}(2)$	-0.9785	-0.9195	work remaining
$\bar{w}(3)$	-1.0549	-0.9059	start-time
$\bar{w}(4)$	-0.7128	-0.6274	end-time
$\bar{w}(5)$	-0.3268	0.0103	when machine is next free
$\bar{w}(6)$	1.8678	1.3710	current makespan
$\bar{w}(7)$	-1.5607	-1.6290	slack time for this particular machine
$\bar{w}(8)$	-0.7511	-0.7607	slack time for all machines
$\bar{w}(9)$	-0.2664	-0.3639	slack time weighted w.r.t. number of
			operations already assigned

Table: Mean value, standard deviation, median value, minimum and maximum values for the test sets corresponding to data distributions U(1,100) and U(50,100), on both models $lin_{U(1,100)}$ and $lin_{U(50,100)}$.



Fixed weights vs. varied weights

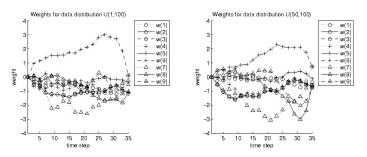


Figure: Weights of features as a function of time, for data distribution U(1,100) (left) and U(50,100) (right).



Robustness towards data distribution using fixed weights

	model	test set	mean	std	med	min	max
#1	$l\bar{i}n_{U(1,100)}$	U(1, 100)	1.0862	0.0580	1.0785	1.0000	1.2722
#2	$l\bar{i}n_{U(50,100)}$	U(1, 100)	1.0706	0.0493	1.0597	1.0000	1.2204
#3	$l\bar{i}n_{U(1,100)}$	U(50, 100)	1.1356	0.0791	1.1296	1.0000	1.5284
#4	$l\bar{i}n_{U(50,100)}$	U(50, 100)	1.0695	0.0459	1.0658	1.0000	1.2201

Table: Mean value, standard deviation, median value, minimum and maximum values for the test sets corresponding to data distributions U(1,100) and U(50,100), on both fixed weight models $l\bar{i}n_{U(1,100)}$ and $l\bar{i}n_{U(50,100)}$.

Future work

- Overcome problems due to non unique sequence representation of JSP
- Other learning methods, e.g. reinforcement learning;
- Other data distributions and dimensions of JSP

References

References



S.S. Panwalkar and W. Iskander.

A Survey of Scheduling Rules.

Operations Research, 25(1):45-61, January 1977.