Practical Performance Practices

CppCon 2016 - This session only works if you interact!

Please come forward.

Jason Turner

- http://github.com/lefticus/presentations
- http://cppcast.com
- http://chaiscript.com
- http://cppbestpractices.com
- C++ Weekly YouTube Series
- @lefticus
- Independent Contractor
- http://articles.emptycrate.com/idocpp

I prefer an interactive session - please ask questions

```
#include <string>
int main()
{
   std::string s("a");
   return s.size();
}
```

g++ 5.1+

```
main:
    mov     eax, 1
    ret
```

```
#include <string>
int main()
{
  return std::string("a").size() + std::string("b").size();
}
```

```
.LCO:
        .string "basic string:: M construct null not valid"
void std:: cxx11::basic string<char, std::char traits<char>, std::allocator<char> >::
              rbp
       mov r12, rsi
              .L4
       mov edi, OFFSET FLAT:.LCO
               std:: throw logic error(char const*)
              rbx, rdx
              rbx, r12
              rdi, QWORD PTR [rbp+0]
               eax, BYTE PTR [r12]
               BYTE PTR [rdi], al
```

```
.L17:
               rsi, [rsp+8]
               edx, edx
               rdi, rbp
                std:: cxx11::basic string<char, std::char traits<char>, std::allocato
               rdx, \overline{QWORD} PTR [rsp+8]
               QWORD PTR [rbp+0], rax
               rdi, rax
                QWORD PTR [rbp+16], rdx
.L5:
               rdx, rbx
               rsi, r12
                memcpy
               rax, QWORD PTR [rsp+8]
              BYTE PTR [rdx+rax], 0
               rsp, 16
               rbx
        .string "a"
.LC3:
```

```
main:
               rbx
               edx, OFFSET FLAT: LC2+1
              esi, OFFSET FLAT: LC2
       lea rax, [rsp+16]
       mov rdi, rsp
              void std:: cxx11::basic string<char, std::char traits<char>, std::all
               rax, [rsp+48]
              rdi, [rsp+32]
              edx, OFFSET FLAT: LC3+1
              esi, OFFSET FLAT:.LC3
              rbx, QWORD PTR [rsp+8]
              QWORD PTR [rsp+32], rax
               void std:: cxx11::basic string<char, std::char traits<char>, std::all
               rdi, QWORD PTR [rsp+32]
               rax, [rsp+48]
               ebx, DWORD PTR [rsp+40]
               rdi, rax
               operator delete(void*)
               rdi, QWORD PTR [rsp]
               rdi, rax
               .L24
               operator delete(void*)
```

```
add rsp, 64
mov eax, ebx
pop rbx
ret
mov rdi, QWORD PTR [rsp]
lea rdx, [rsp+16]
mov rbx, rax
cmp rdi, rdx
je .L22
call operator delete(void*)

.L22:
mov rdi, rbx
call _Unwind_Resume
```

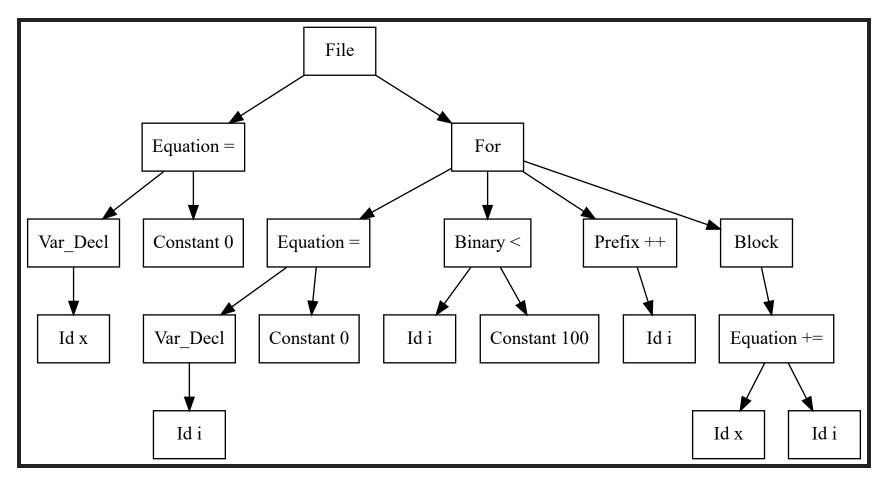
 But trying to predict what the compiler can optimize is a risky game

Profiling ChaiScript

- Performance measuring ChaiScript is difficult
- Great number of template instantations
- Nature of scripting means execution is spread over many similar functions

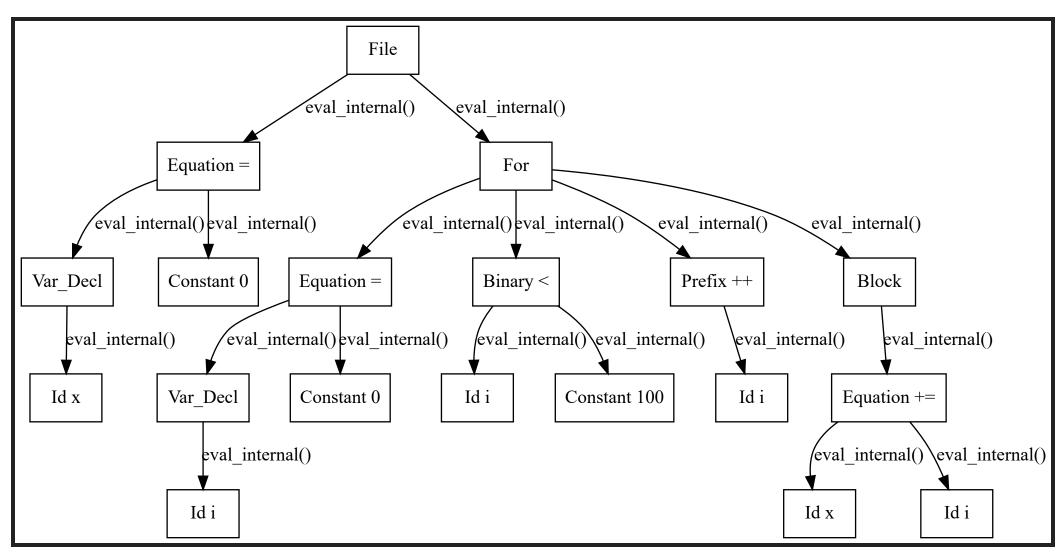
Parsed Nodes

```
var x = 0;
for (var i = 0; i < 100; ++i) {
  x += i;
}</pre>
```

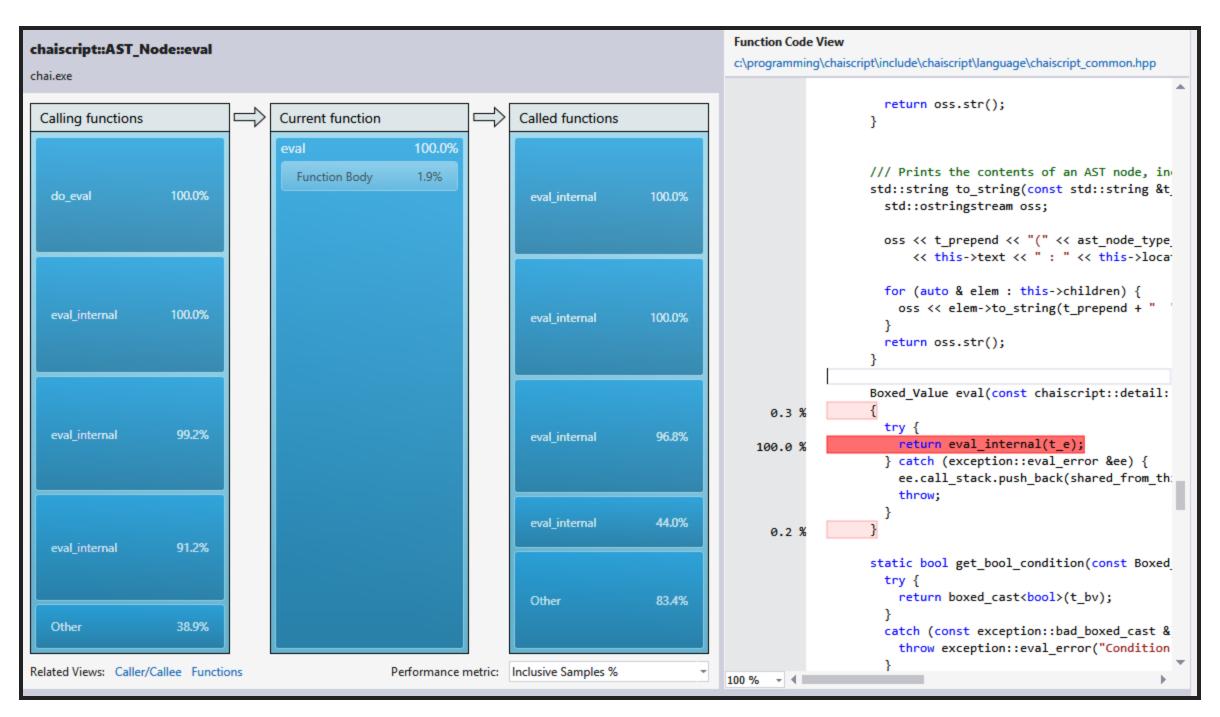


Parsed Nodes

```
var x = 0;
for (var i = 0; i < 100; ++i) {
   x += i;
}</pre>
```



Performance Profiling



Performance Practices

This led to the creation of several rules and practices that I follow to make well-performing code 'by default'

Which Is Better In Normal Use?

std::vector

- or -

std::list

• WHY?

```
int main()
{
   std::list<int> v{1};
}
```

• What has to happen here?

```
main:
               %r12
       pushq
               %rbp
       pushq
               $24, %edi
        movl
        pushq
               %rbx
               $32, %rsp
        subq
               $0, 16(%rsp)
              %rsp, %rbp
              %rsp, (%rsp)
              %rsp, 8(%rsp)
       call     operator new(unsigned long)
               %rax, %rdi
               $0, (%rax)
               $0, 8(%rax)
               $1, 16(%rax)
       movl
               %rsp, %rsi
               std:: detail:: List node base:: M hook(std:: detail:: List node base
               (%rsp), %rdi
               $1, 16(%rsp)
        addq
               %rsp, %rdi
        cmpq
                .L9
```

```
.L10:
              (%rdi), %rbp
               operator delete(void*)
              %rbx, %rbp
       cmpq
               %rbp, %rdi
               .L10
.L9:
               $32, %rsp
       addq
       xorl
               %eax, %eax
               %rbx
       popq
               %rbp
       popq
               %r12
       popq
               (%rsp), %rdi
               %rax, %rbp
```

- Allocate a new node
- Handle exception thrown during node allocation?
- Assign the value
- Hook up some pointers
- Delete node
- etc?

std::vector

std::vector

```
int main()
{
   std::vector<int> v{1};
}
```

• What has to happen here?

std::vector

```
main:
    subq $8, %rsp
    movl $4, %edi
    call operator new(unsigned long)
    movl $1, (%rax)
    movq %rax, %rdi
    call operator delete(void*)
    xorl %eax, %eax
    addq $8, %rsp
    ret
```

- Allocate a buffer
- Assign a value in the buffer
- Delete the buffer

Part 1: Don't Do More Work Than You Have To

What about std::array?

```
int main()
{
   std::array<int, 1> v{1};
}
```

What about std::array?

Code is completely compiled away

Don't Do More Work Than You Have To Container Practices

- Always prefer std::array
- Then std::vector
- Then only differ if you need specific behavior
- Make sure you understand what the library has to do

```
int main()
{
   std::string s;
   s = "A Somewhat Rather Long String";
}
```

- Construct a string object
- Reassign string object

Always const

```
int main()
{
   const std::string s = "A Somewhat Rather Long String";
}
```

- Construct and initialize in one step
- ~32% more efficient

Always const - Complex Initialization

```
int main()
{
   const int i = std::rand();
   std::string s;
   switch (i % 4) {
      case 0:
        s = "long string is mod 0";
        break;
   case 1:
        s = "long string is mod 1";
        break;
   case 2:
        s = "long string is mod 2";
        break;
   case 3:
        s = "long string is mod 3";
        break;
}
```

• How can we make [s][const] in this context?

Always const - Complex Initialization - Use IIFE

```
int main()
{
    const int i = std::rand();
    const std::string s = [&](){
        switch (i % 4) {
            case 0:
                return "long string is mod 0";
            case 1:
                 return "long string is mod 1";
            case 2:
                 return "long string is mod 2";
            case 3:
                 return "long string is mod 3";
            }
        }();
}
```

~31% more efficient

Always Initialize When Const Isn't Practical

```
struct Int
{
    Int(std::string t_s)
    {
        m_s = t_s;
    }
    int val() const {
        return std::atoi(m_s.c_str());
    }
    std::string m_s;
};
```

 Same issues as previous examples

Always Initialize When Const Isn't Practical

```
struct Int
{
    Int(std::string t_s) : m_s(std::move(t_s))
    {
       int val() const {
         return std::atoi(m_s.c_str());
      }
      std::string m_s;
};
```

- Same gains as const initializer
- What's wrong with this version now?
- val() parses string on each call

Don't Recalculate Values - Calculate on First Use

```
struct Int
{
    Int(std::string t_s) : s(std::move(t_s))
    {
        int val() const {
            if (!is_calculated) {
                value = std::atoi(s);
        }
        return value;
    }

    mutable bool is_calculated = false;
    mutable int value;
    std::string s;
};
```

- What's wrong now?
- C++ Core Guidelines state that const methods should be thread safe
- What else?
- is_calculated isn't being set

Don't Recalculate Values - Calculate On First Use

```
struct Int
{
   Int(std::string t_s) : s(std::move(t_s))
   {
    int val() const {
        if (!is_calculated) {
            value = std::atoi(s);
            is_calculated = true;
        }
        return value;
   }
   mutable std::atomic_bool is_calculated = false;
   mutable std::atomic_int value;
   std::string s;
};
```

- Branching is slower
- Atomics are slower

Don't Recalculate Values - Calculate At Construction

```
struct Int
{
    Int(const std::string &t_s) : m_i(std::atoi(t_s.c_str()))
    { }
    int val() const {
        return m_i;
    }
    int m_i;
};
```

- No branching, no atomics, smaller runtime (int vs string)
- In the context of a large code base, this took ~2 years to find
- Resulted in 10% performance improvement across system
- The simpler solution is almost always the best solution

Initialization Practices

- Always const
- Always initialize
- Using IIFE can help you initialize
- Don't recalculate values that can be calculated once

```
struct Base {
  virtual ~Base() = default;
  virtual void do_a_thing() = 0;
};

struct Derived: Base {
  virtual ~Derived() = default;
  void do_a_thing() override {}
};
```

- What's wrong here?
- move construction / assignment is disabled (virtual destructor)
- virtual ~Derived() is unnecessary

Don't Disable Move Operations / Use Rule of 0

```
struct Base {
  virtual ~Base() = default;
  Base() = default;
  Base(const Base &) = default; Base& operator=(const Base&) = default;
  Base(Base &&) = default; Base& operator=(Base &&) = default;

  virtual void do_a_thing() = 0;
};

struct Derived : Base {
  virtual void do_a_thing() {}
};
```

 10% improvement with fixing this in just one commonly used class

On The Topic Of Copying

```
#include <string>
struct S {
    S(std::string t_s) : s(std::move(t_s)) {}
    std::string s;
};

int main()
{
    for (int i = 0; i < 10000000; ++i) {
        std::string s = std::string("a not very short string") + "b";
        S o(s);
    }
}</pre>
```

- We all know that copying objects is bad
- So let's use std::move

On The Topic Of Copying

```
#include <string>
struct S {
    S(std::string t_s) : s(std::move(t_s)) {}
    std::string s;
};

int main() {
    for (int i = 0; i < 10000000; ++i) {
        std::string s = std::string("a not very short string") + "b";
        S o(std::move(s));
    }
}</pre>
```

- 29% more efficient
- 32% smaller binary
- Good! But what's better?

Avoid Named Temporaries

```
#include <string>
struct S {
    S(std::string t_s) : s(std::move(t_s)) {}
    std::string s;
};

int main()
{
    for (int i = 0; i < 10000000; ++i) {
        S o(std::string("a not very short string") + "b");
    }
}</pre>
```

- 2% more efficient again
- Can lead to less readable code sometimes, but more maintainable than std::move calls
- This is taking the "don't declare a variable until you need it" philosophy to its ultimate conclusion

```
int use_a_base(std::shared_ptr<Base> p)
{
   return p->value();
}
int main()
{
   auto ptr = std::make_shared<Derived>();
   use_a_base(ptr);
}
```

- What's the problem here?
- Copies are being made of [shared_ptr<Base>]

Avoid (shared_ptr) Copies

```
int use_a_base(const std::shared_ptr<Base> &p)
{
   return p->value();
}
int main()
{
   auto ptr = std::make_shared<Derived>();
   use_a_base(ptr);
}
```

- Fixed!
- Right?
- Wrong!

Avoid Automatic Conversions

```
int use_a_base(const Base &p)
{
   return p->value();
}
int main()
{
   auto ptr = std::make_shared<Derived>();
   use_a_base(ptr.get());
}
```

• This version is 2.5x faster than the last

std::endl

```
void println(ostream &os, const std::string &str)
{
  os << str << std::endl;
}</pre>
```

- What does std::endl do?
- it's equivalent to '\n' << std::flush
- Expect that flush to cost you at least 9x overhead in your
 IO

Real World std::endl Anecdote

```
void write_file(std::ostream &os) {
  os << "a line of text" << std::endl;
  os << "another line of text" << std::endl;
  /* snip */
  os << "many more lines of text" << std::endl;
}

void write_file(const std::string &filename) {
  std::ofstream ofs(filename.c_str());
  write_file(ofs);
}

std::string get_file_as_string() {
  std::stringstream ss;
  write_file(ss);
  return ss.str();
}</pre>
```

Avoid std::endl

Prefer just using ['\n']

```
void println(ostream &os, const std::string &str)
{
  os << str << '\n';
}</pre>
```

Don't Do More Work Than You Have To Hidden Work Practices

- Calculate values once at initialization time
- Obey the rule of 0
- If it looks simpler, it's probably faster
- Avoid object copying
- Avoid automatic conversions
 - Don't pass smart pointers
 - Make conversion operations explicit
- Avoid std::endl

```
int main() {
  std::make_shared<int>(1);
}
```

```
std:: Sp counted ptr inplace<int, std::allocator<int>, ( gnu cxx:: Lock policy)2>::~
std:: Sp counted ptr inplace<int, std::allocator<int>, ( gnu cxx:: Lock policy)2>:: M
std:: Sp counted ptr inplace<int, std::allocator<int>, ( gnu cxx:: Lock policy)2>:: M
              8(%rsi), %rsi
              %rdi, %rdx
               typeinfo name for std:: Sp make shared tag, %rsi
       cmpq
               .L4
              %eax, %eax
       xorl
              $42, (%rsi)
       cmpb
       movl typeinfo name for std:: Sp make shared tag, %edi
              $24, %ecx
       movl
.L4:
       leaq
              16(%rdx), %rax
```

```
.L3:
std:: Sp counted ptr inplace<int, std::allocator<int>, ( gnu cxx:: Lock policy)2>::~
       movl $24, %esi
               operator delete(void*, unsigned long)
std:: Sp counted ptr inplace<int, std::allocator<int>, ( gnu cxx:: Lock policy)2>:: M
               operator delete(void*)
main:
       pushq %rbx
       movl
              $24, %edi
              operator new(unsigned long)
              %rax, %rbx
              $1, 8(%rax)
       movl
              $1, 12(%rax)
       movl
              vtable for std:: Sp counted ptr inplace<int, std::allocator<int>, ( g
               $0, 16(%rax)
       movl
               gthrw pthread key create(unsigned int*, void (*)(void*)), %eax
       movl
               %rax, %rax
        testq
               8(%rbx), %rdi
       leaq
       orl
               $-1, %esi
                gnu cxx:: exchange and add(int volatile*, int)
               \frac{-}{\$1}, \$eax
       subl
```

```
.L22:
       xorl
               %eax, %eax
               %rbx
       popq
.L17:
       movl $0, 8(%rbx)
              $0, 12(%rbx)
       movl
.L23:
              (%rbx), %rax
              %rbx, %rdi
              24(%rax), %rax
              *%rax
               .L22
              (%rbx), %rax
              %rbx, %rdi
              16(%rax), %rax
              *%rax
              12(%rbx), %rdi
       leaq
              $-1, %esi
       orl
               gnu cxx:: exchange and add(int volatile*, int)
              $1, %eax
       subl
               .L22
```

unique_ptr Instantiations

unique_ptr Instantiations

```
int main()
{
   std::make_unique<int>(0);
}
```

What does this have to do?

unique_ptr Instantiations

```
int main()
{
   std::make_unique<int>(0);
}
```

```
main:
    sub    rsp, 8
    mov    edi, 4
    call    operator new(unsigned long)
    mov    esi, 4
    mov    DWORD PTR [rax], 0
    mov    rdi, rax
    call    operator delete(void*, unsigned long)
    xor    eax, eax
    add    rsp, 8
    ret
```

unique_ptr Compared To Manual Memory Management

```
int main()
{
  auto i = new int(0);
  delete i;
}
```

```
main:
    sub     rsp, 8
    mov     edi, 4
    call     operator new(unsigned long)
    mov     esi, 4
    mov     DWORD PTR [rax], 0
    mov     rdi, rax
    call     operator delete(void*, unsigned long)
    xor     eax, eax
    add     rsp, 8
    ret
```

Identical

Part 1: Don't Do More Work Than You Have To - Summary

- Avoid shared_ptr
- Avoid std::endl
- Always const
- Always initialize with meaningful values
- Don't recalculate immutable results

Part 1: Questions?

Part 2: Smaller Code Is Faster Code

```
struct B
{
    virtual ~B() = default; // plus the other default operations
    virtual std::vector<int> get_vec() const = 0;
};

template<typename T>
struct D : B
{
    std::vector<int> get_vec() const override { return m_v; }
    std::vector<int> m_v;
}
```

 With many template instantiations this code blows up in size quickly

DRY In Templates

```
struct B
{
    virtual ~B() = default; // plus the other default operations
    virtual std::vector<int> get_vec() const { return m_v; }
    std::vector<int> m_v;
};

template<typename T>
struct D : B
{
}
```

Factories

Factories

```
struct B {
   virtual ~B() = default;
};

template<int T>
struct D : B {
};

template<int T>
std::shared_ptr<B> d_factory() {
   return std::make_shared<D<T>>();
}

int main() {
   std::vector<std::shared_ptr<B>> v{
      d_factory<1>(), d_factory<2>(), /* ... */ , d_factory<29>(), d_factory<30>()
   };
}
```

- Prefer returning unique_ptr<> (Back To The Basics Herb Sutter ~0:19)
- We already saw that [shared_ptr<>] is big don't make more than you have

Prefer return unique_ptr<> from factories

```
struct B {
   virtual ~B() = default;
};

template<int T>
struct D : B {
};

template<int T>
std::unique_ptr<B> d_factory() {
   return std::make_unique<D<T>>();
}

int main() {
   std::vector<std::shared_ptr<B>> v{
      d_factory<1>(), d_factory<2>(), /* ... */ , d_factory<29>(), d_factory<30>()
   };
}
```

Prefer return unique_ptr<> from factories

```
template<int T> std::unique_ptr<B> d_factory()
{
   return std::make_unique<D<T>>();
}
```

1.30s compile, 30k exe, 149796k compile RAM

```
template<int T> std::shared_ptr<B> d_factory()
{
   return std::make_shared<D<T>>();
}
```

2.24s compile, 70k exe, 164808k compile RAM

```
template<int T> std::shared_ptr<B> d_factory()
{
   return std::make_unique<D<T>>();
}
```

2.43s compile, 91k exe, 190044k compile RAM

Prefer return unique_ptr<> from factories - ChaiScript
Numbers

```
std::unique_ptr<B> d_factory()
{
   return std::make_unique<D>();
}
```

4925k exe

```
std::shared_ptr<B> d_factory()
{
   return std::make_shared<D>();
}
```

7350k exe, ~6% slower

```
std::shared_ptr<B> d_factory()
{
  return std::make_unique<D>();
}
```

7573k exe, ~10% slower (very surprising when I found this bottleneck)

Prefer return unique_ptr<> from factories - A Note About Performance

```
template<int T> std::shared_ptr<B> d_factory()
{
   return std::make_shared<D<T>>();
}
```

- This make_shared version is faster in raw performance
- If you create many short-lived shared objects, the [make_shared] version is fastest
- If you create long-lived shared objects, use the [make_unique] version is fastest
- C++ Core Guidelines are surprisingly inconsistent in examples for factories

Smaller Code Is Faster Code

Avoid std::function<>

- 2.9x slower than bare function call
- 30% compile time overhead
- ~10% compile size overhead

Smaller Code Is Faster Code

Never. Ever. Ever. Use std::bind

```
std::string add(const std::string &lhs, const std::string &rhs) {
  return lhs + rhs;
}
int main() {
  const auto f = std::bind(add, "Hello ", std::placeholders::_1);
  f("World");
}
```

- 1.9x slower than bare function call
- ~15% compile time overhead
- Effective Modern C++ #34
- Any talk on std::function from STL

Smaller Code Is Faster Code

Use Lambdas

```
std::string add(const std::string &lhs, const std::string &rhs) {
  return lhs + rhs;
}
int main() {
  const auto f = [](const std::string &b) {
    return add("Hello ", b);
  };
  f("World");
}
```

- 0 overhead compared to direct function call
- 0% compile time overhead

Part 2: Smaller Code Is Faster Code - Summary

- Don't repeat yourself in templates
- Avoid use of shared_ptr:
- Avoid std::function
- Never use std::bind

Part 2: Smaller Code Is Faster Code - Questions

Bonus Slide - Avoid Non-Local Data Non-Locals Tend To

- 1. Be statics which have a cost associated
- 2. Need some kind of mutex protection
- 3. Be in a container with on-trivial lookup costs ([std::map<>] for example)

Summary

• First ask yourself: What am I asking the compiler to do here?

Initialization Practices

- Always const
- Always initialize

Hidden Work Practices

- Calculate values once at initialization time
- Obey the rule of 0
- If it looks simpler, it's probably faster
- Avoid automatic conversions use explicit
- avoid std::endl

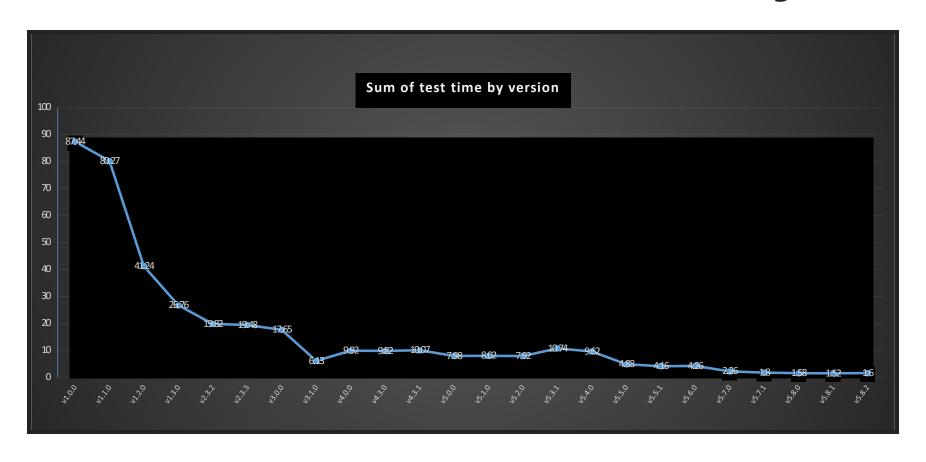
Summary (Continued) Container Practices

- Always prefer std::array
- Then std::vector
- Then only differ if you need specific behavior
- Make sure you understand what the library has to do

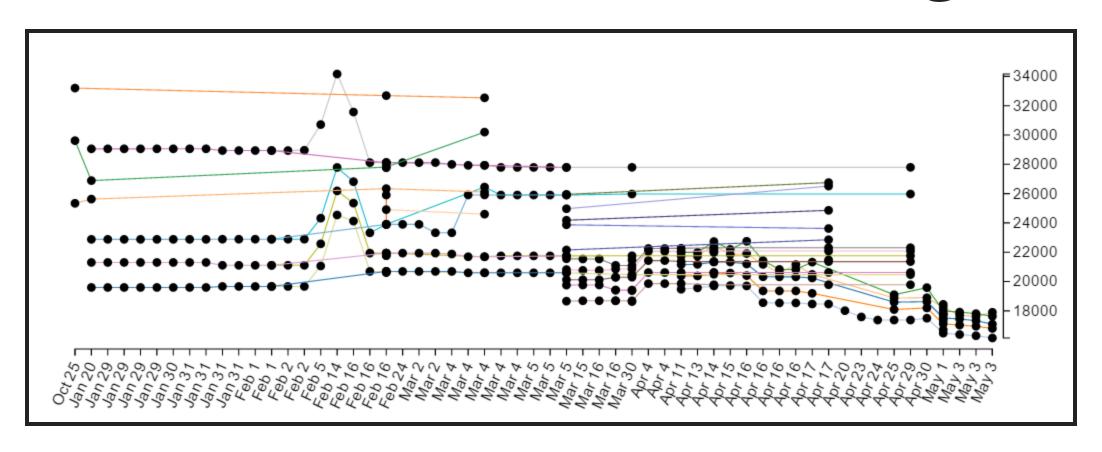
Smaller Code Is Faster Code Practices

- Don't repeat yourself in templates
- Avoid use of std::shared_ptr
- Avoid std::function
- Neveruse:std::bind

Performance History



Performance Monitoring



What About constexpr?

What About constexpr?

```
template<typename Itr>
constexpr bool is sorted(Itr begin, const Itr &end)
 Itr start = begin;
  ++begin;
  while (begin != end) {
   if (!(*start < *begin)) { return false; }</pre>
   start = begin;
   ++begin;
  return true;
template<typename T>
constexpr bool is sorted(const std::initializer list<T> &1) {
  return is sorted(l.begin(), l.end());
int main()
 return is sorted({1,2,3,4,5});
```

What About constexpr?

```
main:
    mov eax, 1
    ret
```

What About Not constexpr?

```
template<typename Itr>
bool is sorted(Itr begin, const Itr &end)
  Itr start = begin;
  ++begin;
  while (begin != end) {
    if (!(*start < *begin)) { return false; }</pre>
    start = begin;
    ++begin;
  return true;
template<typename T>
bool is sorted(const std::initializer list<T> &1) {
  return is sorted(l.begin(), l.end());
  return is sorted(\{1, 2, 3, 4, 5\});
```

 What does this compile to?

What About *Not* constexpr? (with optimizations enabled)

```
main:
    mov eax, 1
    ret
```

constexpr

- Full constexpr enabling of every data structure that can be can result in bigger code
- Bigger code is often slower code
- If you enable constexpr make sure you go all the way

A Quick Note On final

- Proper use of final can help the compiler optimize virtual function calls.
- If you know that a class or method will be the <code>final</code> version, mark it as such

So Why Does This All Work?

So Why Does This All Work? Branches and Predictions

- Code branches are expensive
- Simpler code has fewer branches
- (According to oprofile) ChaiScript v5.8.3 has 1.86x fewer branches then v5.1.0, and 3x the branch prediction success rate

So Why Does This All Work? Cache Hits

- CPU cache is many (hundreds of) times faster than main memory
- Smaller code (and simpler code is smaller) is more likely to fit in to the CPU cache
- (According to oprofile) ChaiScript v5.8.3 hits the Last Level Cache 35x less often than v5.1.0, and has 1% better cache hits rates when it does

So Why Does This All Work? Doing What The Compiler Author Expects

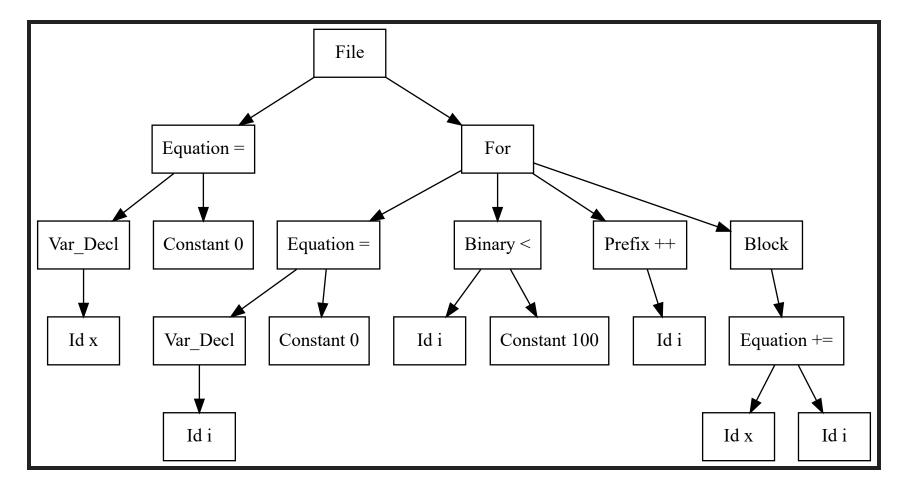
- Idiomatic C++ falls into certain patterns that compiler authors expect to find
- Well known patterns can be optimized better

What's Next?

What's Next?

Simplifying User Input - Before

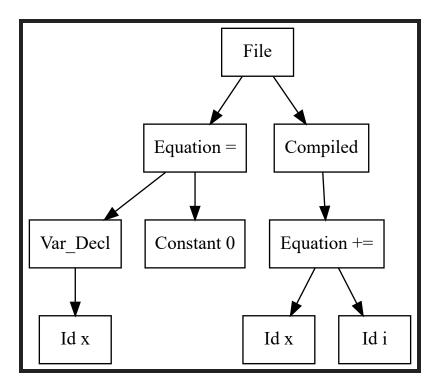
```
var x = 0;
for (var i = 0; i < 100; ++i) {
  x += i;
}</pre>
```



What's Next?

Simplifying User Input - After

```
var x = 0;
for (var i = 0; i < 100; ++i) {
   x += i;
}</pre>
```



What's Next? Simplifying User Input

Nearly every project of significance relies on user input.

Are there ways you can simplify your user input to make the execution of your program faster?

Questions? Jason Turner

- http://github.com/lefticus/presentations
- http://cppcast.com
- http://chaiscript.com
- http://cppbestpractices.com
- C++ Weekly YouTube
- @lefticus
- Independent Contractor
- http://articles.emptycrate.com/idocpp
- Coupons!