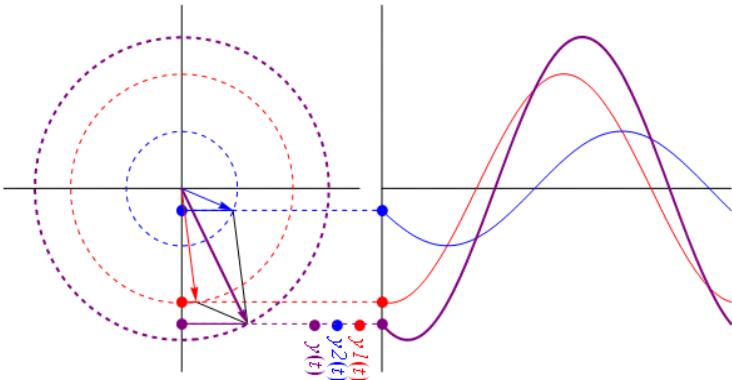


IV International Workshop on Synchrophasor Applications

***The Ecuadorian Wide Area Monitoring,
Protection and Control System - WAMPAC***

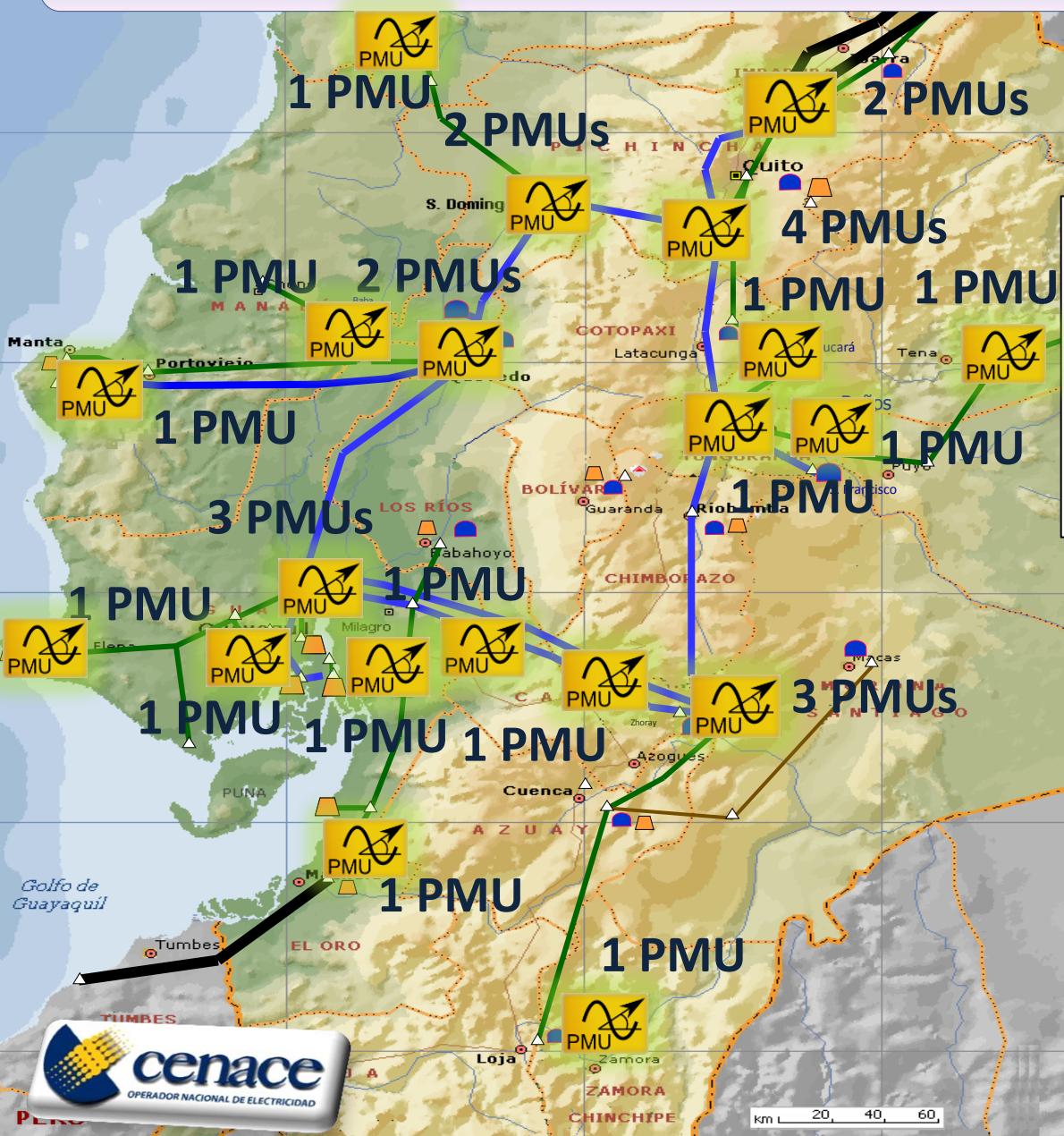


Dr.-Ing. Jaime Cepeda

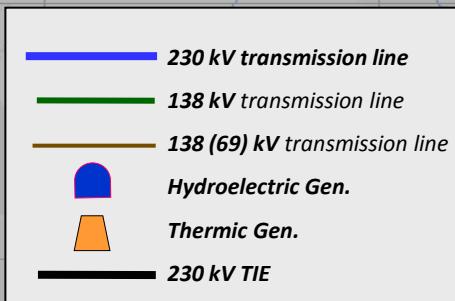
cepedajaim@ieee.org
jcepeda@cenace.org.ec

November 29, 2016

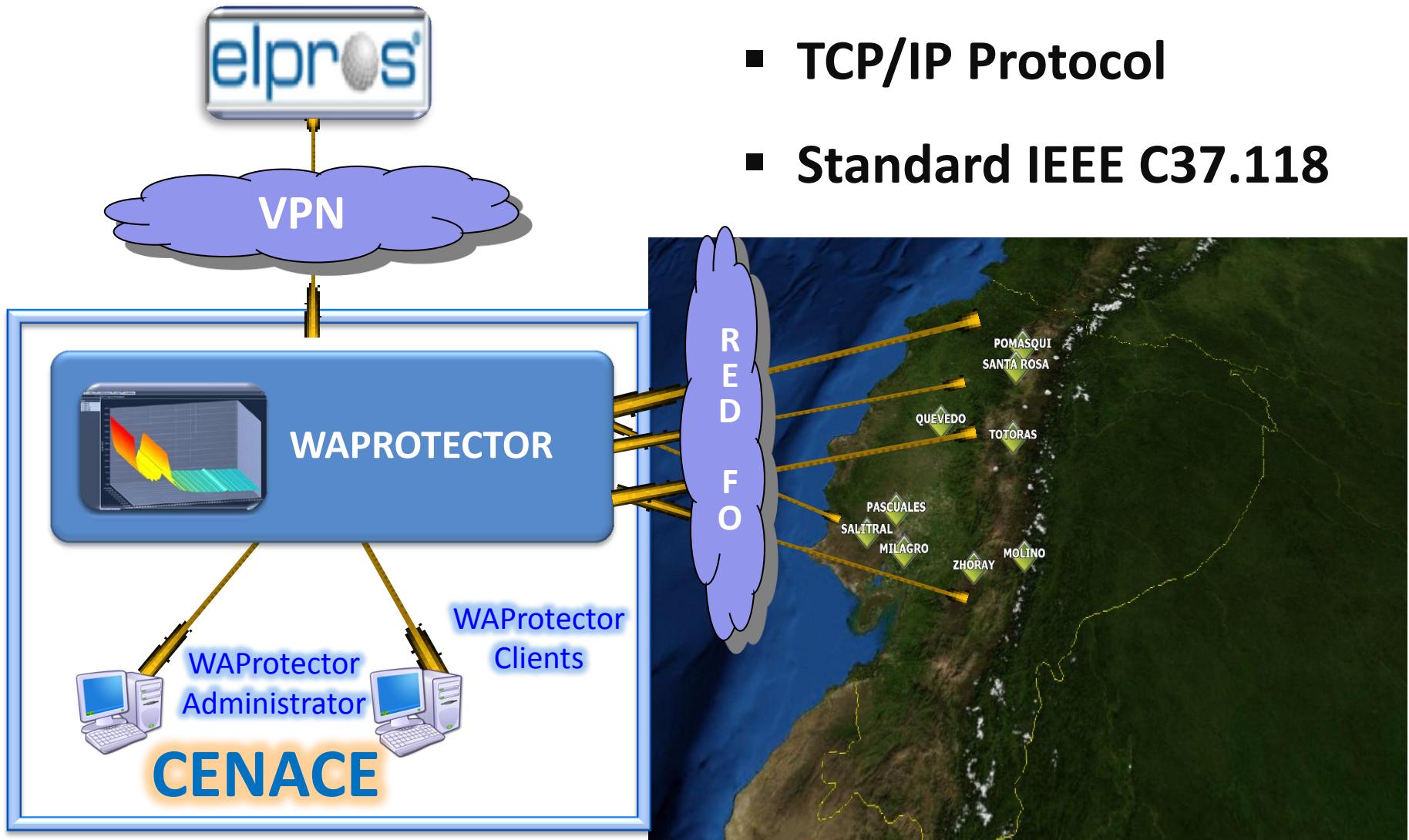
PMUs installed at Sistema Nacional Interconectado



- 30 PMUs Arbiter model 1133A
- Phasor Data Concentrator PDC based on Software located at CENACE



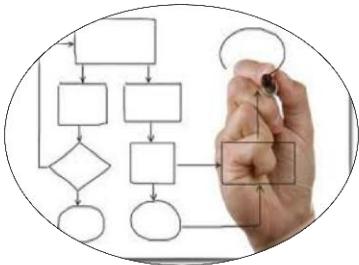
WAMS Platform - WAProtector



Independent System Operator - ISO



Synchronized Phasor Measurement Applications - ISO



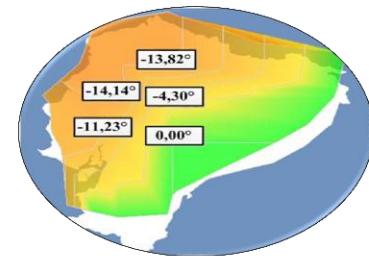
PLANNING

- PMU location
- Parametrization of WAMS Applications
- Dispatch based on security constraints
- PSS tuning
- Design of wide area protection and control schemes
- Model parameter identification



REAL TIME OPERATION

- Static and dynamic security state Monitoring
- Early warning
- Situational awareness
- Control
- Protection
- Operators' Training

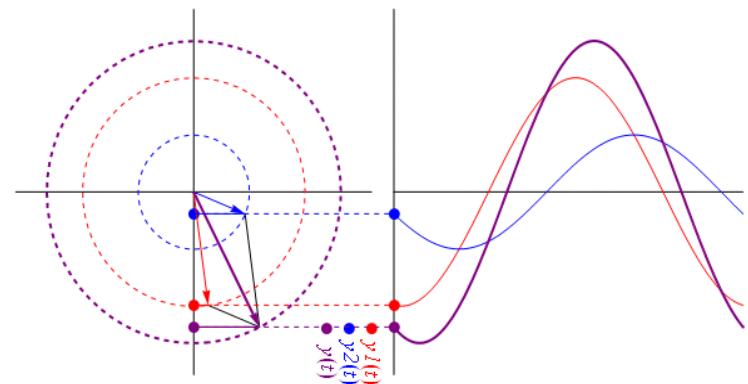
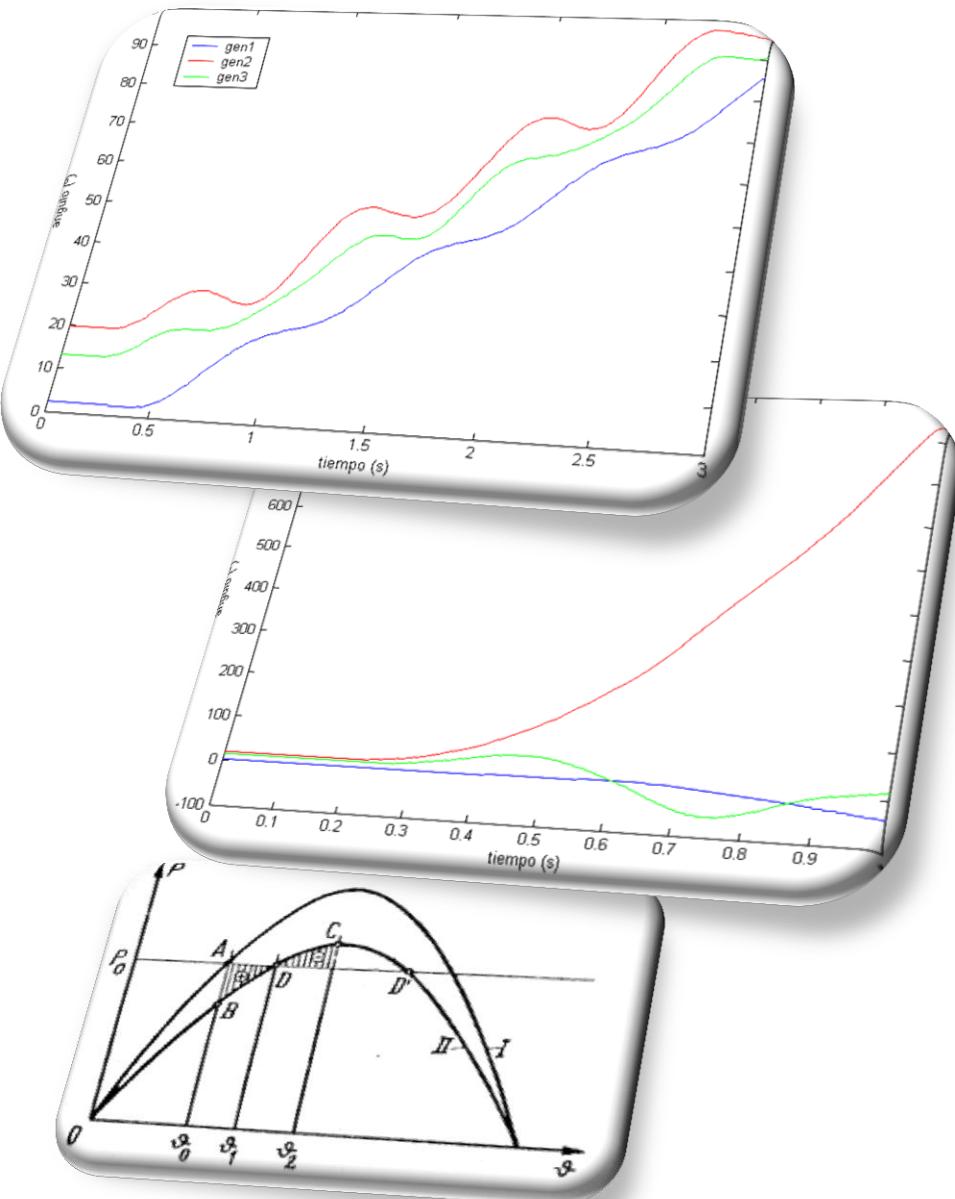


POST-OPERATIVE ANALYSIS

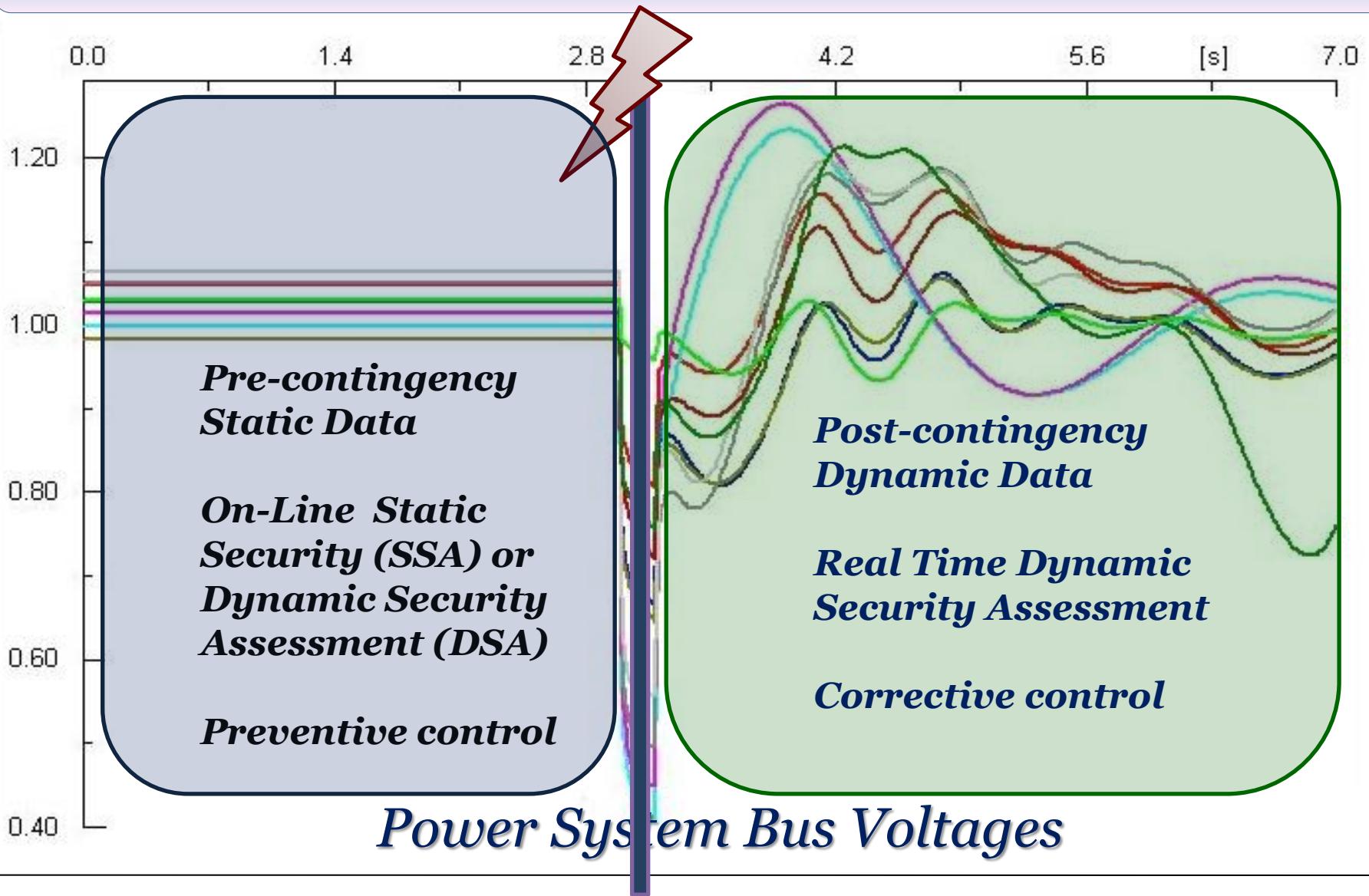
- Post-Mortem Analysis
- Static security statistics
- Dynamic security statistics
- Vulnerability status patterns identification
- Power Quality analysis



Real Time Operation



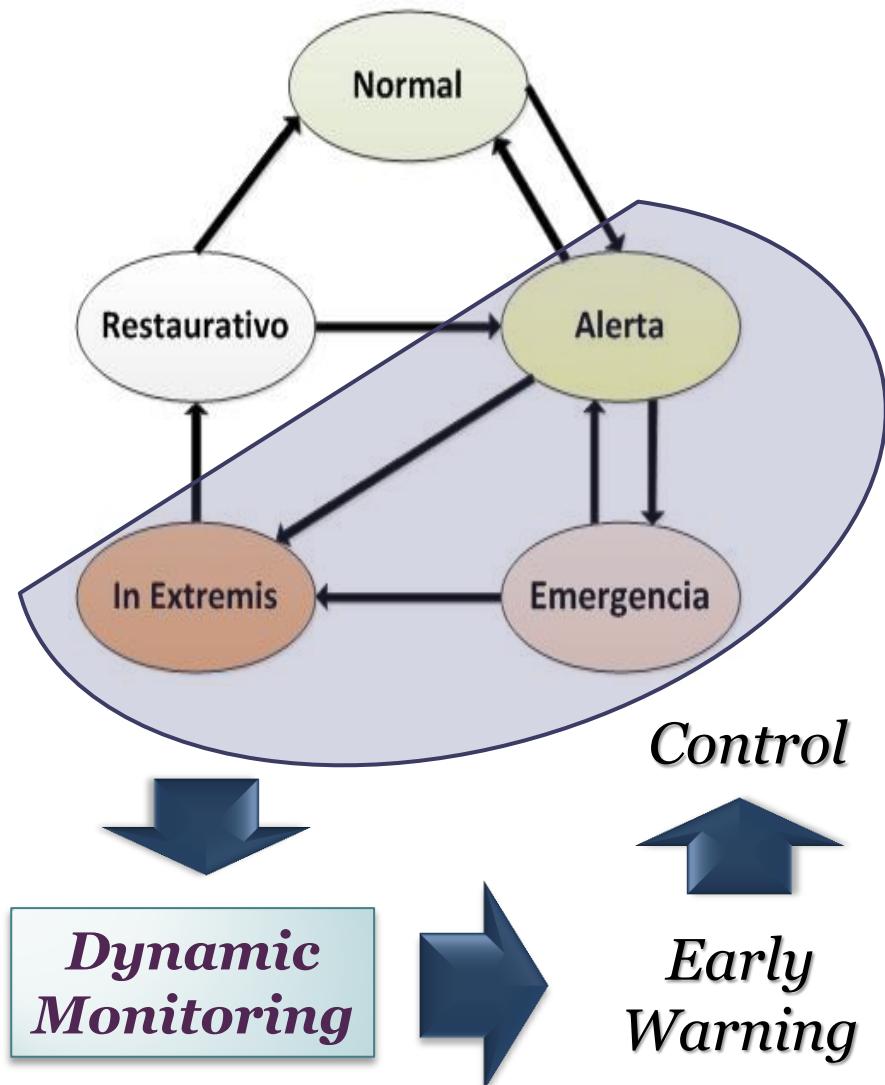
PMUs – Assessment and Types of Control Actions



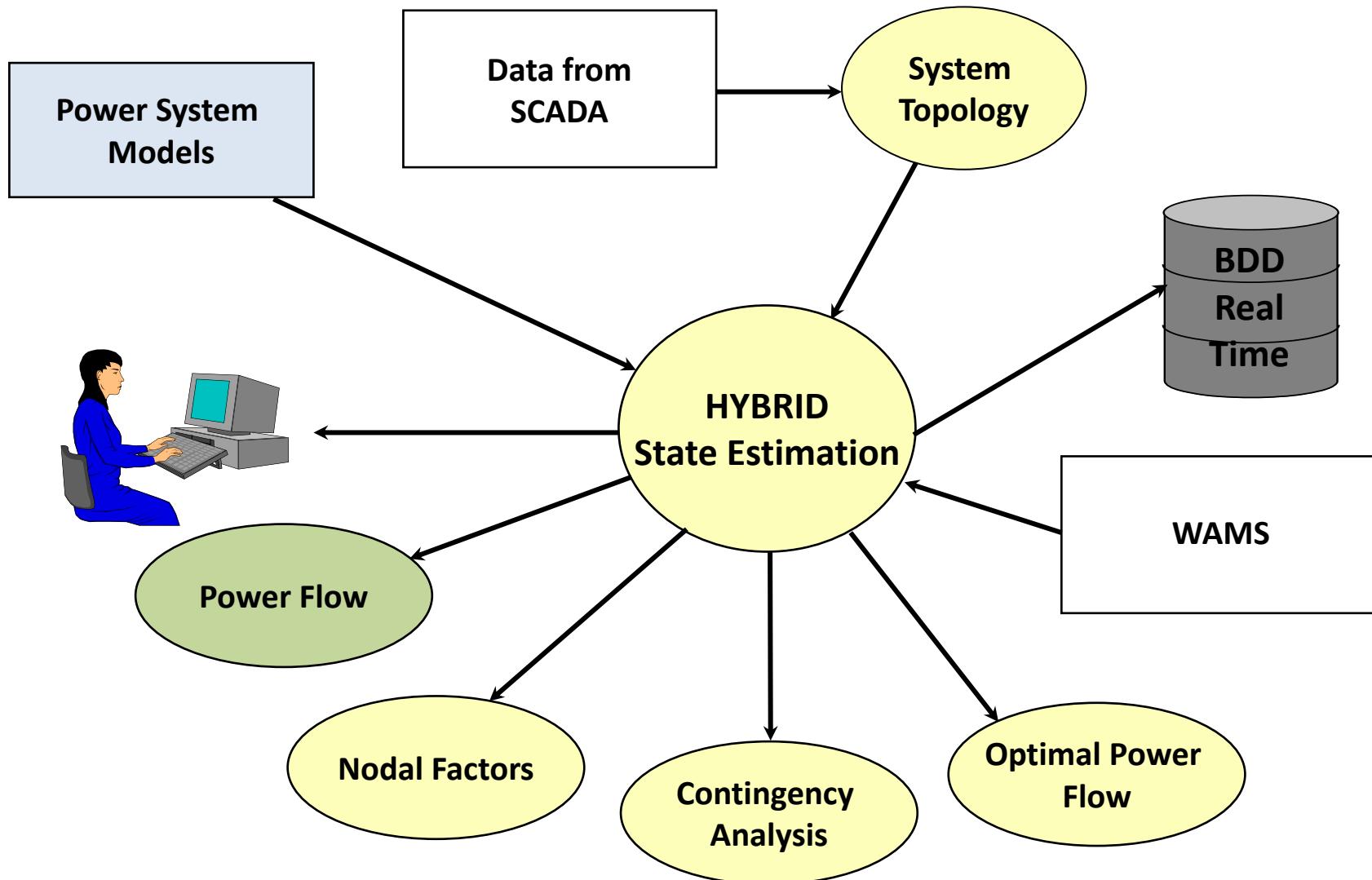
Assessment and Enhancement of Power System Security

WAMPAC System:

- Static and Dynamic Monitoring
- Power System Vulnerability Status
- Preventive and Corrective Control
- Special Protection Schemes' Trigger



Steady-state Monitoring - SCADA/EMS - WAMS



Static Security Assessment – Contingency Analysis

- ✓ To assess the degree of security facing the loss of power system elements (contingency) \Rightarrow “**What if**” Analysis.
- ✓ **Contingency Types:**
 - Simple contingency (N-1 criterion)
 - Double contingency (N-2 criterion)
 - Multiple contingency (N-x criterion)
- ✓ It involves performing a **complete power flow** for each of the selected contingencies, to evaluate the state of the system after each contingency.

Dynamic Security Assessment

Power System Stability

Voltage
Stability

Angle
Stability

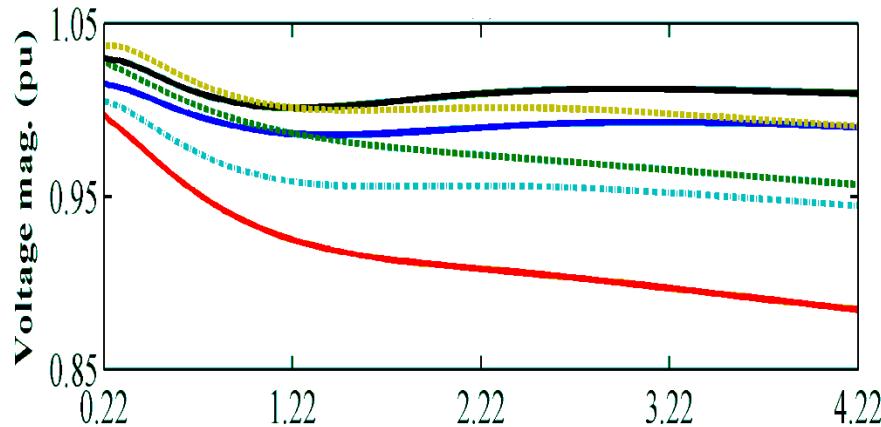
Frequency
Stability

Voltage Stability

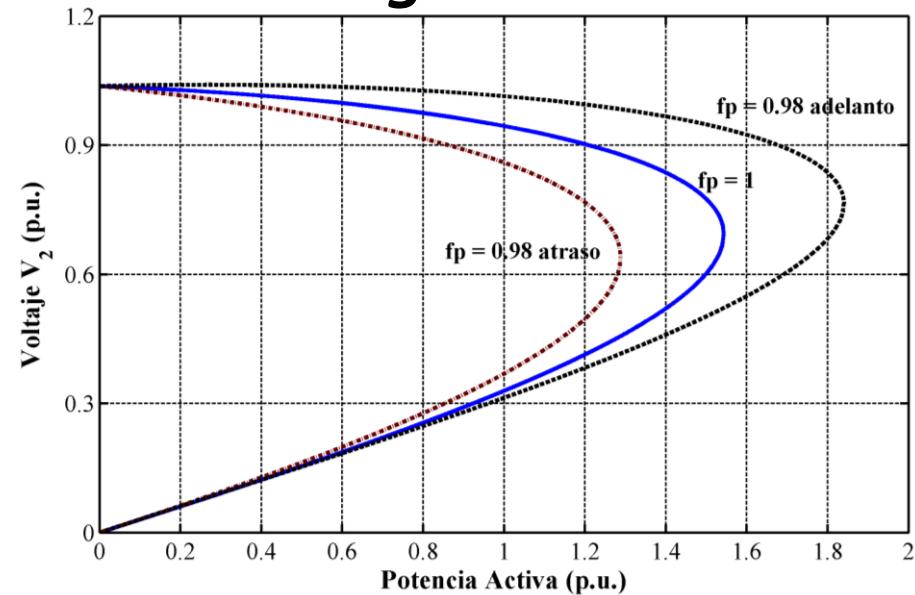
Ability of a power system to maintain steady voltages at all buses in the system after being subjected to a disturbance.

Lack of reactive power resources in the grid.

Short - Term



Long - Term



Voltage Stability Assessment

OFF-LINE

- Dynamic Analysis*
- Sensitivity analysis*
- Modal Analysis*
- Distance to Instability (CPF: P-V curves)*

ON-LINE

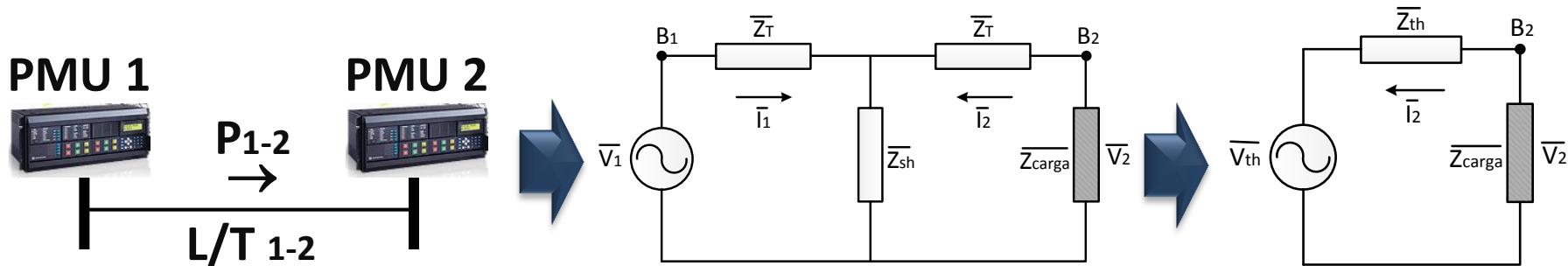
- Artificial Intelligence Systems:*** to estimate the power system
cargability margin.
 - Artificial Neural Network (ANN)
 - adaptive neuro-fuzzy inference system (ANFIS)

Thevenin Equivalent:

Real time determination of Power – Voltage (P-V) in real time

Voltage Stability of Corridors

- Voltage Stability of Corridors \Rightarrow Thevenin Equivalent \Rightarrow Transmission Line Transfer Capacity

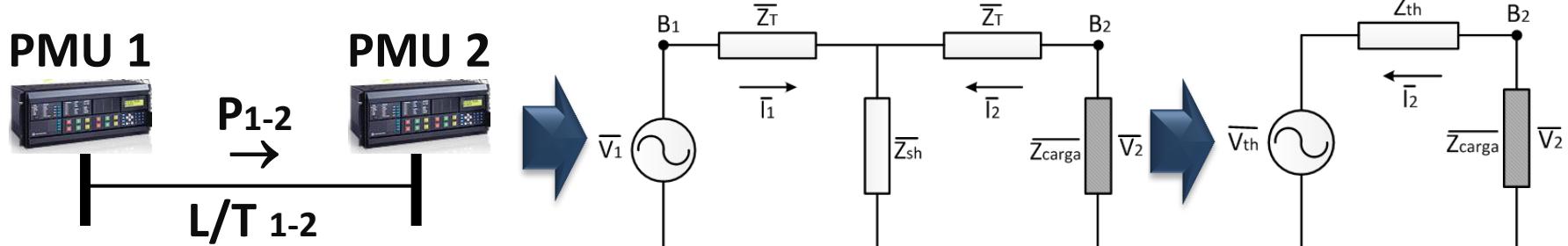


$$\bar{Z}_T = \frac{\bar{V}_1 - \bar{V}_2}{\bar{I}_1 - \bar{I}_2} \quad \bar{Z}_{sh} = \frac{\bar{I}_1 \bar{V}_2 - \bar{I}_2 \bar{V}_1}{\bar{I}_1 \bar{I}_1 - \bar{I}_2 \bar{I}_2} \quad \Rightarrow \quad \bar{Z}_{th} = \frac{\bar{Z}_T + \bar{Z}_{sh}}{\bar{Z}_T \cdot \bar{Z}_{sh}} + \bar{Z}_T \quad \bar{V}_{th} = \frac{\bar{Z}_{sh}}{\bar{Z}_{sh} + \bar{Z}_T} \bar{V}_1$$

$$\bar{S}_c = \bar{V}_2 \cdot (-\bar{I}_2)^* = \bar{V}_2 \cdot \left(\frac{\bar{V}_{th} - \bar{V}_2}{\bar{Z}_{th}} \right)^* = \bar{V}_2 \cdot \left(\frac{\bar{V}_{th} - \bar{V}_2}{R_{th} + jX_{th}} \right)^*$$

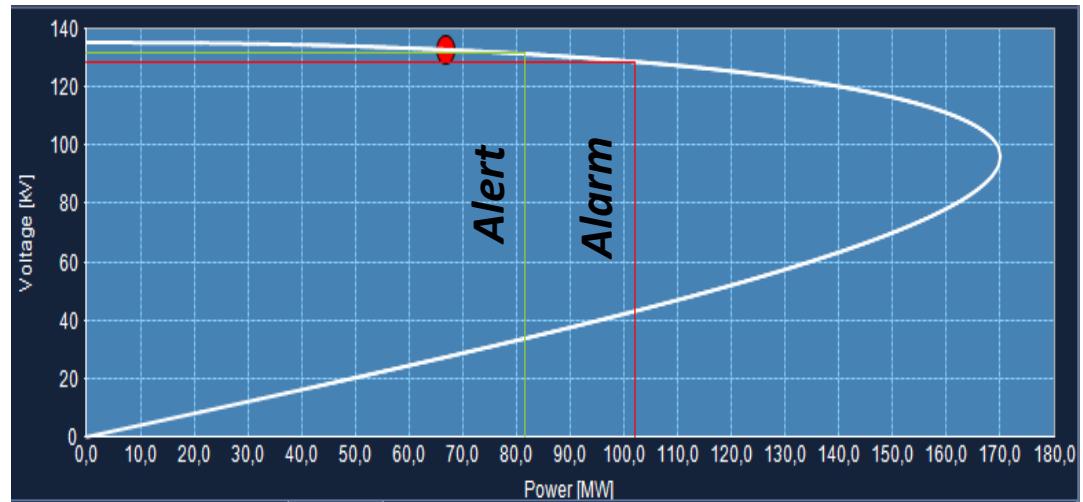
$$V_2 = \sqrt{\frac{V_{th}^2}{2} - (QX_{th} + PR_{th}) \pm \sqrt{\frac{V_{th}^4}{4} - V_{th}^2(QX_{th} + PR_{th}) - (PX_{th} - QR_{th})^2}}$$

Voltage Stability of Corridors

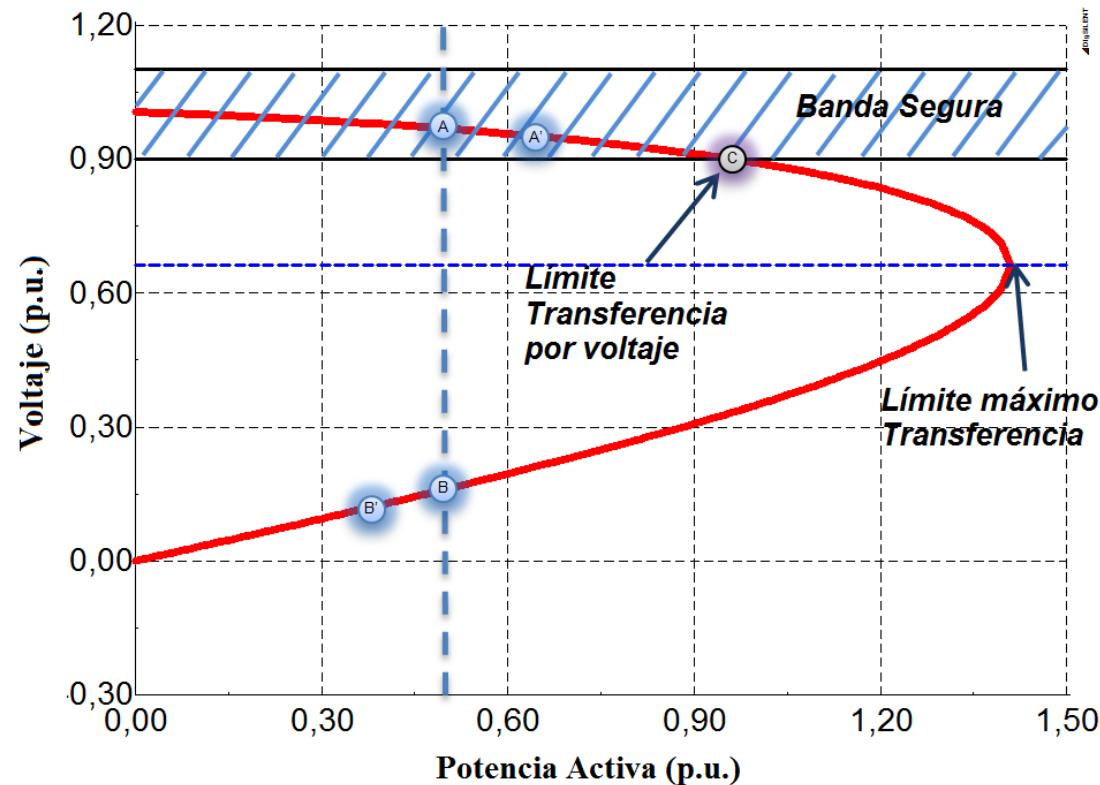


$$V_2 = \sqrt{\frac{V_{th}^2}{2} - (QX_{th} + PR_{th}) \pm \sqrt{\frac{V_{th}^4}{4} - V_{th}^2(QX_{th} + PR_{th}) - (PX_{th} - QR_{th})^2}}$$

Monitoring of the operating point of the corridor regarding pre defined limits
⇒ Congestion Alert

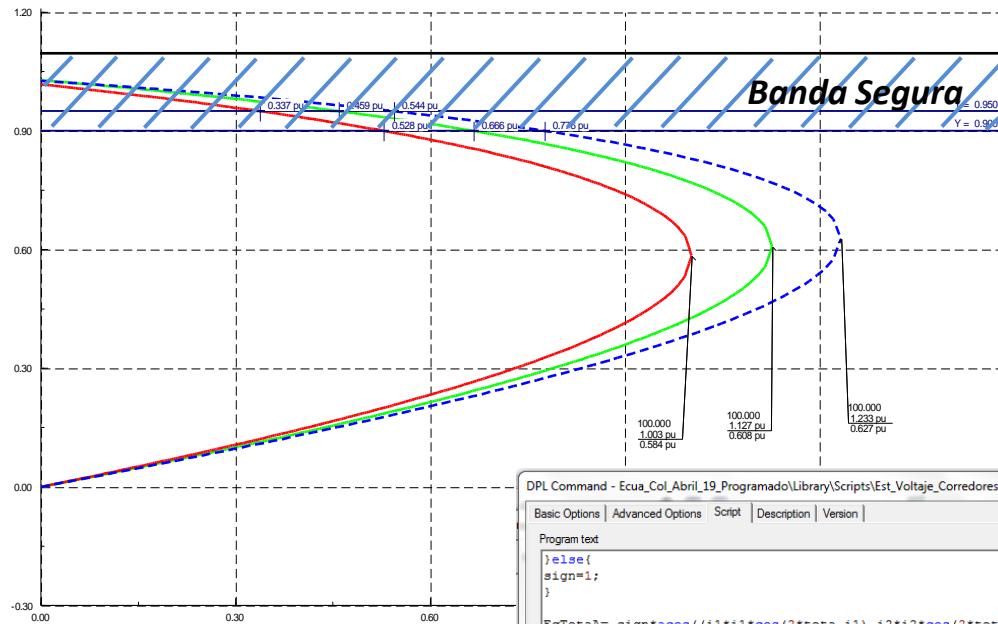
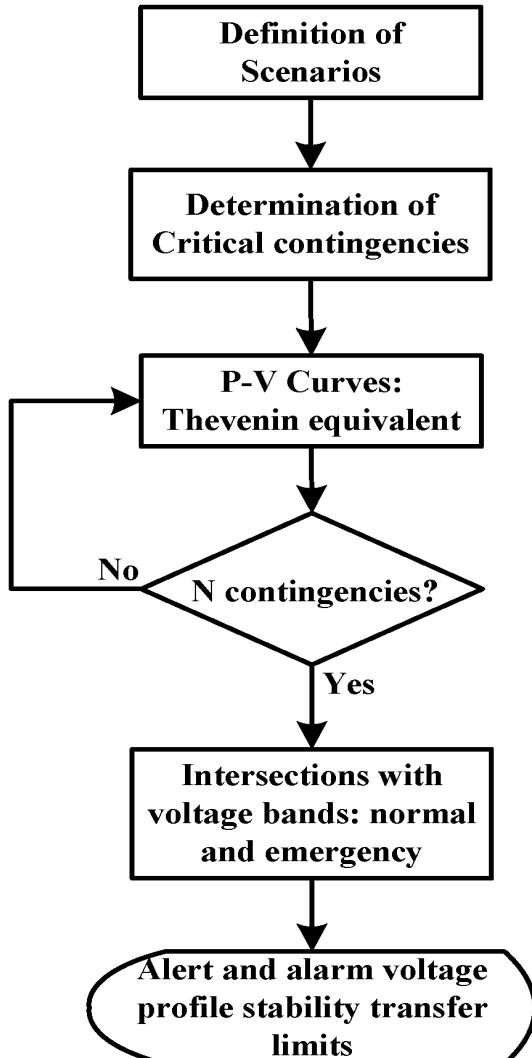


Voltage Stability of Corridors



| Voltaje de Barras | Inferior | | Superior | |
|-------------------|----------|------------|----------|------------|
| | Normal | Emergencia | Normal | Emergencia |
| 230 kV | -5% | -10% | 5% | 6% |
| 138 kV | -5% | -10% | 5% | 6% |
| 69, 46, 34.5 kV | -3% | -5% | 5% | 6% |

Voltage Stability of Corridors – Determination of Limits



**Script en DPL
(DlgsILENT
Programming
Language)**

DPL Command - Ecua_Col_Abril_19_Programado\Library\Scripts\Est_Voltaje_Corredores.ComDpl

| | | | | |
|---------------|------------------|--------|-------------|---------|
| Basic Options | Advanced Options | Script | Description | Version |
|---------------|------------------|--------|-------------|---------|

Program text

```

else{
sign=1;
}

EqTetaA=-sign*acos((i1*i1*cos(2*teta_i1)-i2*i2*cos(2*teta_i2))/EqA);

Rsh=(i1*v2*EqA*cos(teta_i1+teta_v2+EqTetaA)-i2*v1*EqA*cos(teta_i2+teta_v1));
Xsh=(i1*v2*EqA*sin(teta_i1+teta_v2+EqTetaA)-i2*v1*EqA*sin(teta_i2+teta_v1));

Zsh=sqrt(Rsh*Rsh+Xsh*Xsh);

if(Xsh<0){
sign=-1;
}else{
sign=1;
}

teta_sh=sign*acos(Rsh/Zsh);

Rt=v1/i1*cos(teta_v1-teta_i1)-Rsh-Zsh*i2/i1*cos(teta_i2-teta_i1+teta_sh);
Xt=v1/i1*sin(teta_v1-teta_i1)-Xsh-Zsh*i2/i1*sin(teta_i2-teta_i1+teta_sh);

Zt=sqrt(Rt*Rt+Xt*Xt);

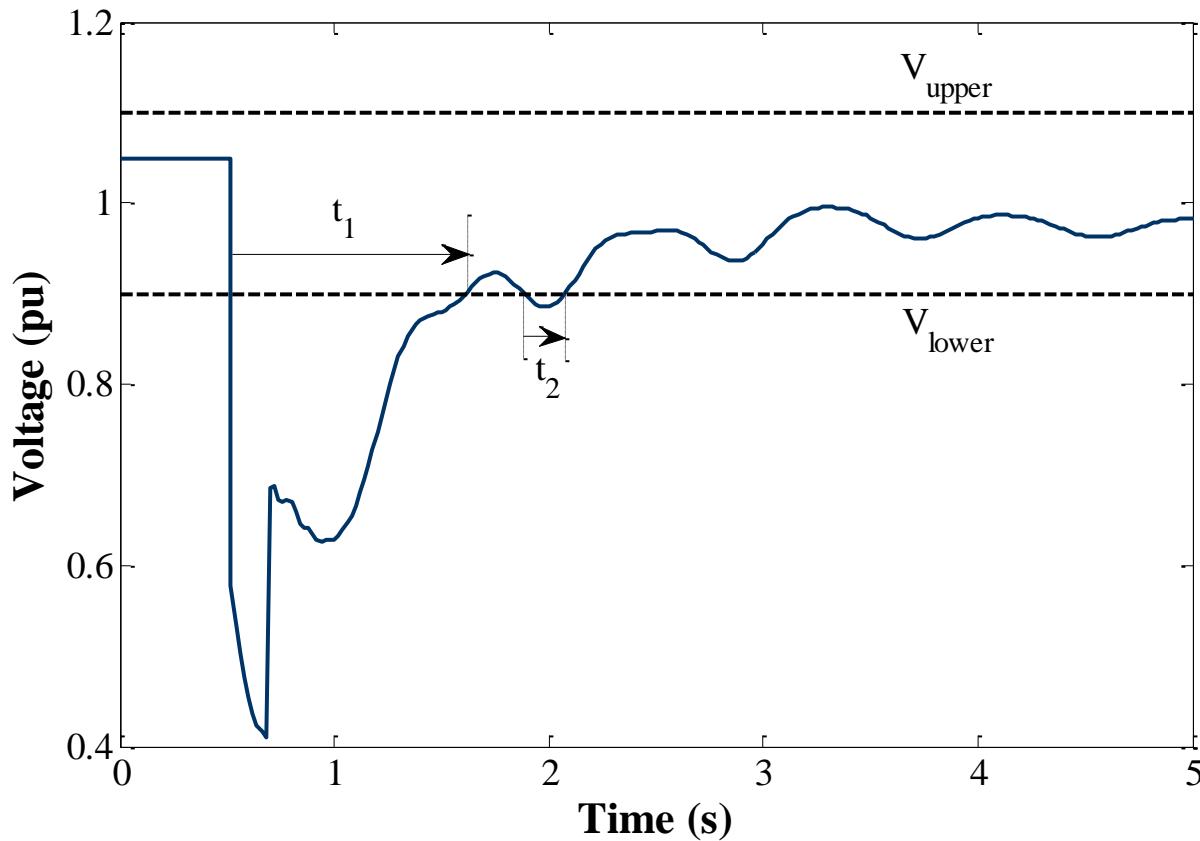
if(Xt<0){
sign=-1;
}else{
}

```

Buttons: Read Only, Close, Cancel, Save, Check, Contents

Bottom status bar: READ, Ln 19, Col 41

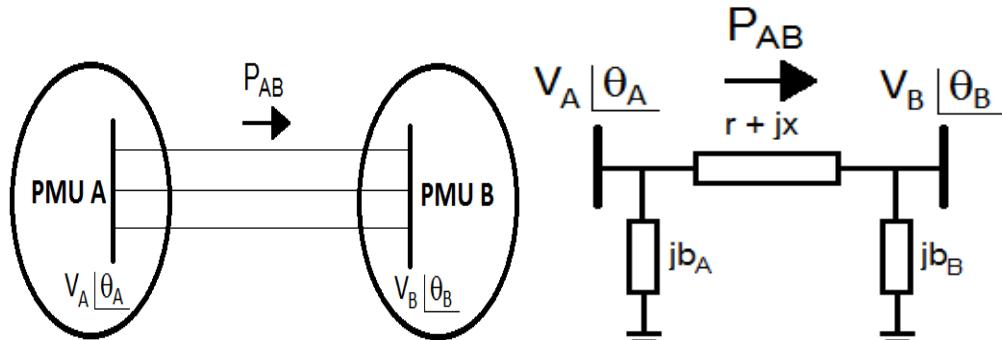
Short-term Voltage Stability



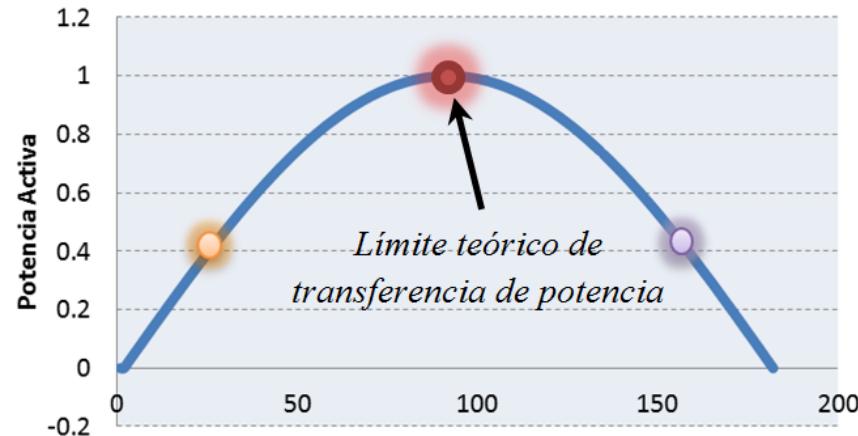
$$VDI_i = \begin{cases} 0 & \text{if } V_{lower} \leq V \leq V_{upper} \\ \min \left\{ 1, \frac{t_n}{tv_{max}} \right\} & \text{if } V < V_{lower} \vee V > V_{upper} \end{cases}$$

Steady-state Angle Stability

- Angular difference between the nodes of the power system \Rightarrow Direct measurement of the transmission capacity between the nodes
- Maximum limit of angular difference between nodes A and B \Rightarrow power transfer limit.
- \Rightarrow Angular Difference Monitoring \Rightarrow power system congestion alert

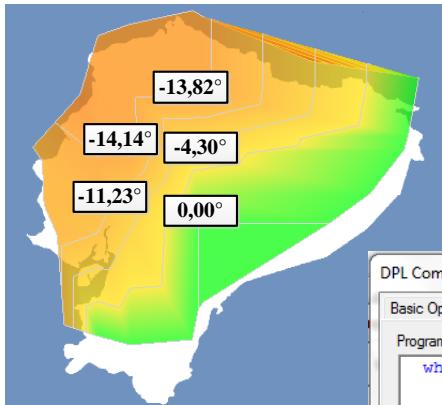
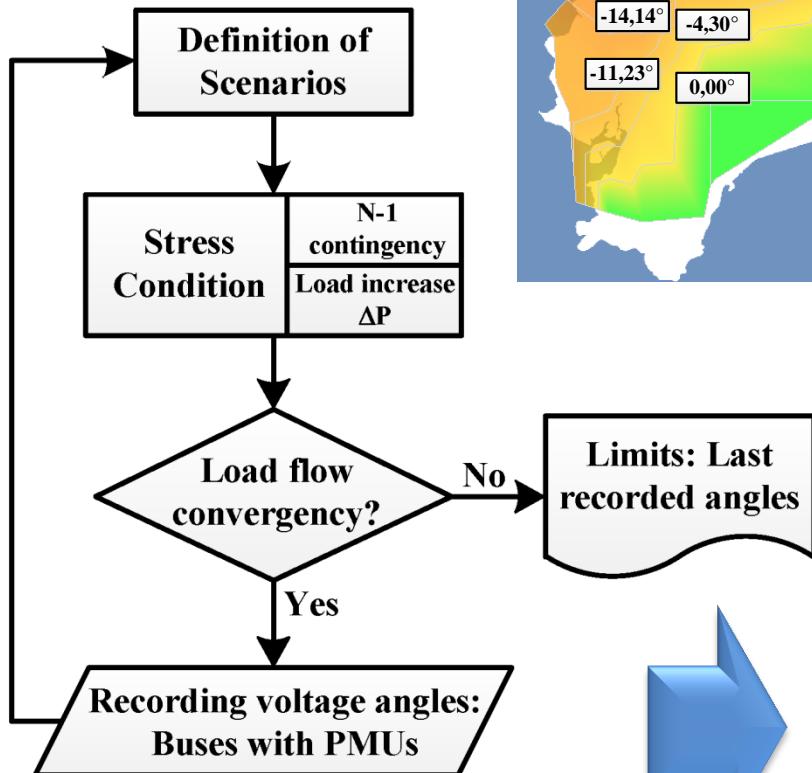


$$P_{AB} \cong \frac{V_A V_B \sin(\theta_A - \theta_B)}{x}$$



$$P_{AB} \approx \frac{V_A V_B (\theta_A - \theta_B)}{x} \xrightarrow{\text{Ángulo}} P_{AB} \propto (\theta_A - \theta_B)$$

Steady-State Angle Stability – Determination of Limits



Script en DPL (DiGILENT Programming Language)

The screenshot shows the DiGILENT Programming Language (DPL) command window with the following script content:

```
while (Load) {
    Load=scale0=Load*scale0*stepval/stepvalold;
    Ptot=Ptot+Load*piini*Load*scale0;
    Load=Sloads.Next();
}
ierr=Ldf.Execute();
output('Last load flow calculation at Ptot=Ptot MW');
}

! if (Plot) {
!   Plot.SetScaleX();
!   Plot.SetScaleY();
!
!-----
Ldf.Execute();

temp=Molino:m:Ul;
temp1=Molino:m:phiu;

printf('Vol=%f',temp);
printf('Ang=%f',temp1);

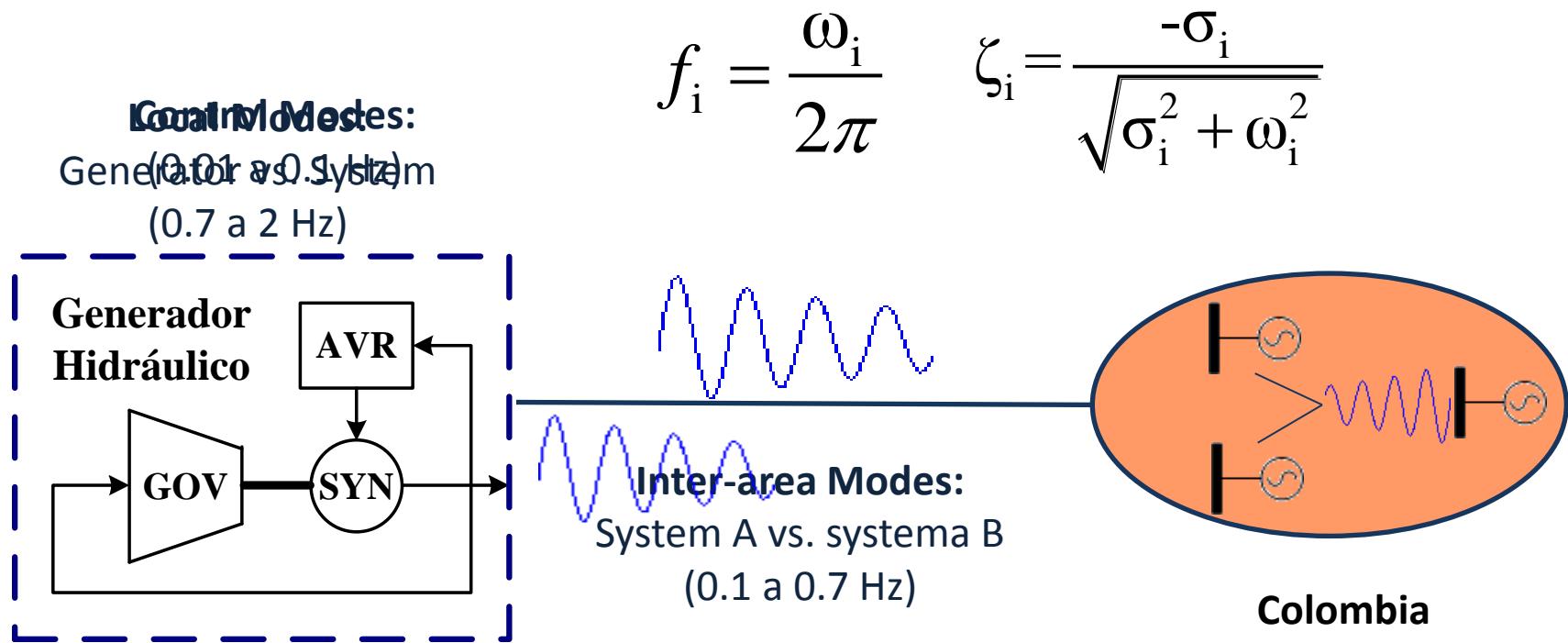
n=1;
file=sprintf('%s%d%s','C:\jcepeda\mis documentos\Angulos\angulos',n,'.txt

fopen(file,'a',1);
```

The window also includes standard buttons for Close, Cancel, Save, Check, and Contents, and a status bar indicating 'Ln 169, Col 10'.

Oscillatory Stability

- Load or generation variations \Rightarrow Generators try to find new equilibrium (stable) points \Rightarrow power and frequency oscillations caused by electric energy interchanges between machines
- **Oscillatory Modes**



Oscillatory Stability Assessment

- **Based on Simulations**

- Time Domain Simulations*

- Non-linear interactions
 - Mode excitation facing large perturbations

- Modal Analysis*

- Linearized system model
 - Mode excitation facing small perturbations (***small signal stability***)

- **Based on Signals**

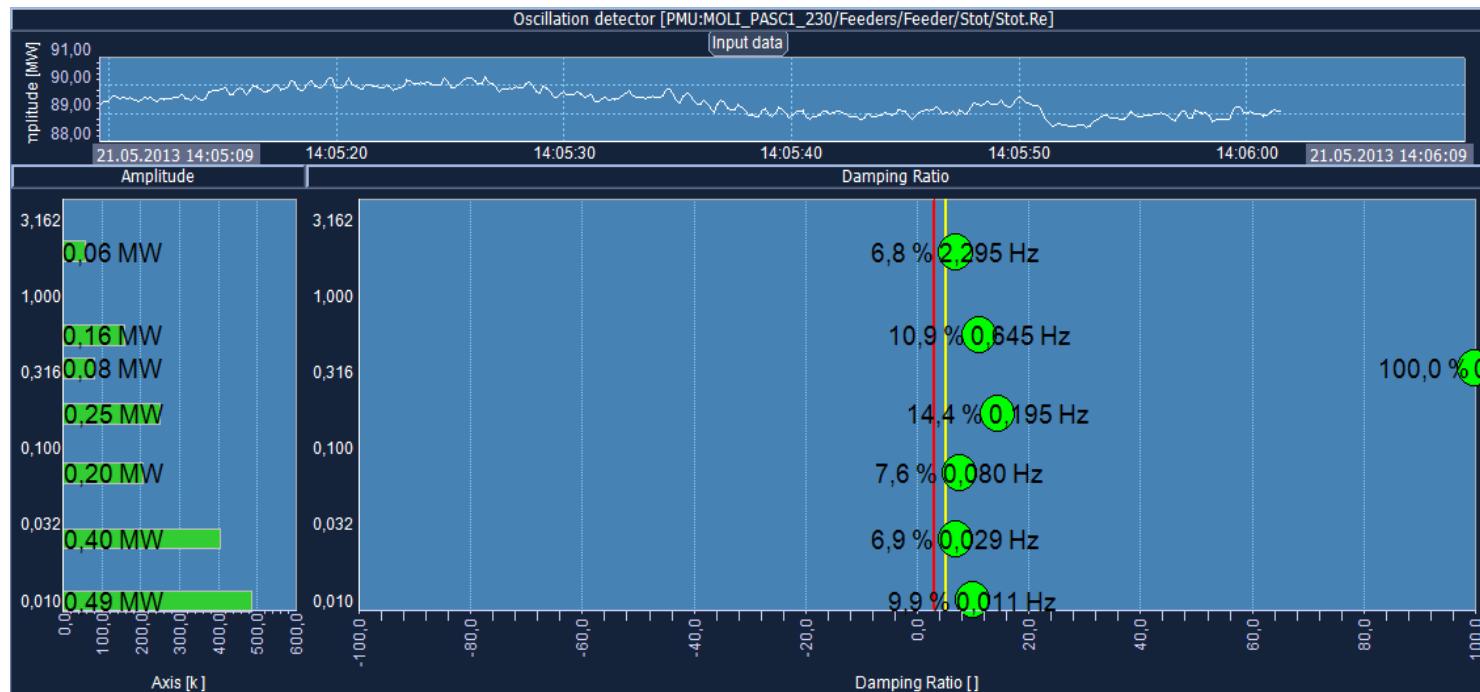
- Modal Identification Algorithms*

- Electric signals are decomposed in their oscillatory modes
 - Fourier Analysis, Prony Analysis, Hilbert-Huang Transform, Kalman Filter, Wavelet Transform, WAProtector Algorithm

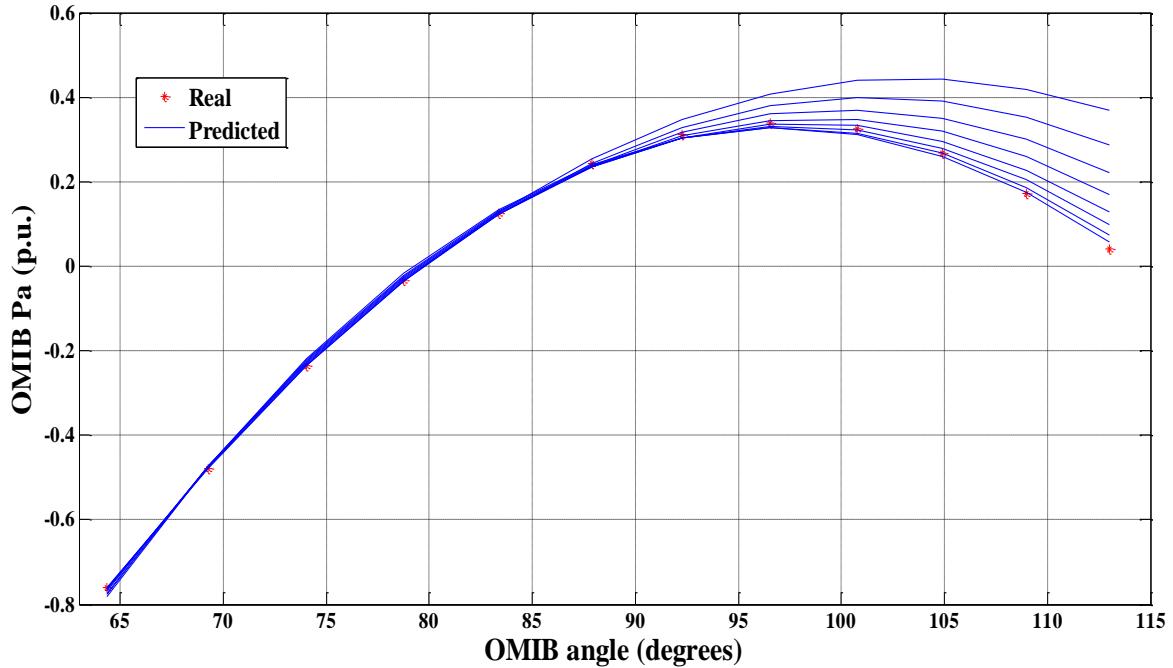
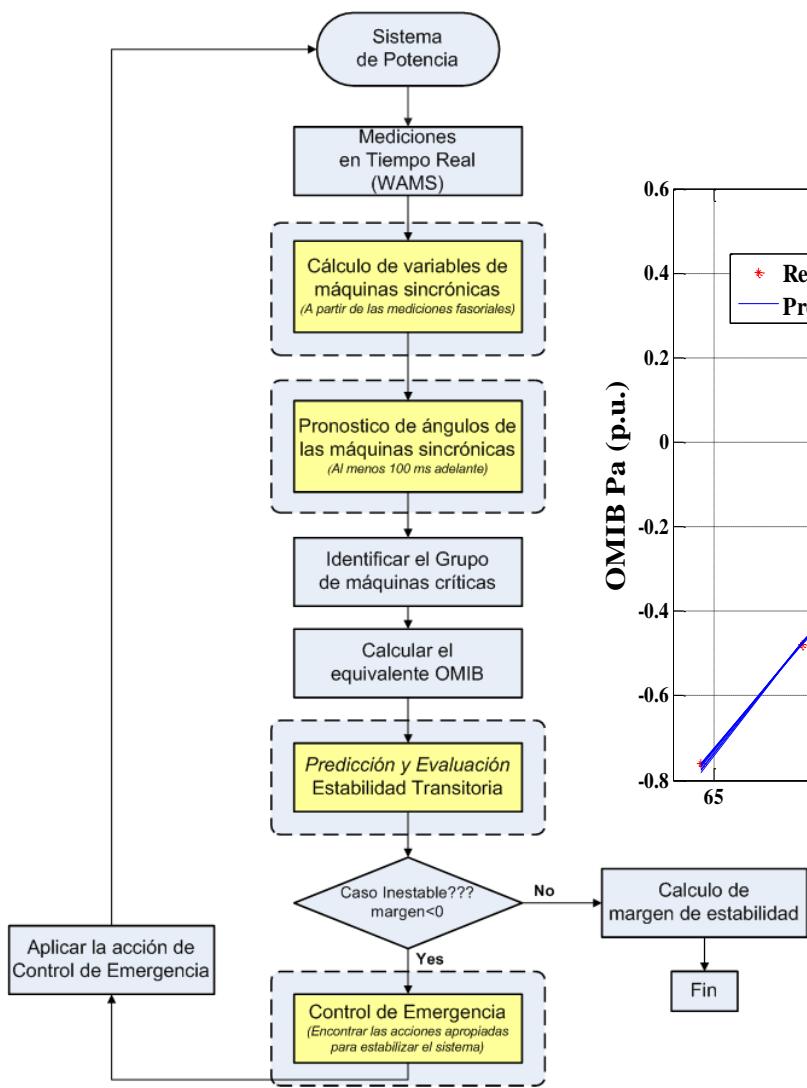
Modal identification algorithms

- These algorithms allow estimating the frequency, damping, amplitude and relative phase of modal components present in a given oscillatory signal which can be theoretically represented by the summation of the modes immersed in this signal.

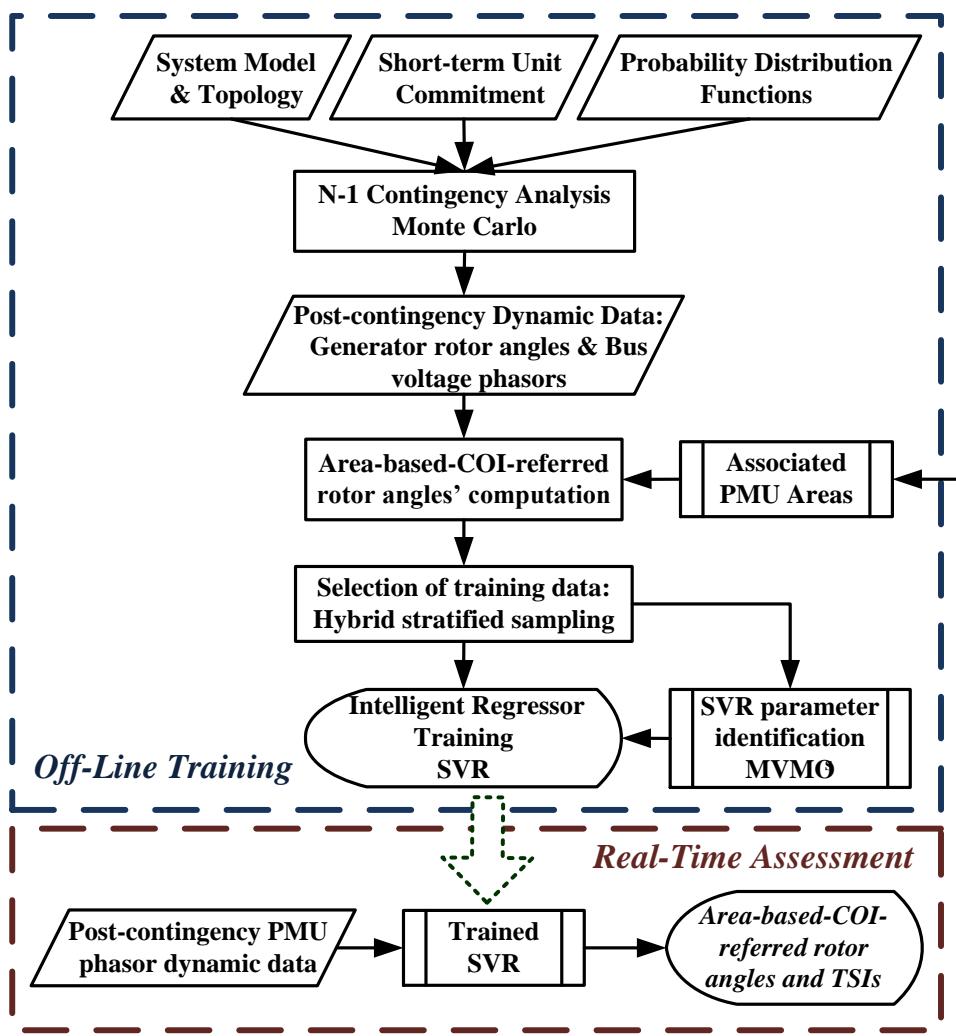
$$\hat{y}(t) = \sum_{i=1}^n A_i e^{\sigma_i t} \cos(\omega_i t + \phi_i)$$



Real Time Transient Stability Assessment: E-SIME



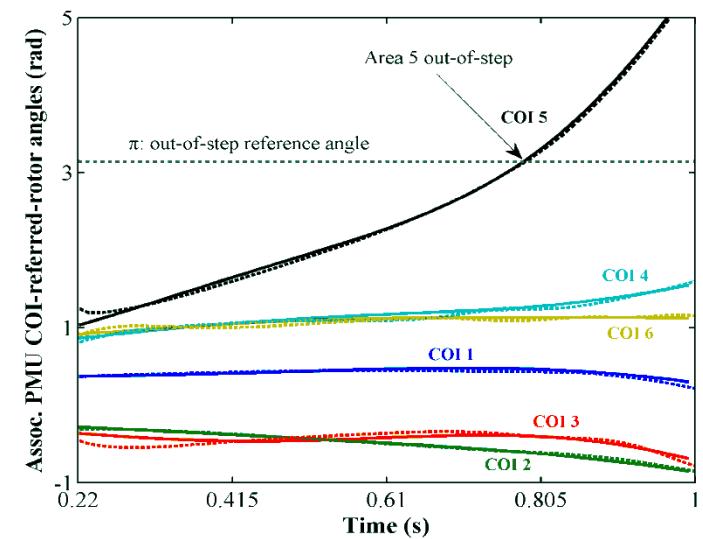
Real Time Transient Stability Assessment - COI estimation



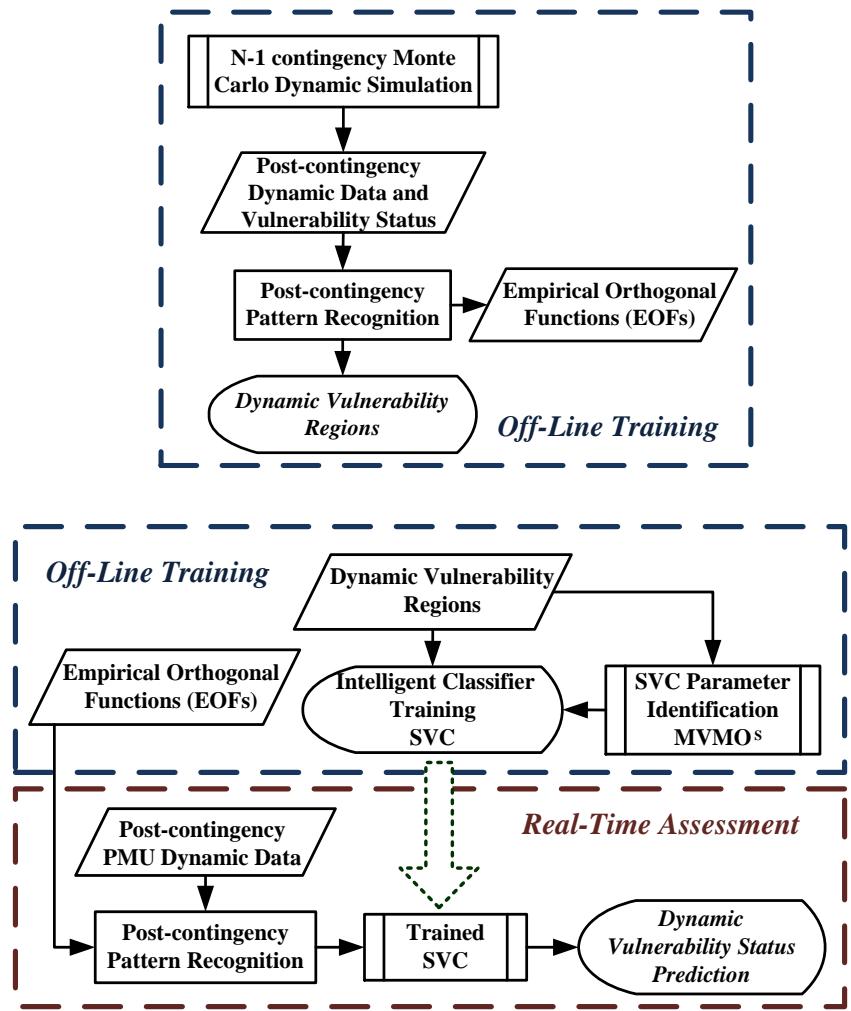
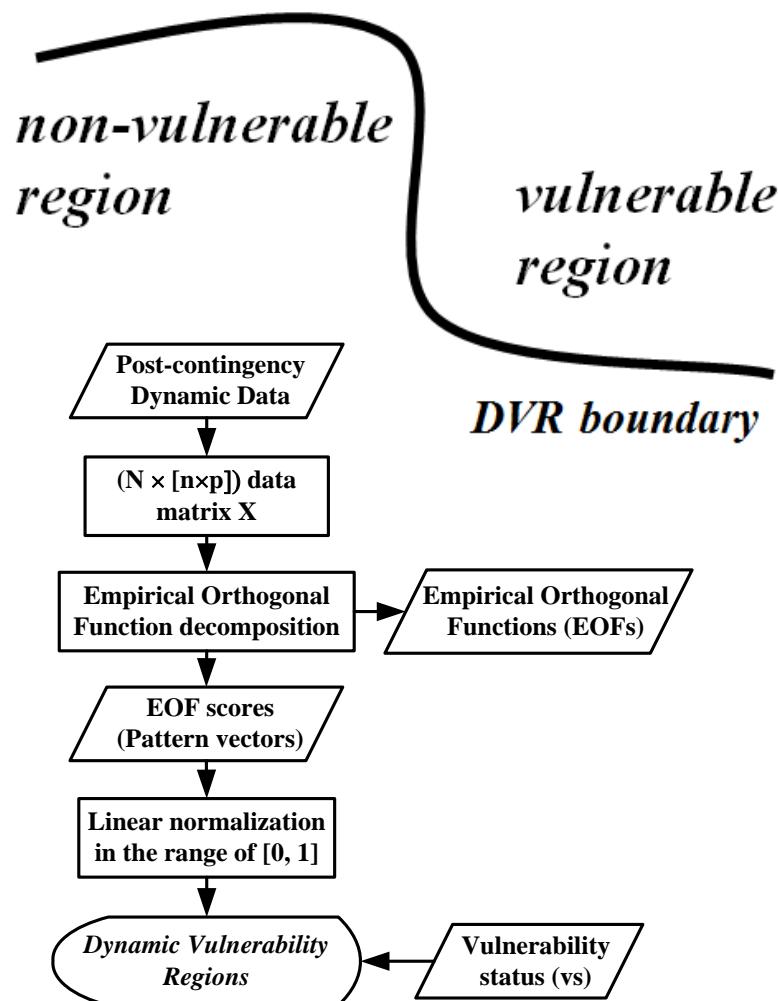
$$\delta_{COI_j} = \frac{1}{M_j} \sum_{i=1}^{N_j} M_i \delta_i$$

$$M_j = \sum_{i=1}^N M_i$$

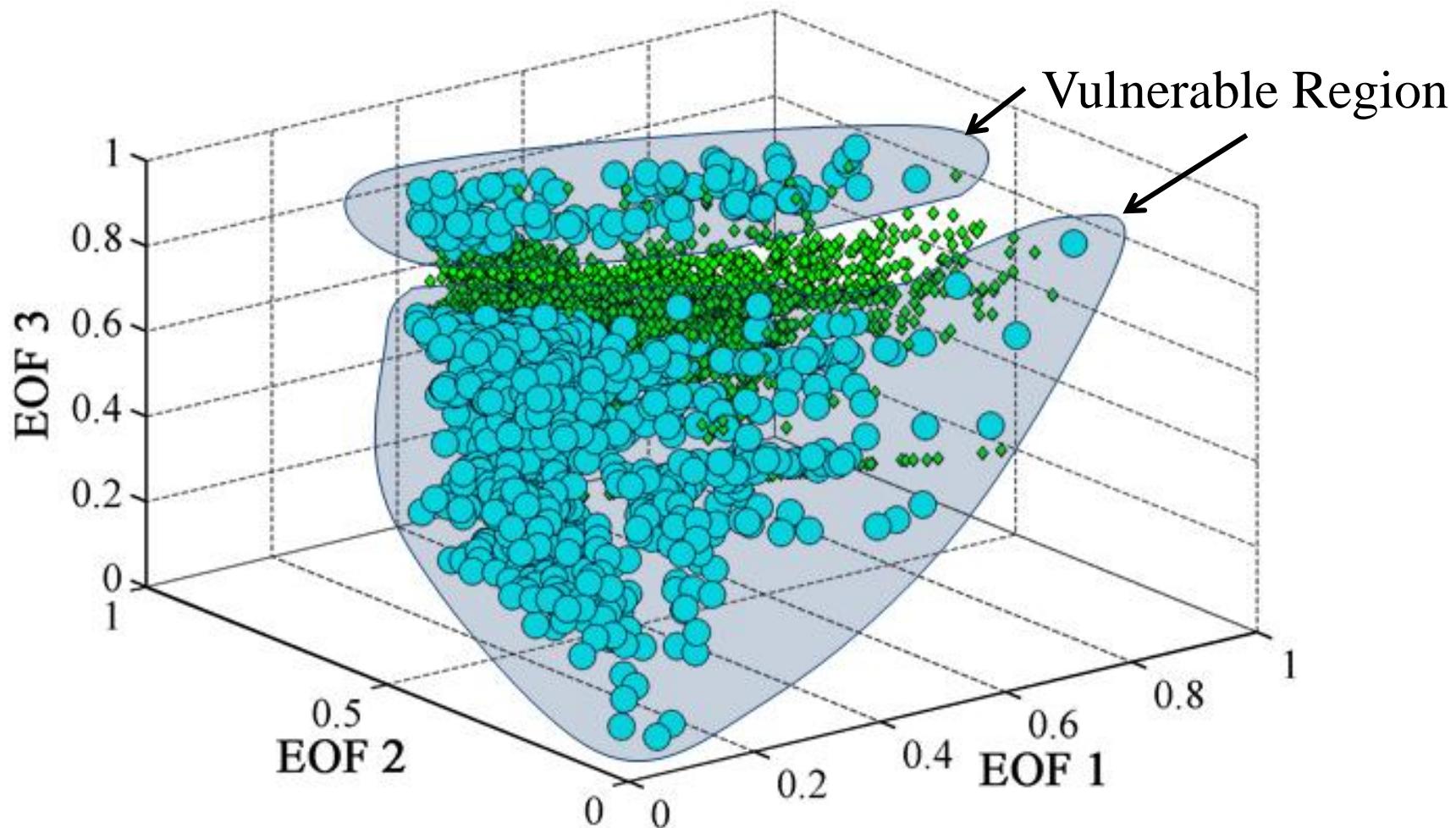
$$\delta_j^{COI_{System}} = \delta_{COI_j} - \delta_{COI_{System}}$$



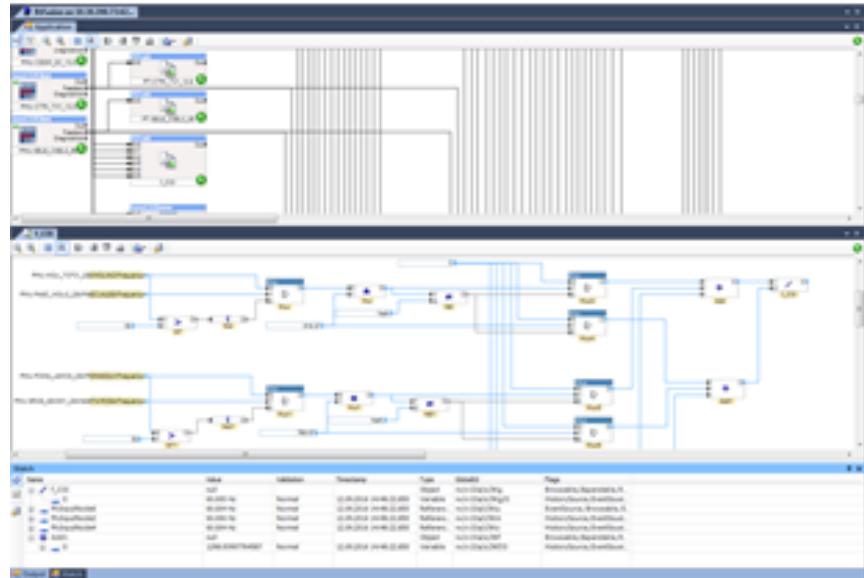
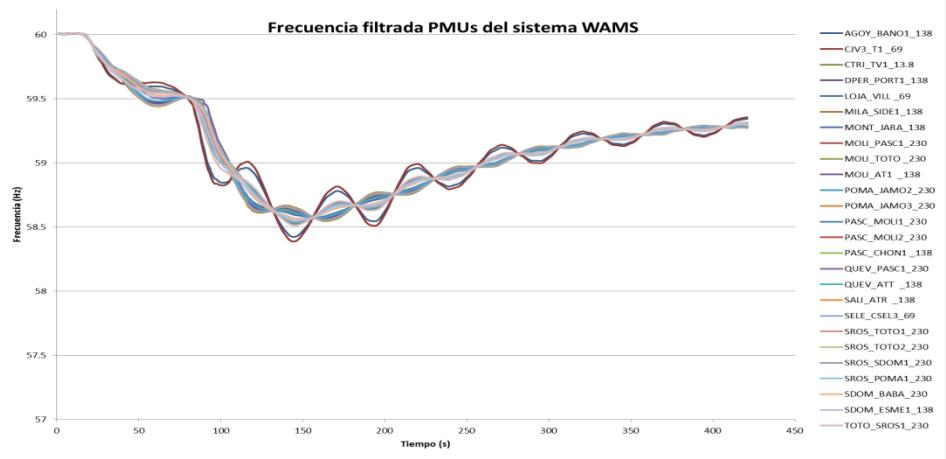
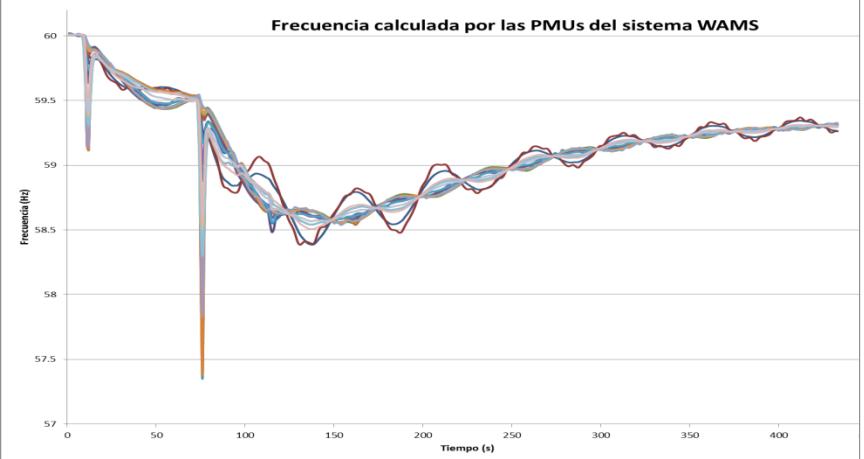
Real Time Transient Stability Assessment – Stability Status Prediction



Real Time Transient Stability Assessment – Stability Status Prediction

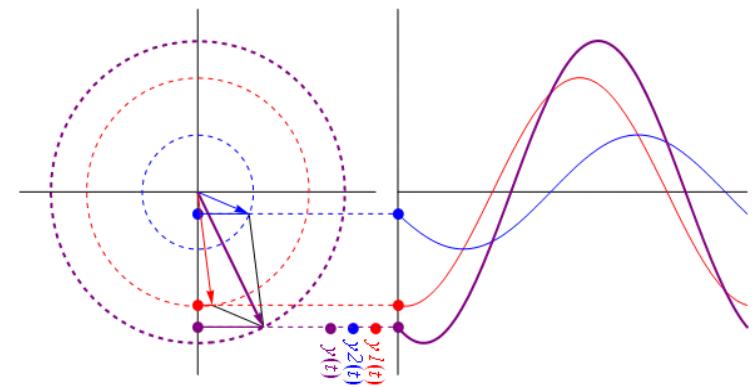
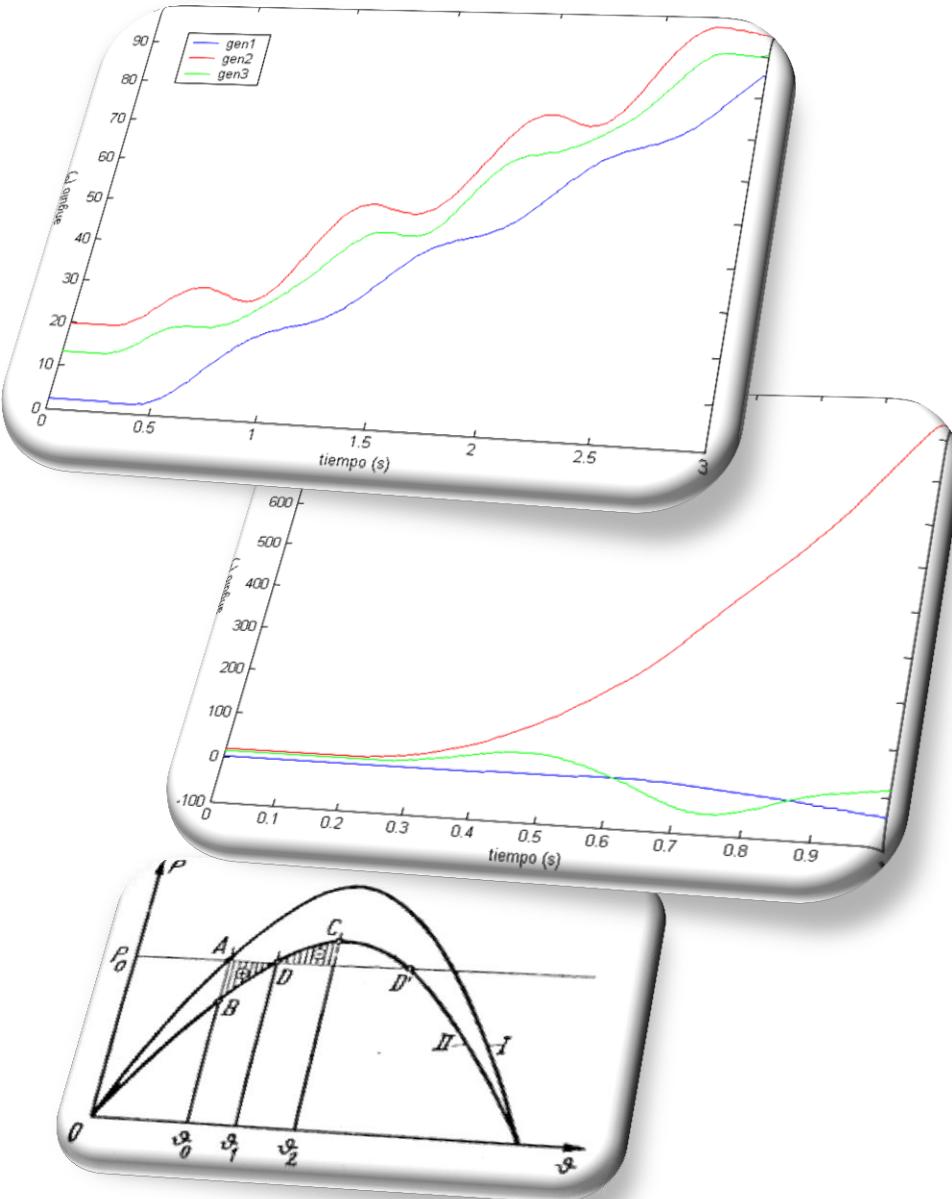


Frequency Stability

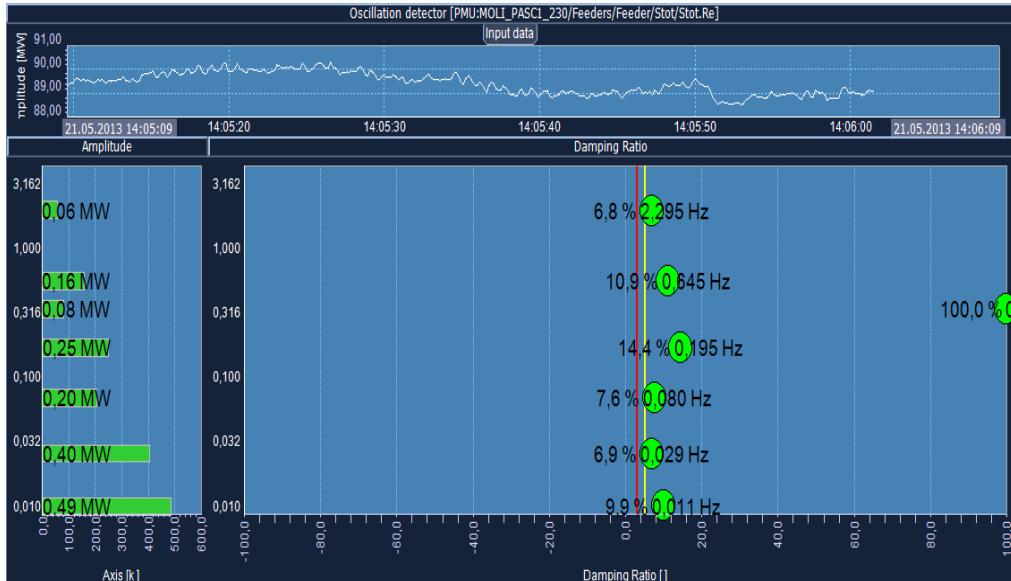


$$\mathbf{f}_k = \lambda_1^{1/2} u_{k1} \mathbf{v}_1 + \lambda_2^{1/2} u_{k2} \mathbf{v}_2 + \dots + \lambda_p^{1/2} u_{kp} \mathbf{v}_p \quad f_{COI} = \frac{\sum_{i=1}^N H_i}{\sum_{i=1}^N H_i}$$

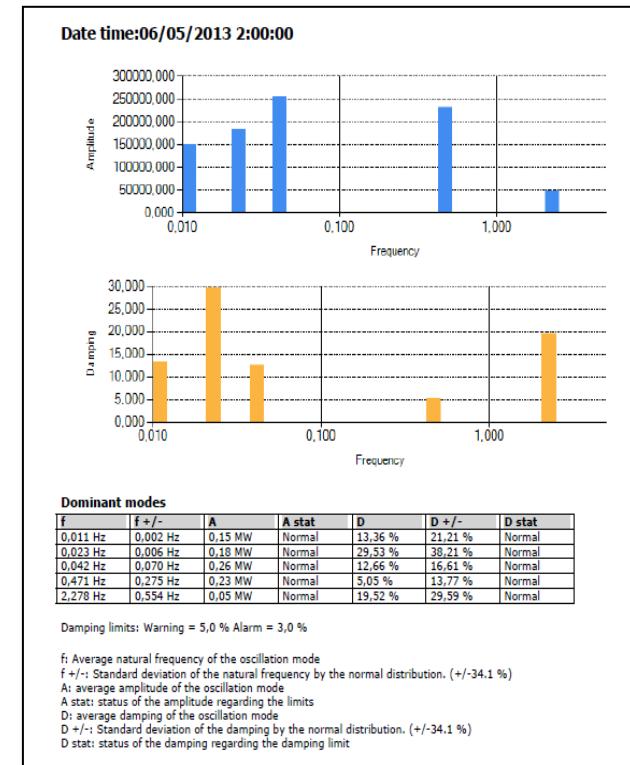
Post-Operative Analysis



Oscillatory Stability WAMS Data



Oscillatory Modes Identified for each update period (1 ciclo)

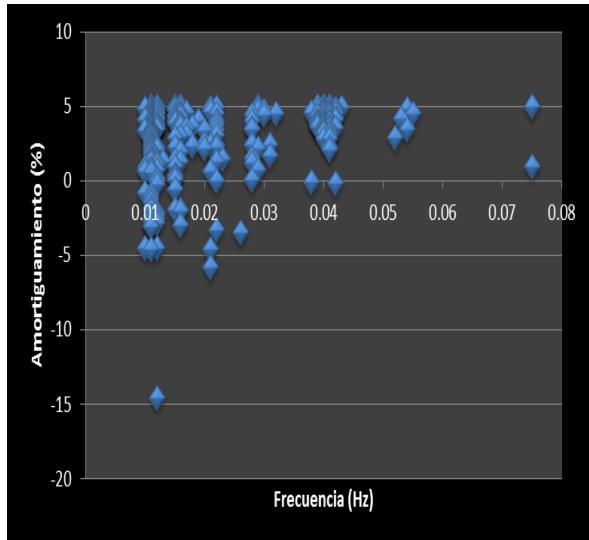


Average information of Oscillatory Modes per Hour

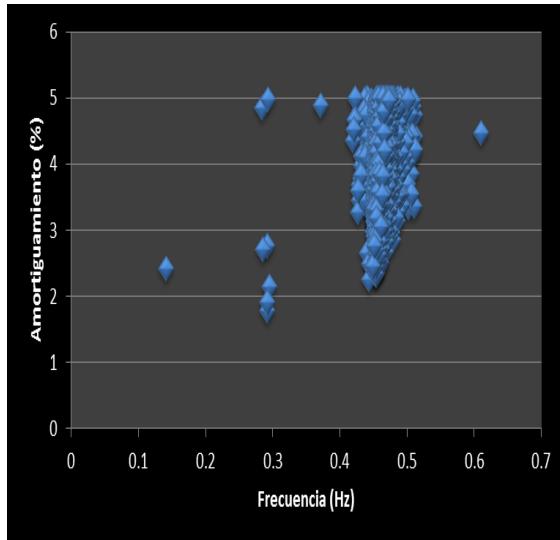


Oscillatory stability Post-operative Analysis

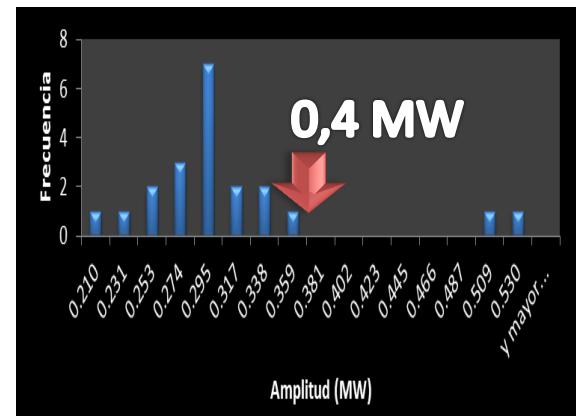
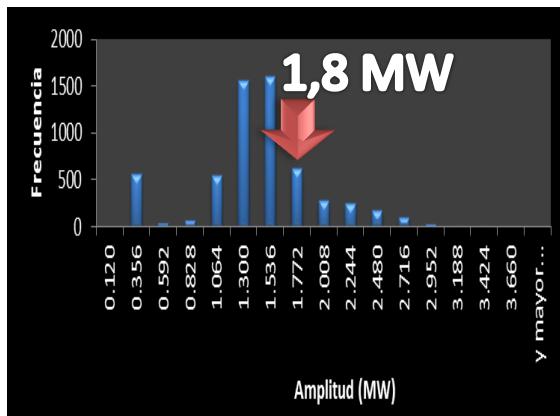
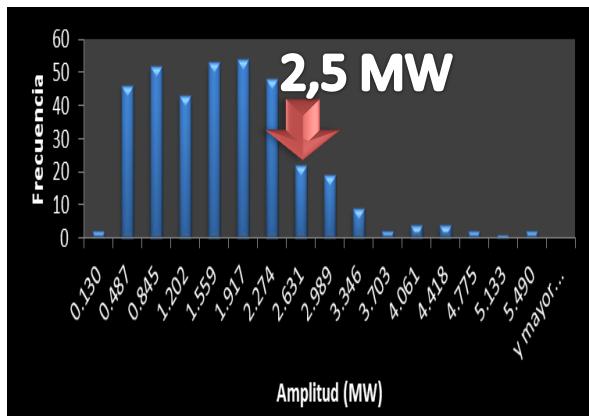
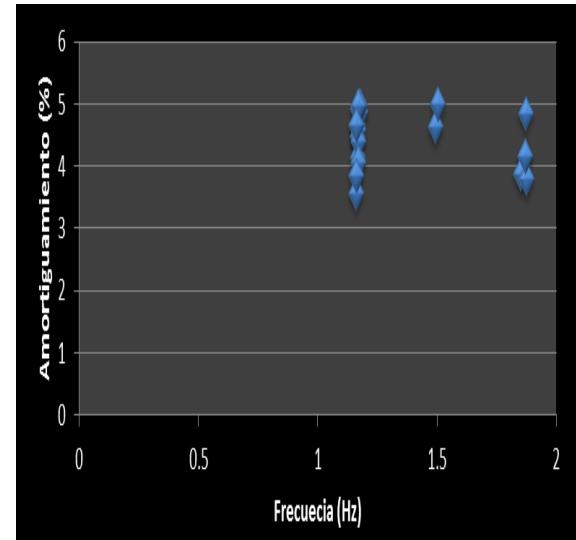
Control Modes



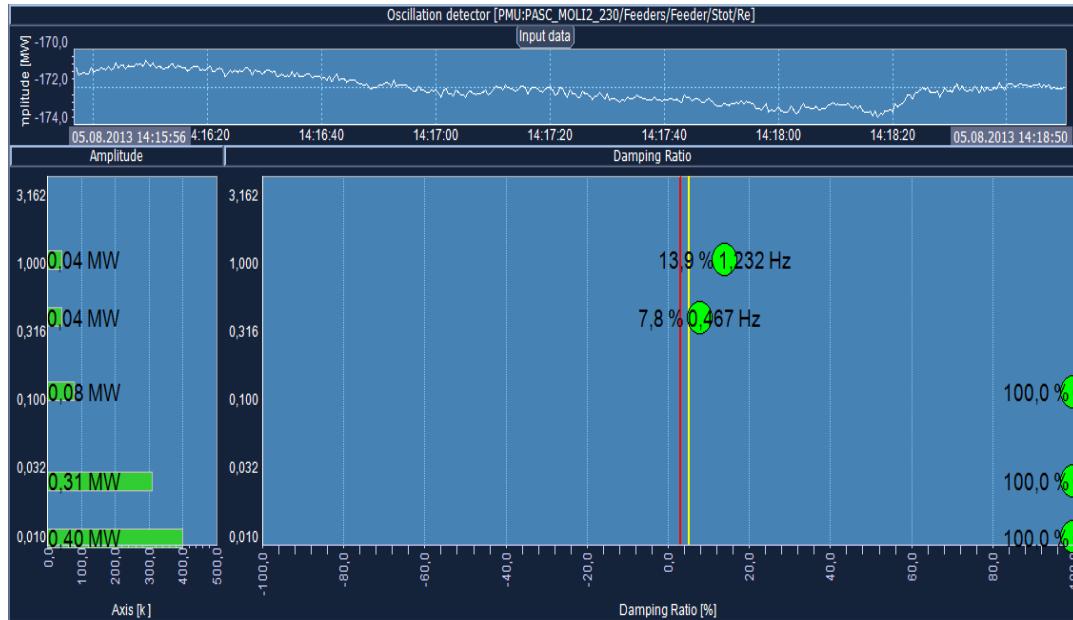
Inter-area Modes



Local Modes



Oscillatory Stability – Determination of Limits



Damping:
Alarm: 3%
Alert: 5%



Amplitude:

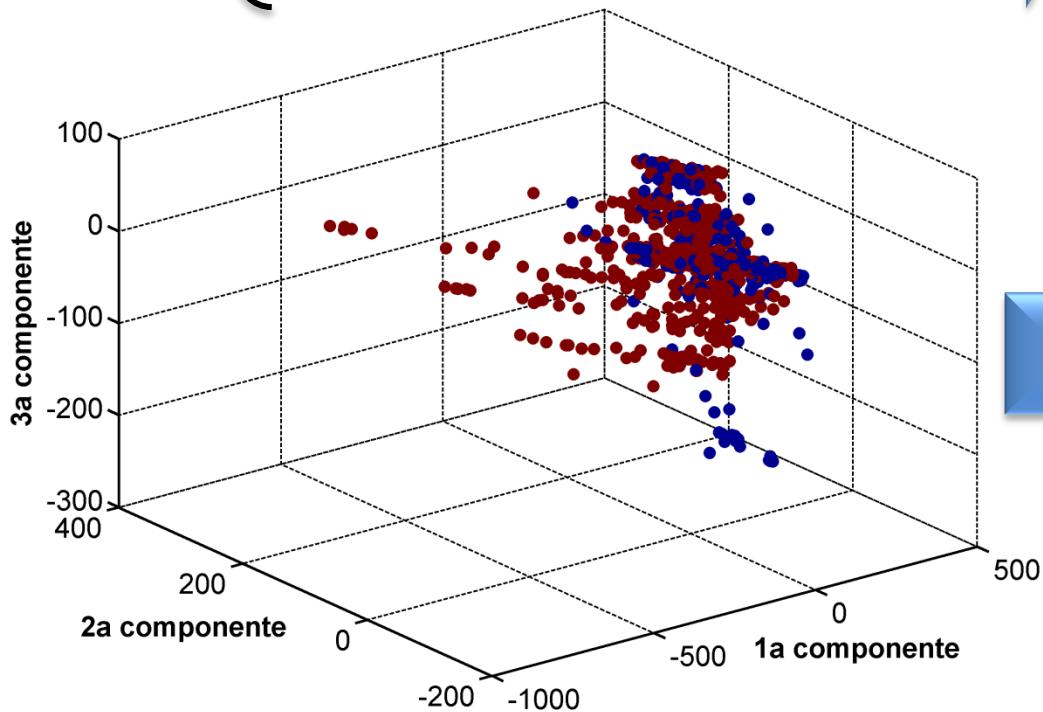
| Límites | CONTROL | INTER-AREA | LOCALES |
|-------------|---------|------------|---------|
| Alerta (MW) | 2.5 | 1.8 | 0.4 |
| Alarma (MW) | 3.5 | 2.4 | 0.6 |

Analytics – Statistics of Oscillatory Stability

Data Analytics

Key Tasks

*Outliers Detection
Data Preparation
Data Mining
Data Recognition*



System Security Regions

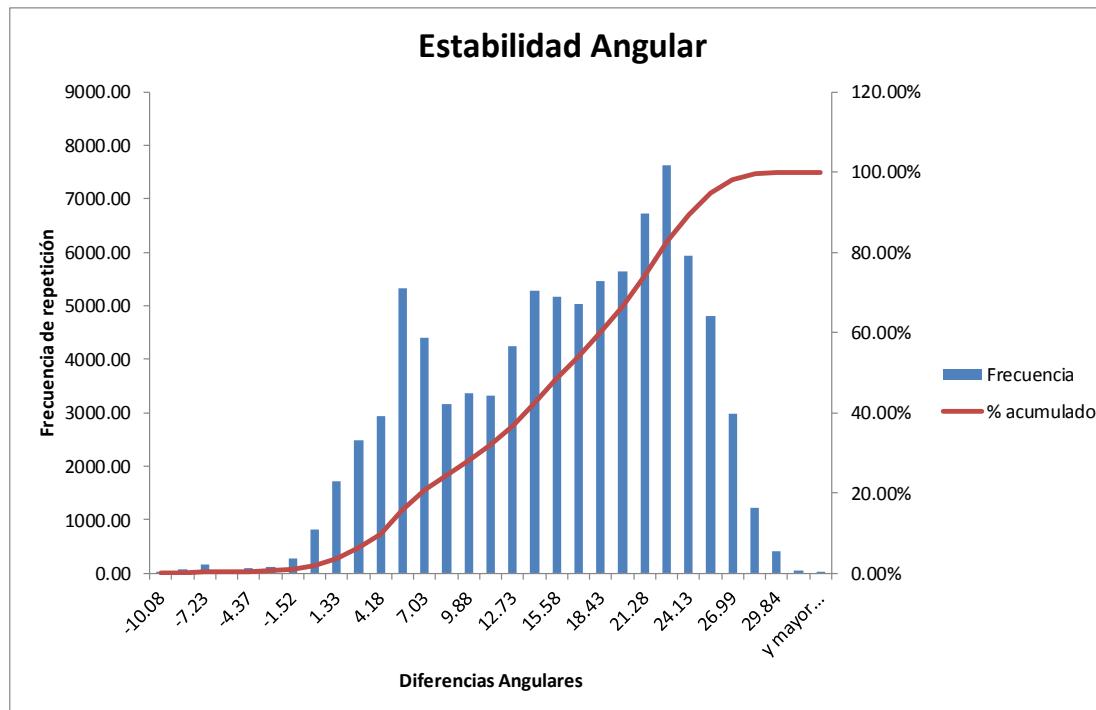


Characterization of operation states ⇒ correlation with poorly-damped modes

Steady-state angle stability Post-operative Analysis

Deviations in the limits established for the angular difference between **Santa Rosa and Molino** (reference), for August 2015 (scenario considered as high hydrology)

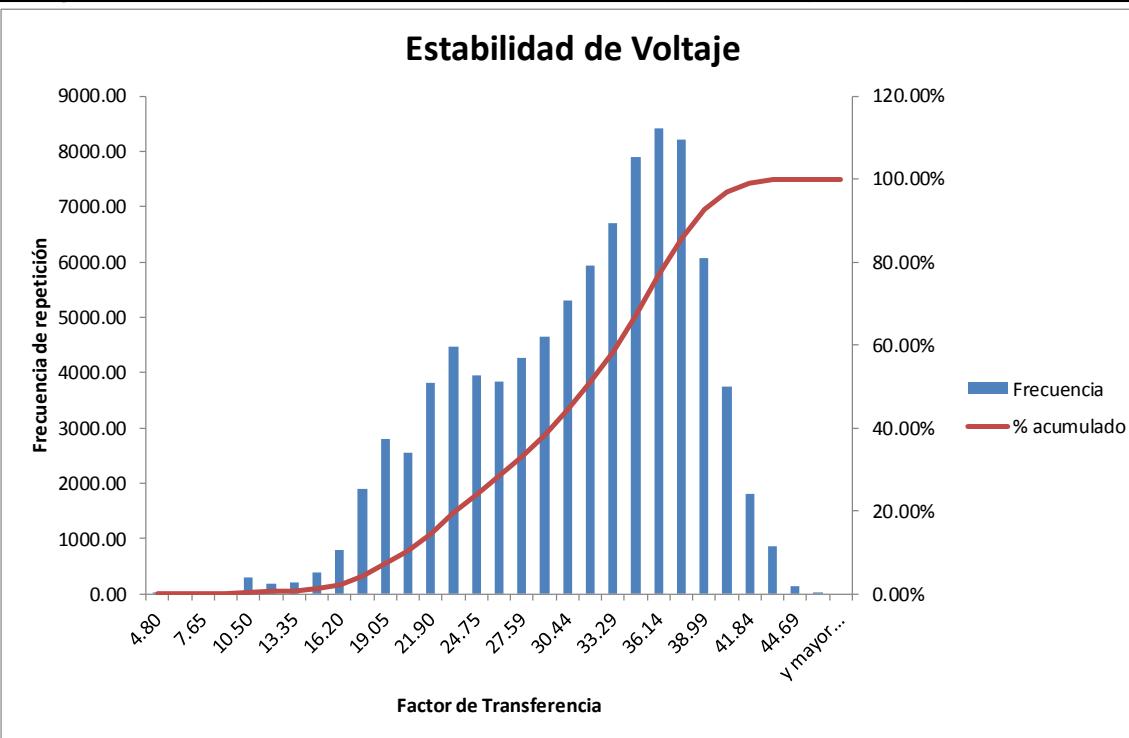
| MOLINO - SANTA ROSA | | | | LIMITES ALTA H | | DESVIOS | LIMITES BAJA H | | DESVIOS |
|---------------------|--------|-----------|-------|----------------|-------|---------|----------------|-------|---------|
| Max. (°) | 31.26 | PROMEDIO | 14.98 | Alerta (°) | 23.26 | 10.6% | Alerta (°) | 15.56 | 51.6% |
| Min. (°) | -10.08 | DSTANDARD | 7.66 | Alarma (°) | 35.04 | 0.0% | Alarma (°) | 29.42 | 0.0% |



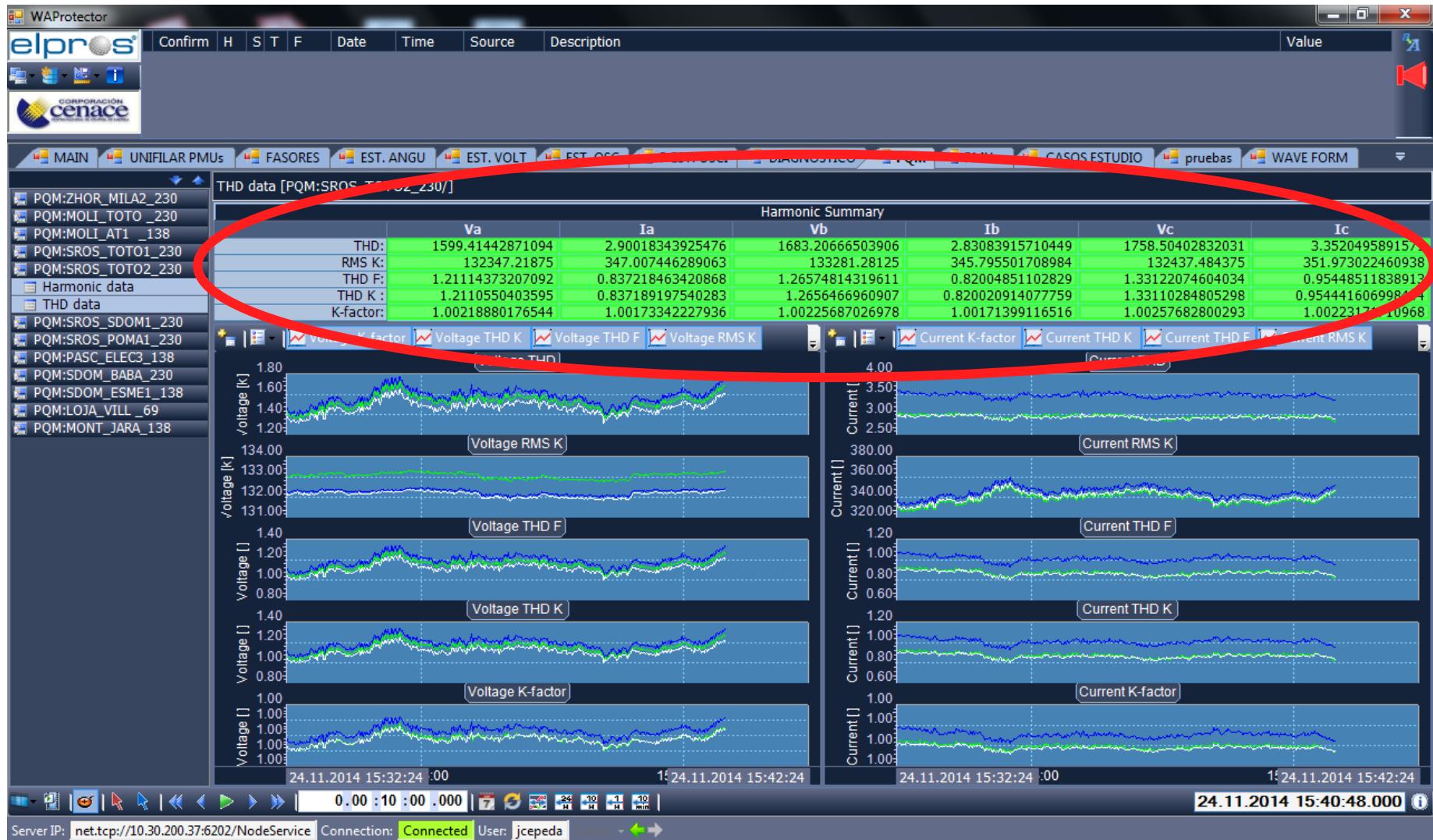
Voltage stability Post-operative Analysis

Deviations in the limits established for voltage stability of **corridor Santa Rosa - Totoras**, for August 2015 (scenario considered as high hydrology)

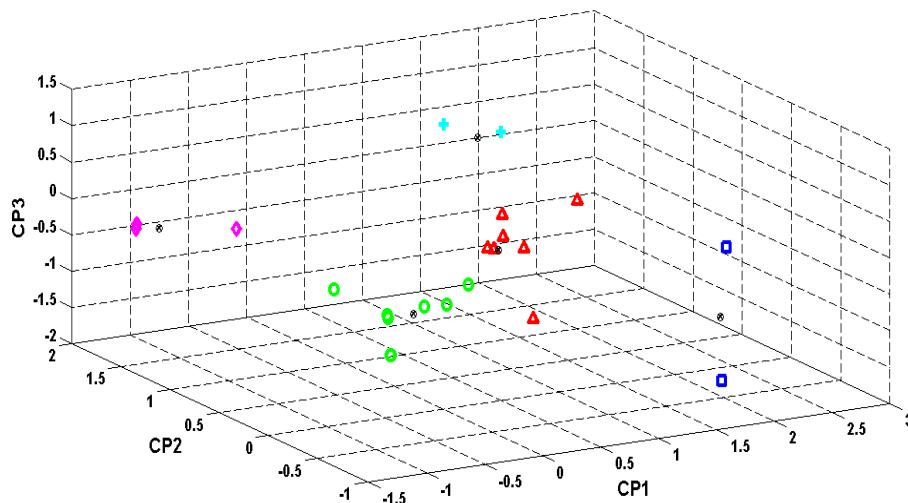
| SANTA ROSA - TOTORAS | | | | LIMITES ALTA H | | DESVIOS | | LIMITES BAJA H | | DESVIOS | |
|----------------------|-------|-----------|-------|----------------|-------|---------|---------------|----------------|------|---------|--|
| Max. (LF-P) | 46.11 | PROMEDIO | 30.36 | Alerta (LF-P) | 55.00 | 0.0% | Alerta (LF-P) | 42.00 | 0.2% | | |
| Min. (LF-P) | 4.80 | DSTANDARD | 6.91 | Alarma (LF-P) | 73.00 | 0.0% | Alarma (LF-P) | 59.00 | 0.0% | | |



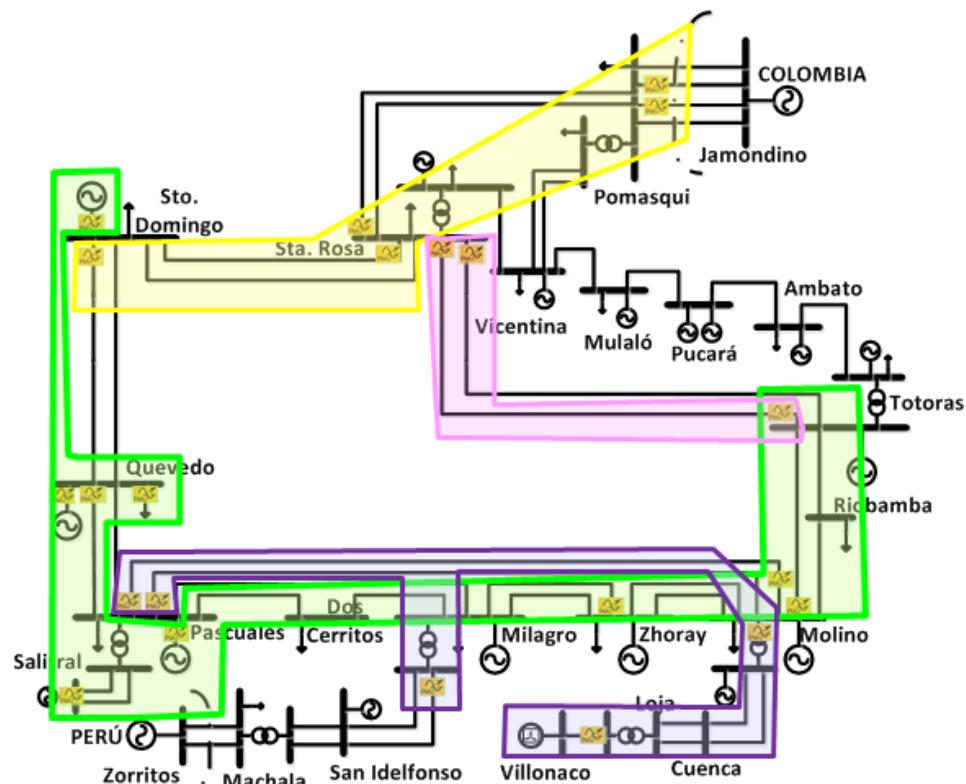
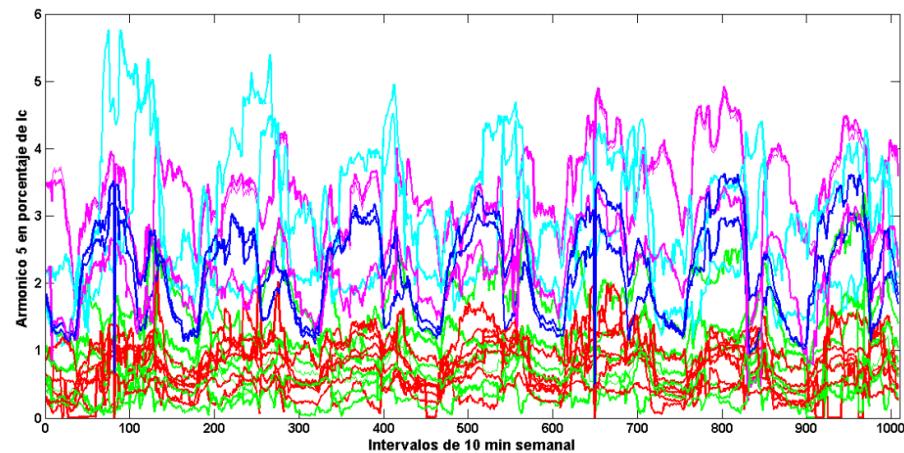
Power Quality



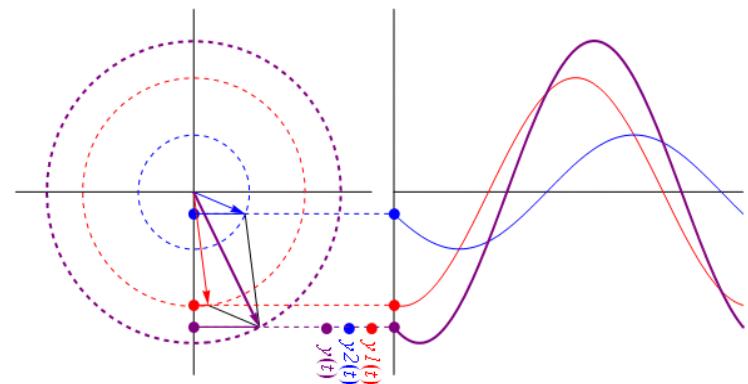
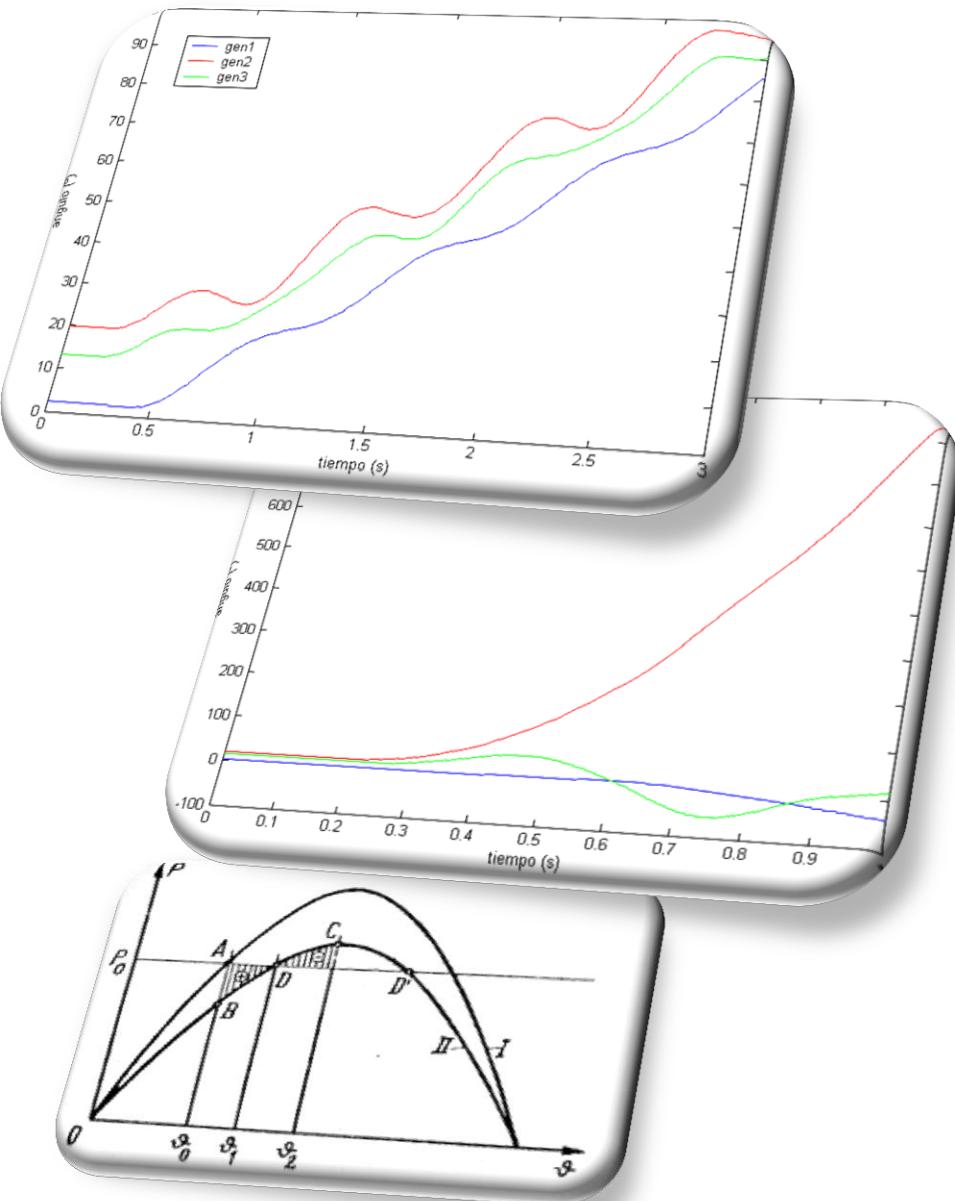
Geographic Characterization of Harmonics



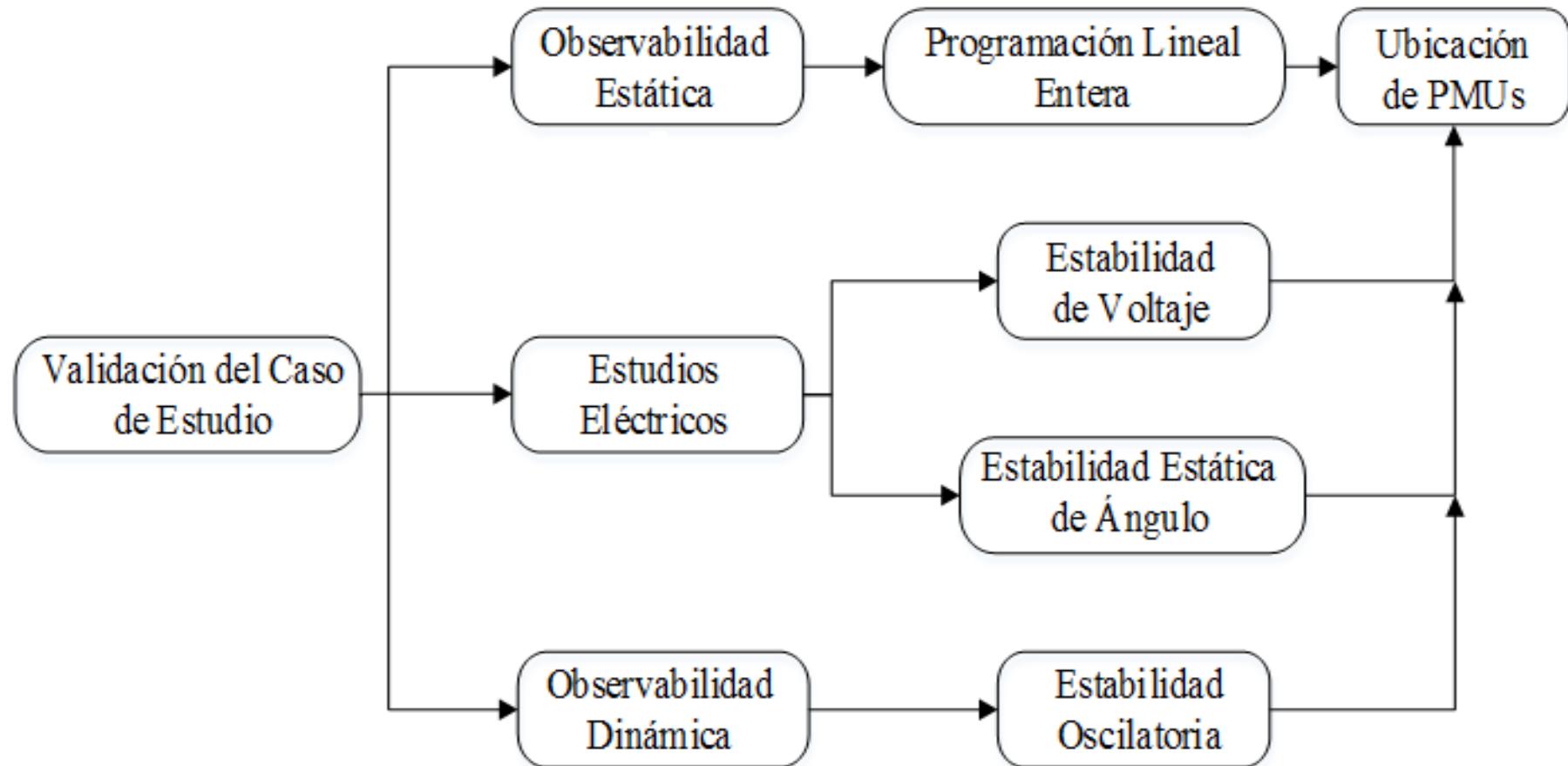
Geographic Clusters – Current Harmonics



Planning



PMU Location



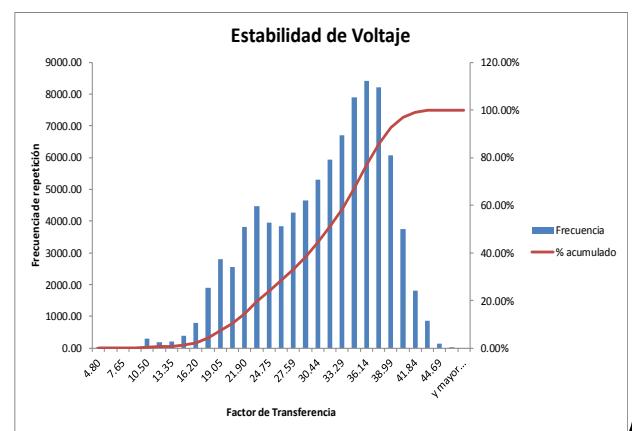
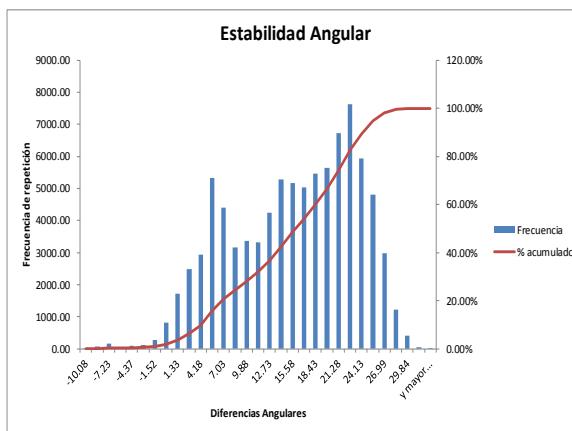
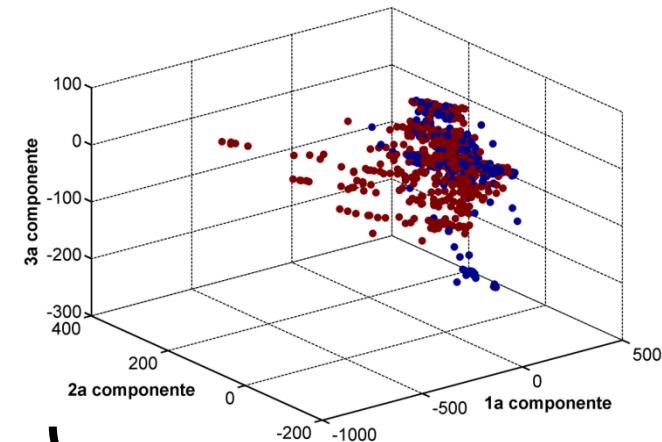
Requerimientos para la supervisión y control en tiempo real del Sistema Nacional Interconectado (REGULACIÓN No. ARCONEL- 003/16)

Dispatch with Security Constraints

Oscillatory Stability Patterns

Steady-state Angle Stability Statistics

Voltage Stability Statistics

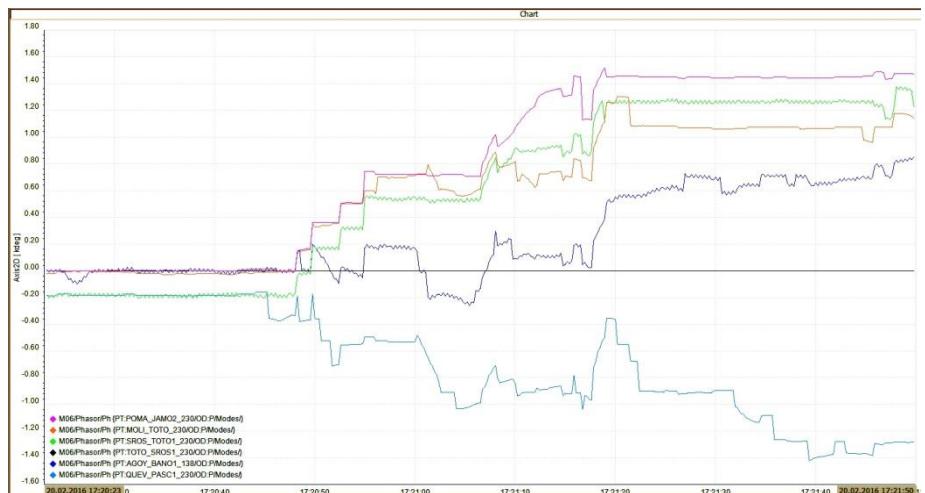
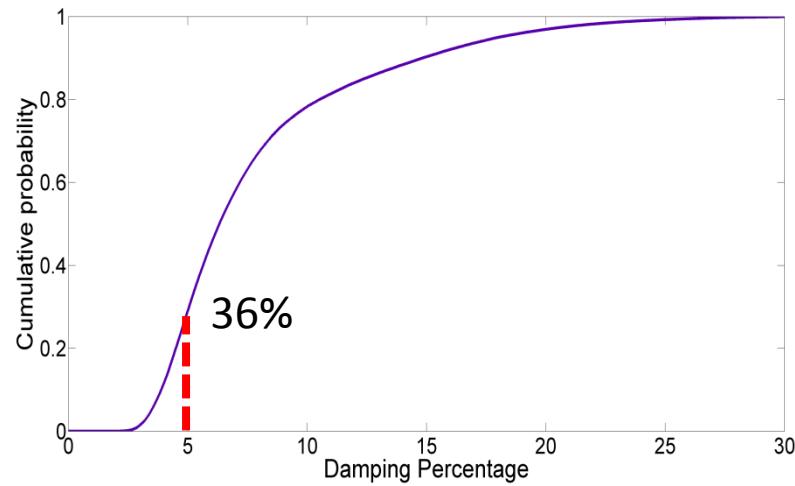
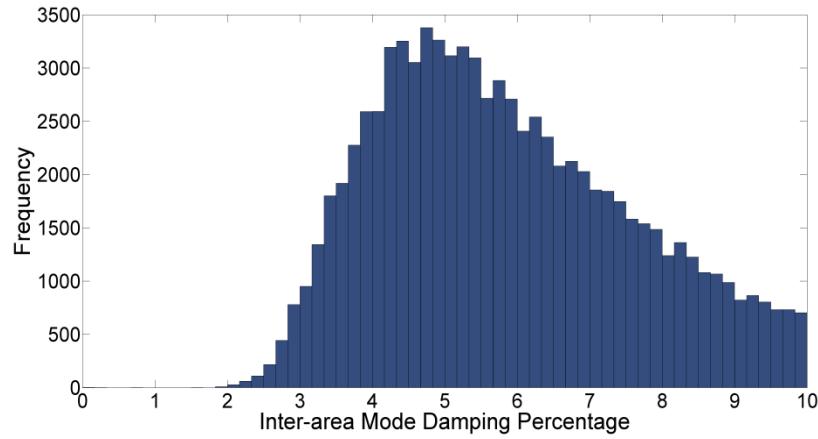
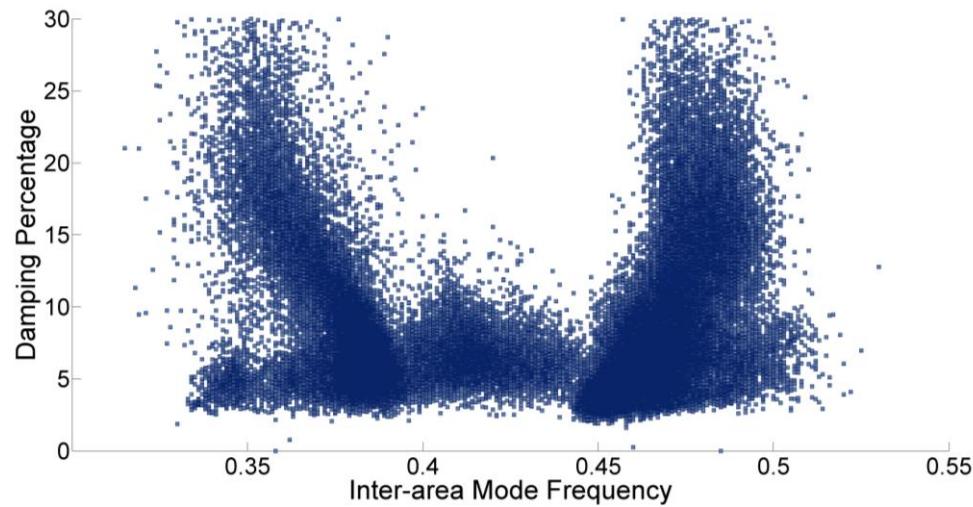


Correlations with Operation States

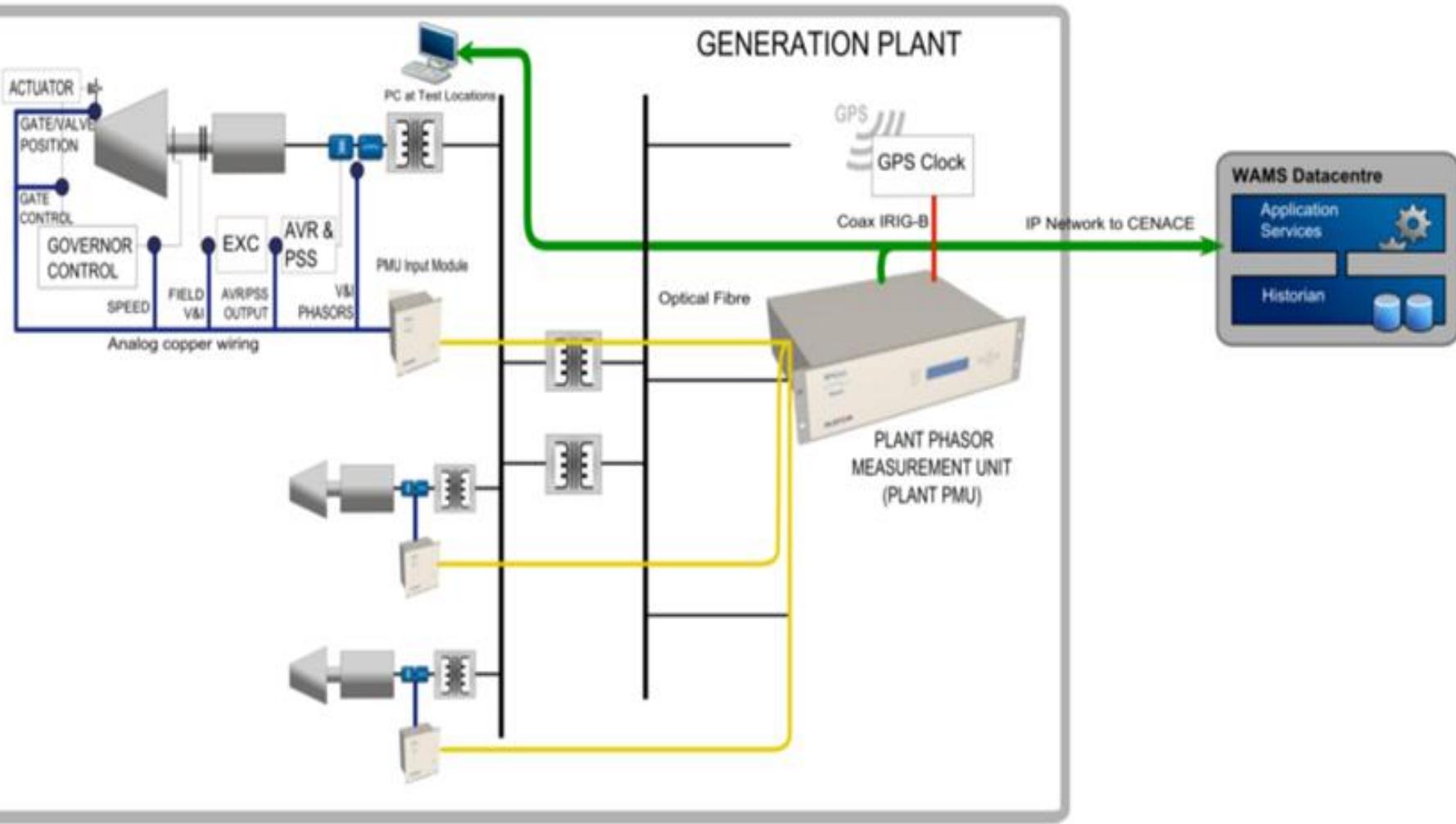


Seasonal Constraints based Dispatch

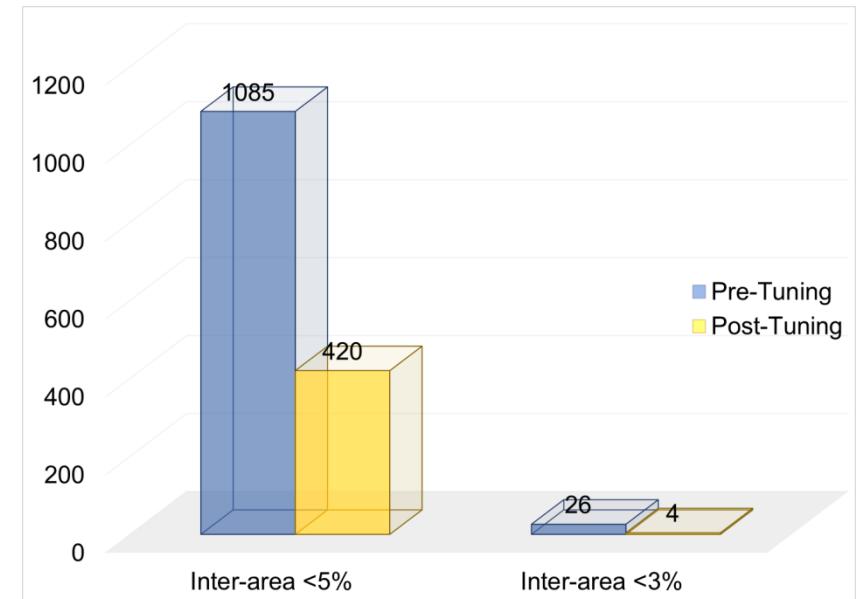
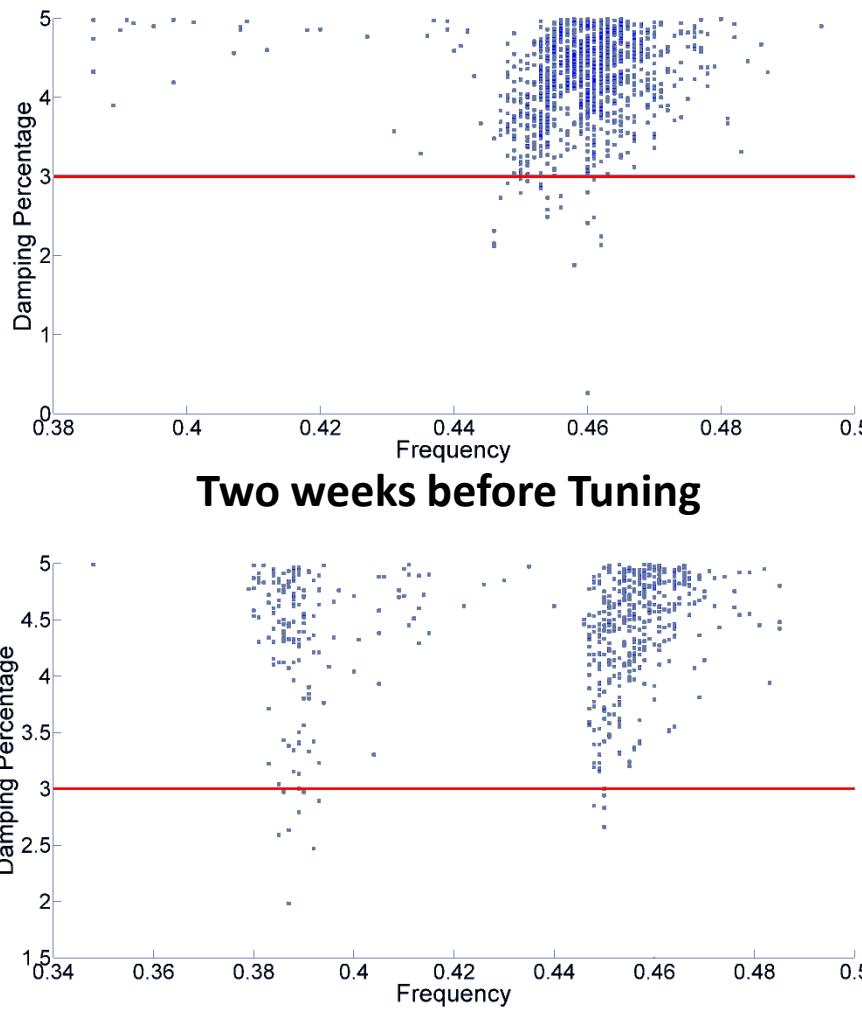
PSS Tuning



PSS Tuning



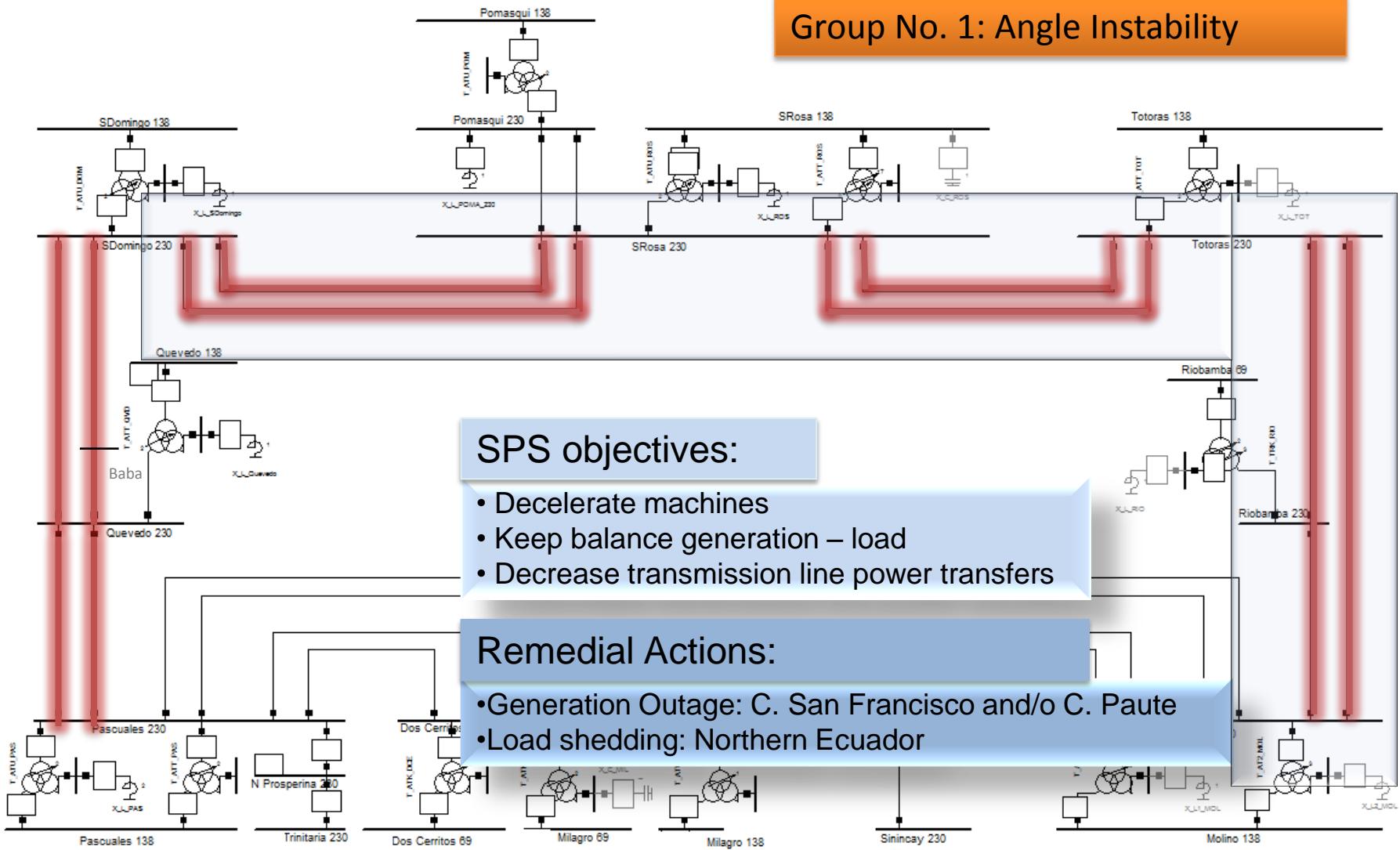
PSS Tuning



Two weeks after Tuning

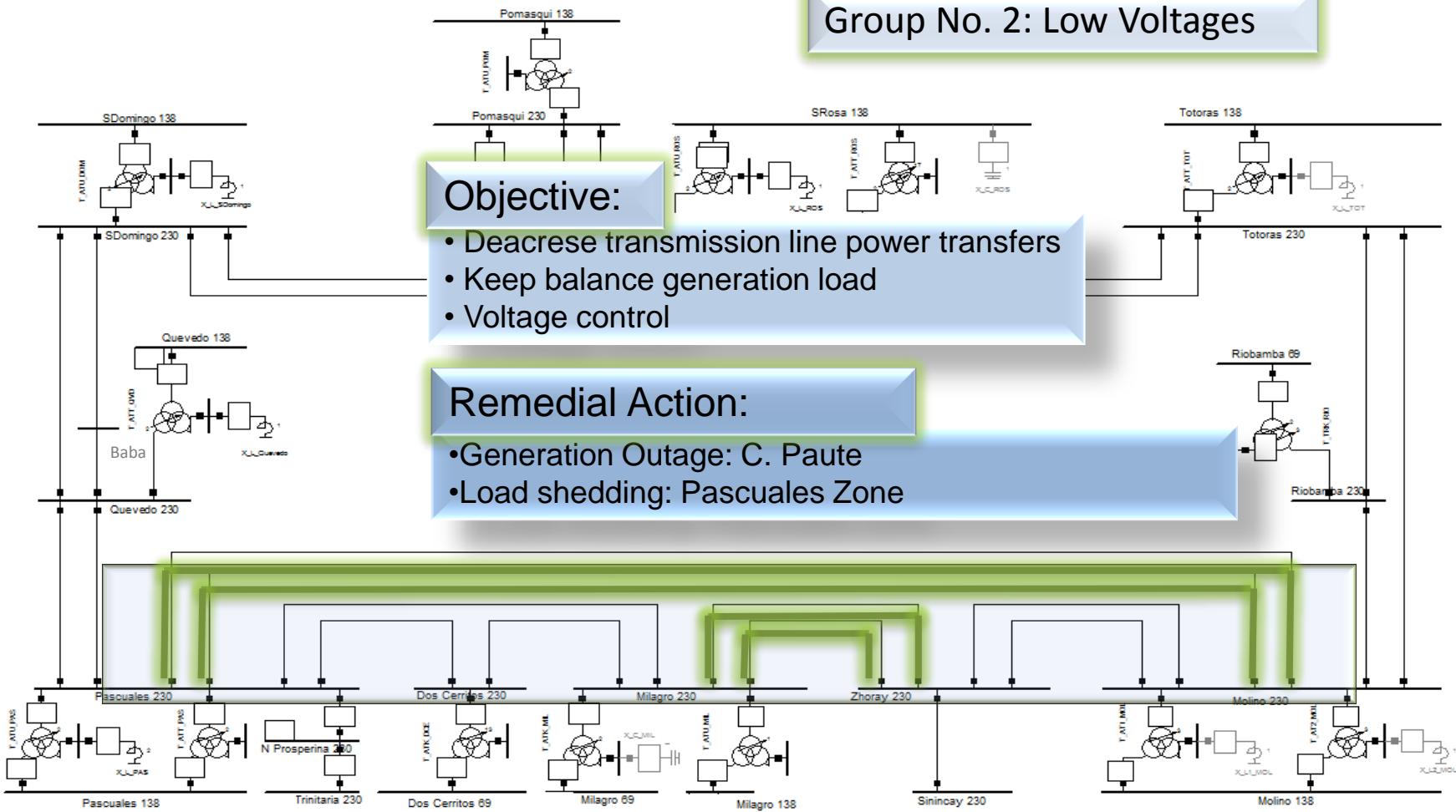
Special Protection Scheme – SPS

Group No. 1: Angle Instability



Special Protection Scheme – SPS

Group No. 2: Low Voltages



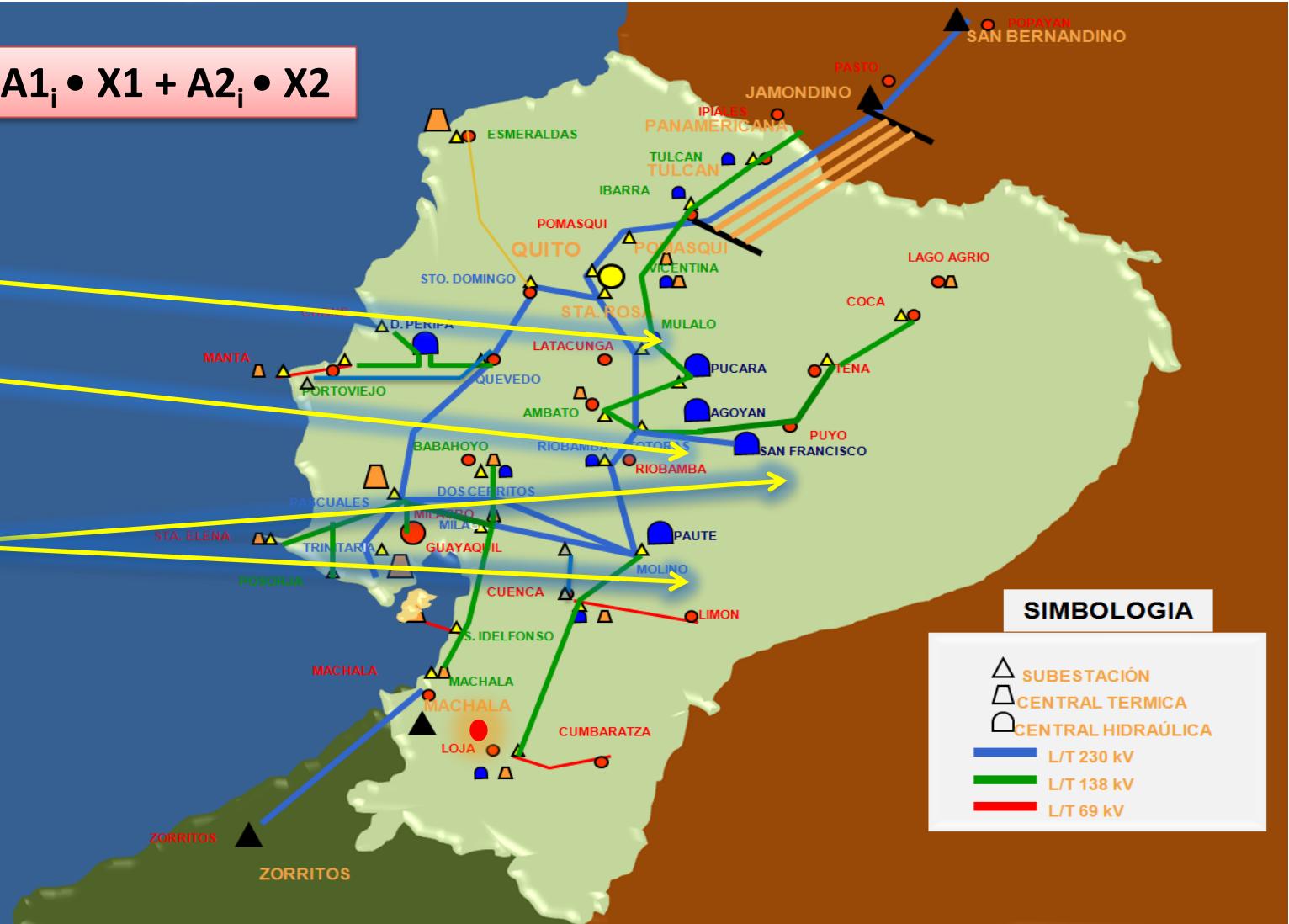
Intelligent Protection Scheme

$$Y = A0_i + A1_i \cdot X1 + A2_i \cdot X2$$

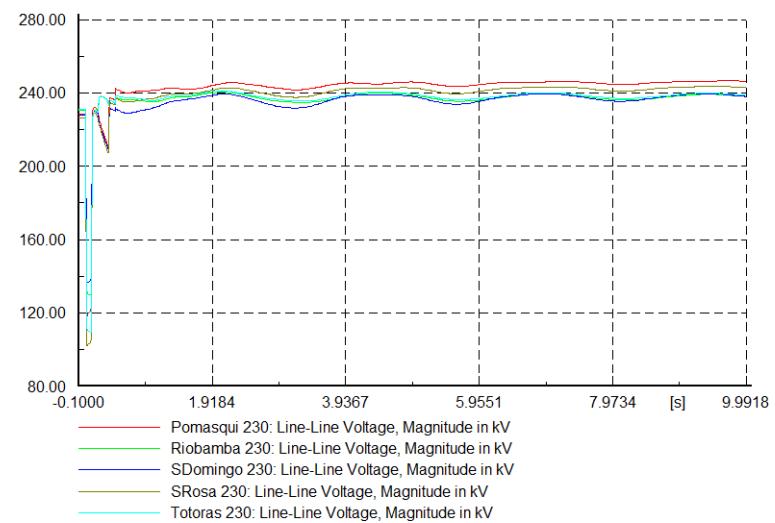
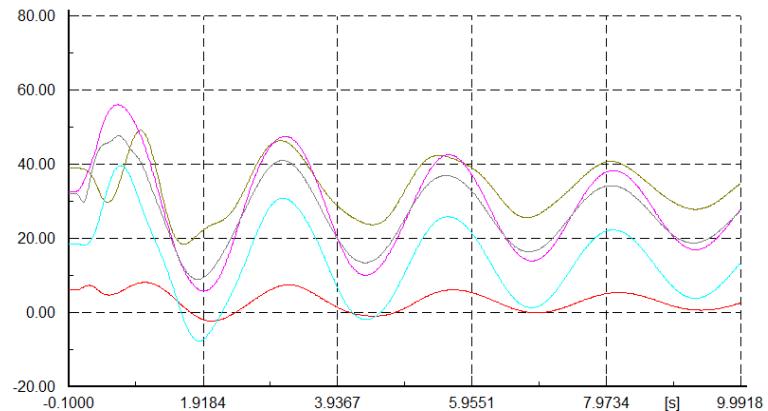
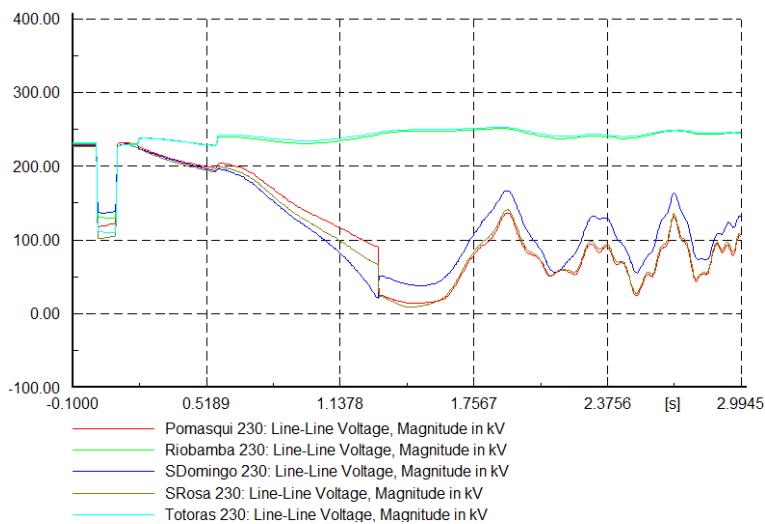
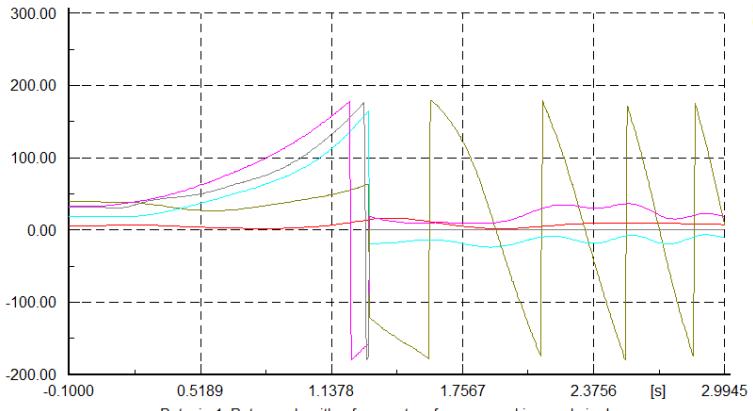
X1

X2

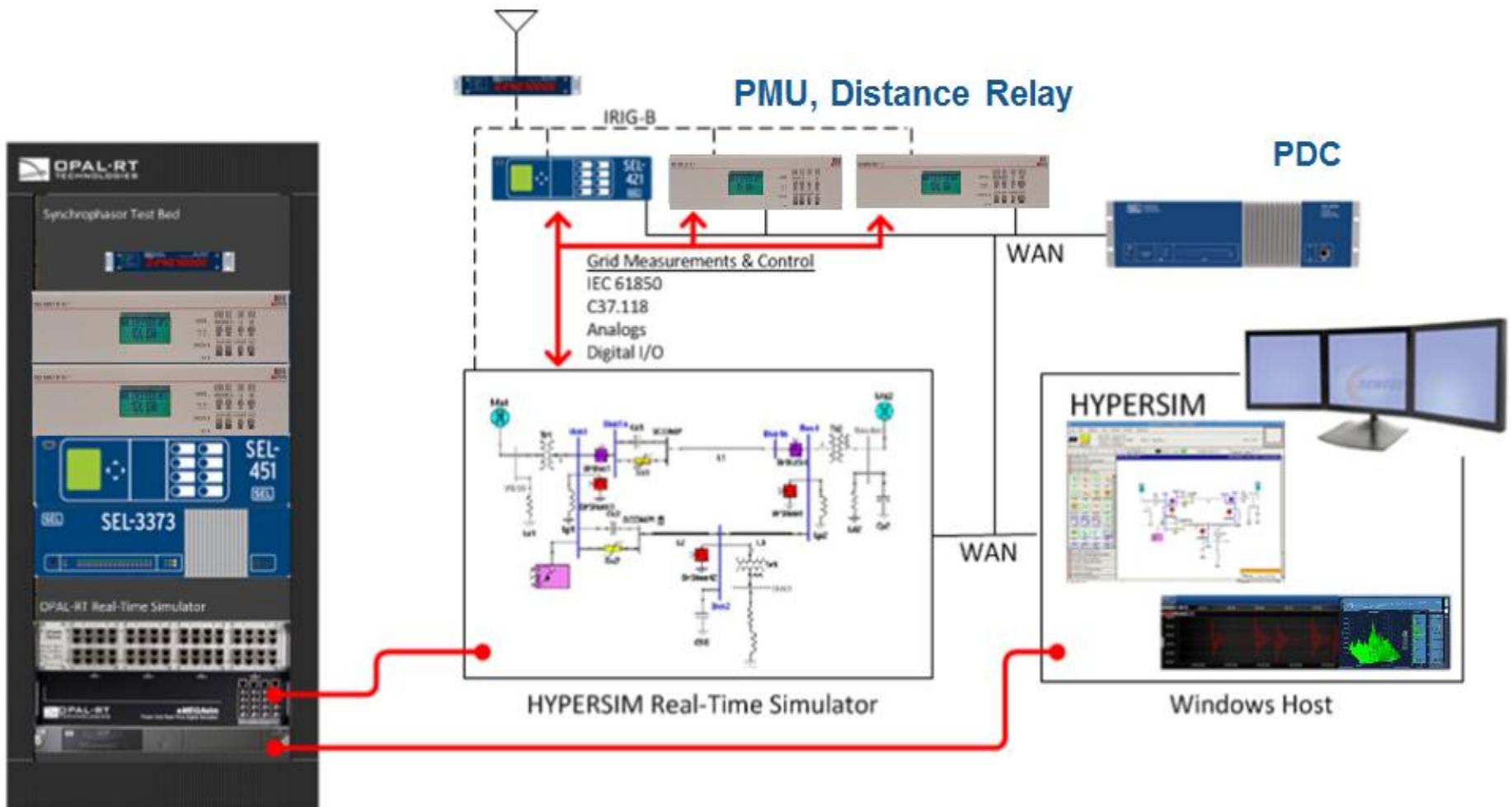
Y



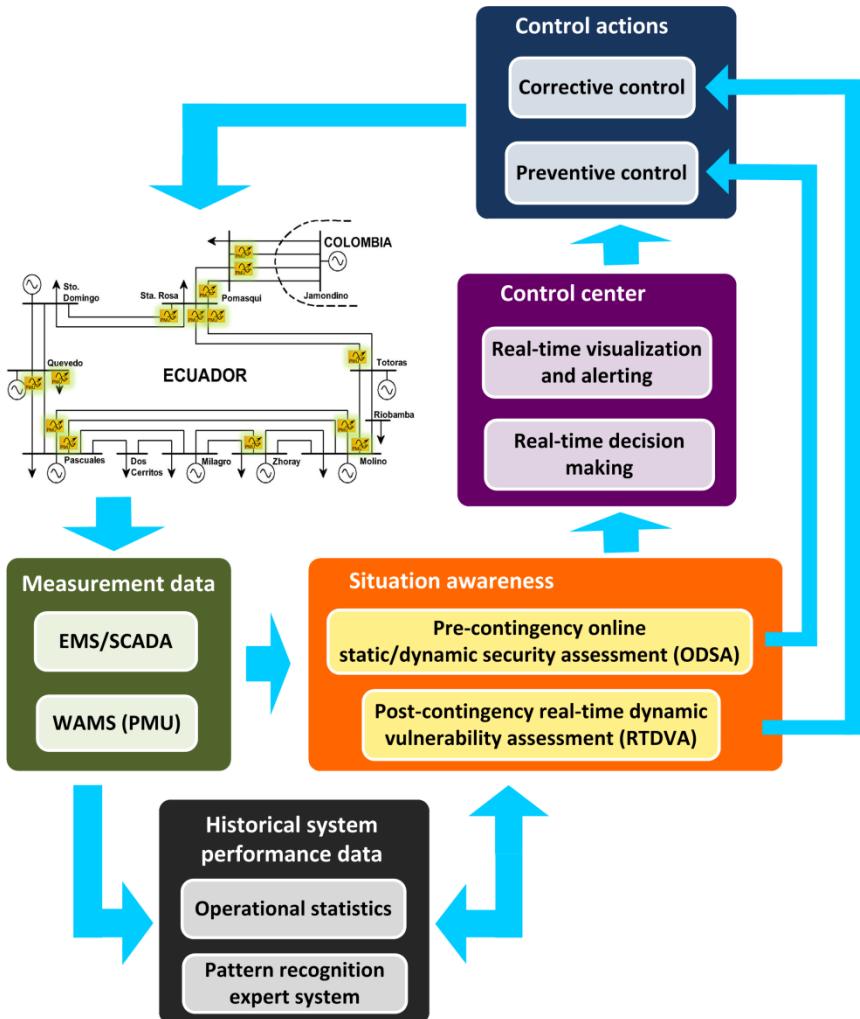
SPS Mitigation Effect



Parameter Identification - PMU Testbed - SPS Designed – Operators' Training



Real Time Security Assessment and Enhancement



- Update of system behavior **knowledge database** (i.e. operational statistics) and execution of **pattern recognition** routines, which supports the dynamic security assessment (DSA) and real-time dynamic vulnerability assessment (DVA) tasks.
- **DSA** in normal operating states to determine whether or not the system security level is to be degraded in future time when considering a selected set of credible contingencies.
- **Real-time DVA** to determine the actual system security level as well as the tendency of changing its conditions to a critical state in post-disturbance immediate time.

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