Lecture 18 Tree-based Methods II: Classification Tree

ECE 625: Data Analysis and Knowledge Discovery

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Outline

Tree Pruning

Classification Trees

Summary and Remark

Pruning a Tree

- ► The process described above may produce good predictions on the training set, but is likely to overfit the data, leading to poor test set performance. Why?
- ▶ A smaller tree with fewer splits (that is, fewer regions R_1, \dots, R_J) might lead to lower variance and better interpretation at the cost of a little bias.
- One possible alternative to the process described above is to grow the tree only so long as the decrease in the RSS due to each split exceeds some (high) threshold.
- This strategy will result in smaller trees, but is too short-sighted: a seemingly worthless split early on in the tree might be followed by a very good split that is, a split that leads to a large reduction in RSS later on.



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Pruning a Tree

- A better strategy is to grow a very large tree T_0 , and then prune it back in order to obtain a subtree.
- Cost complexity pruning also known as weakest link pruning
 is used to do this.
- we consider a sequence of trees indexed by a nonnegative tuning parameter α . For each value of α there is a subtree T constructed by collapsing some internal nodes of T_0 , such that

$$\sum_{m=1}^{|T|} \sum_{i:x_i \in R_m} (y_i - \hat{y}_{R_m})^2 + \alpha |T|$$

is minimized.

▶ Here |T| indicates the number of terminal nodes of the tree T, R_m is the rectangle (i.e. the subset of predictor space) corresponding to the mth terminal node, and \hat{y}_{R_m} is the mean of the training observations in R_m .

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How to find the best subtree for each α ?

- ► There are two terms in the loss function, one is its fidelity and the other one is its penalty.
- For each α , the optimal T_{α} can be found by weakest link pruning: we successively collapse the internal node that produces the smallest per-node increase in RSS, and continue until we produce the single-node (root) tree. You want to lose little in RSS but save in tree complexity
- Theory This gives a finite sequence of subtrees, and it is shown that this sequence must contain T_{α} . then just choose the tree that minimizes eq in prev slide
 - We select an optimal value $\hat{\alpha}$ using cross-validation.
 - We then return to the full data set and obtain the subtree corresponding to $\hat{\alpha}$.

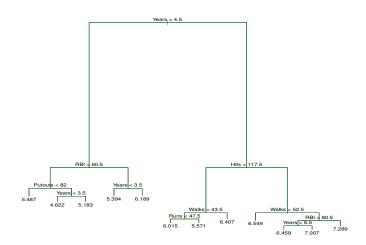
Building a Pruned Regression Tree: the Overall Algorithm

- 1 Use recursive binary splitting to grow a large tree on the training data, stopping only when each terminal node has fewer than some minimum number of observations.
- 2 Apply cost complexity pruning to the large tree in order to obtain a sequence of best subtrees, as a function of α .
- 3 Use K-fold cross-validation to choose α . For each $k = 1, \dots, K$:
 - Repeat Steps 1 and 2 on the (K-1)/Kth fraction of the training data, excluding the kth fold.
 - Evaluate the mean squared prediction error on the data in the left-out kth fold, as a function of α .
 - Average the results over K left-out folds, and pick α^* to minimize the average CV error.
- 4 Return the subtree from Step 2 (applied onto the full training dataset) that corresponds to the chosen α^* .

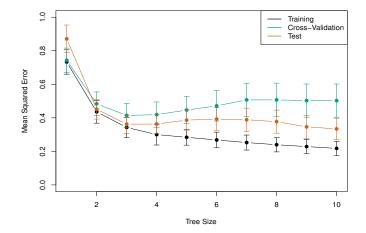
Baseball salary data

- ▶ First, we randomly divided the data set in half, yielding 132 observations in the training set and 131 observations in the test set.
- We then built a large regression tree on the training data and varied α in in order to create subtrees with different numbers of terminal nodes.
- Finally, we performed six-fold cross-validation in order to estimate the cross-validated MSE of the trees as a function of α .

Baseball salary data



Baseball salary data



Classification Trees

- Very similar to a regression tree, except that it is used to predict a qualitative response rather than a quantitative one.
- For a classification tree, we predict that each testing observation is from the most commonly occurring class of training observations in the region to which it belongs. majority vote
- ▶ Just as in the regression setting, we use recursive binary splitting to grow a classification tree.

Classification Trees

- ► In the classification setting, RSS cannot be used as a criterion for making the binary splits.
- A natural alternative to RSS is the classification error rate. this is simply the fraction of the training observations in that region that do not belong to the most common class:

$$E=1-\max_{k}\hat{p}_{mk}.$$

Here \hat{p}_{mk} represents the proportion of training observations in the *m*th region that are from the *k*th class.

► However classification error is not sufficiently sensitive for tree-growing, and in practice two other measures are preferable.

Gini Index and Cross-Entropy

► The Gini index is denoted by

$$G = \sum_{k=1}^{K} \hat{p}_{mk} (1 - \hat{p}_{mk})$$

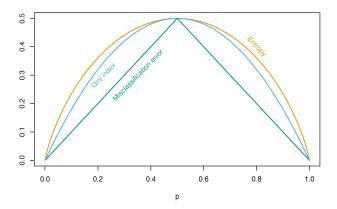
a measure of total variance across the K classes. The Gini index takes on a small value if all of the \hat{p}_{mk} 's are close to zero or one.

- ► For this reason the Gini index is referred to as a measure of node purity a small value indicates that a node contains predominantly observations from a single class.
- ► An alternative to the Gini index is cross-entropy, given by

$$D = -\sum_{k=1}^K \hat{p}_{mk} \log \hat{p}_{mk}.$$

It turns out that the Gini index and the cross-entropy are very similar numerically.

Different Node Impurity Measures for the 2-Class Case

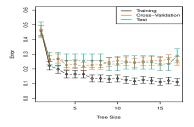


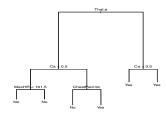
Heart Data

- ► These data contain a binary outcome HD of 303 patients who presented with chest pain.
- An outcome value of Yes indicates the presence of heart disease based on an angiographic test, while No means no heart disease.
- ► There are 13 predictors including Age, Sex, Chol (a cholesterol measurement), and other heart and lung function measurements.
- Cross-validation yields a tree with six terminal nodes. See next figure.

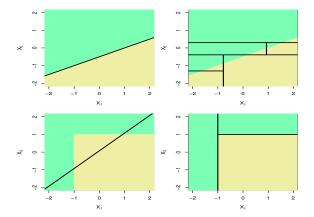
Heart Data







Trees Versus Linear Models



- ▶ Top Row: True linear boundary; Bottom row: true non-linear boundary.
- Left column: linear model; Right column: tree-based model.

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Advantages and Disadvantages of Trees

- ► Trees are very easy to explain to people. In fact, they are even easier to explain than linear regression!
- ► Some people believe that decision trees more closely mirror human decision-making than do the regression and classification approaches.
- ► Trees can be displayed graphically, and are easily interpreted even by a non-expert (especially if they are small).
- ► Trees can easily handle qualitative predictors without the need to create dummy variables
- Unfortunately, trees generally do not have the same level of predictive accuracy as some of the other regression and classification approaches seen in the textbook.
- ► However, by aggregating many decision trees, the predictive performance of trees can be substantially improved. We will introduce these concepts next.



Summary and Remark

- Pruning a tree
- Classification Tree
- ► Read textbook Chapter 9
- ▶ Do R lab