

Register file structure : regfile\_xgs\_athena.pdf

Created by imaval on 2020/04/30 18:00:16

Register file CRC32 : 0x048F2887

## 1. Main Parameters

Register file endianness: little endian

Address bus width: 11 bits

Data bus width: 32 bits

## 2. Memory Map

Section name	Address(es) / Address Ranges	Register name	Access Type
SYSTEM	0x000	TAG	R
	0x004	VERSION	R
	0x008	CAPABILITY	R
	0x00C	SCRATCHPAD	RW
DMA	0x070	CTRL	RW
	0x078	FSTART	RW
	0x07C	FSTART_HIGH	RW
	0x080	FSTART_G	RW
	0x084	FSTART_G_HIGH	RW
	0x088	FSTART_R	RW
	0x08C	FSTART_R_HIGH	RW
	0x090	LINE_PITCH	RW
	0x094	LINE_SIZE	RW
	0x098	CSC	RW
ACQ	0x100	GRAB_CTRL	RW
	0x108	GRAB_STAT	R
	0x110	READOUT_CFG1	R
	0x118	READOUT_CFG2	RW
	0x120	READOUT_CFG3	R
	0x128	EXP_CTRL1	RW
	0x130	EXP_CTRL2	RW
	0x138	EXP_CTRL3	RW
	0x140	TRIGGER_DELAY	RW
	0x148	STROBE_CTRL1	RW
	0x150	STROBE_CTRL2	RW
	0x158	ACQ_SER_CTRL	RW
	0x160	ACQ_SER_ADDDATA	RW
	0x168	ACQ_SER_STAT	R
	0x170	LVDS_CTRL	RW
	0x178	LVDS_CTRL2	RW
	0x180	LVDS_TRAINING	RW
	0x188	LVDS_STAT	R

Section name	Address(es) / Address Ranges	Register name	Access Type
	0x18C	LVDS_STAT2	R
	0x190	SENSOR_CTRL	RW
	0x198	SENSOR_STAT	R
	0x1A0	SENSOR_GEN_CFG	RW
	0x1A8	SENSOR_INT_CTL	RW
	0x1B0	SENSOR_GAIN_ANA	RW
	0x1B8	SENSOR_BLACK_CAL	RW
	0x1C0	SENSOR_ROI_CONF0	RW
	0x1C4	SENSOR_ROI2_CONF0	RW
	0x1C8	SENSOR_ROI_CONF1	RW
	0x1CC	SENSOR_ROI2_CONF1	RW
	0x1D0	SENSOR_ROI_CONF2	RW
	0x1D4	SENSOR_ROI2_CONF2	RW
	0x1D8	CRC	RW
	0x1E0	DEBUG_PINS	RW
	0x1E8	TRIGGER_MISSED	RW
	0x1F0	SENSOR_FPS	R
	0x220	DEBUG	RW
	0x228	DEBUG_CNTR1	R
	0x230	DEBUG_CNTR2	R
	0x234	DEBUG_CNTR3	R
	0x23C	EXP_FOT	RW
	0x244	ACQ_SFNC	W
	0x254	NOPEL	RW
DATA	0x300	LUT_CTRL	RW
	0x308	LUT_RB	R
	0x310	WB_MULT1	RW
	0x318	WB_MULT2	RW
	0x320	WB_B_ACC	R
	0x328	WB_G_ACC	R
	0x330	WB_R_ACC	R
	0x338	FPN_ADD	RW
	0x33C	FPN_READ_REG	RW
	0x340, 0x344, ... ,0x35C	FPN_DATA (7:0)	RW
	0x360	FPN_CONTRAST	RW
	0x368	FPN_ACC_ADD	RW
	0x370	FPN_ACC_DATA	R
	0x380	DPC_LIST_CTRL	RW
	0x384	DPC_LIST_DATA	RW
	0x388	DPC_LIST_DATA_RD	R
HISPI	0x400	CTRL	RW
	0x404	IDELAYCTRL_STATU S	R
	0x408, 0x40C, ... ,0x41C	LANE_DECODER_STA TUS (5:0)	RW
	0x420, 0x424, 0x428	LANE_PACKER_STA TUS (2:0)	RW

### 3. Registers definition

## Section: SYSTEM

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Address Range: [0x000 - 0x00C]

## TAG

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Address: section "SYSTEM" base address + 0x000

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
VALUE(23:16)							
15	14	13	12	11	10	9	8
VALUE(15:8)							
7	6	5	4	3	2	1	0
VALUE(7:0)							

<b>VALUE (23:0)</b> <i>STATIC</i>	Tag identifier	
Value at Reset:	0x58544d	
Possible Values:	0x58544D	MTX ASCII string

Address: section "SYSTEM" base address + 0x004

Description:

Revisions

1.3.x : First functional revision with a single list of multiple Ethernet frames

1.4.x : Second revision. Implements multiple list of frames

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
MAJOR(7:0)							
15	14	13	12	11	10	9	8
MINOR(7:0)							
7	6	5	4	3	2	1	0
HW(7:0)							

<b>MAJOR (7:0)</b>	
<i>STATIC</i>	
Value at Reset:	0x0

<b>MINOR (7:0)</b>	
<i>STATIC</i>	
Value at Reset:	0x0

<b>HW (7:0)</b>	
<i>RO</i>	

Address: section "SYSTEM" base address + 0x008

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
Reserved							
7	6	5	4	3	2	1	0
VALUE(7:0)							

VALUE (7:0)	
STATIC	
Value at Reset:	0x0

Address: section "SYSTEM" base address + 0x00C

31	30	29	28	27	26	25	24
VALUE(31:24)							
23	22	21	20	19	18	17	16
VALUE(23:16)							
15	14	13	12	11	10	9	8
VALUE(15:8)							
7	6	5	4	3	2	1	0
VALUE(7:0)							

VALUE (31:0)	
RW	
Value at Reset:	0x0

Section: DMA

Address Range: [0x070 - 0x0A4]

CTRL

Initial Grab Address Register

Address: section "DMA" base address + 0x000

Description:  
Initial Grab Address LOW 32 bits

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
Reserved							
7	6	5	4	3	2	1	0
Reserved							GRAB_QUEUE_EN

GRAB_QUEUE_EN RW		
Value at Reset:	0x0	
Possible Values:	0x0	
	0x1	

Address: section "DMA" base address + 0x008

Description:

Initial Grab Address LOW 32 bits

31	30	29	28	27	26	25	24
VALUE(31:24)							
23	22	21	20	19	18	17	16
VALUE(23:16)							
15	14	13	12	11	10	9	8
VALUE(15:8)							
7	6	5	4	3	2	1	0
VALUE(7:0)							

<b>VALUE (31:0)</b>	Initial GRAB ADDRESS Register	
<i>RW</i>	This is the address in the host ram where the grab engine will start writing pixel data.	
Value at Reset:	0x0	
Possible Values:	Any Value	



Address: section "DMA" base address + 0x00C

Description:

Initial Grab Address HI 32 bits

31	30	29	28	27	26	25	24
VALUE(31:24)							
23	22	21	20	19	18	17	16
VALUE(23:16)							
15	14	13	12	11	10	9	8
VALUE(15:8)							
7	6	5	4	3	2	1	0
VALUE(7:0)							

<b>VALUE (31:0)</b>	Initial GRAB ADDRESS Register High	
<i>RW</i>	This is the high 32 bits of the 64-bit addresses in the host ram where the grab engine will start writing pixel data.	
Value at Reset:	0x0	
Possible Values:	Any Value	

Address: section "DMA" base address + 0x010

Description:

Grab Address LOW 32 bits for the Green plane. Only used when grabbing in Planar mode.

31	30	29	28	27	26	25	24
VALUE(31:24)							
23	22	21	20	19	18	17	16
VALUE(23:16)							
15	14	13	12	11	10	9	8
VALUE(15:8)							
7	6	5	4	3	2	1	0
VALUE(7:0)							

<b>VALUE (31:0)</b>	GRAb ADDRess Register	
<i>RW</i>	This is the address in the host ram where the grab engine will start writing pixel data.	
Value at Reset:	0x0	
Possible Values:	Any Value	

Address: section "DMA" base address + 0x014

Description:

Green Grab Address HIGH 32 bits

31	30	29	28	27	26	25	24
VALUE(31:24)							
23	22	21	20	19	18	17	16
VALUE(23:16)							
15	14	13	12	11	10	9	8
VALUE(15:8)							
7	6	5	4	3	2	1	0
VALUE(7:0)							

<b>VALUE (31:0)</b> <i>RW</i>	GRAb ADDRess Register High	
	This is the high part of the 64-bit addresses in the host ram where the grab engine will start writing pixel data.	
Value at Reset:	0x0	
Possible Values:	Any Value	Any value

Address: section "DMA" base address + 0x018

Description:

Grab Address LOW 32 bits for the Red plane. Only used when grabbing in Planar mode.

31	30	29	28	27	26	25	24
VALUE(31:24)							
23	22	21	20	19	18	17	16
VALUE(23:16)							
15	14	13	12	11	10	9	8
VALUE(15:8)							
7	6	5	4	3	2	1	0
VALUE(7:0)							

<b>VALUE (31:0)</b>	GRAb ADDRess Register	
<i>RW</i>	This is the address in the host ram where the grab engine will start writing pixel data.	
Value at Reset:	0x0	
Possible Values:	Any Value	Any value

Address: section "DMA" base address + 0x01C

Description:

Red Grab Address HIGH 32 bits

31	30	29	28	27	26	25	24
VALUE(31:24)							
23	22	21	20	19	18	17	16
VALUE(23:16)							
15	14	13	12	11	10	9	8
VALUE(15:8)							
7	6	5	4	3	2	1	0
VALUE(7:0)							

<b>VALUE (31:0)</b> <i>RW</i>	GRAb ADDRess Register High	
	This is the high part of the 64-bit addresses in the host ram where the grab engine will start writing pixel data.	
Value at Reset:	0x0	
Possible Values:	Any Value	Any value

Address: section "DMA" base address + 0x020

Description:  
Grab Line Pitch Register

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
VALUE(15:8)							
7	6	5	4	3	2	1	0
VALUE(7:0)							

VALUE (15:0)	Grab LinePitch
RW	This is the line pitch when writing in ram. It is measured in bytes, not pixels.
Value at Reset:	0x0

Address: section "DMA" base address + 0x024

Description:

Host Line Size Register.

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
Reserved		VALUE(13:8)					
7	6	5	4	3	2	1	0
VALUE(7:0)							

<b>VALUE (13:0)</b> <i>RW</i>	Host Line size	
	This is the line size when writing in host ram. It is measured in bytes, not pixels. If this register is higher than the actual data provided by the sensor, stray data will be written into host memory. If this register is lower than the data provided by the sensor, image data will be cropped at the end of the line.  For backward compatibility, the value of 0 indicates that the FPGA should auto-compute the line sized based on data provided by the sensor interface.	
Value at Reset:	0x0	
Possible Values:	0x1 - 0x3FFF	Written line size in host frame.
	0x0	Auto-compute line size from sensor data.

Address: section "DMA" base address + 0x028

31	30	29	28	27	26	25	24
Reserved					COLOR_SPACE(2:0)		
23	22	21	20	19	18	17	16
DUP_LAST_LINE	Reserved						
15	14	13	12	11	10	9	8
Reserved						REVERSE_Y	REVERSE_X
7	6	5	4	3	2	1	0
Reserved							

<b>COLOR_SPACE (2:0)</b>		
<i>RW</i>	Output color space used to transfer data to the DMA engine.	
Value at Reset:	0x0	
Possible Values:	0x0	Reserved for Mono sensor operation
	0x1	BGR32
	0x2	YUV 4:2:2 in full range
	0x3	Planar 8-bits
	0x4	Reserved for Y only with color sensor
	0x5	RAW color pixels (8bpp or 10bpp selected with MONO10 registor)

<b>DUP_LAST_LINE</b>		
<i>RW</i>	This field is used to enable the duplicate last line feature. When turned on, the datapath will regenerate the last line when it receives the end of frame marker from the acquisition section.  The goal of this feature is to compensate for the lost line during the Bayer demosaic processing.	
Value at Reset:	0x0	
Possible Values:	0x0	normal processing
	0x1	last line is duplicated

<b>REVERSE_Y</b>	REVERSE Y	
<i>RW</i>	Reverse readout	
Value at Reset:	0x0	
Possible Values:	0x0	Bottom to top readout
	0x1	Top to bottom readout

<b>REVERSE_X</b>		
<i>RW</i>		
Value at Reset:	0x0	



## Section: ACQ

Address Range: [0x100 - 0x254]

### GRAB\_CTRL

### GRAB ConTRoL Register

Address: section "ACQ" base address + 0x000

Description:

Grag Control Register

31	30	29	28	27	26	25	24
RESET_GRAB	Reserved	GRAB_ROI2_EN	ABORT_GRAB	Reserved	Reserved	SLOPE_CFG(1:0)	
23	22	21	20	19	18	17	16
Reserved							TRIGGER_O VERLAP_BUFn
15	14	13	12	11	10	9	8
TRIGGER_O VERLAP	TRIGGER_ACT(2:0)			Reserved	Reserved	TRIGGER_SRC(1:0)	
7	6	5	4	3	2	1	0
Reserved			GRAB_SS	Reserved	Reserved	BUFFER_ID	GRAB_CMD

<b>RESET_GRAB</b> <i>RW</i>							
	This register resets the entire python_ctrl.						
Value at Reset:	0x0						
Possible Values:	0x0			Reset not active			
	0x1			Reset active			

<b>GRAB_ROI2_EN</b> <i>RW</i>							
	Enable the second ROI on the frame (KNS). This register is not DB. 1) No Y overlap is allowed 2) Xsize must be the same for the two ROI for the moment(DMA constraint). 3) EOF and SOF in between the two in-frame ROIs will be masked to the DMA. The DMA will see one frame, with the two ROI inside.						
Value at Reset:	0x0						
Possible Values:	0x0			Dual ROI disable			
	0x1			Dual ROI enable			

<b>ABORT_GRAB</b> <i>WO/AutoClr</i>	ABORT GRAB						
	This is the grab reset, it will reset all the grab queued.						
Possible Values:	0x0			Normal operation			
	0x1			Reset Grab			

<b>SLOPE_CFG (1:0)</b> <i>RW</i>	Multiple SLOPE integration ConFiGuration	
	<p>This field is the multiple SLOPE integration configuration register. This register is not double buffered in the FPGA.</p> <p>If a single slope mode is selected, register EXP_CTRL1.EXPOSURE_SS must be programmed.</p> <p>If a dual slope mode is selected, registers EXP_CTRL1.EXPOSURE_SS and EXP_CTRL2.EXPOSURE_DS must be programmed.</p> <p>If a tripple slope mode is selected registers EXP_CTRL1.EXPOSURE_SS, EXP_CTRL2.EXPOSURE_DS and EXP_CTRL2.EXPOSURE_TS must be programmed.</p>	
Value at Reset:	0x1	
Possible Values:	0x0	RESERVED
	0x1	Single slope mode (default mode)
	0x2	Dual slope mode
	0x3	Triple slope mode

<b>TRIGGER_OVERLAP_BUF Fn</b> <i>RW</i>		
	NOT FULLY VALIDATED. DON'T USE. SET IT TO '0'.	
Value at Reset:	0x0	
Possible Values:	0x0	Buffer the trigger received during the dead window in PET mode and execute
	0x1	The trigger will be ignored during dead window in PET mode.

<b>TRIGGER_OVERLAP</b> <i>RW</i>		
	This field enables the trigger overlap. In this mode the exposure and the readout of the sensor can be done in parallel for higher framerates.	
Value at Reset:	0x1	
Possible Values:	0x0	Trigger Overlap disable
	0x1	Trigger Overlap enable (default)

<b>TRIGGER_ACT (2:0)</b> <i>RW</i>	TRIGGER ACTivation	
	<p>This is the trigger activation . This register selects the activation of the trigger when the trigger source is set to Hardware Snapshot mode .</p> <p>This register is Double Buffered, so the trigger activation may change from one grab command to another.</p> <p>In activation Level HI/LO with EXPOSURE_MODE register set to Timed, the camera will be triggered in continuous way if the level of the external trigger remains at the LEVEL programmed in this register.</p> <p>In activation Level HI/LO with EXPOSURE_MODE register set to Trigger Width, the Exposure time will be set by the level of the trigger input. The FPGA exposure regsiters will be ignored. The Dual and Triple slope are not supported in the mode.</p>	
Value at Reset:	0x0	
Possible Values:	0x0	Rising edge
	0x1	Falling edge
	0x2	Rising or Falling edge
	0x3	Level HI
	0x4	Level LO
	0x5	RESERVED
	0x6	RESERVED
	0x7	RESERVED

<b>TRIGGER_SRC (1:0)</b> <i>RW</i>	TRIGGER SouRCe	
	This is the trigger source. This register selects the source of the grab trigger. This register is Double Buffered, so the trigger source may change from one grab command to another. TRIGGER_SRC(1) may be seen as a TRIGGER_STATE by the software driver.	
Value at Reset:	0x0	
Possible Values:	0x0	RESERVED
	0x1	Immediate mode (Continuous)
	0x2	Hardware Snapshot mode
	0x3	Software Snapshot mode

<b>GRAB_SS</b> <i>WO/AutoClr</i>	GRAB Software Snapshot	
	This is the software snapshot register when the trigger source selected is Software Snapshot mode.	
Possible Values:	0x0	Idle
	0x1	Start a grab

<b>BUFFER_ID</b> <i>RW</i>		
	This is the ID of the DMA parameters to associate with this grab command.	
Value at Reset:	0x0	

<b>GRAB_CMD</b> <i>WO/AutoClr</i>	GRAB CoMmanD	
	When the trigger source is set to Immediate mode(Continuous), an exposure sequence will be automatically executed. When the trigger source is set to Software Snapshot mode or Hardware Snapshot mode, GRAB_CMD will act as an ARM.  The GRAB_CMD will take around 13 clks to reccord the grab parametters to the SPI fifo. The GRAB_CMD_DONE register may be readed to avoid fifo corruption before sending another Grab command instruction.	
Possible Values:	0x0	Idle
	0x1	Start grab command

## GRAB\_STAT

Address: section "ACQ" base address + 0x008

31	30	29	28	27	26	25	24
GRAB_CMD_DONE	ABORT_PET	ABORT_DELA I	ABORT_DONE E	Reserved		TRIGGER_RDY	
23	22	21	20	19	18	17	16
Reserved	ABORT_MNGR_STAT(2:0)			TRIG_MNGR_STAT(3:0)			
15	14	13	12	11	10	9	8
Reserved	TIMER_MNGR_STAT(2:0)			GRAB_MNGR_STAT(3:0)			
7	6	5	4	3	2	1	0
Reserved	GRAB_FOT	GRAB_READ OUT	GRAB_EXPO SURE	Reserved	GRAB_PEND ING	GRAB_ACTI VE	GRAB_IDLE

<b>GRAB_CMD_DONE</b> <i>RO</i>	GRAB CoMmanD DONE						
	The GRAB_CMD will take around 13 clks to reccord the grab parametters to the SPI fifo. This register may be readed to avoid fifo corruption before sending another Grab command instruction.						
Possible Values:	0x0		Grab Command in process				
	0x1		Grab command idle				

<b>ABORT_PET</b> <i>RO</i>	ABORT during PET						
	This is the ABORT PET flag. It is set to '1' when an abort is detected in the PETengin phase of the trigger. It is set back to '0' when ABORT_DONE is set to '1'.						
Possible Values:	0x0		Abort in PET Phase idle				
	0x1		Abort in PET Phase active				

<b>ABORT_DELAI</b> <i>RO</i>							
	This is the ABORT DELAI flag. It is set to '1' when an abort is detected in the delai phase of the trigger. It is set back to '0' when ABORT_DONE is set to '1'.						
Possible Values:	0x0		Abort in Delai Phase idle				
	0x1		Abort in Delai Phase active				

<b>ABORT_DONE</b> <i>RO</i>	ABORT is DONE						
	This read-only field indicates the RESET_GRAB command status. If 0, an abort sequence is executing.						
Possible Values:	0x0		Abort sequence not finished yet				
	0x1		Abort DONE, or not started (reset value)				

<b>TRIGGER_RDY</b> <i>RO</i>							

<b>ABORT_MNGR_STAT (2:0)</b> <i>RO</i>							
	DEBUG ABORT MANAGER STATE MACHINE						

<b>TRIG_MNGR_STAT (3:0)</b>	
<i>RO</i>	DEBUG TRIGGER MANAGER STATE MACHINE

<b>TIMER_MNGR_STAT (2:0)</b>	
<i>RO</i>	DEBUG TIMER MANAGER STATE MACHINE

<b>GRAB_MNGR_STAT (3:0)</b>	
<i>RO</i>	DEBUG GRAB MANAGER STATE MACHINE

<b>GRAB_FOT</b>	GRAB Field Overhead Time	
<i>RO</i>	This is the sensor FOT (Field Overhead Time).	
Possible Values:	0x0	Not in FOT
	0x1	In FOT

<b>GRAB_READOUT</b>		
<i>RO</i>	This is the sensor readout status. It goes to '1' on the SO_FOT and goes to '0' when the datapath decoder decodes the end of frame.	

<b>GRAB_EXPOSURE</b>		
<i>RO</i>	This is the sensor integration status	
Possible Values:	0x0	Idle
	0x1	Integrating

<b>GRAB_PENDING</b>		
<i>RO</i>	Grab pending status. When this register is set to one, a second grab command is queued in the fpga.	
Possible Values:	0x0	No grab pending
	0x1	Grab pending

<b>GRAB_ACTIVE</b>		
<i>RO</i>	Grab active status. When this register is set to one, at least one grab command has been received.	

<b>GRAB_IDLE</b>		
<i>RO</i>	GRAB IDLE status. When this register is set to '1', The grab engin is in idle state.	
Possible Values:	0x0	Grab is in process
	0x1	Grab is Idle

## READOUT\_CFG1

Address: section "ACQ" base address + 0x010

31	30	29	28	27	26	25	24
Reserved						ROT_LENGTH(9:8)	
23	22	21	20	19	18	17	16
ROT_LENGTH(7:0)							
15	14	13	12	11	10	9	8
FOT_LENGTH(15:8)							
7	6	5	4	3	2	1	0
FOT_LENGTH(7:0)							

<b>ROT_LENGTH (9:0)</b> <i>STATIC</i>	Row Overhead Time LENGTH	
	This is the length of the Row Overhead Time.	
	[NOT USED FOR THE MOMENT- FOR FUTURE USE]	
Value at Reset:	0x0	
Possible Values:	Any Value	Any 8 bits value

<b>FOT_LENGTH (15:0)</b> <i>STATIC</i>	Frame Overhead Time LENGTH	
	This is the length of the Frame Overhead Time.	
	[NOT USED FOR THE MOMENT- FOR FUTURE USE]	
Value at Reset:	0x0	
Possible Values:	Any Value	Any 16 bit value

## READOUT\_CFG2

Address: section "ACQ" base address + 0x018

31	30	29	28	27	26	25	24
Reserved			READOUT_EN	Reserved			
23	22	21	20	19	18	17	16
READOUT_LENGTH(23:16)							
15	14	13	12	11	10	9	8
READOUT_LENGTH(15:8)							
7	6	5	4	3	2	1	0
READOUT_LENGTH(7:0)							

<b>READOUT_EN</b> <i>RW</i>	READOUT ENable	
	This is the readout enable register. This register can be used to mask a readout in the sensor datapath by masking the "Arm datapath" signal generated by the controller. It can be used to mask a readout if a dummy grab is needed. This register is double buffered.	
Value at Reset:	0x0	
Possible Values:	0x0	Disable readout
	0x1	Enable readout

<b>READOUT_LENGTH (23:0)</b> <i>RW</i>		
	This is the readout length register. This register is a register software calculated that gives the readout length to the grab engine. This register will depend on the ROI, Subsampling, Binning and LVDS channels used. It is used in the PET engine calculations. In Sys_Clock domain.	
Value at Reset:	0x0	
Possible Values:	Any Value	Any 24 bits value

READOUT\_CFG3

Address: section "ACQ" base address + 0x020

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
Reserved							
7	6	5	4	3	2	1	0
BL_LINES(7:0)							

BL_LINES (7:0) STATIC	BLack LINES	
	This is thenumber of black lines programmed in the sensor needed for PET engin calculations.	
	[NOT USED FOR THE MOMENT- FOR FUTURE USE]	
Value at Reset:	0x2	
Possible Values:	Any Value	between 1 and 255



## EXP\_CTRL1

Address: section "ACQ" base address + 0x028

31	30	29	28	27	26	25	24
Reserved			EXPOSURE_ LEV_MODE	EXPOSURE_SS(27:24)			
23	22	21	20	19	18	17	16
EXPOSURE_SS(23:16)							
15	14	13	12	11	10	9	8
EXPOSURE_SS(15:8)							
7	6	5	4	3	2	1	0
EXPOSURE_SS(7:0)							

<b>EXPOSURE_LEV_MODE</b>	EXPOSURE LEVel MODE	
<i>RW</i>	This is the exposure level mode selector. When selecting the TRIGGER ACTIVATION = Level Mode, this register selects the exposure method used. When this register is set to '0' the timed mode is selected; Register EXPOSURE_SS is used for the exposure time. When this register is set to '1' the external trigger width is used for the exposure time.	
Value at Reset:	0x0	
Possible Values:	0x0	Timed Mode
	0x1	Trigger Width

<b>EXPOSURE_SS (27:0)</b>	EXPOSURE Single Slope	
<i>RW</i>	This is the total exposure time in single/dual/triple slope mode.	
	This register is double buffered.	
Value at Reset:	0x0	
Possible Values:	Any Value	Any 28 bits value

## EXP\_CTRL2

Address: section "ACQ" base address + 0x030

31	30	29	28	27	26	25	24
Reserved				EXPOSURE_DS(27:24)			
23	22	21	20	19	18	17	16
EXPOSURE_DS(23:16)							
15	14	13	12	11	10	9	8
EXPOSURE_DS(15:8)							
7	6	5	4	3	2	1	0
EXPOSURE_DS(7:0)							

<b>EXPOSURE_DS (27:0)</b> <i>RW</i>	EXPOSURE Dual Slope	
	During the total exposure time defined in register EXPOSURE_SS, the register EXPOSURE_DS define time of the 'kneepoint 1'. The value of EXPOSURE_DS is always lower than EXPOSURE_SS and EXPOSURE_TS.	
	This register is double buffered.	
Value at Reset:	0x0	
Possible Values:	Any Value	Any 28 bits value

## EXP\_CTRL3

Address: section "ACQ" base address + 0x038

31	30	29	28	27	26	25	24
Reserved				EXPOSURE_TS(27:24)			
23	22	21	20	19	18	17	16
EXPOSURE_TS(23:16)							
15	14	13	12	11	10	9	8
EXPOSURE_TS(15:8)							
7	6	5	4	3	2	1	0
EXPOSURE_TS(7:0)							

<b>EXPOSURE_TS (27:0)</b> <i>RW</i>	EXPOSURE Tripple Slope	
	During the total exposure time defined in register EXPOSURE_SS, the register EXPOSURE_TS define time of the 'kneepoint2'. The value of EXPOSURE_TS is always lower than EXPOSURE_SS and higher than EXPOSURE_DS.	
	This register is double buffered.	
Value at Reset:	0x0	
Possible Values:	Any Value	Any 28 bits value

## TRIGGER\_DELAY

Address: section "ACQ" base address + 0x040

31	30	29	28	27	26	25	24
Reserved				TRIGGER_DELAY(27:24)			
23	22	21	20	19	18	17	16
TRIGGER_DELAY(23:16)							
15	14	13	12	11	10	9	8
TRIGGER_DELAY(15:8)							
7	6	5	4	3	2	1	0
TRIGGER_DELAY(7:0)							

<b>TRIGGER_DELAY (27:0)</b> <i>RW</i>	<b>TRIGGER_DELAY</b>	
	This is the trigger delay. This trigger delay can be applied to HW(Only edge mode), SW and Continuous mode.	
	In HW level mode, the trigger cannot be delayed, since the level time represents the exposure time.	
	This register is double buffered	
Value at Reset:	0x0	
Possible Values:	Any Value	Any 28 bits value

## STROBE\_CTRL1

Address: section "ACQ" base address + 0x048

31	30	29	28	27	26	25	24
STROBE_E	Reserved			STROBE_PO L	STROBE_START(27:24)		
23	22	21	20	19	18	17	16
STROBE_START(23:16)							
15	14	13	12	11	10	9	8
STROBE_START(15:8)							
7	6	5	4	3	2	1	0
STROBE_START(7:0)							

<b>STROBE_E</b> <i>RW</i>	STROBE Enable	
	This register enables the strobe logic	
	This register is double buffered	
Value at Reset:	0x0	
Possible Values:	0x0	Strobe disabled
	0x1	Strobe enabled

<b>STROBE_POL</b> <i>RW</i>	STROBE POLarity	
	This is the strobe polarity at the pin of the FPGA.	
	This register is not double buffered.	
Value at Reset:	0x0	
Possible Values:	0x0	Active high strobe
	0x1	Active low strobe

<b>STROBE_START (27:0)</b> <i>RW</i>	STROBE START	
	This is the strobe start location. This location depends on the Strobe Mode used.	
	In Strobe Mode='0', the start of the strobe is situated during the exposure time. In Strobe Mode='1', the start of the strobe is situated during the trigger delay.	
	This register is double buffered	
Value at Reset:	0x0	
Possible Values:	Any Value	Any 28 bits value

## STROBE\_CTRL2

Address: section "ACQ" base address + 0x050

31	30	29	28	27	26	25	24
STROBE_MODE	Reserved	STROBE_B_EN	STROBE_A_EN	STROBE_END(27:24)			
23	22	21	20	19	18	17	16
STROBE_END(23:16)							
15	14	13	12	11	10	9	8
STROBE_END(15:8)							
7	6	5	4	3	2	1	0
STROBE_END(7:0)							

<b>STROBE_MODE</b> <i>RW</i>	<b>STROBE MODE</b>	
	This register selects the location of the Strobe Start.	
	When this register is set to 0, the STROBE_START register is located during the exposure timer.	
	When this register is set to 1, the STROBE_START register is located during the trigger delay timer.	
	In HW level mode the strobe mode must be set to STROBE MODE=0 since the trigger cannot be delayed.	
	This register is double buffered	
Value at Reset:	0x0	
Possible Values:	0x0	Strobe start during exposure
	0x1	Strobe start during trigger delay

<b>STROBE_B_EN</b> <i>STATIC</i>	<b>STROBE phase B ENable</b>	
	The field enables the generation of STROBE_B signal, for a NEXIS system. This register is double buffered to support back2back mode in nexis systems.	
	NOT USED IN GTR IMPLEMENTATION	
Value at Reset:	0x0	
Possible Values:	0x0	Enable Strobe B
	0x1	Disable Strobe B

<b>STROBE_A_EN</b> <i>STATIC</i>	<b>STROBE phase A ENable</b>	
	The field enables the generation of STROBE_A signal(Default strobe), for a NEXIS system. This register is double buffered to support back2back mode in nexis systems.	
	NOT USED IN GTR IMPLEMENTATION	
Value at Reset:	0x1	
Possible Values:	0x0	Enable Strobe A (default strobe)
	0x1	Disable Strobe A

STROBE_END (27:0) <i>RW</i>	STROBE END	
	This is the strobe end location. This location does not depend on the Strobe Mode used.	
	This register is double buffered	
Value at Reset:	0xffffffff	
Possible Values:	Any Value	Any 28 bits value

Address: section "ACQ" base address + 0x058

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved			SER_ROI_UPDATE	SER_BLACKCAL_UPDATE	SER_GAIN_UPDATE	SER_SUBBIN_UPDATE	SER_WRn
15	14	13	12	11	10	9	8
Reserved						SER_CMD(1:0)	
7	6	5	4	3	2	1	0
Reserved			SER_RF_SS	Reserved			SER_WF_SS

<b>SER_ROI_UPDATE</b>	
RW	**FEATURE NOT IMPLEMENTED YET** This register disable the ROI preprogramming of the sensor to avoid reprogramming latencies, if frame to frame changes is not needed in the application.
Value at Reset:	0x0

<b>SER_BLACKCAL_UPDATE</b>	
RW	**FEATURE NOT IMPLEMENTED YET** This register disable the Blackcal preprogramming of the sensor to avoid reprogramming latencies, if frame to frame changes is not needed in the application.
Value at Reset:	0x0

<b>SER_GAIN_UPDATE</b>	
RW	**FEATURE NOT IMPLEMENTED YET** This register disable the Gain preprogramming of the sensor to avoid reprogramming latencies, if frame to frame changes is not needed in the application.
Value at Reset:	0x0

<b>SER_SUBBIN_UPDATE</b>	
RW	**FEATURE NOT IMPLEMENTED YET** This register disable the SUBsmapping/BINing preprogramming of the sensor to avoid reprogramming latencies, if frame to frame changes is not needed in the application.
Value at Reset:	0x0

<b>SER_WRn</b>	SERial Write/Readn	
RW	This register configures the type of the serial access to the CMOS sensor	
Value at Reset:	0x1	
Possible Values:	0x0	Read access
	0x1	Write access



<b>SER_CMD (1:0)</b> <i>RW</i>	<b>SERial CoMmand</b>	
	This is the type of command sent to the serial fifo.	
	To access the Sensor, write SER_WF_SS=1 with SER_CMD=0x0, with the parametters: SER_WRn, SER_ADD(8:0) and SER_DAT(15:0).	
	To insert a timer between fifo commands, write SER_WF_SS=1 with SER_CMD=0x1, with the parametter: SER_DAT(15:0). The value of the timer inserted is calculated with the following formula: $\text{Timer} = \text{SER\_DAT}(15:0) * 1024 * \text{SYS\_PERIOD}$ , SYS_PERIOD is 1/62.5mhz. The granularity of the timer is 16.384us	
	To insert a Stop separator command, write SER_WF_SS=1 with SER_CMD=0x3. When the read logic encounter this command, it will stop read from the fifo until a new SER_RF_SS is received.	
Value at Reset:	0x0	
Possible Values:	0x0	CMOS sensor access COMMAND
	0x1	Insert timer COMMAND
	0x2	STOP separator COMMAND
	0x3	RESERVED

<b>SER_RF_SS</b> <i>WO/AutoClr</i>	<b>SERial Read Fifo SnapShot</b>	
	This is the read fifo snapshot. When the read fifo logic receives this snapshot, it will read all the fifo comands until a STOP separator command is read or Empty fifo is detected.	
Possible Values:	0x0	Idle
	0x1	Start Read FIFO

<b>SER_WF_SS</b> <i>WO/AutoClr</i>	<b>SERial Write Fifo SnapShot</b>	
	When the system toggle this bit, the address, data and command are wrote to the command fifo. This fifo can contain the entire dcf, so the driver will not need to pool the status bit. This is a auto reset bit register, so after the driver write one, the bit will be auto reset to 0. To start the FIFO read logic write '1' to regsiter SER_RF_SS.	
Possible Values:	0x0	Idle
	0x1	Write a command to the FIFO

Address: section "ACQ" base address + 0x060

31	30	29	28	27	26	25	24
SER_DAT(15:8)							
23	22	21	20	19	18	17	16
SER_DAT(7:0)							
15	14	13	12	11	10	9	8
Reserved							SER_ADD(8)
7	6	5	4	3	2	1	0
SER_ADD(7:0)							

<b>SER_DAT (15:0)</b>	SERial interface DATA	
<i>RW</i>	This is the write data to be send to the CMOS sensor by the serial interface, or the config data to a TIMER command or to a POWER sequence command. See register SER_CMD.	
Value at Reset:	0x0	
Possible Values:	Any Value	Any 16 bits value

<b>SER_ADD (8:0)</b>	SERial interface ADDRESS	
<i>RW</i>	This is the read/write address of the register in the CMOS sensor.	
Value at Reset:	0x0	
Possible Values:	Any Value	Any 9 bits value

Address: section "ACQ" base address + 0x068

31	30	29	28	27	26	25	24
Reserved							SER_FIFO_EMPTY
23	22	21	20	19	18	17	16
Reserved							SER_BUSY
15	14	13	12	11	10	9	8
SER_DAT_R(15:8)							
7	6	5	4	3	2	1	0
SER_DAT_R(7:0)							

<b>SER_FIFO_EMPTY</b>	SERial FIFO EMPTY	
<i>RO</i>	This is the EMPTY flag of the xilinx fifo, when '1' there are no pending operations in the fifo.	

<b>SER_BUSY</b>	SERial BUSY	
<i>RO</i>	This is the BUSY status of the FIFO read logic. The flag will be set to '1' when the SER_RF_SS is set to '1'. It will be reseted to '0' when the read logic will decode a STOP separator command or when the FIFO will be empty.	
Possible Values:	0x0	FIFO read logic is idle
	0x1	FIFO read logic is running

<b>SER_DAT_R (15:0)</b>	SERial interface DATa Read	
<i>RO</i>	This is the data read from CMOS sensor.	
Possible Values:	Any Value	Any 16 bits value

## LVDS\_CTRL

Address: section "ACQ" base address + 0x070

31	30	29	28	27	26	25	24
LVDS_BIT_RATE(15:8)							
23	22	21	20	19	18	17	16
LVDS_BIT_RATE(7:0)							
15	14	13	12	11	10	9	8
Reserved			LVDS_MODE	LVDS_SER_FACTOR(3:0)			
7	6	5	4	3	2	1	0
LVDS_CH(3:0)				Reserved		LVDS_START_CALIB	LVDS_SYS_RESET

<b>LVDS_BIT_RATE (15:0)</b> <i>RW</i>	LVDS BIT RATE selector
	This is the LVDS interface bit rate selector.  Program 0x720 when the LVDS channel is set to 10bits. Program 0x576 when the LVDS channel is set to 8bits .
Value at Reset:	0x720

<b>LVDS_MODE</b> <i>RO</i>	This is the LVDS Mode implemented in the fpga.	
	LVDS10 is 720Mbps per LVDS channel LVDS8 is 576Mbps per LVDS channel	
Possible Values:	0x0	LVDS10
	0x1	LVDS8

<b>LVDS_SER_FACTOR (3:0)</b> <i>RW</i>		
	Pour l'instant il est statique dans le generique, car le BUFR ne nous permet pas de reconfigurer live le facteur de division de 5 a 4 !!!!!	
Value at Reset:	0xa	

<b>LVDS_CH (3:0)</b> <i>RW</i>	LVDS CHannels	
	This regsiters defines the number of LVDS channels used.  Set this register to 1, when only 1 LVDS channel is used. Set this register to 2, when 2 LVDS channels are used. Set this register to 4, when 4 LVDS channels are used. Set this register to 8, when 8 LVDS channels are used.	
Value at Reset:	0x4	
Possible Values:	0x1	1 LVDS channel
	0x2	2 LVDS channels
	0x4	4 LVDS Channels
	0x8	8 LVDS Channels
	Others	RESERVED

<b>LVDS_START_CALIB</b> <i>WO/AutoClr</i>	LVDS START CALIBration	
	This register starts the LVDS CALIBRATION. A phase detect calibration is first performed. After the phase detect calibration, a bitslip calibration is performed.	
	A LVDS calibration is always performed at the Start Of FOT	
Possible Values:	0x0	Idle
	0x1	Perform a LVDS calibration

<b>LVDS_SYS_RESET</b> <i>RW</i>	LVDS SYStem LVDS RESET	
	This is the LVDS reset register. After deassert this register, a LVDS calibration is needed.	
Value at Reset:	0x1	
Possible Values:	0x0	LVDS not in reset state
	0x1	LVDS module reset

## LVDS\_CTRL2

Address: section "ACQ" base address + 0x078

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
REMAP_MODE_SUPP(7:0)							
15	14	13	12	11	10	9	8
Reserved							
7	6	5	4	3	2	1	0
Reserved			LVDS_DECODE_EN	Reserved	LVDS_DECODE_REMAP_MODE(2:0)		

<b>REMAP_MODE_SUPP (7:0)</b>	REMAPer MODE SUPPORTed	
<i>RO</i>	Each bit in this field is a remap mode supported in the fpga. If a value 0x41 is read, then only P1300x4 and P1300x2 are supported by the fpga.	
Possible Values:	0x1	P1300 x4 supported
	0x2	P1300 x1 supported
	0x4	P5000 x4 supported
	0x8	P5000 x1 supported
	0x10	P5000 x8 supported
	0x20	P5000 x2 supported
	0x40	P1300 x2 supported
	0x80	Not implemented yet

<b>LVDS_DECODE_EN</b>		
<i>RW</i>		
Value at Reset:	0x0	
Possible Values:	0x0	Decoder Disable
	0x1	Decoder Enable

<b>LVDS_DECODE_REMAP_MODE (2:0)</b>		
<i>RW</i>	This is the configuration for the decoder and remapper logic in the datapath. This register also configures the Sensor SPI frequency.	
Value at Reset:	0x0	
Possible Values:	0x0	Python 1300, 4x LVDS
	0x1	Python 1300, 1x LVDS
	0x2	Python 5000, 4x LVDS
	0x3	Python 5000, 1x LVDS
	0x4	Python 5000, 8x LVDS
	0x5	Python 5000, 2x LVDS
	0x6	Python 1300, 2x LVDS

## LVDS\_TRAINING

Address: section "ACQ" base address + 0x080

31	30	29	28	27	26	25	24
Reserved						DATA_TRAINING(9:8)	
23	22	21	20	19	18	17	16
DATA_TRAINING(7:0)							
15	14	13	12	11	10	9	8
Reserved						CTRL_TRAINING(9:8)	
7	6	5	4	3	2	1	0
CTRL_TRAINING(7:0)							

<b>DATA_TRAINING (9:0)</b>		
<i>RW</i>	This is the training pattern for LVDS DATA CHANNELS. This register must match the training pattern register of the Python sensor.	
Value at Reset:	0x3a6	
Possible Values:	Any Value	Any 10 bits value

<b>CTRL_TRAINING (9:0)</b>		
<i>RW</i>	This is the training pattern for the LVDS CONTROL CHANNEL. This register must match the training pattern register of the Python sensor.	
Value at Reset:	0x3a6	
Possible Values:	Any Value	Any 10 bits value

## LVDS\_STAT

Address: section "ACQ" base address + 0x088

31	30	29	28	27	26	25	24
Reserved		IDELAY_RDY	LVDS_RDY	Reserved		LVDS_CALIB_OK	LVDS_CALIB_ACT
23	22	21	20	19	18	17	16
Reserved		BS_DONE_STAT	BS_CH_LOCK_STAT(8:4)				
15	14	13	12	11	10	9	8
BS_CH_LOCK_STAT(3:0)				Reserved		PD_DONE_STAT	PD_CH_LOCK_STAT(8)
7	6	5	4	3	2	1	0
PD_CH_LOCK_STAT(7:0)							

<b>IDELAY_RDY</b> <i>RO</i>	Input DELAY ReaDY						
	The Input DELAY ReaDY (RDY) signal indicates when the IDELAYE2 and ODELAYE2 modules in the specific region are calibrated, after receiving the REFCLOCK(200Mhz) and SYS_RESET deasserted.						
Possible Values:	0x0		IDELAYE2 module not calibrated				
	0x1		IDELAYE2 module calibrated				

<b>LVDS_RDY</b> <i>RO</i>	LVDS ReaDY						
	This register goes to '1' when the LVDS_SYS_RESET register is deasserted and that the LVDS logic is ready to start the calibration sequence.						
Possible Values:	0x0		LVDS module not ready to calibration				
	0x1		LVDS module ready to calibration				

<b>LVDS_CALIB_OK</b> <i>RO</i>	LVDS CALIBration OK						
	This register register is the LVDS calibration result.						
Possible Values:	0x0		Calibration sequence fail				
	0x1		Calibration sequence success				

<b>LVDS_CALIB_ACT</b> <i>RO</i>	LVDS CALIBration ACTivate						
	This register informs that the calibration sequence is calibrating the LVDS interface. Read register CALIB_OK when CALIB_ACT goes to '0' to see the result of the calibration sequence.						
Possible Values:	0x0		Calibration is idle				
	0x1		Calibration is active				

<b>BS_DONE_STAT</b> <i>RO</i>	BitSlip DONE STATus						
	This is the bitslip done status. It informs that the BitSlips sequence is finish. See BS_CH_LOCK_STAT for individual channel lock status.						
Possible Values:	0x0		BitSlip sequence in progress				
	0x1		BitSlip sequence finish				



<b>BS_CH_LOCK_STAT (8:0)</b> <i>RO</i>	BitSlip CHannel LOCK STATus
	This is the bitslip channel lock status. It informs wich channel is locked after the BitSlip calibration sequence.

<b>PD_DONE_STAT</b> <i>RO</i>	
	This is thephase detect done status. It informs that the PhaseDetect sequence is finish. See PD_CH_LOCK_STAT for individual channel lock status.

<b>PD_CH_LOCK_STAT (8:0)</b> <i>RO</i>	Phase Detect LOCK STATus
	This is the Phase Detect channel lock status. It informs wich channel is locked after the Phase Detect calibration sequence.

LVDS\_STAT2

Address: section "ACQ" base address + 0x08C

31	30	29	28	27	26	25	24
WORD_ALIGN(31:24)							
23	22	21	20	19	18	17	16
WORD_ALIGN(23:16)							
15	14	13	12	11	10	9	8
WORD_ALIGN(15:8)							
7	6	5	4	3	2	1	0
WORD_ALIGN(7:0)							

<b>WORD_ALIGN (31:0)</b>	Word ALIGNement
<i>RO</i>	This register indicates the Word Alignment Status. (1 byte per channel). When the data channel is aligned with the sync a value of '2' is read. When the Data changes one clk before the sync a value of '1' is read. When the Data changes one clk after the sync a value of '3' is read.

Address: section "ACQ" base address + 0x090

31	30	29	28	27	26	25	24
Reserved							SENSOR_REFRESH_TEMP
23	22	21	20	19	18	17	16
Reserved							SENSOR_POWERDOWN
15	14	13	12	11	10	9	8
Reserved		SENSOR_REMAP_CFG(1:0)		Reserved			SENSOR_COLOR
7	6	5	4	3	2	1	0
Reserved			SENSOR_REFRESH_UPDATE	Reserved		SENSOR_REFRESH_SETN	SENSOR_POWERUP

<b>SENSOR_REFRESH_TEMP</b> <i>WO/AutoClr</i>	SENSOR REFRESH TEMPerature	
	This register starts a sensor temperature read on the serial interface of the Python sensor. The temperature value readed will be available on field SENSOR_TEMP when field SENSOR_TEMP_VALID is set to '1'.	
Possible Values:	0x0	Idle
	0x1	Starts a Temperature read on Python SPI interface

<b>SENSOR_POWERDOWN</b> <i>WO/AutoClr</i>		
	After a PowerUp sequence(SESOR_POWERUP_DONE=1), successfull or not, this register can reset the power state machine to idle state(All power disable, oscillator disable and reset).	
	This power down don't do power sequencing.	

<b>SENSOR_REMAP_CFG (1:0)</b> <i>RW</i>	SENSOR REMAPing ConFiGuration	
	This is the configuration for the remapper logic bloc. Bit(0) enables the image valid data Bit(1) enables the black calibration data valid data	
Value at Reset:	0x1	
Possible Values:	0x0	
	0x1	Black data disabled, Valid data enabled
	0x2	
	0x3	

<b>SENSOR_COLOR</b> <i>RW</i>	SENSOR COLOR	
	This register informs the datapath logic that a color sensor is used. This information is needed for the remapper logic.	
Value at Reset:	0x0	
Possible Values:	0x0	Monochrome sensor
	0x1	Color sensor

<b>SENSOR_REG_UPDATE</b>	SENSOR REGISTER UPDATE	
<i>RW</i>	By setting this bit to 1, the SENSOR CONTROLLER WILL UPDATE the programmed CMOS sensor registers at the beginning of each grab.	
Value at Reset:	0x1	
Possible Values:	0x0	Do not update registers
	0x1	Update registers

<b>SENSOR_RESETN</b>	SENSOR RESET Not	
<i>RW</i>	After a successful PowerUP sequence, writing this field to '0' reset the Python CMOS sensor.	
Value at Reset:	0x1	
Possible Values:	0x0	Reset the sensor after a successful powerUP
	0x1	Nothing

<b>SENSOR_POWERUP</b>		
<i>WO/AutoClr</i>	This register powerup the supply of the sensor, enable the sensor clock and do a reset to the sensor.	
Possible Values:	0x0	idle
	0x1	Start the power sequence

Address: section "ACQ" base address + 0x098

31	30	29	28	27	26	25	24
SENSOR_TEMP(7:0)							
23	22	21	20	19	18	17	16
SENSOR_TEMP_VALID	Reserved						SENSOR_POWERDOWN
15	14	13	12	11	10	9	8
Reserved		SENSOR_RESETN	SENSOR_OSC_EN	Reserved	SENSOR_VCCPIX_PG	SENSOR_VCC_C33_PG	SENSOR_VCC_C18_PG
7	6	5	4	3	2	1	0
Reserved	SENSOR_VCC_CPIX_EN	SENSOR_VCC_C33_EN	SENSOR_VCC_C18_EN	Reserved		SENSOR_POWERUP_STATUS	SENSOR_POWERUP_DONE

<b>SENSOR_TEMP (7:0)</b>		
<i>RO</i>	This register gives the Temperature of the Python sensor after a SENSOR_REFRESH_TEMP snapshot. The field SENSOR_TEMP_VALID indicates when the SENSOR_TEMP value is valid.	
Possible Values:	Any Value	

<b>SENSOR_TEMP_VALID</b>	SENSOR TEMPerature VALID	
<i>RO</i>	This field indicates that the field SENSOR_TEMP have valid temperature after a SENSOR_REFRESH_TEMP snapshot.	
Possible Values:	0x0	SENSOR_TEMPERATURE register is not valid
	0x1	SENSOR_TEMPERATURE register is valid

<b>SENSOR_POWERDOWN</b>		
<i>RO</i>	This field indicates that the sensor is in powerdown state.	
Possible Values:	0x0	Not in powerdown state
	0x1	Powerdown

<b>SENSOR_RESETN</b>	SENSOR RESET N	
<i>RO</i>	This is the sensor RESETN status.	
Possible Values:	0x0	In reset state
	0x1	Not in reset

<b>SENSOR_OSC_EN</b>	SENSOR OSCILLATOR ENable	
<i>RO</i>	This is the sensor oscillator enable status.	
Possible Values:	0x0	Disable
	0x1	Enable

<b>SENSOR_VCCPIX_PG</b>	SENSOR supply PIX VCC Power Good	
<i>RO</i>	This is the PIX VCC Power Good status.	
Possible Values:	0x0	Disable
	0x1	Enable

<b>SENSOR_VCC33_PG</b>	SENSOR supply 3.3 VCC Power Good	
<i>RO</i>	This is the 3.3V VCC Power Good status.	
Possible Values:	0x0	Disable
	0x1	Enable

<b>SENSOR_VCC18_PG</b>	SENSOR supply 1.8 VCC Power Good	
<i>RO</i>	This is the 1.8V VCC Power Good status.	
Possible Values:	0x0	Disable
	0x1	Enable

<b>SENSOR_VCCPIX_EN</b>	SENSOR supply PIX VCC ENable	
<i>RO</i>	This is the PIX VCC enable status.	
Possible Values:	0x0	Disable
	0x1	Enable

<b>SENSOR_VCC33_EN</b>	SENSOR supply 3.3 VCC ENable	
<i>RO</i>	This is the 3.3V VCC enable status.	
Possible Values:	0x0	Disable
	0x1	Enable

<b>SENSOR_VCC18_EN</b>	SENSOR supply 1.8 VCC ENable	
<i>RO</i>	This is the 1.8V VCC enable status.	
Possible Values:	0x0	Disable
	0x1	Enable

<b>SENSOR_POWERUP_STAT</b>		
<i>RO</i>	When a powerup sequence is finish, this register indicates the result of the POWERUP sequence.	
Possible Values:	0x0	PowerUp sequence fail
	0x1	PowerUp sequence success

<b>SENSOR_POWERUP_DONE</b>		
<i>RO</i>	This register indicates that the POWERUP sequence is finish. Read register SENSOR_POWERUP_STAT to see the result.	
Possible Values:	0x0	PowerUp sequence not started
	0x1	PowerUp sequence finish

## SENSOR\_GEN\_CFG

Address: section "ACQ" base address + 0x0A0

Description:

SENSOR ADDRESS 192 DEC

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
reserved_1(6:0)							BINNING
7	6	5	4	3	2	1	0
SUBSAMPLING	NZROT_XSM_DELAY_ENABLE	SLAVE_MODE	TRIGGERED_MODE	XLAG_ENABLE	ZERO_ROT_ENABLE	ROLLING_SHUTTER	ENABLE

<b>reserved_1 (6:0)</b>	
<i>RW</i>	(13:11) Monitor pin mode = 0x1
Value at Reset:	0x4

<b>BINNING</b>	BINNING enable	
<i>RW</i>	Binning mode selection	
	Subsampling and Binning cannot operate at the same time. The sensor will choose Binning if the two are selected. This situation must be avoid in driver.	
	If using a ROI with BINNING OR SUBSAMPLING, follow this constraints:	
	1) XStart with Subsampling OR Binning: if a ROI is used with Subsampling or Binning, the start kernel MUST be EVEN. 2) XEnd with Subsampling OR Binning: if a ROI is used with Subsampling or Binning, the end kernel and the start line MUST be ODD. 3) YStart with Subsampling OR Binning: if a ROI is used with Subsampling or Binning, the start line MUST be EVEN. 4) YEnd with Subsampling OR Binning: If a ROI is used with Subsampling, the end line MUST be ODD.	
Value at Reset:	0x0	
Possible Values:	0x0	No binning
	0x1	Binning

<b>SUBSAMPLING</b> <i>RW</i>	SUBSAMPLING enable	
	Subsampling mode selection.  Subsampling and Binning cannot operate at the same time. The sensor will choose Binning if the two are selected. This situation must be avoid in driver.  If using a ROI with BINNING OR SUBSAMPLING, follow this constraints:  1) XStart with Subsampling OR Binning: if a ROI is used with Subsampling or Binning, the start kernel MUST be EVEN. 2) XEnd with Subsampling OR Binning: if a ROI is used with Subsampling or Binning, the end kernel and the start line MUST be ODD. 3) YStart with Subsampling OR Binning: if a ROI is used with Subsampling or Binning, the start line MUST be EVEN. 4) YEnd with Subsampling OR Binning: If a ROI is used with Subsampling, the end line MUST be ODD.	
Value at Reset:	0x0	
Possible Values:	0x0	No subsampling
	0x1	Subsampling

<b>NZROT_XSM_DELAY_ENABLE</b> <i>RW</i>	NZROT XSM DELAY ENABLE	
	Insert delay between end of ROT and start of readout in NonZero ROT readout mode if '1'. ROT delay is defined by register xsm_delay	
Value at Reset:	0x0	
Possible Values:	0x0	Don't insert delay
	0x1	Insert delay defined by register nzrot_xsm_delay

<b>SLAVE_MODE</b> <i>RW</i>	SLAVE MODE	
	Master/Slave Selection	
Value at Reset:	0x1	
Possible Values:	0x0	Master
	0x1	Slave

<b>TRIGGERED_MODE</b> <i>RW</i>	TRIGGERED MODE	
	Triggered mode Selection	
Value at Reset:	0x1	
Possible Values:	0x0	Normal mode
	0x1	Triggered mode

<b>XLAG_ENABLE</b> <i>RW</i>		
	Xlag	
Value at Reset:	0x0	
Possible Values:	0x0	Xlag OFF
	0x1	Xlag ON

<b>ZERO_ROT_ENABLE</b> <i>RW</i>	ZERO ROT ENABLE	
	ZERO ROT mode ENABLE	
Value at Reset:	0x0	
Possible Values:	0x0	Idle
	0x1	Enable



<b>ROLLING_SHUTTER</b>	ROLLING SHUTTER	
<i>RW</i>	Rolling shutter mode	
Value at Reset:	0x0	
Possible Values:	0x0	Rolling shutter disable
	0x1	Rolling shutter enable(non supported)

<b>ENABLE</b>	Sequencer ENABLE	
<i>RW</i>	Sequencer ENABLE	
Value at Reset:	0x1	
Possible Values:	0x0	Idle
	0x1	Enable

## SENSOR INT CTL

Address: section "ACQ" base address + 0x0A8

Description:

SENSOR ADDRESS 194 DEC

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
reserved_2(1:0)		BINNING_MODE(1:0)		SUBSAMPLING_MODE(1:0)		reserved1	Reserved
7	6	5	4	3	2	1	0
reserved0(7:0)							

<b>reserved_2 (1:0)</b>	
<i>RW</i>	
Value at Reset:	0x0

<b>BINNING_MODE (1:0)</b>	BINNING MODE	
<i>RW</i>	Binning mode selector	
Value at Reset:	0x0	
Possible Values:	0x0	Binning in x and y (VITA compatible)
	0x1	Binning in x, not y
	0x2	Binning in y, not x
	0x3	Binning in x and y

<b>SUBSAMPLING_MODE (1:0)</b>	SUBSAMPLING MODE	
<i>RW</i>	Subsampling mode selector	
Value at Reset:	0x0	
Possible Values:	0x0	Subsampling in x and y (VITA compatible)
	0x1	Subsampling in x, not y
	0x2	Subsampling in y, not in x
	0x3	Subsampling in x and y

<b>reserved1</b>	
<i>RW</i>	
Value at Reset:	0x0

<b>reserved0 (7:0)</b> <i>RW</i>	 (2) fr_mode = 0x0 : reset length (4) int_priority =0x0 : frame readout has priority over integration (5) halt_mode =0x0 : the sensor stops immediately when disabled, without finishing the current frame. (6) fss_enable =0 : No generation of FSS (7) fse_enable =0 : No generation of FSE
Value at Reset:	0x0

## SENSOR\_GAIN\_ANA

Address: section "ACQ" base address + 0x0B0

Description:

SENSOR ADDRESS 204 DEC

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
reserved(2:0)				AFE_GAIN0(7:3)			
7	6	5	4	3	2	1	0
AFE_GAIN0(2:0)				MUX_GAINSW0(4:0)			

<b>reserved (2:0)</b>	
<i>RW</i>	
Value at Reset:	0x0

<b>AFE_GAIN0 (7:0)</b>	AFE GAIN
<i>RW</i>	GAIN STAGE 2 : AFE Programmable Gain Setting
Value at Reset:	0xf

<b>MUX_GAINSW0 (4:0)</b>	Column MUX GAIN
<i>RW</i>	GAIN STAGE 1 : Column Gain Setting
Value at Reset:	0x3

## SENSOR\_BLACK\_CAL

Address: section "ACQ" base address + 0x0B8

Description:

SENSOR ADDRESS 128 DEC

P1300: 0x470f

P5000: 0x4714

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
CRC_SEED	reserved(3:0)				BLACK_SAMPLES(2:0)		
7	6	5	4	3	2	1	0
BLACK_OFFSET(7:0)							

<b>CRC_SEED</b>	
<i>RW</i>	
Value at Reset:	0x0

<b>reserved (3:0)</b>	
<i>RW</i>	
Value at Reset:	0x8

<b>BLACK_SAMPLES (2:0)</b>	
<i>STATIC</i>	
Value at Reset:	0x7

<b>BLACK_OFFSET (7:0)</b>	BLACK OFFSET
<i>RW</i>	Desired black level at output
Value at Reset:	0xf

## SENSOR ROI\_CONF0

Address: section "ACQ" base address + 0x0C0

Description:

SENSOR ADDRESS 256 or 259 DEC

31	30	29	28	27	26	25	24
Reserved							X_END_MSB
23	22	21	20	19	18	17	16
Reserved							X_START_MSB
15	14	13	12	11	10	9	8
X_END(7:0)							
7	6	5	4	3	2	1	0
X_START(7:0)							

<b>X_END_MSB</b>	X END
<i>RW</i>	X End Configuration, in kernels for P480
Value at Reset:	0x1

<b>X_START_MSB</b>	X START MSB
<i>RW</i>	X Start Configuration, in kernels for P480
Value at Reset:	0x0

<b>X_END (7:0)</b>	X END
<i>RW</i>	X End Configuration, in kernels
Value at Reset:	0x9f

<b>X_START (7:0)</b>	X START
<i>RW</i>	X Start Configuration, in kernels
Value at Reset:	0x0

## SENSOR ROI2\_CONF0

Address: section "ACQ" base address + 0x0C4

Description:

SENSOR ADDRESS 256 or 259 DEC

31	30	29	28	27	26	25	24
Reserved							X_END_MSB
23	22	21	20	19	18	17	16
Reserved							X_START_MSB
15	14	13	12	11	10	9	8
X_END(7:0)							
7	6	5	4	3	2	1	0
X_START(7:0)							

<b>X_END_MSB</b>	X END
<i>RW</i>	X End Configuration, in kernels for P480
Value at Reset:	0x1

<b>X_START_MSB</b>	X START MSB
<i>RW</i>	X Start Configuration, in kernels for P480
Value at Reset:	0x0

<b>X_END (7:0)</b>	X END
<i>RW</i>	X End Configuration, in kernels
Value at Reset:	0x9f

<b>X_START (7:0)</b>	X START
<i>RW</i>	X Start Configuration, in kernels
Value at Reset:	0x0

## SENSOR ROI\_CONF1

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Address: section "ACQ" base address + 0x0C8

Description:

SENSOR ADDRESS 257 or 260 DEC

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
reserved(2:0)			Y_START(12:8)				
7	6	5	4	3	2	1	0
Y_START(7:0)							

<b>reserved (2:0)</b>	
<i>STATIC</i>	
Value at Reset:	0x0

<b>Y_START (12:0)</b>	Y START
<i>RW</i>	Y Start Configuration
Value at Reset:	0x0



## SENSOR ROI2\_CONF1

Address: section "ACQ" base address + 0x0CC

Description:

SENSOR ADDRESS 257 or 260 DEC

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
reserved(2:0)				Y_START(12:8)			
7	6	5	4	3	2	1	0
Y_START(7:0)							

<b>reserved (2:0)</b>	
<i>STATIC</i>	
Value at Reset:	0x0

<b>Y_START (12:0)</b>	Y START
<i>RW</i>	Y Start Configuration
Value at Reset:	0x0

## SENSOR ROI\_CONF2

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Address: section "ACQ" base address + 0x0D0

Description:

SENSOR ADDRESS 258 or 261 DEC

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
reserved(2:0)				Y_END(12:8)			
7	6	5	4	3	2	1	0
Y_END(7:0)							

<b>reserved (2:0)</b>	
<i>STATIC</i>	
Value at Reset:	0x0

<b>Y_END (12:0)</b>	Y END
<i>RW</i>	Y End Configuration
Value at Reset:	0x3ff

## SENSOR ROI2\_CONF2

Address: section "ACQ" base address + 0x0D4

Description:

SENSOR ADDRESS 258 or 261 DEC

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
reserved(2:0)				Y_END(12:8)			
7	6	5	4	3	2	1	0
Y_END(7:0)							

<b>reserved (2:0)</b>	
<i>STATIC</i>	
Value at Reset:	0x0

<b>Y_END (12:0)</b>	Y END
<i>RW</i>	Y End Configuration
Value at Reset:	0x3ff

CRC

Address: section "ACQ" base address + 0x0D8

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved					CRC_InitValue	CRC_Reset	CRC_EN
15	14	13	12	11	10	9	8
Reserved							
7	6	5	4	3	2	1	0
CRC_STATUS(7:0)							

CRC_InitValue	
RW	
Value at Reset:	0x0

CRC_Reset	
WO/AutoClr	Reset CRC state if error is detected

CRC_EN	CRC ENable
RW	
Value at Reset:	0x1

CRC_STATUS (7:0)		
RO		
Possible Values:	0x0	NO ERROR
	0x1	CRC ERROR

## DEBUG PINS

Address: section "ACQ" base address + 0x0E0

31	30	29	28	27	26	25	24
Reserved				Debug3_sel(4:0)			
23	22	21	20	19	18	17	16
Reserved				Debug2_sel(4:0)			
15	14	13	12	11	10	9	8
Reserved				Debug1_sel(4:0)			
7	6	5	4	3	2	1	0
Reserved				Debug0_sel(4:0)			

<b>Debug3_sel (4:0)</b> <i>RW</i>	
	debug_vector16(0) <= python_monitor0; debug_vector16(1) <= python_monitor1; debug_vector16(2) <= grab_mngr_trig_rdy; debug_vector16(3) <= curr_trig0; debug_vector16(4) <= strobe; debug_vector16(5) <= python_exposure; debug_vector16(6) <= FOT; debug_vector16(7) <= readout; debug_vector16(8) <= readout_stateD; debug_vector16(9) <= ext_trig; debug_vector16(10) <= REGFILE.ACQ.GRAB_CTRL.GRAB_CMD; debug_vector16(11) <= REGFILE.ACQ.GRAB_CTRL.GRAB_SS; debug_vector16(12) <= grab_mngr_trig; debug_vector16(13) <= grab_mngr_trig_rdy; debug_vector16(14) <= grab_pending; debug_vector16(15) <= grab_active;
Value at Reset:	0x1f

<b>Debug2_sel (4:0)</b> <i>RW</i>	
	debug_vector16(0) <= python_monitor0; debug_vector16(1) <= python_monitor1; debug_vector16(2) <= grab_mngr_trig_rdy; debug_vector16(3) <= curr_trig0; debug_vector16(4) <= strobe; debug_vector16(5) <= python_exposure; debug_vector16(6) <= FOT; debug_vector16(7) <= readout; debug_vector16(8) <= readout_stateD; debug_vector16(9) <= ext_trig; debug_vector16(10) <= REGFILE.ACQ.GRAB_CTRL.GRAB_CMD; debug_vector16(11) <= REGFILE.ACQ.GRAB_CTRL.GRAB_SS; debug_vector16(12) <= grab_mngr_trig; debug_vector16(13) <= grab_mngr_trig_rdy; debug_vector16(14) <= grab_pending; debug_vector16(15) <= grab_active;
Value at Reset:	0x1f

<b>Debug1_sel (4:0)</b> RW	<div></div> <div> debug_vector16(0) &lt;= python_monitor0;  debug_vector16(1) &lt;= python_monitor1;  debug_vector16(2) &lt;= grab_mngr_trig_rdy;  debug_vector16(3) &lt;= curr_trig0;  debug_vector16(4) &lt;= strobe;  debug_vector16(5) &lt;= python_exposure;  debug_vector16(6) &lt;= FOT;  debug_vector16(7) &lt;= readout;  debug_vector16(8) &lt;= readout_stateD;  debug_vector16(9) &lt;= ext_trig;  debug_vector16(10) &lt;= REGFILE.ACQ.GRAB_CTRL.GRAB_CMD;  debug_vector16(11) &lt;= REGFILE.ACQ.GRAB_CTRL.GRAB_SS;  debug_vector16(12) &lt;= grab_mngr_trig;  debug_vector16(13) &lt;= grab_mngr_trig_rdy;  debug_vector16(14) &lt;= grab_pending;  debug_vector16(15) &lt;= grab_active; </div>
Value at Reset:	0x1f

<b>Debug0_sel (4:0)</b> RW	<div></div> <div> debug_vector16(0) &lt;= python_monitor0;  debug_vector16(1) &lt;= python_monitor1;  debug_vector16(2) &lt;= grab_mngr_trig_rdy;  debug_vector16(3) &lt;= curr_trig0;  debug_vector16(4) &lt;= strobe;  debug_vector16(5) &lt;= python_exposure;  debug_vector16(6) &lt;= FOT;  debug_vector16(7) &lt;= readout;  debug_vector16(8) &lt;= readout_stateD;  debug_vector16(9) &lt;= ext_trig;  debug_vector16(10) &lt;= REGFILE.ACQ.GRAB_CTRL.GRAB_CMD;  debug_vector16(11) &lt;= REGFILE.ACQ.GRAB_CTRL.GRAB_SS;  debug_vector16(12) &lt;= grab_mngr_trig;  debug_vector16(13) &lt;= grab_mngr_trig_rdy;  debug_vector16(14) &lt;= grab_pending;  debug_vector16(15) &lt;= grab_active; </div>
Value at Reset:	0x1f

## TRIGGER\_MISSED

Address: section "ACQ" base address + 0x0E8

31	30	29	28	27	26	25	24
Reserved			TRIGGER_MISSED_RST	Reserved			
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
TRIGGER_MISSED_CNTR(15:8)							
7	6	5	4	3	2	1	0
TRIGGER_MISSED_CNTR(7:0)							

<b>TRIGGER_MISSED_RST</b>	TRIGGER MISSED ReSeT	
<i>WO/AutoClr</i>	This is the trigger missed reset.	
Possible Values:	0x1	Reset the Trigger counter reset

<b>TRIGGER_MISSED_CNTR (15:0)</b>	TRIGGER MISSED CouNTeR	
<i>RO</i>	This is the number of trigger missed detected.	
Possible Values:	Any Value	

SENSOR\_FPS

Address: section "ACQ" base address + 0x0F0

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
SENSOR_FPS(15:8)							
7	6	5	4	3	2	1	0
SENSOR_FPS(7:0)							

SENSOR_FPS (15:0) RO	SENSOR Frame Per Second
	This is the number of frames received in 1 second interval. This register can count up to 64k frame/s.



## DEBUG

Address: section "ACQ" base address + 0x120

31	30	29	28	27	26	25	24
Reserved			DEBUG_RST_CNTR	Reserved		TEST_MODE_PIX_START(9:8)	
23	22	21	20	19	18	17	16
TEST_MODE_PIX_START(7:0)							
15	14	13	12	11	10	9	8
Reserved						TEST_MOVE	TEST_MODE
7	6	5	4	3	2	1	0
Reserved					LED_TEST_COLOR(1:0)		LED_TEST

<b>DEBUG_RST_CNTR</b>		
<i>RW</i>	This register clears the debug cntrs	
Value at Reset:	0x1	
Possible Values:	0x0	
	0x1	Reset counters

<b>TEST_MODE_PIX_START (9:0)</b>		
<i>RW</i>	This register defines the value of the first pixel in the frame when the TEST_MODE is activated. In 8 bits mode only 8-MSB bits of the register is used.	
Value at Reset:	0x0	

<b>TEST_MOVE</b>		
<i>RW</i>	This field when in TEST_MODE=1, makes the ramp move. The first pixel of the frame is incremented by one each frame.	
Value at Reset:	0x0	
Possible Values:	0x0	Static test ramp
	0x1	The test ramp moves

<b>TEST_MODE</b>		
<i>RW</i>	This field set the FPGA in test mode. The fpga will send a programmable ramp to the host using the syncs received from the sensor. The generated ramp can move when set with the field TEST_MOVE.  In color mode (LVDSx1), the ramp pixel is repeated 3 times to generate a B&W ramp in RGB24 mode.	
Value at Reset:	0x0	
Possible Values:	0x0	Normal acquisition data from sensor
	0x1	Test mode, a ramp is generated.

<b>LED_TEST_COLOR (1:0)</b> <i>RW</i>		
Value at Reset:	0x0	
Possible Values:	0x0	The LED is OFF
	0x1	The LED is GREEN
	0x2	The LED is RED
	0x3	The LED is ORANGE

<b>LED_TEST</b> <i>RW</i>		
	This register will put the LED status in test mode. The test mode is controlled by <b>LED_TEST_COLOR</b>	
Value at Reset:	0x0	
Possible Values:	0x0	The LED is in user mode.
	0x1	The LED is in test mode.

**DEBUG\_CNTR1**

---

Address: section "ACQ" base address + 0x128

31	30	29	28	27	26	25	24
EOF_CNTR(31:24)							
23	22	21	20	19	18	17	16
EOF_CNTR(23:16)							
15	14	13	12	11	10	9	8
EOF_CNTR(15:8)							
7	6	5	4	3	2	1	0
EOF_CNTR(7:0)							

EOF_CNTR (31:0)	
RO	This is the EOF CNTR

**DEBUG\_CNTR2**

---

Address: section "ACQ" base address + 0x130

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
Reserved				EOL_CNTR(11:8)			
7	6	5	4	3	2	1	0
EOL_CNTR(7:0)							

EOL_CNTR (11:0) RO	
	This is the EOL CNTR

**DEBUG\_CNTR3**

Address: section "ACQ" base address + 0x134

31	30	29	28	27	26	25	24
Reserved				SENSOR_FRAME_DURATION(27:24)			
23	22	21	20	19	18	17	16
SENSOR_FRAME_DURATION(23:16)							
15	14	13	12	11	10	9	8
SENSOR_FRAME_DURATION(15:8)							
7	6	5	4	3	2	1	0
SENSOR_FRAME_DURATION(7:0)							

SENSOR_FRAME_DURATION (27:0) RO							
	This is the time between the last 2 EOF received (in sys clock domain). This register can count up to 4.29 seconds. It can be used to predict sensor framerate or to verify sync between 3D profiler heads. This feature is enabled by setting register regfile.ACQ.DEBUG.DEBUG_RST_CNTR to 0.						
Possible Values:	Any Value			Any 28 bit value			

## EXP\_FOT

Address: section "ACQ" base address + 0x13C

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							EXP_FOT
15	14	13	12	11	10	9	8
Reserved				EXP_FOT_TIME(11:8)			
7	6	5	4	3	2	1	0
EXP_FOT_TIME(7:0)							

<b>EXP_FOT</b>	EXPosure during FOT	
<i>RW</i>	When set to '1' this register, the output exposure and strobe signals will take into account the exposure in the FOT of the frame. This timing must be programmed in register EXP_FOT_TIME. This timing must be calculated from the OnSemi setting files .	
Value at Reset:	0x0	
Possible Values:	0x0	Disable exposure during FOT in output exposure signal and Strobe
	0x1	Enable exposure during FOT in output exposure signal and Strobe

<b>EXP_FOT_TIME (11:0)</b>	EXPosure during FOT TIME	
<i>RW</i>	This is the time of the exposure during the FOT. This timing must be calculated from the OnSemi setting files .  From DCF v1.2, for all LVDS modes :  P5000 & P2000 EXP_FOT=40.666us, program value 0x9e9  P1300 & P500 & P300 EXP_FOT=27.333us, program value 0x6ac	
Value at Reset:	0x0	

## ACQ\_SFNC

---

Address: section "ACQ" base address + 0x144

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
Reserved							
7	6	5	4	3	2	1	0
Reserved							RELOAD_GRAB_PARAMS

RELOAD_GRAB_PARAMS <i>WO/AutoClr</i>		
Possible Values:	0x0	
	0x1	

Address: section "ACQ" base address + 0x154

#### Description:

A noise peak elimination filter iteratively replaces the central pixel in a 3x3 neighborhood, if the pixel is a minimum or maximum within that neighborhood. It is replaced with the next lowest or highest value (respectively) in the neighborhood.. If the central pixel is not a minimum or maximum, it is left unchanged.

Threshold register controls the sharpness of replacement as follow:

$\text{CurrPixel} - \text{Threshold} > \text{MaxNeighborhood}$ , and  $\text{CurrPixel} - \text{threshold} \geq 0$  : Replace by  $\text{MaxNeighborhood}$

$\text{CurrPixel} + \text{Threshold} < \text{MaxNeighborhood}$ , and  $\text{CurrPixel} + \text{threshold} \leq 1023$  : Replace by  $\text{MinNeighborhood}$

31	30	29	28	27	26	25	24
Reserved						NOPEL_FIFO_UNDERRUN	NOPEL_FIFO_OVERRUN
23	22	21	20	19	18	17	16
Reserved			NOPEL_FIFO_RST	Reserved		NOPEL_BYPASS	NOPEL_ENABLE
15	14	13	12	11	10	9	8
Reserved							
7	6	5	4	3	2	1	0
NOPEL_THRESHOLD(7:0)							

<b>NOPEL_FIFO_UNDERRUN</b> <i>RO</i>	NOPEL FIFO UNDERRUN	
	This is the fifo underrun status of the 2 linebuffers in the NOPEL macro. Write '1' then '0' to field NOPEL_FIFO_RST to reset this flag and reset the Fifo logic.	
Possible Values:	0x0	Underrun not detected
	0x1	Underrun detected

<b>NOPEL_FIFO_OVERRUN</b> <i>RO</i>		
	This is the fifo overrun status of the 2 linebuffers in the NOPEL macro. Write '1' then '0' to field NOPEL_FIFO_RST to reset this flag and reset the Fifo logic.	
Possible Values:	0x0	Overrun not detected
	0x1	Overrun detected

<b>NOPEL_FIFO_RST</b> <i>RW</i>	NOPEL FIFO RESET	
	Write '1' then '0' to field NOPEL_FIFO_RST to reset overrun/underrun flags of the linebuffers and reset the Fifo logic.	
Value at Reset:	0x0	
Possible Values:	0x0	Fifo in normal operation
	0x1	Fifo in reset State



<b>NOPEL_BYPASS</b>	NOPEL BYPASS	
<i>RW</i>	The Nopel bypass serves to send the current pixels instead the new calculated pixel, but using all the Nopel core logic.	
Value at Reset:	0x0	
Possible Values:	0x0	Nopel MIN-MAX used
	0x1	Nopel MIN-MAX bypass, send current pixel

<b>NOPEL_ENABLE</b>		
<i>RW</i>	Enable Nopel filter to correct cold/hot pixels.	
	The grab must be idle when changing this register.	
Value at Reset:	0x1	
Possible Values:	0x0	Nopel filter bypassed
	0x1	Nopel filter used

<b>NOPEL_THRESHOLD (7:0)</b>	NOPEL THRESHOLD	
<i>RW</i>	Nopel Threshold register controls the sharpness of replacement in the Nopel filter logic. Up to 8 bits can be programmed (255 LSB 10 )	
Value at Reset:	0x10	
Possible Values:	Any Value	This is a LSB10 value

## Section: DATA

Address Range: [0x300 - 0x388]

### LUT\_CTRL

Address: section "DATA" base address + 0x000

31	30	29	28	27	26	25	24
LUT_BYPAS S	Reserved	LUT_PALET TE_USE	LUT_PALET TE_W	Reserved		LUT_DATA_W(9:8)	
23	22	21	20	19	18	17	16
LUT_DATA_W(7:0)							
15	14	13	12	11	10	9	8
Reserved	LUT_SEL(2:0)			LUT_WRN	LUT_SS	LUT_ADD(9:8)	
7	6	5	4	3	2	1	0
LUT_ADD(7:0)							

<b>LUT_BYPASS</b>	LUT BYPASS	
RW	When set this register to '1', the LUT logic will not be used, and the 10 bits data will be sent to the DMA. This register is used for optical test usage since the Perceptron/N3 have only 10 to 8 bits LUT only. The DMA must be configured in synthesis to be able to transfer 10bpp images.	
Value at Reset:	0x0	
Possible Values:	0x0	Use LUT logic.
	0x1	LUT logic bypass.

<b>LUT_PALETTE_USE</b>	LUT PALETTE to USE	
RW	This register selects the LUT palette to be used in the grab path.	
Value at Reset:	0x0	
Possible Values:	0x0	Palette 0 is used
	0x1	Palette 1 is used

<b>LUT_PALETTE_W</b>	LUT PALETTE to Write	
RW	This register selects the palette to be written into the LUT. This register must be set to 0 when programming the Palette 0 and to 1 when programming the Palette 1.	
Value at Reset:	0x0	
Possible Values:	0x0	Write Palette 0
	0x1	Write Palette 1

<b>LUT_DATA_W (9:0)</b>	LUT DATA to Write	
RW	Data to write in the LUT	
Value at Reset:	0x0	

<b>LUT_SEL (2:0)</b> <i>RW</i>	LUT SElection	
	LUT programming selector.	
	The Color and Mono shares the same 4 physical LUT.	
Value at Reset:	0x0	
Possible Values:	0x0	Read or Write to Gamma / Mono0 LUT
	0x1	Read or write to Blue / Mono1 LUT
	0x2	Read or write to Green / Mono2 LUT
	0x3	Read or write to Red / Mono3 LUT
	0x4	Write ALL LUT with same data.
	0x5	
	0x6	
	0x7	

<b>LUT_WRN</b> <i>RW</i>	LUT Write ReadNot	
	LUT Write mode	
Value at Reset:	0x0	
Possible Values:	0x0	Read operation
	0x1	Write operation

<b>LUT_SS</b> <i>WO/AutoClr</i>	LUT SnapShot	
	Start the LUT OPERATION (R/W)	

<b>LUT_ADD (9:0)</b> <i>RW</i>		
Value at Reset:	0x0	

LUT\_RB

Address: section "DATA" base address + 0x008

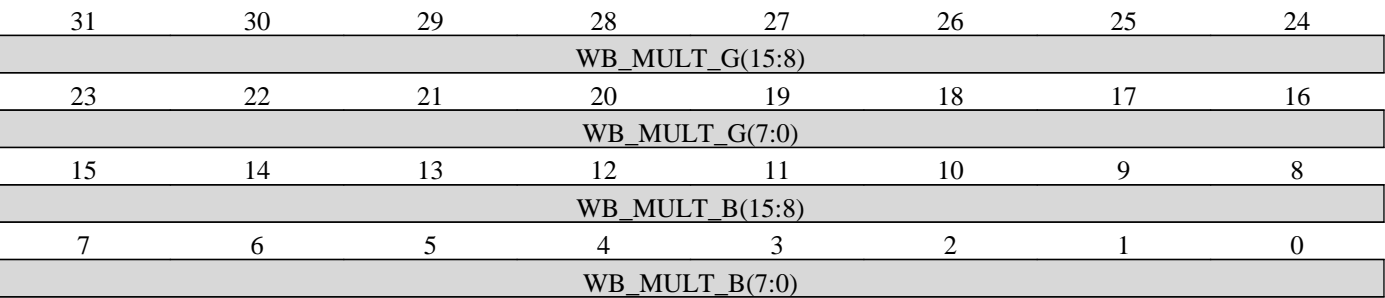
31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
Reserved						LUT_RB(9:8)	
7	6	5	4	3	2	1	0
LUT_RB(7:0)							

LUT_RB (9:0) RO	
	LUT ReadBack

**WB\_MULT1**

---

Address: section "DATA" base address + 0x010



<b>WB_MULT_G (15:0)</b>	
<i>RW</i>	
Value at Reset:	0x1000

<b>WB_MULT_B (15:0)</b>	
<i>RW</i>	
Value at Reset:	0x1000

**WB\_MULT2**

Address: section "DATA" base address + 0x018

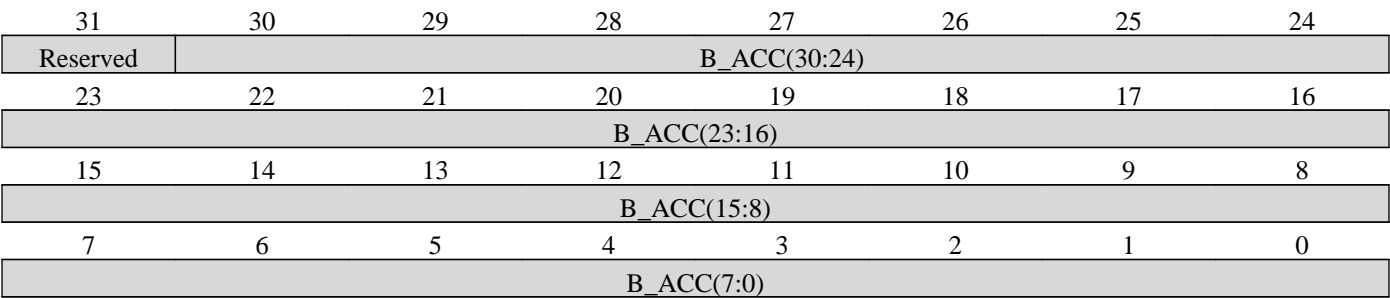
31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
WB_MULT_R(15:8)							
7	6	5	4	3	2	1	0
WB_MULT_R(7:0)							

WB_MULT_R (15:0)	
RW	
Value at Reset:	0x1000

**WB\_B\_ACC**

---

Address: section "DATA" base address + 0x020



<b>B_ACC (30:0)</b>	
<i>RO</i>	ACQquisition Blue ACCumulator

**WB\_G\_ACC**

---

Address: section "DATA" base address + 0x028

31	30	29	28	27	26	25	24
G_ACC(31:24)							
23	22	21	20	19	18	17	16
G_ACC(23:16)							
15	14	13	12	11	10	9	8
G_ACC(15:8)							
7	6	5	4	3	2	1	0
G_ACC(7:0)							

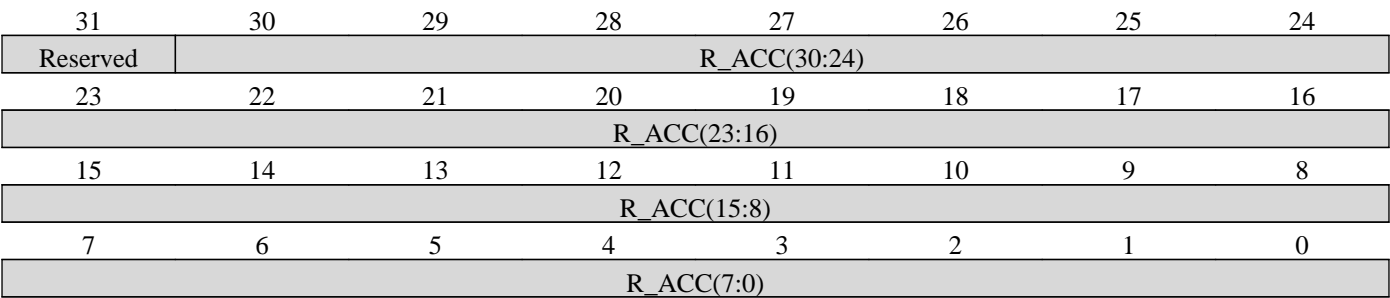
G_ACC (31:0) RO	
	ACQquisition Green ACCumulator



**WB\_R\_ACC**

---

Address: section "DATA" base address + 0x030



<b>R_ACC (30:0)</b>	
<i>RO</i>	ACQuisition Red ACCumulator

## FPN\_ADD

Address: section "DATA" base address + 0x038

31	30	29	28	27	26	25	24
FPN_73	Reserved		FPN_WE	Reserved			FPN_EN
23	22	21	20	19	18	17	16
Reserved							FPN_SS
15	14	13	12	11	10	9	8
Reserved						FPN_ADD(9:8)	
7	6	5	4	3	2	1	0
FPN_ADD(7:0)							

<b>FPN_73</b> <i>RW</i>							
	Use [7].[3] fpn correction instead old [5].[3] .						
	This 7.3 mode is not implemented in the released FPGA.						
Value at Reset:	0x0						
Possible Values:	0x0			Use normal fpn mode 5.3			
	0x1			Use advanced fpn mode 7.3			

<b>FPN_WE</b> <i>RW</i>	FPN Write Enable						
	This register is the coefficient RAM WRITE ENABLE						
Value at Reset:	0x1						
Possible Values:	0x0			Read operation			
	0x1			Write operation			

<b>FPN_EN</b> <i>RW</i>	FPN ENable						
	This field enables the HW FPN and PRNU correction						
Value at Reset:	0x0						
Possible Values:	0x0			HW correction disable			
	0x1			HW correction enable			

<b>FPN_SS</b> <i>WO/AutoClr</i>	FPN SnapShot						
	This register is the snapshot for read/write to the coefficient RAM.						
Possible Values:	0x0			Nothing			
	0x1			Snapshot			

<b>FPN_ADD (9:0)</b> <i>RW</i>	FPN ADDRESS						
	This register is the address to be write/read in the coefficient RAM. The first 512(144bits) locations are correction factors to not SUBsampled image(palette 0). The second 512 locations(144bits) are correction factors to SUBsampled image(palette 1).						
Value at Reset:	0x0						

## FPN\_READ\_REG

Address: section "DATA" base address + 0x03C

31	30	29	28	27	26	25	24
Reserved	FPN_READ_PIX_SEL(2:0)			Reserved			FPN_READ_PRNU(8)
23	22	21	20	19	18	17	16
FPN_READ_PRNU(7:0)							
15	14	13	12	11	10	9	8
Reserved				FPN_READ_FPN(10:8)			
7	6	5	4	3	2	1	0
FPN_READ_FPN(7:0)							

<b>FPN_READ_PIX_SEL (2:0)</b>	
<i>RW</i>	This is the pixel number to be read (0 to 7) in the RAM. Each RAM location contains corrections for 8 pixels per address(FPN_ADD). This field selects the PIXel correction to be readed.
Value at Reset:	0x0
Possible Values:	0x0 - 0x7

<b>FPN_READ_PRNU (8:0)</b>	
<i>RO</i>	This is the PRNU coefficient readed in RAM.

<b>FPN_READ_FPN (10:0)</b>	
<i>RO</i>	This is the FPN coefficient readed in RAM.

## FPN\_DATA (7:0)

Address: section "DATA" base address + 0x040 + (index \* 0x4)

31	30	29	28	27	26	25	24
Reserved							FPN_DATA_PRNU(8)
23	22	21	20	19	18	17	16
FPN_DATA_PRNU(7:0)							
15	14	13	12	11	10	9	8
Reserved					FPN_DATA_FPN(10:8)		
7	6	5	4	3	2	1	0
FPN_DATA_FPN(7:0)							

<b>FPN_DATA_PRNU (8:0)</b>	FPN DATA PRNU
<i>RW</i>	<p>This is the PRNU coefficient be written in RAM.</p> <p>PRNU factor is signed 9 bits [0].[00][+/-][8]</p> <p>From the DoubleValue calculated in SW, program this field as:</p> <p>FPN_DATA_PRNU = int(DoubleVal*2048.0)</p> <p>Clip correction to implement in the driver is :</p> <p>if(DoubleVal &gt; (255.0 / 2048.0) ) DoubleVal = (255.0 / 2048.0) (0.124511718)</p> <p>if(DoubleVal &lt; -(255.0 / 2048.0) ) DoubleVal = -(255.0 / 2048.0) (0.124511718)</p>
Value at Reset:	0x0

<b>FPN_DATA_FPN (10:0)</b>	FPN DATA FPN
<i>RW</i>	<p>This is the FPN coefficient be written in RAM.</p> <p>If FPN 5.3 is implemented(default) factor is signed 9 bits [+/-][5].[3]</p> <p>If FPN 7.3 is implemented(default) factor is signed 11 bits [+/-][7].[3]</p> <p>In 5.3 configuration, from the DoubleValue alculated in SW, program this field as: program this field as:</p> <p>FPN_DATA_FPN = int((DoubleVal/32.0)*256.0)</p> <p>Clip correction to implement in the driver is :</p> <p>if(DoubleValue &gt; 255.0/8.0) DoubleValue= 255.0/8.0 (31.875)</p> <p>if(DoubleValue &lt; -255.0/8.0) DoubleValue= -255.0/8.0 (-31.875)</p>
Value at Reset:	0x0

## FPN CONTRAST

Address: section "DATA" base address + 0x060

31	30	29	28	27	26	25	24
Reserved				CONTRAST_GAIN(11:8)			
23	22	21	20	19	18	17	16
CONTRAST_GAIN(7:0)							
15	14	13	12	11	10	9	8
Reserved							
7	6	5	4	3	2	1	0
CONTRAST_OFFSET(7:0)							

<b>CONTRAST_GAIN (11:0)</b>	
<i>RW</i>	This is a digital gain [4].[8] applied after the EXIT_CP3 subtractor. This register <b>MUST</b> be set to 1 or greater.
Value at Reset:	0x100

<b>CONTRAST_OFFSET (7:0)</b>	<b>CONTRAST OFFSET</b>
<i>RW</i>	This is the constant subtracted to the 10 bit pixel FPN and PRNU corrected. The value is a 8 bits integer value [8].[0] . This register is aligned with the LSB of the 10 bit pixel value.
Value at Reset:	0x0

## FPN\_ACC\_ADD

Address: section "DATA" base address + 0x068

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved		FPN_ACC_M ODE_SEL	FPN_ACC_M ODE_EN	Reserved			FPN_ACC_R_ SS
15	14	13	12	11	10	9	8
Reserved				FPN_ACC_ADD(11:8)			
7	6	5	4	3	2	1	0
FPN_ACC_ADD(7:0)							

<b>FPN_ACC_MODE_SEL</b> <i>RW</i>							
	<p>This register selects if the Contrast Gain and Offset is used for compute the pixel accumulators.</p> <p>If FPN_ACC_MODE_SEL =0 then the module will use CONTRAST_GAIN=1 and CONTRAST_OFFSET=0 for the accumulators.</p> <p>If FPN_ACC_MODE_SEL =1 then the module will use Gain and Offset from registers CONTRAST_GAIN and CONTRAST_OFFSET.</p>						
Value at Reset:	0x0						
Possible Values:	0x0	Don't use Contrast Gain and Offset					
	0x1	Use Contrast Gain and Offset					

<b>FPN_ACC_MODE_EN</b> <i>RW</i>	FPN ACCumulator MODE ENable						
	This field defines the accumulator mode. When this register is set to '1', the accumulators will start count and no frame will be sent to the host memory.						
Value at Reset:	0x0						
Possible Values:	0x0	Normal DMA transfert mode					
	0x1	Accumulator mode					

<b>FPN_ACC_R_SS</b> <i>WO/AutoClr</i>	FPN ACCumulator Read Snapshot						
	This is the column read accumulator snapshot.						

<b>FPN_ACC_ADD (11:0)</b> <i>RW</i>	FPN ACCumulator ADDress						
	This is the column accumulator adress to read.						
Value at Reset:	0x0						

## FPN\_ACC\_DATA

Address: section "DATA" base address + 0x070

31	30	29	28	27	26	25	24
Reserved							FPN_ACC_R_WORKING
23	22	21	20	19	18	17	16
FPN_ACC_DATA(23:16)							
15	14	13	12	11	10	9	8
FPN_ACC_DATA(15:8)							
7	6	5	4	3	2	1	0
FPN_ACC_DATA(7:0)							

<b>FPN_ACC_R_WORKING</b> <i>RO</i>	FPN ACCumulator Read WORKING						
	This field is the working status of the read-to-column accumulator. The data in the field FPN_ACC_DATA will be valid when FPN_ACC_R_WORKING is set to '0'						
Possible Values:	0x0	The data in the field FPN_ACC_DATA is valid					
	0x1	The data in the field FPN_ACC_DATA is invalid					

<b>FPN_ACC_DATA (23:0)</b> <i>RO</i>	FPN ACCumulator DATA						
	This is the column accumulator.						
Possible Values:		Any 24 bits value					

## DPC\_LIST\_CTRL

Address: section "DATA" base address + 0x080

31	30	29	28	27	26	25	24
dpc_fifo_underrun	dpc_fifo_overrun	Reserved	dpc_fifo_reset	Reserved	dpc_firstlast_line_remove	dpc_pattern0_cfg	dpc_enable
23	22	21	20	19	18	17	16
Reserved		dpc_list_count(5:0)					
15	14	13	12	11	10	9	8
Reserved			dpc_list_WRn	Reserved			dpc_list_ss
7	6	5	4	3	2	1	0
Reserved		dpc_list_add(5:0)					

<b>dpc_fifo_underrun</b> <i>RO</i>							
	This is the fifo underrun status of the 2 linebuffers in the dpc macro. Write '1' then '0' to field dpc_FIFO_RST to reset this flag and reset the Fifo logic.						
Possible Values:	0x0			Underrun not detected			
	0x1			Underrun detected			

<b>dpc_fifo_overrun</b> <i>RO</i>							
	This is the fifo overrun status of the 2 linebuffers in the DPC macro. Write '1' then '0' to field dpc_FIFO_RST to reset this flag and reset the Fifo logic.						
Possible Values:	0x0			Overrun not detected			
	0x1			Overrun detected			

<b>dpc_fifo_reset</b> <i>RW</i>							
	Write '1' then '0' to field dpcL_FIFO_RST to reset overrun/underrun flags of the line buffers and reset the Fifo logic.						
	The DPC dual port ram is not SW reset .						
	The fifo in each processing DPC unit is HW reset at each SOF.						
Value at Reset:	0x0						
Possible Values:	0x0			Fifo in normal operation			
	0x1			Fifo in reset State			

<b>dpc_firstlast_line_remove</b> <i>RW</i>							
	When this register is set to 1, the DPC macro will remove the first and last line of the image corrected. This can be usefull if we want to correct the 4 pixels in the corners of the image. The SW can program two more lines in the frame so the DPC macro can have enough pixels to correct the 4 pixel coners.						
Value at Reset:	0x0						
Possible Values:	0x0			Do not remove any lines of the image received			
	0x1			Remove first and last line of the image received			



<b>dpc_pattern0_cfg</b> <i>RW</i>	This field configures the behaviour of the correction pattern 0x0. If this field is set to 0x0 then the current pixel will not be corrected. If this field is set to 0x1 then the current pixel will be replaced by the value 0x3ff (white pixel)	
Value at Reset:	0x0	
Possible Values:	0x0	Do not correct current pixel
	0x1	Replace current pixel by a white pixel (0x3ff)

<b>dpc_enable</b> <i>RW</i>	Dead Pixel Correction core Enable, when this field is set to 1, the DPC logic will correct all the dead pixels that are listed in the DPC list.  The grab must be idle when changing this register.	
Value at Reset:	0x0	
Possible Values:	0x0	DPC logic is bypassed
	0x1	PDC logic is enable

<b>dpc_list_count (5:0)</b> <i>RW</i>	This is the number of entries in the DPC list. The driver need to set the dcp_list_count in order to correct the image. Up to 63 pixels can be corrected. The value 0 is allowed and when set to 0 no pixel will be corrected.	
Value at Reset:	0x0	
Possible Values:	Any Value	Any value from 0 to 63

<b>dpc_list_WRn</b> <i>RW</i>	This is the Write/ReadN flag. To write to the DPC list set this bit to 1 and start the transaction with the dpc_list_ss field. To read from the DPC list set this bit to 0 and start the transaction with the dpc_list_ss field.	
Value at Reset:	0x0	
Possible Values:	0x0	Read list operation
	0x1	Write list operation

<b>dpc_list_ss</b> <i>WO/AutoClr</i>	This is the DPC snapshot. In order to start a write or read transaction the snapshot needs to be written to '1'. This bit is a auto clear regisiter.	
Possible Values:	0x0	Do nothing
	0x1	Start the READ/WRITE transaction

<b>dpc_list_add (5:0)</b> <i>RW</i>	This is the address of the DPC list to be access by the read/write operation. Pixel 0 to correct is located at address b000000. Since the dpc_list_count field is also 6 bit wide, address 0 to 62 of the list can be used.	
Value at Reset:	0x0	

## DPC\_LIST\_DATA

Address: section "DATA" base address + 0x084

31	30	29	28	27	26	25	24
dpc_list_corr_pattern(7:0)							
23	22	21	20	19	18	17	16
dpc_list_corr_y(11:4)							
15	14	13	12	11	10	9	8
dpc_list_corr_y(3:0)				dpc_list_corr_x(11:8)			
7	6	5	4	3	2	1	0
dpc_list_corr_x(7:0)							

<b>dpc_list_corr_pattern (7:0)</b>	
<i>RW</i>	<p>This is pattern of the pixel to be corrected when executing a write to the DPC list.</p> <p>2 bit correction : 34, 17, 136, 68          4 bit correction : 170, 153, 51, 204, 85, 102          6 bit correction: 187,238 (mapped to 170), 119,221 (mapped to 85)          8 bit correction : 255          Set pixel to 255 (white), debug : 0</p>
Value at Reset:	0x0

<b>dpc_list_corr_y (11:0)</b>	
<i>RW</i>	This is Y location of the pixel to be corrected when executing a write to the DPC list.
Value at Reset:	0x0

<b>dpc_list_corr_x (11:0)</b>	
<i>RW</i>	This is X location of the pixel to be corrected when executing a write to the DPC list.
Value at Reset:	0x0

## DPC\_LIST\_DATA\_RD

Address: section "DATA" base address + 0x088

31	30	29	28	27	26	25	24
dpc_list_corr_pattern(7:0)							
23	22	21	20	19	18	17	16
dpc_list_corr_y(11:4)							
15	14	13	12	11	10	9	8
dpc_list_corr_y(3:0)				dpc_list_corr_x(11:8)			
7	6	5	4	3	2	1	0
dpc_list_corr_x(7:0)							

<b>dpc_list_corr_pattern (7:0)</b>	
<i>RO</i>	<p>This is pattern of the pixel read from DPC list.</p> <p>2 Bit correction : 34, 17, 136, 68</p> <p>4 Bit correction : 170, 153, 51, 204, 85, 102</p> <p>6 bit correction: 187,238 (mapped to 170), 119,221 (mapped to 85)</p> <p>8 bit correction : 255</p> <p>Set pixel to 255 (white), debug : 0</p>

<b>dpc_list_corr_y (11:0)</b>	
<i>RO</i>	This is Y location of the pixel read from the DPC list.

<b>dpc_list_corr_x (11:0)</b>	
<i>RO</i>	This is X location of the pixel read from the DPC list.

Address Range: [0x400 - 0x428]

**CTRL**

Address: section "HISPI" base address + 0x000

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
Reserved							
7	6	5	4	3	2	1	0
Reserved				RESET_IDELAYCTRL	CALIBRATE_SERDES	CLR	ENABLE

<b>RESET_IDELAYCTRL</b>	Reset the Xilinx macro IDELAYCTRL	
<i>RW</i>		
Value at Reset:	0x0	
Possible Values:	0x0	No effect
	0x1	Reset IDELAYCTRL

<b>CALIBRATE_SERDES</b>	Initiate the SERDES TAP calibration	
<i>WO/AutoClr</i>		
Possible Values:	0x0	No effect
	0x1	Initiate the calibration

<b>CLR</b>		
<i>RW</i>		
Value at Reset:	0x0	

<b>ENABLE</b>		
<i>RW</i>		
Value at Reset:	0x0	

# IDELAYCTRL\_STATUS

Address: section "HISPI" base address + 0x004

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
Reserved							
7	6	5	4	3	2	1	0
Reserved							PLL_LOCKED

PLL_LOCKED RO	IDELAYCTRL PLL locked	
Possible Values:	0x0	IDELAYCTRL PLL unlocked
	0x1	IDELAYCTRL PLL locked

LANE\_DECODER\_STATUS  
(5:0)

Address: section "HISPI" base address + 0x008 + (index \* 0x4)

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
Reserved							FIFO_UNDE RRUN
7	6	5	4	3	2	1	0
FIFO_OVERR UN	CALIBRARTI ON_ERROR	CALIBRATIO N_ACTIVE	CALIBRATION_TAP_VALUE(4:0)				

FIFO_UNDERRUN	
RW	
Value at Reset:	0x0

FIFO_OVERRUN	
RW	
Value at Reset:	0x0

CALIBRARTION_ERROR	
RW	
Value at Reset:	0x0

CALIBRATION_ACTIVE	
RO	

CALIBRATION_TAP_VALU E (4:0)	
RO	

LANE PACKER STATUS (2:0)

Address: section "HISPI" base address + 0x020 + (index \* 0x4)

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
Reserved							FIFO_UNDE RRUN
7	6	5	4	3	2	1	0
FIFO_OVERR UN	Reserved						

FIFO_UNDERRUN <i>RW</i>	
Value at Reset:	0x0

FIFO_OVERRUN <i>RW</i>	
Value at Reset:	0x0