Register file structure : regfile_xgs_athena.pdf Created by jmansill on 2021/02/26 14:33:32

Register file CRC32 : 0x7AF286C6

1. Main Parameters

Register file endianness: little endian

Address bus width: 11 bits Data bus width: 32 bits

2. Memory Map

Section name	Address(es) / Address Ranges	Register name	Access Type
SYSTEM	0x000	TAG	R
	0x004	VERSION	R
	0x008	CAPABILITY	R
	0x00C	SCRATCHPAD	RW
DMA	0x070	CTRL	RW
	0x078	FSTART	RW
	0x07C	FSTART_HIGH	RW
	0x080	FSTART_G	RW
	0x084	FSTART_G_HIGH	RW
	0x088	FSTART_R	RW
	0x08C	FSTART_R_HIGH	RW
	0x090	LINE_PITCH	RW
	0x094	LINE_SIZE	RW
	0x098	CSC	RW
	0x0A8	OUTPUT_BUFFER	RW
	0x0AC	TLP	R
	0x0B0	ROI_X	RW
ACQ	0x100	GRAB_CTRL	RW
	0x108	GRAB_STAT	R
	0x110	READOUT_CFG1	RW
	0x114	READOUT_CFG_FRA ME_LINE	RW
	0x118	READOUT_CFG2	R
	0x120	READOUT_CFG3	RW
	0x124	READOUT_CFG4	RW
	0x128	EXP_CTRL1	RW
	0x130	EXP_CTRL2	RW
	0x138	EXP_CTRL3	RW
	0x140	TRIGGER_DELAY	RW
	0x148	STROBE_CTRL1	RW
	0x150	STROBE_CTRL2	RW
	0x158	ACQ_SER_CTRL	RW

Section name	Address(es) / Address Ranges	Register name	Access Type
	0x160	ACQ_SER_ADDATA	RW
	0x168	ACQ_SER_STAT	R
	0x190	SENSOR_CTRL	RW
	0x198	SENSOR_STAT	R
	0x19C	SENSOR_SUBSAMPLI	RW
	0x1A4	SENSOR_GAIN_ANA	RW
	0x1A8	SENSOR_ROI_Y_STA RT	RW
	0x1AC	SENSOR_ROI_Y_SIZE	RW
	0x1B8	SENSOR_M_LINES	RW
	0x1BC	SENSOR_DP_GR	RW
	0x1C0	SENSOR_DP_GB	RW
	0x1C4	SENSOR_DP_R	RW
	0x1C8	SENSOR_DP_B	RW
	0x1CC	SENSOR_GAIN_DIG_ G	RW
	0x1D0	SENSOR_GAIN_DIG_ RB	RW
	0x1D8	FPGA_ROI_X_START	RW
	0x1DC	FPGA_ROI_X_SIZE	RW
	0x1E0	DEBUG_PINS	RW
	0x1E8	TRIGGER_MISSED	RW
	0x1F0	SENSOR FPS	R
	0x1F4	SENSOR_FPS2	R
	0x2A0	DEBUG	RW
	0x2A8	DEBUG CNTR1	R
	0x2B8	EXP_FOT	RW
	0x2C0	ACQ_SFNC	RW
	0x2D0	TIMER_CTRL	RW
	0x2D4	TIMER_DELAY	RW
	0x2D8	TIMER DURATION	RW
HISPI	0x400	CTRL	RW
111011	0x404	STATUS	R
	0x408		R
	0x40C	IDLE_CHARACTER	RW
	0x410	PHY	RW
	0x414	FRAME_CFG	RW
	0x418	FRAME_CFG_X_VALI	
	0x424, 0x428, ,0x438	LANE_DECODER_ST ATUS (5:0)	RW
	0x43C, 0x440, ,0x450	TAP_HISTOGRAM (5:0)	R
	0x454	DEBUG	RW
DPC	0x480	DPC_CAPABILITIES	R
	0x484	DPC_LIST_CTRL	RW
	0x488	DPC_LIST_STAT	R
	0x48C	DPC_LIST_DATA1	RW
	0x490	DPC_LIST_DATA2	RW
	0x494	DPC_LIST_DATA1_R D	R
	0x498	DPC_LIST_DATA2_R D	R
LUT	0x4B0	LUT_CAPABILITIES	R

Section name	Address(es) / Address Ranges	Register name	Access Type
	0x4B4	LUT_CTRL	RW
	0x4B8	LUT_RB	R
BAYER	0x4C0	BAYER_CFG	RW
	0x4C4	WB_MUL1	RW
	0x4C8	WB_MUL2	RW
	0x4CC	WB_B_ACC	R
	0x4D0	WB_G_ACC	R
	0x4D4	WB_R_ACC	R
SYSMONXIL	0x700	TEMP	R
	0x704	VCCINT	R
	0x708	VCCAUX	R
	0x718	VCCBRAM	R
	0x780	TEMP_MAX	R
	0x790	TEMP_MIN	R

3. Registers definition

Section: SYSTEM

Address Range: [0x000 - 0x00C]

TAG

Address: section "SYSTEM" base address + 0x000

31	30	29	28	27	26	25	24			
	Reserved									
23	22	21	20	19	18	17	16			
	VALUE(23:16)									
15	14	13	12	11	10	9	8			
	VALUE(15:8)									
7	6	5	4	3	2	1	0			
			VALU	JE(7:0)						

VALUE (23:0)	Tag identifier	
STATIC		
Value at Reset:	0x58544d	
Possible Values:	0x58544D	MTX ASCII string

Description:

Revisions

0.1.0 : First functionnal revision

0.2.0 : Removed tha lane_packer module

31	30	29	28	27	26	25	24		
	Reserved								
23	22	21	20	19	18	17	16		
			MAJO	R(7:0)					
15	14	13	12	11	10	9	8		
	MINOR(7:0)								
7	6	5	4	3	2	1	0		
	HW(7:0)								

MAJOR (7:0)	
STATIC	
Value at Reset:	0x0

MINOR (7:0)	
STATIC	
Value at Reset:	0x2

HW (7:0)	
STATIC	
Value at Reset:	0x0

31	30	29	28	27	26	25	24	
			Rese	erved				
23	22	21	20	19	18	17	16	
			Rese	erved				
15	14	13	12	11	10	9	8	
	Reserved							
7	6	5	4	3	2	1	0	
	VALUE(7:0)							

VALUE (7:0)			
STATIC			
Value at Reset:	0x0		

Address: section "SYSTEM" base address + 0x00C

31	30	29	28	27	26	25	24			
	VALUE(31:24)									
23	22	21	20	19	18	17	16			
			VALUE	E(23:16)						
15	14	13	12	11	10	9	8			
	VALUE(15:8)									
7	6	5	4	3	2	1	0			
	VALUE(7:0)									

VALUE (31:0)	
RW	
Value at Reset:	0x0

Address Range: [0x070 - 0x0B8]

CTRL

Initial Grab Address Register

Address: section "DMA" base address + 0x000

Description:

Initial Grab Address LOW 32 bits

31	30	29	28	27	26	25	24		
	Reserved								
23	22	21	20	19	18	17	16		
	Reserved								
15	14	13	12	11	10	9	8		
			Res	erved					
7	6	5	4	3	2	1	0		
	Reserved						GRAB_QUEU E_EN		
							E_EN		

GRAB_QUEUE_EN		
RW		
Value at Reset:	0x0	
Possible Values:	0x0	
	0x1	

Description:

Initial Grab Address LOW 32 bits

31	30	29	28	27	26	25	24			
	VALUE(31:24)									
23	22	21	20	19	18	17	16			
	VALUE(23:16)									
15	14	13	12	11	10	9	8			
	VALUE(15:8)									
7	6	5	4	3	2	1	0			
	VALUE(7:0)									

VALUE (31:0)	Nitial GRAb ADDRess Register			
RW	This is the address in the host ram where the grab engine will start writing pixel data.			
Value at Reset:	0x0			
Possible Values:	Any Value			

Description:

Initial Grab Address HI 32 bits

31	30	29	28	27	26	25	24			
	VALUE(31:24)									
23	22	21	20	19	18	17	16			
	VALUE(23:16)									
15	14	13	12	11	10	9	8			
	VALUE(15:8)									
7	6	5	4	3	2	1	0			
	VALUE(7:0)									

VALUE (31:0)	INitial GRAb ADDRess Register High			
RW	This is the high 32 bits of the 64-bit addresses in the host ram where the grab engine will start writing pixel data.			
Value at Reset:	0x0			
Possible Values:	Any Value			

Description:

Grab Address LOW 32 bits for the Green plane. Only used when grabbing in Planar mode.

31	30	29	28	27	26	25	24		
	VALUE(31:24)								
23	22	21	20	19	18	17	16		
	VALUE(23:16)								
15	14	13	12	11	10	9	8		
	VALUE(15:8)								
7	6	5	4	3	2	1	0		
	VALUE(7:0)								

VALUE (31:0)	GRAb ADDRess Register
RW	This is the address in the host ram where the grab engine will start writing pixel data.
Value at Reset:	0x0
Possible Values:	Any Value

Description:

Green Grab Address HIGH 32 bits

31	30	29	28	27	26	25	24			
	VALUE(31:24)									
23	22	21	20	19	18	17	16			
	VALUE(23:16)									
15	14	13	12	11	10	9	8			
	VALUE(15:8)									
7	6	5	4	3	2	1	0			
	VALUE(7:0)									

VALUE (31:0) RW	This is the high pa	GRAb ADDRess Register High This is the high part of the 64-bit addresess in the host ram where the grab engine will start writing pixel data.			
Value at Reset:	0x0	0x0			
Possible Values:	Any Value	Any value			

Description:

Grab Address LOW 32 bits for the Red plane. Only used when grabbing in Planar mode.

31	30	29	28	27	26	25	24			
	VALUE(31:24)									
23	22	21	20	19	18	17	16			
	VALUE(23:16)									
15	14	13	12	11	10	9	8			
	VALUE(15:8)									
7	6	5	4	3	2	1	0			
	VALUE(7:0)									

VALUE (31:0)	GRAb ADDRess Regis	GRAb ADDRess Register			
RW	This is the address in th	This is the address in the host ram where the grab engine will start writing pixel data.			
Value at Reset:	0x0				
Possible Values:	Any Value	Any value			

Description:

Red Grab Address HIGH 32 bits

31	30	29	28	27	26	25	24
			VALUE	E(31:24)			
23	22	21	20	19	18	17	16
			VALUE	E(23:16)			
15	14	13	12	11	10	9	8
			VALU	E(15:8)			
7	6	5	4	3	2	1	0
	VALUE(7:0)						

VALUE (31:0) RW	GRAb ADDRess I This is the high pa writing pixel data.	rt of the 64-bit addresess in the host ram where the grab engine will start			
Value at Reset:	0x0	0x0			
Possible Values:	Any Value	Any Value Any value			

Description:

Grab Line Pitch Register

31	30	29	28	27	26	25	24
	Reserved						
23	22	21	20	19	18	17	16
			Rese	erved			
15	14	13	12	11	10	9	8
			VALU	E(15:8)			
7	6	5	4	3	2	1	0
	VALUE(7:0)						

VALUE (15:0)	Grab LinePitch
RW	This is the line pitch when writing in ram. It is measured in bytes, not pixels.
Value at Reset:	0x0

Description:

Host Line Size Register.

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
			Rese	erved			
15	14	13	12	11	10	9	8
Rese	rved		VALUE(13:8)				
7	6	5	4	3	2	1	0
	VALUE(7:0)						

VALUE (13:0)	Host Line size	Host Line size			
RW	register is higher the host memory. If the cropped at the end	This is the line size when writing in host ram. It is measured in bytes, not pixels. If this register is higher than the actual data provided by the sensor, stray data will be written into host memory. If this register is lower than the data provided by the sensor, image data will be cropped at the end of the line. For backward compatibility, the value of 0 indicates that the FPGA should auto-compute the line sized based on data provided by the sensor interface.			
Value at Reset:	0x0	0x0			
Possible Values:	e Values: 0x1 - 0x3FFF Written line size in host frame.				
	0x0	Auto-compute line size from sensor data.			

31	30	29	28	27	26	25	24
		Reserved			C	OLOR_SPACE(2	2:0)
23	22	21	20	19	18	17	16
DUP_LAST_ LINE				Reserved			
15	14	13	12	11	10	9	8
		Reserved			SUB_X	REVERSE_Y	REVERSE_X
7	6	5	4	3	2	1	0
	Reserved						

COLOR_SPACE (2:0)						
RW	Output color s	Output color space used to transfer data to the DMA engine.				
Value at Reset:	0x0	0x0				
Possible Values:	0x0	Reserved for Mono sensor operation				
	0x1	BGR32				
	0x2	YUV 4:2:2 in full range				
	0x3	Planar 8-bits				
	0x4	Reserved for Y only with color sensor				
	0x5	RAW color pixels (8bpp or 10bpp selected with MONO10 regsiter)				

DUP_LAST_LINE						
RW	regenerate the	This field is used to enable the duplicate last line feature. When turned on, the datapath will regenerate the last line when it receives the end of frame marker from the acquisition section. The goal of this feature is to compensate for the lost line during the Bayer demosaic processing.				
Value at Reset:	0x0					
Possible Values:	0x0	0x0 normal processing				
	0x1	last line is duplicated				

SUB_X	
RW	
Value at Reset:	0x0

REVERSE_Y	REVERSE Y	
RW	Reverse readou	t
Value at Reset:	0x0	
Possible Values:	0x0	Bottom to top readout
	0x1	Top to bottom readout

REVERSE_X	
RW	
Value at Reset:	0x0

_	31	30	29	28	27	26	25	24
	MAX_LINE_BUFF_CNT(3:0)				Reserved		LINE_PTR_WIDTH(1:0)	
_	23	22	21	20	19	18	17	16
	ADDRESS_BUS_WIDTH(3:0)				Reserved			
	15	14	13	12	11	10	9	8
				Rese	rved			
	7	6	5	4	3	2	1	0
		Reserved		PCIE_BACK_ PRESSURE		Reserved		CLR_MAX_L INE_BUFF_C NT

MAX_LINE_BUFF_CNT (3:0)	Maximum line buffer count			
RO	This is an elastic line buffer. This fields records maximum number of line buffer that was used for transfering data. This field is cleared by the system reset and can also be cleared by the field			
	registerfile.DMA.OUTPUT_BUFFER.CLR_MAX_LINE_BUFF_CNT			

LINE_PTR_WIDTH (1:0)	Line pointer size (in bits)	Line pointer size (in bits)			
RW	Set the line pointer size (in bits) 3 = 3 bits wide: The full memory buffer is divided in 8 sub line buffers				
Value at Reset:	0x2				
Possible Values:	0x0 Not valid				
	0x1 The buffer is divided in 2 line buffers				
	0x2 The buffer is divided in 4 line buffers				
	0x3	The buffer is divided in 8 line buffers			

ADDRESS_BUS_WIDTH (3:0)	Line buffer address size in bits			
	Indicate to the software the size of the DMA output line buffer address bus in bits. For example for a 11 bits address bus, the buffer size in bytes is: 2pow(11) * 8 bytes = 16KB (16384 bytes)			

PCIE_BACK_PRESSURE	PCIE link back pressure	PCIE link back pressure detected				
RW2C	Indicates that the DMA line buffer was full while the XGS sensor was still pushing data. When this occures the Athena rely on the buffering (FiFo) along the data path as the last ressort to absorb the pcie back pressure. This should not occur.					
Value at Reset:	0x0	0x0				
Possible Values:	0x0 No effect					
	0x1 Back pressure detected on PCIe					

CLR_MAX_LINE_BUFF_CN T	Clear maximum line buffer count				
WO/AutoClr					
Possible Values:	0x0	No effect			
	0x1	Clear the max count			

31	30	29	28	27	26	25	24	
	Reserved				MAX_PAYLOAD(11:8)			
23	22	21	20	19	18	17	16	
	MAX_PAYLOAD(7:0)							
15	14	13	12	11	10	9	8	
			Rese	erved				
7	6	5	4	3	2	1	0	
Reserved				BUS_MASTE R_EN	CF	G_MAX_PLD(2	:0)	
	R_EN							

MAX_PAYLOAD (11:0)	
RO	

BUS_MASTER_EN	
RO	

CFG_MAX_PLD (2:0)	PCIe Device Control Register (Offset 08h); bits 7 downto 5				
RO	See PCIe Baser2.1, Section 7.8.4. Device Control Register (Offset 08h)				
	This field indicates the maximum TLP payload size allowed by the host for this Function. As a Receiver, the Function must handle TLPs as large as the set value. As a Transmitter, the Function must not generate TLPs exceeding the set value. Permissible values that can be programmed are indicated by the Max_Payload_Size Supported in the Device Capabilities register (see Section 7.8.3).				
	Functions that support only the 128-byte max payload size are permitted to hardwire this field to 000b. System software is not required to program the same value for this field for all the Functions of a multi-Function device. Refer to Section 2.2.2 for important guidance. For ARI Devices, Max_Payload_Size is determined solely by the setting in Function 0. The settings in the other Functions always return whatever value software programmed for each, but otherwise are ignored by the component. Default value of this field is 000b.				
Possible Values:	0x0	128 bytes max payload size			
	0x1 256 bytes max payload size				
	0x2 512 bytes max payload size				
	0x3 1024 bytes max payload size				
	Others	Not supported by Xilinx endpoint			

ROI_X

31	30	29	28	27	26	25	24	
	Reserved			X_END(12:8)				
23	22	21	20	19	18	17	16	
	X_END(7:0)							
15	14	13	12	11	10	9	8	
	Reserved				X_START(12:8)			
7	6	5	4	3	2	1	0	
	X_START(7:0)							

X_END (12:0)	
RW	This register defines the position of the last horizontal valid pixel (including interpolation pixels).
Value at Reset:	0x3ff

X_START (12:0)	
RW	This register defines the position of the first horizontal valid pixel (including interpolation pixels).
Value at Reset:	0x0

Address Range: [0x100 - 0x2D8]

GRAB_CTRL

GRAB ConTRoL Register

Address: section "ACQ" base address + 0x000

Description:

Grag Control Register

31	30	29	28	27	26	25	24
RESET_GRA B	Reserved	GRAB_ROI2_ EN	ABORT_GRA	A	Res	served	
23	22	21	20	19	18	17	16
			Reserved				TRIGGER_O VERLAP_BU FFn
15	14	13	12	11	10	9	8
TRIGGER_O VERLAP	TRIGGER_ACT(2:0)			Reserved	Т	RIGGER_SRC(2	:0)
7	6	5	4	3	2	1	0
Reserved GRAB		GRAB_SS	Rese	erved	BUFFER_ID	GRAB_CMD	
RESET_GRAB							
RW This register reset		esets the entire	XGS ctrl.				
Value at Reset: 0x0							
Possible Values: 0x0		0x0	Reset not active				
		0x1	Res	set active			

GRAB_ROI2_EN				
RW	1) No Y overl 2) Xsize must 3) EOF and So	Enable the second ROI on the frame (KNS). This register is not DB. 1) No Y overlap is allowed 2) Xsize must be the same for the two ROI for the moment(DMA constraint). 3) EOF and SOF in between the two in-frame ROIs will be masked to the DMA. The DMA will see one frame, with the two ROI inside.		
Value at Reset:	0x0			
Possible Values:	0x0	Dual ROI disable		
	0x1	Dual ROI enable		

ABORT_GRAB	ABORT GRAB		
WO/AutoClr	This is the grab Abort signal, it will reset all the grab queued.		
Possible Values:	0x0 Normal operation		
	0x1	Reset Grab	

TRIGGER_OVERLAP_BUF Fn			
RW	NOT FULLY VALIDATED. DON'T USE. SET IT TO '0'.		
Value at Reset:	0x0		
Possible Values:	0x0	Buffer the trigger received during the dead window in PET mode and execute	
	0x1	The trigger will be ignored during dead window in PET mode.	

TRIGGER_OVERLAP			
RW	This field enables the trigger overlap. In this mode the exposure and the readout of the sensor can be done in parallel for higher framerates.		
Value at Reset:	0x1		
Possible Values:	0x0	Trigger Overlap disable	
	0x1	Trigger Overlap enable (default)	

TRIGGER_ACT (2:0)	TRIGGER AC	Tivation		
RW	source is set to	ger activation . This register selects the activation of the trigger when the trigger Hardware Snapshop mode . Double Buffered, so the trigger activation may change from one grab command		
	In activation Level HI/LO with EXPOSURE_MODE register set to Timed, the camera will be triggered in continuous way if the level of the external trigger remains at the LEVEL programmed in this register.			
	In activation Level HI/LO with EXPOSURE_MODE register set to Trigger Width, t Exposure time will be set by the level of the trigger input. The FPGA exposure regsi be ignored. The Dual and Triple slope are not supported in the mode.			
Value at Reset:	0x0			
Possible Values:	0x0	Rising edge		
	0x1	Falling edge		
	0x2	Rising or Falling edge		
	0x3	Level HI		
	0x4	Level LO		
	0x5	Internal Programmable Timer Trigger		
	0x6	RESERVED		
	0x7	RESERVED		

TRIGGER_SRC (2:0)	TRIGGER SouRCe		
RW	This is the trigger source. This register selects the source of the grab trigger. This register is Double Buffered, so the trigger source may change from one grab command to another. TRIGGER_SRC(1) may be seen as a TRIGGER_STATE by the software driver.		
Value at Reset:	0x0		
Possible Values:	0x0	RESERVED	
	0x1	Immediate mode (Continuous)	
0x2		Hardware Snapshop mode	
	0x3	Software Snapshot mode	
	0x4	SFNC mode (auto trig)	

GRAB_SS WO/AutoClr		GRAB Software Snapshot This is the software snapshot register when the trigger source selected is Software Snapshot		
	mode.	mode.		
Possible Values:	0x0	0x0 Idle		
	0x1	Start a grab		

BUFFER_ID	
RW	This is the ID of the DMA parameters to associate with this grab command.
Value at Reset:	0x0

GRAB_CMD	GRAB CoMma	GRAB CoMmanD		
WO/AutoClr	This is MIL GF	This is MIL GRAB command.		
	automatically e Hardware Snap The GRAB_CM GRAB_CMD_	When the trigger source is set to Immediate mode(Continuous), an exposure sequence will be automatically executed. When the trigger source is set to Software Snapshop mode or Hardware Snapshop mode, GRAB_CMD will act as an ARM. The GRAB_CMD will take around 13 clks to reccord the grab parameters to the SPI fifo. The GRAB_CMD_DONE register may be readed to avoid fifo corruption before sending another Grab command instruction.		
Possible Values:	ossible Values: 0x0 Idle			
	0x1	Start grab command		

31	30	29	28	27	26	25	24
GRAB_CMD_ DONE	ABORT_PET	ABORT_DEL AI	ABORT_DON E		Reserved		TRIGGER_R DY
23	22	21	20	19	18	17	16
Reserved	ABOR	T_MNGR_STA	T(2:0)		TRIG_MNGI	R_STAT(3:0)	
15	14	13	12	11	10	9	8
Reserved	TIMER_MNGR_STAT(2:0)				GRAB_MNG	R_STAT(3:0)	
7	6	5	4	3	2	1	0
Reserved	GRAB_FOT	GRAB_READ OUT	GRAB_EXPO SURE	Reserved	GRAB_PEND ING	GRAB_ACTI VE	GRAB_IDLE

GRAB_CMD_DONE	GRAB CoMmanD DON	GRAB CoMmanD DONE		
RO	The GRAB_CMD will take around 13 clks to reccord the grab parameters to the SPI fifo. This register may be readed to avoid fifo corruption before sending another Grab command instruction.			
Possible Values:	0x0	Grab Command in process		
	0x1	Grab command idle		

ABORT_PET	ABORT during PET	ABORT during PET		
RO		This is the ABORT PET flag. It is set to '1' when an abort is detected in the PETengin phase of the trigger. It is set back to '0' when ABORT DONE is set to '1'.		
Possible Values:	0x0	Abort in PET Phase idle		
	0x1	Abort in PET Phase active		

ABORT_DELAI		
		AI flag. It is set to '1' when an abort is detected in the delai phase of o '0' when ABORT_DONE is set to '1'.
Possible Values:	0x0	Abort in Delai Phase idle
	0x1	Abort in Delai Phase active

ABORT_DONE	ABORT is DO	ABORT is DONE		
RO	This read-only executing.	field indicates the RESET_GRAB command status. If 0, an abort sequence is		
Possible Values:	0x0	Abort sequence not finished yet		
	0x1	Abort DONE, or not started (reset value)		

TRIGGER_RDY	
RO	

ABORT_MNGR_STAT (2:0)	
RO	DEBUG ABORT MANAGER STATE MACHINE

TRIG_MNGR_STAT (3:0)		DEDUCE TRUCCED MANAGED CTATE MACHINE		
RO	DEBUG TRIGGER MANAGER STATE MACHINE			
TIMER_MNGR_STAT (2:0)				
RO	DEBUG TIMER MANAGER STATE MACHINE			
GRAB_MNGR_STAT (3:0)				
RO	DEBUG GRA	B MANAGER STATE MACHINE		
GRAB_FOT	GRAB Field C	Overhead Time		
RO	This is the sens	sor FOT (Field Overhead Time).		
Possible Values:	0x0	Not in FOT		
	0x1	In FOT		
GRAB_READOUT				
RO	This is the sensor readout status. It goes to '1' on the SO_FOT and goes to '0' who			
	datapath decod	ler decodes the end of frame.		
GRAB_EXPOSURE RO	datapath decod	sor integration status Idle		
GRAB_EXPOSURE RO	This is the sens	sor integration status		
GRAB_EXPOSURE RO	This is the sens	sor integration status Idle		
GRAB_EXPOSURE RO Possible Values:	This is the sens	sor integration status Idle		
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING	This is the sens	sor integration status Idle Integrating		
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO	This is the sens	sor integration status Idle Integrating		
GRAB_EXPOSURE RO Possible Values:	This is the sense 0x0 0x1 Grab pending strong stron	sor integration status Idle Integrating status. When this register is set to one, a second grab command is queued in the		
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO	This is the sense 0x0 0x1 Grab pending straight figure 10x0 0x0	sor integration status Idle Integrating status. When this register is set to one, a second grab command is queued in the No grab pending		
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO Possible Values:	This is the sense 0x0 0x1 Grab pending straight figure 10x0 0x0	sor integration status Idle Integrating status. When this register is set to one, a second grab command is queued in the No grab pending		
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO Possible Values: GRAB_ACTIVE	This is the sense 0x0 0x1 Grab pending straight figure 1.0x0 0x1	sor integration status Idle Integrating status. When this register is set to one, a second grab command is queued in the No grab pending		
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO Possible Values:	This is the sense 0x0 0x1 Grab pending strong fpga. 0x0 0x1	sor integration status Idle Integrating status. When this register is set to one, a second grab command is queued in the No grab pending Grab pending		
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO Possible Values: GRAB_ACTIVE RO	This is the sense 0x0 0x1 Grab pending strong fpga. 0x0 0x1	sor integration status Idle Integrating status. When this register is set to one, a second grab command is queued in the No grab pending Grab pending		
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO Possible Values: GRAB_ACTIVE RO GRAB_IDLE	This is the sense 0x0 0x1 Grab pending strong fpga. 0x0 0x1 Grab active stareceived.	sor integration status Idle Integrating status. When this register is set to one, a second grab command is queued in the No grab pending Grab pending		
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO	This is the sense 0x0 0x1 Grab pending strong fpga. 0x0 0x1 Grab active stareceived.	sor integration status Idle Integrating status. When this register is set to one, a second grab command is queued in the No grab pending Grab pending Grab pending ditus. When this register is set to one, at least one grab command has been		

26

31	30	29	28	27	26	25	24
Reserved				FOT_LENGTH_LINE(4:0)			
23	22	21	20	19	18	17	16
			Reserved	Reserved			EO_FOT_SEL
15	14	13	12	11	10	9	8
	FOT_LENGTH(15:8)						
7	6	5	4	3	2	1	0
	FOT_LENGTH(7:0)						

FOT_LENGTH_LINE (4:0) RW	Frame Overhead Time La This is the length of the F	ENGTH LINE Frame Overhead Time in line_time unit.
Value at Reset:	0x0	
Possible Values:	Any Value	Any 16 bit value

EO_FOT_SEL	
RW	This selector selects who will generate the EO_FOT in the controller. When select 0, the EO_FOT is the falling edge detection of the monitor FOT. When select 1, the EO_FOT will be generated inside the controller with programmed FOT_LENGTH.
Value at Reset:	0x0

FOT_LENGTH (15:0)	Frame Overhead Time Ll	ENGTH
		Frame Overhead Time in sys clock. This register is calculated from and LINE_TIME. It is used when EO_FOT_SEL is set to 1.
Value at Reset:	0x0	
Possible Values:	Any Value	Any 16 bit value

READOUT_CFG_FRAME_LIN E

31	30	29	28	27	26	25	24
	Reserved						
23	22	21	20	19	18	17	16
	DUMMY_LINES(7:0)						
15	14	13	12	11	10	9	8
	Reserved CURR_FRAME_LINES(12:8)						
7	6	5	4	3	2	1	0
	CURR_FRAME_LINES(7:0)						

DUMMY_LINES (7:0)	
RW	Number of lines to add in the readout (to debug XGS)
Value at Reset:	0x0

CURR_FRAME_LINES (12:0)	
RO	Current number of lines in the readout calculated by the XGS controller (without FOT).

31	30	29	28	27	26	25	24
	Reserved			READ	OUT_LENGTH	(28:24)	
23	22	21	20	19	18	17	16
	READOUT_LENGTH(23:16)						
15	14	13	12	11	10	9	8
	READOUT_LENGTH(15:8)						
7	6	5	4	3	2	1	0
	READOUT LENGTH(7:0)						

READOUT_LENGTH (28:0)					
	This is the readout length register. This register is calculated by the FPGA in the IRIS4 projectand gives the readout length without the FOT. This register will depend on the ROI, and Subsampling mode. It is used in the PET engin calculations. In Sys Clock domain.				
Possible Values:	Any Value	Any 24 bits value			

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
	Reserved						
15	14	13	12	11	10	9	8
	LINE_TIME(15:8)						
7	6	5	4	3	2	1	0
	LINE_TIME(7:0)						

LINE_TIME (15:0)	LINE TIME	LINE TIME		
RW		This register definel the length of one line of the sensor. It includes blanking and valid time. Line Time Unit is SENSOR Clock Cycles		
Value at Reset:	0x16e	0x16e		
Possible Values:	Any Value	between 1 and 255		

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
	Reserved KEEP_OUT_ TRIG_ENA						
15	14	13	12	11	10	9	8
	KEEP_OUT_TRIG_START(15:8)						
7	6	5	4	3	2	1	0
	KEEP_OUT_TRIG_START(7:0)						

KEEP_OUT_TRIG_ENA	
RW	KEEPOUT zone TRIGger ENAble. When this register is enabled, then the trigger output will be synchronized with the line_int(monitor2) signal from the XGS sensor. To configure this keep out zone, use register READOUT_CFG4.
Value at Reset:	0x0

KEEP_OUT_TRIG_START (15:0)	
RW	During the line time, this register indicates the start of the trigger keep-out zone.
Value at Reset:	0xffff

EXP_CTRL1

31	30	29	28	27	26	25	24
	Reserved		EXPOSURE_ EXPOSURE_SS(27:24) LEV_MODE				
23	22	21	20	19	18	17	16
	EXPOSURE_SS(23:16)						
15	14	13	12	11	10	9	8
	EXPOSURE_SS(15:8)						
7	6	5	4	3	2	1	0
	EXPOSURE_SS(7:0)						

EXPOSURE_LEV_MODE	EXPOSURE LEVel MODE			
RW	This is the exposure level mode selector. When selecting the TRIGGER ACTIVATION = Level Mode, this register selects the exposure method used. When this register is set to '0' the timed mode is selected; Register EXPOSURE_SS is used for the exposure time. When this register is set to '1' the external trigger width is used for the exposure time.			
Value at Reset:	0x0			
Possible Values:	0x0 Timed Mode			
	0x1 Trigger Width			

EXPOSURE_SS (27:0)	EXPOSURE Single Slope				
RW	This is the total exposure time in single/dual/triple slope mode.				
	This register is double buffered.				
Value at Reset:	0x0				
Possible Values:	Any Value	Any 28 bits value			

EXP_CTRL2

31	30	29	28	27	26	25	24
	Rese	erved			EXPOSURE	_DS(27:24)	
23	22	21	20	19	18	17	16
			EXPOSURE	_DS(23:16)			
15	14	13	12	11	10	9	8
			EXPOSURE	E_DS(15:8)			
7	6	5	4	3	2	1	0
			EXPOSUR	E_DS(7:0)			

EXPOSURE_DS (27:0)	EXPOSURE Dual	EXPOSURE Dual				
RW	This is a new 3d profiler feature We will be able to program upto 3 different exposure times (using unused multiSlope registers) Then we will be able to sequence those exposure times. Selection is made with input exposure select.					
Value at Reset:	0x0					
Possible Values:	Any Value	Any 28 bits value				

EXP_CTRL3

31	30	29	28	27	26	25	24
	Reserved				EXPOSURE	_TS(27:24)	
23	22	21	20	19	18	17	16
			EXPOSURE	L_TS(23:16)			
15	14	13	12	11	10	9	8
			EXPOSURE	E_TS(15:8)			
7	6	5	4	3	2	1	0
			EXPOSUR	E_TS(7:0)			

EXPOSURE_TS (27:0)	EXPOSURE Trip	EXPOSURE Tripple				
RW	We will be able to	This is a new 3d profiler feature We will be able to program upto 3 diferent exposure times (using unused multiSlope registers) Then we will be able to sequence those exposure times. Selection is made with input exposure select.				
Value at Reset:	0x0	0x0				
Possible Values:	Any Value	Any 28 bits value				

TRIGGER_DELAY

31	30	29	28	27	26	25	24
	Rese	rved			TRIGGER_D	ELAY(27:24)	
23	22	21	20	19	18	17	16
			TRIGGER_DE	ELAY(23:16)			
15	14	13	12	11	10	9	8
			TRIGGER_D	ELAY(15:8)			
7	6	5	4	3	2	1	0
	TRIGGER_DELAY(7:0)						

TRIGGER_DELAY (27:0)	TRIGGER DELAY				
RW	This is the trigger delay. This trigger delay can be applied to HW(Only edge mode), SW and Continuous mode.				
	In HW level mode, the trigger cannot be delayed, since the level time represents the exposure time.				
	This register is double buffered				
Value at Reset:	0x0				
Possible Values:	Any Value	Any 28 bits value			

STROBE_CTRL1

31	30	29	28	27	26	25	24
STROBE_E	Rese	erved	STROBE_PO L		STROBE_ST	'ART(27:24)	
23	22	21	20	19	18	17	16
			STROBE_ST	ART(23:16)			
15	14	13	12	11	10	9	8
			STROBE_ST	CART(15:8)			
7	6	5	4	3	2	1	0
			STROBE_S	ΓART(7:0)			

STROBE_E	STROBE Enable	STROBE Enable				
RW	This register enables the	he strobe logic.				
	enabled. For Nexis 3 systems, t enabled. For Nexis 3 systems, 5	to enable STROBE_A signal, STROBE_E and STROBE_A_EN must be to enable STROBE_B signal, STROBE_E and STROBE_B_EN must be strong and STROBE_B can be activated at the same time, in this will be the same as they share the same programmation.				
	This register is double	This register is double buffered				
Value at Reset:	0x0					
Possible Values:	0x0	Strobe disabled				
	0x1	Strobe enabled				

STROBE_POL	STROBE POLarity	STROBE POLarity				
RW	This is the strobe polarity	This is the strobe polarity at the pin of the FPGA only for GTR systems.				
	For NEXIS3 systems use register ANPUT\IO\IO_OUT_POL\OUTx_POL This register is not double buffered.					
Value at Reset:	0x0	0x0				
Possible Values:	0x0	Active high strobe				
	0x1	Active low strobe				

STROBE_START (27:0)	STROBE START						
RW	This is the strobe sta	This is the strobe start location. This location depends on the Strobe Mode used.					
	In Strobe Mode='0', the start of the strobe is situated during the exposure time. In Strobe Mode='1', the start of the strobe is situated during the trigger delay. This register is double buffered						
Value at Reset:	0x0						
Possible Values:	Any Value Any 28 bits value						

STROBE_CTRL2

31	30	29	28	27	26	25	24
STROBE_MO DE	Reserved	STROBE_B_ EN	STROBE_A_ EN		STROBE_E	ND(27:24)	
23	22	21	20	19	18	17	16
	STROBE_END(23:16)						
15	14	13	12	11	10	9	8
			STROBE_E	END(15:8)			
7	6	5	4	3	2	1	0
			STROBE_	END(7:0)			

STROBE_MODE	STROBE MODE	STROBE MODE					
RW	This register selec	This register selects the location of the Strobe Start.					
	is set to 0, the STROBE_START register is located during the exposure						
	When this register delay timer.	When this register is set to 1, the STROBE_START register is located during the trigger delay timer.					
	In HW level mode be delayed.	e the strobe mode must be set to STROBE MODE=0 since the trigger cannot					
	This register is do	This register is double buffered					
Value at Reset:	0x0	0x0					
Possible Values:	0x0	Strobe start during exposure					
	0x1	Strobe start during trigger delay					

STROBE_B_EN	STROBE phase B ENable				
RW	This field enables the generation of STROBE_B signal, for a NEXIS 3 system.				
	This register is double buffered to support back2back mode in nexis systems.				
Value at Reset:	0x0				
Possible Values:	0x0 Enable Strobe B				
	0x1 Disable Strobe B				

STROBE_A_EN	STROBE phase A ENable				
RW	This field enables the generation of STROBE_A signal(Default strobe), for a NEXIS 3 system.				
	This register is double buffered to support back2back mode in nexts systems.				
Value at Reset:	0x1				
Possible Values:	0x0 Enable Strobe A (default strobe)				
	0x1 Disable Strobe A				

STROBE_END (27:0)	STROBE END	STROBE END				
RW	This is the strobe end lo	This is the strobe end location. This location does not depend on the Strobe Mode used.				
	This register is double l	This register is double buffered				
Value at Reset:	0xfffffff					
Possible Values:	Any Value	Any 28 bits value				

31	30	29	28	27	26	25	24
	Reserved						
23	22	21	20	19	18	17	16
	Reserved						SER_RWn
15	14	13	12	11	10	9	8
	Reserved					SER_C	MD(1:0)
7	6	5	4	3	2	1	0
	Reserved		SER_RF_SS		Reserved		SER_WF_SS

SER_RWn	SERial Read/V	SERial Read/Writen					
RW	This register co	This register configures the type of the serial access to the CMOS sensor					
Value at Reset:	0x1	0x1					
Possible Values:	0x0	0x0 Write access					
	0x1	Read access					

SER_CMD (1:0)	SERial CoMm	and					
RW	This is the type	This is the type of command sent to the serial fifo.					
		Sensor, write SER_WF_SS=1 with SER_CMD=0x0, with the parametters: ER_ADD(8:0) and SER_DAT(15:0).					
	the parametter following forn 1/62.5mhz. Th To insert a Sto	To insert a timer between fifo commands, write SER_WF_SS=1 with SER_CMD=0x1, with the parametter: SER_DAT(15:0). The value of the timer inserted is calculated with the following formula: Timer= SER_DAT(15:0)*1024*SYS_PERIOD, SYS_PERIOD is 1/62.5mhz. The granularity of the timer is 16.384us To insert a Stop separator command, write SER_WF_SS=1 with SER_CMD=0x3. When the read logic encounter this command, it will stop read from the fifo until a new SER_RF_SS is					
Value at Reset:	0x0						
Possible Values:	0x0	CMOS sensor access COMMAND					
	0x1	Insert timer COMMAND					
	0x2	STOP separator COMMAND					
	0x3 RESERVED						

SER_RF_SS	SERial Read Fifo SnapShot				
	This is the read fifo snapshot. When the read fifo logic receives this snapshot, it will read all the fifo comands until a STOP separator command is read or Empty fifo is detected.				
Possible Values:	0x0 Idle				
	0x1	Start Read FIFO			

SER_WF_SS	SERial Write Fi	SERial Write Fifo SnapShot				
WO/AutoClr	fifo. This fifo ca is a auto reset b	When the system toggle this bit, the address, data and command are wrote to the command fifo. This fifo can contain the entire dcf, so the driver will not need to pool the status bit. This is a auto reset bit register, so after the driver write one, the bit will be auto reset to 0. To start the FIFO read logic write '1' to regsiter SER RF SS.				
Possible Values:	0x0	0x0 Idle				
	0x1	0x1 Write a command to the FIFO				

31	30	29	28	27	26	25	24
			SER_DA	AT(15:8)			
23	22	21	20	19	18	17	16
	SER_DAT(7:0)						
15	14	13	12	11	10	9	8
Reserved				SER_ADD(14:8	3)		
7	6	5	4	3	2	1	0
			SER_A	DD(7:0)			

SER_DAT (15:0)	SERial interface D	SERial interface DATa				
RW		This is the write data to be send to the CMOS sensor by the serial interface, or the config data to a TIMER command or to a POWER sequence command. See register SER CMD.				
Value at Reset:	0x0	0x0				
Possible Values:	Any Value	Any Value Any 16 bits value				

SER_ADD (14:0) RW	SERial interface ADDress This is the read/write address of the register in the CMOS sensor.	
Value at Reset:	0x0	
Possible Values:	Any Value	Any 9 bits value

31	30	29	28	27	26	25	24
			Reserved				SER_FIFO_E MPTY
23	22	21	20	19	18	17	16
			Reserved				SER_BUSY
15	14	13	12	11	10	9	8
	SER_DAT_R(15:8)						
7	6	5	4	3	2	1	0
	SER_DAT_R(7:0)						

SER_FIFO_EMPTY	SERial FIFO EMPTY
RO	This is the EMPTY flag of the xilinx fifo, when '1' there are no pending operations in the fifo.

SER_BUSY	SERial BUSY	7		
RO	SER_RF_SS i	This is the BUSY status of the FIFO read logic. The flag will be set to '1' when the SER_RF_SS is set to '1'. It will be reseted to '0' when the read logic will decode a STOP separator command or when the FIFO will be empty.		
Possible Values:	0x0	FIFO read logic is idle		
	0x1	FIFO read logic is runnning		

SER_DAT_R (15:0)	SERial interface DATa Read		
RO	This is the data read from CMOS sensor.		
Possible Values:	Any Value	Any 16 bits value	

31	30	29	28	27	26	25	24
			Reserved				SENSOR_RE FRESH_TEM P
23	22	21	20	19	18	17	16
			Reserved				SENSOR_PO WERDOWN
15	14	13	12	11	10	9	8
			Reserved				SENSOR_CO LOR
7	6	5	4	3	2	1	0
	Reserved		SENSOR_RE G_UPDATE	Res	erved	SENSOR_RE SETN	SENSOR_PO WERUP

SENSOR_REFRESH_TEMP	SENSOR REFRESH TEI	MPerature
WO/AutoClr	This register starts a sensor temperature read on the serial interface of the Python sensor. The temperature value readed will be available on field SENSOR_TEMP when field SENSOR_TEMP_VALID is set to '1'. [Pas utilise pour le moment dans IRIS4]	
Possible Values:	0x0	Idle
	0x1	Starts a Temperature read on Python SPI interface

SENSOR_POWERDOWN	
	After a PowerUp sequence(SESOR_POWERUP_DONE=1), successfull or not, this register can reset the clock oscillator and enable the reset to the sensor.
	This power down don't do power sequencing.

SENSOR_COLOR	SENSOR COL	LOR		
RW		This register informs the datapath logic that a color sensor is used. This information is needed for the remapper logic.		
Value at Reset:	0x0			
Possible Values:	0x0	Monochrone sensor		
	0x1	Color sensor		

SENSOR_REG_UPDATE	SENSOR REC	SENSOR REGister UPDATE		
RW		By setting this bit to 1, the SENSOR CONTROLLER WILL UPDATE the programed CMOS sensor registers at the beginning of each grab.		
Value at Reset:	0x1			
Possible Values:	0x0	Do not update registers		
	0x1	Update registers		

SENSOR_RESETN	SENSOR RESET Not	SENSOR RESET Not		
RW	After a successfull Pow	After a successfull PowerUP sequence, writing this field to '0' reset the Python CMOS sensor.		
Value at Reset:	0x1			
Possible Values:	0x0	Reset the sensor after a successfull powerUP		
	0x1	Nothing		

SENSOR_POWERUP		
WO/AutoClr	This register Enables the	clk oscillator and removes the reset from the sensor.
Possible Values:	0x0	idle
	0x1	Start the power sequence

31	30	29	28	27	26	25	24
			SENSOR_	ΓΕΜΡ(7:0)			
23	22	21	20	19	18	17	16
SENSOR_TE MP_VALID			Rese	rved			SENSOR_PO WERDOWN
15	14	13	12	11	10	9	8
Reser	rved	SENSOR_RE SETN	SENSOR_OS C_EN		Reserved		SENSOR_VC C_PG
7	6	5	4	3	2	1	0
		Rese	erved			SENSOR_PO WERUP_STA T	SENSOR_PO WERUP_DO NE

SENSOR_TEMP (7:0)	
RO	This register gives the Temperature of the Python sensor after a SENSOR_REFRESH_TEMP snapshot. The field SENSOR_TEMP_VALID indicates when the SENSOR_TEMP value is valid.
	[Pas utilise pour le moment dans IRIS4]
Possible Values:	Any Value

SENSOR_TEMP_VALID	SENSOR TEMPerature	SENSOR TEMPerature VALID		
RO	This field indicates that the field SENSOR_TEMP have valid temperature after a SENSOR_REFRESH_TEMP snapshot.			
	[Pas utilise pour le moment dans IRIS4]			
Possible Values:	0x0	SENSOR_TEMPERATURE register is not valid		
	0x1 SENSOR_TEMPERATURE register is valid			

SENSOR_POWERDOWN		
RO	This field indicates that the sensor is in powerdown state.	
Possible Values:	0x0	Not in powerdown state
	0x1	Powerdown

SENSOR_RESETN	SENSOR RESET N		
RO	This is the sensor RESET	'N status.	
Possible Values:	0x0	In reset state	
	0x1	Not in reset	

SENSOR_OSC_EN	SENSOR OS	SENSOR OSCILLATOR ENable		
RO	This is the se	This is the sensor oscillator enable status.		
Possible Values:	0x0	Disable		
	0x1	Enable		

SENSOR_VCC_PG	SENSOR sur	SENSOR supply VCC Power Good		
RO	This is the V	This is the VCC Power Good status (generated by external HW).		
	[TO BE DEL	ETED, waiting for ON SEMI INFORMATION]		
Possible Values:	0x0	Disable		
	0x1	Enable		

SENSOR_POWERUP_STAT			
RO	When a powerup sequence is finish, this register indicates the result of the POWERUP		
	sequence.		
Possible Values:	PowerUp sequence fail		
	0x1	PowerUp sequence success	

SENSOR_POWERUP_DONE			
	This register indicates that the POWERUP sequence is finish. Read register SENSOR POWERUP STAT to see the result.		
Possible Values:	PowerUp sequence not started		
	0x1	PowerUp sequence finish	

SENSOR_SUBSAMPLING

Address: section "ACQ" base address + 0x09C

0x0

Description:

Value at Reset:

SENSOR ADDRESS

21	20	20	20	27	26	25	2.4
31	30	29	28	27	26	25	24
			Res	served			
23	22	21	20	19	18	17	16
			Res	served			
15	14	13	12	11	10	9	8
			reserve	ed1(11:4)			
7	6	5	4	3	2	1	0
	reserve	ed1(3:0)		ACTIVE_SU BSAMPLING _Y	reserved0	M_SUBSAMP LING_Y	SUBSAMPLI NG_X
reserved1 (11:0)							
STATIC							

ACTIVE_SUBSAMPLING_Y			
RW	Subsampling (Row) for ROI Configurations		
Value at Reset:	0x0		
Possible Values:	x0		
	0x1		

reserved0			
STATIC			
Value at Reset:	0x0		
Possible Values:	0x0	Idle	
	0x1	Enable	

M_SUBSAMPLING_Y		
RW	Subsampling (Row) for M	Region
Value at Reset:	0x0	
Possible Values:	0x0	
	0x1	

SUBSAMPLING_X		
RW	Readout in Column Subsa	ampling Mode
Value at Reset:	0x0	
Possible Values:	0x0	
	0x1	

SENSOR_GAIN_ANA

Address: section "ACQ" base address + 0x0A4

Description:

SENSOR ADDRESS 204 DEC

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
			Rese	rved			
15	14	13	12	11	10	9	8
	reserved1(4:0)			AN	ALOG_GAIN(2	2:0)	
7	6	5	4	3	2	1	0
			reserve	d0(7:0)			
· · · · · · · · · · · · · · · · · · ·	•			·			

reserved1 (4:0)	
STATIC	
Value at Reset:	0x0

ANALOG_GAIN (2:0)		
RW		
Value at Reset:	0x1	
Possible Values:	0x1	1x
	0x3	2x
	0x7	4x

reserved0 (7:0)	
STATIC	
Value at Reset:	0x0

SENSOR_ROI_Y_START

Address: section "ACQ" base address + 0x0A8

Description:

SENSOR ADDRESS

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
			Rese	erved			
15	14	13	12	11	10	9	8
reserved(5:0)						Y_STA	RT(9:8)
7	6	5	4	3	2	1	0
			Y_STA	RT(7:0)			

reserved (5:0)	
STATIC	
Value at Reset:	0x0

Y_START (9:0)	Y START
RW	Y Start in Kernel size (Kernel is 4 lines)
Value at Reset:	0x0

SENSOR_ROI_Y_SIZE

Address: section "ACQ" base address + 0x0AC

Description:

SENSOR ADDRESS

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
			Rese	erved			
15	14	13	12	11	10	9	8
reserved(5:0)						Y_SIZ	ZE(9:8)
7	6	5	4	3	2	1	0
			Y_SIZ	ZE(7:0)			
7 (7 0)							

reserved (5:0)	
STATIC	
Value at Reset:	0x0

Y_SIZE (9:0)	Y SIZE
RW	Y SIZE in Kernel size (Kernel is 4 lines)
Value at Reset:	0x302

SENSOR_M_LINES

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
			Rese	erved			
15	14	13	12	11	10	9	8
M_LINES_DI SPLAY		M_SUPPRESSED(4:0)					
7	6	5	4	3	2	1	0
	M_LINES_SENSOR(7:0)						

M_LINES_DISPLAY	
RW	When setting to 1, the Y_SIZE will have the Black lines included and the first_lines_mask_cnt will be set to 1, to remove only the embedded data
Value at Reset:	0x0

M_SUPPRESSED (4:0)	
RW	Suppress the Readout of Initial Lines in the M Region
Value at Reset:	0x0

M_LINES_SENSOR (9:0)	
RW	Number of Lines to Readout from M Region in Context 0 Unit is #lines
	Total number of Black lines = M_LINES Total number of Black lines transfered as valid Black lines= M_LINES-M_SUPRESSED
Value at Reset:	0x8

SENSOR_DP_GR

Address: section "ACQ" base address + 0x0BC

Description:

Sensor Analog data pedestal for Gr pixels (Black offset)

31	30	29	28	27	26	25	24
	Reserved						
23	22	21	20	19	18	17	16
			Rese	rved			
15	14	13	12	11	10	9	8
	reserved(3:0)				DP_OFFSET	Γ_GR(11:8)	
7	6	5	4	3	2	1	0
			DP_OFFSE	T_GR(7:0)			
	·						

reserved (3:0)	
STATIC	
Value at Reset:	0x0

DP_OFFSET_GR (11:0)	
RW	Sensor Analog data pedestal for Gr pixels (Black offset)
Value at Reset:	0x100

SENSOR_DP_GB

Address: section "ACQ" base address + 0x0C0

Description:

Sensor Analog data pedestal for Gb pixels (Black offset)

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
	Reserved						
15	14	13	12	11	10	9	8
	reserved(3:0) DP_OFFSET_GB(11:8)						
7	6	5	4	3	2	1	0
	DP_OFFSET_GB(7:0)						

reserved (3:0)	
STATIC	
Value at Reset:	0x0

DP_OFFSET_GB (11:0)	
RW	Sensor Analog data pedestal for Gb pixels (Black offset)
Value at Reset:	0x100

SENSOR_DP_R

Address: section "ACQ" base address + 0x0C4

Description:

Sensor Analog data pedestal for R pixels (Black offset)

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
	Reserved						
15	14	13	12	11	10	9	8
	reserved(3:0)				DP_OFFSE	ET_R(11:8)	
7	6	5	4	3	2	1	0
	DP_OFFSET_R(7:0)						

reserved (3:0)	
STATIC	
Value at Reset:	0x0

DP_OFFSET_R (11:0)	
RW	Sensor Analog data pedestal for R pixels (Black offset)
Value at Reset:	0x100

SENSOR_DP_B

Address: section "ACQ" base address + 0x0C8

Description:

Sensor Analog data pedestal for B pixels (Black offset)

31	30	29	28	27	26	25	24
	Reserved						
23	22	21	20	19	18	17	16
	Reserved						
15	14	13	12	11	10	9	8
	reserved(3:0)				DP_OFFSE	ET_B(11:8)	
7	6	5	4	3	2	1	0
	DP_OFFSET_B(7:0)						

reserved (3:0)	
STATIC	
Value at Reset:	0x0

DP_OFFSET_B (11:0)	
RW	Sensor Analog data pedestal for B pixels (Black offset)
Value at Reset:	0x100

SENSOR_GAIN_DIG_G

Address: section "ACQ" base address + 0x0CC

Description:

XGS Context0: R0x3846

31	30	29	28	27	26	25	24
	Reserved						
23	22	21	20	19	18	17	16
	Reserved						
15	14	13	12	11	10	9	8
reserved1			DG	_FACTOR_GR((6:0)		
7	6	5	4	3	2	1	0
reserved0			DG	FACTOR_GB	(6:0)		

reserved1	
STATIC	
Value at Reset:	0x0

DG_FACTOR_GR (6:0)				
RW	Digital Gain Factor for GREEN-R Pixels			
	The digital gain can be configured to separate levels for each color channel (GR, GB, R ar B). The digital gain factor ranges from 1/32 to 2 in steps of 1/32 (64 steps) and its configuration can berepresented by the equation below: Digital gain = Dg_factor/32 Dg_factor=0x20 is unitary gain 1.000 Dg_factor=0x40 is gain x2.00000 Dg_factor=0x01 is gain x0.03125 Dg_factor=0x7f is gain x3.96875			
Value at Reset:	0x20			
Possible Values:	0x1 - 0x7F	Any value in range		

reserved0	
STATIC	
Value at Reset:	0x0

DG_FACTOR_GB (6:0)				
RW	Digital Gain Factor for GREEN-B Pixels			
	The digital gain can be configured to separate levels for each color channel (GR, GB, R and B). The digital gain factor ranges from 1/32 to 2 in steps of 1/32 (64 steps) and its configuration can berepresented by the equation below: Digital gain = Dg_factor/32 Dg_factor=0x20 is unitary gain 1.000 Dg_factor=0x40 is gain x2.00000 Dg_factor=0x01 is gain x0.03125 Dg factor=0x7f is gain x3.96875			
Value at Reset:	0x20			
Possible Values:	0x1 - 0x7F	Any value in range		

SENSOR_GAIN_DIG_RB

Address: section "ACQ" base address + 0x0D0

Description:

XGS Context0: R0x3848

31	30	29	28	27	26	25	24
	Reserved						
23	22	21	20	19	18	17	16
			Rese	erved			
15	14	13	12	11	10	9	8
reserved1	DG_FACTOR_R(6:0)						
7	6	5	4	3	2	1	0
reserved0	DG_FACTOR_B(6:0)						

reserved1	
STATIC	
Value at Reset:	0x0

DG_FACTOR_R (6:0)					
RW	Digital Gain Factor for R	Digital Gain Factor for RED Pixels			
	B). The digital gain factor	ry gain 1.000 x2.00000 x0.03125			
Value at Reset:	0x20				
Possible Values:	0x1 - 0x7F	Any value in range			

reserved0	
STATIC	
Value at Reset:	0x0

DG_FACTOR_B (6:0)					
RW	Digital Gain Factor for	BLUE Pixels			
	B). The digital gain fac configuration can berel Digital gain = Dg_facto Dg_factor=0x20 is unit Dg_factor=0x40 is gain	The digital gain can be configured to separate levels for each color channel (GR, GB, R and B). The digital gain factor ranges from 1/32 to 2 in steps of 1/32 (64 steps) and its configuration can berepresented by the equation below: Digital gain = Dg_factor/32 Dg_factor=0x20 is unitary gain 1.000 Dg_factor=0x40 is gain x2.00000 Dg_factor=0x01 is gain x0.03125			
Value at Reset:	0x20	0x20			
Possible Values:	0x1 - 0x7F	Any value in range			

FPGA_ROI_X_START

31	30	29	28	27	26	25	24	
	Reserved							
23	22	21	20	19	18	17	16	
	Reserved							
15	14	13	12	11	10	9	8	
Reserved					X_START(12:8))		
7	6	5	4	3	2	1	0	
	X_START(7:0)							

X_START (12:0)	X START
RW	X Start in pixels (Kernel is 8 pixels), so 3lsb bits are not used.
Value at Reset:	0x0

FPGA_ROI_X_SIZE

31	30	29	28	27	26	25	24	
	Reserved							
23	22	21	20	19	18	17	16	
	Reserved							
15	14	13	12	11	10	9	8	
	Reserved				X_SIZE(12:8)			
7	6	5	4	3	2	1	0	
	X_SIZE(7:0)							

X_SIZE (12:0)	X SIZE
RW	X SIZE in pixel size (Kernel is 8 pixel), so 3lsb bits are not used.
Value at Reset:	0x0

DEBUG_PINS

31	30	29	28	27	26	25	24
	Reserved				Debug3_sel(4:0)	ı	
23	22	21	20	19	18	17	16
Reserved			Debug2_sel(4:0)				
15	14	13	12	11	10	9	8
	Reserved				Debug1_sel(4:0)	ı	
7	6	5	4	3	2	1	0
	Reserved				Debug0_sel(4:0)		

Debug3_sel (4:0)	
RW	debug_vector(0x0) <= python_monitor0;
	debug_vector(0x1) <= python_monitor1;
	debug_vector(0x2) <= grab_mngr_trig_rdy;
	debug_vector(0x3) <= curr_trig0;
	debug_vector(0x4) <= strobe;
	debug_vector(0x5) <= python_exposure;
	$debug_vector(0x6) \leftarrow FOT;$
	debug_vector(0x7) <= readout;
	debug_vector(0x8) <= readout_stateD;
	debug_vector(0x9) <= ext_trig;
	debug_vector(0xa) <= REGFILE.ACQ.GRAB_CTRL.GRAB_CMD;
	debug_vector(0xb) <= REGFILE.ACQ.GRAB_CTRL.GRAB_SS;
	debug_vector(0xc)<= grab_mngr_trig;
	debug_vector(0xd) <= grab_mngr_trig_rdy;
	debug_vector(0xe) <= grab_pending;
	debug_vector(0xf) <= grab_active;
	debug_vector(0x10) <= DEC_DATA_EN;
	$debug_vector(0x11) \le DEC_SOL;$
	debug_vector(0x12) <= DEC_SOF;
	$debug_vector(0x13) \le DEC_EOL;$
	$debug_vector(0x14) \le DEC_EOF;$
	debug_vector(0x15) <= DEC_CRC;
	debug_vector(0x16) <= DEC_TRAIN;
	debug_vector(0x17) <= fpnprnu_corr_sof;
	debug_vector(0x18) <= fpnprnu_corr_sol;
	debug_vector(0x19) <= fpnprnu_corr_data_val;
	debug_vector(0x1a) <= fpnprnu_corr_eol;
	debug_vector(0x1b) <= fpnprnu_corr_eof;
	debug_vector(0x1c) <= python_ssn_int;
	$debug_vector(0x1d) \le debug_lvds(0);$
	$debug_vector(0x1e) \le debug_lvds(1);$
	$debug_vector(0x1f) \le 'Z';$
Value at Reset:	0x1f

```
Debug2 sel (4:0)
RW
                                    debug\_vector(0x0) \le python\_monitor0;
                                     debug_vector(0x1) <= python_monitor1;
                                    debug_vector(0x2) <= grab_mngr_trig_rdy;
debug_vector(0x3) <= curr_trig0;</pre>
                                     debug_vector(0x4) <= strobe;
                                     debug_vector(0x5) <= python_exposure;
debug_vector(0x6) <= FOT;</pre>
                                     debug vector(0x7) \le readout;
                                     debug_vector(0x8) <= readout_stateD;</pre>
                                     debug_vector(0x9) <= ext_trig;
                                     debug_vector(0xa) <= REGFILE.ACQ.GRAB_CTRL.GRAB_CMD;</pre>
                                     debug_vector(0xb) <= REGFILE.ACQ.GRAB_CTRL.GRAB_SS;</pre>
                                     debug_vector(0xc)<= grab_mngr_trig;</pre>
                                     debug_vector(0xd) <= grab_mngr_trig_rdy;</pre>
                                     debug_vector(0xe) <= grab_pending;</pre>
                                     debug_vector(0xf) <= grab_active;</pre>
                                     debug_vector(0x10) <= DEC_DATA_EN;
debug_vector(0x11) <= DEC_SOL;
                                     debug vector(0x12) <= DEC SOF:
                                     debug_vector(0x13) <= DEC_EOL;
                                    debug_vector(0x14) <= DEC_EOF;
debug_vector(0x15) <= DEC_CRC;
debug_vector(0x16) <= DEC_TRAIN;
                                     debug_vector(0x17) <= fpnprnu_corr_sof;
                                     debug_vector(0x18) <= fpnprnu_corr_sol;
                                     debug_vector(0x19) <= fpnprnu_corr_data_val;
                                     debug_vector(0x1a) <= fpnprnu_corr_eol;
                                     debug vector(0x1b) \le fpnprnu corr eof;
                                     debug_vector(0x1c) <= python_ssn_int;
                                     debug_vector(0x1d) <= debug_lvds(0);</pre>
                                     debug_vector(0x1e) <= debug_lvds(1);
                                     debug\_vector(0x1f) \le 'Z';
Value at Reset:
                                    0x1f
```

```
Debug1_sel (4:0)
RW
                                  debug_vector(0x0) <= python_monitor0;
                                 debug_vector(0x1) <= python_monitor1;
                                  debug_vector(0x2) <= grab_mngr_trig_rdy;
                                  debug_vector(0x3) <= curr_trig0;</pre>
                                  debug_vector(0x4) <= strobe;
                                  debug_vector(0x5) <= python_exposure;
                                 debug vector(0x6) <= FOT;
                                  debug\_vector(0x7) \le readout;
                                  debug_vector(0x8) <= readout_stateD;</pre>
                                  debug vector(0x9) \le ext trig
                                 debug_vector(0xa) <= REGFILE.ACQ.GRAB_CTRL.GRAB_CMD;
                                 debug_vector(0xb) <= REGFILE.ACQ.GRAB_CTRL.GRAB_SS;</pre>
                                  debug_vector(0xc)<= grab_mngr_trig;</pre>
                                  debug_vector(0xd) <= grab_mngr_trig_rdy;</pre>
                                  debug_vector(0xe) <= grab_pending;</pre>
                                 debug_vector(0xf) <= grab_active
                                  debug_vector(0x10) <= DEC_DATA_EN;
                                 debug_vector(0x11) <= DEC_SOL;
debug_vector(0x12) <= DEC_SOF;
debug_vector(0x13) <= DEC_EOL;
                                  debug vector(0x14) <= DEC EOF;
                                  debug_vector(0x15) <= DEC_CRC;
                                  debug_vector(0x16) <= DEC_TRAIN;</pre>
                                  debug_vector(0x17) <= fpnprnu_corr_sof;
                                 debug_vector(0x18) <= fpnprnu_corr_sol;
                                  debug_vector(0x19) <= fpnprnu_corr_data_val;
                                  debug_vector(0x1a) <= fpnprnu_corr_eol;</pre>
                                  debug_vector(0x1b) <= fpnprnu_corr_eof;
                                  debug_vector(0x1c) <= python_ssn_int;</pre>
                                  debug_vector(0x1d) <= debug_lvds(0);
                                  debug_vector(0x1e) <= debug_lvds(1);
                                  debug\_vector(0x1f) \le 'Z';
Value at Reset:
                                 0x1f
```

Debug0_sel (4:0)	
RW	debug_vector(0x0) <= python_monitor0;
	debug_vector(0x1) <= python_monitor1;
	debug_vector(0x2) <= grab_mngr_trig_rdy;
	debug_vector(0x3) <= curr_trig0;
	debug_vector(0x4) <= strobe;
	debug_vector(0x5) <= python_exposure;
	$debug_vector(0x6) \le FOT;$
	debug_vector(0x7) <= readout;
	debug_vector(0x8) <= readout_stateD;
	debug_vector(0x9) <= ext_trig;
	debug_vector(0xa) <= REGFILE.ACQ.GRAB_CTRL.GRAB_CMD;
	debug_vector(0xb) <= REGFILE.ACQ.GRAB_CTRL.GRAB_SS;
	debug_vector(0xc)<= grab_mngr_trig;
	debug_vector(0xd) <= grab_mngr_trig_rdy;
	debug_vector(0xe) <= grab_pending;
	debug_vector(0xf) <= grab_active;
	debug_vector(0x10) <= DEC_DATA_EN;
	debug_vector(0x11) <= DEC_SOL;
	debug_vector(0x12) <= DEC_SOF;
	debug_vector(0x13) <= DEC_EOL;
	debug_vector(0x14) <= DEC_EOF;
	debug_vector(0x15) <= DEC_CRC; debug_vector(0x16) <= DEC_TRAIN;
	debug_vector(0x10) <= DEC_TRAIN, debug_vector(0x17) <= fpnprnu_corr_sof;
	debug_vector(0x17) <= iphiprinu_cori_soi, debug_vector(0x18) <= fpnprinu_cori_soi;
	debug_vector(0x16) <= fpnprnu_corr_data_val;
	debug_vector(0x12) <= fpnprnu_corr_eol;
	debug_vector(0x1b) <= fpnprnu_corr_eof;
	debug_vector(0x1c) <= rpnpma_con_cor, debug_vector(0x1c) <= python_ssn_int;
	debug_vector(0x1d) <= pydron_son_int; debug_vector(0x1d) <= debug_lvds(0);
	$debug_vector(0x1e) \leftarrow debug_lvds(1);$
	$\begin{array}{c} abcdg_{-}(cost)(s) < abcdg_{-}(cost)(s) \\ debug \ vector(0x1f) <= 'Z'; \end{array}$
Value at Reset:	0x1f

TRIGGER_MISSED

31	30	29	28	27	26	25	24
	Reserved		TRIGGER_MI SSED_RST		Rese	rved	
23	22	21	20	19	18	17	16
	Reserved						
15	14	13	12	11	10	9	8
	TRIGGER_MISSED_CNTR(15:8)						
7	6	5	4	3	2	1	0
	TRIGGER_MISSED_CNTR(7:0)						

TRIGGER_MISSED_RST	TRIGGER MISSED ReSeT				
WO/AutoClr	This is the trigger missed reset.				
Possible Values:	0x1 Reset the Trigger counter reset				

TRIGGER_MISSED_CNTR (15:0)	TRIGGER MISSED CouNTeR			
RO	This is the number of trigg	ger missed detected.		
Possible Values:	Any Value			

SENSOR_FPS

31	30	29	28	27	26	25	24
	Reserved						
23	22	21	20	19	18	17	16
	Reserved						
15	14	13	12	11	10	9	8
	SENSOR_FPS(15:8)						
7	6	5	4	3	2	1	0
	SENSOR_FPS(7:0)						

SENSOR_FPS (15:0)	SENSOR Frame Per Second
	This is the number of frames received in 1 second interval. This register can count up to 64k frame/s. This counter counts on SO_FOT event.

SENSOR_FPS2

31	30	29	28	27	26	25	24
	Reserved						
23	22	21	20	19	18	17	16
Reserved			SENSOR_FPS(19:16)				
15	14	13	12	11	10	9	8
	SENSOR_FPS(15:8)						
7	6	5	4	3	2	1	0
	SENSOR_FPS(7:0)						

SENSOR_FPS (19:0)	SENSOR Frame Per Second
	This is the number of frames received in 10 second interval. This register can count up to 1.049 million frames. This counter counts on SO_FOT event.

DEBUG

31	30	29	28	27	26	25	24
	Reserved		DEBUG_RST _CNTR		Rese	rved	
23	22	21	20	19	18	17	16
			Rese	rved			
15	14	13	12	11	10	9	8
			Rese	rved			
7	6	5	4	3	2	1	0
		Reserved			LED_TEST_0	COLOR(1:0)	LED_TEST

DEBUG_RST_CNTR					
RW	This register clears the	This register clears the debug cntrs			
Value at Reset:	0x1	0x1			
Possible Values:	0x0				
	0x1	Reset counters			

LED_TEST_COLOR (1:0)		
RW		
Value at Reset:	0x0	
Possible Values:	0x0	The LED is OFF
	0x1	The LED is GREEN
	0x2	The LED is RED
	0x3	The LED is ORANGE

LED_TEST			
RW	This register will put the LED status in test mode. The test mode is controlled by LED_TEST_COLOR		
Value at Reset:	0x0		
Possible Values:	0x0	The LED is in user mode.	
	0x1	The LED is in test mode.	

DEBUG_CNTR1

31	30	29	28	27	26	25	24
	Reserved			SENSOR_FRAME_DURATION(27:24)			
23	22	21	20	19	18	17	16
		SEN	SOR_FRAME_	DURATION(23	3:16)		
15	14	13	12	11	10	9	8
	SENSOR_FRAME_DURATION(15:8)						
7	6	5	4	3	2	1	0
	SENSOR_FRAME_DURATION(7:0)						

SENSOR_FRAME_DURATI ON (27:0)					
	up to 4.29 seconds. It can profiler heads.				
	This feature is enabled by	setting register regfile.ACQ.DEBUG.DEBUG_RST_CNTR to 0.			
Possible Values:	Any Value	Any 28 bits value			

31	30	29	28	27	26	25	24
	Reserved						
23	22	21	20	19	18	17	16
Reserved						EXP_FOT	
15	14	13	12	11	10	9	8
	Reserved				EXP_FOT_	TIME(11:8)	
7	6	5	4	3	2	1	0
	EXP_FOT_TIME(7:0)						

EXP_FOT	EXPosure during FOT	EXPosure during FOT		
RW	When set to '1' this register, the output exposure and strobe signals will take into account the exposure in the FOT of the frame. This timing must be programmed in register EXP_FOT_TIME. This timing must be calculated from the OnSemi setting files.			
Value at Reset:	0x1			
Possible Values:	0x0 Disable exposure during FOT in output exposure signal and Strob			
	0x1	Enable exposure during FOT in output exposure signal and Strobe		

EXP_FOT_TIME (11:0)	EXPosure during FOT TIME
RW	This is the time of the exposure during the FOT. This timing must be calculated from the OnSemi setting files .
	From DCF v1.2, for all LVDS modes :
	P5000 & P2000 EXP_FOT=40.666us, program value 0x9ee
	P1300 & P500 & P300 EXP_FOT=27.333us, program value 0x6ac
Value at Reset:	0x9ee

ACQ_SFNC

31	30	29	28	27	26	25	24		
	Reserved								
23	22	21	20	19	18	17	16		
	Reserved								
15	14	13	12	11	10	9	8		
			Rese	erved					
7	6	5	4	3	2	1	0		
	Reserved						RELOAD_GR AB PARAMS		

RELOAD_GRAB_PARAMS		
RW	This register is not used for time	the moment. It may be used in the future to reload the exposure
Value at Reset:	0x1	
Possible Values:	0x0	
	0x1	

TIMER_CTRL

31	30	29	28	27	26	25	24	
	Reserved							
23	22	21	20	19	18	17	16	
			Rese	rved				
15	14	13	12	11	10	9	8	
	Reserved							
7	6	5	4	3	2	1	0	
	Reserved		TIMERSTOP		Reserved		TIMERSTAR T	

ADAPTATIVE						
RW	not generate trigger	When this field is set to 1, the timer will adapt the trigger to the trigger_rdy of the controller to not generate trigger missed. When the timer is programmed too fast and the ADAPTATIVE field is set to 0, trigger missed will be generated.				
Value at Reset:	0x1					
Possible Values:	0x0 Non adaptative					
	0x1 Adaptative to trigger_rdy					

TIMERSTOP	
WO/AutoClr	This field stops the internal programmable Timer Trigger

TIMERSTART	
WO/AutoClr	This field starts the internal programmable Timer Trigger.

TIMER_DELAY

31	30	29	28	27	26	25	24		
VALUE(31:24)									
23	22	21	20	19	18	17	16		
	VALUE(23:16)								
15	14	13	12	11	10	9	8		
	VALUE(15:8)								
7	6	5	4	3	2	1	0		
	VALUE(7:0)								

VALUE (31:0)	
RW	This register sets the delay for the first trigger generated when the timer is used.
	This register is double buffered with TimerStart register.
Value at Reset:	0x0

TIMER_DURATION

31	30	29	28	27	26	25	24			
	VALUE(31:24)									
23	22	21	20	19	18	17	16			
	VALUE(23:16)									
15	14	13	12	11	10	9	8			
	VALUE(15:8)									
7	6	5	4	3	2	1	0			
	VALUE(7:0)									

VALUE (31:0)	
RW	This register sets the timer duration. When the counter reaches the value programmed in this register the counter will be reseted to 0. The trigger will be generated when the counter reaches value 0x1. This register is double buffered with TIMERSTART register.
Value at Reset:	0x0

Address Range: [0x400 - 0x454]

CTRL

31	30	29	28	27	26	25	24		
	Reserved								
23	22	21	20	19	18	17	16		
	Reserved								
15	14	13	12	11	10	9	8		
			Rese	erved					
7	6	5	4	3	2	1	0		
Reserved SW_CLR_ID SW_CLR_HIS SW_CALIB_S ENABLE_DA ENABLE_HI ELAYCTRL PI ERDES TA PATH PI						ENABLE_HIS			
			LETTETKE		LIEBER	111_11111	. 1		

SW_CLR_IDELAYCTRL	Reset the Xilinx macro IDELAYCTRL	
RW		
Value at Reset:	0x1	
Possible Values:	0x0	No effect
	0x1	Reset IDELAYCTRL

SW_CLR_HISPI	
RW	
Value at Reset:	0x0

SW_CALIB_SERDES	Initiate the SERDES TAP calibrartion	
WO/AutoClr		
Possible Values:	0x0	No effect
	0x1	Initiate the calibration

ENABLE_DATA_PATH	
RW	
Value at Reset:	0x0

ENABLE_HISPI	
RW	
Value at Reset:	0x0

31	30	29	28	27	26	25	24		
	FSM(3:0)				Reserved				
23	22	21	20	19	18	17	16		
			Rese	erved					
15	14	13	12	11	10	9	8		
			Rese	erved					
7	6	5	4	3	2	1	0		
	Reserved		CRC_ERROR	PHY_BIT_LO CKED_ERRO R	FIFO_ERROR	CALIBRATIO N_ERROR	CALIBRATIO N_DONE		

FSM (3:0)	HISPI finite state machine status				
RO					
Possible Values:	0x0	S_DISABLED			
	0x1	S_IDLE			
	0x2	S_RESET_PHY			
	0x3	S_INIT			
	0x4	S_START_CALIBRATION			
	0x5	S_CALIBRATE			
	0x6	S_PACK			
	0x7	S_FLUSH_PACKER			
	0x8	S_SOF			
	0x9	S_EOF			
	0xA	S_SOL			
	0xB	S_EOL			
	0xC	Reserved			
	0xD	Reserved			
	0xE	FSM error (Unknown state)			
	0xF	S_DONE			

CRC_ERROR	Lane CRC error				
RO					
Possible Values:	0x0	No lane CRC error occured			
	0x1	Lane CRC error occured			

PHY_BIT_LOCKED_ERRO R	
RO	

FIFO_ERROR	Calibration active				
RO					
Possible Values:	0x0	No FiFo error occured			
	0x1	FiFo error occured			

CALIBRATION_ERROR	Calibration error					
RO						
Possible Values:	0x0	No calibration error				
	0x1	A calibration error occured				

CALIBRATION_DONE	Calibration sequence completed					
RO						
Possible Values:	0x0	Calibration sequence not completed				
	0x1	Last calibration sequence completed successfully				

IDELAYCTRL_STATUS

31	30	29	28	27	26	25	24		
	Reserved								
23	22	21	20	19	18	17	16		
	Reserved								
15	14	13	12	11	10	9	8		
			Rese	erved					
7	6	5	4	3	2	1	0		
	Reserved						PLL_LOCKE		

PLL_LOCKED	IDELAYCTR	DELAYCTRL PLL locked				
RO						
Possible Values:	0x0	IDELAYCTRL PLL unlocked				
	0x1	IDELAYCTRL PLL locked				

IDLE_CHARACTER

31	30	29	28	27	26	25	24		
	Reserved								
23	22	21	20	19	18	17	16		
			Rese	erved					
15	14	13	12	11	10	9	8		
	Reserved VALUE(11:8)								
7	6	5	4	3	2	1	0		
	VALUE(7:0)								

VALUE (11:0)		
RW		
Value at Reset:	0x3A6	
Possible Values:	Any Value	

31	30	29	28	27	26	25	24
	Reserved					PIXEL_PER	R_LANE(9:8)
23	22	21	20	19	18	17	16
	PIXEL_PER_LANE(7:0)						
15	14	13	12	11	10	9	8
	Reserved				N	MUX_RATIO(2:	0)
7	6	5	4	3	2	1	0
		Reserved				NB_LANES(2:0))

PIXEL_PER_LANE (9:0)	Number of pixels per lanes			
RW				
Value at Reset:	0xAE			
Possible Values:	Any Value			

MUX_RATIO (2:0)	
STATIC	This is the configuration MUX ratio of the XGS sensor used. For GTX camera the mux ratio is fixed and set to 4.
Value at Reset:	0x4

NB_LANES (2:0)	Number of physical lane enabled			
RW	This is the physical number of HiSPI lanes available for the XGS sensor used. In GTX camera configuration: - Must be set to 4 in XGS5000, XGS3000, XGS2000 and XGS1300. - Must be set to 6 in XGS16M, XGS12M, XGS9.4M and XGS8M XGS1300.			
Value at Reset:	0x0			
Possible Values:	0x0 All lanes are disabled			
	0x4	4 lanes enabled		
0x6 6 lanes enabled		6 lanes enabled		
	Others	Reserved (All lanes are disabled)		

FRAME_CFG

31	30	29	28	27	26	25	24
	Reserved				LINES_PER_1	FRAME(11:8)	
23	22	21	20	19	18	17	16
			LINES_PER_	FRAME(7:0)			
15	14	13	12	11	10	9	8
	Reserved			PIXE	ELS_PER_LINE(12:8)	
7	6	5	4	3	2	1	0
	PIXELS_PER_LINE(7:0)						

LINES_PER_FRAME (11:0)	
RW	This is the total number of lines in a frame including dummy, BL, Interpolation and valid pixels. Reset value is 3102 (XGS12M). The value may change depending on the Black Lines(BL) programmed in the M-LINES section of the frame. Reset value is 3102 (0xc1e, XGS12M)
Value at Reset:	0xc1e

PIXELS_PER_LINE (12:0)	
RW	This is the total number of pixel in a line, including dummy, BL, Interpolation and valid pixels. Reset value is 4176 (0x1050, XGS12M)
Value at Reset:	0x1050

FRAME_CFG_X_VALID

31	30	29	28	27	26	25	24
	Reserved			X_END(12:8)			
23	22	21	20	19	18	17	16
			X_EN	D(7:0)			
15	14	13	12	11	10	9	8
	Reserved				X_START(12:8)		
7	6	5	4	3	2	1	0
	X_START(7:0)						

X_END (12:0)	
RW	This register defines the position of the last horizontal valid pixel (including initials dummy pixels, black reference pixels and interpolation pixels). The location of the last X valid pixel differs between XGS family members and configurations. The dcf will load the location of the X end. It is defined as 1-based number
	For XGS12000, in a monochrome sensor the x end is 4132 (0x1024). For XGS12000, in a color sensor the x end is 4136 (0x1028). (For BAYER correction)
Value at Reset:	0x1023

X_START (12:0)	
RW	This register defines the position of the first horizontal valid pixel (including dummy pixels, black reference pixels and interpolation pixels). The location of the first X valid pixel differs between XGS family members and configurations. The dcf will load the location of the X start. It is defined as 1-based number
	For XGS12000, in a monochrome sensor the x start is 36 (0x24). For XGS12000, in a color sensor the x start is 32 (0x22). (For BAYER correction)
Value at Reset:	0x24

LANE_DECODER_STATUS

(5:0)

Address: section "HISPI" base address + 0x024 + (index * 0x4)

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
	Reserved						
15	14	13	12	11	10	9	8
CRC_ERROR	PHY_SYNC_ ERROR	PHY_BIT_LO CKED_ERRO R			Reserved		CALIBRATIO N_TAP_VAL UE(4)
7	6	5	4	3	2	1	0
					FIFO_UNDE RRUN	FIFO_OVERR UN	

CRC_ERROR	CRC Error		
RW2C			
Value at Reset:	0x0		
Possible Values:	0x0	CRC no error occured	
	0x1	CRC error occured	

PHY_SYNC_ERROR		
RW2C		
Value at Reset:	0x0	
Possible Values:	0x0	Pixel bit boundaries unlocked
	0x1	Pixel bit boundaries locked

PHY_BIT_LOCKED_ERRO		
RW2C		
Value at Reset:	0x0	
Possible Values:	0x0	Pixel bit boundaries unlocked
	0x1	Pixel bit boundaries locked

PHY_BIT_LOCKED		
RO		
Possible Values:	0x0	Pixel bit boundaries unlocked
	0x1	Pixel bit boundaries locked

CALIBRATION_TAP_VALU E (4:0)	
RO	

CALIBRATION_ERROR	
RW2C	
Value at Reset:	0x0
CALIBRATION_DONE	
RO	
FIFO_UNDERRUN	
RW2C	
Value at Reset:	0x0
FIFO_OVERRUN	
RW2C	
Value at Reset:	0v0

TAP_HISTOGRAM (5:0)

Address: section "HISPI" base address + 0x03C + (index * 0x4)

31	30	29	28	27	26	25	24		
	VALUE(31:24)								
23	22	21	20	19	18	17	16		
VALUE(23:16)									
15	14	13	12	11	10	9	8		
	VALUE(15:8)								
7	6	5	4	3	2	1	0		
	VALUE(7:0)								

VALUE (31:0)	
RO	

DEBUG

31	30	29	28	27	26	25	24
	AD_TAPS			AP_LANE_5(4			TAP_LANE_4 (4)
23	22	21	20	19	18	17	16
	TAP_LA				TAP_LAN		
15	14	13	12	11	10	9	8
TAP_LANE_3 (0)		Т	TAP_LANE_2(4:0	0)		TAP_L	ANE_1(4:3)
7	6	5	4	3	2	1	0
TAP_I	LANE_1(2:	0)		,	TAP_LANE_0(4:0)	
MANUAL_CALIB	_EN						
Value at Reset:		0x0					
		•					
LOAD_TAPS							
WO/AutoClr							
1							
TAP_LANE_5 (4:0)						
Value at Reset:		0x0					
		1000					
TAP_LANE_4 (4:0	<u> </u>						
RW	,						
Value at Reset:		0x0					
		•					
TAP_LANE_3 (4:0)						
RW	,						
Value at Reset:		0x0					
TAP_LANE_2 (4:0)						
RW	,						
Value at Reset:		0x0					
TAP_LANE_1 (4:0)						
RW	•						
Value at Reset:		0x0					

TAP_LANE_0 (4:0)	
RW	
Value at Reset:	0x0

Section: DPC

Address Range: [0x480 - 0x498]

DPC_CAPABILITIES

31	30	29	28	27	26	25	24
	Reserved				DPC_LIST_LI	ENGTH(11:8)	
23	22	21	20	19	18	17	16
	DPC_LIST_LENGTH(7:0)						
15	14	13	12	11	10	9	8
	Reserved						
7	6	5	4	3	2	1	0
Reserved				DPC_VI	ER(3:0)		

DPC_LIST_LENGTH (11:0)	
RO	This register defines the maximum number of pixels that can be corrected by the DPC module. (ONE-based). This register is calculated with formula: (2^DPC_CORR_PIXELS_DEPTH)-1, where DPC_CORR_PIXELS_DEPTH is a generic to the DPC module. For GTX value is 511

DPC_VER (3:0)					
RO	Implemented version of the DPC module				
Possible Values:	0x0	Initial monochrone correction only, 2 lines buffered.			

DPC_LIST_CTRL

31	30	29	28	27	26	25	24
Reserved		dpc_fifo_reset	dpc_firstlast_li ne_rem		dpc_list_co	ount(11:8)	
23	22	21	20	19	18	17	16
	dpc_list_count(7:0)						
15	14	13	12	11	10	9	8
dpc_pattern0_ cfg	dpc_enable	dpc_list_WRn	dpc_list_ss		dpc_list_a	ndd(11:8)	
7	6	5	4	3	2	1	0
	dpc_list_add(7:0)						

dpc_fifo_reset					
RW		then '0' to field dpcL_FIFO_RST to reset overrun/underrun flags of the line buffers et the Fifo logic.			
	The DPC dual port ram is not SW reset.				
	The fifo in each	The fifo in each processing DPC unit is HW reset at each SOF.			
Value at Reset:	0x0	0x0			
Possible Values:	0x0	Fifo in normal operation			
	0x1	Fifo in reset State			

dpc_firstlast_line_rem						
RW	corrected. This can be us program two	When this register is set to 1, the DPC macro will remove the first and last line of the image corrected. This can be usefull if we want to correct the 4 pixels in the corners of the image. The SW can program two more lines in the frame so the DPC macro can have enough pixels to correct the 4 pixel coners.				
Value at Reset:	0x0	0x0				
Possible Values:	0x0	0x0 Do not remove any lines of the image received				
	0x1 Remove first and last line of the image received					

dpc_list_count (11:0)				
RW	This is the number of entries in the DPC list. The driver need to set the dcp_list_count in order to correct the image. The value 0 is allowed and when set to 0 no pixel will be corrected. Up to (2^DPC_CORR_PIXELS_DEPTH)-1 pixels can be corrected. If generic DPC_CORR_PIXELS_DEPTH in XGS_Athena module is set to 9, up to 511 pixels may be corrected.			
Value at Reset:	0x0			
Possible Values:	Any Value	0 to 2^DPC_CORR_PIXELS_DEPTH		

dpc_pattern0_cfg					
RW	This field configures the behabieur of the correction pattern 0x0. If this field is set to 0x0 then the current pixel will not be corrected. If this field is set to 0x1 then the current pixel will be replaced by the value 0x3ff (white pixel)				
Value at Reset:	0x0				
Possible Values:	0x0 Do not correct current pixel				
	0x1 Replace current pixel by a white pixel (0x3ff)				

dpc_enable						
RW	Dead Pixel Correction core Enable, when this field is set to 1, the DPC logic will correct all the dead pixels that are listed in the DPC list. The grab must be idle when changing this register.					
Value at Reset:	0x0	0x0				
Possible Values:	0x0 DPC logic is bypassed					
	0x1	DPC logic is enabled				

dpc_list_WRn							
RW	with the dpc_li	This is the Write/ReadN flag. To write to the DPC list set this bit to 1 and start the transaction with the dpc_list_ss field. To read from the DPC list set this bit to 0 and start the transaction with the dpc_list_ss field.					
Value at Reset:	0x0						
Possible Values:	0x0	0x0 Read list operation					
	0x1	0x1 Write list operation					

dpc_list_ss					
WO/AutoClr This is the DPC snapshot. In order to start a write or read transaction the snapsot is writen to '1'. This bit is a auto clear regsiter.					
Possible Values:	0x0	0x0 Do nothing			
	0x1	Start the READ/WRITE transaction			

dpc_list_add (11:0)				
RW	This is the address of the DPC list to be access by the read/write operation. Pixel 0 to correct is located at address b000000. Since the dpc_list_count field is also 6 bit wide, address 0 to 62 of the list can be used. Address 0x3f cannot be used. This DPC location will not be corrected.			
Value at Reset:	0x0			
Possible Values:	Valid DPC adress			

DPC_LIST_STAT

31	30	29	28	27	26	25	24
dpc_fifo_unde rrun	dpc_fifo_overr un		Reserved				
23	22	21	20	19	18	17	16
	Reserved						
15	14	13	12	11	10	9	8
	Reserved						
7	6	5	4	3	2	1	0
			Rese	erved			

dpc_fifo_underrun					
RO		o underrun status of the 2 linebuffers in the dpc macro. Write '1' then '0' to field ST to reset this flag and reset the Fifo logic.			
Possible Values:	0x0	0x0 Underrun not detected			
	0x1	Underrun detected			

dpc_fifo_overrun					
RO		This is the fifo overrun status of the 2 linebuffers in the dpc macro. Write '1' then '0' to field dpc_FIFO_RST to reset this flag and reset the Fifo logic.			
Possible Values:	0x0	Overrun not detected			
	0x1	Overrun detected			

DPC_LIST_DATA1

31	30	29	28	27	26	25	24
Reserved				dpc_list_co	orr_y(11:8)		
23	22	21	20	19	18	17	16
	dpc						
15	14	13	12	11	10	9	8
Reserved				dŗ	oc_list_corr_x(12	:8)	
7	6	5	4	3	2	1	0
dpc_list_corr_x(7:0)							

dpc_list_corr_y (11:0)	
RW	This is Y location of the pixel to be corrected when executing a write to the DPC list.
Value at Reset:	0x0

dpc_list_corr_x (12:0)	
RW	This is X location of the pixel to be corrected when executing a write to the DPC list.
Value at Reset:	0x0

DPC_LIST_DATA2

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
	Reserved						
15	14	13	12	11	10	9	8
	Reserved						
7	6	5	4	3	2	1	0
	dpc_list_corr_pattern(7:0)						

dpc_list_corr_pattern (7:0)	
RW	This is pattern of the pixel to be corrected when executing a write to the DPC list.
	2 bit correction: 34, 17, 136, 68 4 bit correction: 170, 153, 51, 204, 85, 102 6 bit correction: 187,238 (mapped to 170), 119,221 (mapped to 85) 8 bit correction: 255 Set pixel to 255 (white), debug: 0
Value at Reset:	0x0

DPC_LIST_DATA1_RD

31	30	29	28	27	26	25	24
	Rese	rved			dpc_list_co	orr_y(11:8)	
23	22	21	20	19	18	17	16
	dpc_list_corr_y(7:0)						
15	14	13	12	11	10	9	8
Reserved				dŗ	oc_list_corr_x(12	:8)	
7	6	5	4	3	2	1	0
	dpc_list_corr_x(7:0)						

dpc_list_corr_y (11:0)	
RO	This is Y location of the pixel to be corrected when executing a write to the DPC list.

dpc_list_corr_x (12:0)	
RO	This is X location of the pixel to be corrected when executing a write to the DPC list.

DPC_LIST_DATA2_RD

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
	Reserved						
15	14	13	12	11	10	9	8
	Reserved						
7	6	5	4	3	2	1	0
	dpc_list_corr_pattern(7:0)						

dpc_list_corr_pattern (7:0)	
RO	This is pattern of the pixel to be corrected when executing a write to the DPC list.
	2 bit correction: 34, 17, 136, 68 4 bit correction: 170, 153, 51, 204, 85, 102 6 bit correction: 187,238 (mapped to 170), 119,221 (mapped to 85) 8 bit correction: 255 Set pixel to 255 (white), debug: 0

Section: LUT

Address Range: [0x4B0 - 0x4B8]

LUT_CAPABILITIES

31	30	29	28	27	26	25	24
	Rese	rved			LUT_SIZE_C	ONFIG(11:8)	
23	22	21	20	19	18	17	16
	LUT_SIZE_CONFIG(7:0)						
15	14	13	12	11	10	9	8
	Reserved						
7	6	5	4	3	2	1	0
	Reserved				LUT_V	ER(3:0)	

LUT_SIZE_CONFIG (11:0)		
RO		
Possible Values:	0x0	Reserved
	0x1	10 to 8 bits LUT (Mono Only)
	0x2	8 to 8 bits RGB LUT (Color Only)

LUT_VER (3:0)				
RO	Implemented version of the LUT module			
Possible Values:	0x0 Initial monochrone LUT			
	0x1	Initial color LUT		

LUT_CTRL

31	30	29	28	27	26	25	24	
Reserved LUT_BY S				Reserved				
23	22	21	20	19	18	17	16	
			LUT_DAT	'A_W(7:0)				
15	14	13	12	11	10	9	8	
	LUT_SEL(3:0) LUT_WRN LUT_SS LUT_ADD(9:8)							
7	6	5	4	3	2	1	0	
	LUT_ADD(7:0)							

LUT_BYPASS	LUT BYPASS
	When set this register to '1', the LUT logic will not be used, and the 8MSB bits of the input data will send to the DMA. Bypassing the LUT, decrease power comsunption of the fpga.
Value at Reset:	0x0

LUT_DATA_W (7:0)	LUT DATA to Write
RW	Data to write in the LUT.
Value at Reset:	0x0

LUT_SEL (3:0)	LUT SELectio	LUT SELection					
RW	LUT programm	LUT programmation selector.					
Value at Reset:	0x0	0x0					
Possible Values:	0x1	Write Blue LUT(Color only)					
	0x2	Write Green LUT(Color only)					
	0x4	Write Red LUT(Color only)					
	0x8	Write all LUT with same data (Mono or Color)					

LUT_WRN	LUT Write Read	LUT Write ReadNot					
RW	LUT Write mod	LUT Write mode					
Value at Reset:	0x0	0x0					
Possible Values:	0x0	0x0 Read operation					
	0x1	Write operation					

LUT_SS	LUT SnapShot				
WO/AutoClr	Start the LUT READ or WRITE OPERATION				

LUT_ADD (9:0)	
RW	
Value at Reset:	0x0

LUT_RB

31	30	29	28	27	26	25	24	
Reserved								
23	22	21	20	19	18	17	16	
	Reserved							
15	14	13	12	11	10	9	8	
	Reserved							
7	6	5	4	3	2	1	0	
	LUT_RB(7:0)							

LUT_RB (7:0)	
STATIC	Not Implemented to save FPGA ressources
Value at Reset:	0x0

Section: BAYER

Address Range: [0x4C0 - 0x4D4]

BAYER_CFG

31	30	29	28	27	26	25	24		
	Reserved								
23	22	21	20	19	18	17	16		
	Reserved								
15	14	13	12	11	10	9	8		
	Reserved								
7	6	5	4	3	2	1	0		
	Reserved								

BAYER_EN						
RW	This register e	enables the Bayer demosaic and RGB LUT.				
Value at Reset:	0x0	0x0				
Possible Values:	0x0	Output is RAW8				
	0x1	Output is RGB24				

WB_MUL1

31	30	29	28	27	26	25	24		
	WB_MULT_G(15:8)								
23	22	21	20	19	18	17	16		
WB_MULT_G(7:0)									
15	14	13	12	11	10	9	8		
WB_MULT_B(15:8)									
7	6	5	4	3	2	1	0		
	WB_MULT_B(7:0)								

WB_MULT_G (15:0)	
RW	White Balance factor [4].[12]
Value at Reset:	0x1000

WB_MULT_B (15:0)	
RW	White Balance factor [4].[12]
Value at Reset:	0x1000

WB_MUL2

31	30	29	28	27	26	25	24	
	Reserved							
23	22	21	20	19	18	17	16	
	Reserved							
15	14	13	12	11	10	9	8	
	WB_MULT_R(15:8)							
7	6	5	4	3	2	1	0	
	WB_MULT_R(7:0)							

WB_MULT_R (15:0)	
RW	White Balance factor [4].[12]
Value at Reset:	0x1000

WB_B_ACC

31	30	29	28	27	26	25	24
Reserved				B_ACC(30:24)			
23	22	21	20	19	18	17	16
	B_ACC(23:16)						
15	14	13	12	11	10	9	8
	B_ACC(15:8)						
7	6	5	4	3	2	1	0
	B_ACC(7:0)						

B_ACC (30:0)	
RO	ACQuisition Blue ACCumulator

WB_G_ACC

31	30	29	28	27	26	25	24
			G_ACC	C(31:24)			
23	22	21	20	19	18	17	16
	G_ACC(23:16)						
15	14	13	12	11	10	9	8
			G_AC	C(15:8)			
7	6	5	4	3	2	1	0
	G_ACC(7:0)						

G_ACC (31:0)	
RO	ACQuisition Green ACCumulator

WB_R_ACC

31	30	29	28	27	26	25	24
Reserved				R_ACC(30:24)			
23	22	21	20	19	18	17	16
	R_ACC(23:16)						
15	14	13	12	11	10	9	8
			R_AC	C(15:8)			
7	6	5	4	3	2	1	0
	R_ACC(7:0)						

R_ACC (30:0)	
RO	ACQuisition Red ACCumulator

Address Range: [0x700 - 0x7FC]

Description:

Access Xilinx embedded system monitoring module.

See Xilinx UG480

TEMP

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
	Reserved						
15	14	13	12	11	10	9	8
	SMTEMP(11:4)						
7	6	5	4	3	2	1	0
	SMTEMP(3:0) Reserved						

SMTEMP (11:0)	ystem Monitor TEMPerature					
RO	This field reports the temperature of the die. Maximum-measurement error is ± 4 degC. The temperature in Celcius = (SMTEMP*503.975/4096) – 273.15.					
Possible Values:	Any Value					

31	30	29	28	27	26	25	24
	Reserved						
23	22	21	20	19	18	17	16
	Reserved						
15	14	13	12	11	10	9	8
	SMVINT(11:4)						
7	6	5	4	3	2	1	0
	SMVINT(3:0)				Rese	rved	

SMVINT (11:0)	System Monitor VCCINT			
	This field reports voltage for VCCINT supply: VCCINT = (SMVINT/4096)x3V. VCCINT is the core voltage nominally set to 1.0V			
Possible Values:	Any Value			

31	30	29	28	27	26	25	24
			Rese	rved			
23	22	21	20	19	18	17	16
	Reserved						
15	14	13	12	11	10	9	8
	SMVAUX(11:4)						
7	6	5	4	3	2	1	0
	SMVAUX(3:0)				Rese	rved	

SMVAUX (11:0)	System Monitor VCCAUX			
	This field reports voltage for VCCAUX supply: VCCAUX = (SMVAUX/4096)x3V. VCCAUX is the auxiliary voltage nominally set to 1.8V.			
Possible Values:	Any Value			

31	30	29	28	27	26	25	24
			Rese	rved			
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
	SMVBRAM(11:4)						
7	6	5	4	3	2	1	0
	SMVBRAM(3:0)				Rese	rved	

SMVBRAM (11:0)	System Monitor VCCBRAM				
	This field reports voltage for VCCBRAM supply: VCCBRAM = (SMVBRAM/4096)x3V. VCCBRAM is the block RAM supply nominally set to 1.0V.				
Possible Values:	Any Value				

31	30	29	28	27	26	25	24
			Rese	rved			
23	22	21	20	19	18	17	16
	Reserved						
15	14	13	12	11	10	9	8
			SMTMA	X(11:4)			
7	6	5	4	3	2	1	0
	SMTMAX(3:0) Reserved						

SMTMAX (11:0)	System Monitor Temperature MAXimum				
RO	This field reports the maximum temperature that has been measured by on-chip sensor. The maximum temperature (in Celcius) = $(SMTMAX*503.975/4096) - 273.15$.				
Possible Values:	Any Value				

31	30	29	28	27	26	25	24
			Resei	ved			
23	22	21	20	19	18	17	16
	Reserved						
15	14	13	12	11	10	9	8
	SMTMIN(11:4)						
7	6	5	4	3	2	1	0
	SMTMIN(3:0) Reserved						

SMTMIN (11:0)	System Monitor Temperature MINimum				
RO	This field reports the maximum temperature that has been measured by on-chip sensor. The maximum temperature (in Celcius) = (SMTMIN*503.975/4096) – 273.15.				
Possible Values:	Any Value				