Register file structure : regfile_xgs_ctrl.pdf Created by jmansill on 2020/04/01 08:20:09

Register file CRC32:0xAB304108

1. Main Parameters

Register file endianness: little endian

Address bus width: 12 bits Data bus width: 32 bits

2. Memory Map

Section name	Address(es) / Address Ranges	Register name	Access Type
SYSTEM	0x000	ID	R
	0x030	ACQ_CAP	R
ACQ	0x100	GRAB_CTRL	RW
	0x108	GRAB_STAT	R
	0x110	READOUT_CFG1	RW
	0x118	READOUT_CFG2	R
	0x120	READOUT_CFG3	RW
	0x124	READOUT_CFG4	RW
	0x128	EXP_CTRL1	RW
	0x130	EXP_CTRL2	RW
	0x138	EXP_CTRL3	RW
	0x140	TRIGGER_DELAY	RW
	0x148	STROBE_CTRL1	RW
	0x150	STROBE_CTRL2	RW
	0x158	ACQ_SER_CTRL	RW
	0x160	ACQ_SER_ADDATA	RW
	0x168	ACQ_SER_STAT	R
	0x190	SENSOR_CTRL	RW
	0x198	SENSOR_STAT	R
	0x1A0	SENSOR_SUBSAMPLI NG	RW
	0x1A4	SENSOR_GAIN_ANA	RW
	0x1A8	SENSOR_ROI_Y_STA RT	RW
	0x1AC	SENSOR_ROI_Y_SIZE	RW
	0x1B0	SENSOR_ROI2_Y_ST ART	RW
	0x1B4	SENSOR_ROI2_Y_SIZ E	RW
	0x1D8	SENSOR_M_LINES	RW
	0x1DC	SENSOR_F_LINES	RW
	0x1E0	DEBUG_PINS	RW
	0x1E8	TRIGGER_MISSED	RW

Section name	Address(es) / Address Ranges	Register name	Access Type
	0x1F0	SENSOR_FPS	R
	0x2A0	DEBUG	RW
	0x2A8	DEBUG_CNTR1	R
	0x2B0	DEBUG_CNTR2	R
	0x2B4	DEBUG_CNTR3	R
	0x2B8	EXP_FOT	RW
	0x2C0	ACQ_SFNC	RW

3. Registers definition

Section: SYSTEM

Address Range: [0x000 - 0x030]

ID

Address: section "SYSTEM" base address + 0x000

Description:

Static ID

31	30	29	28	27	26	25	24
	StaticID(31:24)						
23	22	21	20	19	18	17	16
	StaticID(23:16)						
15	14	13	12	11	10	9	8
	StaticID(15:8)						
7	6	5	4	3	2	1	0
	StaticID(7:0)						

StaticID (31:0)	MINUTEs of the build	
RO		

Address: section "SYSTEM" base address + 0x030

31	30	29	28	27	26	25	24
			Rese	rved			
23	22	21	20	19	18	17	16
			Rese	rved			
15	14	13	12	11	10	9	8
DPC	EXP_FOT	FPN_73	COLOR		CH_LV	DS(3:0)	
7	6	5	4	3	2	1	0
	Reserved LUT_WIDTH Reserved LUT_PALETTE(1:0)					LETTE(1:0)	

DPC				
STATIC	This field indi	This field indicate if the Dead Pixel Corection is implemented in the fpga.		
Value at Reset:	0x1			
Possible Values:	0x0	DPC is not implemented		
	0x1	DPC is implemented		

EXP_FOT	
STATIC	This field indicate if the Exposure during FOT is implemented in the fpga.
Value at Reset:	0x1

FPN_73	FPN 7.3 corre	FPN 7.3 correction CAP		
RO		This field indicate if the FPN correction 7.3 is implemented instead the default 5.3 in the FPGA acquisition.		
Possible Values:	0x0	0x0 Default 5.3 FPN correction implemented		
	0x1	New 7.3 FPN correction implemented		

COLOR	
RO	This field indicate if the COLOR path is implemented in the FPGA acquisition.

CH_LVDS (3:0)	
RO	This is the number of LVDS DATA channels connected between the CMOS sensor and the
	FPGA. This number does not include the LVDS CTROL channel.

LUT_WIDTH		
RO	This is the LUT width im	plemented in the acquisition core.
Possible Values:	0x0	LUT 10 to 10 Bits
	0x1	LUT 10 to 8 Bits

LUT_PALETTE (1:0)				
RO	This is the nu	This is the number of LUT palette implemented in the acquisition module		
Possible Values:	0x0	No LUT implemented		
	0x1	1 LUT implemented		
	0x2	2 LUT implemented		

Address Range: [0x100 - 0x2CC]

GRAB_CTRL

GRAB ConTRoL Register

Address: section "ACQ" base address + 0x000

0x1

Description:

Grag Control Register

31	30	29	28	27	26	25	24
RESET_GRA B	Reserved	GRAB_ROI2_ EN	ABORT_GR B	RA	Re	served	
23	22	21	20	19	18	17	16
			Reserved				TRIGGER_O VERLAP_BU FFn
15	14	13	12	11	10	9	8
TRIGGER_O VERLAP	TRIGGER_ACT(2:0)		Reserved	TRIGGER_SRC(2:0)		:0)	
7	6	5	4	3	2	1	0
	Reserved		GRAB_SS	Res	erved	BUFFER_ID	GRAB_CMD
RESET_GRAB	i						
RW This register resets the			esets the entir	e python_ctrl.			
Value at Reset:	Value at Reset: 0x0						
Possible Values:	Values: 0x0 Rese			set not active			

GRAB_ROI2_EN				
RW	1) No Y overl 2) Xsize must 3) EOF and S	Enable the second ROI on the frame (KNS). This register is not DB. 1) No Y overlap is allowed 2) Xsize must be the same for the two ROI for the moment(DMA constraint). 3) EOF and SOF in between the two in-frame ROIs will be masked to the DMA. The DMA will see one frame, with the two ROI inside.		
Value at Reset:	0x0	0x0		
Possible Values:	0x0	0x0 Dual ROI disable		
	0x1	Dual ROI enable		

Reset active

ABORT_GRAB	ABORT GRAB	ABORT GRAB		
WO/AutoClr	This is the grab reset, it will reset all the grab queued.			
Possible Values:	0x0 Normal operation			
	0x1	Reset Grab		

TRIGGER_OVERLAP_BUF Fn			
RW	NOT FULLY VALIDATED. DON'T USE. SET IT TO '0'.		
Value at Reset:	0x0		
Possible Values:	0x0	Buffer the trigger received during the dead window in PET mode and execute	
	0x1	The trigger will be ignored during dead window in PET mode.	

TRIGGER_OVERLAP				
RW		This field enables the trigger overlap. In this mode the exposure and the readout of the sensor can be done in parallel for higher framerates.		
Value at Reset:	0x1			
Possible Values:	0x0	Trigger Overlap disable		
	0x1	Trigger Overlap enable (default)		

TRIGGER_ACT (2:0)	TRIGGER AC	Tivation		
RW	source is set to	This is the trigger activation. This register selects the activation of the trigger when the trigger source is set to Hardware Snapshop mode. This register is Double Buffered, so the trigger activation may change from one grab command to another.		
	In activation Level HI/LO with EXPOSURE_MODE register set to Timed, the camera will be triggered in continuous way if the level of the external trigger remains at the LEVEL programmed in this register. In activation Level HI/LO with EXPOSURE_MODE register set to Trigger Width, the Exposure time will be set by the level of the trigger input. The FPGA exposure regsiters will be ignored. The Dual and Triple slope are not supported in the mode.			
Value at Reset:	0x0	0x0		
Possible Values:	0x0	0x0 Rising edge		
	0x1	Falling edge		
	0x2	Rising or Falling edge		
	0x3	Level HI		
	0x4	Level LO		
	0x5 RESERVED 0x6 RESERVED			
	0x7	RESERVED		

TRIGGER_SRC (2:0)	TRIGGER Son	TRIGGER SouRCe			
RW	Double Buffer	This is the trigger source. This register selects the source of the grab trigger. This register is Double Buffered, so the trigger source may change from one grab command to another. TRIGGER_SRC(1) may be seen as a TRIGGER_STATE by the software driver.			
Value at Reset:	0x0	0x0			
Possible Values:	0x0	0x0 RESERVED			
	0x1	Immediate mode (Continuous)			
	0x2	Hardware Snapshop mode			
	0x3 Software Snapshot mode				
	0x4	SFNC mode (auto trig)			

GRAB_SS	GRAB Softwar	GRAB Software Snapshot		
WO/AutoClr	This is the soft mode.	This is the software snapshot register when the trigger source selected is Software Snapshot mode.		
Possible Values:	0x0	0x0 Idle		
	0x1	Start a grab		

BUFFER_ID	
RW	This is the ID of the DMA parameters to associate with this grab command.
Value at Reset:	0x0

GRAB_CMD	GRAB CoMmanD	GRAB CoMmanD		
WO/AutoClr	This is MIL GRAB	This is MIL GRAB command.		
	automatically execu Hardware Snapshop The GRAB_CMD v	When the trigger source is set to Immediate mode(Continuous), an exposure sequence will be automatically executed. When the trigger source is set to Software Snapshop mode or Hardware Snapshop mode, GRAB_CMD will act as an ARM. The GRAB_CMD will take around 13 clks to reccord the grab parametters to the SPI fifo. The GRAB_CMD_DONE register may be readed to avoid fifo corruption before sending another		
Possible Values:	0x0	0x0 Idle		
	0x1	Start grab command		

31	30	29	28	27	26	25	24
GRAB_CMD_ DONE	ABORT_PET	ABORT_DEL AI	ABORT_DON E		Reserved		TRIGGER_R DY
23	22	21	20	19	18	17	16
Reserved	ABORT_MNGR_STAT(2:0)			TRIG_MNGR_STAT(3:0)			
15	14	13	12	11	10	9	8
Reserved	TIMER_MNGR_STAT(2:0)				GRAB_MNG	R_STAT(3:0)	
7	6	5	4	3	2	1	0
Reserved	GRAB_FOT	GRAB_READ OUT	GRAB_EXPO SURE	Reserved	GRAB_PEND ING	GRAB_ACTI VE	GRAB_IDLE

GRAB_CMD_DONE	GRAB CoMmanD DONE		
RO	The GRAB_CMD will take around 13 clks to reccord the grab parameters to the SPI fifo. This register may be readed to avoid fifo corruption before sending another Grab command instruction.		
Possible Values:	0x0 Grab Command in process		
	Ox1 Grab command idle		

ABORT_PET	ABORT during PET		
RO	This is the ABORT PET flag. It is set to '1' when an abort is detected in the PETengin phase of the trigger. It is set back to '0' when ABORT_DONE is set to '1'.		
Possible Values:	0x0 Abort in PET Phase idle		
	0x1	Abort in PET Phase active	

ABORT_DELAI			
	This is the ABORT DELAI flag. It is set to '1' when an abort is detected in the delai phase of the trigger. It is set back to '0' when ABORT_DONE is set to '1'.		
Possible Values:	0x0	Abort in Delai Phase idle	
	0x1	Abort in Delai Phase active	

ABORT_DONE	ABORT is DO	ABORT is DONE		
RO	This read-only executing.	This read-only field indicates the RESET_GRAB command status. If 0, an abort sequence is executing.		
Possible Values:	0x0	0x0 Abort sequence not finished yet		
	0x1	Abort DONE, or not started (reset value)		

TRIGGER_RDY	
RO	

ABORT_MNGR_STAT (2:0)	
RO	DEBUG ABORT MANAGER STATE MACHINE

TRIC MICR CTATE (2.4)			
TRIG_MNGR_STAT (3:0)	DEBUG TRIGGER MANAGER STATE MACHINE		
RO	DEBUG TRIGGER MANAGER STATE MACHINE		
TIMER_MNGR_STAT (2:0)			
D.O.	DEBLIC TIME	R MANAGER STATE MACHINE	
RO	DEBOG TIME	R MANAOLR STATE MACHINE	
GRAB_MNGR_STAT (3:0)			
RO	DEBLIC CRAI	3 MANAGER STATE MACHINE	
NO	DEDUC CICAL	J MANAOLK STATE MACHINE	
GRAB_FOT	GRAB Field O	verhead Time	
RO		or FOT (Field Overhead Time).	
Possible Values:	0x0	Not in FOT	
	0x1	In FOT	
GRAB_READOUT			
011112_112112 0 0 1	This is the sensor readout status. It goes to '1' on the SO_FOT and goes to '0' when the		
RO	This is the sens	or readout status. It goes to '1' on the SO_FOT and goes to '0' when the	
	This is the sens datapath decode	or readout status. It goes to '1' on the SO_FOT and goes to '0' when the er decodes the end of frame.	
GRAB_EXPOSURE	datapath decode	er decodes the end of frame.	
RO	datapath decode	or readout status. It goes to '1' on the SO_FOT and goes to '0' when the er decodes the end of frame. or integration status Idle	
RO GRAB_EXPOSURE RO	This is the sens	or integration status	
GRAB_EXPOSURE RO	This is the sens	or integration status Idle	
GRAB_EXPOSURE RO	This is the sens	or integration status Idle	
GRAB_EXPOSURE RO Possible Values:	This is the sens	or integration status Idle	
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING	This is the sens 0x0 0x1 Grab pending s	or integration status Idle Integrating	
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO	This is the sens 0x0 0x1 Grab pending s fpga.	or integration status Idle Integrating tatus. When this register is set to one, a second grab command is queued in the	
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO	This is the sens 0x0 0x1 Grab pending s fpga. 0x0	or integration status Idle Integrating tatus. When this register is set to one, a second grab command is queued in the No grab pending	
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO Possible Values:	This is the sens 0x0 0x1 Grab pending s fpga. 0x0	or integration status Idle Integrating tatus. When this register is set to one, a second grab command is queued in the No grab pending	
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO	This is the sens 0x0 0x1 Grab pending s fpga. 0x0 0x1	or integration status Idle Integrating tatus. When this register is set to one, a second grab command is queued in the No grab pending	
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO Possible Values:	This is the sens 0x0 0x1 Grab pending s fpga. 0x0 0x1	or integration status Idle Integrating tatus. When this register is set to one, a second grab command is queued in the No grab pending Grab pending	
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO Possible Values:	This is the sens 0x0 0x1 Grab pending s fpga. 0x0 0x1	or integration status Idle Integrating tatus. When this register is set to one, a second grab command is queued in the No grab pending Grab pending	
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO Possible Values: GRAB_ACTIVE RO	This is the sens 0x0 0x1 Grab pending s fpga. 0x0 0x1 Grab active state received.	or integration status Idle Integrating tatus. When this register is set to one, a second grab command is queued in the No grab pending Grab pending	
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO Possible Values: GRAB_ACTIVE RO	This is the sens 0x0 0x1 Grab pending s fpga. 0x0 0x1 Grab active state received.	or integration status Idle Integrating tatus. When this register is set to one, a second grab command is queued in the No grab pending Grab pending Grab pending tus. When this register is set to one, at least one grab command has been	

31	30	29	28	27	26	25	24
Reserved	GRAB_REVX _OVER_RST	GRAB_REVX _OVER	GRAB_REVX	Rese	erved	ROT_LEN	NGTH(9:8)
23	22	21	20	19	18	17	16
			ROT_LEN	IGTH(7:0)			
15	14	13	12	11	10	9	8
			FOT_LEN	GTH(15:8)			
7	6	5	4	3	2	1	0
			FOT_LEN	GTH(7:0)			

GRAB_REVX_OVER_RST	
WO/AutoClr	This field reset the reverseX overrun flag GRAB_REVX_OVER.

GRAB_REVX_OVER		
RO		ftware that a reverseX overrun has been detected. When this status bit will remain at '1' until it is reset by the field RST.
Possible Values:	0x0	No ReverseX Overrun detected
	0x1	At least one ReverseX Overrun was detected

GRAB_REVX	
RW	
Value at Reset:	0x0

ROT_LENGTH (9:0)	Row Overhead Time LENGTH		
STATIC	This is the length of the Row Overhead Time.		
	[NOT USED FOR THE MOMENT- FOR FUTURE USE]		
Value at Reset:	0x0		
Possible Values:	Any Value	Any 8 bits value	

FOT_LENGTH (15:0)	Frame Overhead Time LENGTH		
STATIC	This is the length of the Frame Overhead Time.		
	[NOT USED FOR THE MOMENT- FOR FUTURE USE]		
Value at Reset:	0x0		
Possible Values:	Any Value	Any 16 bit value	

31	30	29	28	27	26	25	24	
	Reserved			READ	OUT_LENGTH	(28:24)		
23	22	21	20	19	18	17	16	
	READOUT_LENGTH(23:16)							
15	14	13	12	11	10	9	8	
	READOUT_LENGTH(15:8)							
7	6	5	4	3	2	1	0	
	READOUT_LENGTH(7:0)							

READOUT_LENGTH (28:0)		
	readout lenght to the grab	register. This register is a register software calculated that gives the engin. This register will depend on the ROI, Subsampling, Binning. It is used in the PET engin calculations. In Sys_Clock domain.
Possible Values:	Any Value	Any 24 bits value

31	30	29	28	27	26	25	24			
	Reserved									
23	22	21	20	19	18	17	16			
Reserved KEEP_C TRIG							KEEP_OUT_ TRIG_ENA			
15	14	13	12	11	10	9	8			
			LINE_TI	ME(15:8)						
7	6	5	4	3	2	1	0			
			LINE_T	IME(7:0)						

KEEP_OUT_TRIG_ENA	
	KEEPOUT zone TRIGger ENAble. When this register is enabled, then the trigger output will be synchronized with the line_int(monitor2) signal from the XGS sensor. To configure this keep out zone, use register READOUT_CFG4.
Value at Reset:	0x0

LINE_TIME (15:0)	LINE TIME			
RW	Line Time Unit is SENSOR Clock Cycles			
Value at Reset:	0x16e			
Possible Values:	Any Value	between 1 and 255		

31	30	29	28	27	26	25	24		
KEEP_OUT_TRIG_END(15:8)									
23	22	21	20	19	18	17	16		
	KEEP_OUT_TRIG_END(7:0)								
15	14	13	12	11	10	9	8		
	KEEP_OUT_TRIG_START(15:8)								
7	6	5	4	3	2	1	0		
			KEEP_OUT_TR	LIG_START(7:0)					

KEEP_OUT_TRIG_END (15:0)	
RW	During the line time, this register indicates the end of the trigger keep-out zone.
Value at Reset:	0x16d

KEEP_OUT_TRIG_START (15:0)	
RW	During the line time, this register indicates the start of the trigger keep-out zone.
Value at Reset:	0x16e

EXP_CTRL1

31	30	29	28	27	26	25	24	
	Reserved		EXPOSURE_ LEV_MODE					
23	22	21	20	19	18	17	16	
	EXPOSURE_SS(23:16)							
15	14	13	12	11	10	9	8	
	EXPOSURE_SS(15:8)							
7	6	5	4	3	2	1	0	
	EXPOSURE_SS(7:0)							

EXPOSURE_LEV_MODE	EXPOSURE LEVel MODE						
RW	This is the exposure level mode selector. When selecting the TRIGGER ACTIVATION = Level Mode, this register selects the exposure method used. When this register is set to '0' the timed mode is selected; Register EXPOSURE_SS is used for the exposure time. When this register is set to '1' the external trigger width is used for the exposure time.						
Value at Reset:	0x0						
Possible Values:	0x0 Timed Mode						
	0x1						

EXPOSURE_SS (27:0)	EXPOSURE Single Slope				
RW	This is the total exposure time in single/dual/triple slope mode.				
	This register is double buffered.				
Value at Reset:	0x0				
Possible Values:	Any Value	Any 28 bits value			

EXP_CTRL2

31	30	29	28	27	26	25	24	
	Reserved				EXPOSURE	L_DS(27:24)		
23	22	21	20	19	18	17	16	
	EXPOSURE_DS(23:16)							
15	14	13	12	11	10	9	8	
	EXPOSURE_DS(15:8)							
7	6	5	4	3	2	1	0	
	EXPOSURE_DS(7:0)							

EXPOSURE_DS (27:0)	EXPOSURE Dual	EXPOSURE Dual			
RW	We will be able to	This is a new 3d profiler feature We will be able to program upto 3 diferent exposure times (using unused multiSlope registers) Then we will be able to sequence those exposure times. Selection is made with input exposure select.			
Value at Reset:	0x0	0x0			
Possible Values:	Any Value	Any 28 bits value			

EXP_CTRL3

31	30	29	28	27	26	25	24
	Reserved			EXPOSURE_TS(27:24)			
23	22	21	20	19	18	17	16
			EXPOSURE	L_TS(23:16)			
15	14	13	12	11	10	9	8
	EXPOSURE_TS(15:8)						
7	6	5	4	3	2	1	0
	EXPOSURE_TS(7:0)						

EXPOSURE_TS (27:0)	EXPOSURE Tripple	EXPOSURE Tripple			
RW	This is a new 3d profiler feature We will be able to program upto 3 different exposure times (using unused multiSlope registers) Then we will be able to sequence those exposure times. Selection is made with input exposure select.				
Value at Reset:	0x0				
Possible Values:	Any Value	Any 28 bits value			

TRIGGER_DELAY

31	30	29	28	27	26	25	24
	Reserved			TRIGGER_DELAY(27:24)			
23	22	21	20	19	18	17	16
			TRIGGER_DI	ELAY(23:16)			
15	14	13	12	11	10	9	8
	TRIGGER_DELAY(15:8)						
7	6	5	4	3	2	1	0
			TRIGGER_D	DELAY(7:0)			

TRIGGER_DELAY (27:0)	TRIGGER DELAY			
RW	This is the trigger delay. This trigger delay can be applied to HW(Only edge mode), SW and Continuous mode.			
	In HW level mode, the trigger cannot be delayed, since the level time represents the exposure time.			
	This register is double buffered			
Value at Reset:	0x0			
Possible Values:	Any Value	Any 28 bits value		

STROBE_CTRL1

31	30	29	28	27	26	25	24
STROBE_E	Rese	erved	STROBE_PO L		STROBE_ST	ART(27:24)	
23	22	21	20	19	18	17	16
			STROBE_STA	ART(23:16)			
15	14	13	12	11	10	9	8
	STROBE_START(15:8)						
7	6	5	4	3	2	1	0
			STROBE_ST	ΓART(7:0)			

STROBE_E	STROBE Enable	STROBE Enable			
RW	This register enal	This register enables the strobe logic.			
	enabled. For Nexis 3 syste enabled. For Nexis 3 syste	For Nexis 3 systems, to enable STROBE_B signal, STROBE_E and STROBE_B_EN must			
	This register is do	This register is double buffered			
Value at Reset:	0x0	0x0			
Possible Values:	0x0	Strobe disabled			
	0x1	Strobe enabled			

STROBE_POL	STROBE POLarity	STROBE POLarity		
RW	This is the strobe polarity	This is the strobe polarity at the pin of the FPGA only for GTR systems.		
	For NEXIS3 systems use register ANPUT\IO\IO_OUT_POL\OUTx_POL This register is not double buffered.			
Value at Reset:	0x0	0x0		
Possible Values:	0x0	Active high strobe		
	0x1	Active low strobe		

STROBE_START (27:0)	STROBE START	STROBE START			
RW	This is the strobe start le	This is the strobe start location. This location depends on the Strobe Mode used.			
	In Strobe Mode='0', the start of the strobe is situated during the exposure time. In Strobe Mode='1', the start of the strobe is situated during the trigger delay. This register is double buffered				
Value at Reset:	0x0	0x0			
Possible Values:	Any Value Any 28 bits value				

STROBE_CTRL2

31	30	29	28	27	26	25	24
STROBE_MO DE	Reserved	STROBE_B_ EN	STROBE_A_ EN		STROBE_E	ND(27:24)	
23	22	21	20	19	18	17	16
	STROBE_END(23:16)						
15	14	13	12	11	10	9	8
	STROBE_END(15:8)						
7	6	5	4	3	2	1	0
	STROBE_END(7:0)						

STROBE_MODE	STROBE MODE	STROBE MODE			
RW	This register selec	This register selects the location of the Strobe Start.			
	When this register timer.	is set to 0, the STROBE_START register is located during the exposure			
	When this register delay timer.	When this register is set to 1, the STROBE_START register is located during the trigger delay timer.			
	In HW level mode be delayed.	e the strobe mode must be set to STROBE MODE=0 since the trigger cannot			
	This register is do	This register is double buffered			
Value at Reset:	0x0				
Possible Values:	0x0	Strobe start during exposure			
	0x1	Strobe start during trigger delay			

STROBE_B_EN	STROBE phase B ENable			
RW	This field enables the generation of STROBE_B signal, for a NEXIS 3 system.			
	This register is double buffered to support back2back mode in nexis systems.			
Value at Reset:	0x0			
Possible Values:	0x0 Enable Strobe B			
	0x1	Disable Strobe B		

STROBE_A_EN	STROBE phase A ENable				
RW	This field enables the generation of STROBE_A signal(Default strobe), for a NEXIS 3 system.				
	This register is double buffered to support back2back mode in nexis systems.				
Value at Reset:	0x1				
Possible Values:	0x0 Enable Strobe A (default strobe)				
	0x1	Disable Strobe A			

STROBE_END (27:0)	STROBE END	STROBE END				
RW	This is the strobe end lo	This is the strobe end location. This location does not depend on the Strobe Mode used.				
	This register is double l	This register is double buffered				
Value at Reset:	0xfffffff	0xfffffff				
Possible Values:	Any Value	Any 28 bits value				

31	30	29	28	27	26	25	24
	Reserved						
23	22	21	20	19	18	17	16
			Reserved				SER_RWn
15	14	13	12	11	10	9	8
	Reserved				SER_C	MD(1:0)	
7	6	5	4	3	2	1	0
	Reserved		SER_RF_SS		Reserved		SER_WF_SS

SER_RWn	SERial Read/V	SERial Read/Writen				
RW	This register co	This register configures the type of the serial access to the CMOS sensor				
Value at Reset:	0x1	0x1				
Possible Values:	0x0	0x0 Write access				
	0x1	Read access				

SER_CMD (1:0)	SERial CoMma	and				
RW	This is the type	This is the type of command sent to the serial fifo.				
		ensor, write SER_WF_SS=1 with SER_CMD=0x0, with the parametters: R_ADD(8:0) and SER_DAT(15:0).				
	the parametter: following form 1/62.5mhz. The	or between fifo commands, write SER_WF_SS=1 with SER_CMD=0x1, with SER_DAT(15:0). The value of the timer inserted is calculated with the ula: Timer= SER_DAT(15:0)*1024*SYS_PERIOD, SYS_PERIOD is granularity of the timer is 16.384us o separator command, write SER_WF_SS=1 with SER_CMD=0x3. When the unter this command, it will stop read from the fifo until a new SER_RF_SS is				
	received.					
Value at Reset:	0x0	0x0				
Possible Values:	0x0	0x0 CMOS sensor access COMMAND				
	0x1	Insert timer COMMAND				
	0x2	0x2 STOP separator COMMAND				
	0x3	RESERVED				

SER_RF_SS	SERial Read Fifo SnapSh	SERial Read Fifo SnapShot			
	This is the read fifo snapshot. When the read fifo logic receives this snapshot, it will read all the fifo comands until a STOP separator command is read or Empty fifo is detected.				
Possible Values:	0x0 Idle				
	0x1	Start Read FIFO			

SER_WF_SS	SERial Write Fifo SnapS	SERial Write Fifo SnapShot		
WO/AutoClr	When the system toggle this bit, the address, data and command are wrote to the command fifo. This fifo can contain the entire dcf, so the driver will not need to pool the status bit. This is a auto reset bit register, so after the driver write one, the bit will be auto reset to 0. To start the FIFO read logic write '1' to regsiter SER RF SS.			
Possible Values:	0x0 0x1	Idle Write a command to the FIFO		

31	30	29	28	27	26	25	24
	SER_DAT(15:8)						
23	22	21	20	19	18	17	16
			SER_D	AT(7:0)			
15	14	13	12	11	10	9	8
Reserved	SER_ADD(14:8)						
7	6	5	4	3	2	1	0
	SER_ADD(7:0)						

SER_DAT (15:0)	SERial interface D	SERial interface DATa				
RW		This is the write data to be send to the CMOS sensor by the serial interface, or the config data to a TIMER command or to a POWER sequence command. See register SER CMD.				
Value at Reset:	0x0	0x0				
Possible Values:	Any Value	Any 16 bits value				

SER_ADD (14:0) RW	SERial interface ADDress This is the read/write address of the register in the CMOS sensor.			
Value at Reset:	0x0			
Possible Values:	Any Value	Any 9 bits value		

31	30	29	28	27	26	25	24
			Reserved				SER_FIFO_E MPTY
23	22	21	20	19	18	17	16
			Reserved				SER_BUSY
15	14	13	12	11	10	9	8
			SER_DA	T_R(15:8)			
7	6	5	4	3	2	1	0
			SER_DA	T_R(7:0)			

SER_FIFO_EMPTY	SERial FIFO EMPTY
RO	This is the EMPTY flag of the xilinx fifo, when '1' there are no pending operations in the fifo.

SER_BUSY	SERial BUS	SERial BUSY		
RO	SER_RF_SS	This is the BUSY status of the FIFO read logic. The flag will be set to '1' when the SER_RF_SS is set to '1'. It will be reseted to '0' when the read logic will decode a STOP separator command or when the FIFO will be empty.		
Possible Values:	0x0	0x0 FIFO read logic is idle		
	0x1	FIFO read logic is runnning		

SER_DAT_R (15:0)	SERial interface DATa R	ERial interface DATa Read		
RO	This is the data read from	This is the data read from CMOS sensor.		
Possible Values:	Any Value	Any 16 bits value		

31	30	29	28	27	26	25	24
			Reserved				SENSOR_RE FRESH_TEM P
23	22	21	20	19	18	17	16
			Reserved				SENSOR_PO WERDOWN
15	14	13	12	11	10	9	8
			Reserved				SENSOR_CO LOR
7	6	5	4	3	2	1	0
	Reserved		SENSOR_RE G_UPTATE	Rese	erved	SENSOR_RE SETN	SENSOR_PO WERUP

SENSOR_REFRESH_TEMP	SENSOR REFRESH TE	SENSOR REFRESH TEMPerature		
	This register starts a sensor temperature read on the serial interface of the Python sensor. The temperature value readed will be available on field SENSOR_TEMP when field SENSOR TEMP VALID is set to '1'.			
Possible Values:	0x0 Idle			
	0x1	Starts a Temperature read on Python SPI interface		

SENSOR_POWERDOWN	
WO/AutoClr	After a PowerUp sequence(SESOR_POWERUP_DONE=1), successfull or not, this register can reset the clock oscillator and enable the reset to the sensor.
	This power down don't do power sequencing.

SENSOR_COLOR	SENSOR CO	SENSOR COLOR		
RW		This register informs the datapath logic that a color sensor is used. This information is needed for the remapper logic.		
Value at Reset:	0x0			
Possible Values:	0x0	0x0 Monochrone sensor		
	0x1	Color sensor		

SENSOR_REG_UPTATE	SENSOR REGister UPD	ATE	
RW	By setting this bit to 1, the SENSOR CONTROLLER WILL UPDATE the programed CMOS sensor registers at the beginning of each grab.		
Value at Reset:	0x1		
Possible Values:	0x0 Do not update registers		
	0x1	Update registers	

SENSOR_RESETN	SENSOR RESI	SENSOR RESET Not		
RW	After a success	After a successfull PowerUP sequence, writing this field to '0' reset the Python CMOS sensor.		
Value at Reset:	0x1			
Possible Values:	0x0	Reset the sensor after a successfull powerUP		
	0x1	Nothing		

SENSOR_POWERUP			
WO/AutoClr	This register Enables the clk oscillator and removes the reset from the sensor.		
Possible Values:	0x0 idle		
	0x1	Start the power sequence	

31	30	29	28	27	26	25	24
			SENSOR_7	ΓΕΜΡ(7:0)			
23	22	21	20	19	18	17	16
SENSOR_TE MP_VALID			Rese	rved			SENSOR_PO WERDOWN
15	14	13	12	11	10	9	8
Rese	rved	SENSOR_RE SETN	SENSOR_OS C_EN		Reserved		SENSOR_VC C_PG
7	6	5	4	3	2	1	0
	Reserved SENSOR_PO WERUP_STA T						

SENSOR_TEMP (7:0)		
RO		mperature of the Python sensor after a SENSOR_REFRESH_TEMP OR_TEMP_VALID indicates when the SENSOR_TEMP value is
Possible Values:	Any Value	

SENSOR_TEMP_VALID	SENSOR TEMPerature VALID		
RO	This field indicates that the field SENSOR_TEMP have valid temperature after a SENSOR_REFRESH_TEMP snapshot.		
Possible Values:	0x0 SENSOR_TEMPERATURE register is not valid		
	0x1	SENSOR_TEMPERATURE register is valid	

SENSOR_POWERDOWN				
RO	This field indicates that the sensor is in powerdown state.			
Possible Values:	0x0 Not in powerdown state			
	0x1	Powerdown		

SENSOR_RESETN	SENSOR RESET N				
RO	This is the sensor RESETN status.				
Possible Values:	0x0 In reset state				
	0x1 Not in reset				

SENSOR_OSC_EN	SENSOR OSCILLATOR ENable					
RO	This is the sensor oscillator enable status.					
Possible Values:	0x0 Disable					
	Ox1 Enable					

SENSOR_VCC_PG	SENSOR supply VCC Power Good				
RO	This is the VCC Power C	This is the VCC Power Good status (generated by external HW).			
Possible Values:	0x0 Disable				
	0x1	Enable			

SENSOR_POWERUP_STAT		
RO	When a powerup sequence	ce is finish, this register indicates the result of the POWERUP
	sequence.	
Possible Values:	0x0	PowerUp sequence fail
	0x1	PowerUp sequence success

SENSOR_POWERUP_DONE		
RO	This register indicates tha SENSOR_POWERUP_S	t the POWERUP sequence is finish. Read register TAT to see the result.
Possible Values:	0x0	PowerUp sequence not started
	0x1	PowerUp sequence finish

SENSOR_SUBSAMPLING

Address: section "ACQ" base address + 0x0A0

0x0

Description:

Value at Reset:

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
			Re	served			
15	14	13	12	11	10	9	8
	reserved1(11:4)						
7	6	5	4	3	2	1	0
	reserve	ed1(3:0)		ACTIVE_SU BSAMPLING _Y	reserved0	M_SUBSAMP LING_Y	SUBSAMPLI NG_X
reserved1 (11:0)							
STATIC							

ACTIVE_SUBSAMPLIN	G_Y
RW	Subsampling (Row) for ROI Configurations
Value at Reset:	0x0
Possible Values:	0x0
	0x1

reserved0		
STATIC		
Value at Reset:	0x0	
Possible Values:	0x0	Idle
	0x1	Enable

M_SUBSAMPLING_Y		
RW	Subsampling (Row) for M	I Region
Value at Reset:	0x0	
Possible Values:	0x0	
	0x1	

SUBSAMPLING_X		
RW	Readout in Column Subsa	ampling Mode
Value at Reset:	0x0	
Possible Values:	0x0	
	0x1	

SENSOR_GAIN_ANA

Address: section "ACQ" base address + 0x0A4

Description:

SENSOR ADDRESS 204 DEC

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
	Reserved						
15	14	13	12	11	10	9	8
	reserved1(4:0) ANALOG_GAIN(2:0)					2:0)	
7	6	5	4	3	2	1	0
reserved0(7:0)							

reserved1 (4:0)	
STATIC	
Value at Reset:	0x0

ANALOG_GAIN (2:0)		
RW		
Value at Reset:	0x1	
Possible Values:	0x1	1x
	0x3	2x
	0x7	4x

reserved0 (7:0)	
STATIC	
Value at Reset:	0x0

SENSOR_ROI_Y_START

Address: section "ACQ" base address + 0x0A8

Description:

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
			Rese	erved			
15	14	13	12	11	10	9	8
	reserved(5:0)					Y_STA	RT(9:8)
7	6	5	4	3	2	1	0
			Y_STA	RT(7:0)			
							_

reserved (5:0)	
STATIC	
Value at Reset:	0x0

Y_START (9:0)	START			
RW	Y Start in Kernel size (Kernel is 4 lines)			
Value at Reset:	0x0			

SENSOR_ROI_Y_SIZE

Address: section "ACQ" base address + 0x0AC

Description:

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
			Rese	erved			
15	14	13	12	11	10	9	8
	reserved(5:0)					Y_SIZE(9:8)	
7	6	5	4	3	2	1	0
			Y_SIZ	ZE(7:0)			
reserved (5:0)							

reserved (5:0)	
STATIC	
Value at Reset:	0x0

Y_SIZE (9:0)	Y SIZE
RW	Y SIZE in Kernel size (Kernel is 4 lines)
Value at Reset:	0x302

SENSOR_ROI2_Y_START

Address: section "ACQ" base address + 0x0B0

Description:

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
			Rese	erved			
15	14	13	12	11	10	9	8
	reserved(5:0)					Y_STA	RT(9:8)
7	6	5	4	3	2	1	0
			Y_STA	RT(7:0)			

reserved (5:0)	
STATIC	
Value at Reset:	0x0

Y_START (9:0)	START			
RW	Y Start in Kernel size (Kernel is 4 lines)			
Value at Reset:	0x0			

SENSOR_ROI2_Y_SIZE

Address: section "ACQ" base address + 0x0B4

0x0

Description:

SENSOR ADDRESS

Value at Reset:

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
			Rese	erved			
15	14	13	12	11	10	9	8
	reserved(5:0)					Y_SIZE(9:8)	
7	6	5	4	3	2	1	0
			Y_SIZ	ZE(7:0)			
reserved (5:0)							
STATIC STATIC							

Y_SIZE (9:0)	Y SIZE
RW	Y SIZE in Kernel size (Kernel is 4 lines)
Value at Reset:	0x302

SENSOR_M_LINES

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
			Rese	erved			
15	14	13	12	11	10	9	8
Reserved	M_SUPPRESSED(4:0) M_LINES_SENSOR(9:8)						
7	6	5	4	3	2	1	0
	M_LINES_SENSOR(7:0)						

M_SUPPRESSED (4:0)	
RW	Suppress the Readout of Initial Lines in the M Region
Value at Reset:	0x0

M_LINES_SENSOR (9:0)	
RW	Number of Lines to Readout from M Region in Context 0 Unit is #lines
	Total number of Black lines = M_LINES-M_SUPRESSED
Value at Reset:	0x8

SENSOR_F_LINES

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
			Rese	erved			
15	14	13	12	11	10	9	8
Reserved	F_SUPPRESSED(4:0) F_LINES_SENSOR(9:8)			ENSOR(9:8)			
7	6	5	4	3	2	1	0
	F_LINES_SENSOR(7:0)						

F_SUPPRESSED (4:0)	
RW	Suppress the Readout of Initial Lines in the F Region, Unit is #lines
Value at Reset:	0x0

F_LINES_SENSOR (9:0)	
RW	Number of Lines to Read from F Region in Context 0 Unit is #lines
Value at Reset:	0x8

DEBUG_PINS

Address: section "ACQ" base address + 0x0E0

31	30	29	28	27	26	25	24
	Reserved				Debug3_sel(4:0)		
23	22	21	20	19	18	17	16
	Reserved				Debug2_sel(4:0)		
15	14	13	12	11	10	9	8
	Reserved				Debug1_sel(4:0)		
7	6	5	4	3	2	1	0
	Reserved				Debug0_sel(4:0)		

Debug3_sel (4:0)	
RW	debug_vector(0x0) <= python_monitor0;
	debug_vector(0x1) <= python_monitor1;
	debug_vector(0x2) <= grab_mngr_trig_rdy;
	debug_vector(0x3) <= curr_trig0;
	$debug_vector(0x4) \le strobe;$
	debug_vector(0x5) <= python_exposure;
	$\frac{g}{g}$ debug_vector(0x6) <= FOT;
	$debug_vector(0x7) \le readout;$
	debug_vector(0x8) <= readout_stateD;
	debug_vector(0x9) <= ext_trig;
	debug_vector(0xa) <= REGFILE.ACQ.GRAB_CTRL.GRAB_CMD;
	debug_vector(0xb) <= REGFILE.ACQ.GRAB_CTRL.GRAB_SS;
	debug_vector(0xc)<= grab_mngr_trig;
	debug_vector(0xd) <= grab_mngr_trig_rdy;
	debug_vector(0xe) <= grab_pending;
	debug_vector(0xf) <= grab_active;
	debug_vector(0x10) <= DEC_DATA_EN;
	debug_vector(0x11) <= DEC_SOL;
	debug_vector(0x12) <= DEC_SOF;
	debug_vector(0x13) <= DEC_EOL;
	debug_vector(0x14) <= DEC_EOF;
	$debug_vector(0x15) \le DEC_CRC;$
	debug_vector(0x16) <= DEC_TRAIN;
	debug_vector(0x17) <= fpnprnu_corr_sof;
	debug_vector(0x18) <= fpnprnu_corr_sol;
	debug_vector(0x19) <= fpnprnu_corr_data_val;
	debug_vector(0x1a) <= fpnprnu_corr_eol;
	debug_vector(0x1b) <= fpnprnu_corr_eof;
	debug_vector(0x1c) <= python_ssn_int;
	$debug_vector(0x1d) \le debug_lvds(0);$
	$debug_vector(0x1e) \le debug_vector(0x1e)$;
	$debug_vector(0x1f) \le 'Z';$
Value at Reset:	0x1f

```
Debug2 sel (4:0)
RW
                                    debug\_vector(0x0) \le python\_monitor0;
                                     debug_vector(0x1) <= python_monitor1;
                                    debug_vector(0x2) <= grab_mngr_trig_rdy;
debug_vector(0x3) <= curr_trig0;</pre>
                                     debug vector(0x4) \le strobe;
                                     debug_vector(0x5) <= python_exposure;
debug_vector(0x6) <= FOT;</pre>
                                     debug vector(0x7) \le readout;
                                     debug_vector(0x8) <= readout_stateD;</pre>
                                     debug_vector(0x9) <= ext_trig;
                                     debug_vector(0xa) <= REGFILE.ACQ.GRAB_CTRL.GRAB_CMD;</pre>
                                     debug_vector(0xb) <= REGFILE.ACQ.GRAB_CTRL.GRAB_SS;</pre>
                                     debug_vector(0xc)<= grab_mngr_trig;</pre>
                                     debug_vector(0xd) <= grab_mngr_trig_rdy;</pre>
                                     debug_vector(0xe) <= grab_pending;</pre>
                                     debug_vector(0xf) <= grab_active;</pre>
                                     debug_vector(0x10) <= DEC_DATA_EN;
debug_vector(0x11) <= DEC_SOL;
                                     debug vector(0x12) <= DEC SOF:
                                     debug_vector(0x13) <= DEC_EOL;
                                    debug_vector(0x14) <= DEC_EOF;
debug_vector(0x15) <= DEC_CRC;
debug_vector(0x16) <= DEC_TRAIN;
                                     debug_vector(0x17) <= fpnprnu_corr_sof;
                                     debug_vector(0x18) <= fpnprnu_corr_sol;
                                     debug_vector(0x19) <= fpnprnu_corr_data_val;
                                     debug_vector(0x1a) <= fpnprnu_corr_eol;
                                     debug vector(0x1b) \le fpnprnu corr eof;
                                     debug_vector(0x1c) <= python_ssn_int;
                                     debug_vector(0x1d) <= debug_lvds(0);</pre>
                                     debug_vector(0x1e) <= debug_lvds(1);
                                     debug\_vector(0x1f) \le 'Z';
Value at Reset:
                                    0x1f
```

```
Debug1_sel (4:0)
RW
                                  debug_vector(0x0) <= python_monitor0;
                                 debug_vector(0x1) <= python_monitor1;
                                  debug_vector(0x2) <= grab_mngr_trig_rdy;
                                  debug_vector(0x3) <= curr_trig0;</pre>
                                  debug_vector(0x4) <= strobe;
                                  debug_vector(0x5) <= python_exposure;
                                 debug vector(0x6) <= FOT;
                                  debug\_vector(0x7) \le readout;
                                  debug_vector(0x8) <= readout_stateD;</pre>
                                  debug vector(0x9) \le ext trig
                                 debug_vector(0xa) <= REGFILE.ACQ.GRAB_CTRL.GRAB_CMD;
                                 debug_vector(0xb) <= REGFILE.ACQ.GRAB_CTRL.GRAB_SS;</pre>
                                  debug_vector(0xc)<= grab_mngr_trig;</pre>
                                  debug_vector(0xd) <= grab_mngr_trig_rdy;</pre>
                                  debug_vector(0xe) <= grab_pending;</pre>
                                 debug_vector(0xf) <= grab_active
                                  debug_vector(0x10) <= DEC_DATA_EN;
                                 debug_vector(0x11) <= DEC_SOL;
debug_vector(0x12) <= DEC_SOF;
debug_vector(0x13) <= DEC_EOL;
                                  debug vector(0x14) <= DEC EOF;
                                  debug_vector(0x15) <= DEC_CRC;
                                  debug_vector(0x16) <= DEC_TRAIN;</pre>
                                  debug_vector(0x17) <= fpnprnu_corr_sof;
                                 debug_vector(0x18) <= fpnprnu_corr_sol;
                                  debug_vector(0x19) <= fpnprnu_corr_data_val;
                                  debug_vector(0x1a) <= fpnprnu_corr_eol;</pre>
                                  debug_vector(0x1b) <= fpnprnu_corr_eof;
                                  debug_vector(0x1c) <= python_ssn_int;</pre>
                                  debug_vector(0x1d) <= debug_lvds(0);
                                  debug_vector(0x1e) <= debug_lvds(1);
                                  debug\_vector(0x1f) \le 'Z';
Value at Reset:
                                 0x1f
```

Debug0_sel (4:0)	
RW	debug_vector(0x0) <= python_monitor0;
	debug_vector(0x1) <= python_monitor1;
	debug_vector(0x2) <= grab_mngr_trig_rdy;
	debug_vector(0x3) <= curr_trig0;
	$debug_vector(0x4) \le strobe;$
	debug_vector(0x5) <= python_exposure;
	$ debug_vector(0x6) <= FOT;$
	debug_vector(0x7) <= readout;
	debug_vector(0x8) <= readout_stateD;
	debug_vector(0x9) <= ext_trig;
	debug_vector(0xa) <= REGFILE.ACQ.GRAB_CTRL.GRAB_CMD;
	debug_vector(0xb) <= REGFILE.ACQ.GRAB_CTRL.GRAB_SS;
	debug_vector(0xc)<= grab_mngr_trig;
	debug_vector(0xd) <= grab_mngr_trig_rdy;
	debug_vector(0xe) <= grab_pending;
	debug_vector(0xf) <= grab_active;
	debug_vector(0x10) <= DEC_DATA_EN;
	debug_vector(0x11) <= DEC_SOL;
	debug_vector(0x12) <= DEC_SOF;
	debug_vector(0x13) <= DEC_EOL;
	debug_vector(0x14) <= DEC_EOF;
	$debug_vector(0x15) \le DEC_CRC;$
	$debug_vector(0x16) \le DEC_TRAIN;$
	debug_vector(0x17) <= fpnprnu_corr_sof;
	debug_vector(0x18) <= fpnprnu_corr_sol;
	debug_vector(0x19) <= fpnprnu_corr_data_val;
	debug_vector(0x1a) <= fpnprnu_corr_eol;
	debug_vector(0x1b) <= fpnprnu_corr_eof;
	debug_vector(0x1c) <= python_ssn_int;
	$debug_vector(0x1d) \le debug_lvds(0);$
	debug_vector(0x1e) <= debug_lvds(1);
	$debug_vector(0x1f) <= 'Z';$
Value at Reset:	0x1f

TRIGGER_MISSED

Address: section "ACQ" base address + 0x0E8

31	30	29	28	27	26	25	24
	Reserved		TRIGGER_MI SSED_RST	Reserved			
23	22	21	20	19	18	17	16
	Reserved						
15	14	13	12	11	10	9	8
	TRIGGER_MISSED_CNTR(15:8)						
7	6	5	4	3	2	1	0
	TRIGGER_MISSED_CNTR(7:0)						

TRIGGER_MISSED_RST	TRIGGER MISSED ReSeT			
WO/AutoClr	This is the trigger missed	reset.		
Possible Values:	0x1	Reset the Trigger counter reset		

TRIGGER_MISSED_CNTR (15:0)	TRIGGER MISSED Coul	NTeR
RO	This is the number of trigg	ger missed detected.
Possible Values:	Any Value	

SENSOR_FPS

Address: section "ACQ" base address + 0x0F0

31	30	29	28	27	26	25	24
	Reserved						
23	22	21	20	19	18	17	16
			Rese	erved			
15	14	13	12	11	10	9	8
			SENSOR_	FPS(15:8)			
7	6	5	4	3	2	1	0
	SENSOR_FPS(7:0)						

SENSOR_FPS (15:0)	SENSOR Frame Per Second
	This is the number of frames received in 1 second interval. This register can count up to 64k frame/s. This counter counts on SO_FOT event.

Address: section "ACQ" base address + 0x1A0

31	30	29	28	27	26	25	24
	Reserved		DEBUG_RST _CNTR	Rese	erved	TEST_MODE_	PIX_START(9
23	22	21	20	19	18	17	16
			TEST_MODE_P	IX_START(7:0))		
15	14	13	12	11	10	9	8
		Res	served			TEST_MOVE	TEST_MODE
7	6	5	4	3	2	1	0
LED_STA	Γ_CLHS(1:0)	LED_STA	T_CTRL(1:0)	Reserved	LED_TEST_	_COLOR(1:0)	LED_TEST

DEBUG_RST_CNTR					
RW	This register clears the d	This register clears the debug cntrs			
Value at Reset:	0x1				
Possible Values:	0x0				
	0x1	Reset counters			

TEST_MODE_PIX_START (9:0)	
	This register defines the value of the first pixel in the frame when the TEST_MODE is activated. In 8 bits mode only 8-MSB bits of the register is used.
Value at Reset:	0x0

TEST_MOVE				
This field when in TEST_MODE=1, makes the ramp move. The first pixel of incremented by one each frame.				
Value at Reset:	0x0			
Possible Values:	0x0	Static test ramp		
	0x1	The test ramp moves		

TEST_MODE						
RW	using the syncs receveiv field TEST_MOVE.	GA in test mode. The fpga will send a programmable ramp to the host eived from the sensor. The generated ramp can move when set with the Gx1), the ramp pixel is repeated 3 times to generate a B&W ramp in				
Value at Reset:	0x0					
	UXU					
Possible Values:	0x0 Normal acquisition data from sensor					
	0x1 Test mode, a ramp is generated.					

LED_STAT_CLHS (1:0)	
RO	

LED_STAT_CTRL (1:0)	
RO	

LED_TEST_COLOR (1:0) RW		
Value at Reset:	0x0	
Possible Values:	0x0	The LED is OFF
	0x1	The LED is GREEN
	0x2	The LED is RED
	0x3	The LED is ORANGE

LED_TEST							
RW		This register will put the LED status in test mode. The test mode is controlled by LED_TEST_COLOR					
Value at Reset:	0x0						
Possible Values:	0x0	The LED is in user mode.					
	0x1	The LED is in test mode.					

DEBUG_CNTR1

Address: section "ACQ" base address + 0x1A8

31	30	29	28	27	26	25	24		
	EOF_CNTR(31:24)								
23	22	21	20	19	18	17	16		
	EOF_CNTR(23:16)								
15	14	13	12	11	10	9	8		
	EOF_CNTR(15:8)								
7	6	5	4	3	2	1	0		
	EOF_CNTR(7:0)								

EOF_CNTR (31:0)	
	This is the EOF CNTR. This feature is enabled by setting register regfile.ACQ.DEBUG.DEBUG RST CNTR to 0.

DEBUG_CNTR2

Address: section "ACQ" base address + 0x1B0

31	30	29	28	27	26	25	24	
Reserved								
23	22	21	20	19	18	17	16	
Reserved								
15	14	13	12	11	10	9	8	
Reserved EOL_CNTR(11:8)								
7	6	5	4	3	2	1	0	
EOL_CNTR(7:0)								

EOL_CNTR (11:0)	
	This is the EOL CNTR. This feature is enabled by setting register regfile.ACQ.DEBUG.DEBUG_RST_CNTR to 0.

DEBUG_CNTR3

Address: section "ACQ" base address + 0x1B4

31	30	29	28	27	26	25	24
	Reserved			SEN	SOR_FRAME_	DURATION(27	7:24)
23	22	21	20	19	18	17	16
	SENSOR_FRAME_DURATION(23:16)						
15	14	13	12	11	10	9	8
	SENSOR_FRAME_DURATION(15:8)						
7	6	5	4	3	2	1	0
	SENSOR FRAME DURATION(7:0)						

SENSOR_FRAME_DURATI ON (27:0)					
	up to 4.29 seconds. It can profiler heads.	the last 2 EOF received(in sys clock domain). This register can count be used to predict sensor framerate or to verify sync between 3D			
	This feature is enabled by setting register regfile.ACQ.DEBUG.DEBUG_RST_CNTR to 0.				
Possible Values:	Any Value	Any 28 bits value			

Address: section "ACQ" base address + 0x1B8

31	30	29	28	27	26	25	24		
	Reserved								
23	22	21	20	19	18	17	16		
			Reserved				EXP_FOT		
15	14	13	12	11	10	9	8		
Reserved					EXP_FOT_	TIME(11:8)			
7	6	5	4	3	2	1	0		
	EXP_FOT_TIME(7:0)								

EXP_FOT	EXPosure duri	EXPosure during FOT		
RW	exposure in the EXP_FOT_TI	When set to '1' this register, the output exposure and strobe signals will take into account the exposure in the FOT of the frame. This timing must be programmed in register EXP_FOT_TIME. This timing must be calculated from the OnSemi setting files .		
Value at Reset:	0x1	0x1		
Possible Values:	0x0	Disable exposure during FOT in output exposure signal and Strobe		
	0x1	Enable exposure during FOT in output exposure signal and Strobe		

EXP_FOT_TIME (11:0)	EXPosure during FOT TIME	
RW	This is the time of the exposure during the FOT. This timing must be calculated from the OnSemi setting files.	
	From DCF v1.2, for all LVDS modes :	
	P5000 & P2000 EXP_FOT=40.666us, program value 0x9ee	
	P1300 & P500 & P300 EXP_FOT=27.333us, program value 0x6ac	
Value at Reset:	0x9ee	

ACQ_SFNC

Address: section "ACQ" base address + 0x1C0

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
Reserved							
7	6	5	4	3	2	1	0
Reserved						RELOAD_GR	
							AB PARAMS

RELOAD_GRAB_PARAMS				
RW	This register is not used for the moment. It may be used in the future to reload the exposure time			
Value at Reset:	0x1			
Possible Values:	0x0			
	0x1			