Register file structure : regfile_xgs_athena.pdf Created by amarchan on 2021/08/25 10:19:17

Register file CRC32: 0x9D7A0FC4

1. Main Parameters

Register file endianness: little endian

Address bus width: 11 bits Data bus width: 32 bits

2. Memory Map

Section name	Address(es) / Address Ranges	Register name	Access Type
SYSTEM	0x000	TAG	R
	0x004	VERSION	R
	0x008	CAPABILITY	R
	0x00C	SCRATCHPAD	RW
DMA	0x070	CTRL	RW
	0x078	FSTART	RW
	0x07C	FSTART_HIGH	RW
	0x080	FSTART_G	RW
	0x084	FSTART_G_HIGH	RW
	0x088	FSTART_R	RW
	0x08C	FSTART_R_HIGH	RW
	0x090	LINE_PITCH	RW
	0x094	LINE_SIZE	RW
	0x098	CSC	RW
	0x0A8	OUTPUT_BUFFER	RW
	0x0AC	TLP	R
	0x0B0	ROI_X	RW
	0x0BC	ROI_Y	RW
ACQ	0x100	GRAB_CTRL	RW
	0x108	GRAB_STAT	R
	0x110	READOUT_CFG1	RW
	0x114	READOUT_CFG_FRA ME_LINE	RW
	0x118	READOUT_CFG2	R
	0x120	READOUT_CFG3	RW
	0x124	READOUT_CFG4	RW
	0x128	EXP_CTRL1	RW
	0x130	EXP_CTRL2	RW
	0x138	EXP_CTRL3	RW
	0x140	TRIGGER_DELAY	RW
	0x148	STROBE_CTRL1	RW
	0x150	STROBE_CTRL2	RW

Section name	Address(es) / Address Ranges	Register name	Access Type
	0x158	ACQ_SER_CTRL	RW
	0x160	ACQ_SER_ADDATA	RW
	0x168	ACQ_SER_STAT	R
	0x190	SENSOR_CTRL	RW
	0x198	SENSOR_STAT	R
	0x19C	SENSOR_SUBSAMPLI	
	0x1A4	SENSOR_GAIN_ANA	RW
	0x1A8	SENSOR_ROI_Y_STA RT	RW
	0x1AC	SENSOR_ROI_Y_SIZE	RW
	0x1B8	SENSOR_M_LINES	RW
	0x1BC	SENSOR_DP_GR	RW
	0x1C0	SENSOR_DP_GB	RW
	0x1C4	SENSOR_DP_R	RW
	0x1C8	SENSOR_DP_B	RW
	0x1CC	SENSOR_GAIN_DIG_ G	RW
	0x1D0	SENSOR_GAIN_DIG_ RB	RW
	0x1D8	FPGA_ROI_X_START	RW
	0x1DC	FPGA_ROI_X_SIZE	RW
	0x1E0	DEBUG_PINS	RW
	0x1E8	TRIGGER_MISSED	RW
	0x1F0	SENSOR_FPS	R
	0x1F4	SENSOR_FPS2	R
	0x2A0	DEBUG	RW
	0x2A8	DEBUG_CNTR1	R
	0x2B8	EXP_FOT	RW
	0x2C0	ACQ_SFNC	RW
	0x2D0	TIMER_CTRL	RW
	0x2D4	TIMER_DELAY	RW
	0x2D8	TIMER_DURATION	RW
HISPI	0x400	CTRL	RW
	0x404	STATUS	R
	0x408		R
	0x40C	IDLE CHARACTER	RW
	0x410	PHY	RW
	0x414	FRAME_CFG	RW
	0x418	FRAME_CFG_X_VALI	RW
	0x424, 0x428, ,0x438	LANE_DECODER_ST ATUS (5:0)	RW
	0x43C, 0x440, ,0x450	TAP_HISTOGRAM (5:0)	R
	0x454	DEBUG	RW
DPC	0x480	DPC_CAPABILITIES	R
	0x484	DPC_LIST_CTRL	RW
	0x488	DPC_LIST_STAT	R
	0x48C	DPC_LIST_DATA1	RW
	0x490	DPC_LIST_DATA2	RW
	0x494	DPC_LIST_DATA1_R D	R
	0x498	DPC_LIST_DATA2_R	R

Section name	Address(es) / Address Ranges	Register name	Access Type
LUT	0x4B0	LUT_CAPABILITIES	R
	0x4B4	LUT_CTRL	RW
	0x4B8	LUT_RB	R
BAYER	0x4C0	BAYER_CAPABILITIE S	R
	0x4C4	WB_MUL1	RW
	0x4C8	WB_MUL2	RW
	0x4CC	WB_B_ACC	R
	0x4D0	WB_G_ACC	R
	0x4D4	WB_R_ACC	R
	0x4D8	CCM_CTRL	RW
	0x4DC	CCM_KR1	RW
	0x4E0	CCM_KR2	RW
	0x4E4	CCM_KG1	RW
	0x4E8	CCM_KG2	RW
	0x4EC	CCM_KB1	RW
	0x4F0	CCM_KB2	RW
SYSMONXIL	0x700	TEMP	R
	0x704	VCCINT	R
	0x708	VCCAUX	R
	0x718	VCCBRAM	R
	0x780	TEMP_MAX	R
	0x790	TEMP_MIN	R

3. Registers definition

Section: SYSTEM

Address Range: [0x000 - 0x00C]

TAG

Address: section "SYSTEM" base address + 0x000

31	30	29	28	27	26	25	24			
	Reserved									
23	22	21	20	19	18	17	16			
	VALUE(23:16)									
15	14	13	12	11	10	9	8			
	VALUE(15:8)									
7	6	5	4	3	2	1	0			
			VALU	JE(7:0)						

VALUE (23:0)	Tag identifier	
STATIC		
Value at Reset:	0x58544d	
Possible Values:	0x58544D	MTX ASCII string

Description:

Revisions

0.1.0 : First functionnal revision

0.2.0 : Removed tha lane_packer module

31	30	29	28	27	26	25	24		
	Reserved								
23	22	21	20	19	18	17	16		
			MAJO	R(7:0)					
15	14	13	12	11	10	9	8		
	MINOR(7:0)								
7	6	5	4	3	2	1	0		
	HW(7:0)								

MAJOR (7:0)	
STATIC	
Value at Reset:	0x0

MINOR (7:0)	
STATIC	
Value at Reset:	0x2

HW (7:0)	
STATIC	
Value at Reset:	0x0

31	30	29	28	27	26	25	24	
			Rese	erved				
23	22	21	20	19	18	17	16	
			Rese	erved				
15	14	13	12	11	10	9	8	
	Reserved							
7	6	5	4	3	2	1	0	
			VALU	JE(7:0)				

VALUE (7:0)			
STATIC			
Value at Reset:	0x0		

Address: section "SYSTEM" base address + 0x00C

31	30	29	28	27	26	25	24			
	VALUE(31:24)									
23	22	21	20	19	18	17	16			
			VALUE	E(23:16)						
15	14	13	12	11	10	9	8			
	VALUE(15:8)									
7	6	5	4	3	2	1	0			
	VALUE(7:0)									

VALUE (31:0)	
RW	
Value at Reset:	0x0

Address Range: [0x070 - 0x0C4]

CTRL

Initial Grab Address Register

Address: section "DMA" base address + 0x000

Description:

Initial Grab Address LOW 32 bits

31	30	29	28	27	26	25	24		
	Reserved								
23	22	21	20	19	18	17	16		
	Reserved								
15	14	13	12	11	10	9	8		
	Reserved								
7	6	5	4	3	2	1	0		
Reserved						GRAB_QUEU E_EN			

GRAB_QUEUE_EN		
RW		
Value at Reset:	0x0	
Possible Values:	0x0	
	0x1	

Description:

Initial Grab Address LOW 32 bits

31	30	29	28	27	26	25	24			
	VALUE(31:24)									
23	22	21	20	19	18	17	16			
	VALUE(23:16)									
15	14	13	12	11	10	9	8			
	VALUE(15:8)									
7	6	5	4	3	2	1	0			
	VALUE(7:0)									

VALUE (31:0)	Nitial GRAb ADDRess Register				
RW	This is the address in the host ram where the grab engine will start writing pixel data.				
Value at Reset:	0x0				
Possible Values:	Any Value				

Description:

Initial Grab Address HI 32 bits

31	30	29	28	27	26	25	24			
	VALUE(31:24)									
23	22	21	20	19	18	17	16			
	VALUE(23:16)									
15	14	13	12	11	10	9	8			
	VALUE(15:8)									
7	6	5	4	3	2	1	0			
	VALUE(7:0)									

VALUE (31:0)	INitial GRAb ADDRess Register High			
RW	This is the high 32 bits of the 64-bit addresses in the host ram where the grab engine will start writing pixel data.			
Value at Reset:	0x0			
Possible Values:	Any Value			

Description:

Grab Address LOW 32 bits for the Green plane. Only used when grabbing in Planar mode.

31	30	29	28	27	26	25	24		
	VALUE(31:24)								
23	22	21	20	19	18	17	16		
	VALUE(23:16)								
15	14	13	12	11	10	9	8		
	VALUE(15:8)								
7	6	5	4	3	2	1	0		
	VALUE(7:0)								

VALUE (31:0)	GRAb ADDRess Register
RW	This is the address in the host ram where the grab engine will start writing pixel data.
Value at Reset:	0x0
Possible Values:	Any Value

Description:

Green Grab Address HIGH 32 bits

31	30	29	28	27	26	25	24			
	VALUE(31:24)									
23	22	21	20	19	18	17	16			
	VALUE(23:16)									
15	14	13	12	11	10	9	8			
	VALUE(15:8)									
7	6	5	4	3	2	1	0			
	VALUE(7:0)									

VALUE (31:0) RW	This is the high pa	GRAb ADDRess Register High This is the high part of the 64-bit addresses in the host ram where the grab engine will start writing pixel data.			
Value at Reset:	0x0	0x0			
Possible Values:	Any Value	Any value			

Description:

Grab Address LOW 32 bits for the Red plane. Only used when grabbing in Planar mode.

31	30	29	28	27	26	25	24			
	VALUE(31:24)									
23	22	21	20	19	18	17	16			
	VALUE(23:16)									
15	14	13	12	11	10	9	8			
	VALUE(15:8)									
7	6	5	4	3	2	1	0			
	VALUE(7:0)									

VALUE (31:0)	GRAb ADDRess Regis	GRAb ADDRess Register			
RW	This is the address in th	This is the address in the host ram where the grab engine will start writing pixel data.			
Value at Reset:	0x0				
Possible Values:	Any Value	Any value			

Description:

Red Grab Address HIGH 32 bits

31	30	29	28	27	26	25	24
			VALUE	E(31:24)			
23	22	21	20	19	18	17	16
			VALUE	E(23:16)			
15	14	13	12	11	10	9	8
			VALU	E(15:8)			
7	6	5	4	3	2	1	0
	VALUE(7:0)						

VALUE (31:0) RW	GRAb ADDRess I This is the high pa writing pixel data.	rt of the 64-bit addresess in the host ram where the grab engine will start			
Value at Reset:	0x0	0x0			
Possible Values:	Any Value	Any Value Any value			

Description:

Grab Line Pitch Register

31	30	29	28	27	26	25	24
	Reserved						
23	22	21	20	19	18	17	16
			Rese	erved			
15	14	13	12	11	10	9	8
			VALU	E(15:8)			
7	6	5	4	3	2	1	0
	VALUE(7:0)						

VALUE (15:0)	Grab LinePitch
RW	This is the line pitch when writing in ram. It is measured in bytes, not pixels.
Value at Reset:	0x0

Description:

Host Line Size Register.

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
			Rese	erved			
15	14	13	12	11	10	9	8
Rese	rved	VALUE(13:8)					
7	6	5	4	3	2	1	0
	VALUE(7:0)						

VALUE (13:0)	Host Line size	Host Line size			
RW	register is higher the host memory. If the cropped at the end	This is the line size when writing in host ram. It is measured in bytes, not pixels. If this register is higher than the actual data provided by the sensor, stray data will be written into host memory. If this register is lower than the data provided by the sensor, image data will be cropped at the end of the line. For backward compatibility, the value of 0 indicates that the FPGA should auto-compute the line sized based on data provided by the sensor interface.			
Value at Reset:	0x0	0x0			
Possible Values:	0x1 - 0x3FFF Written line size in host frame.				
	0x0	Auto-compute line size from sensor data.			

31	30	29	28	27	26	25	24
	Reserved					OLOR_SPACE(2	2:0)
23	22	21	20	19	18	17	16
DUP_LAST_ LINE				Reserved			
15	14	13	12	11	10	9	8
Rese	erved		SUB_	X(3:0)		REVERSE_Y	REVERSE_X
7	6	5	4	3	2	1	0
	Reserved						

COLOR_SPACE (2:0)						
RW	Output color s	Output color space used to transfer data to the DMA engine.				
Value at Reset:	0x0	0x0				
Possible Values:	0x0	Reserved for Mono sensor operation				
	0x1	BGR32				
	0x2	YUV 4:2:2 in full range				
	0x3	Reserved for Planar 8-bits (Not implemented yet)				
	0x4	Reserved for Y only with color sensor (Not implemented)				
	0x5	RAW color pixels (For color sensor only, 8bpp)				

DUP_LAST_LINE					
RW	This field is used to enable the duplicate last line feature. When turned on, the datapath w regenerate the last line when it receives the end of frame marker from the acquisition secti. The goal of this feature is to compensate for the lost line during the Bayer demosaic processing.				
Value at Reset:	0x0	0x0			
Possible Values:	0x0	0x0 normal processing			
	0x1	last line is duplicated			

SUB_X (3:0)	
RW	
Value at Reset:	0x0

REVERSE_Y	REVERSE Y	
RW	Reverse readou	t
Value at Reset:	0x0	
Possible Values:	0x0	Bottom to top readout
	0x1	Top to bottom readout

REVERSE_X	Reverse image	Reverse image in X direction				
RW		When this field is set each row is mirorred while streamed out. Miror process is applied on a pixel resolution. This means for multi-bytes pixels, bytes are always streamed in the right order.				
Value at Reset:	0x0	0x0				
Possible Values:	0x0	0x0 Reverse X disabled				
	0x1	0x1 Reverse X enabled				

_	31	30	29	28	27	26	25	24
	MAX_LINE_BUFF_CNT(3:0)				Reserved		LINE_PTR_WIDTH(1:0)	
_	23	22	21	20	19	18	17	16
	ADDRESS_BUS_WIDTH(3:0)				Reserved			
	15	14	13	12	11	10	9	8
				Rese	rved			
	7	6	5	4	3	2	1	0
		Reserved		PCIE_BACK_ PRESSURE		Reserved		CLR_MAX_L INE_BUFF_C NT

MAX_LINE_BUFF_CNT (3:0)	Maximum line buffer count		
RO	This is an elastic line buffer. This fields records maximum number of line buffer that was used for transfering data. This field is cleared by the system reset and can also be cleared by the field		
	registerfile.DMA.OUTPUT_BUFFER.CLR_MAX_LINE_BUFF_CNT		

LINE_PTR_WIDTH (1:0)	Line pointer size (in bits)	Line pointer size (in bits)			
RW	Set the line pointer size (in bits) 3 = 3 bits wide: The full memory buffer is divided in 8 sub line buffers				
Value at Reset:	0x2				
Possible Values:	0x0 Not valid				
	0x1	The buffer is divided in 2 line buffers			
	0x2 The buffer is divided in 4 line buffers				
	0x3	The buffer is divided in 8 line buffers			

ADDRESS_BUS_WIDTH (3:0)	Line buffer address size in bits				
RO	Indicate to the software the size of the DMA output line buffer address bus in bits. For example for a 11 bits address bus, the buffer size in bytes is :				
	2pow(11) * 8 bytes = 16KB (16384 bytes)				

PCIE_BACK_PRESSURE	PCIE link back pressure	PCIE link back pressure detected				
RW2C	Indicates that the DMA line buffer was full while the XGS sensor was still pushing data. When this occures the Athena rely on the buffering (FiFo) along the data path as the last ressort to absorb the pcie back pressure. This should not occur.					
Value at Reset:	0x0	0x0				
Possible Values:	0x0 No effect					
	0x1 Back pressure detected on PCIe					

CLR_MAX_LINE_BUFF_CN T	Clear maximum line buffer count				
WO/AutoClr					
Possible Values:	0x0	No effect			
	0x1	Clear the max count			

31	30	29	28	27	26	25	24	
	Reserved				MAX_PAY	LOAD(11:8)		
23	22	21	20	19	18	17	16	
	MAX_PAYLOAD(7:0)							
15	14	13	12	11	10	9	8	
	Reserved							
7	6	5	4	3	2	1	0	
	Reserved				CF	G_MAX_PLD(2	::0)	

MAX_PAYLOAD (11:0)	
RO	

BUS_MASTER_EN	
RO	

CFG_MAX_PLD (2:0)	PCIe Device Control Re	PCIe Device Control Register (Offset 08h); bits 7 downto 5				
RO	See PCIe Baser2.1, Sect	See PCIe Baser2.1, Section 7.8.4. Device Control Register (Offset 08h)				
	This field indicates the maximum TLP payload size allowed by the host for this Function. As a Receiver, the Function must handle TLPs a large as the set value. As a Transmitter, the Function must not generate TLPs exceeding th value. Permissible values that can be programmed are indicated by the Max_Payload_Size Supported in the Device Capabilities register (see Section 7.8.3).					
	Functions that support only the 128-byte max payload size are permitted to hardwire this field to 000b. System software is not required to program the same value for this field for all the Functions of a multi-Function device. Refer to Section 2.2.2 for important guidance. For ARI Devices, Max_Payload_Size is determined solely by the setting in Function 0. The settings in the other Functions always return whatever value software programmed for each, but otherwise are ignored by the component. Default value of this field is 000b.					
Possible Values:	0x0 128 bytes max payload size					
	0x1 256 bytes max payload size					
	0x2 512 bytes max payload size					
	0x3 1024 bytes max payload size					
	Others	Not supported by Xilinx endpoint				

ROI_X

31	30	29	28	27	26	25	24	
ROI_EN	Reserved		X_SIZE(12:8)					
23	22	21	20	19	18	17	16	
	X_SIZE(7:0)							
15	14	13	12	11	10	9	8	
	Reserved				X_START(12:8)			
7	6	5	4	3	2	1	0	
	X_START(7:0)							

ROI_EN	Region of inter	Region of interest enable		
RW	on the X_STA disabled the fu The first valide	This bit activate the region of interest mechanism (cropping). If enabled, this mechanism rely on the X_START and X_SIZE parameters todetermine the valid region of a row. If ROI_EN is disabled the full sensor image is sent to the host. The first valide pixel is located at X_START and the last valid pixel is located at at X_STOP = X_START + (X_SIZE -1)		
Value at Reset:	0x0	0x0		
Possible Values:	0x0	Region of interest is disabled		
	0x1	Region of interest is enabled		

X_SIZE (12:0)	
RW	This register defines the size in pixels of the region of interest (On the X axis)
Value at Reset:	0x3ff

X_START (12:0)	
RW	This register defines the position of the first horizontal valid pixel (including interpolation pixels).
Value at Reset:	0x0

ROI_Y

31	30	29	28	27	26	25	24
ROI_EN	Reserved				Y_SIZE(12:8)		
23	22	21	20	19	18	17	16
			Y_SIZ	ZE(7:0)			
15	14	13	12	11	10	9	8
Reserved				Y_START(12:8))		
7	6	5	4	3	2	1	0
	Y_START(7:0)						

ROI_EN	Region of inte	Region of interest enable		
RW	mechanism re row. If ROI_E The first valid	This bit activate the region of interest mechanism (cropping)in the Y axix. If enabled, this mechanism rely on the Y_START and Y_SIZE parameters to determine the valid region of a row. If ROI_EN is disabled the full sensor image is sent to the host. The first valide line is located at Y_START and the last valid line is located at at Y_STOP = Y_START + (Y_SIZE -1)		
Value at Reset:	0x0	0x0		
Possible Values:	0x0	Region of interest is disabled		
	0x1	Region of interest is enabled		

Y_SIZE (12:0)	
RW	This register defines the size in lines of the region of interest.
Value at Reset:	0x3ff

Y_START (12:0)	
RW	This register defines the position of the first vertical valid line.
Value at Reset:	0x0

Address Range: [0x100 - 0x2D8]

GRAB_CTRL

GRAB ConTRoL Register

Address: section "ACQ" base address + 0x000

0x1

Description:

Grag Control Register

31	30	29	28	27	26	25	24
RESET_GRA B	Reserved	GRAB_ROI2_ EN	ABORT_GRA B		Res	served	
23	22	21	20	19	18	17	16
			Reserved				TRIGGER_O VERLAP_BU FFn
15	14	13	12	11	10	9	8
TRIGGER_O VERLAP	TRIGGER_ACT(2:0)		:0)	Reserved	TRIGGER_SRC(2:0)		:0)
7	6	5	4	3	2	1	0
	Reserved		GRAB_SS	Rese	erved	BUFFER_ID	GRAB_CMD
RESET_GRAB							
RW This register r			esets the entire X	GS ctrl.			
Value at Reset: 0x0							
Possible Values:	Possible Values: 0x0 Rese			t not active			

GRAB_ROI2_EN				
RW	1) No Y overl 2) Xsize must 3) EOF and So	Enable the second ROI on the frame (KNS). This register is not DB. 1) No Y overlap is allowed 2) Xsize must be the same for the two ROI for the moment(DMA constraint). 3) EOF and SOF in between the two in-frame ROIs will be masked to the DMA. The DMA will see one frame, with the two ROI inside.		
Value at Reset:	0x0	0x0		
Possible Values:	0x0	0x0 Dual ROI disable		
	0x1	Dual ROI enable		

Reset active

ABORT_GRAB	ABORT GRAB		
WO/AutoClr	This is the grab Abort signal, it will reset all the grab queued.		
Possible Values:	0x0 Normal operation		
	0x1	Reset Grab	

TRIGGER_OVERLAP_BUF Fn			
RW	NOT FULLY VALIDATED. DON'T USE. SET IT TO '0'.		
Value at Reset:	0x0		
Possible Values:	0x0	Buffer the trigger received during the dead window in PET mode and execute	
	0x1	The trigger will be ignored during dead window in PET mode.	

TRIGGER_OVERLAP				
RW		This field enables the trigger overlap. In this mode the exposure and the readout of the sensor can be done in parallel for higher framerates.		
Value at Reset:	0x1			
Possible Values:	0x0	Trigger Overlap disable		
	0x1	Trigger Overlap enable (default)		

TRIGGER_ACT (2:0)	TRIGGER AC	Tivation		
RW	This is the trigger activation . This register selects the activation of the trigger when the trigger source is set to Hardware Snapshop mode . This register is Double Buffered, so the trigger activation may change from one grab command to another.			
	In activation Level HI/LO with EXPOSURE_MODE register set to Timed, the camera will triggered in continuous way if the level of the external trigger remains at the LEVEL programmed in this register.			
	In activation Level HI/LO with EXPOSURE_MODE register set to Trigger Width, the Exposure time will be set by the level of the trigger input. The FPGA exposure regsiters will be ignored. The Dual and Triple slope are not supported in the mode.			
Value at Reset:	0x0			
Possible Values:	0x0	Rising edge		
	0x1	Falling edge		
	0x2	Rising or Falling edge		
	0x3 Level HI			
	0x4Level LO0x5Internal Programmable Timer Trigger0x6RESERVED			
	0x7	RESERVED		

TRIGGER_SRC (2:0)	TRIGGER Son	TRIGGER SouRCe		
RW	Double Buffer	This is the trigger source. This register selects the source of the grab trigger. This register is Double Buffered, so the trigger source may change from one grab command to another. TRIGGER_SRC(1) may be seen as a TRIGGER_STATE by the software driver.		
Value at Reset:	0x0	0x0		
Possible Values:	0x0	0x0 RESERVED		
	0x1	0x1 Immediate mode (Continuous)		
	0x2	0x2 Hardware Snapshop mode		
	0x3 Software Snapshot mode			
	0x4	SFNC mode (auto trig)		

GRAB_SS	GRAB Softwar	GRAB Software Snapshot		
WO/AutoClr	This is the softy mode.	This is the software snapshot register when the trigger source selected is Software Snapshot mode.		
Possible Values:	0x0	Idle		
	0x1	Start a grab		

BUFFER_ID	
RW	This is the ID of the DMA parameters to associate with this grab command.
Value at Reset:	0x0

GRAB_CMD	GRAB CoMma	GRAB CoMmanD		
WO/AutoClr	This is MIL GI	This is MIL GRAB command.		
	automatically e Hardware Snap The GRAB_CI	er source is set to Immediate mode(Continuous), an exposure sequence will be executed. When the trigger source is set to Software Snapshop mode or oshop mode, GRAB_CMD will act as an ARM. MD will take around 13 clks to reccord the grab parametters to the SPI fifo. The DONE register may be readed to avoid fifo corruption before sending another linstruction.		
Possible Values:	0x0	Idle		
	0x1	Start grab command		

GRAB_STAT

31	30	29	28	27	26	25	24
GRAB_CMD_ DONE	ABORT_PET	ABORT_DEL AI	ABORT_DON E		Reserved		TRIGGER_R DY
23	22	21	20	19	18	17	16
Reserved	ABORT_MNGR_STAT(2:0)			TRIG_MNGR_STAT(3:0)			
15	14	13	12	11	10	9	8
Reserved	TIMER_MNGR_STAT(2:0)			GRAB_MNG	R_STAT(3:0)		
7	6	5	4	3	2	1	0
Reserved	GRAB_FOT	GRAB_READ OUT	GRAB_EXPO SURE	Reserved	GRAB_PEND ING	GRAB_ACTI VE	GRAB_IDLE

GRAB_CMD_DONE	GRAB CoMmanD DONE			
RO	The GRAB_CMD will take around 13 clks to reccord the grab parametters to the SPI fifo. This register may be readed to avoid fifo corruption before sending another Grab command instruction.			
Possible Values:	0x0	Grab Command in process		
	0x1	Ox1 Grab command idle		

ABORT_PET	ABORT during PET		
RO	This is the ABORT PET flag. It is set to '1' when an abort is detected in the PETengin phase of the trigger. It is set back to '0' when ABORT_DONE is set to '1'.		
Possible Values:	0x0 Abort in PET Phase idle		
	Ox1 Abort in PET Phase active		

ABORT_DELAI			
	This is the ABORT DELAI flag. It is set to '1' when an abort is detected in the delai phase of the trigger. It is set back to '0' when ABORT_DONE is set to '1'.		
Possible Values:	0x0 Abort in Delai Phase idle		
	0x1	Abort in Delai Phase active	

ABORT_DONE	ABORT is DO	ABORT is DONE		
RO	This read-only executing.	This read-only field indicates the RESET_GRAB command status. If 0, an abort sequence is executing.		
Possible Values:	0x0	0x0 Abort sequence not finished yet		
	0x1	Abort DONE, or not started (reset value)		

TRIGGER_RDY	
RO	

ABORT_MNGR_STAT (2:0)	
RO	DEBUG ABORT MANAGER STATE MACHINE

TRIC MICR CTATE (2.4)					
TRIG_MNGR_STAT (3:0)	DEDUCTRICATE MANAGER CHATE MACHINE				
RO	DEBUG TRIG	GER MANAGER STATE MACHINE			
TIMER_MNGR_STAT (2:0)					
D.O.	DEBLIC TIME	R MANAGER STATE MACHINE			
RO	DEBOO TIME	R MANAOLR STATE MACHINE			
GRAB_MNGR_STAT (3:0)					
RO	DEBLIC CRAI	3 MANAGER STATE MACHINE			
NO	DEDUC CICAL	J MANAOLK STATE MACHINE			
GRAB_FOT	GRAB Field O	verhead Time			
RO		or FOT (Field Overhead Time).			
Possible Values:	0x0	Not in FOT			
	0x1	In FOT			
GRAB_READOUT					
011112_112112 0 0 1	This is the sensor readout status. It goes to '1' on the SO_FOT and goes to '0' when the				
RO	This is the sens	or readout status. It goes to '1' on the SO_FOT and goes to '0' when the			
	This is the sens datapath decode	or readout status. It goes to '1' on the SO_FOT and goes to '0' when the er decodes the end of frame.			
GRAB_EXPOSURE	datapath decode	er decodes the end of frame.			
RO	datapath decode	or readout status. It goes to '1' on the SO_FOT and goes to '0' when the er decodes the end of frame. or integration status Idle			
RO GRAB_EXPOSURE RO	This is the sens	or integration status			
GRAB_EXPOSURE RO	This is the sens	or integration status Idle			
GRAB_EXPOSURE RO	This is the sens	or integration status Idle			
GRAB_EXPOSURE RO Possible Values:	This is the sens	or integration status Idle			
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING	This is the sens 0x0 0x1 Grab pending s	or integration status Idle Integrating			
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO	This is the sens 0x0 0x1 Grab pending s fpga.	or integration status Idle Integrating tatus. When this register is set to one, a second grab command is queued in the			
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO	This is the sens 0x0 0x1 Grab pending s fpga. 0x0	or integration status Idle Integrating tatus. When this register is set to one, a second grab command is queued in the No grab pending			
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO Possible Values:	This is the sens 0x0 0x1 Grab pending s fpga. 0x0	or integration status Idle Integrating tatus. When this register is set to one, a second grab command is queued in the No grab pending			
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO	This is the sens 0x0 0x1 Grab pending s fpga. 0x0 0x1	or integration status Idle Integrating tatus. When this register is set to one, a second grab command is queued in the No grab pending			
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO Possible Values:	This is the sens 0x0 0x1 Grab pending s fpga. 0x0 0x1	or integration status Idle Integrating tatus. When this register is set to one, a second grab command is queued in the No grab pending Grab pending			
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO Possible Values:	This is the sens 0x0 0x1 Grab pending s fpga. 0x0 0x1	or integration status Idle Integrating tatus. When this register is set to one, a second grab command is queued in the No grab pending Grab pending			
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO Possible Values: GRAB_ACTIVE RO	This is the sens 0x0 0x1 Grab pending s fpga. 0x0 0x1 Grab active state received.	or integration status Idle Integrating tatus. When this register is set to one, a second grab command is queued in the No grab pending Grab pending			
GRAB_EXPOSURE RO Possible Values: GRAB_PENDING RO Possible Values: GRAB_ACTIVE RO	This is the sens 0x0 0x1 Grab pending s fpga. 0x0 0x1 Grab active state received.	or integration status Idle Integrating tatus. When this register is set to one, a second grab command is queued in the No grab pending Grab pending Grab pending tus. When this register is set to one, at least one grab command has been			

28

31	30	29	28	27	26	25	24	
	Reserved			FOT_LENGTH_LINE(4:0)				
23	22	21	20	19	18	17	16	
			Reserved				EO_FOT_SEL	
15	14	13	12	11	10	9	8	
	FOT_LENGTH(15:8)							
7	6	5	4	3	2	1	0	
	FOT_LENGTH(7:0)							

FOT_LENGTH_LINE (4:0) RW	Frame Overhead Time LENGTH LINE This is the length of the Frame Overhead Time in line_time unit.			
Value at Reset:	0x0			
Possible Values:	Any Value	Any 16 bit value		

EO_FOT_SEL	
RW	This selector selects who will generate the EO_FOT in the controller. When select 0, the EO_FOT is the falling edge detection of the monitor FOT. When select 1, the EO_FOT will be generated inside the controller with programmed FOT_LENGTH.
Value at Reset:	0x0

FOT_LENGTH (15:0)	Frame Overhead Time LENGTH				
RW	This is the length of the Frame Overhead Time in sys clock. This register is calculated from FOT_LENGTH_LINE and LINE_TIME. It is used when EO_FOT_SEL is set to 1.				
Value at Reset:	0x0				
Possible Values:	Any Value	Any 16 bit value			

READOUT_CFG_FRAME_LIN E

31	30	29	28	27	26	25	24	
	Reserved							
23	22	21	20	19	18	17	16	
			DUMMY_I	LINES(7:0)				
15	14	13	12	11	10	9	8	
	Reserved CURR_FRAME_LINES(12:8)							
7	6	5	4	3	2	1	0	
	CURR_FRAME_LINES(7:0)							

DUMMY_LINES (7:0)	
RW	Number of lines to add in the readout (to debug XGS)
Value at Reset:	0x0

CURR_FRAME_LINES (12:0)	
RO	Current number of lines in the readout calculated by the XGS controller (without FOT).

31	30	29	28	27	26	25	24
	Reserved			READ	OUT_LENGTH	(28:24)	
23	22	21	20	19	18	17	16
			READOUT_LI	ENGTH(23:16)			
15	14	13	12	11	10	9	8
			READOUT_L	ENGTH(15:8)			
7	6	5	4	3	2	1	0
	READOUT LENGTH(7:0)						

READOUT_LENGTH (28:0)						
	This is the readout length register. This register is calculated by the FPGA in the IRIS4 projectand gives the readout length without the FOT. This register will depend on the ROI, an Subsampling mode. It is used in the PET engin calculations. In Sys Clock domain.					
Possible Values:	Any Value	Any 24 bits value				

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
	Reserved						
15	14	13	12	11	10	9	8
	LINE_TIME(15:8)						
7	6	5	4	3	2	1	0
			LINE_T	IME(7:0)			

LINE_TIME (15:0)	LINE TIME	LINE TIME				
RW		This register definel the length of one line of the sensor. It includes blanking and valid time . Line Time Unit is SENSOR Clock Cycles				
Value at Reset:	0x16e	0x16e				
Possible Values:	Any Value	Any Value between 1 and 255				

31	30	29	28	27	26	25	24
	Reserved						
23	22	21	20	19	18	17	16
			Reserved				KEEP_OUT_ TRIG_ENA
15	14	13	12	11	10	9	8
	KEEP_OUT_TRIG_START(15:8)						
7	6	5	4	3	2	1	0
	KEEP_OUT_TRIG_START(7:0)						

KEEP_OUT_TRIG_ENA	
RW	KEEPOUT zone TRIGger ENAble. When this register is enabled, then the trigger output will be synchronized with the line_int(monitor2) signal from the XGS sensor. To configure this keep out zone, use register READOUT_CFG4.
Value at Reset:	0x0

KEEP_OUT_TRIG_START (15:0)	
RW	During the line time, this register indicates the start of the trigger keep-out zone.
Value at Reset:	0xffff

EXP_CTRL1

31	30	29	28	27	26	25	24
	Reserved		EXPOSURE_ LEV_MODE		EXPOSURE	_SS(27:24)	
23	22	21	20	19	18	17	16
			EXPOSURE	_SS(23:16)			
15	14	13	12	11	10	9	8
	EXPOSURE_SS(15:8)						
7	6	5	4	3	2	1	0
	EXPOSURE_SS(7:0)						

EXPOSURE_LEV_MODE EXPOSURE LEVel MODE				
RW	This is the exposure level mode selector. When selecting the TRIGGER ACTIVATION = Level Mode, this register selects the exposure method used. When this register is set to '0' the timed mode is selected; Register EXPOSURE_SS is used for the exposure time. When this register is set to '1' the external trigger width is used for the exposure time.			
Value at Reset:	0x0	0x0		
Possible Values:	0x0 Timed Mode			
	0x1	Trigger Width		

EXPOSURE_SS (27:0)	EXPOSURE Single Slope				
RW	This is the total exposure time in single/dual/triple slope mode.				
	This register is double buffered.				
Value at Reset:	0x0				
Possible Values:	Any Value	Any 28 bits value			

EXP_CTRL2

31	30	29	28	27	26	25	24		
	Reserved				EXPOSURE_DS(27:24)				
23	22	21	20	19	18	17	16		
			EXPOSURE	_DS(23:16)					
15	14	13	12	11	10	9	8		
	EXPOSURE_DS(15:8)								
7	6	5	4	3	2	1	0		
	EXPOSURE_DS(7:0)								

EXPOSURE_DS (27:0)	EXPOSURE Dual	EXPOSURE Dual			
RW	This is a new 3d profiler feature We will be able to program upto 3 different exposure times (using unused multiSlope reg Then we will be able to sequence those exposure times. Selection is made with input exposure select.				
Value at Reset:	0x0	0x0			
Possible Values:	Any Value	Any 28 bits value			

EXP_CTRL3

31	30	29	28	27	26	25	24		
	Reserved				EXPOSURE_TS(27:24)				
23	22	21	20	19	18	17	16		
	EXPOSURE_TS(23:16)								
15	14	13	12	11	10	9	8		
	EXPOSURE_TS(15:8)								
7	6	5	4	3	2	1	0		
	EXPOSURE_TS(7:0)								

EXPOSURE_TS (27:0)	EXPOSURE Tripple			
RW	This is a new 3d profiler feature We will be able to program upto 3 different exposure times (using unused multiSlope registers. Then we will be able to sequence those exposure times. Selection is made with input exposure select.			
Value at Reset:	0x0			
Possible Values:	Any Value	Any 28 bits value		

TRIGGER_DELAY

31	30	29	28	27	26	25	24
	Reserved			TRIGGER_DELAY(27:24)			
23	22	21	20	19	18	17	16
TRIGGER_DELAY(23:16)							
15	14	13	12	11	10	9	8
	TRIGGER_DELAY(15:8)						
7	6	5	4	3	2	1	0
	TRIGGER_DELAY(7:0)						

TRIGGER_DELAY (27:0)	TRIGGER DELAY				
RW	This is the trigger delay. This trigger delay can be applied to HW(Only edge mode), SW and Continuous mode.				
	In HW level mode, the trigger cannot be delayed, since the level time represents the exposure time.				
	This register is double buffered				
Value at Reset:	0x0				
Possible Values:	Any Value Any 28 bits value				

STROBE_CTRL1

31	30	29	28	27	26	25	24
STROBE_E	Reserved		STROBE_PO L	STROBE_START(27:24)			
23	22	21	20	19	18	17	16
	STROBE_START(23:16)						
15	14	13	12	11	10	9	8
	STROBE_START(15:8)						
7	6	5	4	3	2	1	0
	STROBE_START(7:0)						

STROBE_E	STROBE Enable	STROBE Enable				
RW	This register enables the st	This register enables the strobe logic.				
	enabled. For Nexis 3 systems, to enabled. For Nexis 3 systems, STRO	For Nexis 3 systems, to enable STROBE_B signal, STROBE_E and STROBE_B_EN must be enabled. For Nexis 3 systems, STROBE_A and STROBE B can be activated at the same time, in this case the two strobes will be the same as they share the same programmation.				
Value at Reset:	0x0	0x0				
Possible Values:	0x0 S	Strobe disabled				
	0x1 Strobe enabled					

STROBE_POL	STROBE POLarity	STROBE POLarity			
RW	This is the strobe polarity	This is the strobe polarity at the pin of the FPGA only for GTR systems.			
	For NEXIS3 systems use register ANPUT\IO\IO_OUT_POL\OUTx_POL This register is not double buffered.				
Value at Reset:	0x0	0x0			
Possible Values:	0x0 Active high strobe				
	0x1 Active low strobe				

STROBE_START (27:0)	STROBE START	STROBE START				
RW	This is the strobe start lo	This is the strobe start location. This location depends on the Strobe Mode used.				
	In Strobe Mode='0', the start of the strobe is situated during the exposure time. In Strobe Mode='1', the start of the strobe is situated during the trigger delay. This register is double buffered					
Value at Reset:	0x0					
Possible Values:	Any Value Any 28 bits value					

STROBE_CTRL2

31	30	29	28	27	26	25	24
STROBE_MO DE	Reserved	STROBE_B_ EN	STROBE_A_ EN	STROBE_END(27:24)			
23	22	21	20	19	18	17	16
	STROBE_END(23:16)						
15	14	13	12	11	10	9	8
	STROBE_END(15:8)						
7	6	5	4	3	2	1	0
	STROBE_END(7:0)						

STROBE_MODE	STROBE MOD	STROBE MODE				
RW	This register sel	This register selects the location of the Strobe Start.				
	When this regis timer.	When this register is set to 0, the STROBE_START register is located during the exposure timer.				
	When this register is set to 1, the STROBE_START register is located during the trigger delay timer.					
	In HW level mode the strobe mode must be set to STROBE MODE=0 since the delayed.					
	This register is	This register is double buffered				
Value at Reset:	0x0	0x0				
Possible Values:	0x0	Strobe start during exposure				
	0x1 Strobe start during trigger delay					

STROBE_B_EN	STROBE phase B ENable					
RW	This field enables the generation of STROBE_B signal, for a NEXIS 3 system.					
	This register is double buffered to support back2back mode in nexts systems.					
Value at Reset:	0x0					
Possible Values:	0x0 Enable Strobe B					
	0x1	0x1 Disable Strobe B				

STROBE_A_EN	STROBE phase A ENable				
RW	This field enables the generation of STROBE_A signal(Default strobe), for a NEXIS 3 system.				
	This register is double buffered to support back2back mode in nexis systems.				
Value at Reset:	0x1				
Possible Values:	0x0 Enable Strobe A (default strobe)				
	0x1 Disable Strobe A				

STROBE_END (27:0)	STROBE END	STROBE END				
RW	This is the strobe end loo	This is the strobe end location. This location does not depend on the Strobe Mode used.				
	This register is double by	This register is double buffered				
Value at Reset:	0xfffffff	0xffffff				
Possible Values:	Any Value	Any 28 bits value				

31	30	29	28	27	26	25	24	
	Reserved							
23	22	21	20	19	18	17	16	
	Reserved						SER_RWn	
15	14	13	12	11	10	9	8	
	Reserved SEF					SER_C	MD(1:0)	
7	6	5	4	3	2	1	0	
	Reserved SER_RF_SS Reserved SER_WF_S						SER_WF_SS	

SER_RWn	SERial Read/V	SERial Read/Writen				
RW	This register co	This register configures the type of the serial access to the CMOS sensor				
Value at Reset:	0x1	0x1				
Possible Values:	0x0	Write access				
	0x1	Read access				

SER_CMD (1:0)	SERial CoMma	and				
RW	This is the type	This is the type of command sent to the serial fifo.				
		ensor, write SER_WF_SS=1 with SER_CMD=0x0, with the parametters: R_ADD(8:0) and SER_DAT(15:0).				
	To insert a timer between fifo commands, write SER_WF_SS=1 with SER_CMD=0x1 the parametter: SER_DAT(15:0). The value of the timer inserted is calculated with the following formula: Timer= SER_DAT(15:0)*1024*SYS_PERIOD, SYS_PERIOD is 1/62.5mhz. The granularity of the timer is 16.384us To insert a Stop separator command, write SER_WF_SS=1 with SER_CMD=0x3. Whe read logic encounter this command, it will stop read from the fifo until a new SER_RF					
	received.					
Value at Reset:	0x0	<u>-</u>				
Possible Values:	0x0	CMOS sensor access COMMAND				
	0x1 Insert timer COMMAND					
	0x2	STOP separator COMMAND				
	0x3	RESERVED				

SER_RF_SS	SERial Read Fifo SnapShot					
	This is the read fifo snapshot. When the read fifo logic receives this snapshot, it will read all the fifo comands until a STOP separator command is read or Empty fifo is detected.					
Possible Values:	0x0 Idle					
	0x1	Start Read FIFO				

SER_WF_SS	SERial Write Fifo SnapShot				
WO/AutoClr	When the system toggle this bit, the address, data and command are wrote to the command fifo. This fifo can contain the entire dcf, so the driver will not need to pool the status bit. T is a auto reset bit register, so after the driver write one, the bit will be auto reset to 0. To stath the FIFO read logic write '1' to register SER RF SS.				
Possible Values:	0x0 Idle 0x1 Write a command to the FIFO				

31	30	29	28	27	26	25	24	
SER_DAT(15:8)								
23	22	21	20	19	18	17	16	
SER_DAT(7:0)								
15	14	13	12	11	10	9	8	
Reserved	Reserved SER_ADD(14:8)							
7	6	5	4	3	2	1	0	
	SER_ADD(7:0)							

SER_DAT (15:0)	SERial interface D	SERial interface DATa				
RW		This is the write data to be send to the CMOS sensor by the serial interface, or the config data to a TIMER command or to a POWER sequence command. See register SER CMD.				
Value at Reset:	0x0	0x0				
Possible Values:	Any Value	Any 16 bits value				

SER_ADD (14:0) RW	SERial interface ADDress This is the read/write address of the register in the CMOS sensor.					
Value at Reset:	0x0					
Possible Values:	Any Value	Any 9 bits value				

31	30	29	28	27	26	25	24	
			Reserved				SER_FIFO_E MPTY	
23	22	21	20	19	18	17	16	
			Reserved				SER_BUSY	
15	14	13	12	11	10	9	8	
			SER_DA	Γ_R(15:8)				
7	6	5	4	3	2	1	0	
	SER_DAT_R(7:0)							

SER_FIFO_EMPTY	SERial FIFO EMPTY
RO	This is the EMPTY flag of the xilinx fifo, when '1' there are no pending operations in the fifo.

SER_BUSY	SERial BUS	SERial BUSY				
RO	SER_RF_SS	This is the BUSY status of the FIFO read logic. The flag will be set to '1' when the SER_RF_SS is set to '1'. It will be reseted to '0' when the read logic will decode a STOP separator command or when the FIFO will be empty.				
Possible Values:	0x0	0x0 FIFO read logic is idle				
	0x1	0x1 FIFO read logic is runnning				

SER_DAT_R (15:0)	SERial interface DATa Read				
RO	This is the data read from CMOS sensor.				
Possible Values:	Any Value	Any 16 bits value			

31	30	29	28	27	26	25	24
			Reserved				SENSOR_RE FRESH_TEM P
23	22	21	20	19	18	17	16
			Reserved				SENSOR_PO WERDOWN
15	14	13	12	11	10	9	8
			Reserved				SENSOR_CO LOR
7	6	5	4	3	2	1	0
	Reserved		SENSOR_RE G_UPDATE	Rese	erved	SENSOR_RE SETN	SENSOR_PO WERUP

SENSOR_REFRESH_TEMP	SENSOR REFRESH TEMPerature	
WO/AutoClr	This register starts a sensor temperature read on the serial interface of the Python sensor. The temperature value readed will be available on field SENSOR_TEMP when field SENSOR_TEMP_VALID is set to '1'. [Pas utilise pour le moment dans IRIS4]	
Possible Values:	0x0	Idle
	0x1	Starts a Temperature read on Python SPI interface

SENSOR_POWERDOWN	
	After a PowerUp sequence(SESOR_POWERUP_DONE=1), successfull or not, this register can reset the clock oscillator and enable the reset to the sensor.
	This power down don't do power sequencing.

SENSOR_COLOR	SENSOR COL	LOR		
RW		This register informs the datapath logic that a color sensor is used. This information is needed for the remapper logic.		
Value at Reset:	0x0	0x0		
Possible Values:	0x0	0x0 Monochrone sensor		
	0x1	Color sensor		

SENSOR_REG_UPDATE	SENSOR REC	SENSOR REGister UPDATE		
RW		By setting this bit to 1, the SENSOR CONTROLLER WILL UPDATE the programed CMOS sensor registers at the beginning of each grab.		
Value at Reset:	0x1	0x1		
Possible Values:	0x0	0x0 Do not update registers		
	0x1	Update registers		

SENSOR_RESETN	SENSOR RESET Not		
RW	After a successfull PowerUP sequence, writing this field to '0' reset the Python CMOS sensor.		
Value at Reset:	0x1		
Possible Values:	0x0	Reset the sensor after a successfull powerUP	
	0x1	Nothing	

SENSOR_POWERUP			
WO/AutoClr	This register Enables the clk oscillator and removes the reset from the sensor.		
Possible Values:	0x0	0x0 idle	
	0x1	Start the power sequence	

31	30	29	28	27	26	25	24
			SENSOR_	ΓΕΜΡ(7:0)			
23	22	21	20	19	18	17	16
SENSOR_TE MP_VALID			Rese	rved			SENSOR_PO WERDOWN
15	14	13	12	11	10	9	8
Reser	rved	SENSOR_RE SETN	SENSOR_OS C_EN		Reserved		SENSOR_VC C_PG
7	6	5	4	3	2	1	0
Reserved SENSOR_PO WERUP_STA T				SENSOR_PO WERUP_DO NE			

SENSOR_TEMP (7:0)		
RO	This register gives the Temperature of the Python sensor after a SENSOR_REFRESH_TEM snapshot. The field SENSOR_TEMP_VALID indicates when the SENSOR_TEMP value is valid.	
	[Pas utilise pour le moment dans IRIS4]	
Possible Values:	Any Value	

SENSOR_TEMP_VALID	SENSOR TEMPerature VALID		
RO	This field indicates that the field SENSOR_TEMP have valid temperature after a SENSOR_REFRESH_TEMP snapshot.		
	[Pas utilise pour le moment dans IRIS4]		
Possible Values:	0x0	SENSOR_TEMPERATURE register is not valid	
	0x1	SENSOR_TEMPERATURE register is valid	

SENSOR_POWERDOWN		
RO	This field indicates that the	he sensor is in powerdown state.
Possible Values:	Ox0 Not in powerdown state	
	0x1	Powerdown

SENSOR_RESETN	SENSOR RESET N	
RO	This is the sensor RESETN status.	
Possible Values:	0x0 In reset state	
	0x1	Not in reset

SENSOR_OSC_EN	SENSOR OS	SENSOR OSCILLATOR ENable		
RO	This is the se	This is the sensor oscillator enable status.		
Possible Values:	0x0	Disable		
	0x1	Enable		

SENSOR_VCC_PG	SENSOR sur	SENSOR supply VCC Power Good		
RO	This is the V	This is the VCC Power Good status (generated by external HW).		
	[TO BE DEL	[TO BE DELETED, waiting for ON SEMI INFORMATION]		
Possible Values:	0x0	Disable		
	0x1	Enable		

SENSOR_POWERUP_STAT				
RO	When a powerup sequence	hen a powerup sequence is finish, this register indicates the result of the POWERUP		
	equence.			
Possible Values:	0x0	PowerUp sequence fail		
	0x1	PowerUp sequence success		

SENSOR_POWERUP_DONE			
	This register indicates that the POWERUP sequence is finish. Read register SENSOR_POWERUP_STAT to see the result.		
Possible Values:	PowerUp sequence not started		
	0x1	PowerUp sequence finish	

SENSOR_SUBSAMPLING

Address: section "ACQ" base address + 0x09C

Description:

SENSOR ADDRESS

31	30	29	28	27	26	25	24
			Res	erved			
23	22	21	20	19	18	17	16
			Res	erved			
15	14	13	12	11	10	9	8
			reserve	ed1(11:4)			
7	6	5	4	3	2	1	0
	reserve	d1(3:0)		ACTIVE_SU BSAMPLING _Y	reserved0	M_SUBSAMP LING_Y	SUBSAMPLI NG_X
reserved1 (11:0))						

reserved1 (11:0)	
STATIC	
Value at Reset:	0x0

ACTIVE_SUBSAMPLING_Y		
RW	Subsampling (Row) for RO	OI Configurations
Value at Reset:	0x0	
Possible Values:	0x0	
	0x1	

reserved0		
STATIC		
Value at Reset:	0x0	
Possible Values:	0x0	Idle
	0x1	Enable

M_SUBSAMPLING_Y			
RW	Subsampling (Row) for M Region		
Value at Reset:	0x0		
Possible Values:	0x0		
	0x1		

SUBSAMPLING_X					
RW	Readout in Column Subsampling Mode. We don't use SUB_X in sensor, no fps advantages, and noise is increased! instead using DM subsampling.				
Value at Reset:	0x0				
Possible Values:	0x0	0x0			
	0x1				

SENSOR_GAIN_ANA

Address: section "ACQ" base address + 0x0A4

Description:

SENSOR ADDRESS 204 DEC

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
			Rese	erved			
15	14	13	12	11	10	9	8
	reserved1(4:0)				AN.	ALOG_GAIN(2	2:0)
7	6	5	4	3	2	1	0
			reserve	ed0(7:0)			

reserved1 (4:0)	
STATIC	
Value at Reset:	0x0

ANALOG_GAIN (2:0)		
RW		
Value at Reset:	0x1	
Possible Values:	0x1	1x
	0x3	2x
	0x7	4x

reserved0 (7:0)	
STATIC	
Value at Reset:	0x0

SENSOR_ROI_Y_START

Address: section "ACQ" base address + 0x0A8

Description:

SENSOR ADDRESS

31	30	29	28	27	26	25	24	
Reserved								
23	22	21	20	19	18	17	16	
	Reserved							
15	14	13	12	11	10	9	8	
	reserved(5:0) Y_START(9:8)							
7	6	5	4	3	2	1	0	
Y_START(7:0)								

reserved (5:0)	
STATIC	
Value at Reset:	0x0

Y_START (9:0)	Y START
RW	Y Start in Kernel size (Kernel is 4 lines)
Value at Reset:	0x0

SENSOR_ROI_Y_SIZE

Address: section "ACQ" base address + 0x0AC

Description:

SENSOR ADDRESS

31	30	29	28	27	26	25	24		
Reserved									
23	22	21	20	19	18	17	16		
Reserved									
15	14	13	12	11	10	9	8		
		reserv	ed(5:0)			Y_SIZE(9:8)			
7	6	5	4	3	2	1	0		
	Y_SIZE(7:0)								
reserved (5:0)									

reserved (5:0)	
STATIC	
Value at Reset:	0x0

Y_SIZE (9:0)	Y SIZE
RW	Y SIZE in Kernel size (Kernel is 4 lines)
Value at Reset:	0x302

SENSOR_M_LINES

31	30	29	28	27	26	25	24		
	Reserved								
23	22	21	20	19	18	17	16		
	Reserved								
15	14	13	12	11	10	9	8		
M_LINES_DI SPLAY	M_SUPPRESSED(4:0)								
7	6	5	4	3	2	1	0		
M_LINES_SENSOR(7:0)									

M_LINES_DISPLAY	
RW	When setting to 1, the Y_SIZE will have the Black lines included and the first_lines_mask_cnt will be set to 1, to remove only the embedded data
Value at Reset:	0x0

M_SUPPRESSED (4:0)	
RW	Suppress the Readout of Initial Lines in the M Region
Value at Reset:	0x0

M_LINES_SENSOR (9:0)	
RW	Number of Lines to Readout from M Region in Context 0 Unit is #lines
	Total number of Black lines = M_LINES Total number of Black lines transfered as valid Black lines= M_LINES-M_SUPRESSED
Value at Reset:	0x8

SENSOR_DP_GR

Address: section "ACQ" base address + 0x0BC

Description:

Sensor Analog data pedestal for Gr pixels (Black offset)

31	30	29	28	27	26	25	24	
Reserved								
23	22	21	20	19	18	17	16	
	Reserved							
15	14	13	12	11	10	9	8	
	reserved(3:0) DP_OFFSET_GR(11:8)							
7	6	5	4	3	2	1	0	
	DP_OFFSET_GR(7:0)							

reserved (3:0)	
STATIC	
Value at Reset:	0x0

DP_OFFSET_GR (11:0)	
RW	Sensor Analog data pedestal for Gr pixels (Black offset)
Value at Reset:	0x100

SENSOR_DP_GB

Address: section "ACQ" base address + 0x0C0

Description:

Sensor Analog data pedestal for Gb pixels (Black offset)

31	30	29	28	27	26	25	24	
	Reserved							
23	22	21	20	19	18	17	16	
	Reserved							
15	14	13	12	11	10	9	8	
	reserved(3:0) DP_OFFSET_GB(11:8)							
7	6	5	4	3	2	1	0	
	DP_OFFSET_GB(7:0)							

reserved (3:0)	
STATIC	
Value at Reset:	0x0

DP_OFFSET_GB (11:0)	
RW	Sensor Analog data pedestal for Gb pixels (Black offset)
Value at Reset:	0x100

SENSOR_DP_R

Address: section "ACQ" base address + 0x0C4

Description:

Sensor Analog data pedestal for R pixels (Black offset)

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
	reserved(3:0) DP_OFFSET_R(11:8)						
7	6	5	4	3	2	1	0
DP_OFFSET_R(7:0)							

reserved (3:0)	
STATIC	
Value at Reset:	0x0

DP_OFFSET_R (11:0)	
RW	Sensor Analog data pedestal for R pixels (Black offset)
Value at Reset:	0x100

SENSOR_DP_B

Address: section "ACQ" base address + 0x0C8

Description:

Sensor Analog data pedestal for B pixels (Black offset)

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
	reserved(3:0) DP_OFFSET_B(11:8)						
7	6	5	4	3	2	1	0
DP_OFFSET_B(7:0)							

reserved (3:0)	
STATIC	
Value at Reset:	0x0

DP_OFFSET_B (11:0)	
RW	Sensor Analog data pedestal for B pixels (Black offset)
Value at Reset:	0x100

SENSOR_GAIN_DIG_G

Address: section "ACQ" base address + 0x0CC

Description:

XGS Context0: R0x3846

31	30	29	28	27	26	25	24	
	Reserved							
23	22	21	20	19	18	17	16	
	Reserved							
15	14	13	12	11	10	9	8	
reserved1	DG_FACTOR_GR(6:0)							
7	6	5	4	3	2	1	0	
reserved0	DG_FACTOR_GB(6:0)							

reserved1	
STATIC	
Value at Reset:	0x0

DG_FACTOR_GR (6:0)							
RW	Digital Gain Factor for C	Digital Gain Factor for GREEN-R Pixels					
	B). The digital gain factor	ry gain 1.000 x2.00000 x0.03125					
Value at Reset:	0x20						
Possible Values:	0x1 - 0x7F Any value in range						

reserved0	
STATIC	
Value at Reset:	0x0

DG_FACTOR_GB (6:0)						
RW	Digital Gain Factor for GREEN-B Pixels					
	The digital gain can be configured to separate levels for each color channel (GR, GB, R and B). The digital gain factor ranges from 1/32 to 2 in steps of 1/32 (64 steps) and its configuration can berepresented by the equation below: Digital gain = Dg_factor/32 Dg_factor=0x20 is unitary gain 1.000 Dg_factor=0x40 is gain x2.00000 Dg_factor=0x01 is gain x0.03125 Dg factor=0x7f is gain x3.96875					
Value at Reset:	0x20					
Possible Values:	0x1 - 0x7F	Any value in range				

SENSOR_GAIN_DIG_RB

Address: section "ACQ" base address + 0x0D0

Description:

XGS Context0: R0x3848

31	30	29	28	27	26	25	24	
Reserved								
23	22	21	20	19	18	17	16	
			Rese	erved				
15	14	13	12	11	10	9	8	
reserved1	DG_FACTOR_R(6:0)							
7	6	5	4	3	2	1	0	
reserved0	DG_FACTOR_B(6:0)							

reserved1	
STATIC	
Value at Reset:	0x0

DG_FACTOR_R (6:0)							
RW	Digital Gain Factor for R	Digital Gain Factor for RED Pixels					
	B). The digital gain facto	y gain 1.000 x2.00000 x0.03125					
Value at Reset:	0x20						
Possible Values:	0x1 - 0x7F	Any value in range					

reserved0	
STATIC	
Value at Reset:	0x0

DG_FACTOR_B (6:0)							
RW	Digital Gain Factor for BLUE Pixels						
	B). The digital gain facto	y gain 1.000 x2.00000 x0.03125					
Value at Reset:	0x20						
Possible Values:	0x1 - 0x7F	Any value in range					

FPGA_ROI_X_START

31	30	29	28	27	26	25	24	
	Reserved							
23	22	21	20	19	18	17	16	
	Reserved							
15	14	13	12	11	10	9	8	
	Reserved X_START(12:8)							
7	6	5	4	3	2	1	0	
X_START(7:0)								

X_START (12:0)	X START	
RW	X Start in pixels (Kernel is 8 pixels), so 3lsb bits are not used.	
Value at Reset:	0x0	

FPGA_ROI_X_SIZE

31	30	29	28	27	26	25	24	
	Reserved							
23	22	21	20	19	18	17	16	
	Reserved							
15	14	13	12	11	10	9	8	
	Reserved X_SIZE(12:8)							
7	6	5	4	3	2	1	0	
	X_SIZE(7:0)							

X_SIZE (12:0)	X SIZE
RW	X SIZE in pixel size (Kernel is 8 pixel), so 3lsb bits are not used.
Value at Reset:	0x0

31	30	29	28	27	26	25	24	
Reserved				Debug3_sel(4:0)				
23	22	21	20	19	18	17	16	
Reserved			Debug2_sel(4:0)					
15	14	13	12	11	10	9	8	
Reserved					Debug1_sel(4:0)			
7	6	5	4	3	2	1	0	
Reserved					Debug0_sel(4:0)			

Debug3_sel (4:0)	
RW	debug_vector(0x0) <= python_monitor0;
	debug_vector(0x1) <= python_monitor1;
	debug_vector(0x2) <= grab_mngr_trig_rdy;
	debug_vector(0x3) <= curr_trig0;
	debug_vector(0x4) <= strobe;
	debug_vector(0x5) <= python_exposure;
	$debug_vector(0x6) \le FOT;$
	$debug_vector(0x7) \le readout;$
	debug_vector(0x8) <= readout_stateD;
	debug_vector(0x9) <= ext_trig;
	debug_vector(0xa) <= REGFILE.ACQ.GRAB_CTRL.GRAB_CMD;
	debug_vector(0xb) <= REGFILE.ACQ.GRAB_CTRL.GRAB_SS;
	debug_vector(0xc)<= grab_mngr_trig;
	debug_vector(0xd) <= grab_mngr_trig_rdy;
	debug_vector(0xe) <= grab_pending;
	debug_vector(0xf) <= grab_active;
	debug_vector(0x10) <= DEC_DATA_EN;
	debug_vector(0x11) <= DEC_SOL;
	debug_vector(0x12) <= DEC_SOF;
	debug_vector(0x13) <= DEC_EOL;
	debug_vector(0x14) <= DEC_EOF;
	debug_vector(0x15) <= DEC_CRC;
	debug_vector(0x16) <= DEC_TRAIN;
	debug_vector(0x17) <= fpnprnu_corr_sof;
	debug_vector(0x18) <= fpnprnu_corr_sol;
	debug_vector(0x19) <= fpnprnu_corr_data_val;
	debug_vector(0x1a) <= fpnprnu_corr_eol;
	debug_vector(0x1b) <= fpnprnu_corr_eof;
	debug_vector(0x1c) <= python_ssn_int;
	$debug_vector(0x1d) \le debug_lvds(0);$
	$debug_vector(0x1e) \le debug_vector(1);$
	$debug_vector(0x1f) \le 'Z';$
Value at Reset:	0x1f

```
Debug2 sel (4:0)
RW
                                    debug\_vector(0x0) \le python\_monitor0;
                                     debug_vector(0x1) <= python_monitor1;
                                    debug_vector(0x2) <= grab_mngr_trig_rdy;
debug_vector(0x3) <= curr_trig0;</pre>
                                     debug vector(0x4) \le strobe;
                                     debug_vector(0x5) <= python_exposure;
debug_vector(0x6) <= FOT;</pre>
                                     debug vector(0x7) \le readout;
                                     debug_vector(0x8) <= readout_stateD;</pre>
                                     debug_vector(0x9) <= ext_trig;
                                     debug_vector(0xa) <= REGFILE.ACQ.GRAB_CTRL.GRAB_CMD;</pre>
                                     debug_vector(0xb) <= REGFILE.ACQ.GRAB_CTRL.GRAB_SS;</pre>
                                     debug_vector(0xc)<= grab_mngr_trig;</pre>
                                     debug_vector(0xd) <= grab_mngr_trig_rdy;</pre>
                                     debug_vector(0xe) <= grab_pending;</pre>
                                     debug_vector(0xf) <= grab_active;</pre>
                                     debug_vector(0x10) <= DEC_DATA_EN;
debug_vector(0x11) <= DEC_SOL;
                                     debug vector(0x12) <= DEC SOF:
                                     debug_vector(0x13) <= DEC_EOL;
                                    debug_vector(0x14) <= DEC_EOF;
debug_vector(0x15) <= DEC_CRC;
debug_vector(0x16) <= DEC_TRAIN;
                                     debug_vector(0x17) <= fpnprnu_corr_sof;
                                     debug_vector(0x18) <= fpnprnu_corr_sol;
                                     debug_vector(0x19) <= fpnprnu_corr_data_val;
                                     debug_vector(0x1a) <= fpnprnu_corr_eol;
                                     debug vector(0x1b) \le fpnprnu corr eof;
                                     debug_vector(0x1c) <= python_ssn_int;
                                     debug_vector(0x1d) <= debug_lvds(0);</pre>
                                     debug_vector(0x1e) <= debug_lvds(1);
                                     debug\_vector(0x1f) \le 'Z';
Value at Reset:
                                    0x1f
```

```
Debug1_sel (4:0)
RW
                                   debug_vector(0x0) <= python_monitor0;</pre>
                                  debug_vector(0x1) <= python_monitor1;
                                   debug_vector(0x2) <= grab_mngr_trig_rdy;
                                   debug_vector(0x3) <= curr_trig0;
                                   debug\_vector(0x4) \le strobe;
                                   debug_vector(0x5) <= python_exposure;
                                  debug vector(0x6) <= FOT;
                                   debug\_vector(0x7) \le readout;
                                   debug_vector(0x8) <= readout_stateD;</pre>
                                   debug vector(0x9) \le ext trig
                                  debug_vector(0xa) <= REGFILE.ACQ.GRAB_CTRL.GRAB_CMD;
                                  debug_vector(0xb) <= REGFILE.ACQ.GRAB_CTRL.GRAB_SS;</pre>
                                   debug_vector(0xc)<= grab_mngr_trig;</pre>
                                   debug_vector(0xd) <= grab_mngr_trig_rdy;</pre>
                                   debug_vector(0xe) <= grab_pending;</pre>
                                  debug_vector(0xf) <= grab_active
                                   debug_vector(0x10) <= DEC_DATA_EN;
                                  debug_vector(0x11) <= DEC_SOL;
debug_vector(0x12) <= DEC_SOF;
debug_vector(0x13) <= DEC_EOL;
                                   debug vector(0x14) <= DEC EOF;
                                   debug_vector(0x15) <= DEC_CRC;
                                   debug_vector(0x16) <= DEC_TRAIN;</pre>
                                   debug_vector(0x17) <= fpnprnu_corr_sof;
                                  debug_vector(0x18) <= fpnprnu_corr_sol;
                                   debug_vector(0x19) <= fpnprnu_corr_data_val;
                                   debug_vector(0x1a) <= fpnprnu_corr_eol;</pre>
                                   debug_vector(0x1b) <= fpnprnu_corr_eof;
                                   debug_vector(0x1c) <= python_ssn_int;</pre>
                                   debug_vector(0x1d) <= debug_lvds(0);
                                   debug_vector(0x1e) <= debug_lvds(1);
                                   \underline{\text{debug\_vector}(0x1f)} \le \underline{\text{'Z'}};
Value at Reset:
                                  0x1f
```

Debug0_sel (4:0)	
RW	debug_vector(0x0) <= python_monitor0;
	debug_vector(0x1) <= python_monitor1;
	debug_vector(0x2) <= grab_mngr_trig_rdy;
	debug_vector(0x3) <= curr_trig0;
	debug_vector(0x4) <= strobe;
	debug_vector(0x5) <= python_exposure;
	$ debug_vector(0x6) <= FOT;$
	$debug_vector(0x7) \le readout;$
	debug_vector(0x8) <= readout_stateD;
	debug_vector(0x9) <= ext_trig;
	debug_vector(0xa) <= REGFILE.ACQ.GRAB_CTRL.GRAB_CMD;
	debug_vector(0xb) <= REGFILE.ACQ.GRAB_CTRL.GRAB_SS;
	debug_vector(0xc)<= grab_mngr_trig;
	debug_vector(0xd) <= grab_mngr_trig_rdy;
	debug_vector(0xe) <= grab_pending;
	debug_vector(0xf) <= grab_active;
	debug_vector(0x10) <= DEC_DATA_EN;
	debug_vector(0x11) <= DEC_SOL;
	debug_vector(0x12) <= DEC_SOF;
	$debug_vector(0x13) \le DEC_EOL;$
	debug_vector(0x14) <= DEC_EOF;
	$debug_vector(0x15) \le DEC_CRC;$
	$debug_vector(0x16) \le DEC_TRAIN;$
	$debug_vector(0x17) \le fpnprnu_corr_sof;$
	$debug_vector(0x18) \le fpnprnu_corr_sol;$
	debug_vector(0x19) <= fpnprnu_corr_data_val;
	debug_vector(0x1a) <= fpnprnu_corr_eol;
	debug_vector(0x1b) <= fpnprnu_corr_eof;
	debug_vector(0x1c) <= python_ssn_int;
	$debug_vector(0x1d) \le debug_lvds(0);$
	debug_vector(0x1e) <= debug_lvds(1);
	$debug_vector(0x1f) <= 'Z';$
Value at Reset:	0x1f

TRIGGER_MISSED

31	30	29	28	27	26	25	24	
Reserved TRIGGER_MI Reserved SSED_RST								
23	22	21	20	19	18	17	16	
	Reserved							
15	14	13	12	11	10	9	8	
			TRIGGER_MISSE	ED_CNTR(15:	8)			
7	6	5	4	3	2	1	0	
	TRIGGER_MISSED_CNTR(7:0)							

TRIGGER_MISSED_RST TRIGGER MISSED ReSeT					
WO/AutoClr	This is the trigger missed reset.				
Possible Values:	0x1	Reset the Trigger counter reset			

TRIGGER_MISSED_CNTR (15:0)	TRIGGER MISSED Coul	NTeR
RO	This is the number of trigg	ger missed detected.
Possible Values:	Any Value	·

SENSOR_FPS

31	30	29	28	27	26	25	24		
Reserved									
23	22	21	20	19	18	17	16		
	Reserved								
15	14	13	12	11	10	9	8		
	SENSOR_FPS(15:8)								
7	6	5	4	3	2	1	0		
	SENSOR_FPS(7:0)								

SENSOR_FPS (15:0)	SENSOR Frame Per Second
	This is the number of frames received in 1 second interval. This register can count up to 64k frame/s. This counter counts on SO_FOT event.

SENSOR_FPS2

31	30	29	28	27	26	25	24		
Reserved									
23	22	21	20	19	18	17	16		
	Reserved				SENSOR_FPS(19:16)				
15	14	13	12	11	10	9	8		
	SENSOR_FPS(15:8)								
7	6	5	4	3	2	1	0		
			SENSOR	_FPS(7:0)					

SENSOR_FPS (19:0)	SENSOR Frame Per Second
	This is the number of frames received in 10 second interval. This register can count up to 1.049 million frames. This counter counts on SO FOT event.

31	30	29	28	27	26	25	24	
	Reserved		DEBUG_RST _CNTR					
23	22	21	20	19	18	17	16	
	Reserved							
15	14	13	12	11	10	9	8	
			Rese	rved				
7	6	5	4	3	2	1	0	
Reserved				LED_TEST_0	COLOR(1:0)	LED_TEST		

DEBUG_RST_CNTR					
RW	This register clears the	This register clears the debug cntrs			
Value at Reset:	0x1				
Possible Values:	0x0				
	0x1	Reset counters			

LED_TEST_COLOR (1:0) RW		
Value at Reset:	0x0	
Possible Values:	0x0	The LED is OFF
	0x1	The LED is GREEN
	0x2	The LED is RED
	0x3	The LED is ORANGE

LED_TEST						
RW		This register will put the LED status in test mode. The test mode is controlled by LED_TEST_COLOR				
Value at Reset:	0x0					
Possible Values:	0x0	The LED is in user mode.				
	0x1	The LED is in test mode.				

DEBUG_CNTR1

31	30	29	28	27	26	25	24
	Reserved			SENSOR_FRAME_DURATION(27:24)			
23	22	21	20	19	18	17	16
	SENSOR_FRAME				3:16)		
15	14	13	12	11	10	9	8
	SENSOR_FRAME_DURATION(15:8)						
7	6	5	4	3	2	1	0
	SENSOR FRAME DURATION(7:0)						

SENSOR_FRAME_DURATI ON (27:0)				
	This is the time between the last 2 EOF received(in sys clock domain). This register can count up to 4.29 seconds. It can be used to predict sensor framerate or to verify sync between 3D profiler heads. This feature is enabled by setting register regfile.ACQ.DEBUG.DEBUG_RST_CNTR to 0.			
Possible Values:	Any Value	Any 28 bits value		

31	30	29	28	27	26	25	24
	Reserved						
23	22	21	20	19	18	17	16
Reserved							EXP_FOT
15	14	13	12	11	10	9	8
	Reserved				EXP_FOT_	TIME(11:8)	
7	6	5	4	3	2	1	0
	EXP_FOT_TIME(7:0)						

EXP_FOT	EXPosure durin	ng FOT		
RW	exposure in the EXP_FOT_TIME	When set to '1' this register, the output exposure and strobe signals will take into account the exposure in the FOT of the frame. This timing must be programmed in register EXP_FOT_TIME. This timing must be calculated from the OnSemi setting files.		
Value at Reset:	0x1	0x1		
Possible Values:	0x0	0x0 Disable exposure during FOT in output exposure signal and Strobe		
	0x1	Enable exposure during FOT in output exposure signal and Strobe		

EXP_FOT_TIME (11:0)	EXPosure during FOT TIME			
RW	This is the time of the exposure during the FOT. This timing must be calculated from the OnSemi setting files .			
	From DCF v1.2, for all LVDS modes:			
	P5000 & P2000 EXP_FOT=40.666us, program value 0x9ee			
	P1300 & P500 & P300 EXP_FOT=27.333us, program value 0x6ac			
Value at Reset:	0x9ee			

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
Reserved							
7	6	5	4	3	2	1	0
Reserved						RELOAD_GR	
							AB PARAMS

RELOAD_GRAB_PARAMS					
RW	This register is not used for the moment. It may be used in the future to reload the exposure time				
Value at Reset:	0x1				
Possible Values:	0x0				
	0x1				

TIMER_CTRL

31	30	29	28	27	26	25	24
			Resei	rved			
23	22	21	20	19	18	17	16
			Resei	rved			
15	14	13	12	11	10	9	8
	Reserved				ADAPTATIV E		
7	6	5	4	3	2	1	0
Reserved TIMERSTOP				Reserved		TIMERSTAR T	

ADAPTATIVE					
RW	not generate trigger miss	When this field is set to 1, the timer will adapt the trigger to the trigger_rdy of the controller to not generate trigger missed. When the timer is programmed too fast and the ADAPTATIVE field is set to 0, trigger missed will be generated.			
Value at Reset:	0x1	0x1			
Possible Values:	0x0	0x0 Non adaptative			
	0x1	Ox1 Adaptative to trigger_rdy			

TIMERSTOP	
WO/AutoClr	This field stops the internal programmable Timer Trigger

TIMERSTART	
WO/AutoClr	This field starts the internal programmable Timer Trigger.

TIMER_DELAY

31	30	29	28	27	26	25	24	
	VALUE(31:24)							
23	22	21	20	19	18	17	16	
	VALUE(23:16)							
15	14	13	12	11	10	9	8	
	VALUE(15:8)							
7	6	5	4	3	2	1	0	
			VALU	JE(7:0)				

VALUE (31:0)	
RW	This register sets the delay for the first trigger generated when the timer is used.
	This register is double buffered with TimerStart register.
Value at Reset:	0x0

TIMER_DURATION

31	30	29	28	27	26	25	24
			VALUE	E(31:24)			
23	22	21	20	19	18	17	16
	VALUE(23:16)						
15	14	13	12	11	10	9	8
	VALUE(15:8)						
7	6	5	4	3	2	1	0
	VALUE(7:0)						

VALUE (31:0)	
	This register sets the timer duration. When the counter reaches the value programmed in this register the counter will be reseted to 0. The trigger will be generated when the counter reaches value 0x1. This register is double buffered with TIMERSTART register.
Value at Reset:	0x0

Address Range: [0x400 - 0x454]

CTRL

31	30	29	28	27	26	25	24	
	Reserved							
23	22	21	20	19	18	17	16	
	Reserved							
15	14	13	12	11	10	9	8	
	Reserved							
7	6	5	4	3	2	1	0	
	Reserved			SW_CLR_HIS	SW_CALIB_S		ENABLE_HIS	
			ELAYCTRL	PI	ERDES	TA_PATH	Pl	

SW_CLR_IDELAYCTRL	Reset the Xilinx macro I	DELAYCTRL
RW		
Value at Reset:	0x1	
Possible Values:	0x0	No effect
	0x1	Reset IDELAYCTRL

SW_CLR_HISPI	
RW	
Value at Reset:	0x0

SW_CALIB_SERDES	Initiate the SERDES TAP calibration				
WO/AutoClr					
Possible Values:	0x0	No effect			
	0x1	Initiate the calibration			

ENABLE_DATA_PATH	
RW	
Value at Reset:	0x0

ENABLE_HISPI	
RW	
Value at Reset:	0x0

31	30	29	28	27	26	25	24	
	FSM(3:0)				Reserved			
23	22	21	20	19	18	17	16	
			Rese	erved				
15	14	13	12	11	10	9	8	
			Rese	erved				
7	6	5	4	3	2	1	0	
	Reserved		CRC_ERROR	PHY_BIT_LO CKED_ERRO R	FIFO_ERROR	CALIBRATIO N_ERROR	CALIBRATIO N_DONE	

FSM (3:0)	HISPI finite state machine status				
RO					
Possible Values:	0x0	S_DISABLED			
	0x1	S_IDLE			
	0x2	S_RESET_PHY			
	0x3	S_INIT			
	0x4	S_START_CALIBRATION			
	0x5	S_CALIBRATE			
	0x6	S_PACK			
	0x7	S_FLUSH_PACKER			
	0x8	S_SOF			
	0x9	S_EOF			
	0xA	S_SOL			
	0xB	S_EOL			
	0xC	Reserved			
	0xD	Reserved			
	0xE	FSM error (Unknown state)			
	0xF	S DONE			

CRC_ERROR	Lane CRC error				
RO					
Possible Values:	0x0	No lane CRC error occured			
	0x1	Lane CRC error occured			

PHY_BIT_LOCKED_ERRO R	
RO	

FIFO_ERROR	Calibration active			
RO				
Possible Values:	0x0	No FiFo error occured		
	0x1	FiFo error occured		

CALIBRATION_ERROR	Calibration error	Calibration error			
RO					
Possible Values:	0x0	No calibration error			
	0x1	A calibration error occured			

CALIBRATION_DONE	Calibration sequence completed				
RO					
Possible Values:	0x0	Calibration sequence not completed			
	0x1	Last calibration sequence completed successfully			

IDELAYCTRL_STATUS

31	30	29	28	27	26	25	24	
	Reserved							
23	22	21	20	19	18	17	16	
			Res	erved				
15	14	13	12	11	10	9	8	
			Res	erved				
7	6	5	4	3	2	1	0	
	Reserved						PLL_LOCKE	
							ן ט ן	

PLL_LOCKED	IDELAYCTR	DELAYCTRL PLL locked		
RO				
Possible Values:	0x0	IDELAYCTRL PLL unlocked		
	0x1	IDELAYCTRL PLL locked		

IDLE_CHARACTER

31	30	29	28	27	26	25	24
	Reserved						
23	22	21	20	19	18	17	16
	Reserved						
15	14	13	12	11	10	9	8
Reserved				VALUI	E(11:8)		
7	6	5	4	3	2	1	0
VALUE(7:0)							

VALUE (11:0)		
RW		
Value at Reset:	0x3A6	
Possible Values:	Any Value	

31	30	29	28	27	26	25	24
	Reserved					PIXEL_PER	R_LANE(9:8)
23	22	21	20	19	18	17	16
	PIXEL_PER_LANE(7:0)						
15	14	13	12	11	10	9	8
		Reserved			N	MUX_RATIO(2:	0)
7	6	5	4	3	2	1	0
		Reserved				NB_LANES(2:0))

PIXEL_PER_LANE (9:0)	Number of pixels per	Number of pixels per lanes		
RW				
Value at Reset:	0xAE			
Possible Values:	Any Value			

MUX_RATIO (2:0)	
STATIC	This is the configuration MUX ratio of the XGS sensor used. For GTX camera the mux ratio is fixed and set to 4.
Value at Reset:	0x4

NB_LANES (2:0)	Number of physical lane enabled		
RW	This is the physical number of HiSPI lanes available for the XGS sensor used. In GTX camera configuration: - Must be set to 4 in XGS5000, XGS3000, XGS2000 and XGS1300. - Must be set to 6 in XGS16M, XGS12M, XGS9.4M and XGS8M XGS1300.		
Value at Reset:	0x0		
Possible Values:	0x0	All lanes are disabled	
	0x4	4 lanes enabled	
	0x6	6 lanes enabled	
	Others	Reserved (All lanes are disabled)	

FRAME_CFG

31	30	29	28	27	26	25	24
	Reserved			LINES_PER_FRAME(11:8)			
23	22	21	20	19	18	17	16
			LINES_PER_	FRAME(7:0)			
15	14	13	12	11	10	9	8
	Reserved			PIXI	ELS_PER_LINE((12:8)	
7	6	5	4	3	2	1	0
			PIXELS PER	R LINE(7:0)			

LINES_PER_FRAME (11:0)	
RW	This is the total number of lines in a frame including dummy, BL, Interpolation and valid pixels. Reset value is 3102 (XGS12M). The value may change depending on the Black Lines(BL) programmed in the M-LINES section of the frame. Reset value is 3102 (0xc1e, XGS12M)
Value at Reset:	0xc1e

PIXELS_PER_LINE (12:0)	
	This is the total number of pixel in a line, including dummy, BL, Interpolation and valid pixels. Reset value is 4176 (0x1050, XGS12M)
Value at Reset:	0x1050

FRAME_CFG_X_VALID

31	30	29	28	27	26	25	24
	Reserved				X_END(12:8)		
23	22	21	20	19	18	17	16
			X_EN	D(7:0)			
15	14	13	12	11	10	9	8
	Reserved				X_START(12:8)		
7	6	5	4	3	2	1	0
			X_STA	RT(7:0)			

X_END (12:0)	
RW	This register defines the position of the last horizontal valid pixel (including initials dummy pixels, black reference pixels and interpolation pixels). The location of the last X valid pixel differs between XGS family members and configurations. The dcf will load the location of the X end. It is defined as 1-based number
	For XGS12000, in a monochrome sensor the x end is 4132 (0x1024). For XGS12000, in a color sensor the x end is 4136 (0x1028). (For BAYER correction)
Value at Reset:	0x1023

X_START (12:0)	
RW	This register defines the position of the first horizontal valid pixel (including dummy pixels, black reference pixels and interpolation pixels). The location of the first X valid pixel differs between XGS family members and configurations. The dcf will load the location of the X start. It is defined as 1-based number
	For XGS12000, in a monochrome sensor the x start is 36 (0x24). For XGS12000, in a color sensor the x start is 32 (0x22). (For BAYER correction)
Value at Reset:	0x24

LANE_DECODER_STATUS

(5:0)

Address: section "HISPI" base address + 0x024 + (index * 0x4)

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
Rese			erved				
15	14	13	12	11	10	9	8
CRC_ERROR	PHY_SYNC_ ERROR	PHY_BIT_LO CKED_ERRO R	PHY_BIT_LO CKED		Reserved		CALIBRATIO N_TAP_VAL UE(4)
7	6	5	4	3	2	1	0
CALIBRATION_TAP_VALUE(3:0)			CALIBRATIO N_ERROR	CALIBRATIO N_DONE	FIFO_UNDE RRUN	FIFO_OVERR UN	

CRC_ERROR	CRC Error	
RW2C		
Value at Reset:	0x0	
Possible Values:	0x0	CRC no error occured
	0x1	CRC error occured

PHY_SYNC_ERROR		
RW2C		
Value at Reset:	0x0	
Possible Values:	0x0	Pixel bit boundaries unlocked
	0x1	Pixel bit boundaries locked

PHY_BIT_LOCKED_ERRO		
RW2C		
Value at Reset:	0x0	
Possible Values:	0x0	Pixel bit boundaries unlocked
	0x1	Pixel bit boundaries locked

PHY_BIT_LOCKED		
RO		
Possible Values:	0x0	Pixel bit boundaries unlocked
	0x1	Pixel bit boundaries locked

CALIBRATION_TAP_VALU E (4:0)	
RO	

CALIBRATION_ERROR	
RW2C	
Value at Reset:	0x0
CALIBRATION_DONE	
RO	
FIFO_UNDERRUN RW2C	
Value at Reset:	0x0
FIFO_OVERRUN	
RW2C	
Value at Reset:	0x0

TAP_HISTOGRAM (5:0)

Address: section "HISPI" base address + 0x03C + (index * 0x4)

31	30	29	28	27	26	25	24
			VALUE	E(31:24)			
23	22	21	20	19	18	17	16
			VALUE	E(23:16)			
15	14	13	12	11	10	9	8
			VALU	E(15:8)			
7	6	5	4	3	2	1	0
			VALU	TE(7:0)			

VALUE (31:0)	
RO	

DEBUG

31	30	29	28	27	26	25	24
MANUAL_C L	OAD_TAPS	2)		AP_LANE_5(4			TAP_LANE_4
ALIB_EN	22	21	20	10	10	17	(4)
23	22 TAP_LAN	21 NE 4(3:0)	20	19	18 TAP_LAN	17 F 3(4:1)	16
15	14 14	13	12	11	10	<u>6_3(4.1)</u> 9	8
TAP_LANE_3	11	•	ΓAP_LANE_2(4:		10		ANE_1(4:3)
(0)			·	·			
7	6	5	4	3	2	1	0
TAI	P_LANE_1(2:	0)		1	<u> AP_LANE_0(4:0)</u>)	
MANUAL_CAL	IR FN						
RW	ID_LIV						
Value at Reset:		0x0					
LOAD_TAPS							
WO/AutoClr							
TAB TABLE 5 (4.0\						
TAP_LANE_5 (4	1: 0)						
Value at Reset:		0x0					
TAP_LANE_4 (4	1:0)						
RW							
Value at Reset:		0x0					
TAP_LANE_3 (4	1.0)						
RW	r.U)						
Value at Reset:		0x0					
		'					
TAP_LANE_2 (4	1:0)						
RW							
Value at Reset:		0x0					
TAP_LANE_1 (4	1.0)						
RW	r.U <i>)</i>						
Value at Reset:		0x0					
		•					

TAP_LANE_0 (4:0)	
RW	
Value at Reset:	0x0

Section: DPC

Address Range: [0x480 - 0x498]

DPC_CAPABILITIES

31	30	29	28	27	26	25	24
	Rese	rved			DPC_LIST_LI	ENGTH(11:8)	
23	22	21	20	19	18	17	16
			DPC_LIST_L	ENGTH(7:0)			
15	14	13	12	11	10	9	8
	Reserved						
7	6	5	4	3	2	1	0
	Reserved				DPC_VI	ER(3:0)	

DPC_LIST_LENGTH (11:0)	
	This register defines the maximum number of pixels that can be corrected by the DPC module. (ONE-based). This register is calculated with formula: (2^DPC_CORR_PIXELS_DEPTH)-1, where DPC_CORR_PIXELS_DEPTH is a generic to the DPC module. For GTX value is 511

DPC_VER (3:0)					
RO	Implemented version of the DPC module				
Possible Values:	0x0 Initial monochrone correction only, 2 lines buffered.				

DPC_LIST_CTRL

31	30	29	28	27	26	25	24
Rese	rved	dpc_fifo_reset	dpc_firstlast_li ne_rem		dpc_list_co	ount(11:8)	
23	22	21	20	19	18	17	16
	dpc_list_count(7:0)						
15	14	13	12	11	10	9	8
dpc_pattern0_ cfg	dpc_enable	dpc_list_WRn	dpc_list_ss		dpc_list_a	ndd(11:8)	
7	6	5	4	3	2	1	0
			dpc_list_	add(7:0)			

dpc_fifo_reset							
RW		Write '1' then '0' to field dpcL_FIFO_RST to reset overrun/underrun flags of the line buffe and reset the Fifo logic.					
	The DPC dual	The DPC dual port ram is not SW reset.					
	The fifo in each	The fifo in each processing DPC unit is HW reset at each SOF.					
Value at Reset:	0x0						
Possible Values:	0x0	Fifo in normal operation					
	0x1	Fifo in reset State					

dpc_firstlast_line_rem							
RW	corrected. This can be us program two	When this register is set to 1, the DPC macro will remove the first and last line of the image corrected. This can be usefull if we want to correct the 4 pixels in the corners of the image. The SW can program two more lines in the frame so the DPC macro can have enough pixels to correct the 4 pixel coners.					
Value at Reset:	0x0	0x0					
Possible Values:	0x0	0x0 Do not remove any lines of the image received					
	0x1	0x1 Remove first and last line of the image received					

dpc_list_count (11:0)				
RW	This is the number of entries in the DPC list. The driver need to set the dcp_list_count in order to correct the image. The value 0 is allowed and when set to 0 no pixel will be corrected. Up to (2^DPC_CORR_PIXELS_DEPTH)-1 pixels can be corrected. In GTX_DPC_CORR_PIXELS_DEPTH is set to 9, up to 511 pixels may be corrected.			
Value at Reset:	0x0			
Possible Values:	Any Value	0 to 2^DPC_CORR_PIXELS_DEPTH		

dpc_pattern0_cfg			
RW	This field configures the behabieur of the correction pattern 0x0. If this field is set to 0x0 then the current pixel will not be corrected. If this field is set to 0x1 then the current pixel will be replaced by the value 0x3ff (white pixel)		
Value at Reset:	0x0		
Possible Values:	0x0	Do not correct current pixel	
	0x1	Replace current pixel by a white pixel (0x3ff)	

dpc_enable				
RW	the dead pixels	Dead Pixel Correction core Enable, when this field is set to 1, the DPC logic will correct all the dead pixels that are listed in the DPC list. The grab must be idle when changing this register.		
Value at Reset:	0x0			
Possible Values:	0x0	0x0 DPC logic is bypassed		
	0x1	DPC logic is enabled		

dpc_list_WRn				
RW	with the dpc_l	This is the Write/ReadN flag. To write to the DPC list set this bit to 1 and start the transaction with the dpc_list_ss field. To read from the DPC list set this bit to 0 and start the transaction with the dpc_list_ss field.		
Value at Reset:	0x0			
Possible Values:	0x0	Read list operation		
	0x1	Write list operation		

dpc_list_ss					
WO/AutoClr		This is the DPC snapshot. In order to start a write or read transaction the snapsot needs to be writen to '1'. This bit is a auto clear regsiter.			
Possible Values:	0x0	Do nothing			
	0x1	Start the READ/WRITE transaction			

dpc_list_add (11:0)	
RW	This is the address of the DPC list to be access by the read/write operation. Pixel 0 to correct is located at address 0x000. In GTX_DPC_CORR_PIXELS_DEPTH is set to 9, up to 511 pixels may be corrected. Since the dpc_list_count field is also 9 bit wide, address 0 to 0x1fe of the list can be used. Adress 0x1ff cannot be used. This DPC location will not be corrected.
Value at Reset:	0x0
Possible Values:	Valid DPC adress

DPC_LIST_STAT

31	30	29	28	27	26	25	24
dpc_fifo_unde rrun	dpc_fifo_overr un			Rese	rved		
23	22	21	20	19	18	17	16
			Rese	erved			
15	14	13	12	11	10	9	8
			Rese	erved			
7	6	5	4	3	2	1	0
			Rese	erved			

dpc_fifo_underrun						
		his is the fifo underrun status of the 2 linebuffers in the dpc macro. Write '1' then '0' to field pc FIFO RST to reset this flag and reset the Fifo logic.				
Possible Values:	x0 Underrun not detected					
	0x1	Underrun detected				

dpc_fifo_overrun						
RO		This is the fifo overrun status of the 2 linebuffers in the dpc macro. Write '1' then '0' to field dpc FIFO RST to reset this flag and reset the Fifo logic.				
Possible Values:	0x0	Overrun not detected				
	0x1	Overrun detected				

DPC_LIST_DATA1

31	30	29	28	27	26	25	24
	Reserved			dpc_list_corr_y(11:8)			
23	22	21	20	19	18	17	16
			dpc_list_co	orr_y(7:0)			
15	14	13	12	11	10	9	8
	Reserved			dŗ	oc_list_corr_x(12	:8)	
7	6	5	4	3	2	1	0
			dpc_list_co	orr_x(7:0)			

dpc_list_corr_y (11:0)	
RW	This is Y location of the pixel to be corrected when executing a write to the DPC list.
Value at Reset:	0x0

dpc_list_corr_x (12:0)	
RW	This is X location of the pixel to be corrected when executing a write to the DPC list.
Value at Reset:	0x0

DPC_LIST_DATA2

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
			Rese	erved			
15	14	13	12	11	10	9	8
			Rese	erved			
7	6	5	4	3	2	1	0
			dpc_list_cor	r_pattern(7:0)			

dpc_list_corr_pattern (7:0)	
RW	This is pattern of the pixel to be corrected when executing a write to the DPC list.
	2 bit correction: 34, 17, 136, 68 4 bit correction: 170, 153, 51, 204, 85, 102 6 bit correction: 187,238 (mapped to 170), 119,221 (mapped to 85) 8 bit correction: 255 Set pixel to 255 (white), debug: 0
Value at Reset:	0x0

DPC_LIST_DATA1_RD

31	30	29	28	27	26	25	24
Reserved				dpc_list_corr_y(11:8)			
23	22	21	20	19	18	17	16
			dpc_list_co	orr_y(7:0)			
15	14	13	12	11	10	9	8
Reserved				dţ	pc_list_corr_x(12	:8)	
7	6	5	4	3	2	1	0
			dpc_list_co	orr_x(7:0)			

dpc_list_corr_y (11:0)	
RO	This is Y location of the pixel to be corrected when executing a write to the DPC list.

dpc_list_corr_x (12:0)	
RO	This is X location of the pixel to be corrected when executing a write to the DPC list.

DPC_LIST_DATA2_RD

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
			Rese	erved			
15	14	13	12	11	10	9	8
			Rese	erved			
7	6	5	4	3	2	1	0
			dpc_list_cor	r_pattern(7:0)			

dpc_list_corr_pattern (7:0)	
RO	This is pattern of the pixel to be corrected when executing a write to the DPC list.
	2 bit correction: 34, 17, 136, 68 4 bit correction: 170, 153, 51, 204, 85, 102 6 bit correction: 187,238 (mapped to 170), 119,221 (mapped to 85) 8 bit correction: 255 Set pixel to 255 (white), debug: 0

Section: LUT

Address Range: [0x4B0 - 0x4B8]

LUT_CAPABILITIES

31	30	29	28	27	26	25	24
	Rese	rved			LUT_SIZE_C	ONFIG(11:8)	
23	22	21	20	19	18	17	16
			LUT_SIZE_C	CONFIG(7:0)			
15	14	13	12	11	10	9	8
			Rese	rved			
7	6	5	4	3	2	1	0
Reserved LUT_VER(3:0)							

LUT_SIZE_CONFIG (11:0)		
RO		
Possible Values:	0x0	Reserved
	0x1	10 to 8 bits LUT (Mono Only)
	0x2	8 to 8 bits RGB LUT (Color Only)

LUT_VER (3:0)				
RO	Implemented version of the LUT module			
Possible Values:	0x0	Initial monochrone LUT		
	0x1	Initial color LUT		

LUT_CTRL

31	30	29	28	27	26	25	24
Rese	erved	LUT_BYPAS S_COLOR	LUT_BYPAS S	Rese	rved	LUT_DAT	ΓA_W(9:8)
23	22	21	20	19	18	17	16
			LUT_DAT	CA_W(7:0)			
15	14	13	12	11	10	9	8
	LUT_S	SEL(3:0)		LUT_WRN	LUT_SS	LUT_A	DD(9:8)
7	6	5	4	3	2	1	0
	LUT_ADD(7:0)						

LUT_BYPASS_COLOR	LUT BYPASS COLOR
RW	When set this register to '1', the RGB LUT logic will not be used, and the 8 bits of the input data will send to the DMA. Bypassing the LUT, decrease power comsunption of the fpga.
	This register applies to: 1) Color sensors 10 to 8 per component LUT (between CCM and DMA/YUV conversion)
Value at Reset:	0x1

LUT_BYPASS	LUT BYPASS		
RW When set this register to '1', the LUT will not be used			
	This register applies to: 1) Mono sensors 10 to 8 LUT 2) Color sensors 10 to 10 LUT (between DPC and WB) If a 10 to 8 LUT is used, the 8MSB bits of the input data will send to the DMA. Bypassing the LUT, decrease power comsumption of the fpga.		
Value at Reset:	0x1		

LUT_DATA_W (9:0)	LUT DATA to Write
RW	Data to write in the LUT.
	When using 10 to 8 bits LUT (Mono camera), program bits LUT_DATA_W(7:0) When using 8 to 8 bits LUT (Color camera, RGB LUT), program bits LUT_DATA_W(7:0) When using 10 to 10 bits LUT(Color camera RAW LUT), program bits LUT_DATA_W(9:0)
Value at Reset:	0x0

LUT_SEL (3:0)	LUT SELectio	LUT SELection				
RW	LUT programm	LUT programmation selector.				
Value at Reset:	0x0	0x 0				
Possible Values:	0x1	Write Blue LUT(Color only)				
	0x2	Write Green LUT(Color only)				
	0x4	Write Red LUT(Color only)				
	0x7	Write all component RGB LUT (Color only)				
	0x8	Write LUT 10 to 8(Mono) or LUT 10 to 10(color) with same data				

LUT_WRN	LUT Write ReadNot	LUT Write ReadNot			
RW	LUT Write mode	LUT Write mode			
Value at Reset:	0x0				
Possible Values:	0x0	Read operation			
	0x1	Write operation			

LUT_SS	LUT SnapShot
WO/AutoClr	Start the LUT READ or WRITE OPERATION

LUT_ADD (9:0)	
	When writing to RGB LUT(after the bayer demosaic, 8 to 8 LUT), only the LSB bits of the address are used.
Value at Reset:	0x0

LUT_RB

31	30	29	28	27	26	25	24
			Rese	erved			
23	22	21	20	19	18	17	16
			Rese	erved			
15	14	13	12	11	10	9	8
			Rese	erved			
7	6	5	4	3	2	1	0
	LUT_RB(7:0)						

LUT_RB (7:0)	
STATIC	Not Implemented to save FPGA ressources
Value at Reset:	0x0

Section: BAYER

Address Range: [0x4C0 - 0x4F0]

BAYER_CAPABILITIES

31	30	29	28	27	26	25	24
			Rese	rved			
23	22	21	20	19	18	17	16
			Rese	rved			
15	14	13	12	11	10	9	8
			Rese	rved			
7	6	5	4	3	2	1	0
	Reserved					BAYER_	VER(1:0)

BAYER_VER (1:0)					
RO	Implemented	Implemented version of the BAYER module			
Possible Values:	0x0	Bayer not implemented			
	0x1	Initial Bayer 2x2 version			

WB_MUL1

31	30	29	28	27	26	25	24
			WB_MUL	LT_G(15:8)			
23	22	21	20	19	18	17	16
			WB_MUI	LT_G(7:0)			
15	14	13	12	11	10	9	8
			WB_MUL	LT_B(15:8)			
7	6	5	4	3	2	1	0
	WB_MULT_B(7:0)						

WB_MULT_G (15:0)	
RW	White Balance factor [4].[12]
Value at Reset:	0x1000

WB_MULT_B (15:0)	
RW	White Balance factor [4].[12]
Value at Reset:	0x1000

WB_MUL2

31	30	29	28	27	26	25	24	
Reserved								
23	22	21	20	19	18	17	16	
	Reserved							
15	14	13	12	11	10	9	8	
WB_MULT_R(15:8)								
7	6	5	4	3	2	1	0	
	WB_MULT_R(7:0)							

WB_MULT_R (15:0)	
RW	White Balance factor [4].[12]
Value at Reset:	0x1000

WB_B_ACC

31	30	29	28	27	26	25	24		
Reserved				B_ACC(30:24)					
23	22	21	20	19	18	17	16		
	B_ACC(23:16)								
15	14	13	12	11	10	9	8		
	B_ACC(15:8)								
7	6	5	4	3	2	1	0		
B_ACC(7:0)									

B_ACC (30:0)	
RO	ACQuisition Blue ACCumulator

WB_G_ACC

31	30	29	28	27	26	25	24		
	G_ACC(31:24)								
23	22	21	20	19	18	17	16		
	G_ACC(23:16)								
15	14	13	12	11	10	9	8		
	G_ACC(15:8)								
7	6	5	4	3	2	1	0		
	G_ACC(7:0)								

G_ACC (31:0)	
RO	ACQuisition Green ACCumulator

WB_R_ACC

31	30	29	28	27	26	25	24	
Reserved				R_ACC(30:24)				
23	22	21	20	19	18	17	16	
R_ACC(23:16)								
15	14	13	12	11	10	9	8	
R_ACC(15:8)								
7	6	5	4	3	2	1	0	
	R_ACC(7:0)							

R_ACC (30:0)	
RO	ACQuisition Red ACCumulator

CCM_CTRL

31	30	29	28	27	26	25	24		
	Reserved								
23	22	21	20	19	18	17	16		
	Reserved								
15	14	13	12	11	10	9	8		
	Reserved								
7	6	5	4	3	2	1	0		
	Reserved								

CCM_EN	
RW	
Value at Reset:	0x0

CCM_KR1

31	30	29	28	27	26	25	24	
	Reserved				Kg(1	1:8)		
23	22	21	20	19	18	17	16	
			Kg(7:0)				
15	14	13	12	11	10	9	8	
	Reserved Kr(11:8)							
7	6	5	4	3	2	1	0	
	Kr(7:0)							

Kg (11:0)	
RW	Signed 12 bits value, complement a 2:
Value at Reset:	0x000

Kr (11:0)	
RW	Signed 12 bits value, complement a 2:
Value at Reset:	0x100

CCM_KR2

31	30	29	28	27	26	25	24
	Reserved						
23	22	21	20	19	18	17	16
KOff(7:0)							
15	14	13	12	11	10	9	8
	Reserved Kb(11:8)						
7	6	5	4	3	2	1	0
Kb(7:0)							

KOff (8:0)	
RW	Signed 9 bits value, complement a 2: s8
Value at Reset:	0x00

Kb (11:0)	
RW	Signed 12 bits value, complement a 2: s3.8
Value at Reset:	0x000

CCM_KG1

31	30	29	28	27	26	25	24	
	Reserved			Kg(11:8)				
23	22	21	20	19	18	17	16	
	Kg(7:0)							
15	14	13	12	11	10	9	8	
Reserved					Kr(11:8)			
7	6	5	4	3	2	1	0	
Kr(7:0)								

Kg (11:0)	
RW	Signed 12 bits value, complement a 2: s3.8
Value at Reset:	0x100

Kr (11:0)	
RW	Signed 12 bits value, complement a 2:
Value at Reset:	0x000

CCM_KG2

31	30	29	28	27	26	25	24
	Reserved						
23	22	21	20	19	18	17	16
KOff(7:0)							
15	14	13	12	11	10	9	8
	Reserved Kb(11:8)						
7	6	5	4	3	2	1	0
Kb(7:0)							

KOff (8:0)	
RW	Signed 9 bits value, complement a 2 : s8
Value at Reset:	0x00

Kb (11:0)	
RW	Signed 12 bits value, complement a 2: s3.8
Value at Reset:	0x000

CCM_KB1

31	30	29	28	27	26	25	24
	Reserved			Kg(11:8)			
23	22	21	20	19	18	17	16
	Kg(7:0)						
15	14	13	12	11	10	9	8
	Reserved Kr(11:8)						
7	6	5	4	3	2	1	0
	Kr(7:0)						

Kg (11:0)	
RW	Signed 12 bits value, complement a 2: s3.8
Value at Reset:	0x00

Kr (11:0)	
RW	Signed 12 bits value, complement a 2:
	s3.8
Value at Reset:	0x00

CCM_KB2

31	30	29	28	27	26	25	24		
	Reserved								
23	22	21	20	19	18	17	16		
			KOff	£(7:0)					
15	14	13	12	11	10	9	8		
	Reserved Kb(11:8)								
7	6	5	4	3	2	1	0		
	Kb(7:0)								

KOff (8:0)	
RW	Signed 9 bits value, complement a 2 : s8
Value at Reset:	0x00

Kb (11:0)	
RW	Signed 12 bits value, complement a 2:
Value at Reset:	0x100

Address Range: [0x700 - 0x7FC]

Description:

Access Xilinx embedded system monitoring module.

See Xilinx UG480

TEMP

31	30	29	28	27	26	25	24		
	Reserved								
23	22	21	20	19	18	17	16		
	Reserved								
15	14	13	12	11	10	9	8		
	SMTEMP(11:4)								
7	6	5	4	3	2	1	0		
SMTEMP(3:0) Reserved									

SMTEMP (11:0)	System Monitor TEMPerature						
	This field reports the temperature of the die. Maximum-measurement error is ± 4 degC. The temperature in Celcius = $(SMTEMP*503.975/4096) - 273.15$.						
Possible Values:	Any Value						

31	30	29	28	27	26	25	24	
Reserved								
23	22	21	20	19	18	17	16	
	Reserved							
15	14	13	12	11	10	9	8	
	SMVINT(11:4)							
7	6	5	4	3	2	1	0	
	SMVINT(3:0) Reserved							

SMVINT (11:0)	System Monitor VCCINT	,				
	This field reports voltage for VCCINT supply: VCCINT = (SMVINT/4096)x3V. VCCINT is the core voltage nominally set to 1.0V					
Possible Values:	Any Value					

31	30	29	28	27	26	25	24	
Reserved								
23	22	21	20	19	18	17	16	
	Reserved							
15	14	13	12	11	10	9	8	
	SMVAUX(11:4)							
7	6	5	4	3	2	1	0	
	SMVAUX(3:0) Reserved							

SMVAUX (11:0)	System Monitor VCCAUX					
	This field reports voltage for VCCAUX supply: VCCAUX = (SMVAUX/4096)x3V. VCCAUX is the auxiliary voltage nominally set to 1.8V.					
Possible Values:	Any Value					

31	30	29	28	27	26	25	24	
Reserved								
23	22	21	20	19	18	17	16	
	Reserved							
15	14	13	12	11	10	9	8	
	SMVBRAM(11:4)							
7	6	5	4	3	2	1	0	
	SMVBRAM(3:0) Reserved							

SMVBRAM (11:0)	System Monitor VCCBRAM		
	This field reports voltage for VCCBRAM supply: VCCBRAM = (SMVBRAM/4096)x3V. VCCBRAM is the block RAM supply nominally set to 1.0V.		
Possible Values:	Any Value		

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
SMTMAX(11:4)							
7	6	5	4	3	2	1	0
SMTMAX(3:0)			Reserved				

SMTMAX (11:0)	System Monitor Temperature MAXimum		
RO	This field reports the maximum temperature that has been measured by on-chip sensor. The maximum temperature (in Celcius) = (SMTMAX*503.975/4096) – 273.15.		
Possible Values:	Any Value		

31	30	29	28	27	26	25	24
Reserved							
23	22	21	20	19	18	17	16
Reserved							
15	14	13	12	11	10	9	8
SMTMIN(11:4)							
7	6	5	4	3	2	1	0
SMTMIN(3:0)			Reserved				

SMTMIN (11:0)	System Monitor Temperature MINimum			
RO	This field reports the maximum temperature that has been measured by on-chip sensor. The maximum temperature (in Celcius) = (SMTMIN*503.975/4096) – 273.15.			
Possible Values:	Any Value			