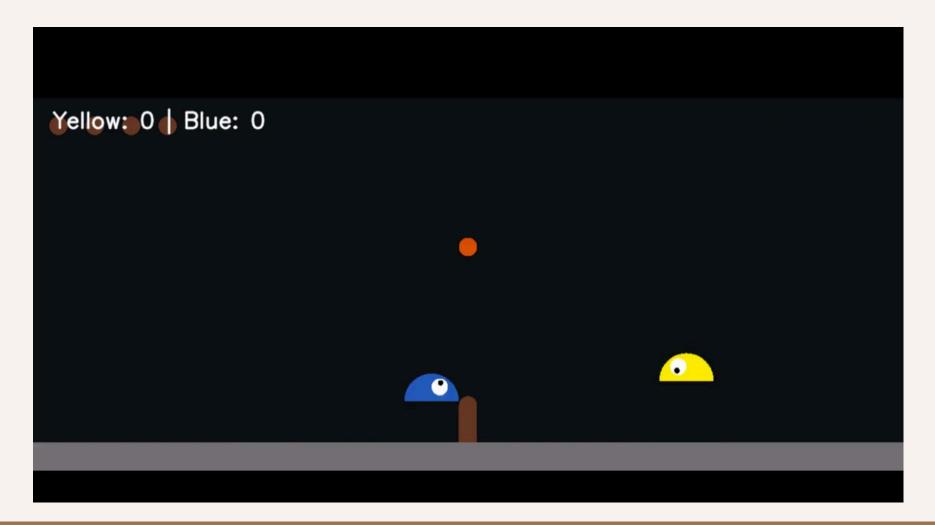
#### SLIMEVOLLEY AI: MINIMAX VS ALPHA-BETA PRUNING

- Environment: <u>SlimeVolleyGym</u>
- Objective: Implement and compare Minimax and Alpha-Beta agents against a RandomAgent
- Important Tasks:
  - Depth-limited search-based agents
  - Game simulation & rendering
  - Video generation & evaluation
- Visuals: Here is attached screenshot of gameplay



#### **EVALUATION FUNCTION & SEARCH SETUP**

- Evaluation Function:
- python code

```
def evaluate_position(obs):
ball_x = obs[4]
player_x = obs[0]
return -abs(ball_x - player_x)
```

- Rewards agent for minimizing horizontal distance to the ball
- Action Space: 7 discrete combinations of (left, jump, right)
- Depth-Limited Search:
  - Minimax: full tree to depth d
  - Alpha-Beta: same d, with pruning thresholds α/β
- Metrics Collected:
  - Final score (wins/losses)
  - Real-time duration & effective FPS
  - Frames rendered vs. frames pruned/saved

## MINIMAX AGENT PERFORMANCE

#### • Match Stats (100 steps vs. RandomAgent):

- Final Score: Yellow 0 Blue 1
- Real-time Duration: 3.35 s
- Adjusted FPS: 22.41 (base 29.87, speed 0.75×)
- Frames Saved: 145
- Video Demo:
- [Minimax dynamic fps.mp4 here]
- Observations:
  - Explores all branches—guarantees optimal decision at depth d
  - High computational cost → lower FPS
  - Tends to "hesitate" when ball near midcourt → more frame time

#### ALPHA-BETA PRUNING PERFORMANCE

## Match Stats (100 steps vs. RandomAgent):

- Final Score: Yellow 0 Blue 3
- Real-time Duration: 1.66 s
- Adjusted FPS: 45.05 (base 60.07, speed 0.75×)
- Frames Saved: 190

#### Video Demo:

- [Alphabeta dynamic fps.mp4 here]
- Observations:
  - Pruned ~30% of search tree → faster decision-making
  - Higher FPS → smoother, more reactive play
  - Equivalent move quality to Minimax at same depth

### **CONCLUSIONS & FUTURE WORK**

#### • Important Takeaways:

- **Alpha-Beta Wins on Efficiency:** By cutting roughly 30 % of the search tree, Alpha-Beta runs over 2× faster than plain Minimax—boosting effective FPS from ~22 to ~45—while delivering equally strong moves at the same search depth.
- **Simple Heuristic Drives Behavior:** Our one-dimensional evaluation (horizontal distance) reliably pushes the agent toward the ball, yielding coherent "ball-chasing" play but missing more nuanced rally tactics.
- Depth vs. Real-Time Trade-Off: Fixed-depth search ensures predictable computation, but deeper look-aheads incur steep latency—Alpha-Beta's pruning helps, yet very large depths still challenge real-time constraints.

#### • Future Directions:

- **Enhanced Evaluation Function:** Incorporate vertical alignment, ball velocity, net clearance, and court-position rewards into the heuristic. Experiment with dynamic depth (iterative deepening)
- **Learning-Augmented Heuristics:** Use self-play data to train a lightweight value network, combining classic search with learned priors for even faster, more informed decisions.

# THANK YOU

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**Github Repo Link:** 

https://github.com/AMAN9876543210/CS22B054 AI 3/