1 Создание класса генерации прямоугольников

Π истинг кода 1 :

```
from PIL import Image, ImageDraw
import random
import numpy as np
class Rectangle:
       Rectangle generation class:
       create_rec: gives coordinates of rectangle,
                   height, width and coordinates of top-left angle of surrounding rectangle
       image_gen: generates, saves and show our rectangle
   def __init__(self, gen, bound):
       self.coords_gen = gen
       self.coords_bound = bound
       self.save = None
       self.background = None
       self.create_rect()
       self.image_gen()
   def create_rect(self):
       w = np.random.randint(150, 250) # rectangle width
       h = np.random.randint(150, 250) # rectangle height
       angle = random.randint(0, 89) * 3.14159 / 180 # rotation angle
       h1 = (h * np.cos(angle))
       h2 = (w * np.sin(angle))
       hhh = h1 + h2 # surrounding rectangle height
       w1 = (h * np.sin(angle))
       w2 = (w * np.cos(angle))
       www = w1 + w2 # surrounding rectangle width
       x0, y0 = (np.random.randint(www/2, 640-www/2), np.random.randint(hhh/2, 480-hhh/2)) # center
       # surrounding angle coordinates
       xb1yb1, xb2yb2, xb3yb3, xb4yb4 = ((x0 - www/2, y0 - hhh/2),
                                        (x0 - www/2, y0 + hhh/2),
                                        (x0 + www/2, y0 + hhh/2),
                                        (x0 + www/2, y0 - hhh/2))
       rotation_matrix = np.array([[np.cos(angle), -np.sin(angle)],
                                  [np.sin(angle), np.cos(angle)]])
       # angle coordinates
       x01y01 = (x0 + (x0 - w / 2 - x0) * rotation_matrix[0][0] + (y0 - h / 2 - y0) * rotation_matrix[0][1],
       x03y03 = (x0 + (x0 + w / 2 - x0) * rotation_matrix[0][0] + (y0 + h / 2 - y0) * rotation_matrix[0][1],
                y0 + (x0 + w / 2 - x0) * rotation_matrix[1][0] + (y0 + h / 2 - y0) * rotation_matrix[1][1])
       x04y04 = (x0 + (x0 - w / 2 - x0) * rotation_matrix[0][0] + (y0 + h / 2 - y0) * rotation_matrix[0][1],
                 y0 + (x0 - w / 2 - x0) * rotation_matrix[1][0] + (y0 + h / 2 - y0) * rotation_matrix[1][1])
       self.coords_gen = (x01y01, x02y02, x03y03, x04y04)
       self.coords_bound = xb2yb2, www, hhh
   def image_gen(self):
       # background with random color
       background = Image.new('RGB', (640, 480), (random.randint(0, 255),
```

 $^{^{1}}$ весь код размещен с комментариями в данном репозитории

```
random.randint(0, 255),
                                                      random.randint(0, 255)))
        rectangle = ImageDraw.Draw(background)
        # rectangle with random color
        rectangle.polygon(self.coords_gen, (random.randint(0, 255),
                                               random.randint(0, 255),
                                               random.randint(0, 255)))
        background.show()
        name = '/home/andrei/PycharmProjects/test_task_GosNIIAS/rect_pics/6.png'
        background.save(name, 'png')
if __name__ == "__main__":
    data = open('data.txt', 'w') # shape data file
    for i in range(0, 1):
        rect = Rectangle(None, None)
        print(f"Bounding rectangle:\n"
               f"x = {rect.coords_bound[0][0]}\n"
               f"y = {rect.coords_bound[0][1]}\n"
               f"w = {rect.coords_bound[1]}\n"
               f"h = {rect.coords_bound[2]}\n\n"
               f"Angles coordinates:\n"
                f"x1 = \{rect.coords\_gen[0][0]\}, \ y1 = \{rect.coords\_gen[0][1]\} \setminus n" 
               f"x2 = \{\texttt{rect.coords\_gen[1][0]}\}, \ y2 = \{\texttt{rect.coords\_gen[1][1]}\} \\ \\ n"
               f"x3 = \{rect.coords\_gen[2][0]\}, \ y3 = \{rect.coords\_gen[2][1]\} \setminus n"
               f"x4 = {rect.coords_gen[3][0]}, y4 = {rect.coords_gen[3][1]}\n"
               f"***********\n", file=data)
    data.close()
```

Примеры:

Bounding rectangle: $x = 177.81297507509635$ $y = 466.7329701271386$ $w = 194.3740498498073$ $h = 213.46594025427723$ Angles coordinates: $x1 = 224.40036474598526$, $y1 = 253.2670298728614$ $x2 = 372.18702492490365$, $y2 = 292.8663110931169$ $x3 = 325.59963525401474$, $y3 = 466.7329701271386$ $x4 = 177.81297507509635$, $y4 = 427.1336889068831$
$\begin{array}{lll} \textbf{Bounding rectangle:} \\ x = 102.84868366448603 & y = 354.6592632085511 \\ w = 344.30263267102794 & h = 343.31852641710225 \\ \textbf{Angles coordinates:} \\ x1 = 249.08962843382267, \ y1 = 11.34073679144889 \\ x2 = 447.15131633551397, \ y2 = 160.59075449842615 \\ x3 = 300.9103715661774, \ y3 = 354.6592632085511 \\ x4 = 102.84868366448605, \ y4 = 205.40924550157382 \\ \end{array}$
$\begin{array}{lll} \textbf{Bounding rectangle:} \\ x = 186.99243908133724 & y = 435.1001196274153 \\ w = 208.01512183732552 & h = 210.20023925483062 \\ \textbf{Angles coordinates:} \\ x1 = 352.91296192481013, \ y1 = 224.8998803725847 \\ x2 = 395.00756091866276, \ y2 = 393.73128958173254 \\ x3 = 229.08703807518987, \ y3 = 435.1001196274153 \\ x4 = 186.99243908133724, \ y4 = 266.26871041826746 \\ \end{array}$
Bounding rectangle: $ \begin{array}{lllllllllllllllllllllllllllllllllll$
$\begin{array}{lll} \textbf{Bounding rectangle:} \\ x = 348.54686848903714 & y = 236.48681849581902 \\ w = 230.90626302192572 & h = 232.97363699163805 \\ \textbf{Angles coordinates:} \\ x1 = 497.76493916360744, y1 = 3.51318150418097 \\ x2 = 579.4531315109629, y2 = 157.1459879975256 \\ x3 = 430.23506083639256, y3 = 236.48681849581902 \\ x4 = 348.54686848903714, y4 = 82.8540120024744 \end{array}$

2 Поиск координат углов прямоугольника при помощи преобразования Хафа

```
import cv2
import numpy as np
import matplotlib.pyplot as plt
from skimage.transform import hough_line, hough_line_peaks
def find_inter(k1, b1, k2, b2):
       y = k1 * x + b1
    y = k2 * x + b2
    if k2 != k1:
       x = - (b2 - b1) / (k2 - k1)
        y = k1 * x + b1
       return x, y
        return None
image = cv2.imread('/home/andrei/PycharmProjects/test_task_GosNIIAS/rect_pics/6.png') # open image
gray = cv2.cvtColor(image, cv2.COLOR_RGB2GRAY) # to gray
gray = cv2.GaussianBlur(gray, (3, 3), 0) # some blur
cv2.imwrite("gray.png", gray) # save gray image
edged = cv2.Canny(gray, 0, 10) # leave only the borders
cv2.imwrite("edged.png", edged) # save edged image
using_angles = np.linspace(-np.pi / 2, np.pi / 2, 1800) # introduce angles array
halfspace, theta, dist = hough_line(edged, using_angles)
# draw Hough Accumulator
plt.figure(figsize=(15, 10))
plt.title('Hough Accumulator', size=30)
plt.imshow(halfspace, cmap='gray')
plt.savefig('accumulator.png')
angle_list = []
fig, axes = plt.subplots(1, 2, figsize=(20, 8))
ax = axes.ravel()
# draw edged rectangle
ax[0].imshow(edged, cmap='gray')
ax[0].set_title('Edged rectangle', size=30)
ax[0].set_axis_off()
ax[1].imshow(image, cmap='gray')
origin = np.array((0, edged.shape[1]))
lines = []
# draw straight lines along the borders using Hough Transform
for _, angle, dist in zip(*hough_line_peaks(halfspace, theta, dist)):
    y0, y1 = (dist - origin * np.cos(angle)) / np.sin(angle)
    ax[1].plot(origin, (y0, y1), '-r')
   lines += [(1 / np.tan(angle), dist / np.sin(angle))]
   print(np.degrees(angle), dist)
inter = []
# lines intersection
for i in range(len(lines)):
    for j in range(i+1, len(lines)):
        \label{lines}  \mbox{print(f"intersection of lines[lines[i]] and {lines[j]}:", end=' ')} 
        point = find_inter(lines[i][0], lines[i][1], lines[j][0], lines[j][1])
        if point != None:
```

```
x, y = point
    if abs(x) > 1000 or abs(y) > 1000:
        print("NO INTERSECTION")
    else:
        print(x, y)
        inter += [(-x, y)]

# draw intersection points
ax[1].plot([i[0] for i in inter], [i[1] for i in inter], 'yo', markersize=12)
ax[1].set_xlim(origin)
ax[1].set_ylim((edged.shape[0], 0))
ax[1].set_title('Detected rectangle', size=30)
plt.savefig('detection.png')
plt.show()
```

Примеры:

















