

Package ‘STPtrajectories’

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Type Package

Title Space-time prism trajectories

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Description Package that uses Space-Time Prism (STP) concept to analyse trajectories.

By incorporating the STP concept, users can analyse their data while taking into account the uncertainty of the location of an individual in between the control points of a trajectory.

The package also supports uncertainty about the control points themselves.

The STPtrajectories package contains methods that calculate Potential Path Areas (PPAs), create random trajectories, calculate when an individual could have been at a spatial location, and test for possible encounters between two individuals by applying the alibi query.

It also provides a method that visualises STP trajectories in 3D.

Depends trajectories

Imports lubridate, maptools, raster, rgeos, rgl, spacetime, plyr, rgdal, geometry

Suggests knitr, rmarkdown

License MIT

LazyData TRUE

RoxygenNote 6.0.1

VignetteBuilder knitr

R topics documented:

alibi_query	2
axes_STP_plot	3
getVmaxtrack	4
potential_stay	5
PPA	7
RTG	9
STPtrajectories	11
STP_plot	12
STP_Track	13

Index	17
--------------	-----------

alibi_query	<i>alibi_query</i>
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Description

This function tests whether there was a possible meeting between two individuals or other moving objects. If the individuals of two trajectories could have met, is tested by applying the alibi query to segments that overlap in time. The alibi query is a Boolean query that checks whether two moving individuals, that are given by two samples of space-time points and speed limitations, could have met each other. The query tests if two space-time prisms intersect. Kuijpers et al. (2011) provide the analytical solution for the alibi query that is used by this function.

Usage

```
alibi_query(STP_track1, STP_track2, stop_if_true = TRUE, return_PIA = FALSE,
            time_interval = 5)
```

Arguments

STP_track1	STP_track1
STP_track2	STP_track2
stop_if_true	logical: Stop if intersection is found. Default=TRUE
return_PIA	logical: Return potential meeting time and Potential Intersection Area(PIA). Default=FALSE
time_interval	Accuracy in seconds of Potential Intersection Area(PIA) and time period that individuals could have been at the same location. Default is 5 seconds, meaning that time period and PIA are based on PPAs calculated for every 5 seconds.

Value

If an intersection is found, the method returns a vector with space-time point of intersecting STPs. If return_PIA is True, the method returns the Potential Intersection Area(PIA) and the time period that the individuals could have been at the same location. If no intersection is found, the method returns FALSE.

Author(s)

Mark ten Vregelaar

References

- Kuijpers, B., Grimson, R., & Othman, W. (2011). An analytic solution to the alibi query in the space-time prisms model for moving object data. *International Journal of Geographical Information Science*, 25(2), 293-322.

Examples

```
library(spacetime)
library(sp)

## create 2 STP_tracks
# time
t1 <- strptime("01/01/2017 00:00:00", "%m/%d/%Y %H:%M:%S")
t2 <- t1+5*60*60 # 5 hours after t1
time1<-seq(t1,t2,30*60)
time2<-time1+0.25*60*60
# spatial coordinates
x1=c(seq(0,25,5),seq(27.5,37.5,2.5))
y1=sample(-2:2, 11,replace = TRUE)
x2=c(seq(0,25,5),seq(27.5,37.5,2.5))
y2=sample(-2:2, 11,replace = TRUE)

n = length(x1)
crs_NL = CRS("+init=epsg:28992")

# create class STIDF
stidf1 = STIDF(SpatialPoints(cbind(x1,y1),crs_NL), time1, data.frame(co2 = rnorm(n),O2=rnorm(n)))
stidf2 = STIDF(SpatialPoints(cbind(x2,y2),crs_NL), time2, data.frame(co2 = rnorm(n),O2=rnorm(n)))

# Track-class {trajectories}
my_track1<-Track(stidf1)
my_track2<-Track(stidf2)
# set maximum speed
v1<-getVmaxtrack(my_track1)+0.00015
v2<-getVmaxtrack(my_track2)+0.00030
# STP_track class
STP_track1<-STP_Track(my_track1,v1)
STP_track2<-STP_Track(my_track2,v2)

## the alibi query
alibi_query(STP_track1,STP_track2) # now only finds first intersection
```

axes_STP_plot

axes_STP_plot

Description

This function adds a bbox with axis to a [STP_plot](#)

Usage

```
axes_STP_plot(minmaxT, z_factor, n_ticks_xy = 3, n_ticks_z = 5,
  expand = 1.1)
```

Arguments

minmaxT	a vector of length 2 with two "POSIXct" or "POSIXt" values. The first and last moment in time of plotted tracks. Make sure first time is equal to the tracks that starts as first. Also take into account time_uncetrainty.
---------	---

z_factor	the z facfor used in the plot
n_ticks_xy	number of ticks used for the x and y axes
n_ticks_z	number of ticks used for the z axes
expand	for expanding the bbox. passed to rgl.bbox. If not all z/time tick are visisble, increase expand value.

Author(s)

Mark ten Vregelaar

Examples

```
## create a STP_track of two points/ one Space-time Prism(STP)
# time
t1 <- as.POSIXct(strptime("01/01/2017 00:00:00", "%m/%d/%Y %H:%M:%S"))
t2 <- t1+0.5*60*60 # 30 after t1
time<-c(t1,t2)
# spatial coordinates
x=c(0,2);y=c(1,3)

n = length(x)
crs_NL = CRS("+init=epsg:28992")

# create class STIDF
stidf1 = STIDF(SpatialPoints(cbind(x,y),crs_NL), time, data.frame(co2 = rnorm(n),O2=rnorm(n)))

# Track-class {trajectories}
my_track1<-Track(stidf1)

# set maximum speed
v1<-getVmaxtrack(my_track1)+0.01
# STP_track class
STP1<-STP_Track(my_track1,v1)

## 3D STP plot of STP
open3d()
z_fac<-2 # relative size of z scale/aspect ratio to spatial scale
# plot STP
STP_plot(STP1,time_interval = 0.5,zfactor = z_fac)

# add axes
axes_STP_plot(time,z_factor = z_fac)
```

getVmaxtrack

getVmaxtrack

Description

This functions calculates the maximum speed found in a trajectory. The maximum speed is based on linear movement between measured points.

Usage

```
getVmaxtrack(track)
```

Arguments

track the trajectory as [STP_Track](#) or [Track](#)

Value

max speed of the moving object

Author(s)

Mark ten Vregelaar

Examples

```
## get a track dataset
data(A3)# see trajectories package: importenvirocar
car_track<-Track(A3)# recalculate connections data
head(car_track@connections)# distance in meters and speed in m/s
## get maximum speed
speed_ms <- getVmaxtrack(car_track)# speed in m/s
# maximum speed. It is the speed required to be able to reach every point in time in km/h
speed_ms*3.6
```

potential_stay	<i>potential_stay</i>
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Description

Function that calculates the time intervals at which the individual could have been at spgeom, a spatial location as a point, line or polygon. The total potential stay time might not be equal to the sum of the intervals. This applies to STP_tracks with multiple intersections for one STP and if the track has time uncertainty. If the track has time uncertainty the method calculates the max potential stay for each STP, which may result in a time overlap in the returned potential stay time intervals. If space-time prism has an activity_time, it is assumed that individual is at the location for the activity. The potential_stay time interval is thus not affected by the activity_time if the sp_geom can be reached.

Usage

```
potential_stay(STP_track, spgeom, x_density = 250)
```

Arguments

STP_track	A STP_Track
spgeom	A Spatialpoints, Spatiallines or Spatialpolygons object
x_density	Parameter used for calculating PPA. Default is 250 coordinates. The amount of x coordinates for which the corresponding y coordinate(s) will be calculated.

Value

A named list with the potential stay time intervals for each STP that intersects with the spatial geometry

Examples

```
library(rgeos)
library(sp)
library(spacetime)
library(rgl)
#-----create a STP_Track-----
# set time
t1 <- as.POSIXct(strptime("01/01/2017 12:00:00", "%m/%d/%Y %H:%M:%S"))
t2 <- as.POSIXct(strptime("01/01/2017 14:00:00", "%m/%d/%Y %H:%M:%S"))
n<-5
time<-seq(t1,t2,length.out = n)
# set coordinates
x=c(1,3,4,7,6)
y=c(2,5,8,9,11)

n = length(x)
crs_NL = CRS("+init=epsg:28992")

# create class STIDF
stidf1 = STIDF(SpatialPoints(cbind(x,y),crs_NL), time, data.frame(co2 = rnorm(n),O2=rnorm(n)))

# Track-class {trajectories}
my_track1<-Track(stidf1)

# set maximum speed
v1<-getVmaxtrack(my_track1)*1.5

# STP_track class
STP_track1<-STP_Track(my_track1,v1)

#-----create a spatialpolygon-----
lake <- readWKT("POLYGON((1 8,1.3 8.5,1.7 8.7,2 9,2.5 9.2,3 9,3.5 8.5,3.2 7.7,2.5 7.5,2 7.5,1 8))")
lake@proj4string<-crs_NL

# calculate the potential stay time for point
intervals <- potential_stay(STP_track = STP_track1,spgeom = lake)
intervals
# calculate the time the individual could have been at the lake
lake_time <- sum(sapply(intervals, function(STP){difftime(STP[2],STP[1],units = 'mins')}))

print(paste('Total time individual could have been at the lake is ',round(lake_time,2),'minutes'))

# visulise in 2D
plot(STP_track1,type='b')
PPA_track<-PPA(STP_track1)
plot(PPA_track,add=T)
plot(lake,add=T,border= 'blue',lwd=2)

# visulise in 3D
open3d()
zf<-STP_plot(STP_track1,time_interval = 0.6)
```

```

axes_STP_plot(c(STP_track1@endTime[1],STP_track1@endTime[n]),z_factor = zfac,n_ticks_z = 5,n_ticks_xy = 4)

x<-lake@polygons[[1]]@Polygons[[1]]@coords[,1]
y<-lake@polygons[[1]]@Polygons[[1]]@coords[,2]
z<-difftime(STP_track1@endTime[n],STP_track1@endTime[1],units = 'mins')*zfac

shade3d(translate3d(
  extrude3d(x,y,thickness = z),0,0,0),col='blue',add=TRUE)

```

PPA

PPA

Description

Function for calculating the Potetial Path Area(PPA) of a STP_track. This function can calculate the PPA for the entire trajectory, a specific moment in time, or a time range. The PPA for a specific moment in time is always based on the two points that before and after the time parameter. If time is outside time range of the [STP_Track](#) but within time uncertainty limits, the method will return the PPA based on the two closest points in time.

Usage

```

PPA(STP_track, time = NULL, points = NULL, x_density = 250,
    time_interval = 1, quadsegs = 12)

```

Arguments

STP_track	The STP_track for which the PPA needs to be calculated
time	Time("POSIXct" or "POSIXt") for which the PPA needs to be calculated. Use time = c(time1,time2) to calculate PPA for a time range. Default is NULL: calculate PPA for entire STP_track
points	The points used for the PPA calculation given as a vector of integers. Default is NULL: calculate PPA for entire STP_track
x_density	Paramter used for calculating the PPA of entire STPs. The amount of x coordinates for which the corresponding y coordinate(s) will be calculated. Only relevant if the PPA for at least 1 complete STP needs to be calculated.
time_interval	The time interval in minutes used for calculating the PPA. Only used for calculating the PPA for a specific moment in time and if only a part of the PPA of a STP needs to be calculated. Default is every minute
quadsegs	Passed to buffer. Number of line segments to use to approximate a quarter circle. Only used where paramter time_interval is relavant.

Value

The Potential Path Area as SpatialPolygons. If time is equal to time of a space-time point and rough_sets (time and location uncertainty points) are 0, method returns NA because there is no PPA

Author(s)

Mark ten Vregelaar

Examples

```

library(spacetime)
library(sp)
#-----create a STP_Track-----
# set time
t1 <- strptime("01/01/2017 00:00:00", "%m/%d/%Y %H:%M:%S")
t2 <- t1+5*60*60
time<-seq(t1,t2,30*60)
# set coordinates
x=c(seq(0,25,5),seq(27.5,37.5,2.5))
y=sample(-2:2, 11,replace = TRUE)

n = length(x)
crs_NL = CRS("+init=epsg:28992")

# create class STIDF
stidf1 = STIDF(SpatialPoints(cbind(x,y),crs_NL), time, data.frame(co2 = rnorm(n),O2=rnorm(n)))

# Track-class {trajectories}
my_track1<-Track(stidf1)

# set maximum speed
v1<-getVmaxtrack(my_track1)+0.00015

# STP_track class
STP_track1<-STP_Track(my_track1,v1)
#-----example 1-----
## PPA entire track
#calculate PPA
PPA1<-PPA(STP_track1)

# plot results
plot(STP_track1,type='b')
plot(PPA1,add=TRUE)
#-----example 2-----
## PPA only using every second point
# calculate PPA
PPA2<-PPA(STP_track1,points = seq(1,11,2))

# plot results
plot(STP_track1,type='b')
plot(PPA2,add=TRUE)
#-----example 3-----
## PPA of a specific moment in time
# calculate PPA
time <- strptime("01/01/2017 01:15:00", "%m/%d/%Y %H:%M:%S")
PPA3<-PPA(STP_track1,time = time)

# plot results
plot(STP_track1,type='b')
plot(PPA3,add=TRUE)
#-----example 4-----
## PPA for a time range
# calculate PPA
timerange1 <- c(t1,strptime("01/01/2017 02:15:00", "%m/%d/%Y %H:%M:%S"))
PPA4<-PPA(STP_track1,time = timerange1)

```



```
# plot results
plot(STP_track1,type='b')
plot(PPA4,add=TRUE)
```

RTG	<i>RTG</i>
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Description

This random trajectory generator (RTG) works as described in Technitis et al.(2015). It creates a trajectory based on the space-time prism concept, it randomly adds a user defined number of points between the points of a trajectory. The new point is randomly placed in the PPA of the corresponding point in time. The added points are evenly divided over time and are always within the space-time prism.

Usage

```
RTG(STP_track, n_points = 1, max_time_interval = NULL, quadsegs = 12,
    iter = 4)
```

Arguments

STP_track	the STP_Track to which the randomly generated space-time points are added
n_points	number of points will be added between the two points. If no value is provided new point(s) will be added between all consecutive space-time points
max_time_interval	The <code>max_time_interval(numeric)</code> is the maximum allowed time difference in minutes between existing control points. If the time difference between two points is bigger than <code>max_time_interval</code> , new control point(s) are added in between the original control points. The Default is NULL, in which case between all control points <code>n_points</code> are added.
quadsegs	Passed to buffer. Number of line segments to use to approximate a quarter circle. Only used where paramter <code>time_interval</code> is relevant
iter	number of times to try to place sample points in the PPA before giving up and returning NULL (default = 4). This may occur when trying to hit a small and awkwardly shaped polygon in a large bounding box with a small number of points.

Value

A [STP_Track](#) with the newly added random space-time points. Slot data has NAs for the new points. Vmax values for new connections are equal to the vmax values of the original connections.

Author(s)

Mark ten Vregelaar

References

- Technitis, G., Othman, W., Safi, K., & Weibel, R. (2015). From A to B, randomly: A point-to-point random trajectory generator for animal movement. *International Journal of Geographical Information Science*, 29(6), 912-934. <http://www.tandfonline.com/doi/abs/10.1080/13658816.2014.999682>

Examples

```
library(spacetime)
library(sp)
#-----example 1-----
## Create a random trajecory based on a begin and end point
## Create trajectory with only two points
# Time
t1 <- as.POSIXct(strptime("01/01/2017 00:00:00", "%m/%d/%Y %H:%M:%S"))
t2 <- t1+0.5*60*60 # 2 hours after t1
time<-c(t1,t2)
# Spatial coordinates
x=c(5,10);y=c(10,20)
n = length(x)
crs_NL = CRS("+init=epsg:28992")

# create class STIDF
stidf1 = STIDF(SpatialPoints(cbind(x,y),crs_NL), time, data.frame(co2 = rnorm(n),O2=rnorm(n)))

# Track-class {trajectories}
track1<-Track(stidf1)

# Set maximum speed
v1<-getVmaxtrack(track1)+0.001
# STP_track class
STP1<-STP_Track(track1,v1)
plot(STP1,type='p',col='red',pch=16,cex=2)

# Create a random trajectory between the two points
random_STP_track<-RTG(STP1,n_points = 10)
plot(random_STP_track,type='b',add=TRUE)

#-----example 2-----
## Add points to a trajectory with multiple points
## Create a STP_track
np <-6 # Number of points original track
t1 <- as.POSIXct(strptime("01/01/2017 00:00:00", "%m/%d/%Y %H:%M:%S"))
random1<-cumsum(sample((0.5*60):(2.8*60*60),np))
time<-t1+random1

x=random1/2
y=seq(1,100,length.out = np)

n = length(x)
crs_NL = CRS("+init=epsg:28992")

# Create class STIDF
stidf2 = STIDF(SpatialPoints(cbind(x,y),crs_NL), time, data.frame(co2 = rnorm(n),O2=rnorm(n)))

# Track-class {trajectories}
```

```

track2<-Track(stdf2)

# Set maximum speed
v1<-getVmaxtrack(track2)+0.1

# STP_track class
STP_track2<-STP_Track(track2,v1)
# STP_track2 is track with different time intervals between the space-time points.
# The distance between two points increases with the time interval
plot(STP_track2,type='p',col='red',pch=16,cex=2)

## Fill blank spot of trajecotries in two steps
# Add 2 random points in between two sapce-time points that more than 90 minutes apart
filled_track1 <-RTG(STP_track2,n_points = 2,max_time_interval = 120)
plot(filled_track1,type='p',pch=16,add=TRUE,col='blue')

# Add 1 random point in between two sapce-time points that more than 45 minutes apart
filled_track2 <-RTG(filled_track1,n_points = 1,max_time_interval = 60)
plot(filled_track2,type='b',add=TRUE,cex=0.7)

```

STPtrajectories

STPtrajectories.

Description

Package that uses Space-Time Prism (STP) concept to analyse trajectories. By incorporating the STP concept, users can analyse their data while taking into account the uncertainty of the location of an individual in between the control points of a trajectory. The package also supports uncertainty about the control points themselves. The STPtrajectories package contains methods that calculate Potential Path Areas (PPAs), create random trajectories, calculate when an individual could have been at a spatial location, and test for possible encounters between two individuals by applying the alibi query. It also provides a method that visualises STP trajectories in 3D.

Background

A trajectory consists of successive points in space and time. The location of the individual between two successive points is unknown, but based on a maximum speed a space-time prism can be calculated. A space-time prism (STP) is defined as the collection of space-time locations the individual could reach, given a speed limitation. The [STP_Track](#) class can be used to handle space-time prism trajectories.

The [alibi_query](#) uses this concept to test if two individuals could have met each other. The package provides related functions to help users in the analysis of their trajectories and take into account the uncertainty about the location of an individual. These include methods to visualise space-time prisms ([STP_plot](#)), calculate the potential path area ([PPA](#)), calculate when an individual could have been at a spatial location ([potential_stay](#)), and a random trajectory generator ([RTG](#)).

help

need help:

- manual: <https://github.com/markvregel/STPtrajectories/blob/master/STPtrajectories.pdf>

- vignette: http://htmlpreview.github.io/?https://raw.githubusercontent.com/markvregel/STPtrajectories/master/vignettes/STP_Tracks.html
- check functions help and examples

Author(s)

Mark ten Vregelaar

See Also

- github: <https://github.com/markvregel/STPtrajectories>
- trajecotries package <https://cran.rstudio.com/web/packages/trajectories/index.html>

STP_plot	<i>STP_plot</i>
----------	-----------------

Description

This function visualizes STPs in 3D. It can be used to plot multiple [STP_Tracks](#) in interactive 3D plot.

Usage

```
STP_plot(STP_track, time_interval = 0.5, zfactor = NULL, col = "red",
         st = NULL, alpha = 1, cut_prisms = TRUE, quadsegs = 12)
```

Arguments

STP_track	A STP_Track .
time_interval	the time interval in minutes. Determines the amount of PPAs that are plotted.
zfactor	relative size of z axis compared to x and y axis. default=NULL: ratio axes depends on input data
col	colour of STP(s).
st	start time as "POSIXct" or "POSIXt". For plotting multiple STP_tracks use 1 starttime.
alpha	transparency of STPs. between 0 and 1
cut_prisms	In case of time uncertainty: whether to cut the middle and normally overlapping prisms at the original time of the space-time points. Only relevant if alpha<1. default is TRUE
quadsegs	Passed to PPA method. Number of line segments used to approximate a quarter circle.

Value

If no zfactor is provided, method returns calculated zfactor. Otherwise method returns NULL

Author(s)

Mark ten Vregelaar

Examples

```

library(spacetime)
library(sp)
library(rgl)
## create 2 STP_tracks
# time
t1 <- strptime("01/01/2017 00:00:00", "%m/%d/%Y %H:%M:%S")
t2 <- t1+5*60*60 # 5 hours after t1
time1<-seq(t1,t2,30*60)
time2<-time1+0.25*60*60
# spatial coordinates
x1=c(seq(0,25,5),seq(27.5,37.5,2.5))
y1=sample(-2:2, 11,replace = TRUE)
x2=x1+7
y2=sample(-2:2, 11,replace = TRUE)

n = length(x1)
crs_NL = CRS("+init=epsg:28992")

# create class STIDF
stidf1 = STIDF(SpatialPoints(cbind(x1,y1),crs_NL), time1, data.frame(co2 = rnorm(n),O2=rnorm(n)))
stidf2 = STIDF(SpatialPoints(cbind(x2,y2),crs_NL), time2, data.frame(co2 = rnorm(n),O2=rnorm(n)))

# Track-class {trajectories}
my_track1<-Track(stidf1)
my_track2<-Track(stidf2)
# set maximum speed
v1<-getVmaxtrack(my_track1)*2
v2<-getVmaxtrack(my_track2)*1.5
# STP_track class
STP_track1<-STP_Track(my_track1,v1)
STP_track2<-STP_Track(my_track2,v2)

open3d()
## 3D STP plot of STP_tracks
z_fac<-0.2 # relative size of z scale/aspect ratio to spatial scale
# plot STPS first STP_track
zf<-STP_plot(STP_track1,time_interval = 1)
# plot STPS second STP_track
STP_plot(STP_track2,time_interval = 1,zf,'blue',st = STP_track1@endTime[1])
# provide st for correct starting location first STP

# calculate first and last moment in time
min_max_Time<-c(STP_track1@endTime[1],STP_track2@endTime[length(STP_track2)])
# add axes
axes_STP_plot(min_max_Time,z_factor = zf)

# add title and change background colour
title3d(main = '2 STP tracks')
bg3d('lightblue')

```

Description

A class to represent Space-Time Prism(STP) trajectories. These are trajectories with a maximum speed for each segment. The maximum speed is added to the connections slot of class [Track](#). The STP_Track can also be combined in classes [Tracks](#) and [TracksCollection](#) of the trajectories package. The STP_Track method can be used to create a STP_Track from a [Track](#) of the trajectories package.

Usage

```
STP_Track(track, vmax, activity_time = 0, location_uncertainty = 0,
          time_uncertainty = 0)
```

Arguments

vmax	The maximum speed of the individual. Must be large enough to reach the next point. Either one vmax for entire track or a vector with the max speed for each segment.
activity_time	Time of an activity in minutes. During this time the individual cannot move. Either one activity_time for entire track or a vector with the activity_time for each segment.
location_uncertainty	Uncertainty of the location of the space-time points in meters. Either one location_uncertainty for entire track or a vector with the location_uncertainty for each point.
time_uncertainty	Uncertainty of the time of the space-time points in minutes. Either one time_uncertainty for entire track or a vector with the time_uncertainty for each point.
Track	Object of class Track

Slots of class "Track"

sp: spatial locations of the track points, with length n
time: time stamps of the track points
endTime: end time stamps of the track points
data: data.frame with n rows, containing attributes of the track points
connections: data.frame, with n-1 rows, containing attributes between the track points such as distance and speed

See Also

trajectories package :<https://cran.rstudio.com/web/packages/trajectories/index.html>

Examples

```
library(spacetime)
library(sp)
#-----create a STP_Track-----
#-----example 1-----
## create trajectory data
t1 <- as.POSIXct(strptime("01/01/2017 12:00:00", "%m/%d/%Y %H:%M:%S"))
t2 <- as.POSIXct(strptime("01/7/2017 12:00:00", "%m/%d/%Y %H:%M:%S"))
time <- seq(t1,t2,2*60*60)
```

```

n <- length(time)
x = cumsum(runif(n) * 8000)
y = smooth(cumsum(runif(n,-0.7,1) * 16000))

crs_NL = CRS("+init=epsg:28992")

points <- SpatialPoints(cbind(x,y),crs_NL)

temp <- -18 + cumsum(runif(n,-0.3,0.25))
altitude <- 200 + cumsum(runif(n,-0.75,1)*50)

data <- data.frame(temperature = temp, elevation = altitude)
## create a STP_track
# create class STIDF
stidf1 = STIDF(points, time, data)

# Track-class {trajectories}
my_track1<-Track(stidf1)

# set maximum speed
v1<-10/3.6# speed 10 km/h = 2.777778 m/s

# STP_track class
STP_track1<-STP_Track(my_track1,v1)
# plot
plot(STP_track1,type='p',pch=19,cex=0.8)
# calculate PPA and add to plot
PPA<-PPA(STP_track1)
plot(PPA,add=TRUE)

#-----example 2-----
## vmax depends on elevation
# assuming that max speed is lower as result of the thinner air
vmax<- getVmaxtrack(STP_track1) + (max(STP_track1@data$elevation[1:n-1])-STP_track1@data$elevation[1:n-1])*
STP_track1@connections$vmax<-vmax
# calculate PPA
PPA<-PPA(STP_track1)
# create tracksCollection and plot
tracks = Tracks(list(tr1 = STP_track1))
tracksCollection = TracksCollection(list(tr = tracks))
stplot(tracksCollection, attr = "elevation", lwd = 3, scales = list(draw =TRUE),
       sp.layout=PPA,xlim = PPA@bbox[1,],ylim = PPA@bbox[2,],main= "Track with PPA\n vmax depends on altitude",
       sub='colour is altitude in meters',xlab='x',ylab='y')
#-----example 3-----
## vmax depends on the distance to get to next point.
# Thus on the distance that needs to be covered in the avialable time
# Assuming that if two points are closer together the max speed is lower
STP_track1@connections$vmax<-STP_track1@connections$speed*1.5
# calculate PPA
PPA<-PPA(STP_track1)
# create tracksCollection and plot
plot(PPA,add=TRUE)
tracks = Tracks(list(tr1 = STP_track1))
tracksCollection = TracksCollection(list(tr = tracks))
stplot(tracksCollection, attr = "vmax", lwd = 3, scales = list(draw = TRUE),
       sp.layout=PPA,xlim = PPA@bbox[1,],ylim = PPA@bbox[2,],
       main= "Track with PPA\n vmax depends on the distance and time budget between consecutive points",

```

```

sub='colour is vmax in m/s',xlab='x',ylab='y',cex.main = 0.75)

#-----subset a STP_Track-----
# make sure vmax is high enough
STP_track1@connections$vmax<-getVmaxtrack(STP_track1)+1
#-----example 1-----
## subset based on space-time points
# get first 10 points
STP_track1_10<-STP_track1[1:10,'']
# only keep every second point
STP_track1_depleted<-STP_track1[seq(1,n,2),'']
plot(STP_track1,type='b')
plot(STP_track1_depleted,type='b')
#-----example 2-----
## subset based on time
STP_track1_a<-STP_track1[1:n,'2017-01-01 12:00:00 CET::2017-01-02 16:00:00 CET']
# only keep every second point within the time interval
STP_track1_b<-STP_track1[seq(1,n,2),'2017-01-01 12:00:00 CET::2017-01-02 16:00:00 CET']
# all points in the night(between 22:00 and 08:00)
STP_track1_c<-STP_track1[1:n,"T22:00/T08:00"] # see package xts for more handy subsetting tricks

```


Index

alibi_query, [2](#), [11](#)

axes_STP_plot, [3](#)

getVmaxtrack, [4](#)

potential_stay, [5](#), [11](#)

PPA, [7](#), [11](#)

RTG, [9](#), [11](#)

STP_plot, [3](#), [11](#), [12](#)

STP_Track, [5](#), [7](#), [9](#), [11](#), [12](#), [13](#)

STPtrajectories, [11](#)

STPtrajectories-package
(STPtrajectories), [11](#)

Track, [5](#), [14](#)

Tracks, [14](#)

TracksCollection, [14](#)