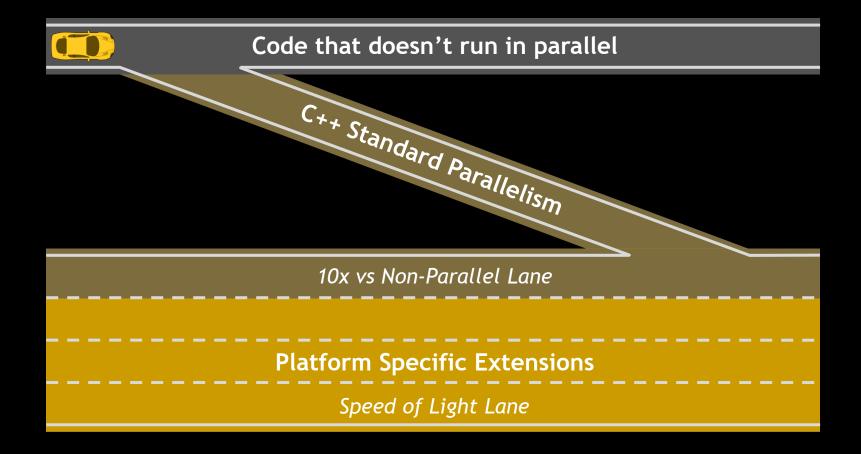
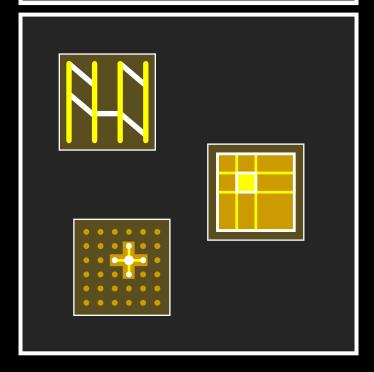


We Need On-Ramps



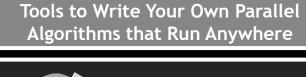
Pillars of Standard Parallelism

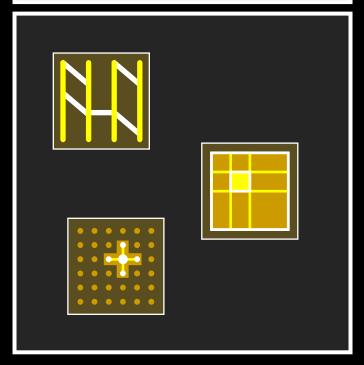
Common Algorithms that Dispatch to Vendor-Optimized Parallel Libraries



Pillars of C Standard Parallelism

Common Algorithms that Dispatch to Vendor-Optimized Parallel Libraries





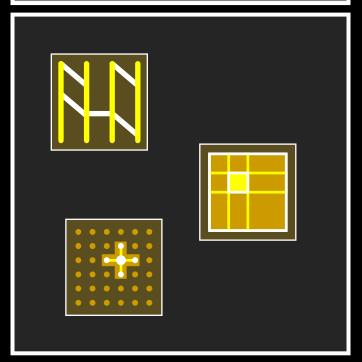
```
sender auto
algorithm (sender auto s) {
 return s | bulk(N,
    [] (auto data) {
      // ...
   | bulk(N,
    [] (auto d: 1) -
```

Pillars of C Standard Parallelism

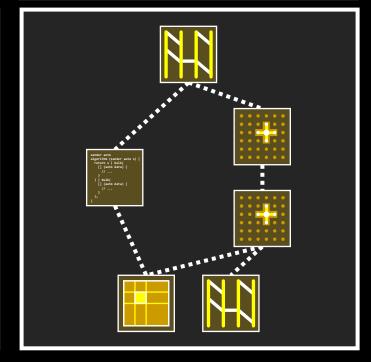
Common Algorithms that Dispatch to Vendor-Optimized Parallel Libraries



Mechanisms for Composing Parallel Invocations into Task Graphs



```
sender auto
algorithm (sender auto s) {
 return s | bulk(N,
    [] (auto data) -
      // ...
   | bulk(N,
    [] (auto da )
```





Serial (C++98)

```
std::vector<T> x{...};
std::for_each(
 begin(x), end(x),
f);
std::for_each(
 begin(x), end(x),
 g);
std::for each(
 begin(x), end(x),
 h);
```

```
std::vector<double> x{...}, y{...};
double dot product = std::transform_reduce(begin(x), end(x),
                                             begin(y));
std::span<std::string view> s{...};
std::sort(begin(s), end(s));
std::unordered map<std::string view, int> db{...};
std::vector<std::pair<std::string view, int>> m{...};
std::copy if(begin(db), end(db), begin(m),
             [] (auto e) { return e.second > 0; });
```

Standard Algorithms

adjacent_difference	is_sorted[_until]	rotate[_copy]
adjacent_find	lexicographical_compare	search[_n]
all_of	max_element	set_difference
any_of	merge	set_intersection
copy[_if _n]	min_element	set_symmetric_difference
count[_if]	minmax_element	set_union
equal	mismatch	sort
fill[_n]	move	stable_partition
find[_end _first_of _if _if_not]	none_of	stable_sort
for_each	nth_element	swap_ranges
generate[_n]	partial_sort[_copy]	transform
includes	partition[_copy]	uninitialized_copy[_n]
inplace_merge	remove[_copy _copy_if _if]	uninitialized_fill[_n]
is_heap[_until]	replace[_copy _copy_if _if]	unique
is_partitioned	reverse[_copy]	unique_copy



Standard Algorithms

Serial (C++98)

Parallel (C++17)

```
std::vector<T> x{...};
std::for each(
 begin(x), end(x),
f);
std::for_each(
 begin(x), end(x),
 g);
std::for each(
 begin(x), end(x),
 h);
```

```
std::vector<T> x{...};
std::for each(
 ex::par unseq,
 begin(x), end(x),
f);
std::for each(
 ex::par unseq,
 begin(x), end(x),
 g);
std::for_each(
 ex::par unseq,
 begin(x), end(x),
 h);
```

```
std::vector<double> x{...}, y{...};
double dot product = std::transform_reduce(ex::par_unseq,
                                             begin(x), end(x),
                                             begin(y));
std::span<std::string view> s{...};
std::sort(ex::par unseq, begin(s), end(s));
std::unordered map<std::string view, int> db{...};
std::vector<std::pair<std::string view, int>> m{...};
std::copy_if(<u>ex::par unseq</u>, begin(db), end(db), begin(m),
             [] (auto e) { return e.second > 0; });
```

Execution Policy	Operations occur	Operations are

Execution Policy	Operations occur	Operations are
std::execution::seq	In the calling thread	Indeterminately sequenced

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std::execution::seq	In the calling thread	Indeterminately sequenced
std::execution::unseq	In the calling thread	Unsequenced

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std::execution::par	Potentially in multiple threads	Indeterminately sequenced within each thread

Execution Policy	Operations occur	Operations are
<pre>std::execution::seq</pre>	In the calling thread	Indeterminately sequenced
<pre>std::execution::unseq</pre>	In the calling thread	Unsequenced
std::execution::par	Potentially in multiple threads	Indeterminately sequenced within each thread
<pre>std::execution::par_unseq</pre>	Potentially in multiple threads	Unsequenced

```
std::size_t word_count(std::string view s) {
std::string view frost = "Whose woods these are I think I know.\n"
                         "His house is in the village though;
                         "He will not see me stopping here
                                                                \n"
                         "To watch his woods fill up with snow.\n";
std::size_t result = word_count(frost);
```

```
std::size_t word_count(std::string_view s) {
 if (s.empty()) return 0;
  return std::transform reduce(ex::par unseq, ...);
std::string view frost = "Whose woods these are I think I know.\n"
                         "His house is in the village though;
                         "He will not see me stopping here
                         "To watch his woods fill up with snow.\n";
std::size t result = word count(frost);
```

```
std::size_t word_count(std::string_view s) {
 if (s.empty()) return 0;
  return std::transform reduce(ex::par unseq,
    begin(s), end(s) - 1, begin(s) + 1,
std::string view frost = "Whose woods these are I think I know.\n"
                         "His house is in the village though; \n"
                         "He will not see me stopping here
                         "To watch his woods fill up with snow.\n";
std::size t result = word count(frost);
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                         "He will not see me stopping here
                         "To watch his woods fill up with snow.\n";
std::size t result = word count(frost);
```

```
std::size t word count(std::string view s) {
 if (s.empty()) return 0;
  return std::transform reduce(ex::par unseq,
    begin(s), end(s) - 1, begin(s) + 1,
    [] (char 1, char r) { return std::isspace(1) && !std::isspace(r); }
std::string view frost = "Whose woods these are I think I know.\n"
                         "His house is in the village though;
                         "He will not see me stopping here
                                                                \n"
                         "To watch his woods fill up with snow.\n";
std::size t result = word count(frost);
```

```
std::size_t word_count(std::string view s) {
 if (s.empty()) return 0;
  return std::transform reduce(ex::par unseq,
    begin(s), end(s) - 1, begin(s) + 1,
      (char 1, char r) { return std::isspace(1) && !std::isspace(r); }
std::size t result
                        0000010000010000010001010000010100000
                         10001000001001001000100000001000000000
                         10010000100010001001000000001000000000
                         10010000010001000001000010010000100000;
```

```
std::size t word count(std::string view s) {
 if (s.empty()) return 0;
 return std::transform reduce(ex::par unseq,
    begin(s), end(s) - 1, begin(s) + 1,
    std::size_t(!std::isspace(s.front()) ? 1 : 0),
      (char l, char r) { return std::isspace(l) && !std::isspace(r); }
std::size t result
                      = 1000001000001000001010000010100000
                         10001000001001001000100000001000000000
                         10010000100010001001000000001000000000
                         10010000010001000001000010010000100000;
```

```
std::size t word count(std::string view s) {
 if (s.empty()) return 0;
 return std::transform reduce(ex::par unseq,
   begin(s), end(s) - 1, begin(s) + 1,
   std::size t(!std::isspace(s.front()) ? 1 : 0),
   std::plus(),
   [] (char l, char r) { return std::isspace(l) && !std::isspace(r); }
std::size t result
                 = 1 + 1 + 1 + 1 + 1+1 + 1+1 +
                       1 + 1 + 1 + 1 + 1 + 1
                       1 +1 + 1 + 1 + 1 + 1
                       1 +1 + 1 + 1 + 1 + 1 + 1;
```

```
std::size t word count(std::string view s) {
 if (s.empty()) return 0;
  return std::transform reduce(ex::par unseq,
    begin(s), end(s) - 1, begin(s) + 1,
    std::size t(!std::isspace(s.front()) ? 1 : 0),
   std::plus(),
    [] (char l, char r) { return std::isspace(l) && !std::isspace(r); }
std::string view frost = "Whose woods these are I think I know.\n"
                         "His house is in the village though; \n"
                         "He will not see me stopping here
                                                                \n"
                         "To watch his woods fill up with snow.\n";
std::size t result = word count(frost);
```

In C++20, the Standard Library introduced ranges.

Unlike iterators, ranges are composable and can be lazy.

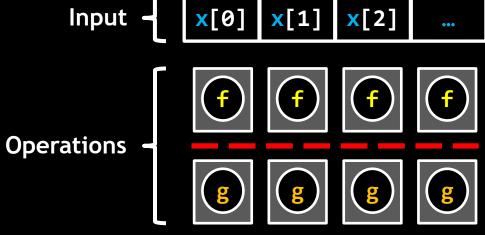
```
std::vector x{...};
         std::for_each(
            ex::par_unseq,
            begin(x), end(x),
            [...] (auto& obj) { ... });
    Input -
             x[0] x[1] x[2]
Operations -
```

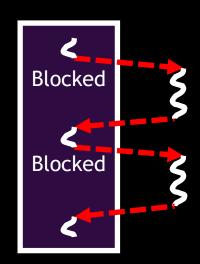
```
auto v = stdv::iota(1, N);
         std::for_each(
            ex::par_unseq,
            begin(v), end(v),
            [...] (auto idx) { ... });
    Input -
Operations -
```

```
std::span A{input, N * M};
std::span B{output, M * N};
auto v = stdv::cartesian_product(
 stdv::iota(0, N),
  stdv::iota(0, M));
std::for_each(ex::par_unseq,
  begin(v), end(v),
  [=] (auto idx) {
    auto [i, j] = idx;
   B[i + j * N] = A[i * M + j];
 });
```

```
std::span A{input, N * M};
  std::span B{output, M * N};
  auto v = stdv::cartesian_product(
    stdv::iota(0, N),
    stdv::iota(0, M));
    Input -
Operations -
```

```
std::vector x{...};
   std::for_each(ex::par unseq,
                  begin(x), end(x), f);
   std::for_each(ex::par_unseq,
                  begin(x), end(x), g);
    Input
                 x[1] x[2]
Operations
```

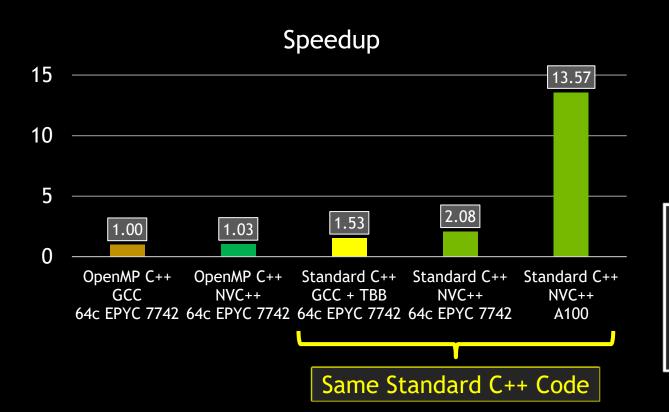


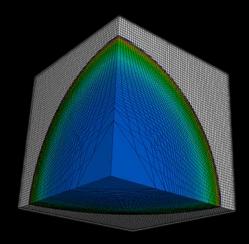


```
std::vector x{...};
   auto v = stdv::transform(x, f);
   std::for_each(ex::par_unseq,
                  begin(v), end(v), g);
    Input
                  x[1] x[2]
Operations
```

```
std::vector x{...};
   auto v = stdv::filter(x,
      [] (auto e) { return e > 0; });
   std::reduce(ex::par unseq,
                begin(v), end(v));
    Input
Operations
```

LULESH

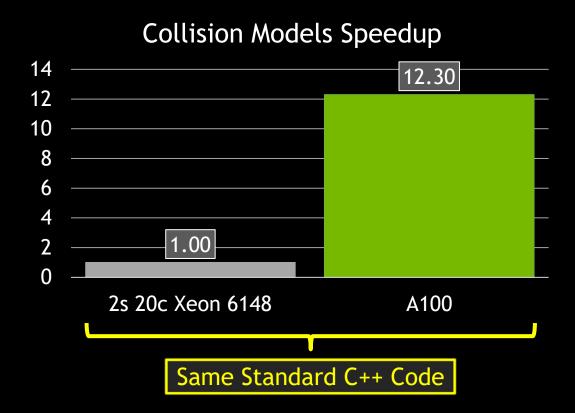




- Mini app for Lagrangian explicit shock hydrodynamics on an unstructured grid.
- Designed to stress vectorization, parallel overheads, & on-node parallelism.
- ~9000 lines of C++.
- Parallel versions in MPI, OpenMP, OpenACC, CUDA, RAJA, Kokkos, Standard C++, ...

https://github.com/LLNL/LULESH

STLBM



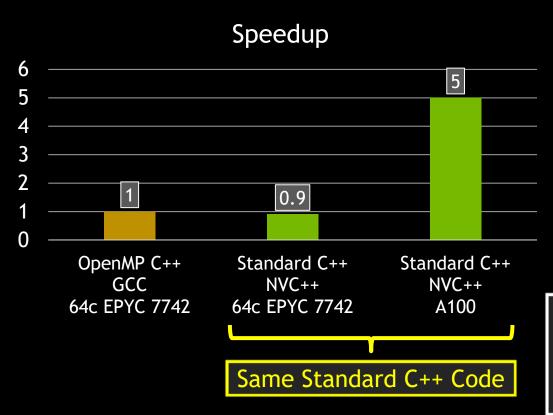
- Framework for parallel Lattice-Boltzmann simulations on multiple targets, including multicore CPUs & GPUs.
- > Implemented with C++ Standard Parallelism.
- No language extensions, external libraries, vendorspecific code annotations, or pre-compilation steps.

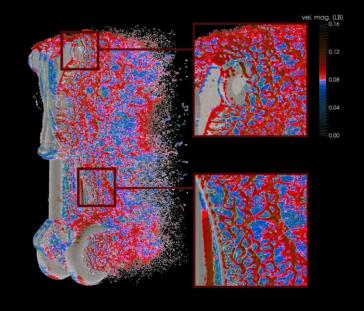
"We have with delight discovered the NVIDIA "stdpar" implementation of C++ Standard Parallel Algorithms. ... We believe that the result produces state-of-the-art performance, is highly didactical, and introduces a paradigm shift in cross-platform CPU/GPU programming in the community."

Professor Jonas Latt, University of Geneva

https://gitlab.com/unigehpfs/stlbm

M-AIA





- Package for aerospace flow and noise simulations.
- Solvers include Finite Volume, Navier-Stokes, and Lattice-Boltzmann.
- Switching from OpenMP to C++ Standard Parallelism.

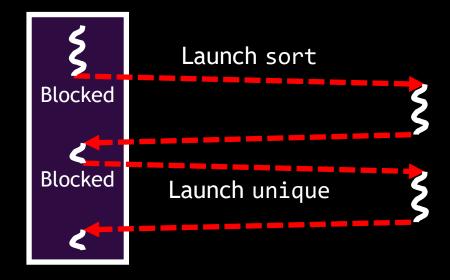
The C++ parallel algorithms introduced in C++17 are great, but they're just the start of the story.

```
std::vector<std::string_view> s{...};
std::sort(<u>ex::par unseq</u>, begin(s), end(s));
std::unique(<u>ex::par unseq</u>, begin(s), end(s));
```

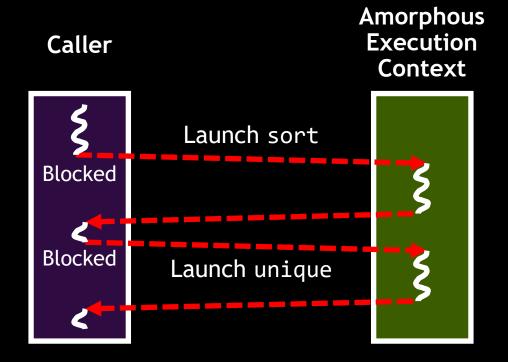
```
std::vector<std::string_view> s{...};

std::sort(ex::par unseq, begin(s), end(s));
std::unique(ex::par unseq, begin(s), end(s));
```

Caller



```
std::vector<std::string_view> s{...};
std::sort(ex::par unseq, begin(s), end(s));
std::unique(ex::par_unseq, begin(s), end(s));
```



Today, C++ has:

- No standard model for asynchrony.
- No standard way to express where things should execute.

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- No standard model for asynchrony.
- No standard way to express where things should execute.

The solution is coming soon:

Senders & Receivers

```
ex::scheduler auto sch = thread_pool.scheduler();

ex::sender auto begin = ex::schedule(sch);
ex::sender auto hi = ex::then(begin, [] { return 13; });
ex::sender auto add = ex::then(hi, [] (int a) { return a + 42; });

auto [i] = this thread::sync wait(add).value();
```

```
ex::scheduler auto sch = thread_pool.scheduler();

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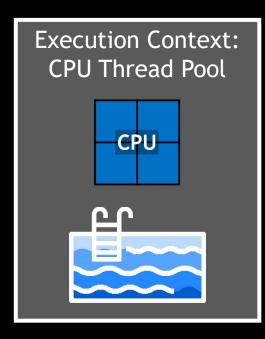
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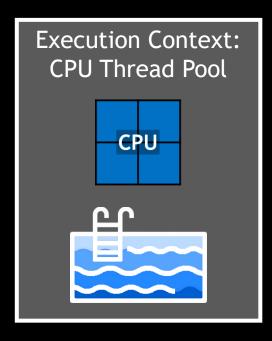
auto [i] = this thread::sync wait(add).value();
```

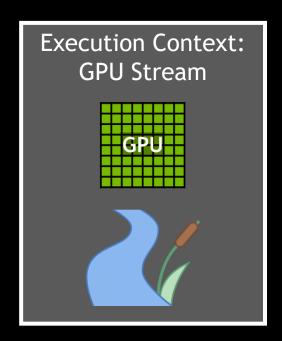
Senders represent asynchronous work.

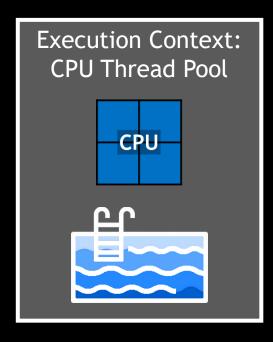
Senders represent asynchronous work.

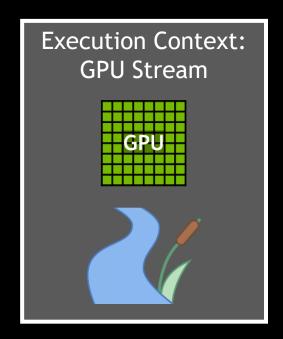
Receivers process asynchronous signals.

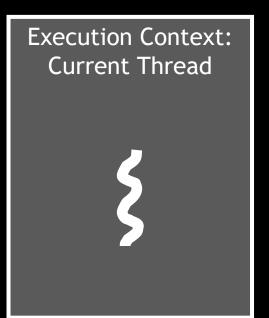


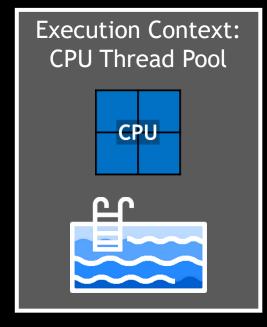




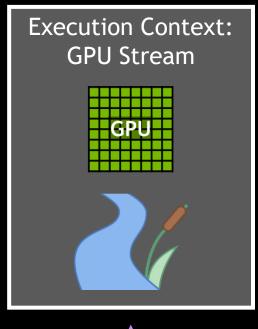


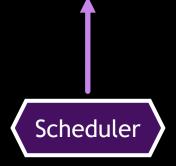






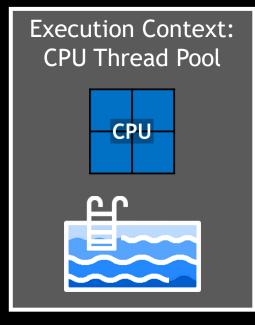




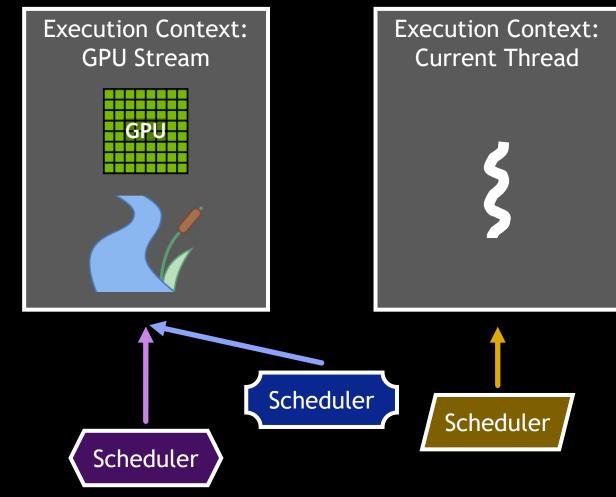


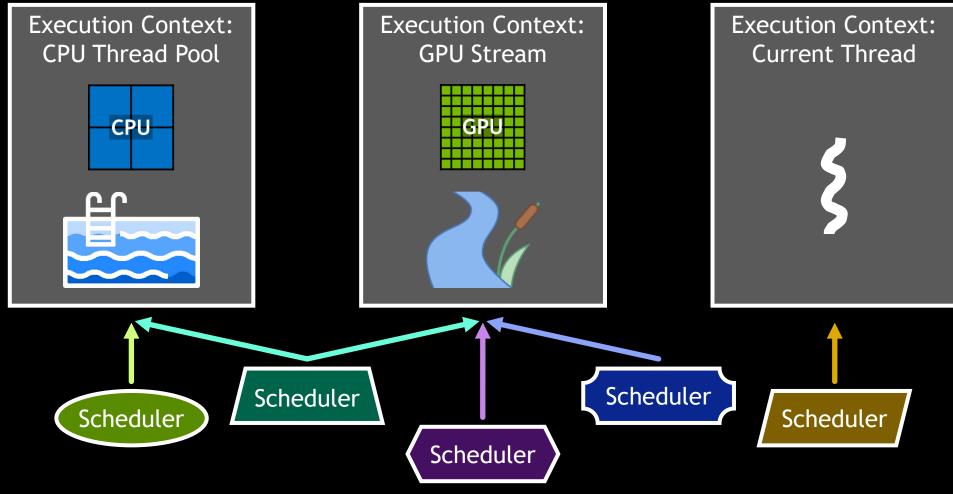








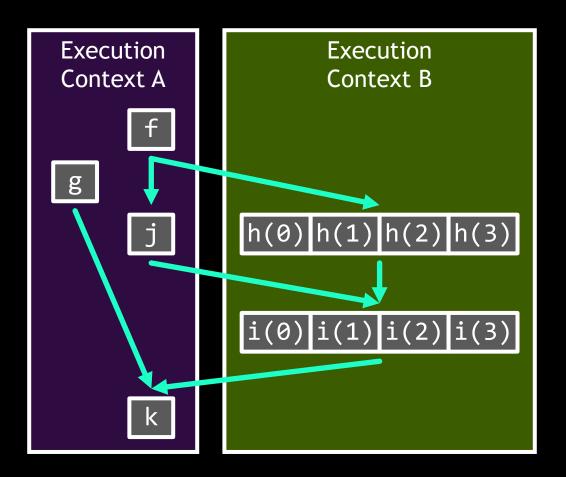




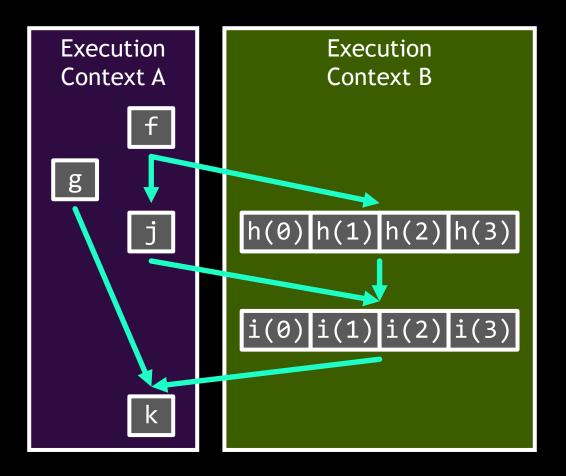
Schedulers produce senders.

> Senders represent asynchronous work.

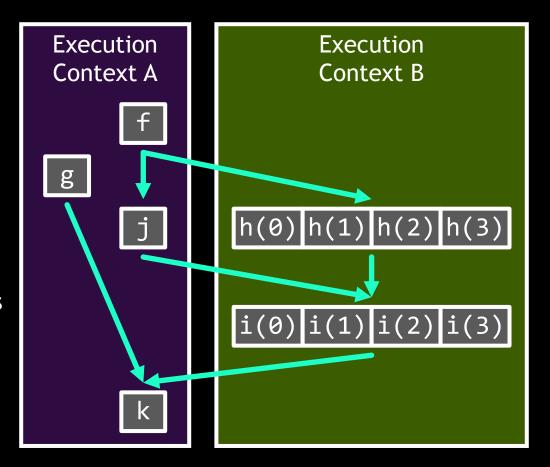
- > Senders represent asynchronous work.
- > Senders form the nodes of a task graph.



- > Senders represent asynchronous work.
- > Senders form the nodes of a task graph.
- > Senders are lazy.

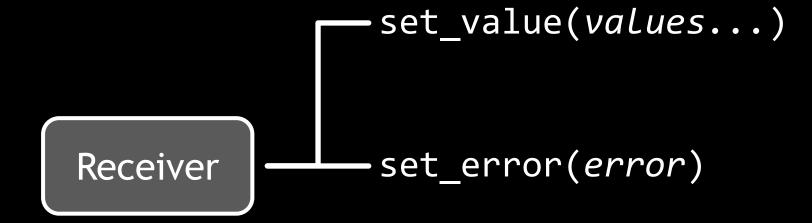


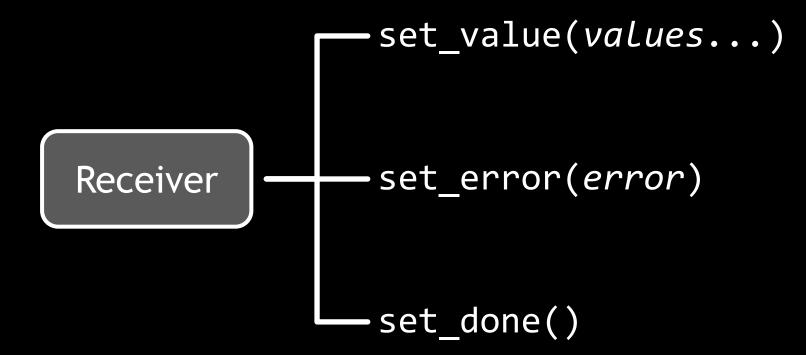
- Senders represent asynchronous work.
- > Senders form the nodes of a task graph.
- Senders are lazy.
- When a sender's work completes, it sends a signal to the receivers attached to it.



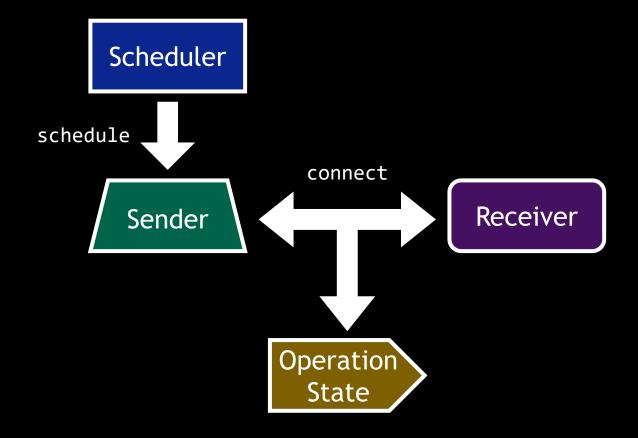
Receiver

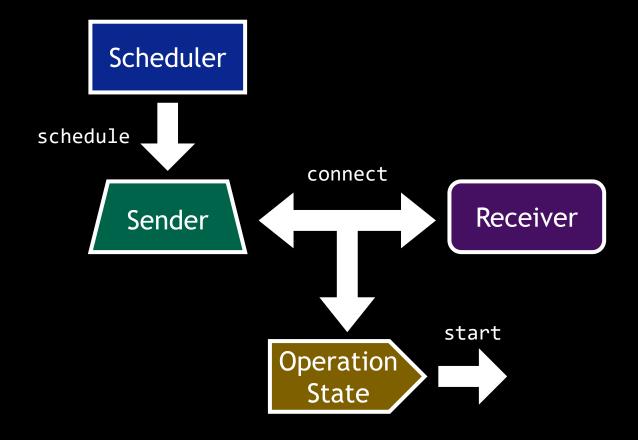
```
Receiver set_value(values...)
```

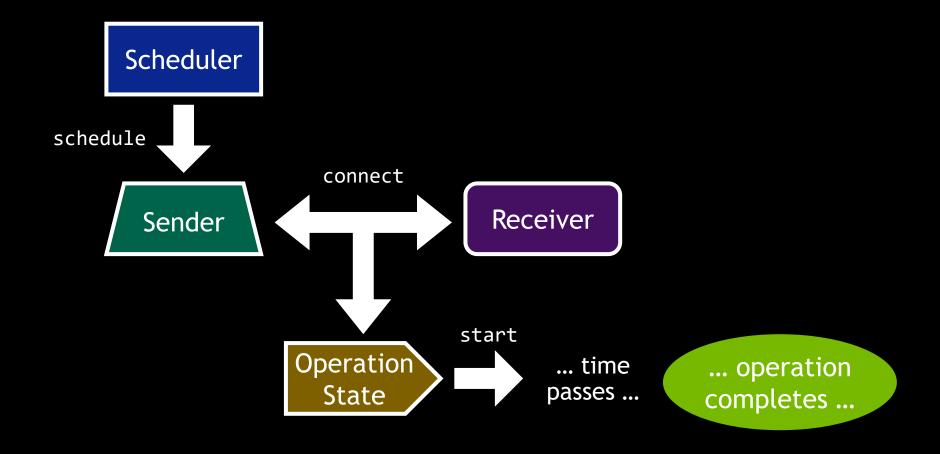


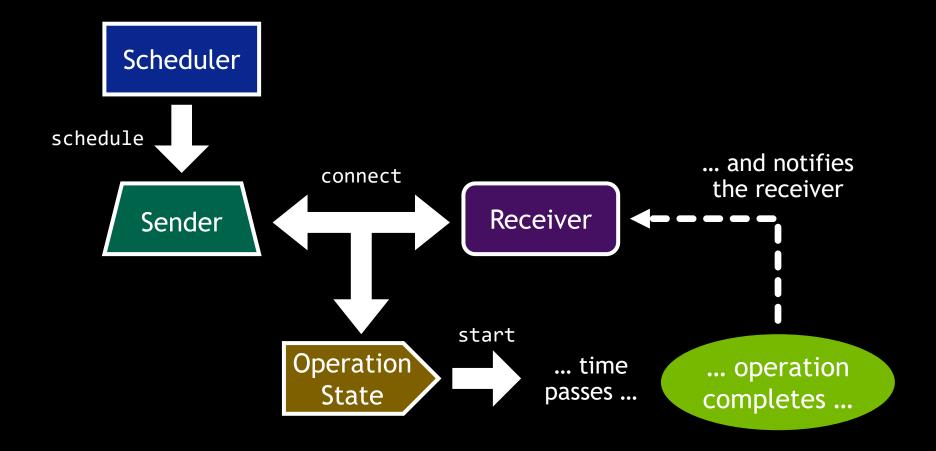


Scheduler schedule Sender









sender auto f(sender auto p, ...);

sender auto f(sender auto p, ...);

> Takes one or more senders.

sender auto f(sender auto p, ...);

- > Takes one or more senders.
- > Return a sender.

```
sender auto f(sender auto p, ...);
> Takes one or more senders.
  Return a sender.
  Pipeable (think *nix shells):
       snd | f | g
       is equivalent to
       g(f(snd))
```

```
std::vector<std::string_view> v{...};
ex::sender auto s = for each async(
                      ex::transfer(
                        unique_async(
                          sort_async(
                            ex::transfer just(gpu_stream_scheduler{}, v)
                        thread_pool.scheduler()
                         (std::string_view e)
                       { std::print(file, "{}\n", e); }
                    );
this thread::sync wait(s);
```

Sender Adaptor	Semantics Of Returned Sender		
<pre>then(sender auto last, invocable auto f)</pre>	Call f with the value sent by last.		

Sender Adaptor	Semantics Of Returned Sender		
<pre>then(sender auto last, invocable auto f)</pre>	Call f with the value sent by last.		
<pre>bulk(sender auto last, shape auto n, invocable auto body)</pre>	Call body for every index in n with the value sent by last.		

Sender Adaptor	Semantics Of Returned Sender			
<pre>then(sender auto last, invocable auto f)</pre>	Call f with the value sent by last.			
<pre>bulk(sender auto last, shape auto n, invocable auto body)</pre>	Call body for every index in n with the value sent by last.			
<u>transfer</u> (sender auto last, scheduler auto sch)	Transition to sch for the next sender.			

Sender Adaptor	Semantics Of Returned Sender		
<pre>then(sender auto last, invocable auto f)</pre>	Call f with the value sent by last.		
<pre>bulk(sender auto last, shape auto n, invocable auto body)</pre>	Call body for every index in n with the value sent by last.		
<u>transfer</u> (sender auto last, scheduler auto sch)	Transition to sch for the next sender.		
<pre>split(sender auto last)</pre>	Can be connected to multiple receivers.		

Sender Adaptor	Semantics Of Returned Sender			
<pre>then(sender auto last, invocable auto f)</pre>	Call f with the value sent by last.			
<pre>bulk(sender auto last, shape auto n, invocable auto body)</pre>	Call body for every index in n with the value sent by last.			
<u>transfer</u> (sender auto last, scheduler auto sch)	Transition to sch for the next sender.			
<pre>split(sender auto last)</pre>	Can be connected multiple times.			
<pre>when all(sender auto inputs)</pre>	Combines multiple senders into an aggregate.			

Sender Adaptor	Semantics Of Returned Sender				
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<pre>ensure started(sender auto last)</pre>	Connects and starts last.				

Sender Adaptor	Semantics Of Returned Sender				
<pre>then(sender auto last, invocable auto f)</pre>	Call f with the value sent by last.				
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Sender Factories	Semantics Of Returned Sender				

Sender Adaptor	Semantics Of Returned Sender				
<pre>then(sender auto last, invocable auto f)</pre>	Call f with the value sent by last.				
<pre>bulk(sender auto last, shape auto n, invocable auto body)</pre>	Call body for every index in n with the value sent by last.				
<pre>transfer(sender auto last,</pre>	Transition to sch for the next sender.				
<pre>split(sender auto last)</pre>	Can be connected multiple times.				
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Sender Factories	Semantics Of Returned Sender				
<pre>schedule (scheduler auto sch)</pre>	Completes on sch.				

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<pre>ensure started(sender auto last)</pre>	Connects and starts last.				
Sender Factories	Semantics Of Returned Sender				
<pre>schedule(scheduler auto sch)</pre>	Completes on sch.				

<u>just</u>(T&&... ts)

Send the values ts.

Sender Adaptor	Semantics Of Returned Sender			
<pre>then(sender auto last, invocable auto f)</pre>	Call f with the value sent by last.			
<pre>bulk(sender auto last, shape auto n, invocable auto body)</pre>	Call body for every index in n with the value sent by last.			
<pre>transfer(sender auto last, scheduler auto sch)</pre>	Transition to sch for the next sender.			
<pre>split(sender auto last)</pre>	Can be connected multiple times.			
<pre>when all(sender auto inputs)</pre>	Combines multiple senders into an aggregate.			
<pre>ensure started(sender auto last)</pre>	Connects and starts last.			
Sender Factories	Semantics Of Returned Sender			
<pre>schedule(scheduler auto sch)</pre>	Completes on sch.			
<u>just</u> (T&& ts)	Send the values ts.			
Sender Consumers	Semantics			

Sender Adaptor	Semantics Of Returned Sender				
<pre>then(sender auto last, invocable auto f)</pre>	Call f with the value sent by last.				
<pre>bulk(sender auto last, shape auto n, invocable auto body)</pre>	Call body for every index in n with the value sent by last.				
<u>transfer</u> (sender auto last, scheduler auto sch)	Transition to sch for the next sender.				
<pre>split(sender auto last)</pre>	Can be connected multiple times.				
<pre>when all(sender auto inputs)</pre>	Combines multiple senders into an aggregate.				
<pre>ensure started(sender auto last)</pre>	Connects and starts last.				
Sender Factories	Semantics Of Returned Sender				
<pre>schedule (scheduler auto sch)</pre>	Completes on sch.				
<u>just</u> (T&& ts)	Send the values ts.				
<u>just</u> (T&& ts) Sender Consumers	•				

```
sender auto before_snd = ...;
sender auto then_f_snd = then_sender(before_snd, f);
sender auto after_snd = after_sender(then_f_snd);
```

```
sender auto before_snd = ...;
sender auto then_f_snd = then_sender(before_snd, f);
sender auto after_snd = after_sender(then_f_snd);
```

Sender: after

Sender: then(f)

Sender: before

```
sender auto before_snd = ...;
sender auto then_f_snd = then_sender(before_snd, f);
sender auto after_snd = after_sender(then_f_snd);
...
return connect(after_snd, ...);
return connect(then_f_snd, after_rcv);
return connect(before_snd, then_f_rcv);
```

Sender: after

Sender: then(f)

Sender: before

```
sender auto before_snd = ...;
sender auto then_f_snd = then_sender(before_snd, f);
sender auto after_snd = after_sender(then_f_snd);
...
return connect(after_snd, ...);
return connect(then_f_snd, after_rcv);
return connect(before_snd, then_f_rcv);
```

Sender: after

Sender: then(f)

Sender: before

Receiver: before

Receiver: then(f)

Receiver: after

```
sender auto before_snd = ...;
sender auto then_f_snd = then_sender(before_snd, f);
sender auto after_snd = after_sender(then_f_snd);
...
return connect(after_snd, ...);
return connect(then_f_snd, after_rcv);
return connect(before_snd, then_f_rcv);
```

Sender: after

Sender: then(f)

Sender: before

Receiver: before

Receiver: then(f)

Receiver: after

```
set_value(before_rcv, ...);
set_value(then_f_rcv, before_val);
set_value(after_rcv, f(before_val));
```

```
inline constexpr sender_adaptor
inclusive_scan_async = [] (...) -> ex::sender auto {
```

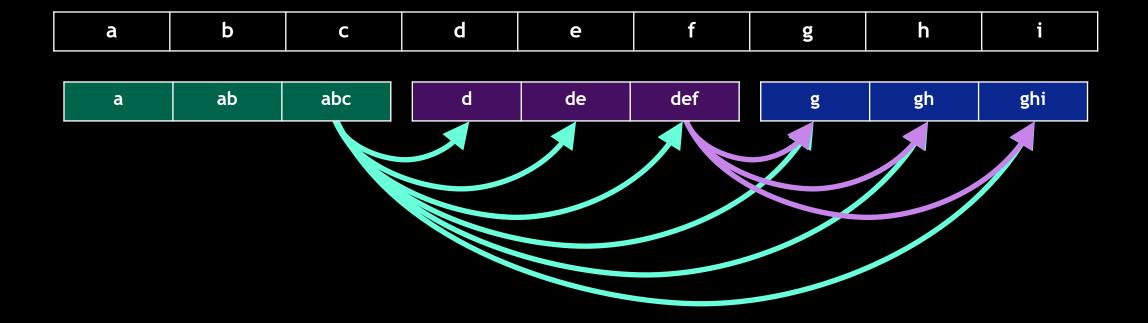
```
inline constexpr sender_adaptor
inclusive_scan_async = [] (ex::sender auto last, auto init, std::size_t tile_count) -> ex::sender auto {
    ...
}
```

```
inline constexpr sender_adaptor
inclusive_scan_async = [] (ex::sender auto last, auto init, std::size t tile_count) -> ex::sender auto {
 return last
        ex::then([=] (stdr::random_access_range auto input) {
                    std::vector<stdr::range_value_t<decltype(input)>> partials(tile_count + 1);
                    partials[0] = init;
                    return send_values(input, std::move(partials));
        ex::bulk(tile count,
                  [=] (std::size_t i, auto input, auto partials) {
                    auto tile size = (input.size() + tile count - 1) / tile count;
                                  = i * tile size;
                    auto start
                                   = std::min(input.size(), (i + 1) * tile_size);
                    auto end
                  })
```

a	b	С	d	е	f	g	h	i
a	b	С	d	е	f	g	h	i

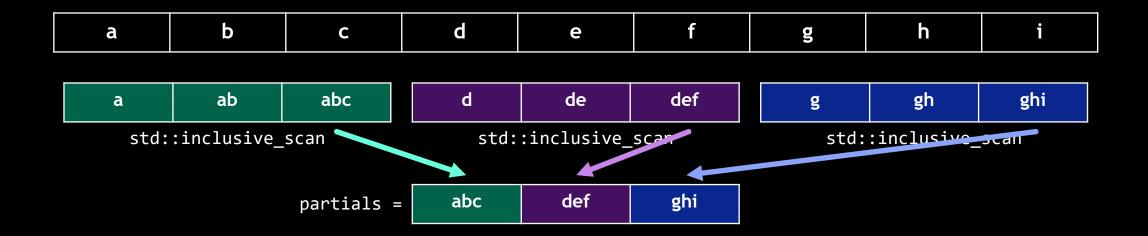
i b d h a C e g ghi ab abc d de def gh a g std::inclusive_scan std::inclusive_scan std::inclusive_scan

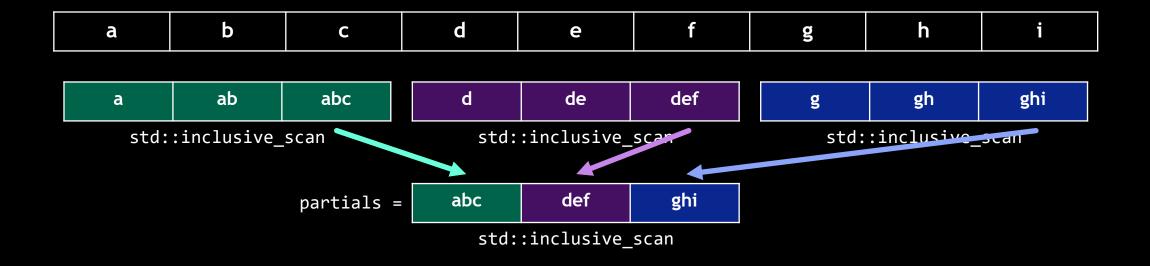
```
inline constexpr sender_adaptor
inclusive scan_async = [] (ex::sender auto last, auto init, std::size t tile_count) -> ex::sender auto {
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                    auto start
                                    = i * tile size;
                                    = std::min(input.size(), (i + 1) * tile_size);
                    auto end
                                         std::inclusive_scan(begin(input) + start,
                                                             begin(input) + end,
                                                             begin(input) + start);
                  })
```



```
inline constexpr sender_adaptor
inclusive scan_async = [] (ex::sender auto last, auto init, std::size t tile_count) -> ex::sender auto {
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                    auto start
                                    = i * tile size;
                                    = std::min(input.size(), (i + 1) * tile_size);
                    auto end
                                    = *--std::inclusive scan(begin(input) + start,
                                                             begin(input) + end,
                                                             begin(input) + start);
                  })
```

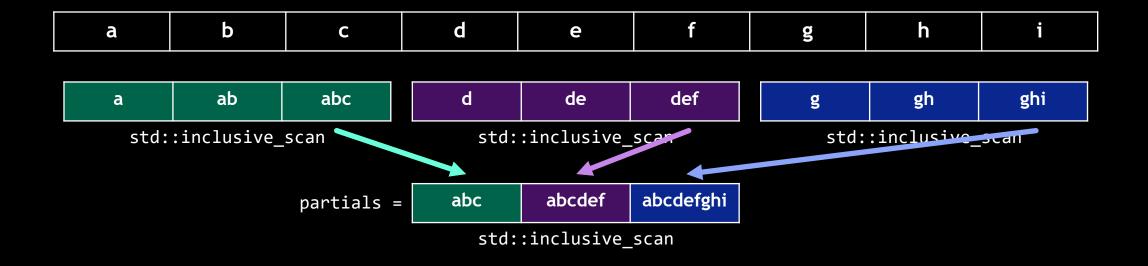
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                    auto end
                    partials[i + 1] = *--std::inclusive scan(begin(input) + start,
                                                            begin(input) + end,
                                                            begin(input) + start);
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```
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inclusive scan_async = [] (ex::sender auto last, auto init, std::size t tile count) -> ex::sender auto {
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        ex::then([=] (stdr::random_access_range auto input) {
                   std::vector<stdr::range value t<decltype(input)>> partials(tile count + 1);
                   partials[0] = init;
                   return send values(input, std::move(partials));
        ex::bulk(tile count,
                  [=] (std::size_t i, auto input, auto partials) {
                   auto tile size = (input.size() + tile count - 1) / tile count;
                   auto start
                                 = i * tile size;
                             = std::min(input.size(), (i + 1) * tile_size);
                   auto end
                   partials[i + 1] = *--std::inclusive_scan(begin(input) + start,
                                                            begin(input) + end,
                                                            begin(input) + start);
       ex::then([] (auto input, auto partials) {
                   std::inclusive scan(begin(partials), end(partials), begin(partials));
                 })
```

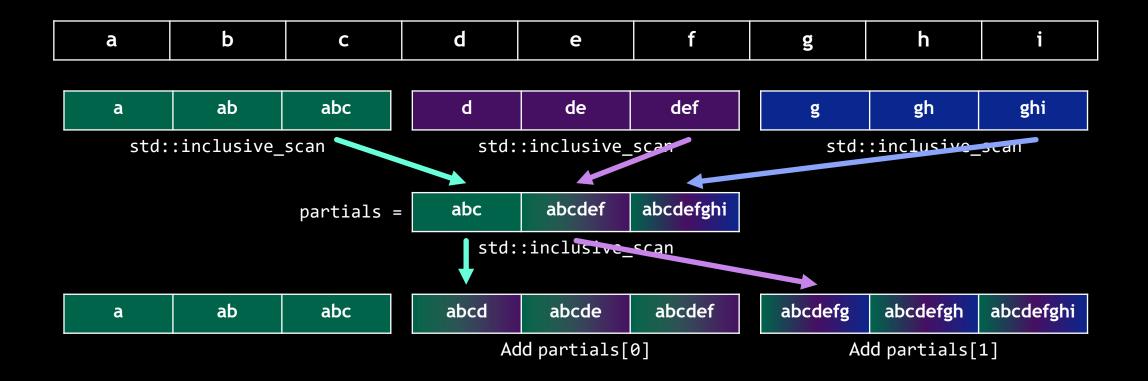
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inline constexpr sender adaptor
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                             = std::min(input.size(), (i + 1) * tile_size);
                   auto end
                   partials[i + 1] = *--std::inclusive_scan(begin(input) + start,
                                                            begin(input) + end,
                                                            begin(input) + start);
                  })
        ex::then([] (auto input, auto partials) {
                   std::inclusive scan(begin(partials), end(partials), begin(partials));
                   return send values(input, std::move(partials));
       ex::bulk(tile count,
                  [=] (std::size_t i, auto input, auto partials) {
                 })
```

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inclusive scan async = [] (ex::sender auto last, auto init, std::size t tile count) -> ex::sender auto {
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        ex::then([=] (stdr::random_access_range auto input) {
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                  [=] (std::size_t i, auto input, auto partials) {
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                   partials[i + 1] = *--std::inclusive scan(begin(input) + start,
                                                            begin(input) + end,
                                                            begin(input) + start);
                 })
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                 })
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                   return send values(input, std::move(partials));
        ex::bulk(tile count,
                  [=] (std::size t i, auto input, auto partials) {
                    auto tile size = (input.size() + tile count - 1) / tile count;
                                 = i * tile size;
                   auto start
                             = std::min(input.size(), (i + 1) * tile size);
                   auto end
                   partials[i + 1] = *--std::inclusive scan(begin(input) + start,
                                                            begin(input) + end,
                                                            begin(input) + start);
                  })
        ex::then([] (auto input, auto partials) {
                   std::inclusive scan(begin(partials), end(partials), begin(partials));
                   return send values(input, std::move(partials));
                  })
        ex::bulk(tile count,
                  [=] (std::size_t i, auto input, auto partials) {
                   auto tile size = (input.size() + tile count - 1) / tile count;
                   auto start
                                  = i * tile size;
                                  = std::min(input.size(), (i + 1) * tile_size);
                   auto end
                   std::for_each(begin(input) + start, begin(input) + end,
                                  [&] (auto& e) { e = partials[i] + e; });
                 })
```



```
inline constexpr sender adaptor
inclusive scan async = [] (ex::sender auto last, auto init, std::size t tile count) -> ex::sender auto {
 return last
         ex::then([=] (stdr::random_access_range auto input) {
                    std::vector<stdr::range value t<decltype(input)>> partials(tile count + 1);
                    partials[0] = init;
                    return send values(input, std::move(partials));
        ex::bulk(tile count,
                  [=] (std::size t i, auto input, auto partials) {
                    auto tile size = (input.size() + tile count - 1) / tile count;
                                  = i * tile size;
                    auto start
                             = std::min(input.size(), (i + 1) * tile size);
                    auto end
                    partials[i + 1] = *--std::inclusive scan(begin(input) + start,
                                                             begin(input) + end,
                                                             begin(input) + start);
                  })
         ex::then([] (auto input, auto partials) {
                    std::inclusive scan(begin(partials), end(partials), begin(partials));
                    return send values(input, std::move(partials));
                  })
        ex::bulk(tile count,
                  [=] (std::size_t i, auto input, auto partials) {
                    auto tile size = (input.size() + tile count - 1) / tile count;
                    auto start
                                  = i * tile size;
                                  = std::min(input.size(), (i + 1) * tile size);
                    auto end
                    std::for_each(begin(input) + start, begin(input) + end,
                                  [&] (auto& e) { e = partials[i] + e; });
       | ex::then([=] (auto input, auto partials) { return input; });
```

```
inline constexpr sender adaptor
inclusive scan async = [] (ex::sender auto last, auto init, std::size t tile count) -> ex::sender auto {
 return last
        ex::then([=] (stdr::random_access_range auto input) {
                   std::vector<stdr::range value t<decltype(input)>> partials(tile count + 1);
                   partials[0] = init;
                   return send values(input, std::move(partials));
        ex::bulk(tile count,
                  [=] (std::size t i, auto input, auto partials) {
                    auto tile size = (input.size() + tile count - 1) / tile count;
                                 = i * tile size;
                   auto start
                             = std::min(input.size(), (i + 1) * tile size);
                   auto end
                   partials[i + 1] = *--std::inclusive scan(begin(input) + start,
                                                            begin(input) + end,
                                                             begin(input) + start);
                  })
        ex::then([] (auto input, auto partials) {
                   std::inclusive scan(begin(partials), end(partials), begin(partials));
                   return send values(input, std::move(partials));
                  })
        ex::bulk(tile count,
                  [=] (std::size t i, auto input, auto partials) {
                   auto tile size = (input.size() + tile count - 1) / tile count;
                   auto start
                                  = i * tile size;
                                  = std::min(input.size(), (i + 1) * tile_size);
                   auto end
                   std::for_each(begin(input) + start, begin(input) + end,
                                  [&] (auto& e) { e = partials[i] + e; });
                  })
        ex::then([=] (auto input, auto partials) { return input; });
```

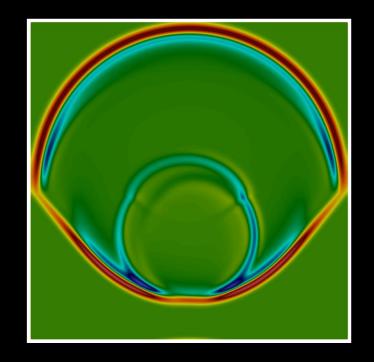
```
stdr::for_each(rng, f);
stdr::for_each(rng, g);
stdr::for_each(rng, h);
```

```
ex::sender of<stdr::range> auto
transform_async(ex::sender of<stdr::range> auto rng, std::callable auto c);
```

```
auto max = *stdr::max_element(rng);
stdr::for_each(rng,
  [=] (auto x) { return x / max; });
```

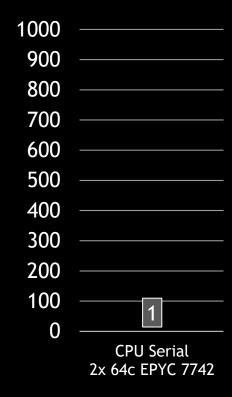
```
ex::sender of<stdr::range, stdr::range, ...> auto
transform async(ex::sender of<stdr::range, stdr::range, ...> auto rngs,
                std::callable auto f);
ex::sender of<stdr::range, std::forward_iterator> auto
max element async(ex::sender of<stdr::range> auto rng);
                                          ex::sender auto snd =
                                              ex::transfer just(sch, rng)
auto max = *stdr::max element(rng);
                                             max element async
                                            ex::let value(
                                                [] (auto r, auto max) {
stdr::for each(rng,
  [=] (auto x) { return x / max; });
                                                  return ex::just(r, max);
                                                })
                                              transform_async(std::divides);
```

```
sender auto maxwell_eqs(scheduler auto& compute,
                        grid accessor A, ...) {
  return repeat_n(n_outer_iterations,
           repeat_n(n_inner_iterations,
               schedule(compute)
              bulk(G.cells, update h(G))
              halo_exchange(G, hx, hy)
              bulk(G.cells, update_e(time, dt, G))
             halo_exchange(G, hx, hy))
            transfer(cpu_serial_scheduler)
            then(output results))
```



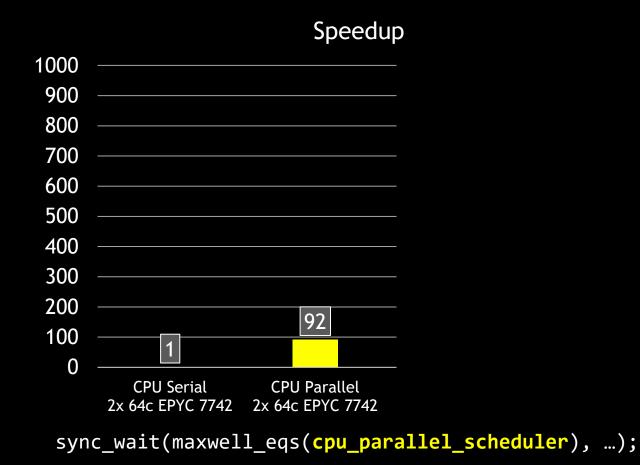
Change one line of code and scale from a single CPU thread...

Speedup

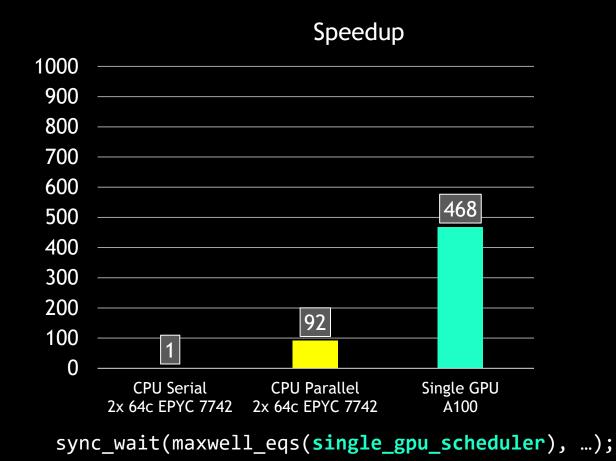


sync_wait(maxwell_eqs(cpu_serial_scheduler), ...);

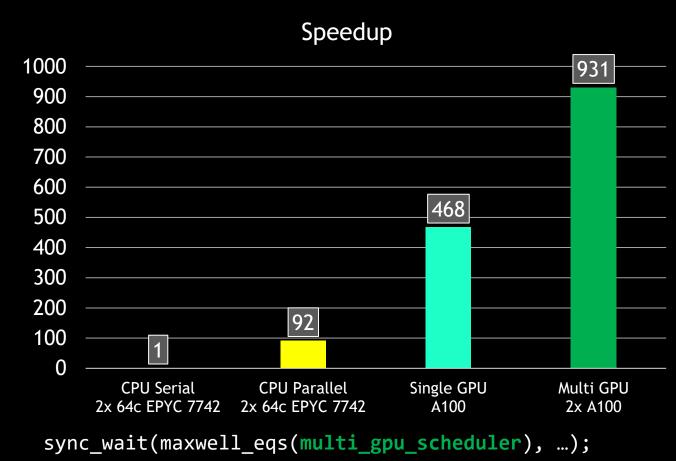
Change one line of code and scale from a single CPU thread up to multiple CPU threads...



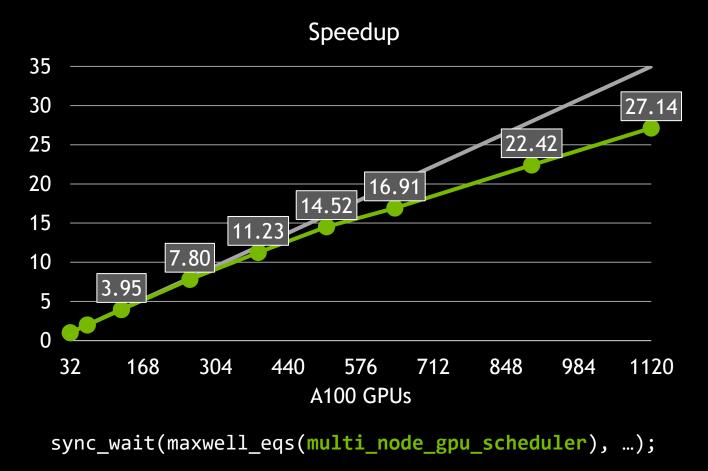
Change one line of code and scale from a single CPU thread up to a GPU...



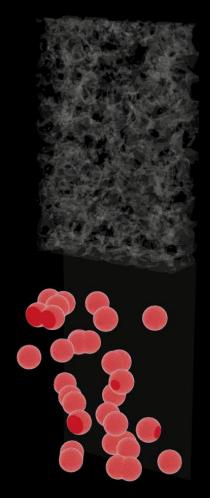
Change one line of code and scale from a single CPU thread up to multiple GPUs...

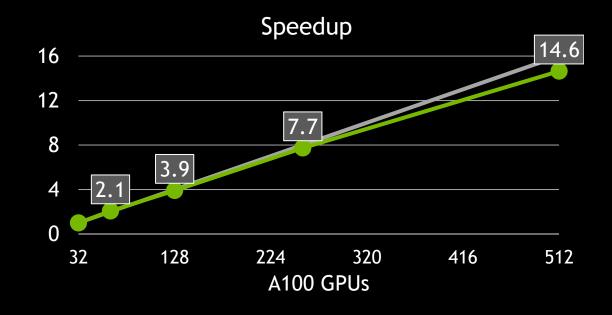


Change one line of code and scale from a single CPU thread up to a cluster of GPUs!



Palabos Carbon Sequestration

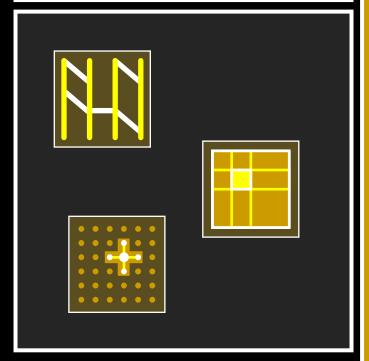




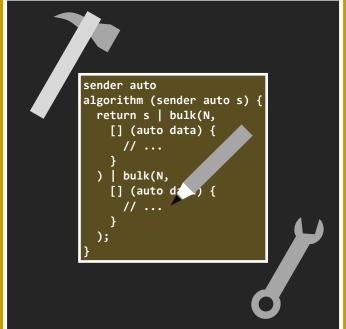
- Palabos is a framework for parallel computational fluid dynamics simulations using the Lattice-Boltzmann method.
- Code for multi-component flow through a porous media ported to C++ Senders and Receivers.
- Application: simulating carbon sequestration in sandstone.

Pillars of C Standard Parallelism

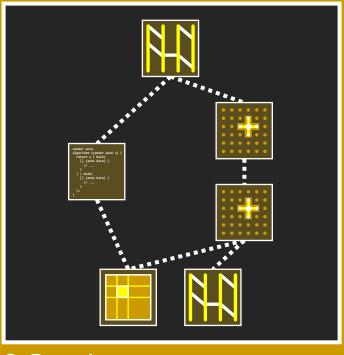
Common Algorithms that Dispatch to Vendor-Optimized Parallel Libraries



Tools to Write Your Own Parallel
Algorithms that Run Anywhere



Mechanisms for Composing Parallel Invocations into Task Graphs



With Senders & Receivers



Standard Algorithms

Serial (C++98)

Parallel (C++17)

Asynchronous

```
std::vector<T> x{...};
std::for each(
 begin(x), end(x),
f);
std::for each(
 begin(x), end(x),
 g);
std::for each(
 begin(x), end(x),
 h);
```

```
std::vector<T> x{...};
std::for each(
 ex::par unseq,
 begin(x), end(x),
f);
std::for each(
 ex::par_unseq,
 begin(x), end(x),
 g);
std::for each(
 ex::par unseq,
 begin(x), end(x),
 h);
```

```
std::vector<T> x(...);
ex::sender auto s
 = ex::transfer just(sch, x)
   for each async(f)
   for each async(g)
  for each async(h);
this thread::sync wait(s);
```

Today, C++ has no reasonable abstraction for multi-dimensional data.

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The solution is coming in C++23:

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- > Metadata can be dynamic or static.
- > Parameterizes layout.

- > Non-owning; pointer + metadata.
- > Metadata can be dynamic or static.
- > Parameterizes layout and access.

template <typename Size, Size... Extents> class std::extents;

```
template <typename Size, Size... Extents>
class std::extents;

std::extents e0{16, 32};
// Equivalent to:
std::extents<std::dynamic extent, std::dynamic extent> e1{16, 32};

e0.rank() == 2
e0.extent(0) == 16
e0.extent(1) == 32
```

```
template <typename Size, Size... Extents>
class std::extents;

std::extents e0{16, 32};

// Equivalent to:
std::extents<std::dynamic extent, std::dynamic extent> e1{16, 32};

std::dextents<<2> e2{16, 32};

e0.rank() == 2
e0.extent(0) == 16
e0.extent(1) == 32
```

```
template <typename Size, Size... Extents>
class std::extents;
std::extents e0{16, 32};
// Equivalent to:
std::extents<std::dynamic extent, std::dynamic extent> e1{16, 32};
std::dextents<2> e2{16, 32};
e0.rank() == 2
e0.extent(0) == 16
e0.extent(1) == 32
std::extents<16, 32> e3;
```

```
template <typename Size, Size... Extents>
class std::extents;
<u>std::extents</u> e0{16, 32};
// Equivalent to:
std::extents<std::dynamic extent, std::dynamic extent> e1{16, 32};
std::dextents<2> e2{16, 32};
e0.rank() == 2
e0.extent(0) == 16
e0.extent(1) == 32
std::extents<16, 32> e3;
std::extents<16, std::dynamic extent> e4{32};
```

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```
template <typename Size, Size... Extents>
class std::extents;
std::extents e0{16, 32};
// Equivalent to:
std::extents<std::dynamic extent, std::dynamic extent> e1{16, 32};
std::dextents<2> e2{16, 32};
e0.rank() == 2
e0.extent(0) == 16
e0.extent(1) == 32
std::extents<16, 32> e3;
std::extents<16, std::dynamic extent> e4{32};
<u>std::extents</u> e5{16, 32, 48, 4};
```

template <</pre>

class std::mdspan;

template $\langle class \underline{T},$

class std::mdspan;

class std::mdspan;

```
template \langle class \underline{T},
            class Extents,
            class LayoutPolicy = std::layout right,
                                                                      >
class std::mdspan;
```

```
template \langle class \underline{I},
           class Extents,
           class LayoutPolicy = std::layout right,
           class AccessorPolicy = std::default accessor<T>>
class std::mdspan;
```

```
template <class T,
          class Extents,
          class LayoutPolicy = std::layout right,
          class AccessorPolicy = std::default accessor<T>>
class std::mdspan;
std::mdspan m0{data, 16, 32};
// Equivalent to:
std::mdspan<double, std::dextents<2>> m1{data, 16, 32};
m0[i, j] == data[i * M + j]
std::mdspan m2{data, std::extents<16, 32>{}};
// Equivalent to:
std::mdspan<double, std::extents<16, 32>> m3{data};
std::mdspan m4{data, std::extents<16, std::dynamic extent>{32}};
```

- > C++, NumPy (default)
- Rightmost extent is contiguous

```
mdspan A{data, N, M};
mdspan A{data, layout right::mapping{N, M}};

A[i, j] == data[i * M + j]
A.stride(0) == M
A.stride(1) == 1
```

- > C++, NumPy (default)
- Rightmost extent is contiguous

```
mdspan A{data, N, M};
mdspan A{data, layout right::mapping{N, M}};

A[i, j] == data[i * M + j]
A.stride(0) == M
A.stride(1) == 1
```

Location	Element	
0	a_{11}	
1	a_{12}	
2	a_{21}	
3	a_{22}	

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$$

- > C++, NumPy (default)
- Rightmost extent is contiguous

Column-Major AKA Left

- > Fortran, MATLAB
- Leftmost extent is contiguous

```
mdspan A{data, N, M};
mdspan A{data, layout right::mapping{N, M}};

A[i, j] == data[i * M + j]
A.stride(0) == M
A.stride(1) == 1
B[i, j] == data[i + j * N]
B.stride(0) == N
B.stride(1) == N
```

Location	Element	
0	a_{11}	
1	a_{12}	
2	a_{21}	
3	a_{22}	

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$$

- > C++, NumPy (default)
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```
mdspan A{data, N, M};
mdspan A{data, layout right::mapping{N, M}};

A[i, j] == data[i * M + j]

A.stride(0) == M

A.stride(1) == 1

B.stride(1) == N
mdspan B{data, layout left::mapping{N, M}};

B[i, j] == data[i + j * N]

B.stride(0) == 1

B.stride(1) == N
```

Location	Element	
0	a_{11}	
1	a_{12}	
2	a_{21}	
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$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$$

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- > C++, NumPy (default)
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```
mdspan A{data, N, M};
mdspan A{data, layout right::mapping{N, M}};

A[i, j] == data[i * M + j]

A.stride(0) == M

A.stride(1) == 1
B[i, j] == data[i + j * N]
B.stride(0) == 1
B.stride(1) == N
```

User-Defined Strides

```
mdspan C{data, layout stride::mapping{extents{N, M}, {X, Y}};

A[i, j] == data[i * X + j * Y]
A.stride(0) == X
A.stride(1) == Y
```

Anyone can define a layout.

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Layouts may:

▶ Be non-contiguous.

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- > Map multiple indices to the same location.

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Layouts may:

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- > Map multiple indices to the same location.
- > Perform complicated computations.

Anyone can define a layout.

Layouts may:

- ▶ Be non-contiguous.
- > Map multiple indices to the same location.
- > Perform complicated computations.
- > Have or refer to state.

Parametric layout enables generic multi-dimensional algorithms.

void your_function(<u>Eigen::Matrix</u><double, Eigen::Dynamic, Eigen::Dynamic>& m);

```
void your_function(<u>Eigen::Matrix</u><double, Eigen::Dynamic, Eigen::Dynamic>& m);
your_function(<u>Eigen::Matrix</u><double, Eigen::Dynamic, Eigen::Dynamic>{...});
```

```
void your_function(Eigen::Matrix<double, Eigen::Dynamic, Eigen::Dynamic>& m);
your_function(Eigen::Matrix<double, Eigen::Dynamic, Eigen::Dynamic>{...});
your_function(boost::numeric::ublas::matrix<double>{...});
your_function(Mat{...}); // PETSc
your_function(blaze::DynamicMatrix<double, blaze::rowMajor>{...});
your_function(cutlass::HostTensor<float, cutlass::layout::ColumnMajor>{...});
// ...
```

```
void your_function(std::mdspan<T, Extents, Layout, Accessor> m);

your_function(Eigen::Matrix<double, Eigen::Dynamic, Eigen::Dynamic>{...});
your_function(boost::numeric::ublas::matrix<double>{...});
your_function(Mat{...}); // PETSc
your_function(blaze::DynamicMatrix<double, blaze::rowMajor>{...});
your_function(cutlass::HostTensor<float, cutlass::layout::ColumnMajor>{...});
// ...
```

```
struct my matrix {
public:
 my matrix(std::size t N, std::size t M)
    : num rows (N), num cols (M), storage (num rows * num cols ) {}
 double& operator()(size t i, size t j)
 { return storage [i * num cols + j]; }
 const double& operator()(size t i, size t j) const
 { return storage [i * num cols + j]; }
  std::size_t num_rows() const { return num_rows_; }
  std::size t num cols() const { return num cols ; }
private:
 std::size t num rows , num cols ;
 std::vector<double> storage ;
};
```

```
struct my matrix {
public:
 my matrix(std::size t N, std::size t M)
    : num rows (N), num cols (M), storage (num rows * num cols ) {}
 double& operator()(size t i, size t j)
 { return storage_[i * num_cols_ + j]; }
 const double& operator()(size t i, size t j) const
 { return storage [i * num cols + j]; }
 std::size t num rows() const { return num rows ; }
 std::size t num cols() const { return num cols ; }
 operator std::mdspan<double, std::dextents<2>>() const
  { return {storage_, num_rows_, num_cols_}; }
private:
 std::vector<double> storage ;
};
```

```
std::mdspan A{input, N, M, O};
std::mdspan B{output, N, M, O};
auto v = stdv::cartesian product(
  stdv::iota(1, A.extent(0) - 1),
  stdv::iota(1, A.extent(1) - 1),
  stdv::iota(1, A.extent(2) - 1));
std::for_each(ex::par_unseq,
  begin(v), end(v),
  [=] (auto idx) {
   auto [i, j, k] = idx;
   B[i, j, k] = (A[i, j, k-1] +
                 A[i-1, j, k] +
     A[i, j-1, k] + A[i, j, k] + A[i, j+1, k]
                  + A[i+1, j, k]
                  + A[i, j, k+1]) / 7.0
  });
```

```
std::mdspan A{input,
             std::layout left::mapping{N, M, 0}};
std::mdspan B{output,
             std::layout left::mapping{N, M, 0}};
auto v = stdv::cartesian product(
 stdv::iota(1, A.extent(0) - 1),
  stdv::iota(1, A.extent(1) - 1),
  stdv::iota(1, A.extent(2) - 1));
std::for each(ex::par unseq,
 begin(v), end(v),
  [=] (auto idx) {
   auto [i, j, k] = idx;
   B[i, j, k] = (A[i, j, k-1] +
                A[i-1, j, k] +
     A[i, j-1, k] + A[i, j, k] + A[i, j+1, k]
                  + A[i+1, j, k]
                  + A[i, j, k+1]) / 7.0
 });
```

```
std::span A{input, N * M};
std::span B{output, M * N};
auto v = stdv::cartesian_product(
  stdv::iota(0, N),
  stdv::iota(0, M));
std::for_each(ex::par_unseq,
  begin(v), end(v),
  [=] (auto idx) {
    auto [i, j] = idx;
   B[i + j * N] = A[i * M + j];
  });
```

```
std::mdspan A{input, N, M};
std::mdspan B{output, M, N};
auto v = stdv::cartesian_product(
  stdv::iota(0, A.extent(0)),
  stdv::iota(0, A.extent(1)));
std::for_each(ex::par_unseq,
  begin(v), end(v),
  [=] (auto idx) {
    auto [i, j] = idx;
   B[j, i] = A[i, j];
  });
```

```
std::mdspan A{input, N, M};
std::mdspan B{output, M, N};

stdr::for_each(
   ex::par_unseq,
   A.indices(),
   [=] (auto [i, j]) {
     B[j, i] = A[i, j];
   });
```

```
std::mdspan A{input, N, M};
std::mdspan B{output, M, N};

ex::sender auto s =
    ex::transfer_just(sch, A.indices())
    | for_each_async(
        [=] (auto [i, j]) {
        B[j, i] = A[i, j];
        });
```


Slice Specifier	Argument	Reduces Rank?
Single Index	Integral	$\overline{\mathbf{V}}$

Slice Specifier	Argument	Reduces Rank?
Single Index	Integral	✓
Range of Indices	<pre>std::pair<integral, integral=""> std::tuple<integral, integral=""></integral,></integral,></pre>	×

Slice Specifier	Argument	Reduces Rank?
Single Index	Integral	\square
Range of Indices	<pre>std::pair<integral, integral=""> std::tuple<integral, integral=""></integral,></integral,></pre>	×
All Indices	std::full_extent	×

```
std::mdspan m0{data, 64, 128, 32};
auto m1 = std::submdspan(m0, std::tuple{15, 23},
                            std::tuple{31, 39},
                            std::tuple{ 7, 15});
m1.rank()
            == 3
```

```
std::mdspan m0{data, 64, 128, 32};
auto m1 = std::submdspan(m0, std::tuple{15, 23},
                             std::tuple{31, 39},
                             std::tuple{ 7, 15});
m1.rank() == 3
m1.extent(0) == 8
m1.extent(1) == 8
m1.extent(2) == 8
m1[i, j, k] == m0[i + 15, j + 31, k + 7]
auto m2 = std::submdspan(m0, 15,
                             std::full extent,
                             31);
```

```
std::mdspan m0{data, 64, 128, 32};
auto m1 = std::submdspan(m0, std::tuple{15, 23},
                            std::tuple{31, 39},
                             std::tuple{ 7, 15});
m1.rank() == 3
m1.extent(0) == 8
m1.extent(1) == 8
m1.extent(2) == 8
m1[i, j, k] == m0[i + 15, j + 31, k + 7]
auto m2 = std::submdspan(m0, 15,
                             std::full extent,
                             31);
m2.rank() == 1
```

```
std::mdspan m0{data, 64, 128, 32};
auto m1 = std::submdspan(m0, std::tuple{15, 23},
                             std::tuple{31, 39},
                             std::tuple{ 7, 15});
m1.rank() == 3
m1.extent(0) == 8
m1.extent(1) == 8
m1.extent(2) == 8
m1[i, j, k] == m0[i + 15, j + 31, k + 7]
auto m2 = std::submdspan(m0, 15,
                             std::full extent,
                             31);
m2.rank() == 1
m2.extent(0) == 128
```

```
std::mdspan m0{data, 64, 128, 32};
auto m1 = std::submdspan(m0, std::tuple{15, 23},
                               std::tuple{31, 39},
                               std::tuple{ 7, 15});
m1.rank() == 3
m1.extent(0) == 8
m1.extent(1) == 8
m1.extent(2) == 8
m1[i, j, k] == m0[i + 15, j + 31, k + 7]
auto m2 = <a href="mailto:std::submdspan">std::submdspan</a> (m0, 15,
                               std::full extent,
                               31);
m2.rank() == 1
m2.extent(0) == 128
m2[j] == m0[15, j, 31]
```

```
std::mdspan A{input, N, M};
std::mdspan B{output, M, N};
std::size_t T = ...;
```

```
std::mdspan A{input, N, M};
std::mdspan B{output, M, N};
std::size t T = ...;
auto outer = stdv::cartesian product(stdv::iota(0, (N + T - 1) / T),
                                      stdv::iota(0, (M + T - 1) / T));
std::for each(ex::par unseq, begin(outer), end(outer),
  [=] (auto tile) {
    auto [x, y] = tile;
    std::tuple selectN{T * \times, std::min(T * (\times + 1), N)};
    std::tuple selectM{T * y, std::min(T * (y + 1), M)};
  });
```

```
std::mdspan A{input, N, M};
std::mdspan B{output, M, N};
std::size t T = ...;
auto outer = stdv::cartesian product(stdv::iota(0, (N + T - 1) / T),
                                      stdv::iota(0, (M + T - 1) / T));
std::for each(ex::par unseq, begin(outer), end(outer),
  [=] (auto tile) {
    auto [x, y] = tile;
    std::tuple selectN{T * \times, std::min(T * (\times + 1), N)};
    std::tuple selectM{T * y, std::min(T * (y + 1), M)};
    auto TA = std::submdspan(A, selectN, selectM);
    auto TB = std::submdspan(B, selectM, selectN);
  });
```

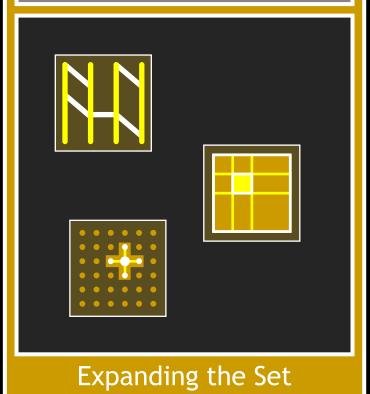
```
std::mdspan A{input, N, M};
std::mdspan B{output, M, N};
std::size t T = ...;
auto outer = stdv::cartesian product(stdv::iota(0, (N + T - 1) / T),
                                      stdv::iota(0, (M + T - 1) / T));
std::for each(ex::par unseq, begin(outer), end(outer),
  [=] (auto tile) {
    auto [x, y] = tile;
    std::tuple selectN{T * \times, std::min(T * (\times + 1), N)};
    std::tuple selectM{T * y, std::min(T * (y + 1), M)};
    auto TA = std::submdspan(A, selectN, selectM);
    auto TB = std::submdspan(B, selectM, selectN);
    auto inner = stdv::cartesian product(stdv::iota(0, TA.extent(0)),
                                          stdv::iota(0, TA.extent(1)));
  });
```

```
std::mdspan A{input, N, M};
std::mdspan B{output, M, N};
std::size t T = ...;
auto outer = stdv::cartesian product(stdv::iota(0, (N + T - 1) / T),
                                      stdv::iota(0, (M + T - 1) / T));
std::for each(ex::par unseq, begin(outer), end(outer),
  [=] (auto tile) {
    auto [x, y] = tile;
    std::tuple selectN{T * \times, std::min(T * (\times + 1), N)};
    std::tuple selectM{T * y, std::min(T * (y + 1), M)};
    auto TA = std::submdspan(A, selectN, selectM);
    auto TB = std::submdspan(B, selectM, selectN);
    auto inner = stdv::cartesian product(stdv::iota(0, TA.extent(0)),
                                          stdv::iota(0, TA.extent(1)));
   for (auto [i, j] : inner)
     TB[i, i] = TA[i, j];
  });
```

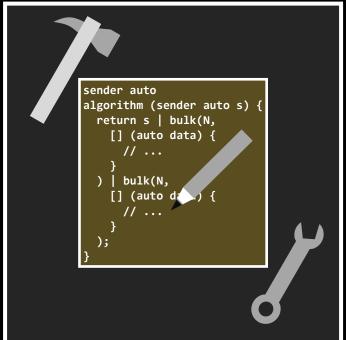
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Pillars of C Standard Parallelism

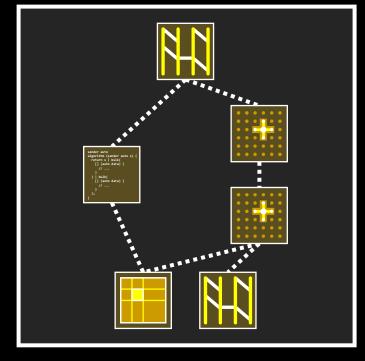
Common Algorithms that Dispatch to Vendor-Optimized Parallel Libraries



Tools to Write Your Own Parallel Algorithms that Run Anywhere



Mechanisms for Composing Parallel Invocations into Task Graphs



```
double *A = ..., *x = ..., *y = ...;
double *dA, *dx, *dy;
cudaMalloc(&dA, N * M * sizeof(double));
cudaMalloc(&dx, M * sizeof(double));
cudaMalloc(&dy, N * sizeof(double));
cublasSetMatrix(N, M, sizeof(double), &A, N, dA, N);
cublasSetVector(M, sizeof(double), &x, 1, dx, 1);
cublasSetVector(N, sizeof(double), &y, 1, dy, 1);
cublasHandle t handle;
cublasCreate(&handle);
double alpha = 3.0, beta = 2.0;
cublasSgemv(handle, CUBLAS OP N, N, M,
            &alpha, dA, N, dx, 1, &beta, dy, 1);
cublasGetVector(N, sizeof(double), &y, 1, dy, 1);
```

```
std::mdspan A{..., N, M};
std::mdspan x{..., M};
std::mdspan y{..., N};
// y = 3.0 A x + 2.0 y
std::matrix vector product(
  ex::par_unseq,
  <u>std::scaled(3.0, A), x,</u>
  std::scaled(2.0, y), y);
```

```
std::mdspan A{..., N, M};
std::mdspan x{..., M};
std::mdspan y{..., N};
// y = 3.0 A x + 2.0 y
std::matrix vector product(
  ex::par_unseq,
  <u>std::scaled(3.0, A), x,</u>
  std::scaled(2.0, y), y);
```

```
std::mdspan A{..., N, M};
std::mdspan x{..., M};
std::mdspan y{..., N};

// y = 3.0 A x + 2.0 y
std::matrix vector product(
   ex::par_unseq,
   std::scaled(3.0, A), x,
   std::scaled(2.0, y), y);
```

```
std::mdspan A{..., N, M};
std::mdspan x{..., M};
std::mdspan b{..., N};
// Solve A \times = b where A = U^T U
// Solve U^T c = b, using x to store c
std::triangular matrix vector solve(ex::par unseq,
                                      std::transposed(A),
                                      std::upper_triangle, std::explicit_diagonal,
                                      b, x);
// Solve U \times = c, overwriting \times with result
std::triangular matrix vector solve(ex::par unseq,
                                      Α,
                                      std::upper triangle, std::explicit diagonal,
                                      x);
```

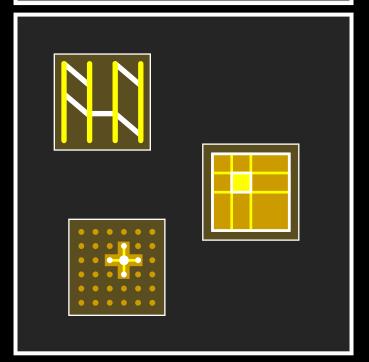
```
std::mdspan A{..., N, M};
std::mdspan x{..., M};
std::mdspan b{..., N};
// Solve A \times = b where A = U^T U
// Solve U^T c = b, using x to store c
std::triangular matrix vector solve(ex::par unseq,
                                      std::transposed(A),
                                      std::upper_triangle, std::explicit_diagonal,
                                      b, x);
// Solve U \times = c, overwriting \times with result
std::triangular matrix vector solve(ex::par unseq,
                                      Α,
                                      std::upper triangle, std::explicit diagonal,
                                      x);
```

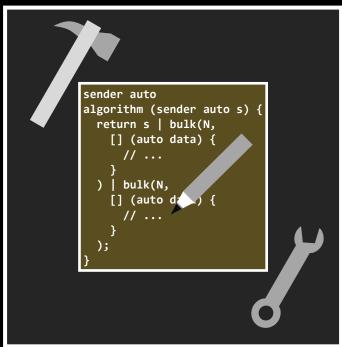
Pillars of C Standard Parallelism

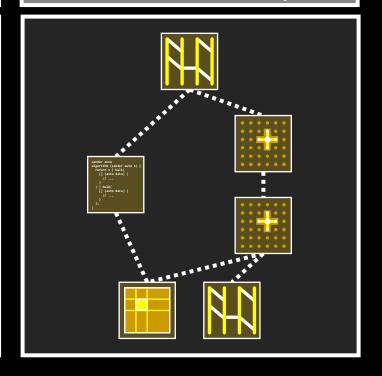
Common Algorithms that Dispatch to Vendor-Optimized Parallel Libraries



Mechanisms for Composing Parallel Invocations into Task Graphs







We Need On-Ramps

