

# CS2208a Assignment 3

Issued on: Monday, November 11, 2013

Due by: 11:55 pm on Monday, November 18, 2013

For this assignment, only an electronic submission (attachments) at owl.uwo.ca is required.

- Attachments must include:
  - **ONE pdf** file that has the three flowcharts, program documentations, and any related communications.
  - **Text** soft copy of the assembly programs that you wrote for each question (*one program attachment per question*), i.e., **THREE assembly program files** in total.
- So, in total, you will submit  $1 + 3 = 4$  files.
- **Failure to follow the above format may cost you 10% of the total assignment mark.**

Late assignments are strongly discouraged

- 10% will be deducted from a late assignment (up to 24 hours after the due date/time)
- After 24 hours from the due date/time, late assignments will receive a zero grade.

In this assignment, you will use the *micro Vision ARM simulator* by Keil, which is an MS Windows based software, to develop the required programs in this assignment. The simulator (version 4) has been installed on all PCs at MC-342 and MC-08 labs.

The simulator may also be installed on your PC. If you have not installed *Keil micro Vision 4 simulator* on your PC yet, you will need to download and install it from <https://www.keil.com/download/product/>

Note that during this month (October 2013), Keil has released a new version of its *MDK-ARM simulator* (*Keil micro Vision 5*). The *MDK-5* installation process has changed from a single monolithic installer to a set of installers.

So, you need to download *MDK-Core Version 5* from <https://www.keil.com/download/product/> as well as the *Legacy support for ARM7 & ARM9 devices* from <http://www2.keil.com/mdk5/legacy>

The author of our text book has provided a *Quick Guide to Using the Keil ARM Simulator*. If you wish, you can access it at <http://www.alanclements.org/usingkeilsimulator.html>

Programming style is very important in assembly language. It is expected to do the following in your programs:

- Using macros for the constants in your program to make it more readable.
- Applying neat spacing and code organization:
  - Assembly language source code should be arranged in three columns: *label*, *instruction*, and *comments*:
    - the *label* field starts at the beginning of the line,
    - the *instruction* field (opcodes + operands) starts at the next TAB stop, and
    - the *comments* are aligned in a column on the right.
- Using appropriate label names.
- Commenting each assembly line



## **Great Ways to Lose Marks**

- Not grouping your lines into logical ideas
- Not using any whitespace at all
- Not bothering to comment
- Commenting the code by just stating what you're doing, instead of why, e.g.,  
`MOV r0, #5 ;move 5 into r0`
- Not paying attention to the programming style (see the previous paragraph)
- Handing it in as soon as it assembles without testing and/or trying to break your code

## Strings

A string is an array representing a sequence of characters. To store a string of  $n$  characters in your program, you need to set aside  $n+1$  bytes of memory. This area of memory will contain the characters in the string, plus one extra special character—the *null* character—to mark the end of the string. The *null* character is a byte whose bits are all zeros (0x00). The actual string consists of any group of characters, which none of them can be the *null* character.

### QUESTION 1 (25 marks)

Draw a detailed flowchart and write an ARM assembly language program to concatenate two strings (**STRING1** and **STRING2**) and store the result in a null terminated **STRING3**. Assume that the length of **STRING1** + the length of **STRING2**  $\leq 255$ .

*You code should be highly optimized, i.e., use as few number of instructions as possible.*

You may want to define the strings as follow:

```
STRING1 DCB "This is a test string1"    ;String1
EoS      DCB 0x00                        ;end of string1
STRING2 DCB "This is a test string2"    ;String
EoS      DCB 0x00                        ;end of string2
STRING3 space 0xFF
```

### QUESTION 2 (35 marks)

Draw a detailed flowchart and write an ARM assembly language program to copy a *null* terminated **STRING1** to a *null* terminated **STRING2**, after removing any occurrences of the word “*the*” in **STRING1**. I.e., if **STRING1** is “**the** woman and **The** man said **the**” then **STRING2** would become “ woman and **The** man said “. However, if **STRING1** is “and **they** said another clo**the**” then **STRING2** would become “and **they** said another clo**the**” without any change.

*You code should be highly optimized, i.e., use as few number of instructions as possible.*

You may want to define the strings as follow:

```
STRING1 DCB "and the man said they must go"    ;String1
EoS      DCB 0x00                                ;end of string1
STRING2 space 0xFF
```

### QUESTION 3 (40 marks)

Draw a detailed flowchart and write an ARM assembly language function (subroutine) that takes a data value stored in register **r0** and returns a value in **r0** as well. The function returns  $y = a \times x^2 + b \times x + c$  where  $a$ ,  $b$ , and  $c$  are signed integer parameters built into the function (i.e., they are not passed to it) and are defined in the memory using **DCD** instruction. The subroutine also performs clipping, i.e., if the output is greater than a value  $d$ , it is constrained to  $d$  (clipped), where  $d$  is another parameter built into the function defined in the memory using **DCD** instruction. The input in **r0** is a signed integer positive binary value in the range 0 to 0xFF. Apart from **r0**, no other registers may be modified by this subroutine, i.e., if you want to use any register as a working register, you have to store its value in a safe place first prior changing it, and to restore this value before returning from the function.

After implementing the function, write an assembly program which stores a value in **r0** and calls your function. Once the control is returned back from the function, the program will double the returned value and store this doubled value in **r1**.

*You code should be highly optimized, i.e., use as few number of instructions as possible.*

**Example1:** if  $a = 5$ ,  $b = 6$ ,  $c = 7$ ,  $d = 90$ , and **r0** = 3,  
then the returned value in **r0** should be 70 and the value in **r1** will be 140.

**Example2:** if  $a = 5$ ,  $b = 6$ ,  $c = 7$ ,  $d = 50$ , and **r0** = 3,  
then the returned value in **r0** should be 50 and the value in **r1** will be 100.

**Example3:** if  $a = -5$ ,  $b = 6$ ,  $c = 7$ ,  $d = 10$ , and **r0** = 3,  
then the returned value in **r0** should be -20 and the value in **r1** will be -40.