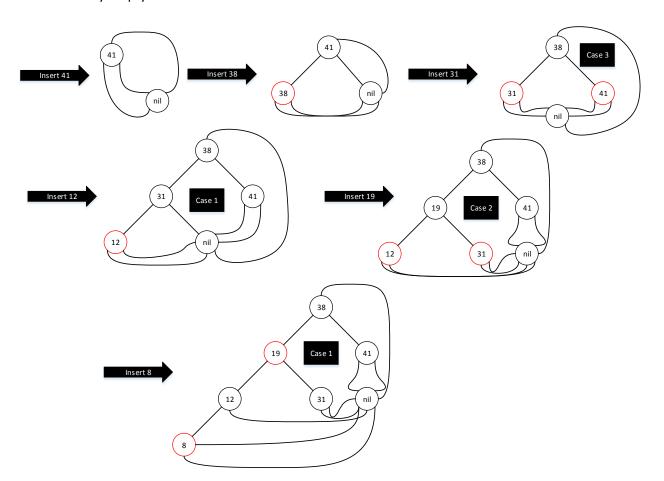
Assignment #2

Student #:

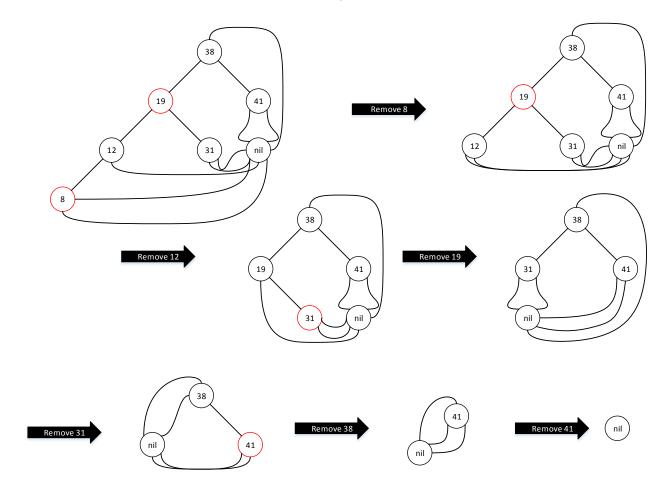
Name: Zaid Albirawi

UWO email: zalbiraw@uwo.ca

1. Show the red-black trees that result after successively inserting the keys 41, 38, 31, 12, 19, 8 into an initially empty red-black tree.



2. Show the red-black tree that result from the successive deletion of the keys in the order 8, 12, 19, 31, 38, 41 from the red-black tree resulted from question 1.



- **3.** An AVL tree is binary search tree that is height balanced: for each node x, the heights of the left and right sub-trees of x differ by a most 1. To implement an AVL tree, we maintain an extra attribute in each node: x.h is the height of node x. As for any other binary search tree T, we assume that T.root points to the root node.
 - a. Prove that an AVL tree with n nodes has height $O(\log n)$. (Hint: Prove that an AVL tree of height h has at least F_h nodes, where F_h is the h^{th} Fibonacci number.)

First, we recall that the heights of the right and left sub-trees of the AVL tree differ by 1, at most. We also recall the tree identity, $n(T)=n(T_1)+n(T_2)+1$, where T1 and T2 are T's right and left sub-trees and n is the number of nodes in each tree. Therefore, a tree with maximum height and a minimal number of nodes, must have a maximum height difference between its sub-trees, 1. Hence, by applying the tree identity to our findings, we conclude that $(T_h)=n(T_{h-1})+n(T_{h-2})+1$.

Proof by induction:

Base case:

$$n(0) = F_0 = 0$$

 $n(1) = F_1 = 1$

Induction case: $n(T_h) \ge F_h$

$$n(T_{h+1}) \ge F_{h+1}$$

 $n(T_h) + n(T_{h-1}) \ge F_h + F_{h-1}$

Since $(T_h) \ge n(T_{h-1})$ and $F_h \ge F_{h-1}$ then,

$$(T_h) \geq F_h$$

Proven by induction.

Now that we have proven that an AVL tree of height h has at least F_h nodes. We can prove that the tree has a height of $(\log n)$.

Since
$$n(T_h) \ge F_h$$
, and $F_h \ge 1.6^h$ then,

$$n(T_h) \ge F_h \ge 1.6^h$$

$$n(T_h) \ge 1.6^h$$

$$h = \log_{1.6} n(T_h)$$

Therefore, h is $\log n(T_h)$

4. Design an efficient data structure using (modified) red-black trees for an abstract data type that supports the following operations.

Insert(x): insert the key x into the data structure if it is not already there.

Delete(x): delete the key x from the data structure if it is there.

Find Smallest (k): find the kth smallest key in the data structure.

What are the time complexities of these operations?

The data structure that will be used to solve this problem is a modified red-black tree structure. This structure will differ from a normal red-black tree in its node class. The new node of the red-black tree will contain an extra integer attribute that will hold the number of nodes that each sub-tree has. Also, to keep track of the number of nodes in each sub-tree, we modify the insert and delete algorithms to use an algorithm called, tracker, that will take in the parent of the node that was inserted or removed, and preforms a sequence of recursive calls that will increment or decrement the number of nodes attribute for each sub-tree root. The algorithms for, insert, delete, insertBalance, deleteBalance, find and tracker, follow.

```
Algorithm: find (key)
In: A key object that is supposedly in the tree.
Out: The node to where the key is or supposed to be placed.
find(kev)
node ← root
while node != NIL do
        if key(node)>key then node \leftarrow left(node)
        else if key(node)<key then node \leftarrow right(node)
        else return node
return NIL
Algorithm: insert (key)
In: A key object that will be inserted into the tree.
Out: A boolean to wither the key object was inserted or not.
insert(key)
if root = NIL then
        root \leftarrow node(key, black)
        return true
else if find(key)= NIL then
        find(key) \leftarrow node(key, red)
        InsertBalance(node)
        tracker(P(node), insert)
        return true
```

else return false

```
Algorithm: delete (key)
In: A key object that is to be deleted from the tree.
Out: A boolean to whether the node containing the key has been deleted or not.
delete(key)
if find(key)=NIL then return false
else
        node \leftarrow find(key)
        if node = red & right(node)=NIL & left(node)=NIL then
                 tracker(P(node), delete)
                 node ← NIL
                 return true
        else if node = black & right(node)!=NIL & left(node)=NIL then
                 tracker(P(node), delete)
                 right(node) \leftarrow black
                 P(right(node)) \leftarrow P(node)
                 node \leftarrow NIL
                 return true
        else if node = black & right(node)=NIL & left(node)!=NIL then
                 tracker(P(node), delete)
                 left(node) \leftarrow black
                 P(left(node)) \leftarrow P(node)
                 node ← NIL
                 return true
        else if node = black & right(node)!=NIL & left(node)!=NIL then
                 tracker(P(node), delete)
                 \mathsf{node} \leftarrow \mathsf{NIL}
                 deleteBalance(node)
                 return true
```

```
Algorithm: insertBalance (node)
In: The node that was recently inserted into the tree
insertBalance(node)
if node = root then root ← black
else if P(node) = red then
        if P(P(node))=black & Sibling(P(node)) = red then
                 P(P(node)) \leftarrow red
                 P(node) \leftarrow black
                 Sibling(P(node)) \leftarrow black
                 InsertBalance (P(node))
        if left(P(node))=true & isRight(node)=true then leftRotation(node)
        else if right(P(node))=true & isLeft(node)=true then rightRotation(node)
        if P(P(node))=black & Sibling(P(node)) = black then
                 P(P(node)) \leftarrow red
                 P(node) \leftarrow black
                 if left(P(node))=true then rightRotation(P(node))
                 else leftRotation(P(node)) root ← black
return insertBalance (P(node))
Algorithm: deleteBalance(node)
In: A key object that is to be deleted from the tree.
deleteBalance(node)
sibling ← Sibling(node)
if node = root then root ← black
else if sibling=red then
        P(node) \leftarrow red
        P(sibling) \leftarrow black
        if isLeft(node)=true then leftRightRotation(node)
        else rightLeftRotation(node)
if sibling=black & left(sibling)=black & right(sibling)=black then
        sibling ← red
        if P(node)=red then P(node) ← black
        else if P(node)!=root then deleteBalance(P(node))
if sibling=black & left(sibling)=red & right(sibling)=black & isRight(sibling)=true then
        sibling ← red
        left(sibling) ← black
        rightLeftRotation(node)
else if sibling=black & left(sibling)=black & right(sibling)=black & isLeft(sibling)=true then
        sibling ← red
        right(sibling) \leftarrow black
        leftRightRotation(node)
if sibling=black & right(sibling)=red & isRight(sibling)=true then
        right(sibling) \leftarrow black
        leftRotation(sibling)
else if sibling=black & left(sibling)=red & isLeft(sibling)=true then
```

```
left(sibling) ← black
rightRotation(sibling)

return deleteBalance(P(node))

Algorithm: tracker (node, str)

In: the parent of the node that has been inserted or deleted, a string specifying if it's an insert or a delete operation.

tracker (node, str)

if String = delete then i ← -1

else i ← 1

if node = root then n (node) ← #nodes(node) + i

else

n (node) ← #nodes(node) + i

tracker(P(node), str)
```

Furthermore, now that each sub-tree has an attribute for the number of nodes it contains, we can introduce the find_smallest (k). This algorithm will determine where the kth smallest element is located in the tree based on the number of nodes in each sub-tree. Hence, since we are looking for the smallest element then we always start our search with the left sub-tree but if k > than the number of nodes in the left sub-tree then we go into the right sub-tree and decrement the value of k by the size of the left sub-tree, algorithm.

The time complexities for the operations insert(key) and delete(key) are $2\log n + c$ because they use the find(key) operation to find the location of the key. The find operation takes $(\log n)$ because of the height of the tree. Furthermore, $\log n + c$ is obtained from the use of the operations insertBalance() and deleteBalance() where every rotation and color change operation preformed in those functions take $O(\log n)$, O(1), respectively. Therefore, the insert and delete operations are $O(\log n)$. The find_smallest operation is also $O(\log n)$ because it iterates through the tree to find the kth smallest value in the tree. Therefore, worst case will be the height of the tree.

5. Describe an algorithm that, given n integers in the range 0 to k, preprocesses its input and then answers any query about how many of the n integers fall into rang [a...b] in O(1)time. Your algorithm should use (n+k) preprocessing time.

To preprocess the data given we use an algorithm named, preprocessCounter. This algorithm will count the number of elements in array A, by incrementing the index correspondent value of array B, B[A[x]], whenever the loop encounters that index. Furthermore, counting all the elements in array A, the algorithm then adds every value in B, B[x] to the previous value, B[x-1]. This will make each index value equal to its number of elements, and all the elements that are to it as well, algorithm

```
Algorithm: preprocessCounter(A, B, k)

In: An array with n integers, A. An empty array of size k, B. An integer k.

Out: An Array that contains the counted number of elements less than i. preprocessCounter(A, B, k)

for i \leftarrow 0 i to k

B[i] \leftarrow 0

for j \leftarrow 0 j to A.length-1

B[A[j]] \leftarrow B[A[j]] + 1

for l \leftarrow 1 i to k

B[i] \leftarrow B[i] + B[i-1]

return B
```

Secondly, the query algorithm will determine the number of elements that fall into range (a, b) based on the results obtained from the preprocessCounter algorithm. The algorithm checks to make sure that both a and b are within the array bounds and performs a O(1) to fetch the number of elements in the range (a, b) by B[b] - B[a], algorithm

```
Algorithm: query(a, b, A, B)

In: Integers a and b that set the range, an array containing the count of elements less than i, B.

Out: An integer that represents the number of integers that fall in the range (a, b) query(a, b)

B \leftarrow preprocessCounter(A, B, A.maxValue)

if a < 0 then a \leftarrow 0

if b > k then b \leftarrow k

return B[b] - B[a]
```

6. Given k sorted sequences each of which has n elements, design an algorithm to merge them into one sorted sequence. What is the time complexity of your algorithm?

Firstly, the algorithm will be divided into two parts, an algorithm named merge that will contain a queue of all the lists to be merged, and merger, which will merges two lists are sends it back to merge to enqueue it back into the queue, merge will keep looping until there is only one list left in the queue, algorithms

```
Algorithm: merger(A, B)
In: A and B are two sorted arrays.
Out: A sorted array of A and B's merged components
merger(A, B)
C \leftarrow array [2n]
i ←0
z \leftarrow 0
n \leftarrow A.size + B.size
for i \leftarrow 0 i to n
         if j < A.size & z < B.size then
                   if A[i] < B[z] then
                             C[i] \leftarrow A[j]
                            j \leftarrow j + 1
                   else
                             C[i] \leftarrow B[z]
                             z \leftarrow z + 1
          else if j < A.size then
                   C[i] \leftarrow A[j]
                   j \leftarrow j + 1
          else
                   C[i] \leftarrow B[z]
                   z \leftarrow z + 1
                   i \leftarrow i + 1
return C
Algorithm: merge(queue)
In: A and B are two sorted arrays.
Out: A sorted array of all the lists in the queue.
merge(queue)
while queue.size > 1 do
         A ← queue.dequeue
          B ← queue.dequeue
          queue.inqueue(merger(A, B))
return queue.dequeue
```

The merge algorithm is divided into two parts, the merge algorithm itself and its helper the merger algorithm. In the merge algorithm the inqueue and dequeue operation are of O(1). While the merger helper algorithm is of $O(kn\log k)$ where kn is equal to the total number of elements and log k is the height of the recursive binary tree that is created by merging different the lists. Therefore the time complexity of the algorithm is $O(kn\log k)$

7. Suppose we have an optimal prefix code on a set $C = \{0,1,...,n-1\}$ of the characters and we wish to transmit this code using as few bits as possible. Show how to represent any optimal prefix code on C using only $2n-1+n[\lg n]$ bits. (Hint: Use 2n-1 bits to specify the structure of the tree, as discovered by the walk of the tree.)

Since we know that a tree with n leaves also has n-1 internal nodes. Then 2n-1 bits are sufficient to store a full structure of a tree of n leaves; this structure is obtainable by running a tree traversal on the tree. Furthermore, the characters of C are going to be represented by tree traversal sequences, as in Huffman's coding, therefore, every character will need $\lg n$ bits to be store, the sequence that each character is represented in depends on the type of tree traversal we choose. Therefore, we need $n \lceil \lg n \rceil$ bits to store all the characters, which adds up to $2n-1+n \lceil \lg n \rceil$.

8. Prove that every node has rank at most $[\lg n]$.

Proof by induction.

A node of rank r is a node of at least size 2^r

Base case: $2^0 = 1$

A node of rank 0 is a node of size 1.

Inductive case: $2^r \le n$

The rank of any node is only increased when it is unionized with another node of the same rank, therefore, $2^{r+1} = 2^r + 2^r$

By inductive hypothesis, $2^r \le n$

$$2^{r} + 2^{r} \le n + n$$

$$2^{r}(1+1) \le 2n$$

$$2 * 2^{r} \le 2n$$

$$2^{r} \le n$$

$$r \le \log n$$

Proven by induction.

9. How many bits are necessary to store x.rank for each node x?

Since x. rank needs $\log n$ bits to be stored and the node also needs $\log n$ bits to be stored. Therefore, the amount of bits that are necessary to store x. rank are $\log \log n$.