



Bipedal robot Mini Pi



Search titles

User Manual for the Mini Pi 1
Product

- Disclaimer and Safety Ins...

Developer Onboarding 2
Course

- HT_Pi Teaching Mode Us...
- HT_Pi Stylized Motion Co...


Developer Advanced 3
Tutorial

- HT_Pi Reinforcement Le...
- HT-Pi Real Machine Depl...
- HT_Pi Policy Conversion ...

Developer Expansion 2
Tutorial

- HT_Pi Voice Control Quic...
- HT_Pi Keyboard Control f...

Bipedal robot Mini Pi / HT_Pi Keyboard Control for Walking User Manual

 Last Updated: 2025-11-28 15:05

1

of 3

Automatic Zoom

HT_Pi & Pi Plus Keyboard Control Walking User Manual

Please start the robot and enter the walking state according to the methc product manual before performing the following operations.

Method 1: Implementation via Command Line

Press `Ctrl+Alt+T` simultaneously on the keyboard to open the termir enter the following commands in the terminal:

1. Download the teleop_twist_keyboard package

代码块

```
1 sudo apt-get install ros-noetic-teleop-twist-keyboard
```

```
hightorque@lubancat:~$ sudo apt-get install ros-noetic-teleop-twist-keyboard
Reading package lists... Done
Building dependency tree
Reading state information... Done
ros-noetic-teleop-twist-keyboard is already the newest version (1.0.0-1).
0 upgraded, 0 newly installed, 0 to remove and 33 not upgraded.
```

2. Enter the following command in the terminal

代码块

```
1 rosrun teleop_twist_keyboard teleop_twist_keyboard.py
```