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Bipedal robot Mini Pi / HT_Pi Keyboard Control for Walking User Manual

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Automatic Zoom

HT_Pi & Pi Plus Keyboard Control Walking User Manual

Please start the robot and enter the walking state according to the method product manual before performing the following operations.

Method 1: Implementation via Command Line

Press **Ctrl+Alt+T** simultaneously on the keyboard to open the terminal and enter the following commands in the terminal:

1. Download the teleop_twist_keyboard package

代码块

```
1 sudo apt-get install ros-noetic-teleop-twist-keyboard
```

```
> hightorque@lubancat:~$ sudo apt-get install ros-noetic-teleop-twist-keyboard
Reading package lists... Done
Building dependency tree
Reading state information... Done
ros-noetic-teleop-twist-keyboard is already the newest version (1.0.0-1).
0 upgraded, 0 newly installed, 0 to remove and 33 not upgraded.
```

2. Enter the following command in the terminal

代码块

```
1 rosrun teleop_twist_keyboard teleop_twist_keyboard.py
```