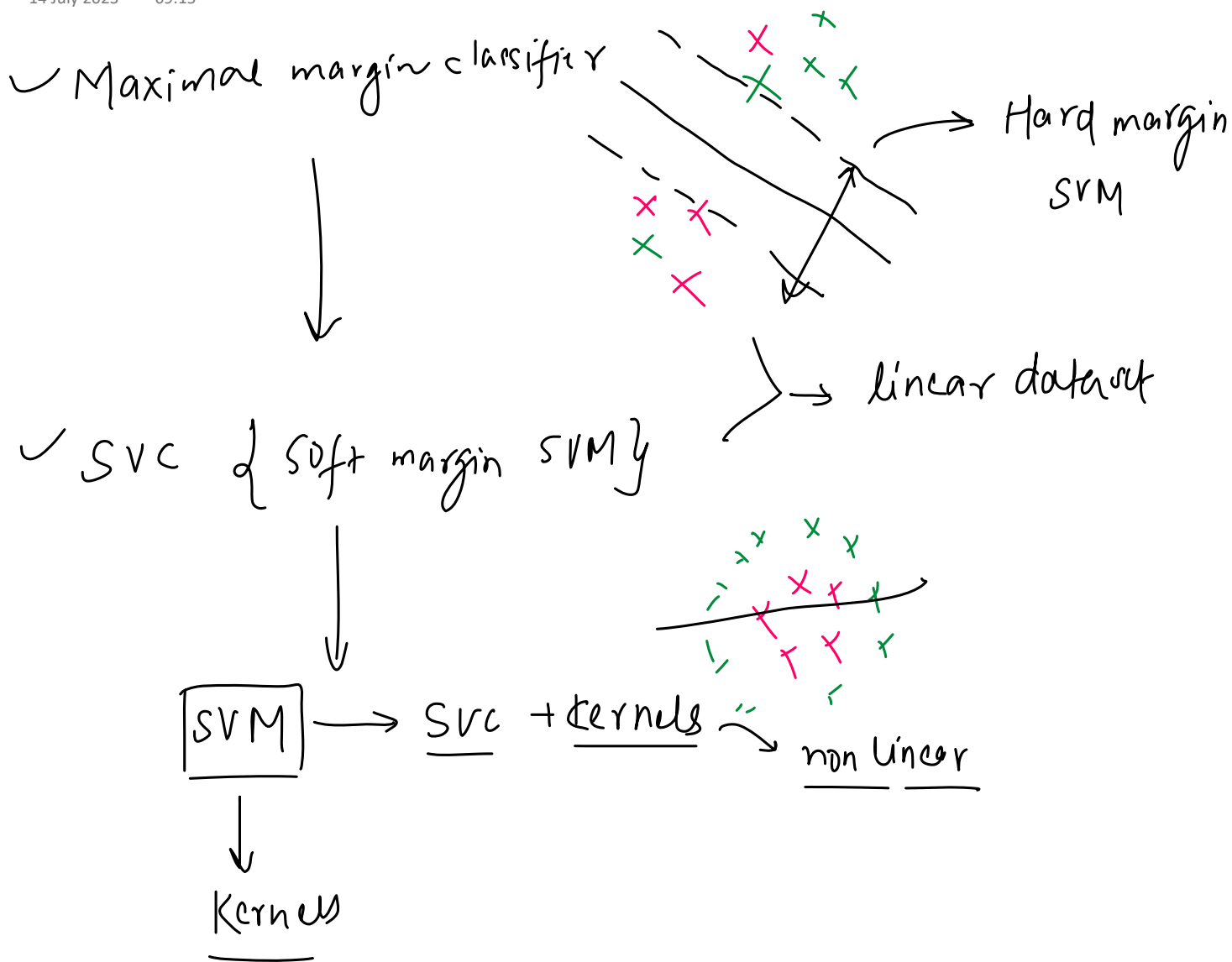


# Problem with SVC

14 July 2023 09:15



SVC

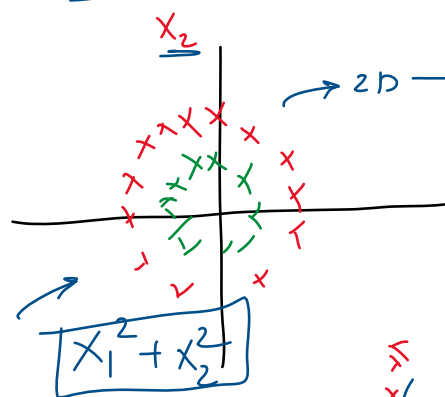
2D - line  
3D → hyper  
1D - point

age | side effect

72	1
32	0
26	0
5	1

functions  
math

$$x_1^2 + x_2^2$$



2D → 3D 1) input → higher dim  
kernels

2) linearly separable

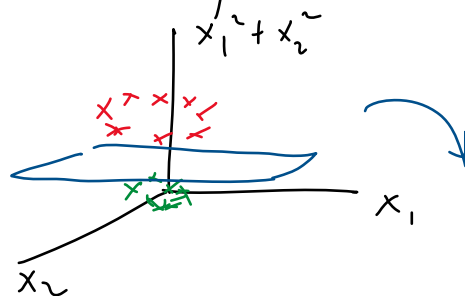
3) SVC

4) project down

classify

$$e^{-x^2} \quad e^{(x_1^2 + x_2^2)}$$

kernel →  $x^2$   $x^2$

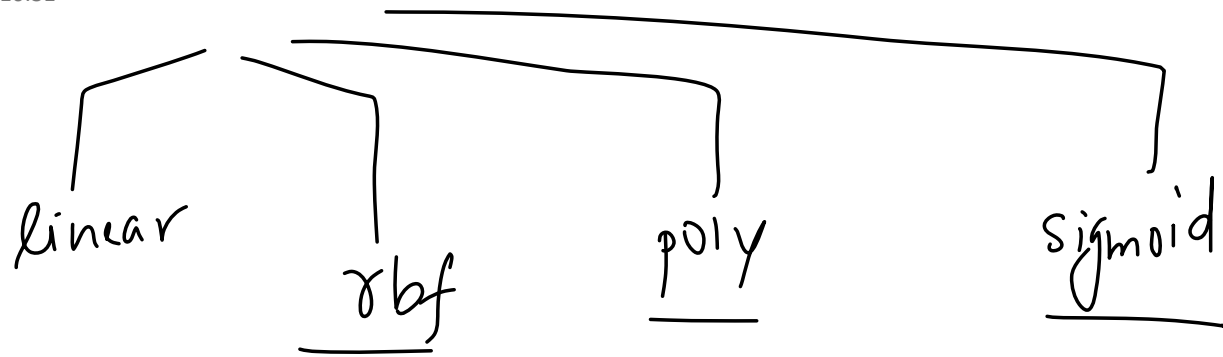


# Code

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# Types of Kernels

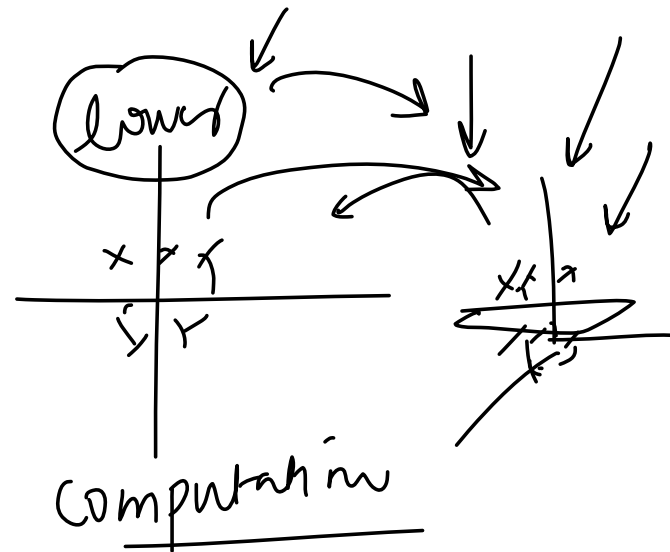
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Why is it called Trick?

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kernel trick ?  
↳ fast



The gradient of a function at a point is a vector that points in the direction of the steepest ascent of the function at that point. The magnitude (or length) of the gradient vector is equal to the rate of increase of the function in that direction.

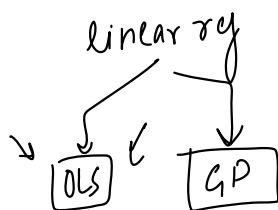
Contour lines (or level sets) of a function are curves that connect points where the function has the same value. For a 2D function, these are like the lines of constant altitude on a topographic map.

There are a few key relationships between gradients and contour lines:

1. The gradient at a point is perpendicular (or orthogonal) to the contour line passing through that point. This is because the contour line represents the direction of no change in the function value, while the gradient represents the direction of maximum change.
2. The gradient points in the direction where the function increases most rapidly. If you were to walk along the contour line (where the function value doesn't change), the direction you'd need to go to start climbing as steeply as possible is the direction of the gradient.
3. The magnitude of the gradient (how long the gradient vector is) indicates how steeply the function is increasing. If the contour lines are close together, that means the function is changing rapidly, so the gradient is large. If the contour lines are far apart, the function is changing slowly, so the gradient is small.

# optimization prob

constrained optimization problem



Logistic Reg

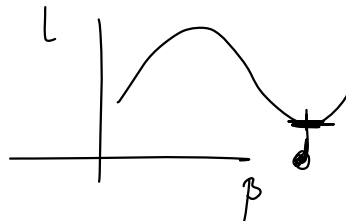
$$L = \underset{\beta}{\operatorname{argmin}} \frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}_i)^2$$

minimize

$$\frac{\partial L}{\partial \beta} = 0$$

min

constraint



$$\underset{A, B, C}{\operatorname{argmin}} \frac{\sqrt{A^2 + B^2}}{2} + C \frac{1}{n} \sum_{i=1}^n \xi_i$$

such that

$$y_i (Ax_{1i} + Bx_{2i} + C) \geq 1 - \xi_i$$

restriction

constrained optimization

argmax

$$x^2 y$$

such that

$$x^2 + y^2 = 1$$

constraint

$x=5 \quad y=7$

$x = \frac{1}{\sqrt{2}} \quad y = \frac{1}{\sqrt{2}}$

$(5)^2 \times 7 = 175 \in$

$\frac{1}{2} \times \frac{1}{\sqrt{2}} = \frac{1}{2\sqrt{2}}$

$$(5)^2 + (7)^2 = 1$$

$$\frac{1}{2} + \frac{1}{2} = 1$$

argmax

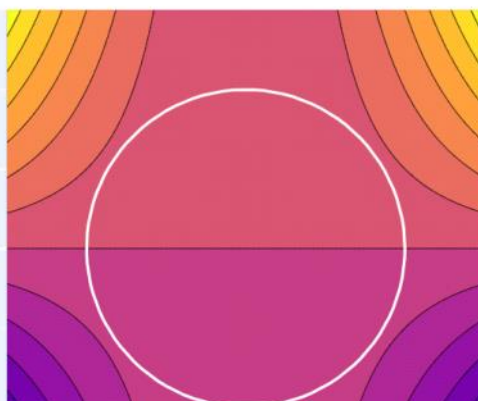
$$x^2 y$$

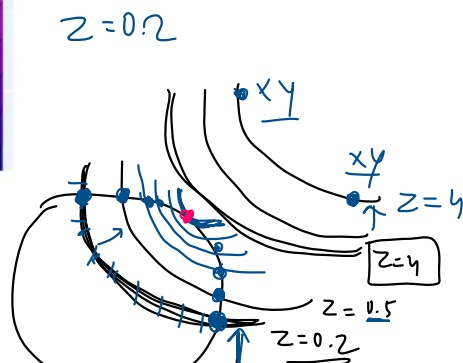
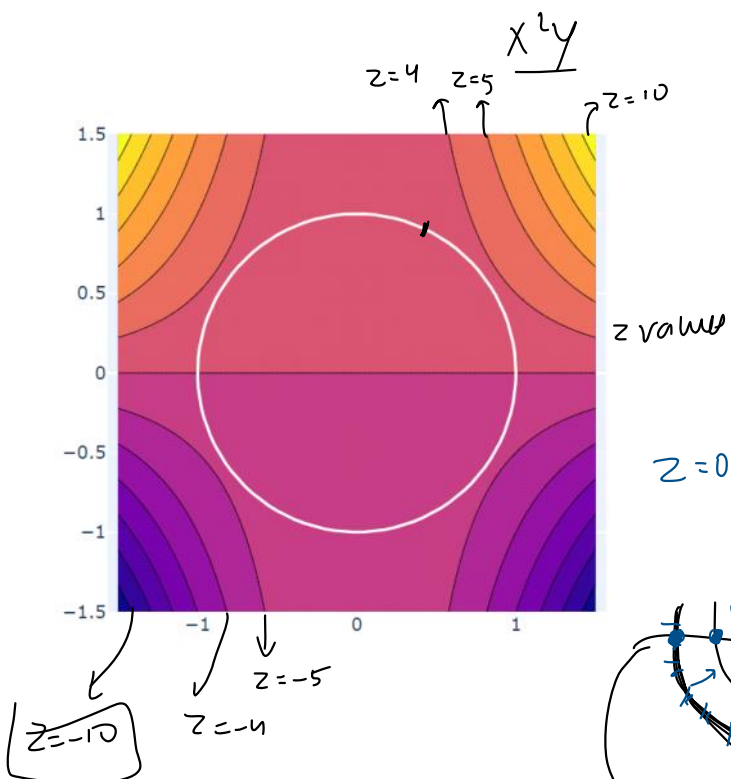
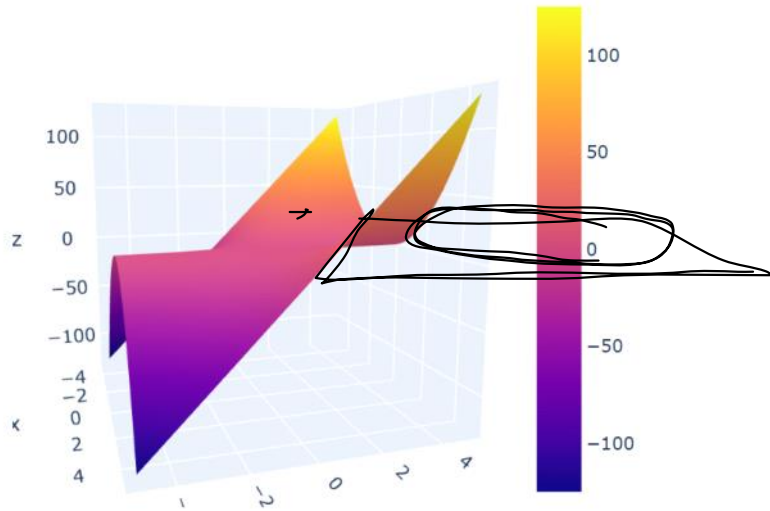
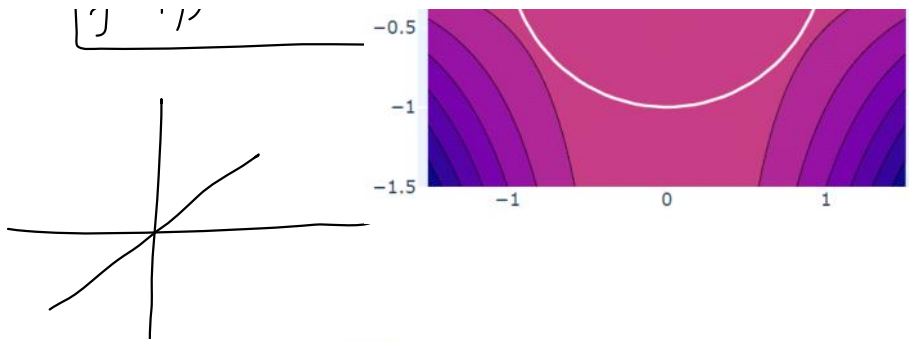
such that

$$x^2 + y^2 = 1.5$$

geometric intuition

$$f(x, y) = z = x$$

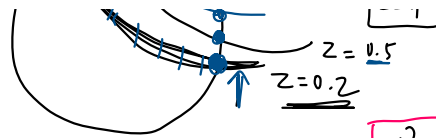




$x, y$   
acceptance



$\boxed{z = -10}$   $z = -4$



$\boxed{x, y}$   
acceptance  
true

$f(x, y) = x^2 y$

constraint:  $\boxed{x^2 + y^2 = 1}$

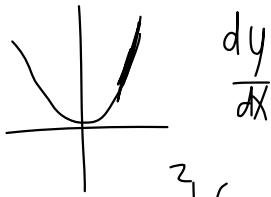
$z = 0.2 \rightarrow$  highest possible value of  $z(x, y)$

$(\sqrt{\frac{2}{3}}, -\frac{1}{\sqrt{3}})$   $(\frac{\sqrt{2}}{3}, \frac{1}{\sqrt{3}})$

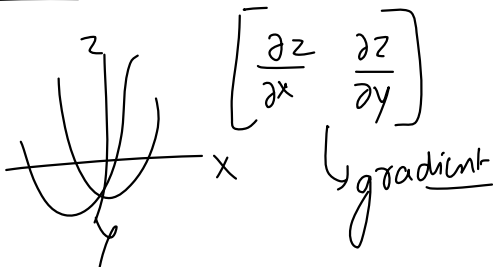
$x, y \rightarrow$  constant

$\boxed{x, y} \rightarrow \max z$

$xy \rightarrow z_{\max}$



$\frac{dy}{dx}$

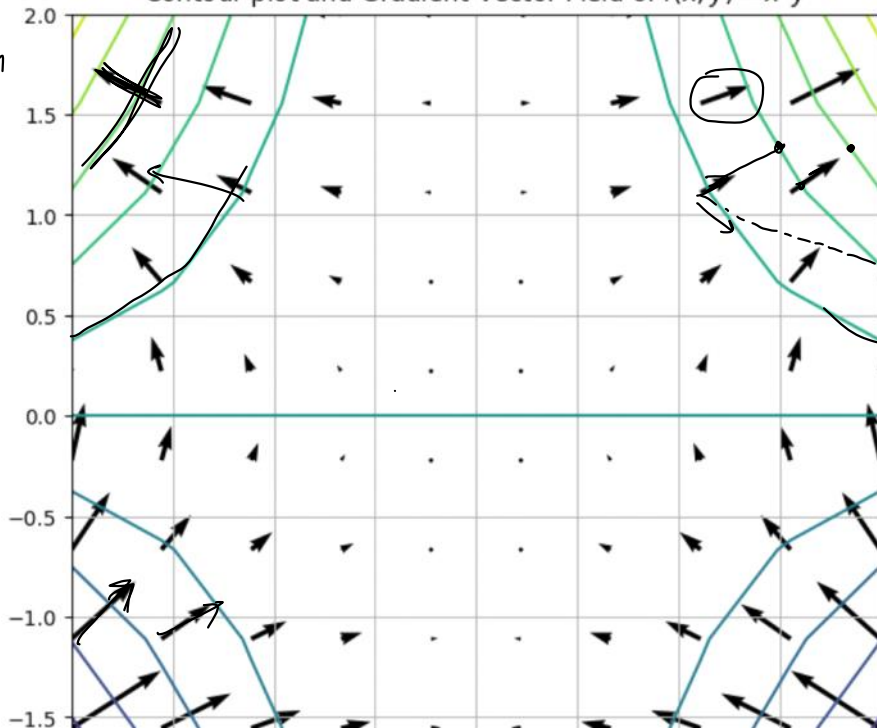


$\begin{bmatrix} \frac{\partial z}{\partial x} & \frac{\partial z}{\partial y} \end{bmatrix}$

gradient

direction of maximum ascent/change

perpendicular

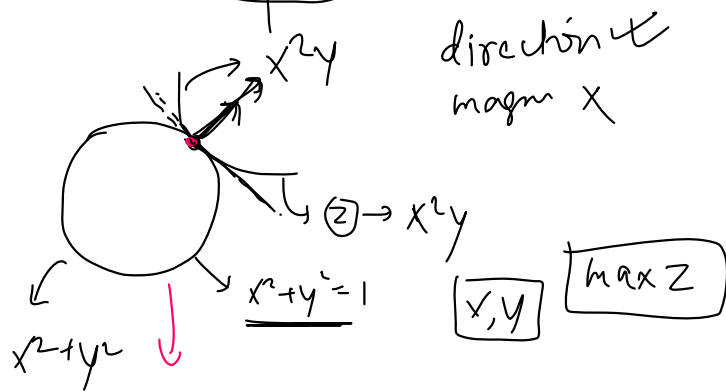
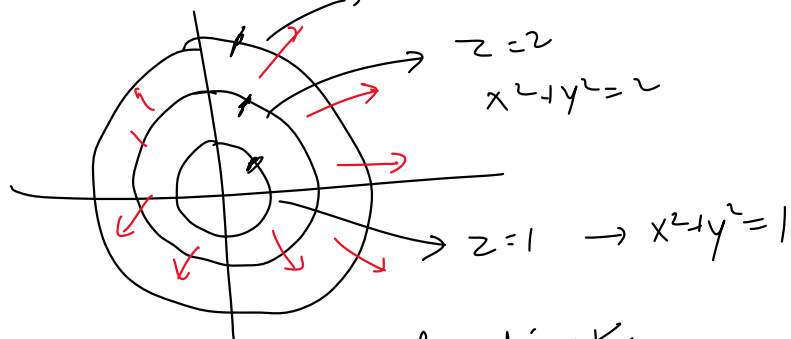
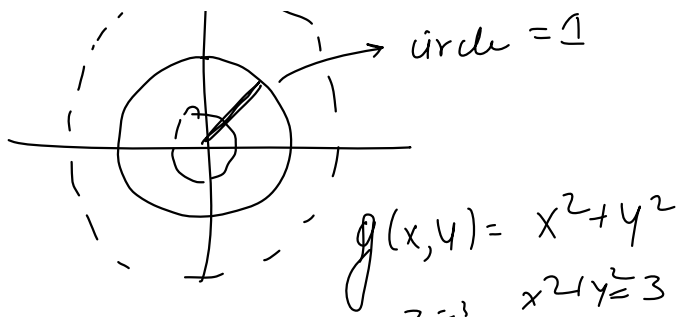


$z = 5$   
 $z = 4$

$x^2 + y^2 = \textcircled{1}$   $x^2 + y^2 = 2$   $x^2 + y^2 = 0.5$



circle = 1



$$\nabla f(x,y) = \lambda \nabla g(x,y)$$

$f(x,y) = x^2y$

$g(x,y) = x^2+y^2$

$$\nabla f(x,y) = \lambda \nabla g(x,y)$$

$\lambda$  scalar

$\lambda$  Lagrange's multiplier

$\nabla f(x,y)$

$\nabla g(x,y)$

$$\nabla f(x,y) = \begin{bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{bmatrix}$$

$\begin{bmatrix} 2xy \\ x^2 \end{bmatrix}$

$$\underline{x^2y} \rightarrow \frac{\partial f}{\partial x} = 2xy$$

$\frac{\partial f}{\partial y} = x^2$

$x^2+y^2 \rightarrow \frac{\partial g}{\partial x} = 2x$





$$Z = x^2 y \rightarrow \frac{2}{3} \frac{1}{\sqrt{3}} = \frac{2}{3\sqrt{3}}$$

$$x, y \rightarrow Z \text{ max}$$

$$\text{given } x^2 + y^2 = 1$$

Lagrangian multiplier (SVM)

$$\frac{2}{3} \frac{1}{\sqrt{3}} = \frac{2}{3\sqrt{3}}$$

$$\left(\sqrt{\frac{2}{3}}\right)^2 + \left(\frac{1}{\sqrt{3}}\right)^2$$

$$\frac{2}{3} + \frac{1}{3} = \frac{3}{3} = 1$$

$$\left[ \underset{x, y}{\operatorname{argmax}} x^2 y \quad \text{ST} \quad x^2 + y^2 = 1 \right] \rightarrow \boxed{\nabla f(x, y) = \lambda g(x, y)}$$

Optimization prob

$$L(x, y, \lambda) = \underset{x, y}{\operatorname{argmax}} \left[ \underbrace{f(x, y)}_{x^2 y} - \lambda \left( \underbrace{g(x, y)}_{x^2 + y^2} - 1 \right) \right]$$

$$\frac{\partial L}{\partial x} = 0$$

1<sup>st</sup>

$$\frac{\partial L}{\partial y} = 0$$

2<sup>nd</sup>

$$\frac{\partial L}{\partial \lambda} = 0$$

3<sup>rd</sup>

$$\frac{\partial f}{\partial x} - \lambda \frac{\partial g}{\partial x} = 0$$

$$\frac{\partial f}{\partial x} = \lambda \frac{\partial g}{\partial x}$$

$$2xy = \lambda 2x$$

$$g(x, y) - 1 = 0$$

$$g(x, y) = 1$$

$$x^2 + y^2 = 1$$

$$\frac{\partial f}{\partial y} - \lambda \frac{\partial g}{\partial y} = 0$$

$$x^2 - \lambda 2y = 0$$

$$x^2 = \lambda 2y$$

$$\sum_{i=1}^n (x_i - y_i)$$

$$(x_1 - y_1) + (x_2 - y_2)$$

$$\left[ \underset{x, y}{\operatorname{argmax}} x^2 y \quad \text{ST} \quad x^2 + y^2 = 1 \right] \xrightarrow{\text{worst opt}} \text{computer}$$

$L$

$\downarrow$  optim-

$L(x, y, \lambda) = \arg \max_{x, y, \lambda} x^2 y - \lambda (x^2 + y^2 - 1)$

$\rightarrow$  large multi  $\rightarrow$  SVM dual problem