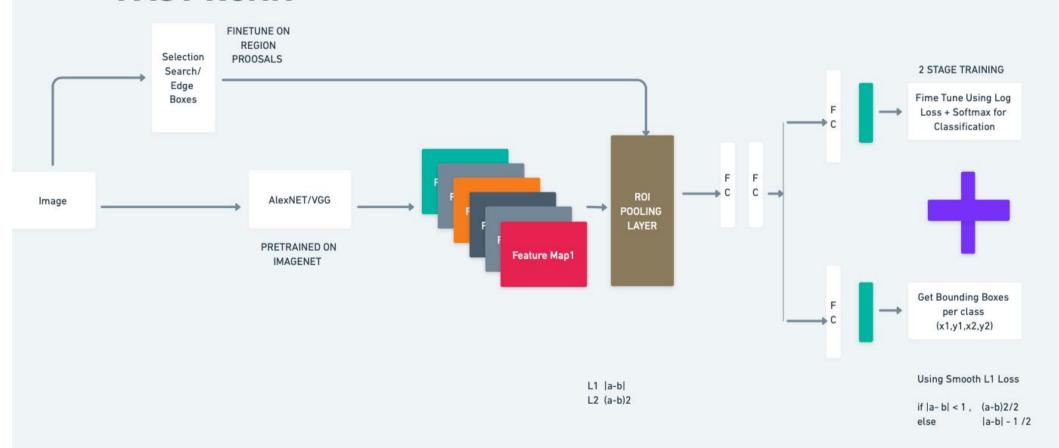
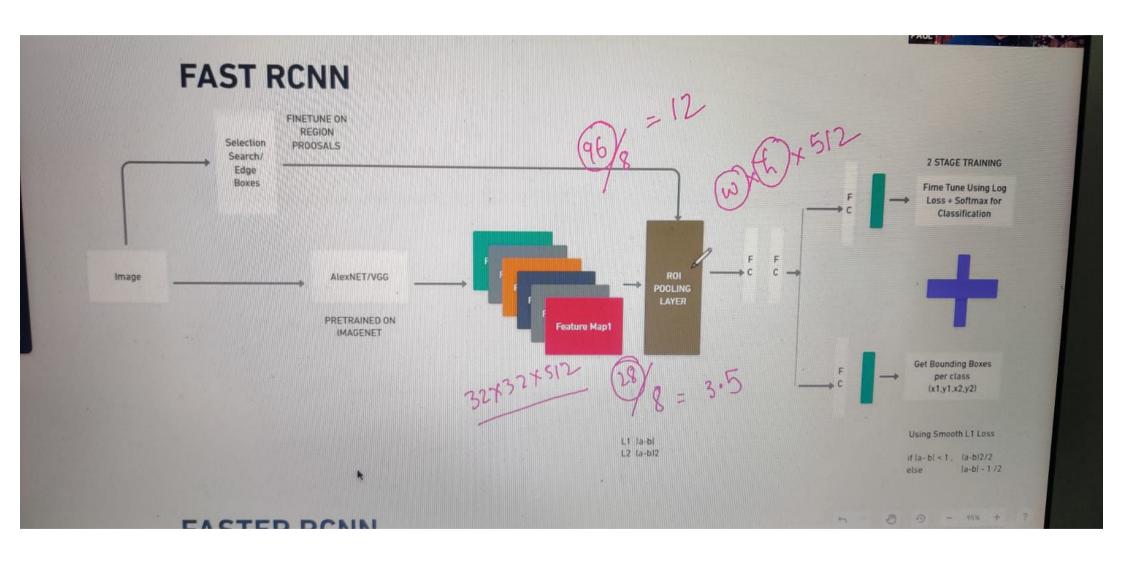
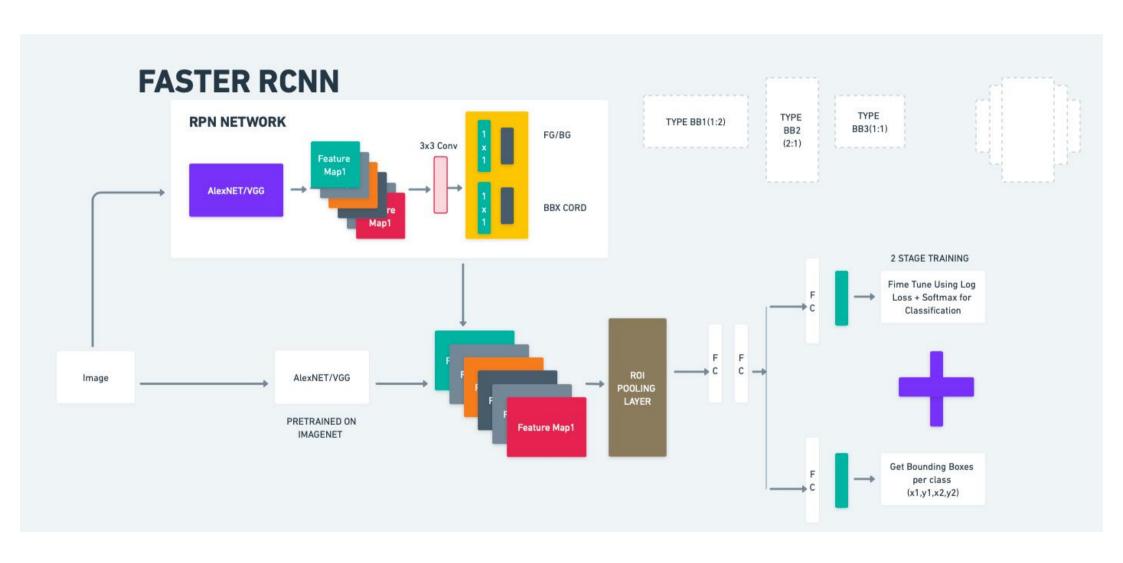


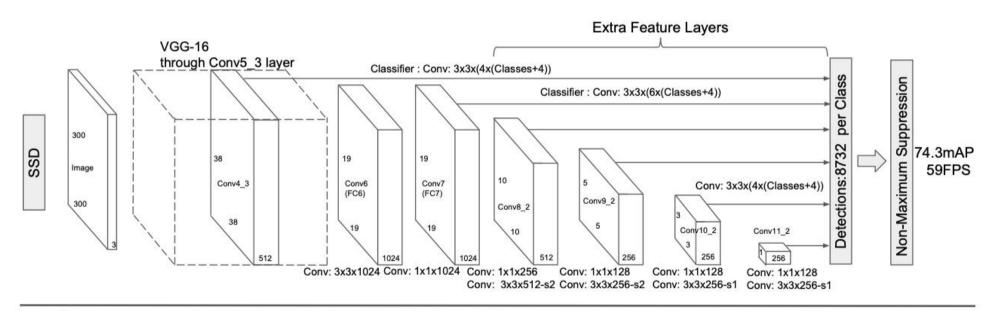
FAST RCNN







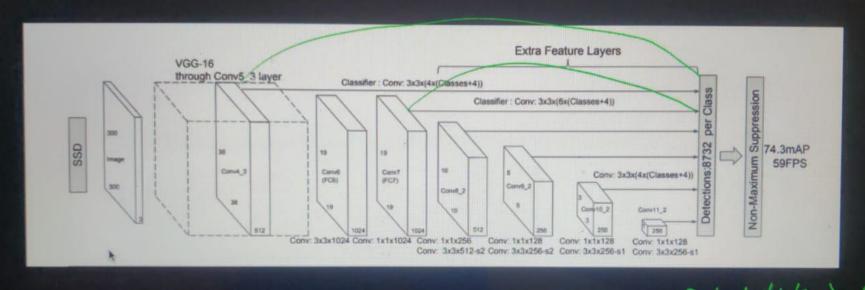
Liu et al.



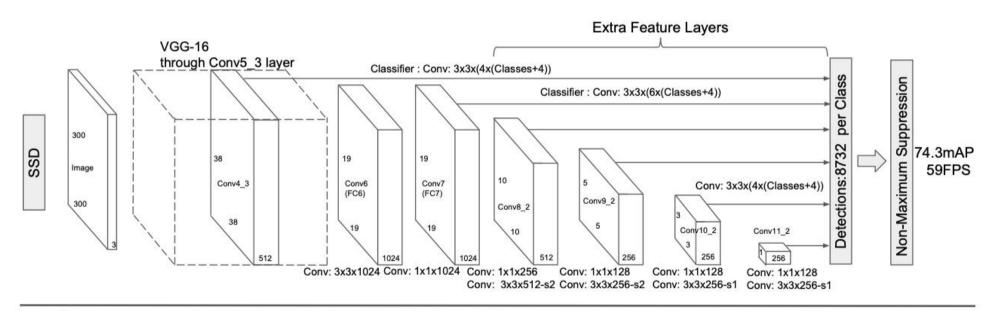
5



PAUL

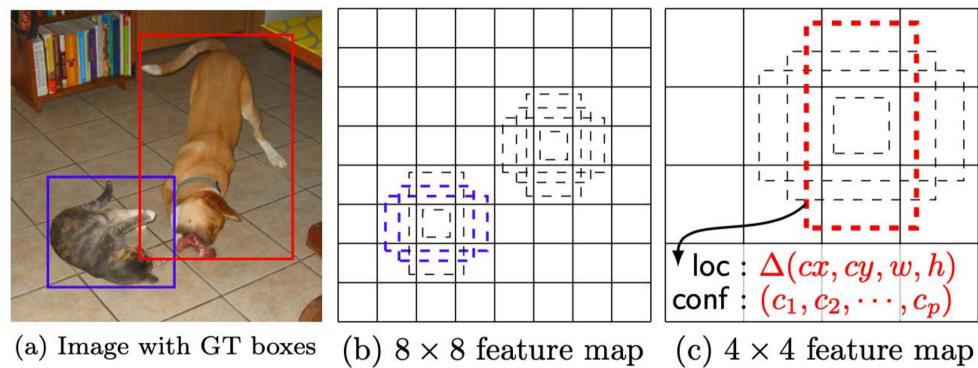


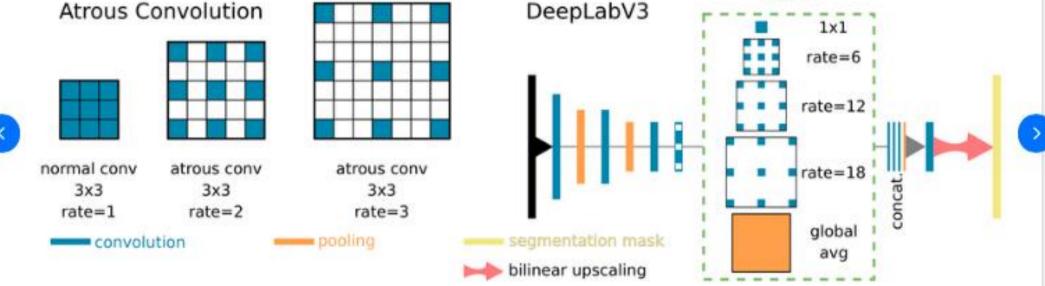
Liu et al.



5

SSD: Single Shot MultiBox Detector





ASPP

Conceptual overview of atrous convolution (left) and the Atrous Spatial Pyramid Pooling module (ASPP) within the DeepLabV3 [59] architecture (right). In atrous convolution, "holes" are inserted into the kernel. They provide a larger receptive field and maintain resolution at the same time. The ASPP module combines atrous convolutions of different rates and global image context via global average pooling in order to exploit feature maps on different scales efficiently [56,58,59].

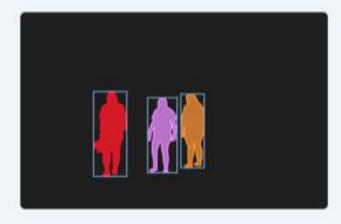
Semantic Segmentation vs. Instance Segmentation vs. Panoptic Segmentation



(a) Image



(b) Semantic Segmentation



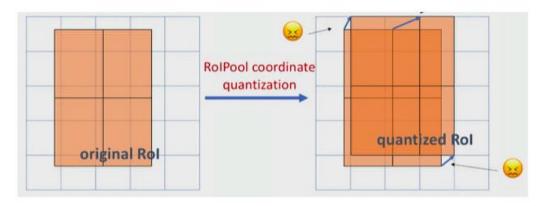
(c) Instance Segmentation



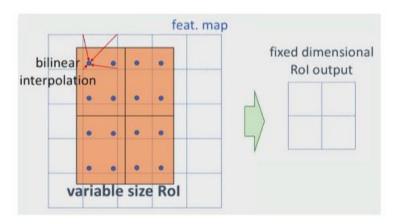
(d) Panoptic Segmentation

RoiAlign

As discussed above, RolPool layer extracts small feature maps from each Rol. The problem with RolPool is quantization. If the Rol doesn't perfectly align with the grid in feature map as shown, the quantization breaks pixel-to-pixel alignment. It isn't much of a problem in object detection, but in case of predicting masks, which require finer spatial localization, it matters.

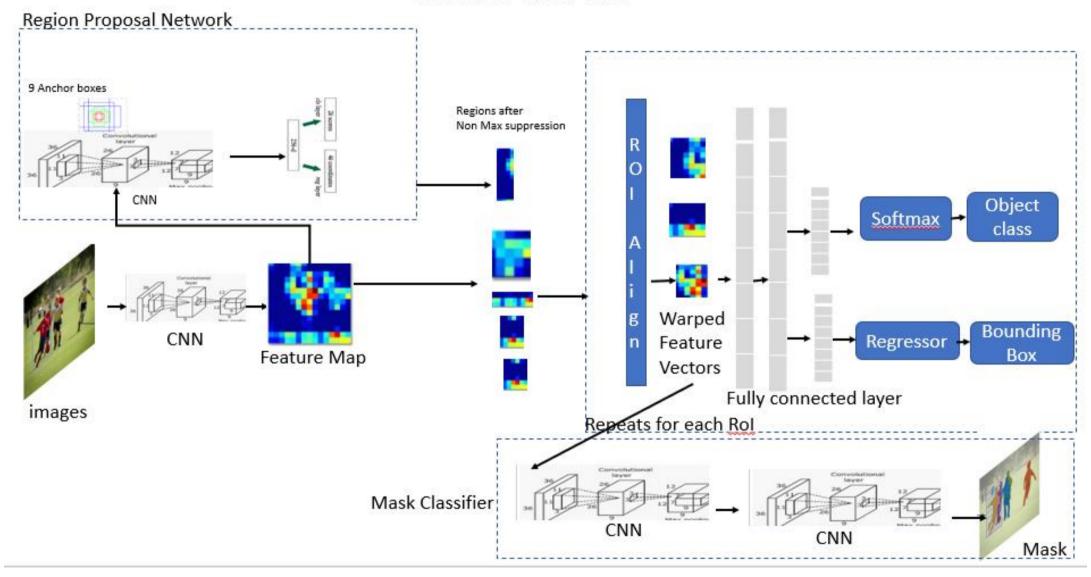


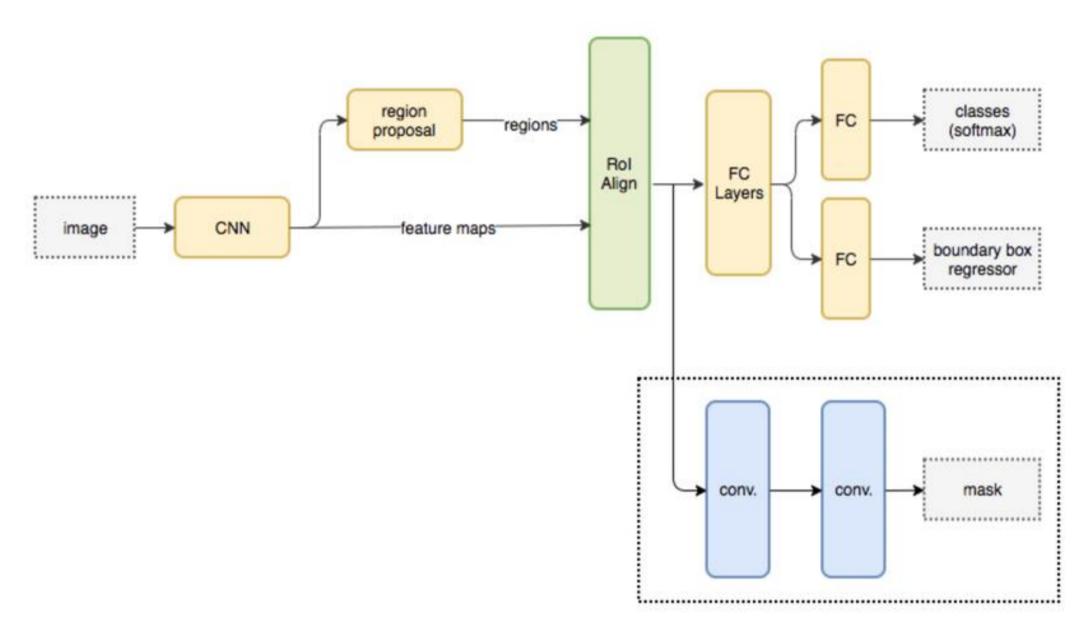
RolAlign is an improvement over the RolPool operation. What RolAlign does is to smoothly transform features from the Rols (which has different aspect sizes) into fixed size feature vectors without using *quantization*. It uses bilinear interpolation to do. A grid of sampling points are used within each bin of Rol, which are used to interpolate the features at its nearest neighbors as shown.



For example, in the above figure, you can't apply the max-pooling directly due to the misalignment of Rol with the feature map grids, thus in case of RolAlign, four points are sampled in each bin using bilinear interpolation from its nearest neighbors. Finally, the max value from these points is chosen to get the required 2x2 feature map.

Mask RCNN

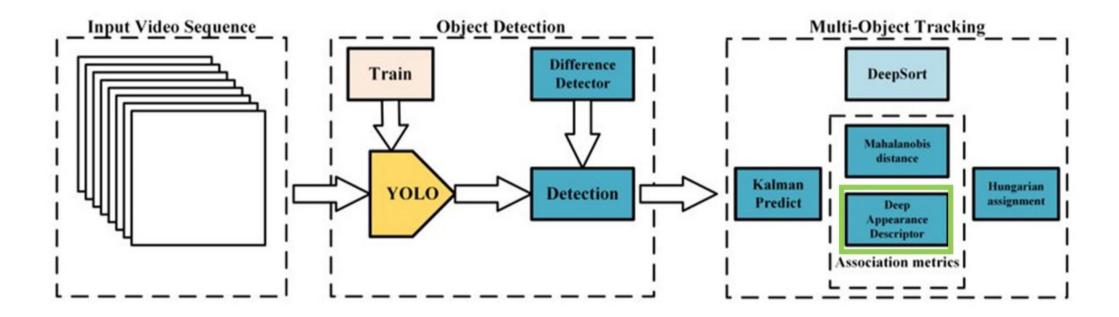


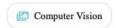


Mask

DeepSORT

Where is the Deep Learning in all of this?





Face Recognition

Edit

440 papers with code • 23 benchmarks • 79 datasets

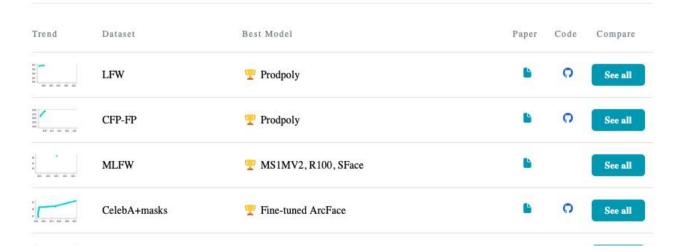
Facial recognition is the task of making a positive identification of a face in a photo or video image against a pre-existing database of faces. It begins with detection - distinguishing human faces from other objects in the image - and then works on identification of those detected faces.

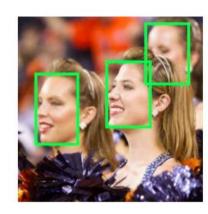
The state of the art tables for this task are contained mainly in the consistent parts of the task: the face verification and face identification tasks.

(Image credit: Face Verification)

Benchmarks Add a Result

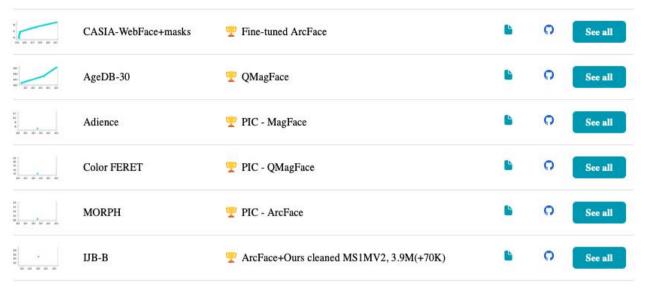
These leaderboards are used to track progress in Face Recognition





Content

- Introduction
- △ Benchmarks
- Datasets
- & Subtasks
- Libraries
- Papers
- Most implemented
- Social
- Latest
- No code



Show all 23 benchmarks

Libraries (1)

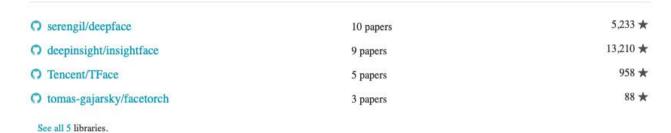
Use these libraries to find Face Recognition models and implementations

Serengil/deepface	10 papers	5,233 ★
• deepinsight/insightface	9 papers	13,210 ★
• Tencent/TFace	5 papers	958 ★
ntomas-gajarsky/facetorch	3 papers	88 🛨

See all 5 libraries.

Libraries ①

Use these libraries to find Face Recognition models and implementations



Datasets



Subtasks

