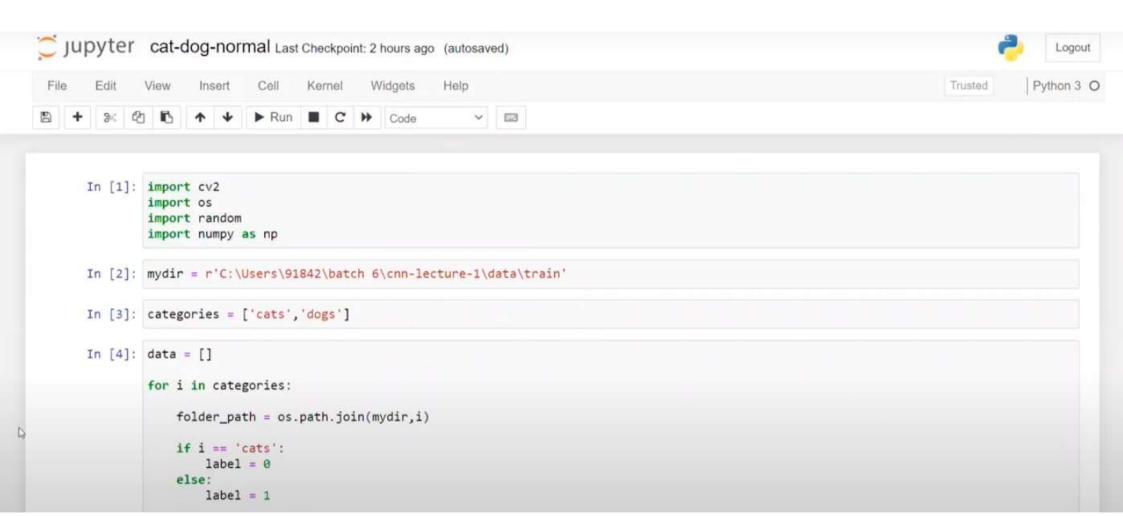


```
In [7]: img = image.img_to_array(img)
 In [8]: type(img)
 Out[8]: numpy.ndarray
In [38]: img.shape
Out[38]: (200, 200, 3)
In [39]: input_batch = img.reshape(1,200,200,3)
In [40]: i=0
         for output in datagen.flow(input_batch,batch_size=1,save_to_dir='aug'):
             i = i + 1
             if i == 10:
                 break
```



```
In [3]: categories = ['cats','dogs']

In [4]: data = []

for i in categories:
    folder_path = os.path.join(mydir,i)

    if i == 'cats':
        label = 0
    else:
        label = 1

    for j in os.listdir(folder_path):

        img_path = os.path.join(folder_path,j)
        img = cv2.imread(img_path)
        img = cv2.resize(img,(150,150))
        data.append([img,label])
```

```
In [7]: y = np.array(y)

In [8]: X = np.array(X)

In [9]: X.shape
Out[9]: (2000, 150, 150, 3)

In [10]: X = X/255
```

```
from keras import Sequential
from keras.layers import Conv2D,MaxPooling2D,Dense,Flatten,Activation,Dropout

Using TensorFlow backend.

In [12]: model = Sequential()
    model.add(Conv2D(32, (3, 3), input_shape=(150, 150,3)))
    model.add(Activation('relu'))
    model.add(MaxPooling2D(pool_size=(2, 2)))

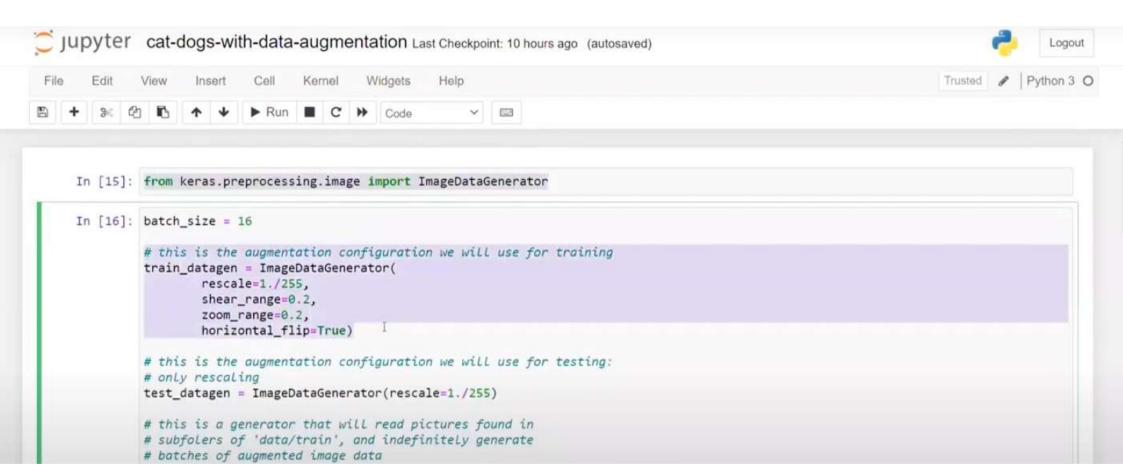
model.add(Conv2D(32, (3, 3)))
    model.add(Activation('relu'))
    model.add(MaxPooling2D(pool_size=(2, 2)))

model.add(Conv2D(64, (3, 3)))
    model.add(Activation('relu'))
    model.add(Activation('relu'))
    model.add(MaxPooling2D(pool_size=(2, 2)))
```

```
In [13]: model.add(Flatten()) # this converts our 3D feature maps to 1D feature vectors
     model.add(Dense(64))
     model.add(Activation('relu'))
     model.add(Dropout(0.5))
     model.add(Dense(1))
     model.add(Activation('sigmoid'))
     model.compile(loss='binary_crossentropy',
              optimizer='rmsprop',
              metrics=['accuracy'])
In [14]: model.fit(X,y,epochs=5,validation_split=0.1)
     Train on 1800 samples, validate on 200 samples
      Epoch 1/5
     0.5050
      Epoch 2/5
```

```
In [14]: model.fit(X,y,epochs=5,validation split=0.1)
  Train on 1800 samples, validate on 200 samples
  Epoch 1/5
  0.5050
  Epoch 2/5
  0.5350
  Epoch 3/5
  0.6600
  Epoch 4/5
  0.7150
  Epoch 5/5
  0.5750
Out[14]: <keras.callbacks.callbacks.History at 0x27bd62d2088>
```

In [ ]:



```
# this is a generator that will read pictures found in
# subfolers of 'data/train', and indefinitely generate
# batches of augmented image data
train_generator = train_datagen.flow_from_directory(
        'data/train', # this is the target directory
       target_size=(150, 150), # all images will be resized to 150x150
        batch_size=batch_size,
        class_mode='binary') # since we use binary_crossentropy loss, we need binary labels
# this is a similar generator, for validation data
validation generator = test datagen.flow from directory(
        'data/valid'.
       target_size=(150, 150),
       batch_size=batch_size,
        class_mode='binary')
Found 2000 images belonging to 2 classes.
Found 1000 images belonging to 2 classes.
```

```
In [17]: from keras.models import Sequential
    from keras.layers import Conv2D, MaxPooling2D
    from keras.layers import Activation, Dropout, Flatten, Dense

model = Sequential()
    model.add(Conv2D(32, (3, 3), input_shape=(150, 150,3)))
    model.add(Activation('relu'))
    model.add(MaxPooling2D(pool_size=(2, 2)))

model.add(Conv2D(32, (3, 3)))
    model.add(Activation('relu'))
    model.add(MaxPooling2D(pool_size=(2, 2)))

model.add(Conv2D(64, (3, 3)))
    model.add(Activation('relu'))
    model.add(MaxPooling2D(pool_size=(2, 2)))
```

Found 1000 images belonging to 2 classes.

```
In [17]: from keras.models import Sequential
         from keras.layers import Conv2D, MaxPooling2D
         from keras.layers import Activation, Dropout, Flatten, Dense
         model = Sequential()
         model.add(Conv2D(32, (3, 3), input_shape=(150, 150,3)))
         model.add(Activation('relu'))
         model.add(MaxPooling2D(pool_size=(2, 2)))
         model.add(Conv2D(32, (3, 3)))
         model.add(Activation('relu'))
         model.add(MaxPooling2D(pool_size=(2, 2)))
         model.add(Conv2D(64, (3, 3)))
         model.add(Activation('relu'))
         model.add(MaxPooling2D(pool_size=(2, 2)))
In [18]: model.add(Flatten()) # this converts our 3D feature maps to 1D feature vectors
         model.add(Dense(64))
         model.add(Activation('relu'))
```

```
model.add(Dense(1))
    model.add(Activation('sigmoid'))
    model.compile(loss='binary_crossentropy',
           optimizer='rmsprop',
           metrics=['accuracy'])
In [19]: model.fit_generator(
        train_generator,
        steps_per_epoch=2000 // batch_size,
        epochs=25.
        validation_data=validation_generator,
        validation_steps=800 // batch_size)
    Epoch 1/25
    0.5088
    Epoch 2/25
    0.6338
    Epoch 3/25
    9.5779
```

model.add(Activation( resu ))
model.add(Dropout(0.5))

```
Epoch 1/25
0.5088
Epoch 2/25
0.6338
Epoch 3/25
0.5770
Epoch 4/25
0.7172
Epoch 5/25
0.6925
Frack 6/2F
```

```
Epoch 20/25
 0.7400
 Epoch 21/25
 0.7449
 Epoch 22/25
 0.7576
 Epoch 23/25
 0.7348
 Epoch 24/25
 0.7399
 Epoch 25/25
 0.7487
Out[19]: <keras.callbacks.callbacks.History at 0x29276314ec8>
```

Tn [ 1.