

# Competitions

Dataset	Images	Classes
<u>Pascal VOC 2012</u> ✓	11,530 images with 27,450 ROI annotated objects	20
<u>COCO</u> -	330,000 images with 1.5 million object instances	80
<u>ImageNet</u> }	<u>150,000 images</u>	<u>1000/200</u>



# ImageNet Samples



# Pascal VOC Samples

**Dining tables - *all images contain at least one dining table.***





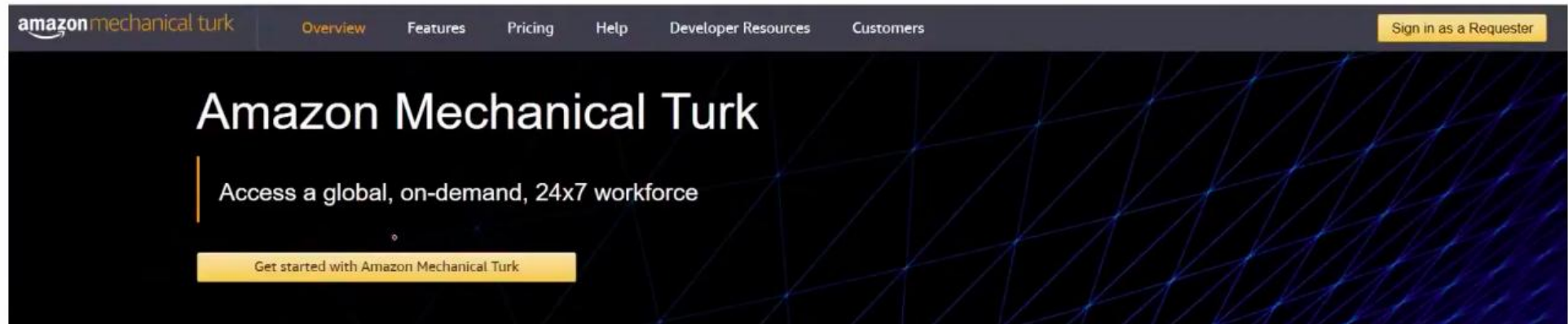
COCO Explorer <http://cocodataset.org/#explore> ✓

search



# Amazon Mechanical Turk

Ev-ODN



Amazon Mechanical Turk (MTurk) is a crowdsourcing marketplace that makes it easier for individuals and businesses to outsource their processes and jobs to a distributed workforce who can perform these tasks virtually. This could include anything from conducting simple data validation and research to more subjective tasks like survey participation, content moderation, and more. MTurk enables companies to harness the collective intelligence, skills, and insights from a global workforce to streamline business processes, augment data collection and analysis, and accelerate machine learning development.

While technology continues to improve, there are still many things that human beings can do much more effectively than computers, such as moderating content, performing data deduplication, or research. Traditionally, tasks like this have been accomplished by hiring a large temporary workforce, which is time consuming, expensive and difficult to scale, or have gone undone. Crowdsourcing is a good way to break down a manual, time-consuming project into smaller, more manageable tasks to be completed by distributed workers over the Internet (also known as 'microtasks').

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# Annotation Tools

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# How to find out TP and FP

TP FP



# How to find out TP and FP

TP FP

→ Person

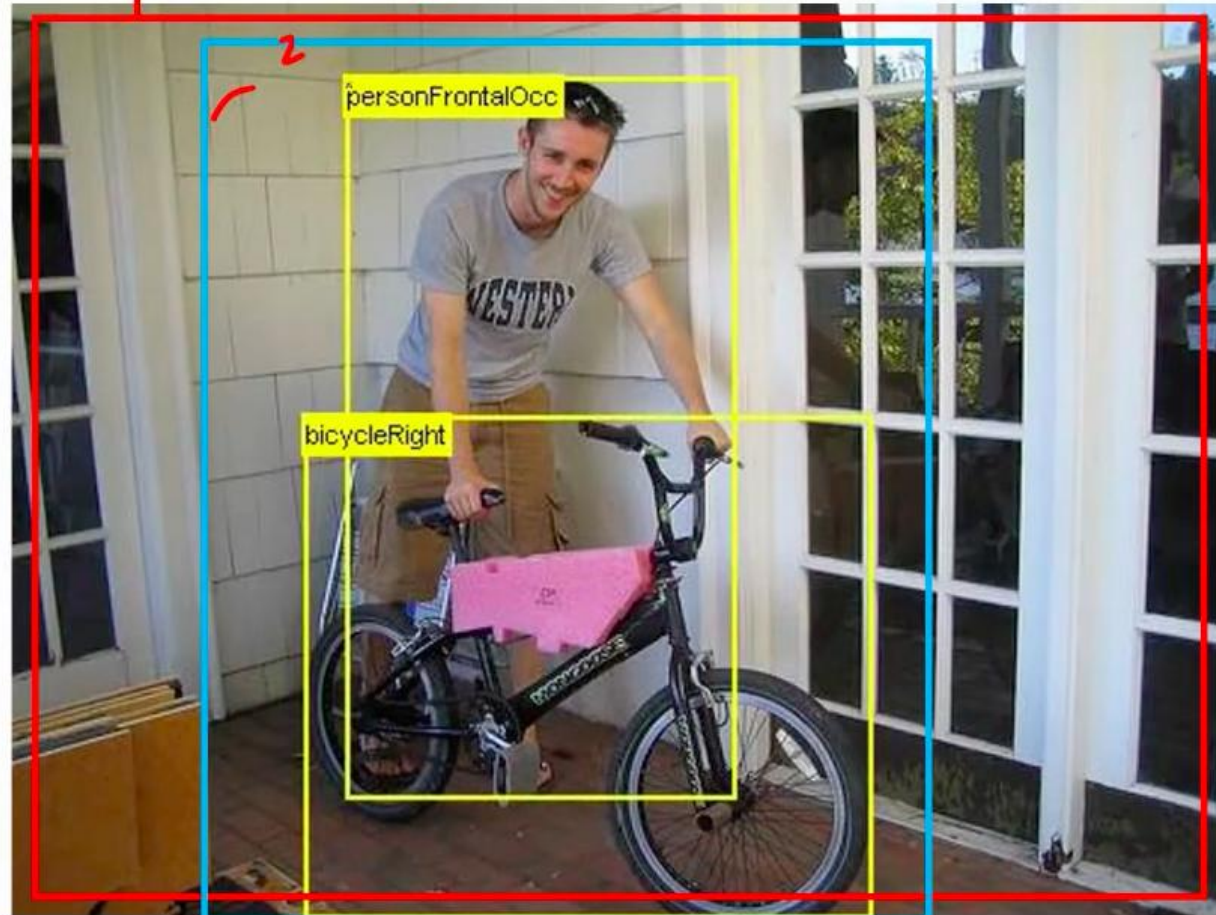




# How to find out TP and FP

TP FP

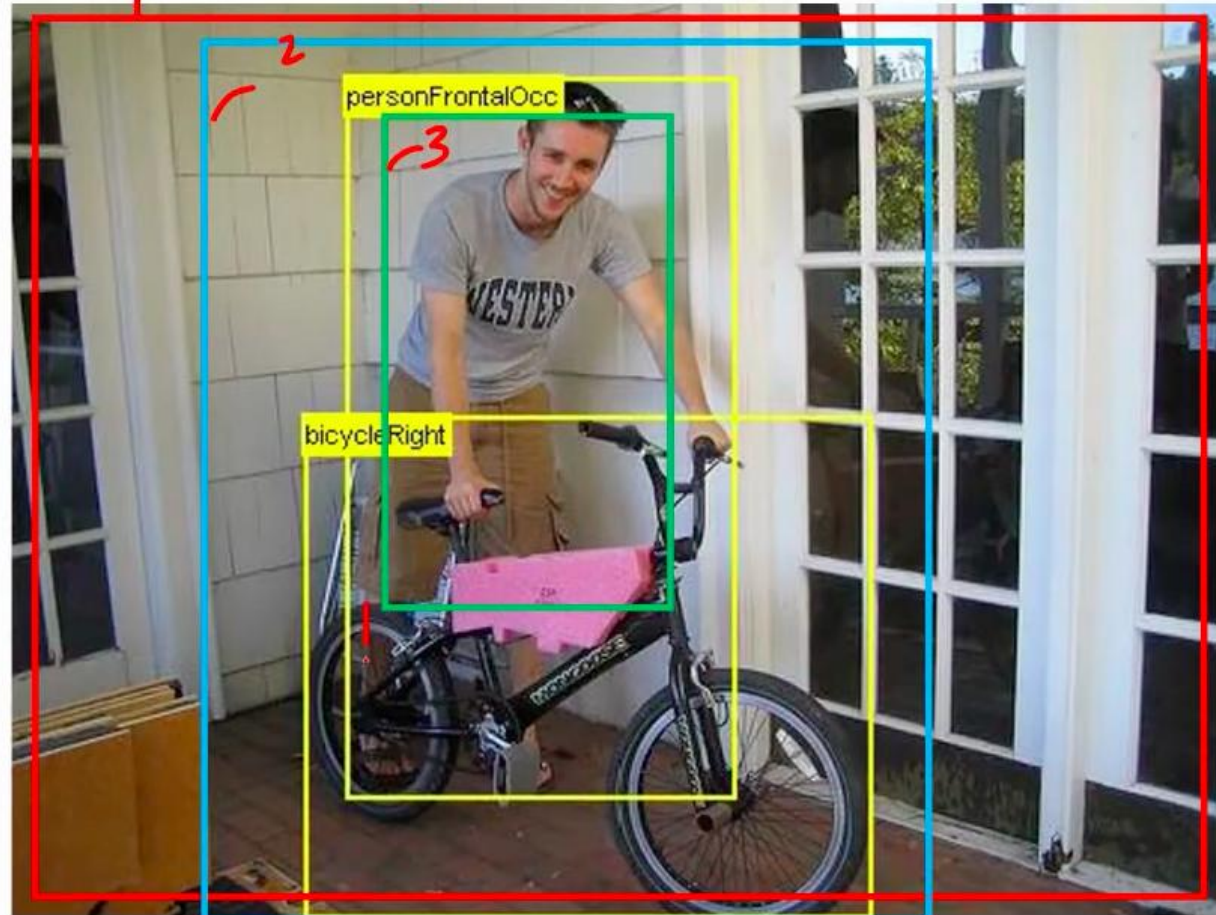
→ Person 1



# How to find out TP and FP

TP FP

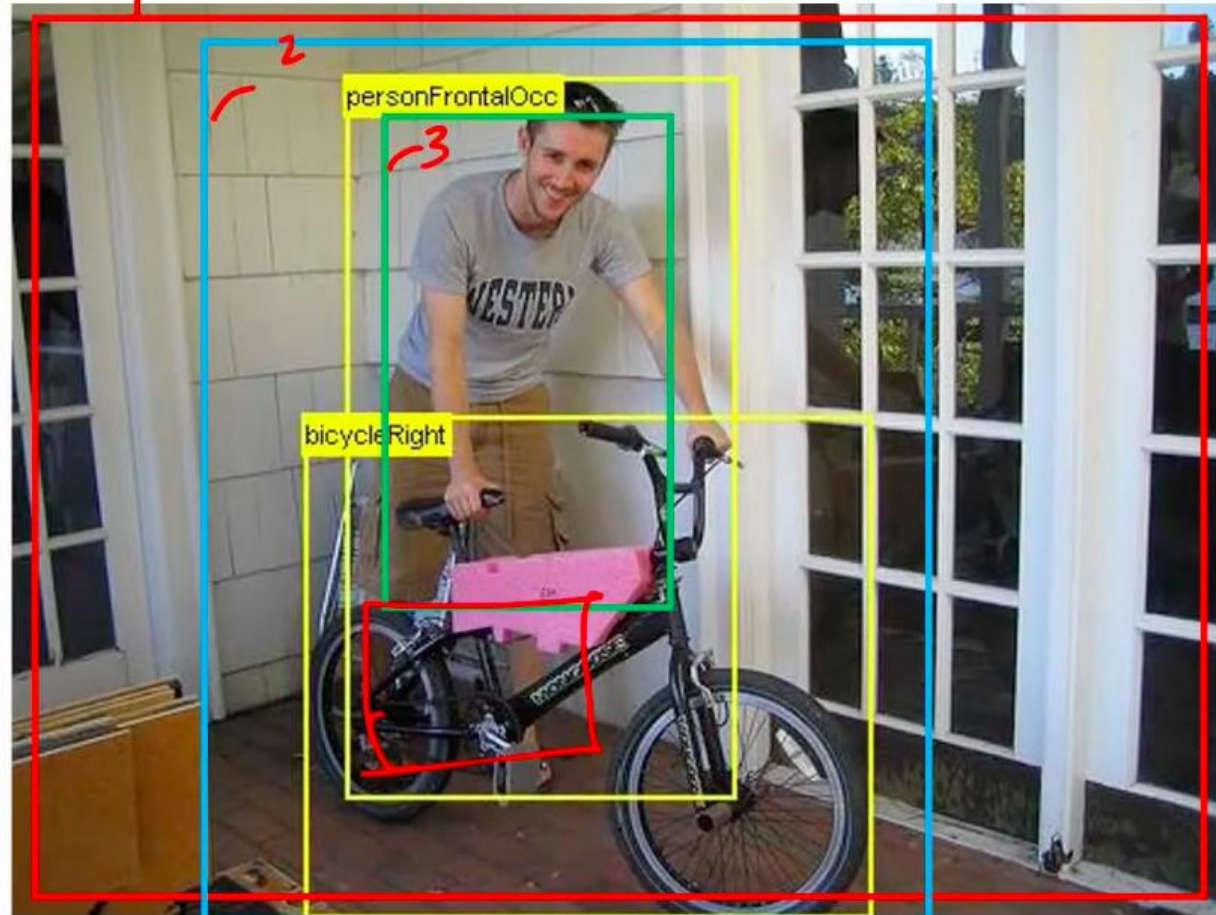
→ Person 1



# How to find out TP and FP

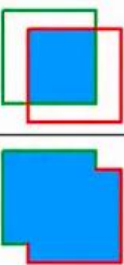
TP FP

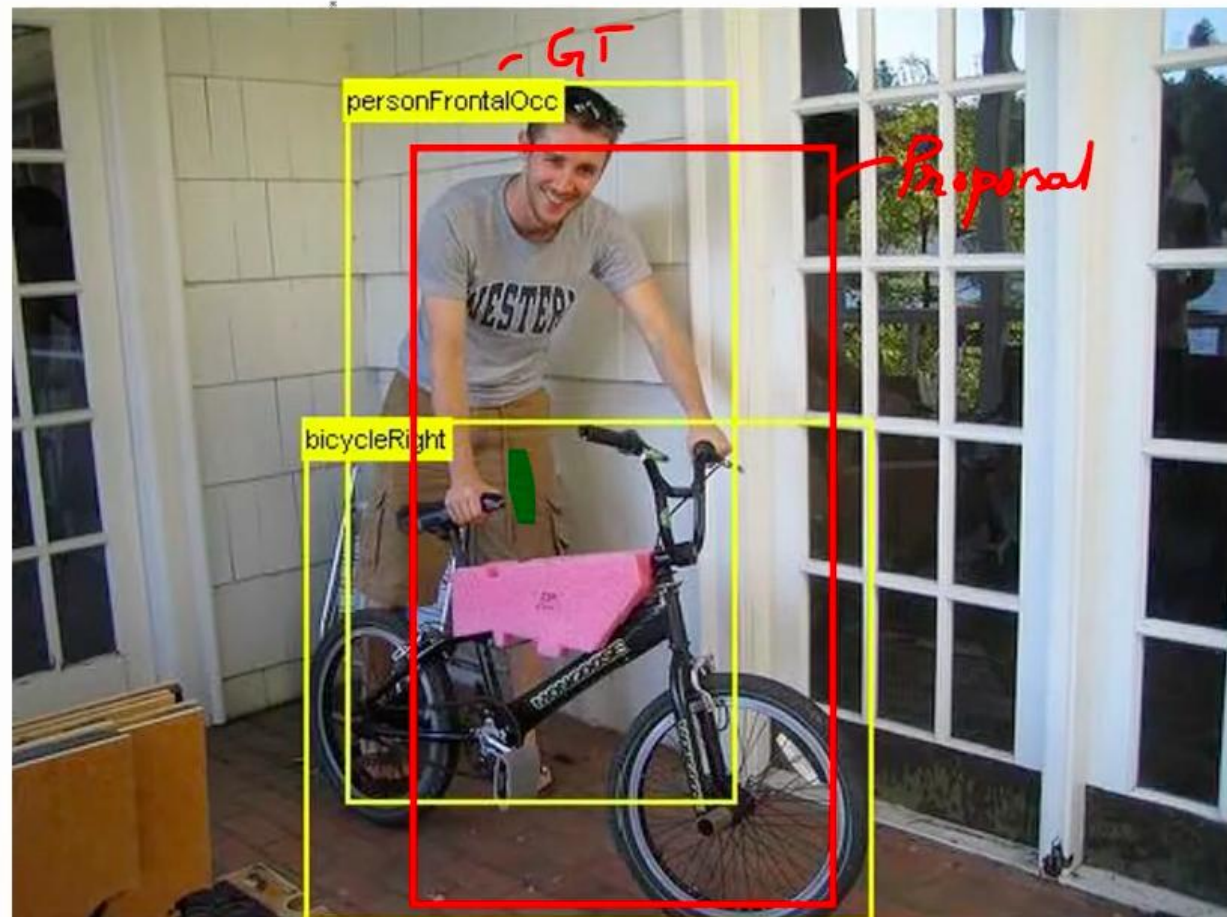
→ Person 1



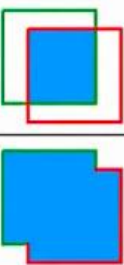


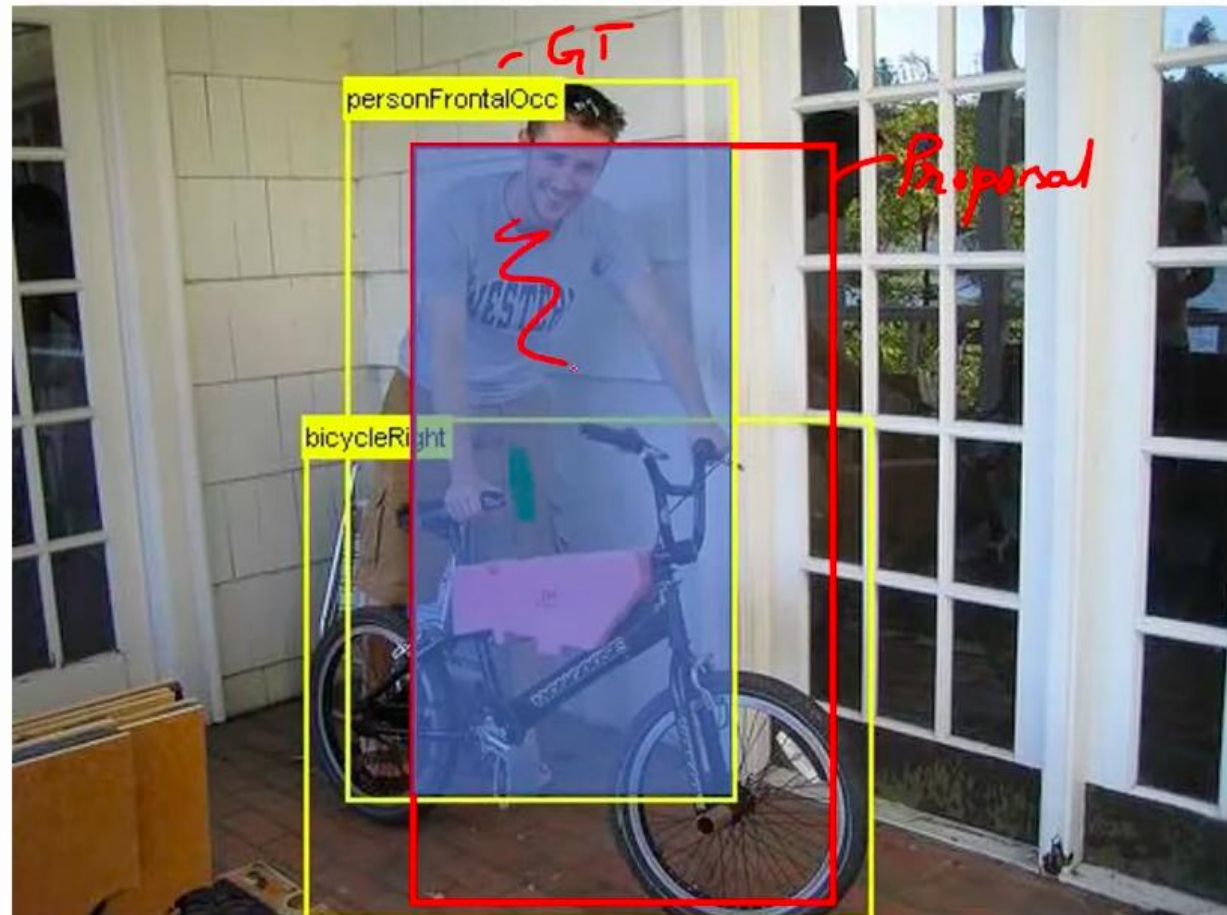
## IoU

$$IOU = \frac{\text{area of overlap}}{\text{area of union}} = \frac{\text{area of overlap}}{\text{area of union}}$$


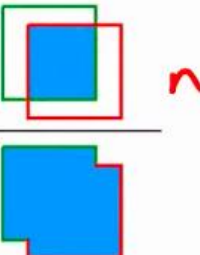


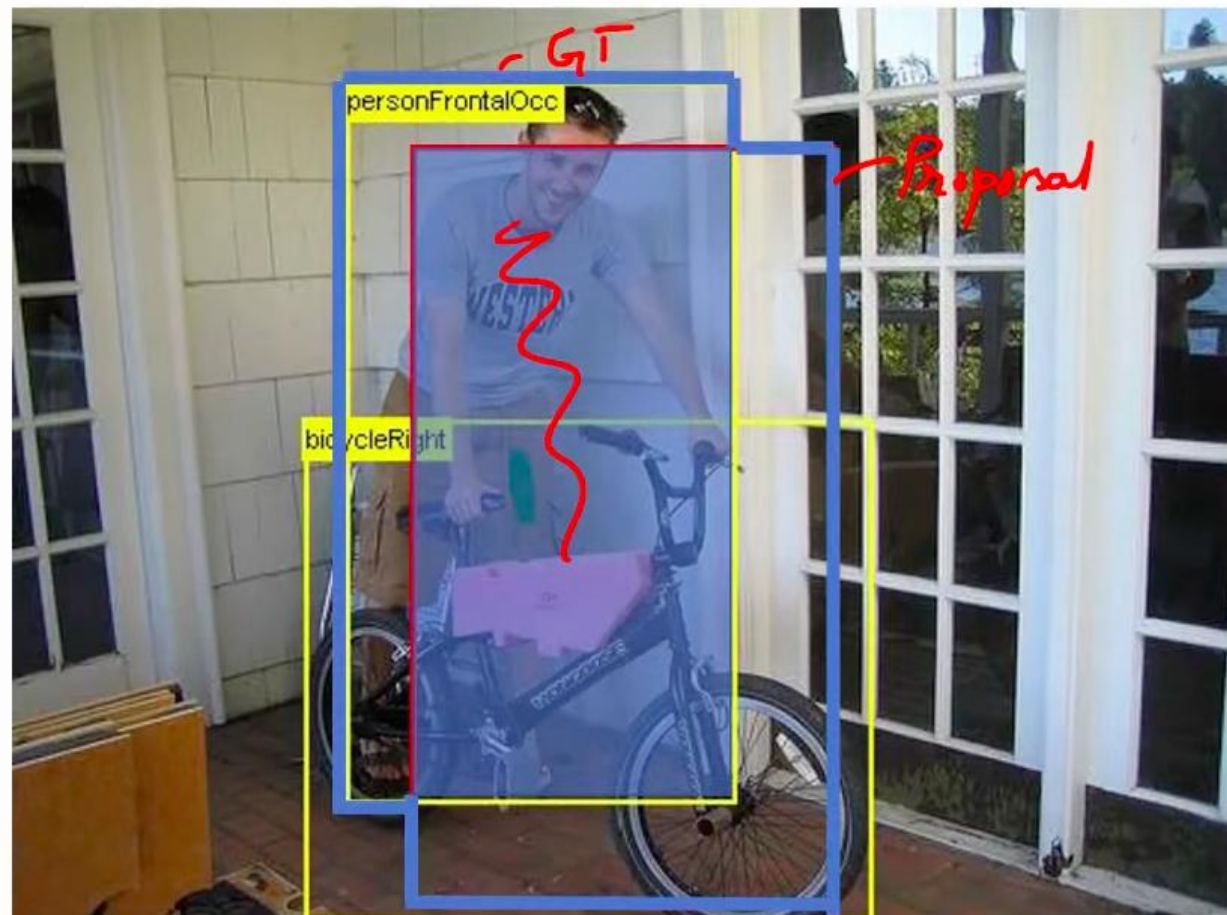
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# IoU

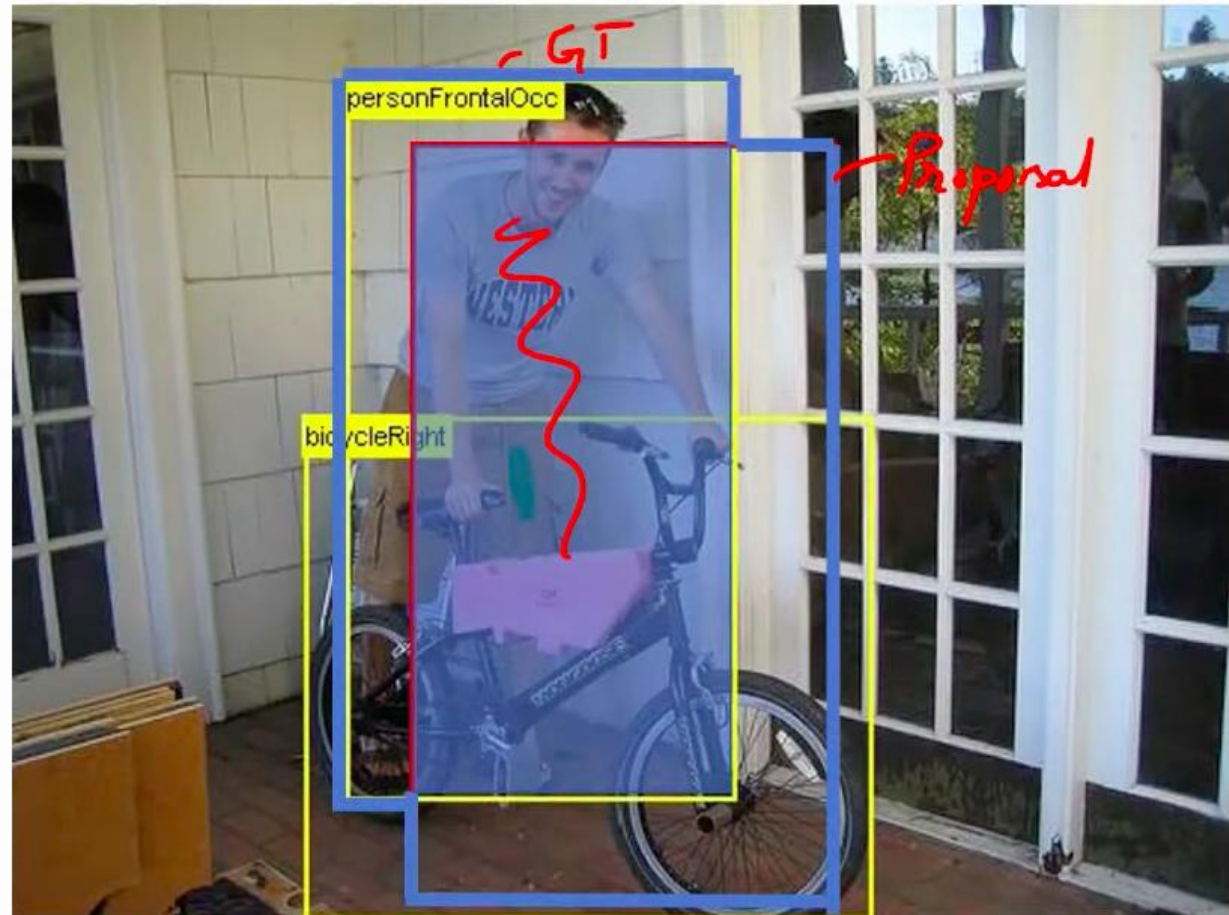
$$IOU = \frac{\text{area of overlap}}{\text{area of union}} = \frac{n}{d}$$

*(Note: In the diagram, 'n' is the area of overlap and 'd' is the area of union, represented by two overlapping blue squares with red outlines.)*

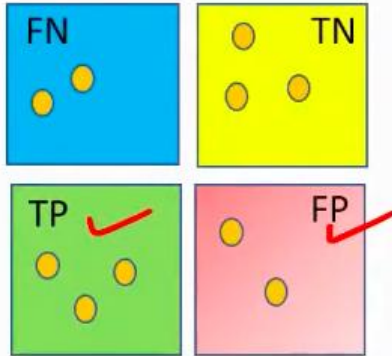
*(Note: Below the formula, there are three examples of bounding boxes with handwritten labels and percentages:)*

- Example 1: A red box labeled "50%" with "FP" (False Positive) written below it.
- Example 2: A red box labeled "25%" with "FP" (False Positive) written below it.
- Example 3: A red box labeled "45%" with "TP" (True Positive) written below it.

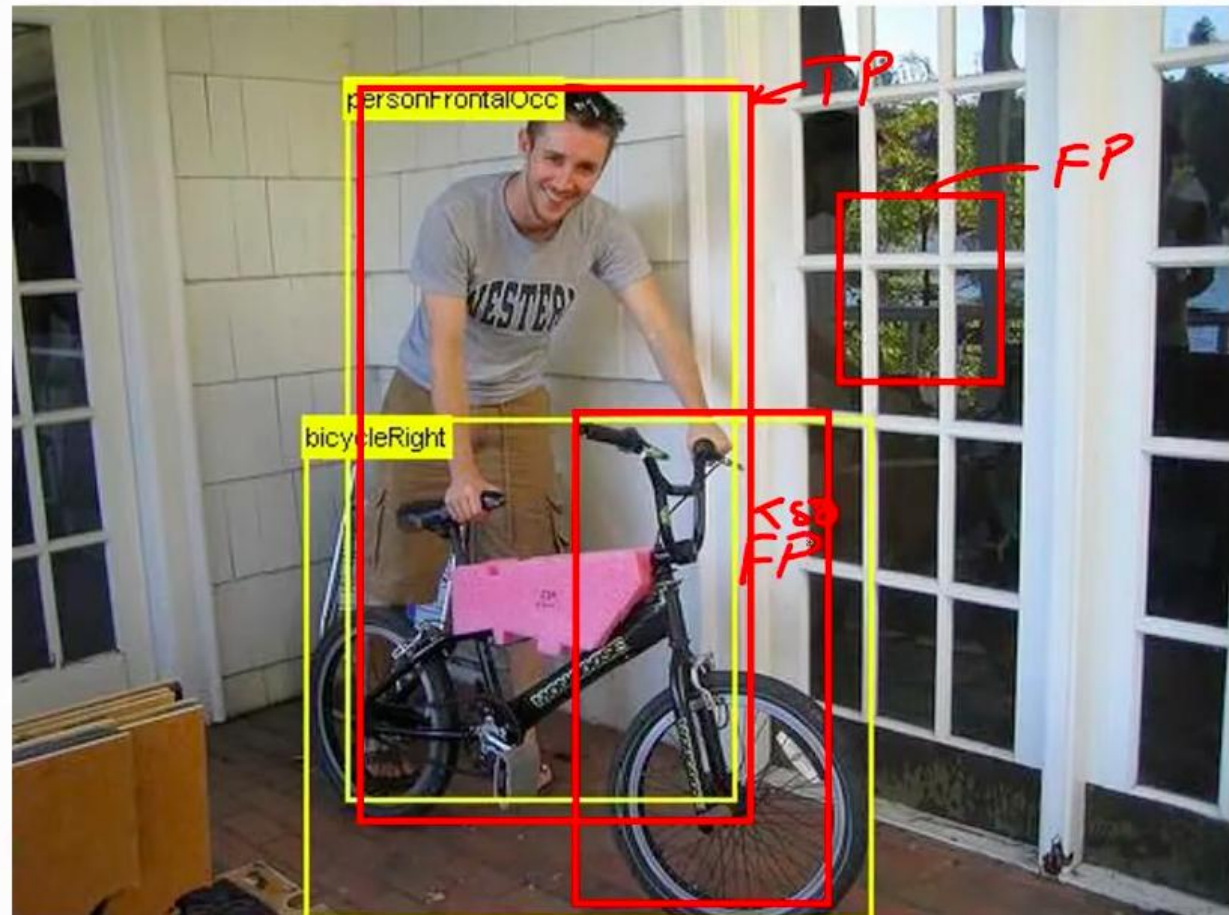
*(Note: There is also a handwritten "= X 75% TP" with "FP" written next to it, and a red squiggly line connecting it to the "45%" example.)*



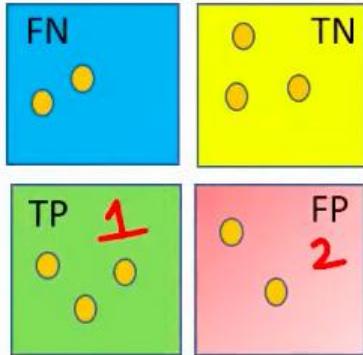
# How to find Calculate Precision and Recall



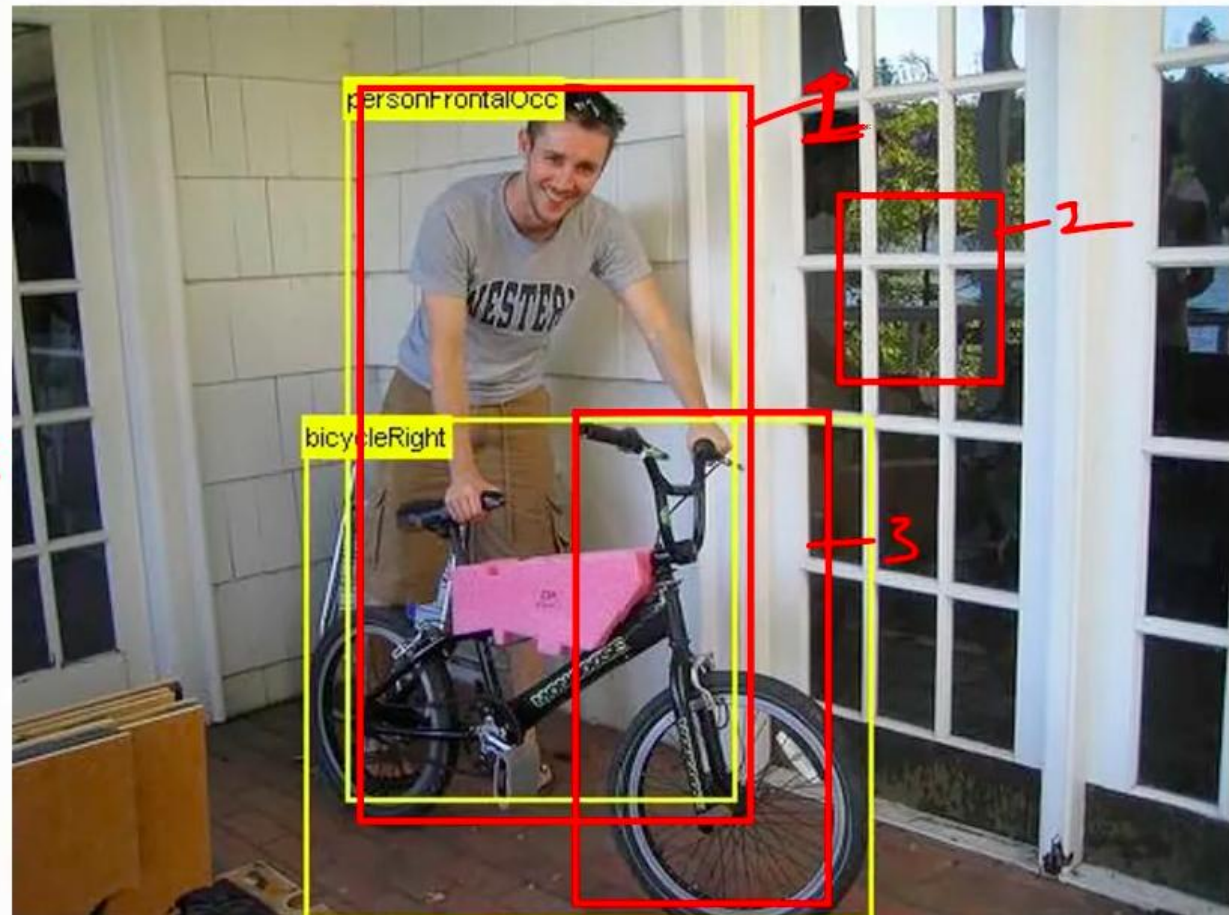
$$P = \frac{TP}{TP + FP}$$



# How to find Calculate Precision and Recall

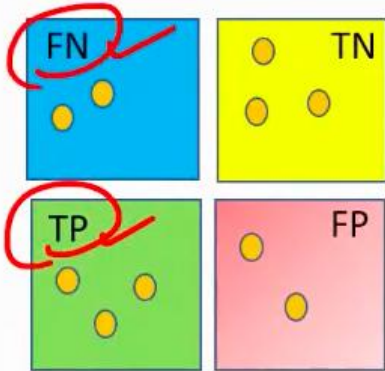


$$P = \frac{TP}{\underbrace{TP + FP}_{\rightarrow \#ROI}} = \frac{1}{3} = 33\%$$

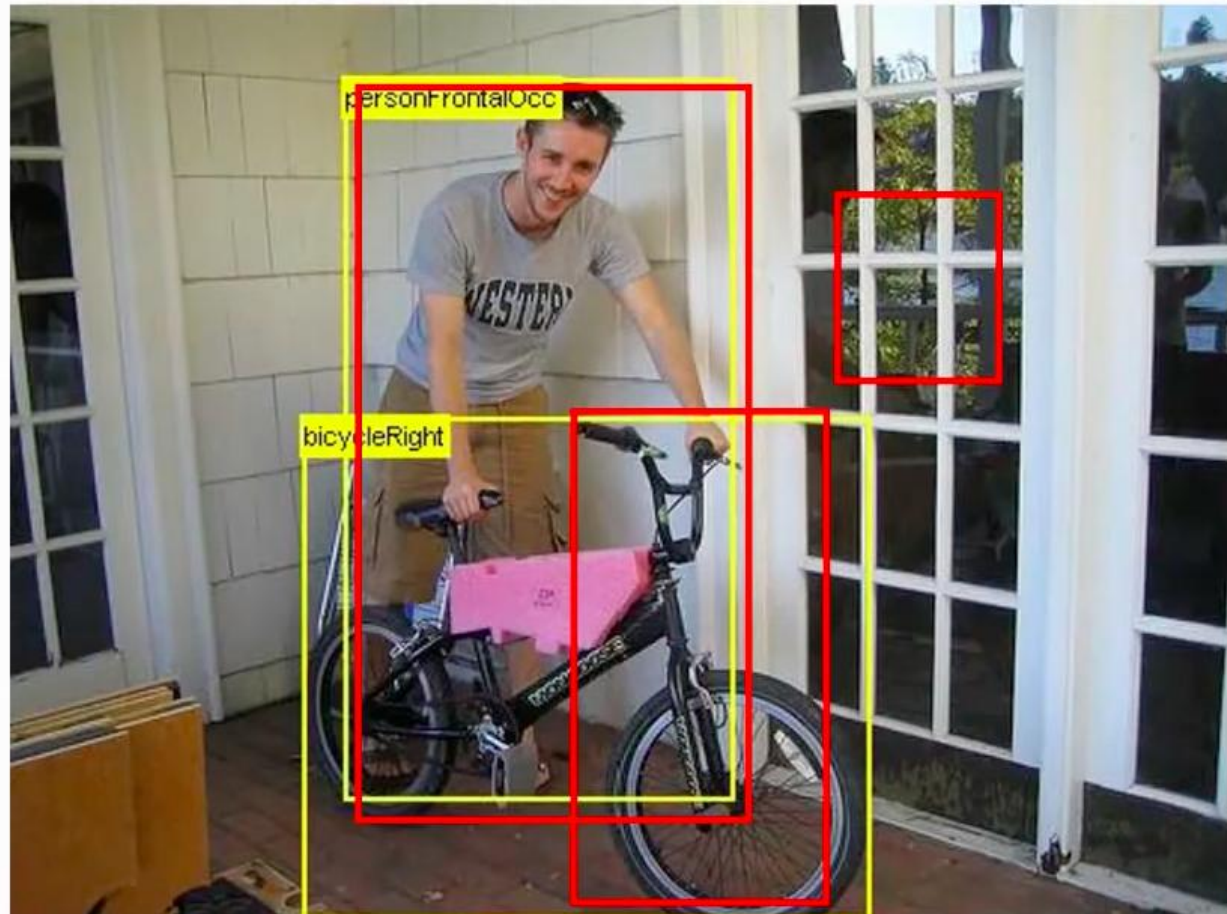




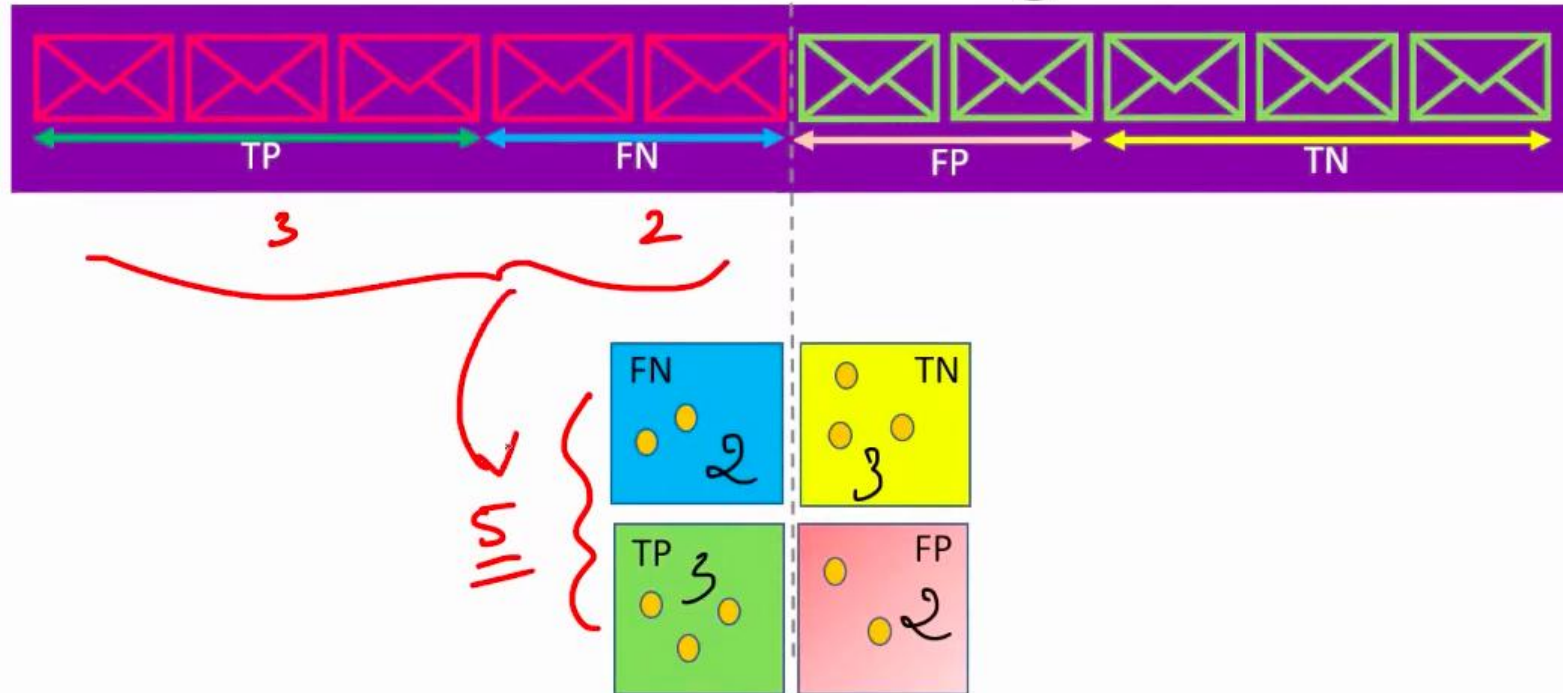
# How to find Calculate Precision and Recall



$$R = \frac{TP}{TP + FN}$$



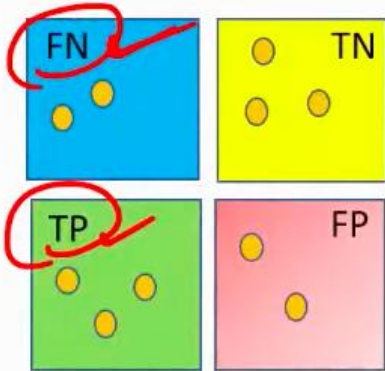
# More Terminologies



$$\text{Precision} = \frac{\text{TP}}{\text{TP} + \text{FP}}$$

$$\text{Recall} = \text{(Sensitivity)} = \frac{\text{TP}}{\text{TP} + \text{FN}}$$

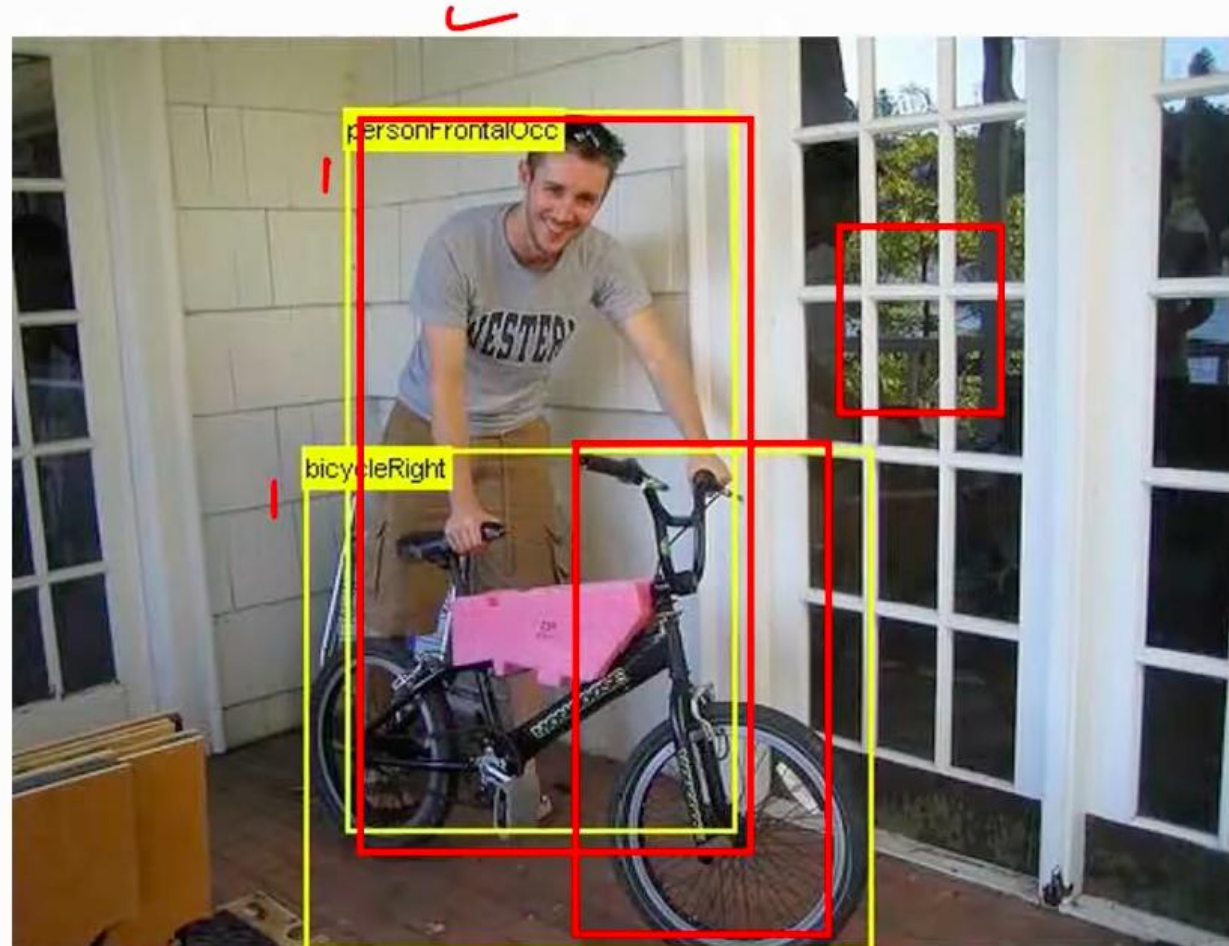
# How to find Calculate Precision and Recall



$$R = \frac{TP}{TP + FN}$$

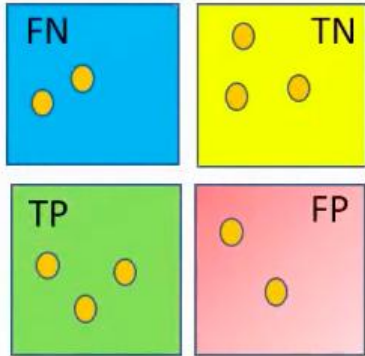
# GT R = 1

$$= \frac{TP}{2} = \frac{1}{2}$$



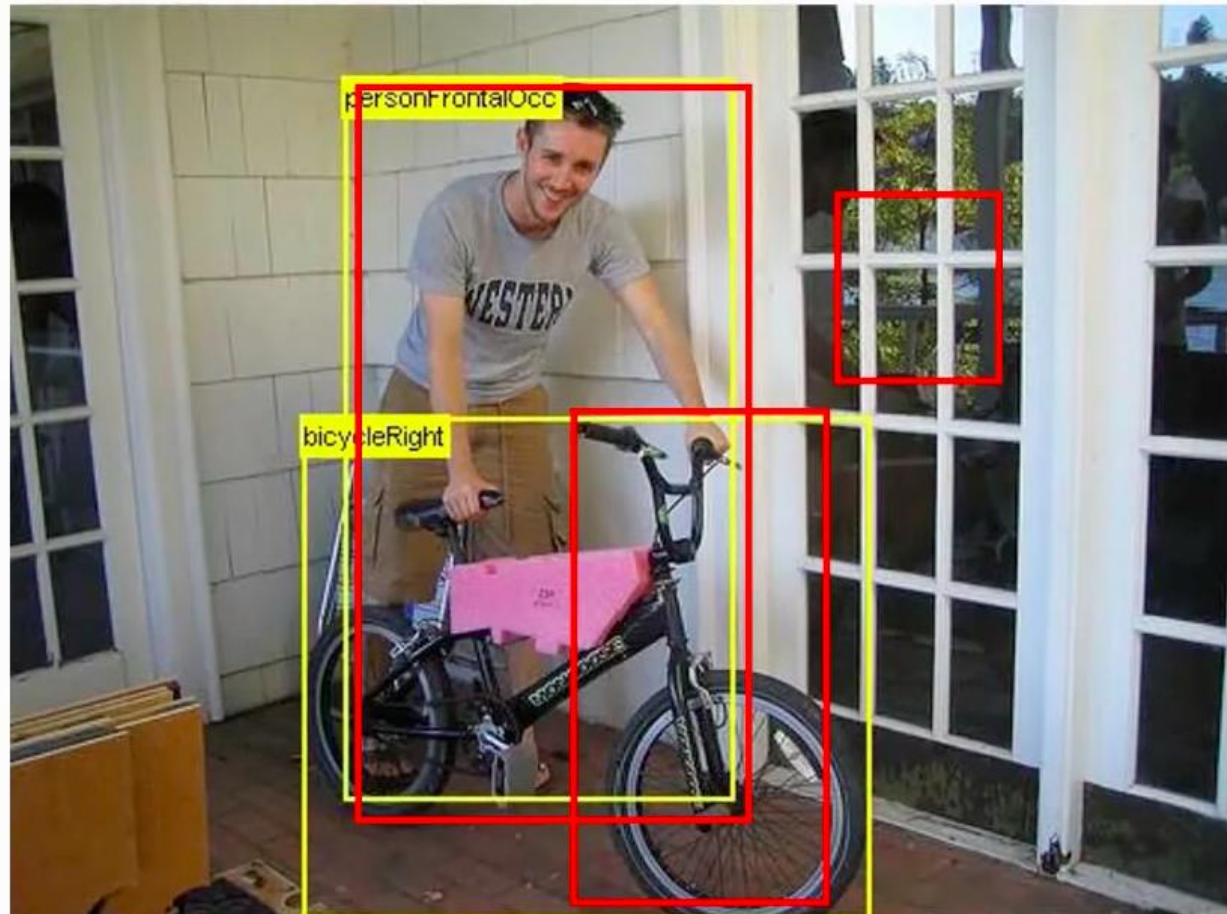


# How to find Calculate Precision and Recall

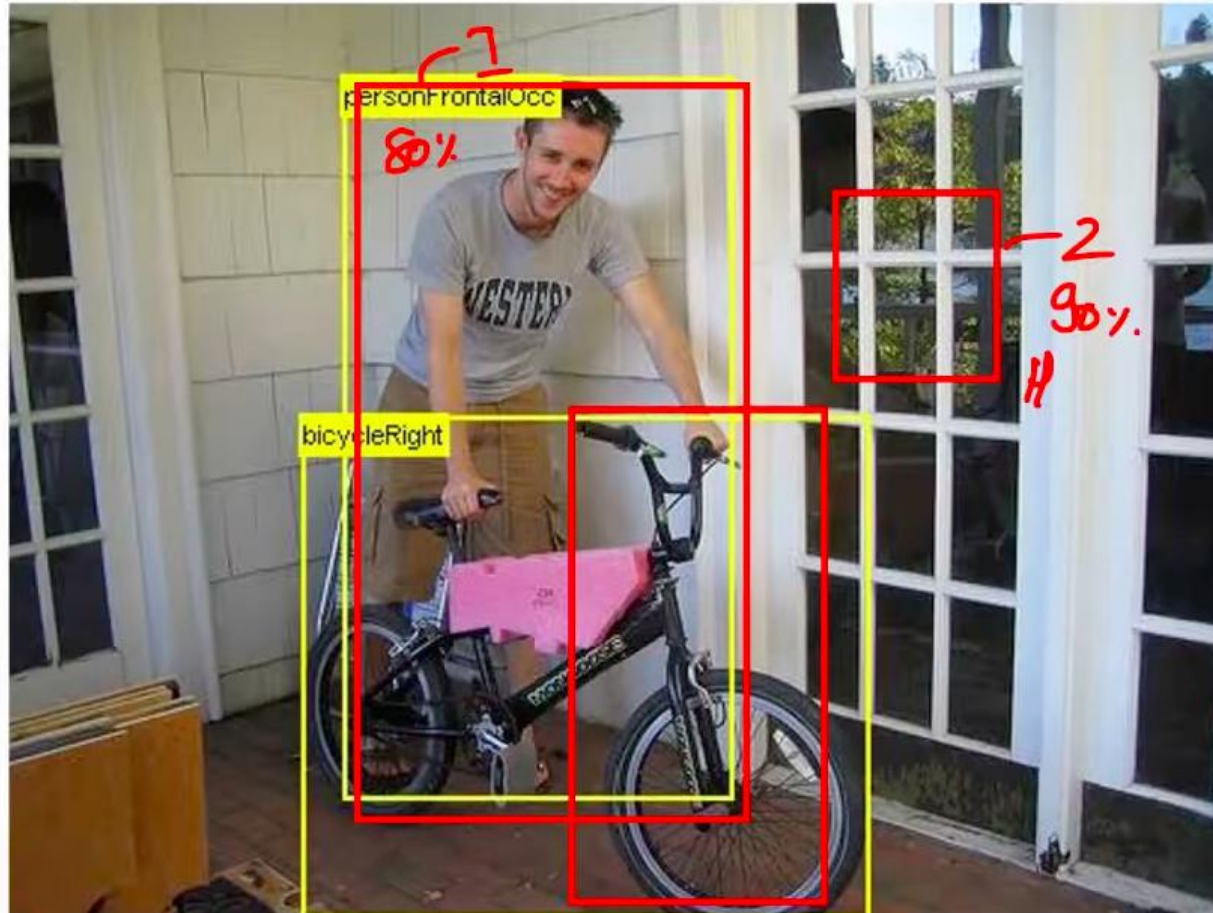


$$P = \frac{TP}{\# \text{ ROI proposals}}$$

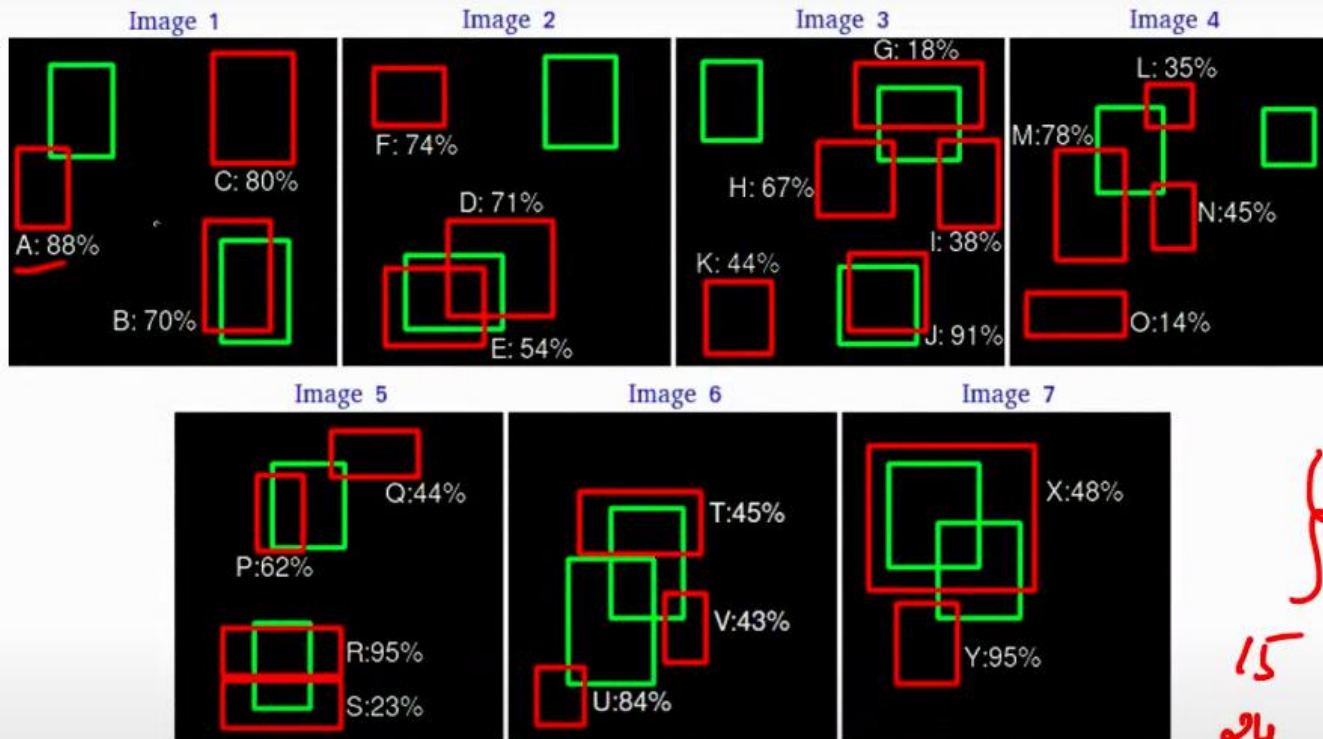
$$R = \frac{TP}{\# \text{ GT ROIs}}$$



# Confidence Scores



## mAP



Hat Tip to Rafael: <https://github.com/rafaelpadilla/Object-Detection-Metrics>

Images	Detections	Confidences	TP or FP
Image 1	A	88%	FP
Image 1	B	70%	TP
Image 1	C	80%	FP
Image 2	D	71%	FP
Image 2	E	54%	TP
Image 2	F	74%	FP
Image 3	G	18%	TP
Image 3	H	67%	FP
Image 3	I	38%	FP
Image 3	J	91%	TP
Image 3	K	44%	FP
Image 4	L	35%	FP
Image 4	M	78%	FP
Image 4	N	45%	FP
Image 4	O	14%	FP
Image 5	P	62%	TP
Image 5	Q	44%	FP
Image 5	R	95%	TP
Image 5	S	23%	FP
Image 6	T	45%	FP
Image 6	U	84%	FP
Image 6	V	43%	FP
Image 7	X	48%	TP
Image 7	Y	95%	FP



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Image 4	M	78%	FP
Image 4	N	45%	FP
Image 4	O	14%	FP
Image 5	P	62%	TP
Image 5	Q	44%	FP
Image 5	R	95%	TP
Image 5	S	23%	FP
Image 6	T	45%	FP
Image 6	U	84%	FP
Image 6	V	43%	FP
Image 7	X	48%	TP
Image 7	Y	95%	FP



Images	Detections	Confidences	TP	FP	Acc TP	Acc FP	Precision	Recall
Image 5	R	95%	1	0	1	0	1	0.0666
Image 7	Y	95%	0	1	1	1	0.5	0.0666
Image 3	J	91%	1	0	2	1	0.6666	0.1333
Image 1	A	88%	0	1	2	2	0.5	0.1333
Image 6	U	84%	0	1	2	3	0.4	0.1333
Image 1	C	80%	0	1	2	4	0.3333	0.1333
Image 4	M	78%	0	1	2	5	0.2857	0.1333
Image 2	F	74%	0	1	2	6	0.25	0.1333
Image 2	D	71%	0	1	2	7	0.2222	0.1333
Image 1	B	70%	1	0	3	7	0.3	0.2
Image 3	H	67%	0	1	3	8	0.2727	0.2
Image 5	P	62%	1	0	4	8	0.3333	0.2666
Image 2	E	54%	1	0	5	8	0.3846	0.3333
Image 7	X	48%	1	0	6	8	0.4285	0.4
Image 4	N	45%	0	1	6	9	0.4	0.4
Image 6	T	45%	0	1	6	10	0.375	0.4
Image 3	K	44%	0	1	6	11	0.3529	0.4
Image 5	Q	44%	0	1	6	12	0.3333	0.4
Image 6	V	43%	0	1	6	13	0.3157	0.4
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$$P = \frac{TP}{TP + FP}$$

$$R = \frac{TP}{GT}$$

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Image 3	I	38%	FP
Image 3	J	91%	TP
Image 3	K	44%	FP
Image 4	L	35%	FP
Image 4	M	78%	FP
Image 4	N	45%	FP
Image 4	O	14%	FP
Image 5	P	62%	TP
Image 5	Q	44%	FP
Image 5	R	95%	TP
Image 5	S	23%	FP
Image 6	T	45%	FP
Image 6	U	84%	FP
Image 6	V	43%	FP
Image 7	X	48%	TP
Image 7	Y	95%	FP

Images	Detections	Confidences	TP	FP	Acc TP	Acc FP	Precision	Recall
Image 5	R	95%	1	0	1	0	1	0.0666
Image 7	Y	95%	0	1	1	1	0.5	0.0666
Image 3	J	91%	1	0	2	1	0.6666	0.1333
Image 1	A	88%	0	1	2	2	0.5	0.1333
Image 6	U	84%	0	1	2	3	0.4	0.1333
Image 1	C	80%	0	1	2	4	0.3333	0.1333
Image 4	M	78%	0	1	2	5	0.2857	0.1333
Image 2	F	74%	0	1	2	6	0.25	0.1333
Image 2	D	71%	0	1	2	7	0.2222	0.1333
Image 1	B	70%	1	0	3	7	0.3	0.2
Image 3	H	67%	0	1	3	8	0.2727	0.2
Image 5	P	62%	1	0	4	8	0.3333	0.2666
Image 2	E	54%	1	0	5	8	0.3846	0.3333
Image 7	X	48%	1	0	6	8	0.4285	0.4
Image 4	N	45%	0	1	6	9	0.4	0.4
Image 6	T	45%	0	1	6	10	0.375	0.4
Image 3	K	44%	0	1	6	11	0.3529	0.4
Image 5	Q	44%	0	1	6	12	0.3333	0.4
Image 6	V	43%	0	1	6	13	0.3157	0.4
Image 3	I	38%	0	1	6	14	0.3	0.4
Image 4	L	35%	0	1	6	15	0.2857	0.4
Image 5	S	23%	0	1	6	16	0.2727	0.4
Image 3	G	18%	1	0	7	16	0.3043	0.4666
Image 4	O	14%	0	1	7	17	0.2916	0.4666

← 1  
is



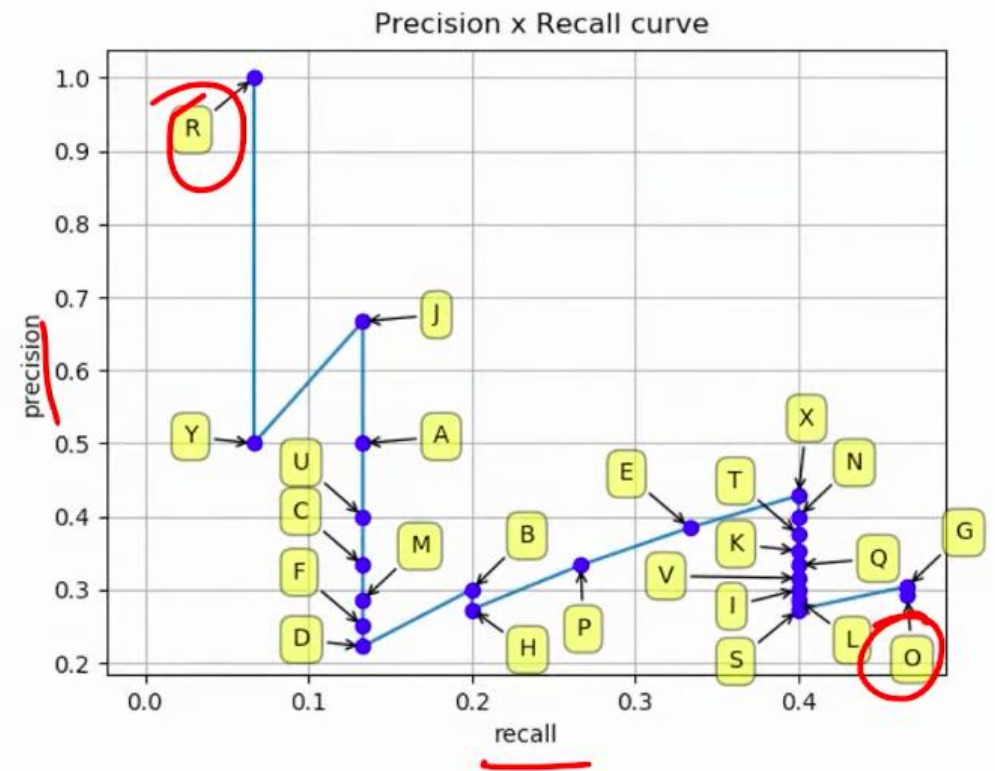
Images	Detections	Confidences	TP or FP
Image 1	A	88%	FP
Image 1	B	70%	TP
Image 1	C	80%	FP
Image 2	D	71%	FP
Image 2	E	54%	TP
Image 2	F	74%	FP
Image 3	G	18%	TP
Image 3	H	67%	FP
Image 3	I	38%	FP
Image 3	J	91%	TP
Image 3	K	44%	FP
Image 4	L	35%	FP
Image 4	M	78%	FP
Image 4	N	45%	FP
Image 4	O	14%	FP
Image 5	P	62%	TP
Image 5	Q	44%	FP
Image 5	R	95%	TP
Image 5	S	23%	FP
Image 6	T	45%	FP
Image 6	U	84%	FP
Image 6	V	43%	FP
Image 7	X	48%	TP
Image 7	Y	95%	FP

Images	Detections	Confidences	TP	FP	Acc TP	Acc FP	Precision	Recall
Image 5	R	95%	1	0	1	0	1	0.0666
Image 7	Y	95%	0	1	1	1	0.5	0.0666
Image 3	J	91%	1	0	2	1	0.6666	0.1333
Image 1	A	88%	0	1	2	2	0.5	0.1333
Image 6	U	84%	0	1	2	3	0.4	0.1333
Image 1	C	80%	0	1	2	4	0.3333	0.1333
Image 4	M	78%	0	1	2	5	0.2857	0.1333
Image 2	F	74%	0	1	2	6	0.25	0.1333
Image 2	D	71%	0	1	2	7	0.2222	0.1333
Image 1	B	70%	1	0	3	7	0.3	0.2
Image 3	H	67%	0	1	3	8	0.2727	0.2
Image 5	P	62%	1	0	4	8	0.3333	0.2666
Image 2	E	54%	1	0	5	8	0.3846	0.3333
Image 7	X	48%	1	0	6	8	0.4285	0.4
Image 4	N	45%	0	1	6	9	0.4	0.4
Image 6	T	45%	0	1	6	10	0.375	0.4
Image 3	K	44%	0	1	6	11	0.3529	0.4
Image 5	Q	44%	0	1	6	12	0.3333	0.4
Image 6	V	43%	0	1	6	13	0.3157	0.4
Image 3	I	38%	0	1	6	14	0.3	0.4
Image 4	L	35%	0	1	6	15	0.2857	0.4
Image 5	S	23%	0	1	6	16	0.2727	0.4
Image 3	G	18%	1	0	7	16	0.3043	0.4666
Image 4	O	14%	0	1	7	17	0.2916	0.4666

← 1  
is

=  $\frac{7}{15}$

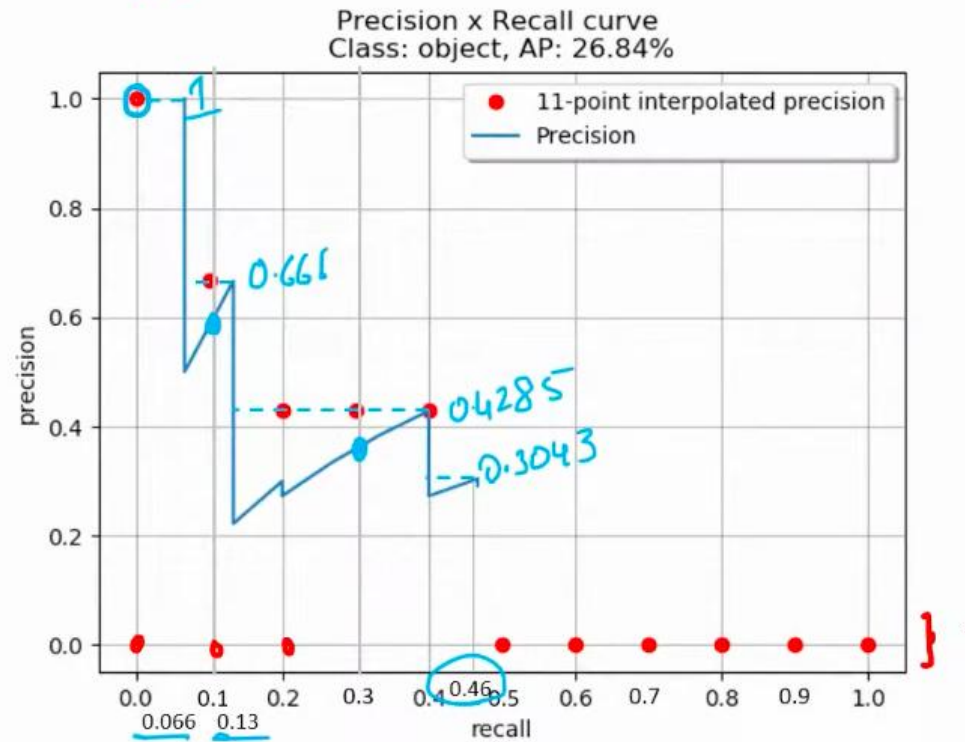
Images	Detections	Confidences	TP	FP	Acc TP	Acc FP	Precision	Recall
Image 5	R	95%	1	0	1	0	1	0.0666
Image 7	Y	95%	0	1	1	1	0.5	0.0666
Image 3	J	91%	1	0	2	1	0.6666	0.1333
Image 1	A	88%	0	1	2	2	0.5	0.1333
Image 6	U	84%	0	1	2	3	0.4	0.1333
Image 1	C	80%	0	1	2	4	0.3333	0.1333
Image 4	M	78%	0	1	2	5	0.2857	0.1333
Image 2	F	74%	0	1	2	6	0.25	0.1333
Image 2	D	71%	0	1	2	7	0.2222	0.1333
Image 1	B	70%	1	0	3	7	0.3	0.2
Image 3	H	67%	0	1	3	8	0.2727	0.2
Image 5	P	62%	1	0	4	8	0.3333	0.2666
Image 2	E	54%	1	0	5	8	0.3846	0.3333
Image 7	X	48%	1	0	6	8	0.4285	0.4
Image 4	N	45%	0	1	6	9	0.4	0.4
Image 6	T	45%	0	1	6	10	0.375	0.4
Image 3	K	44%	0	1	6	11	0.3529	0.4
Image 5	Q	44%	0	1	6	12	0.3333	0.4
Image 6	V	43%	0	1	6	13	0.3157	0.4
Image 3	I	38%	0	1	6	14	0.3	0.4
Image 4	L	35%	0	1	6	15	0.2857	0.4
Image 5	S	23%	0	1	6	16	0.2727	0.4
Image 3	G	18%	1	0	7	16	0.3043	0.4666
Image 4	O	14%	0	1	7	17	0.2916	0.4666



# 11 Point Interpolation

AP

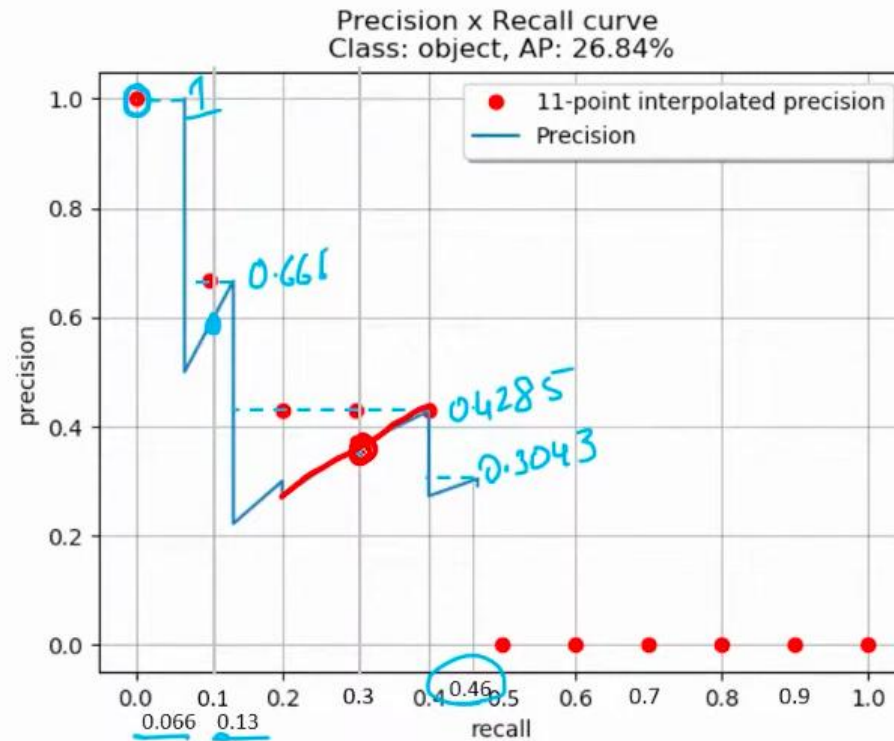
Precision	Recall
1	0.0666
0.5	0.0666
0.6666	0.1333
0.5	0.1333
0.4	0.1333
0.3333	0.1333
0.2857	0.1333
0.25	0.1333
0.2222	0.1333
0.3	0.2
0.2727	0.2
0.3333	0.2666
0.3846	0.3333
0.4285	0.4
0.4	0.4
0.375	0.4
0.3529	0.4
0.3333	0.4
0.3157	0.4
0.3	0.4
0.2857	0.4
0.2727	0.4
0.3043	0.4666
0.2916	0.4666





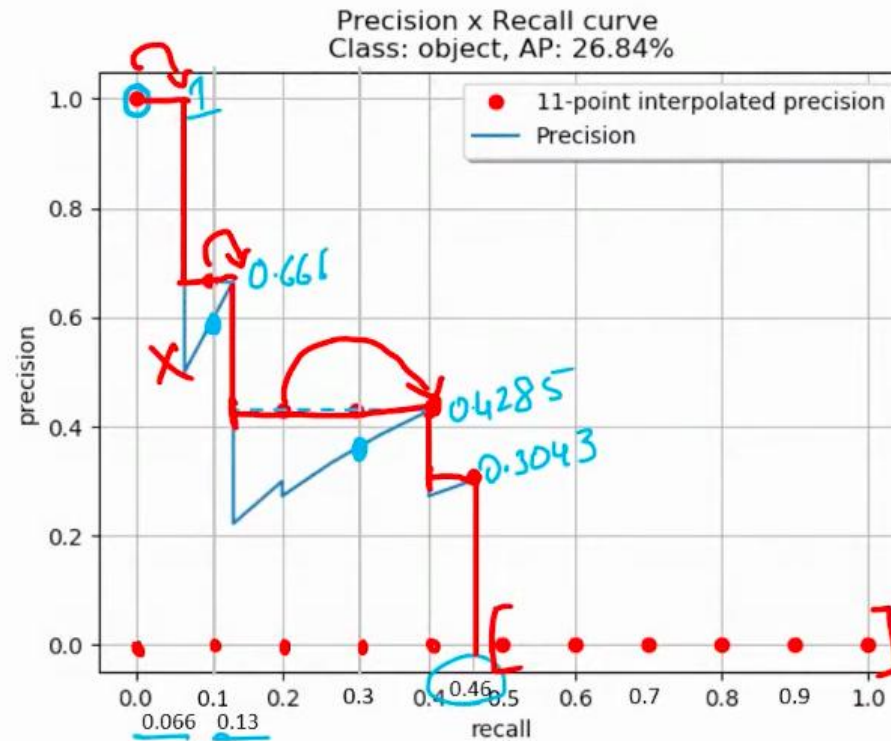
# 11 Point Interpolation

Precision	Recall
<u>1</u>	0.0666
0.5	0.0666
<u>0.6666</u>	0.1333
0.5	0.1333
0.4	0.1333
0.3333	0.1333
0.2857	0.1333
0.25	0.1333
0.2222	0.1333
0.3	0.2
0.2727	0.2
0.3333	0.2666
0.3846	0.3333
<u>0.4285</u>	0.4
0.4	0.4
0.375	0.4
0.3529	0.4
0.3333	0.4
0.3157	0.4
0.3	0.4
0.2857	0.4
0.2727	0.4
<u>0.3043</u>	0.4666
<u>0.2916</u>	0.4666



# 11 Point Interpolation

Precision	Recall
<u>1</u>	0.0666
0.5	0.0666
<u>0.6666</u>	0.1333
0.5	0.1333
0.4	0.1333
0.3333	0.1333
0.2857	0.1333
0.25	0.1333
0.2222	0.1333
0.3	0.2
0.2727	0.2
0.3333	0.2666
0.3846	0.3333
<u>0.4285</u>	0.4
0.4	0.4
0.375	0.4
0.3529	0.4
0.3333	0.4
0.3157	0.4
0.3	0.4
0.2857	0.4
0.2727	0.4
<u>0.3043</u>	0.4666
<u>0.2916</u>	0.4666



$$AP = \frac{1}{11} (1 + 0.666 + 3 \times 0.4285 + 0) = 26.84\%$$

$$= 0.570$$

# Average Precision

## 11 Point Interpolation

$$AP = \frac{1}{11} (1 + 0.6666 + 0.4285 + 0.4285 + 0.4285 + 0 + 0 + 0 + 0 + 0 + 0)$$

$$AP = 26.84\%$$

## All Point Interpolation

Calculating the total area, we have the AP:

$$AP = A1 + A2 + A3 + A4$$

with:

$$A1 = (0.0666 - 0) \times 1 = 0.0666$$

$$A2 = (0.1333 - 0.0666) \times 0.6666 = 0.04446222$$

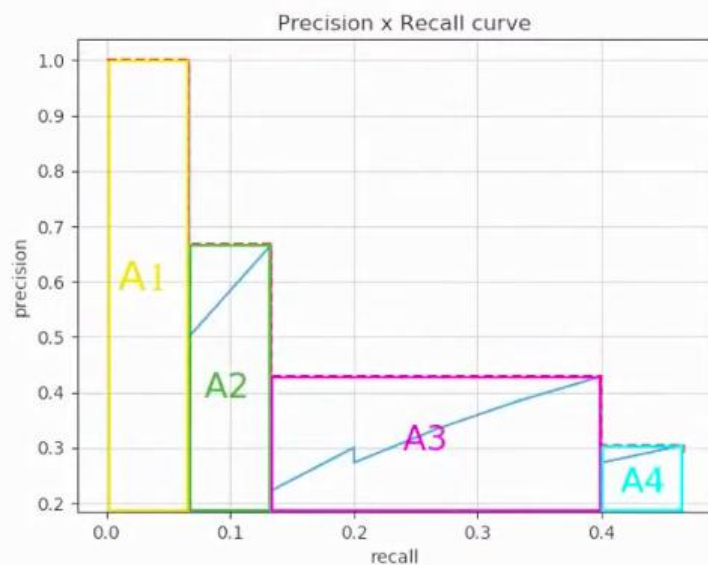
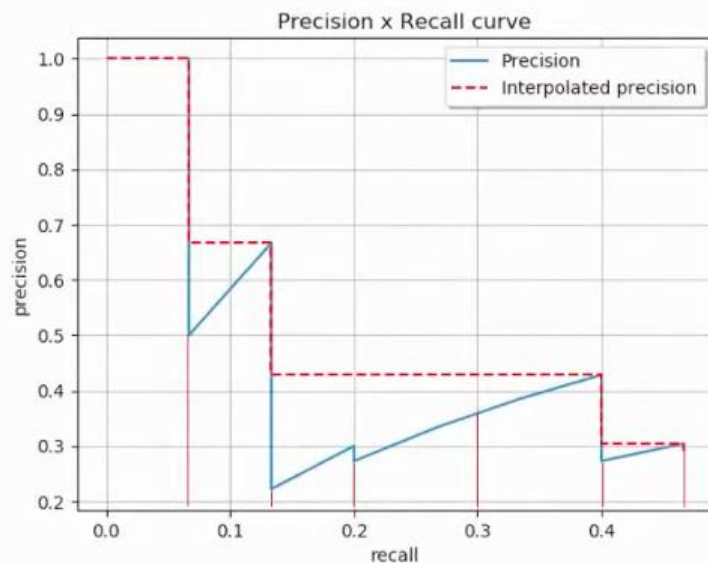
$$A3 = (0.4 - 0.1333) \times 0.4285 = 0.11428095$$

$$A4 = (0.4666 - 0.4) \times 0.3043 = 0.02026638$$

$$AP = 0.0666 + 0.04446222 + 0.11428095 + 0.02026638$$

$$AP = 0.24560955$$

$$AP = 24.56\%$$





# mAP Examples – Pascal VOC

20

Method	data	mAP	aero	bike	bird	boat	bottle	bus	car	cat	chair	cow	table	dog	horse	mbike	person	plant	sheep	sofa	train	tv
Fast [6]	07	66.9	74.5	78.3	69.2	53.2	36.6	77.3	78.2	82.0	40.7	72.7	67.9	79.6	79.2	73.0	69.0	30.1	65.4	70.2	75.8	65.8

Results on Pascal VOC 2007

# mAP Examples – Pascal VOC

20

Method	data	mAP	aero	bike	bird	boat	bottle	bus	car	cat	chair	cow	table	dog	horse	mbike	person	plant	sheep	sofa	train	tv
Fast [6]	07	66.9	74.5	78.3	69.2	53.2	36.6	77.3	78.2	82.0	40.7	72.7	67.9	79.6	79.2	73.0	69.0	30.1	65.4	70.2	75.8	65.8
Fast [6]	07+12	70.0	77.0	78.1	69.3	59.4	38.3	81.6	78.6	86.7	42.8	78.8	68.9	84.7	82.0	76.6	69.9	31.8	70.1	74.8	80.4	70.4
Faster [2]	07	69.9	70.0	80.6	70.1	57.3	49.9	78.2	80.4	82.0	52.2	75.3	67.2	80.3	79.8	75.0	76.3	39.1	68.3	67.3	81.1	67.6
Faster [2]	07+12	73.2	76.5	79.0	70.9	65.5	52.1	83.1	84.7	86.4	52.0	81.9	65.7	84.8	84.6	77.5	76.7	38.8	73.6	73.9	83.0	72.6
Faster [2]	07+12+COCO	78.8	84.3	82.0	77.7	68.9	65.7	88.1	88.4	88.9	63.6	86.3	70.8	85.9	87.6	80.1	82.3	53.6	80.4	75.8	86.6	78.9

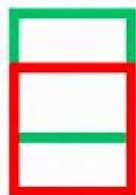
Results on Pascal VOC 2007

Pascal 2007	Pascal 2012	COCO
Train +	Train ] +	Train
Val	Val	Val
Test	Test	Test

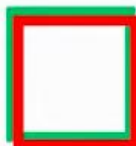
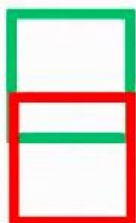
# mAP Examples - COCO

$$IOU = \frac{\text{area of overlap}}{\text{area of union}}$$

< 75



FP



FP

$mAP_{50}$   $mAP_{55}$  ...  $mAP_{95}$

	backbone	AP	AP <sub>50</sub>	AP <sub>75</sub>	AP <sub>S</sub>	AP <sub>M</sub>	AP <sub>L</sub>
<i>Two-stage methods</i>							
Faster R-CNN+++ [3]	ResNet-101-C4	34.9	55.7	37.4	15.6	38.7	50.9
Faster R-CNN w FPN [6]	ResNet-101-FPN	36.2	59.1	39.0	18.2	39.0	48.2
Faster R-CNN by G-RMI [4]	Inception-ResNet-v2 [19]	34.7	55.5	36.7	13.5	38.1	52.0
Faster R-CNN w TDM [18]	Inception-ResNet-v2-TDM	36.8	57.7	39.2	16.2	39.8	<b>52.1</b>
<i>One-stage methods</i>							
YOLOv2 [13]	DarkNet-19 [13]	21.6	44.0	19.2	5.0	22.4	35.5
SSD513 [9, 2]	ResNet-101-SSD	31.2	50.4	33.3	10.2	34.5	49.8
DSSD513 [2]	ResNet-101-DSSD	33.2	53.3	35.2	13.0	35.4	51.1
RetinaNet [7]	ResNet-101-FPN	39.1	59.1	42.3	21.8	42.7	50.2
RetinaNet [7]	ResNeXt-101-FPN	<b>40.8</b>	<b>61.1</b>	<b>44.1</b>	<b>24.1</b>	<b>44.2</b>	51.2
YOLOv3 608 × 608	Darknet-53	33.0	57.9	34.4	18.3	35.4	41.9

COCO for YOLOv3