

ANIRUDH RAGHAVAN

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Autonomy graduate student seeking internship or co-op opportunities to apply and grow skills in autonomy, computer vision, and AI. Experienced in building real-time perception systems and deep learning pipelines for autonomous platforms. Demonstrated success in developing resilient AI systems optimized for complex, real-world scenarios. Eager to apply and expand these skills in impactful, hands-on engineering roles.

EDUCATION

Purdue University, West Lafayette, IN, USA - MSE in Autonomy (Candidate 2026) (GPA: 3.72 / 4) 2024 – Present

- Coursework:** Vehicular Cyber-Physical Systems, Embedded Systems, Autonomous Systems, Artificial Intelligence

Vellore Institute of Technology, Chennai, India - B. Tech- Electronics and Communication Engineering (GPA: 8.11 / 10) 2020 – 2024

- Coursework:** Robotics and Automation, Machine Learning Fundamentals, Control Systems

SKILLS

- Technical Areas:** Computer Vision, Perception, IoT, Embedded Systems, Control Systems, Real-Time Processing
- Languages & Frameworks:** Python, C++, ROS2, OpenCV, YOLO, TensorFlow, PyTorch
- Tools & Platforms:** Gazebo, Rviz, Arduino IDE, Wokwi
- Hardware:** Arduino UNO/Nano, ESP8266, ESP32, STM32, NVIDIA Jetson Nano
- Certification:** Python for Everybody, IBM AI Engineering Specialization, Modern Robotics Course 1: Foundations of Robot Model

EXPERIENCE

Internet of Things, Externship (Remote) — SmartInternz, Hyderabad, India May 2023 – Jul 2023

- Designed and deployed WePark, a smart parking system leveraging ESP32 and IBM Cloud to enable real-time slot tracking and user reservation across mobile platforms.
- Achieved 98% slot detection accuracy, reducing false availability reports by 85% through calibrated sensor integration.
- Implemented cloud-based backend using Firebase and Node-RED, supporting concurrent users with near-zero latency. | [GitHub](#)

PUBLICATION

- Abhishek Sebastian, R. Pragna, K. Vishal Vythianathan, Dasaraju Sohan Sai, U. Shiva Sri Hari Al, **R. Anirudh**, Apurv Choudhary; Design of rubble analyzer probe using ML for earthquake. AIP Conf. Proc. 9 November 2023; 2946 (1): 040003. | [Link](#)

ACADEMIC PROJECTS

Exploring Object Detection and Semantic Segmentation on Road Scene Dataset | [GitHub](#) Jan 2025 – May 2025

- Trained and evaluated YOLOv8 and U-Net on a custom-labelled dataset derived from the Waymo Open Dataset for object detection and semantic segmentation.
- Built a modular benchmarking pipeline for multi-task vision evaluation, supporting easy integration of new models and datasets.
- Achieved 79% IoU on segmentation and 65% mAP on detection, demonstrating strong model performance in complex urban driving scenarios.

Weather-Invariant Object Detection: Enhancing YOLOv8 with Environment Adaptive Preprocessing for Robust Performance Across Diverse Conditions | [GitHub](#) Aug 2024 – Dec 2024

- Developed a modular, scalable pipeline seamlessly integrating weather classification, adaptive image enhancement, and YOLOv8 for robust real-time object detection in adverse weather conditions.
- Achieved 93% mAP across adverse weather datasets using synthetic data and custom augmentations.
- Reduced false negatives by 27% through targeted augmentation and weather-aware preprocessing strategies.

Traffic Sign Recognition Using Deep Learning and Tkinter | [GitHub](#) Jun 2025 – July 2025

- Built a high-accuracy traffic sign recognition system using Convolutional Neural Networks (CNNs) trained on the GTSRB dataset in TensorFlow and achieved 99.2% accuracy on test set.
- Deployed the model using a custom Tkinter GUI to enable real-time image classification for potential in-vehicle applications.