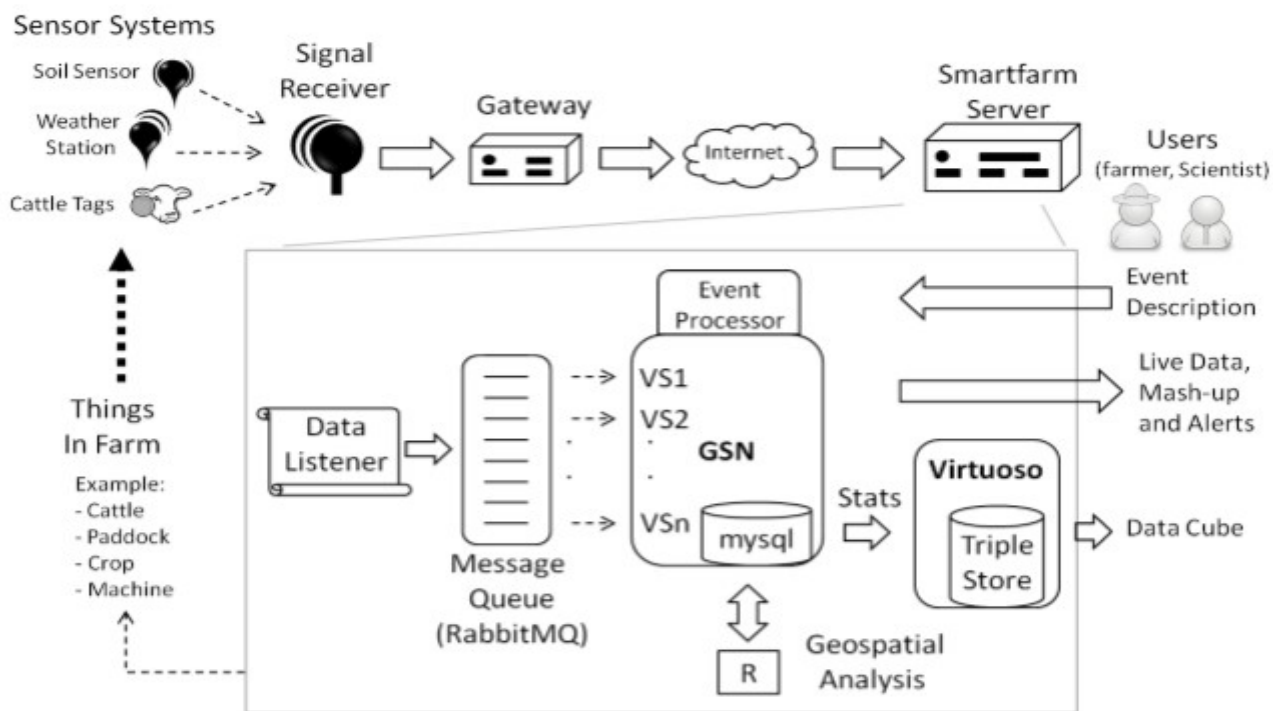
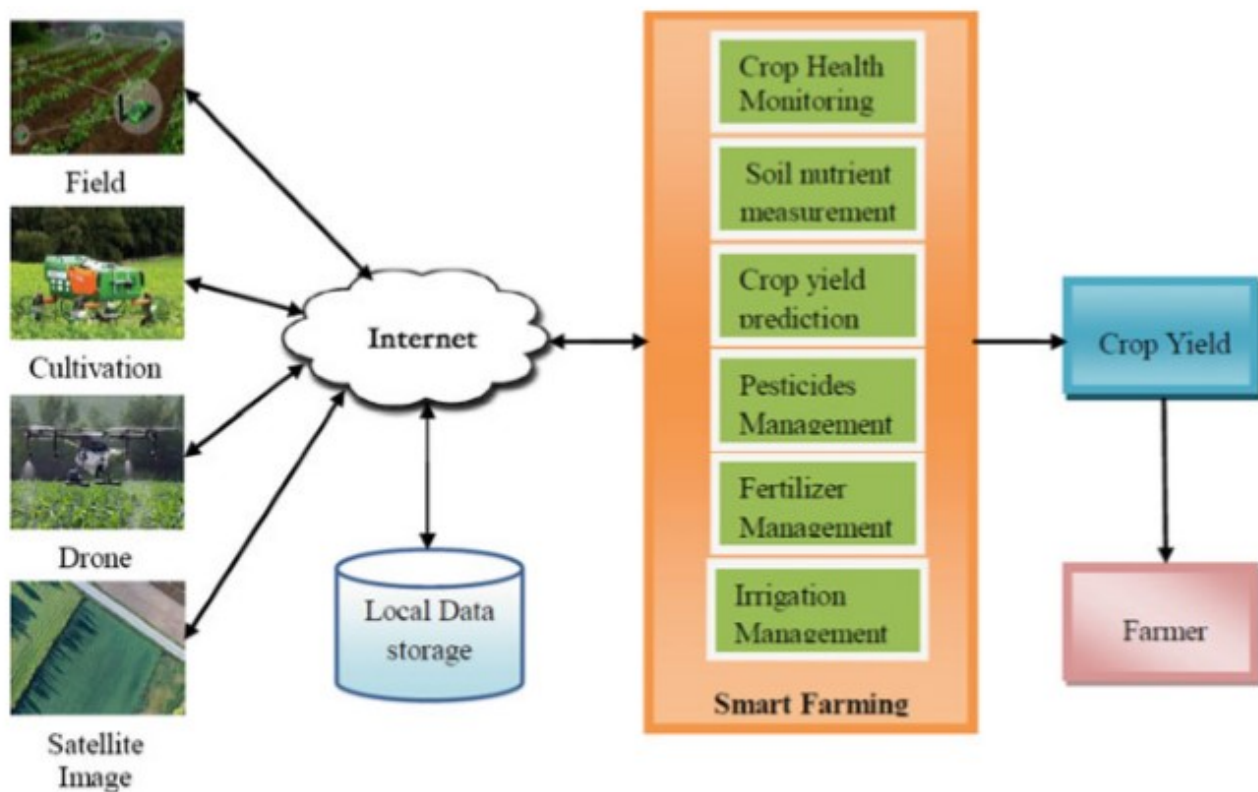


Module-7- Applications of Embedded Systems

7.1 Role in Agriculture sector – Embedded Systems



The Smart Farm System Architecture



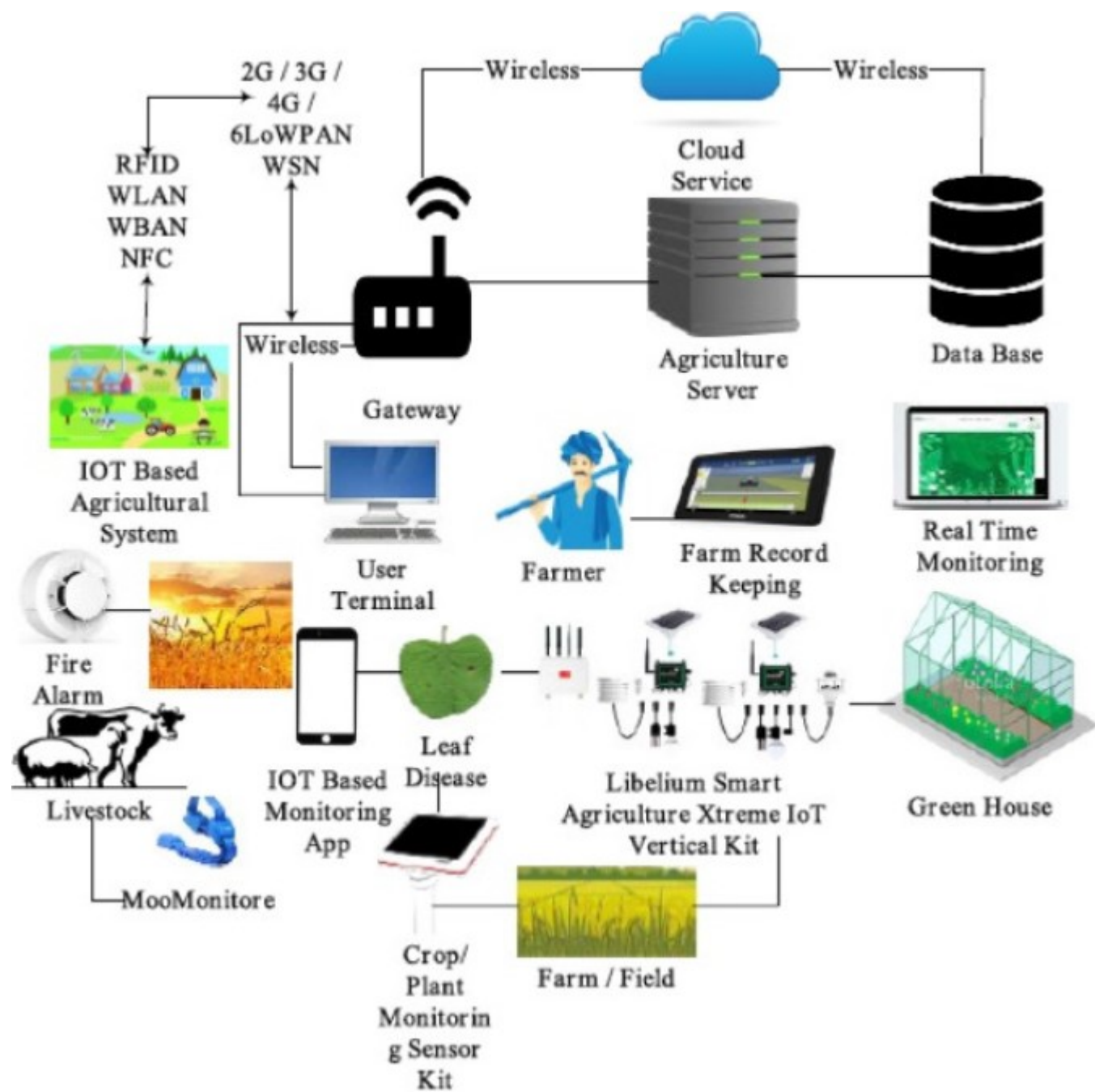
Smart farming architecture

SF technologies

| Technologies | Utility |
|--------------------------|--|
| Wireless sensor networks | Irrigation automation Environmental monitoring |
| Remote sensing | Evaluates the various levels of soil moisture and nutrients, crop health and disease through collected images |
| Variable rate technology | Apply seed or fertilizer based on soil nutrient |
| Artificial intelligence | Monitoring condition of crop Pest detection Crop disease identification Plant species classification |
| Mobile technology | Remote farm monitoring Farm equipment monitoring |
| Drone | Crop data generation and surveillance of cultivation lands Capturing site images Observes failure in crop plantation Autonomous pest identification Autonomous pesticides spraying |

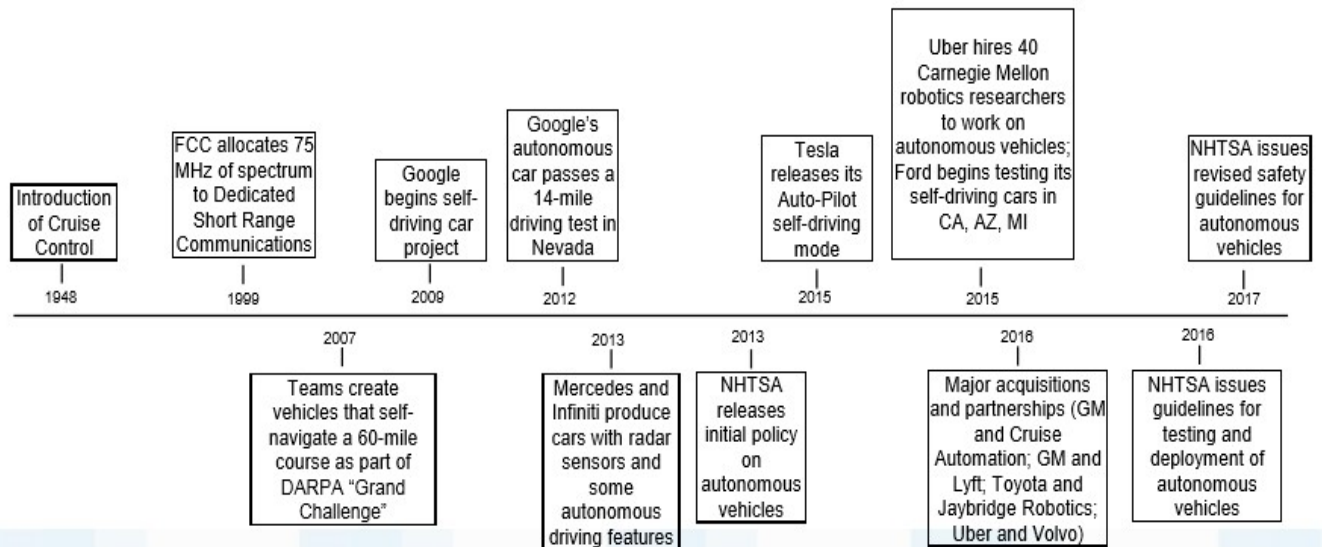
| Issues | Causes | Proposed measures |
|-----------------------|--|--|
| Energy consumption | Sensing Data processing Data transmission | Renewable energy Solar power Kinetic energy |
| Data collection | Sensing of data | Aggregation Compression |
| Transmission range | Ecological effect | Multi-tire Ad hoc network Mesh network |
| Data security | Spoofing Sinkhole Sybil Denial of service Jamming | Access control methods Anomaly detection techniques |
| Fault tolerance | Physical damage Power depletion Blockage Radio Inference Collision | Redundancy mechanism Clustering techniques |
| Sensor node placement | Size of sensor node | Deterministic deployment Random deployment |

Another example for Smart farming



7.2 Example - Automotive electronics - Case Study

History of Autonomous Vehicles



SAE Levels of Automation

SOCIETY OF AUTOMOTIVE ENGINEERS (SAE) AUTOMATION LEVELS

Full Automation



0

No Automation

Zero autonomy; the driver performs all driving tasks.



1

Driver Assistance

Vehicle is controlled by the driver, but some driving assist features may be included in the vehicle design.



2

Partial Automation

Vehicle has combined automated functions, like acceleration and steering, but the driver must remain engaged with the driving task and monitor the environment at all times.



3

Conditional Automation

Driver is a necessity, but is not required to monitor the environment. The driver must be ready to take control of the vehicle at all times with notice.



4

High Automation

The vehicle is capable of performing all driving functions under certain conditions. The driver may have the option to control the vehicle.

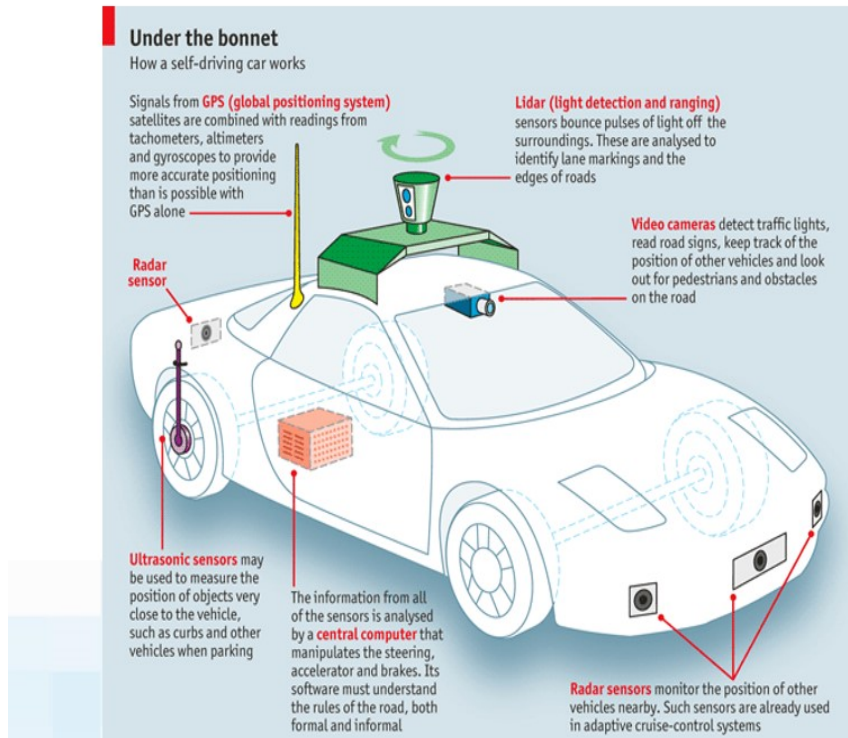


5

Full Automation

The vehicle is capable of performing all driving functions under all conditions. The driver may have the option to control the vehicle.

Basic Physical Ecosystem of an Autonomous Vehicle



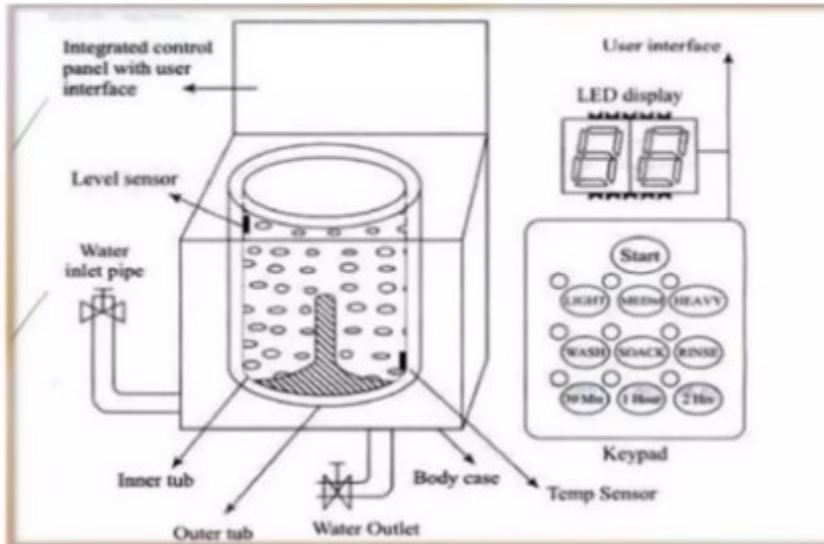
- Global Positioning System (GPS)
- Light Detection and Ranging (LIDAR)
- Cameras (Video)
- Ultrasonic Sensors
- Central Computer
- Radar Sensors
- Dedicated Short-Range Communications-Based Receiver (not pictured)

Key Physical Components of Autonomous Vehicles

- **Cameras** – Provide real-time obstacle detection to facilitate lane departure and track roadway information (like road signs).
- **Radar** – Radio waves detect short & long-range depth.
- **LIDAR** – Measures distance by illuminating target with pulsed laser light and measuring reflected pulses with sensors to create 3-D map of area.
- **GPS** – Triangulates position of car using satellites. Current GPS technology is limited to a certain distance. Advanced GPS is in development.
- **Ultrasonic Sensors** – Uses high-frequency sound waves and bounce-back to calculate distance. Best in close range.
- **Central Computer** – “Brain” of the vehicle. Receives information from various components and helps direct vehicle overall.
- **DRSC - Based Receiver** – Communications device permitting vehicle to communicate with other vehicles (V2V) using DSRC, a wireless communication standard that enables reliable data transmission in active safety applications. NHTSA has promoted the use of DSRC.

7.3 Example - Consumer Electronics – Case Study

BLOCK DIAGRAM



Smart Washing Machine



Advantages of Smart Washing Machines

Connectivity
Options



Sensor-based
Load Selection



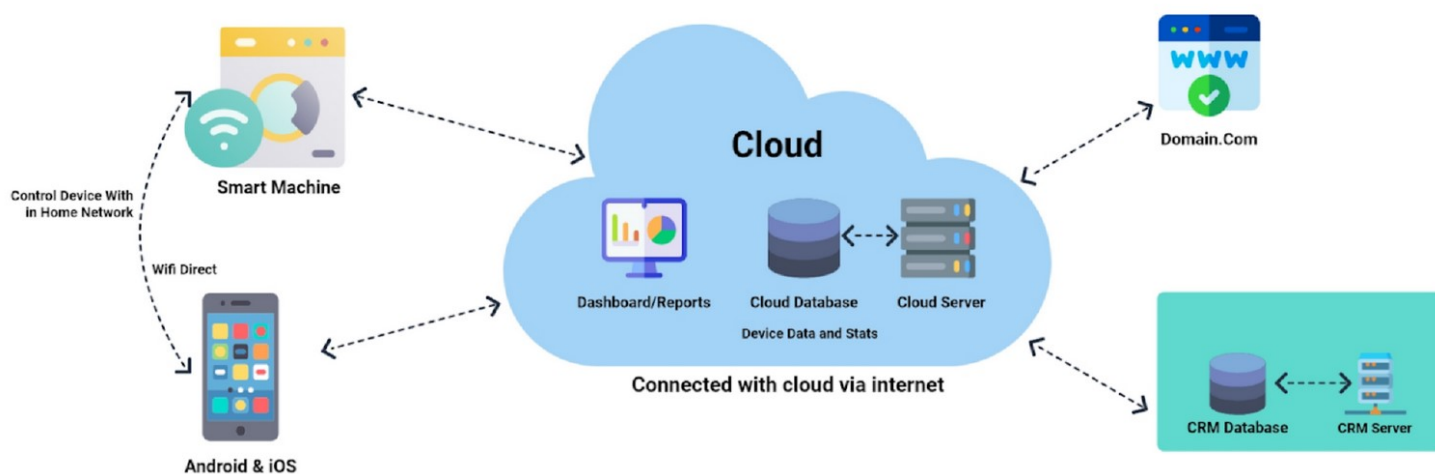
Minimize
Cycle Time



Effective
Wash Range

Consistent
Performance

Smart Washing Machine - System Architecture



7.4 Example – Industrial controls – Case Study

WHAT IS AN INSTRUMENTATION

Instrumentation is the science of applying devices and techniques to measure, display, and control plant process operation.



OBJECTIVES

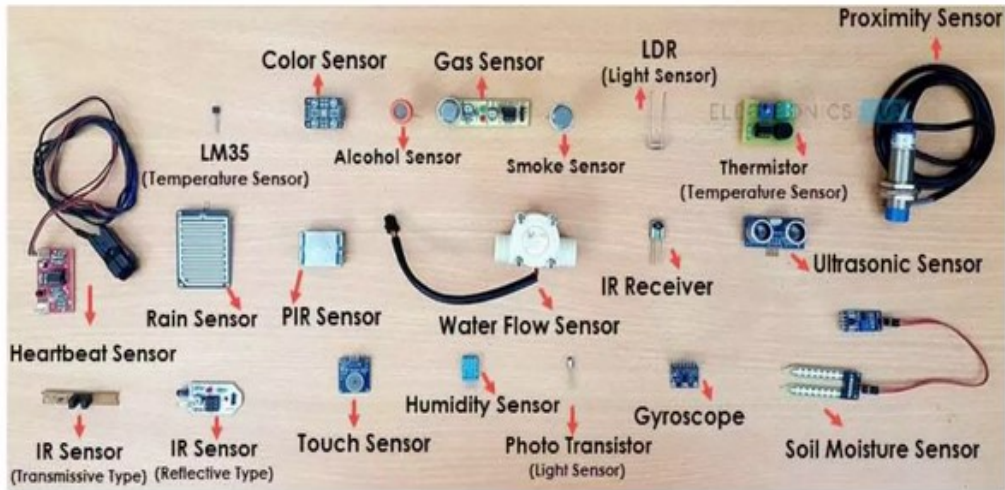
- Optimize process efficiency
- Produce a better product at lower cost in less time
- Provide safety systems for personnel, plant and processes
- Increase and control product quality
- Provide reliable data on raw material, product quantities and service related to process economics
- Provide timely and efficient control to avoid mishaps and to equipment and production loss

Few Industrial control Parameters

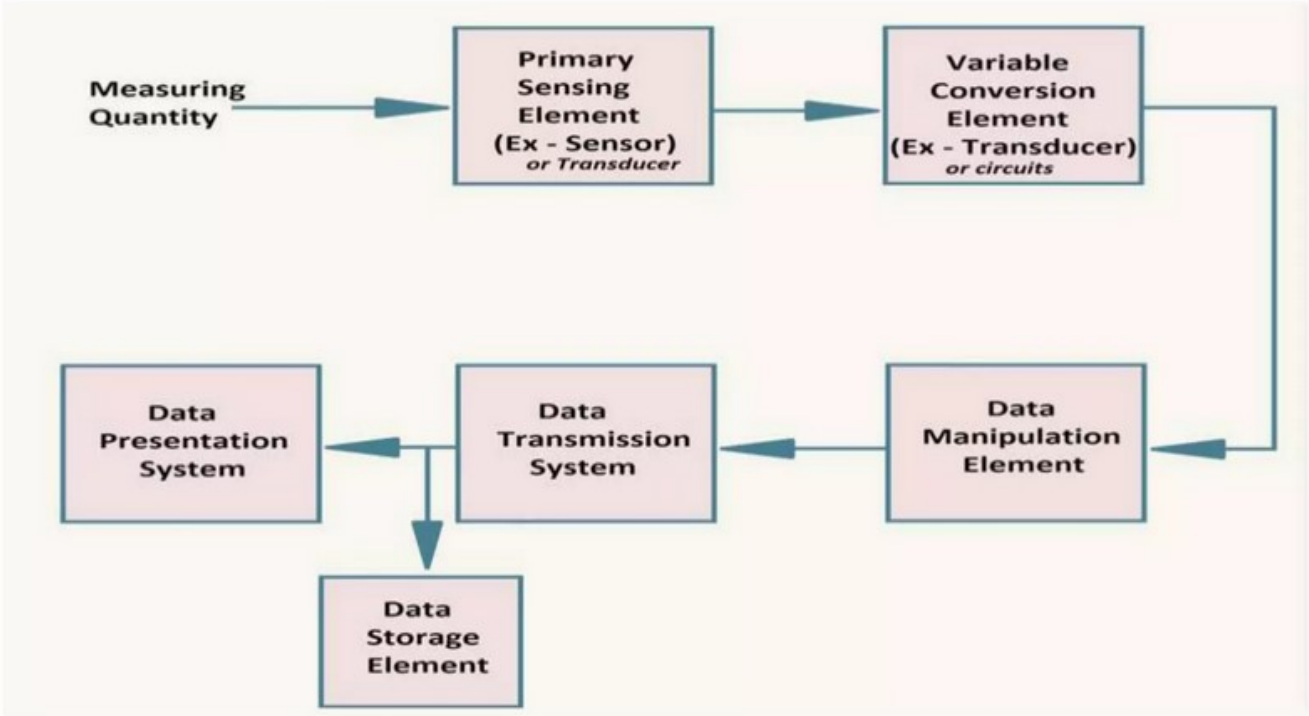
- | | |
|--|---|
| ➤ 1: Temperature measurement | ➤ 8: Final control Elements |
| ➤ 2: Pressure measurement | ➤ 9: Trend recorders and indicators |
| ➤ 3: Flow measurement | ➤ 10: Alarm Annunciation |
| ➤ 4: Level measurement | ➤ 11: Instrument control loops |
| ➤ 5: Analytical measurement | ➤ 12: Smart instrumentation |
| ➤ 6: Vibration and speed monitoring system | ➤ 13: PLC (programmable Logic Controller) |
| ➤ 7: Process Controller | ➤ 14: DCS (Distributed Control System) |

SENSORS

Sensors feel the condition and originate the signal followed by the modification and amplification for effective display/transmission or control objective.



FUNCTIONAL ELEMENT OF INSTRUMENTATION



7.5 Example – Industrial controls – Case Study

Medical embedded systems

- Pocket calculators
- Hearing aids
- Implantable pacemakers and cardiac defibrillators
- Portable equipment for physically challenged
- Wristwatches
- Wireless computing








Pacemaker from Medtronic inc.

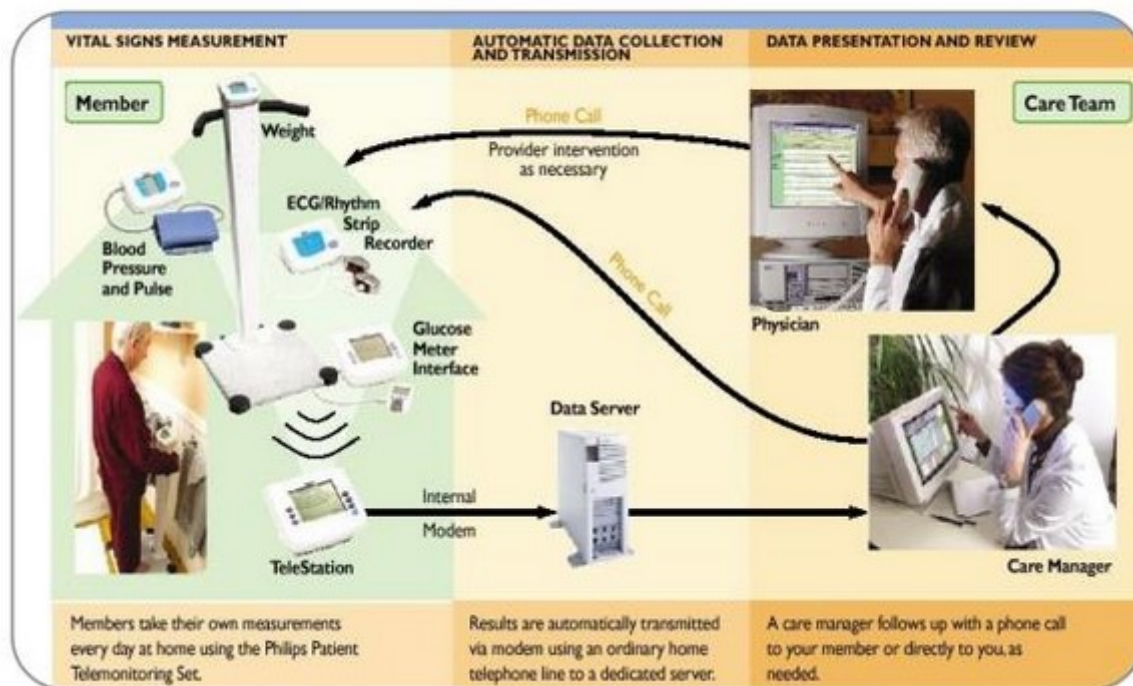


Portable defibrillator From Philips

Power needs are very different – one of the challenge

| | Power range | portability | Re charge | Life of device |
|---|--------------------------|---------------------------|----------------------------|----------------|
|  | 10 micro watts | Light weight and wearable | Possible but preferred not | 3-10 yrs |
|  | 10's of watts | Light weight and portable | Yes once in 24 hrs | 10 yrs |
|  | 100's of watts | yes | Yes once in 24 hrs | 10 yrs |
|  | 50 nano – 50 watts | Yes during use | Once after usage | 25 yrs |
|  | 50 nano to 10 mili watts | no | no | Min 10 years |

Remote Patient Management



Standards in Healthcare - Enabler

