Noise sampling

$$c_i \sim Unif[a, b]$$
$$\Sigma_i = c_i^2 I$$
$$\nu_i \sim N(0, \Sigma_i)$$

$+\nu_i$

Perturbation

$f^{-1}(x_i + \nu_i | c_i)$

Conditional Flow

Data dist.

Perturbed data dist.

Latent space