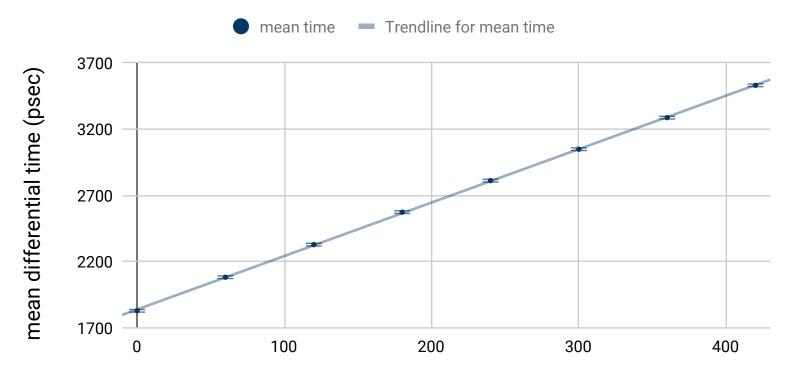
## differential time vs. parallel position



position (motor encoder units)