



# Putting plate kinematics to good use

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# What are the rules ?

Plate boundaries: 3 types

Ridges: plates moving apart

Spreading is typically symmetric

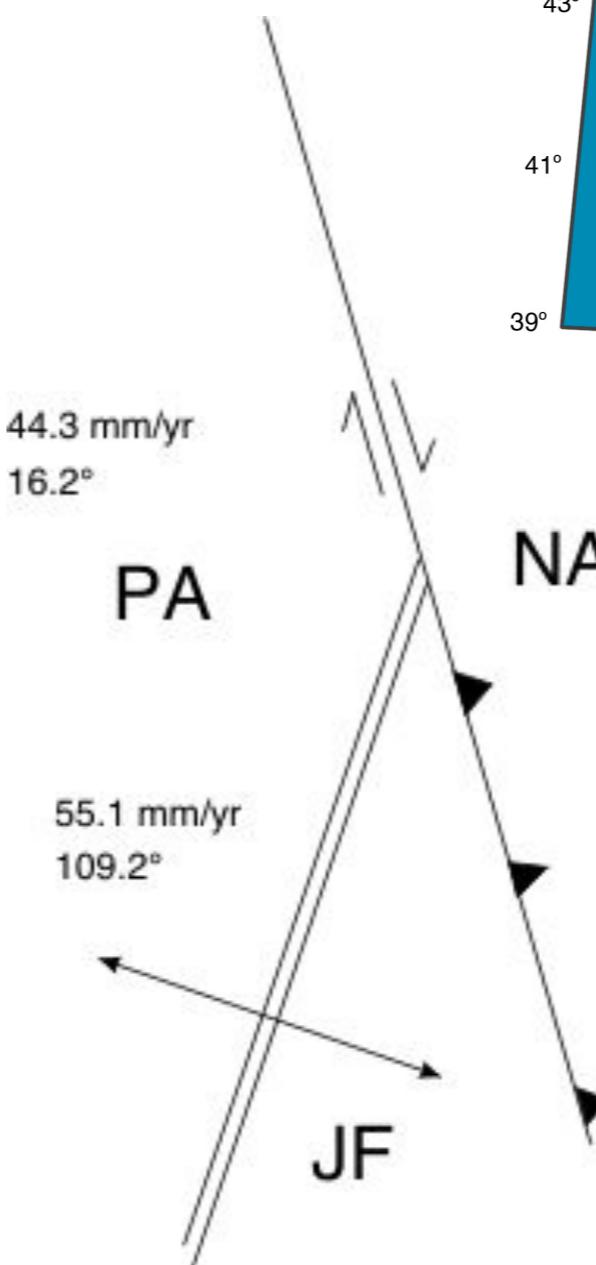
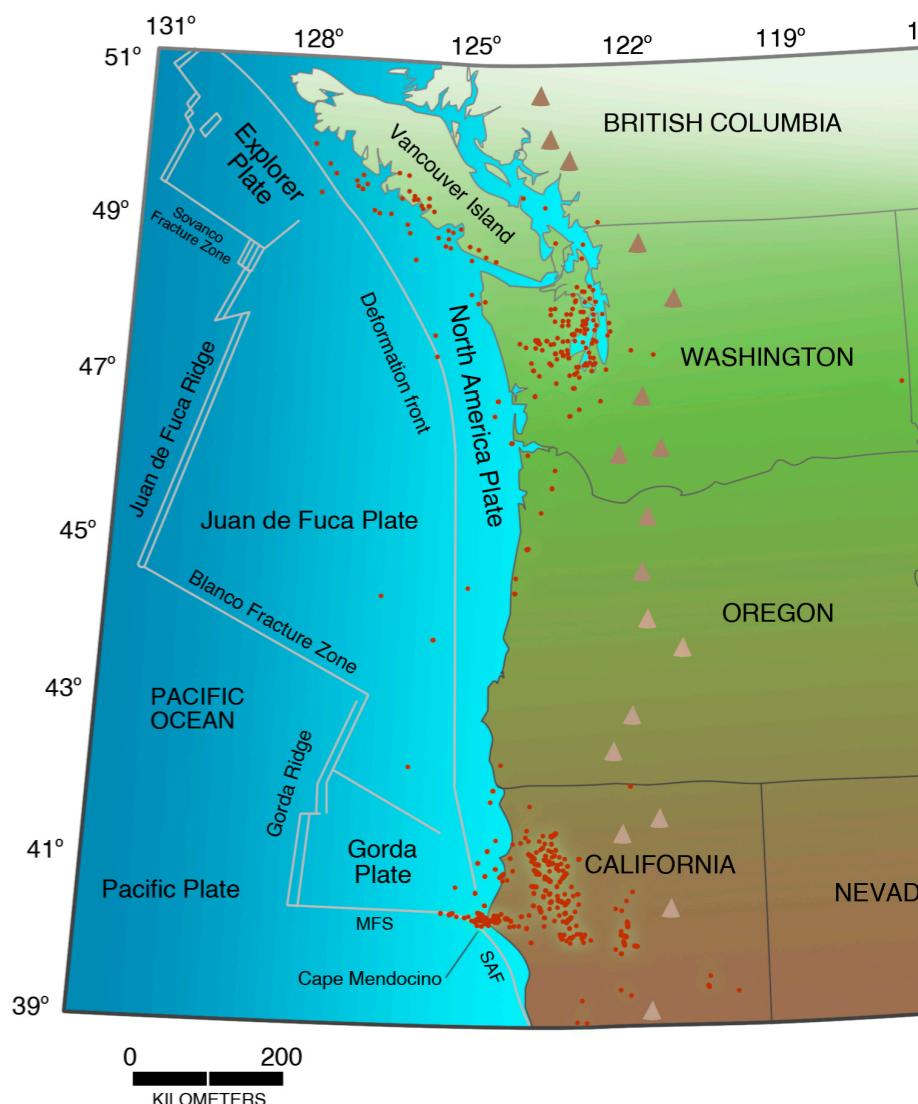
Spreading is typically orthogonal

Trenches: plates converging

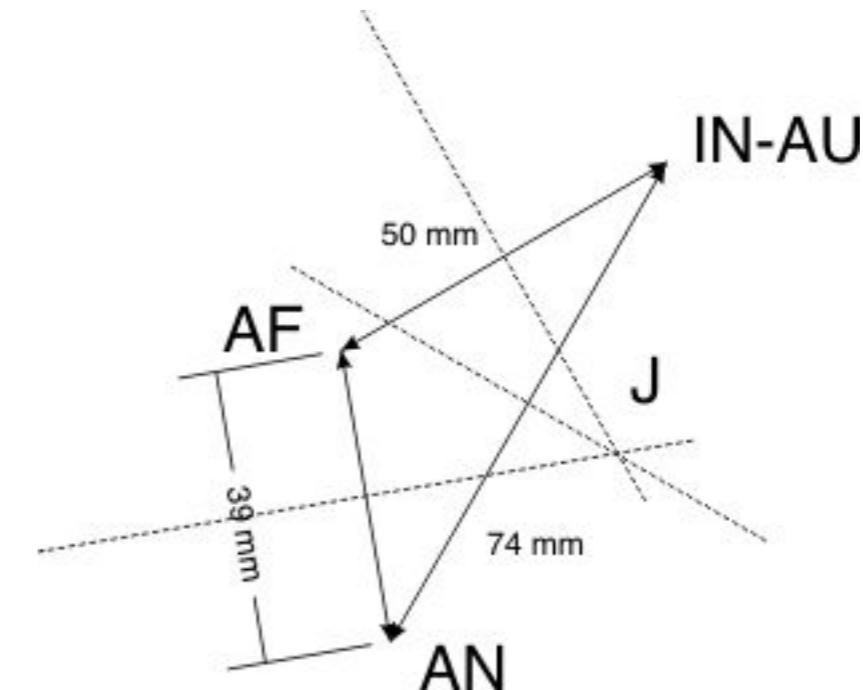
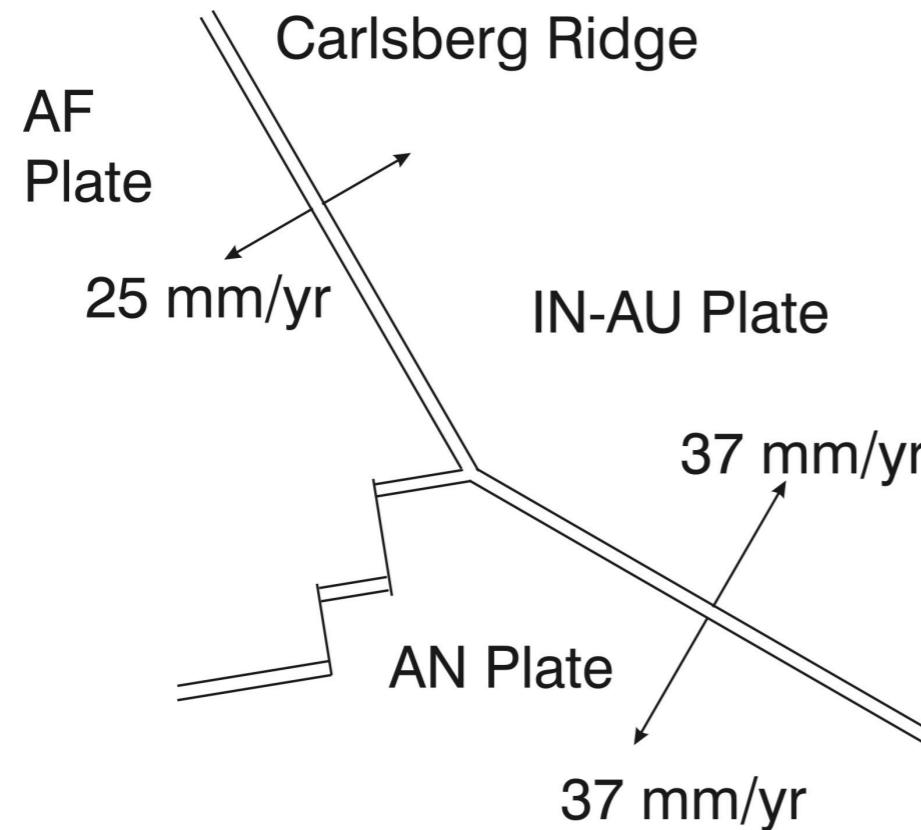
Subduction is highly asymmetric

Subduction is not usually  
orthogonal

Transform faults: motion parallel to  
boundary



# Triple junctions

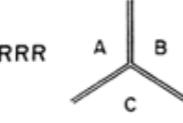
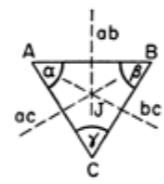
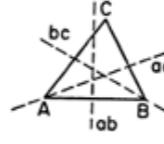
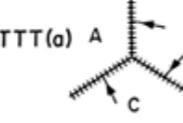
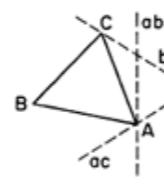
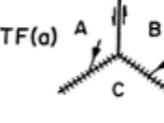
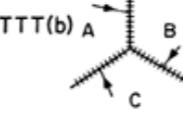
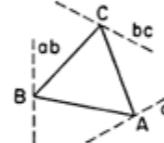
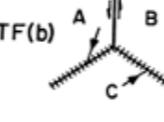
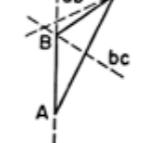
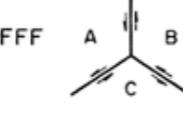
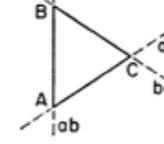
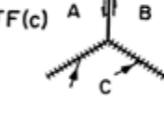
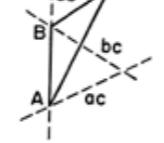
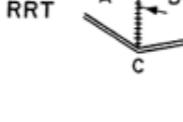
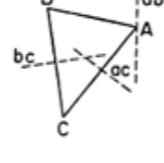
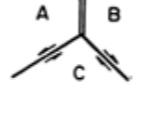
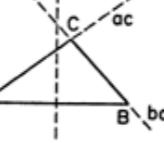
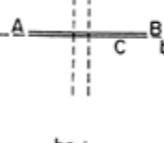
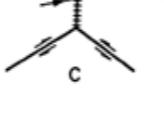
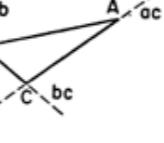
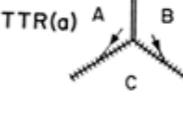
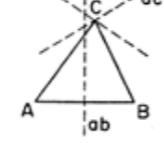
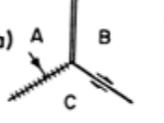
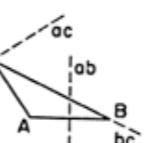
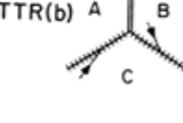
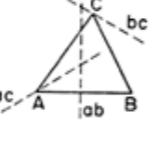
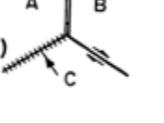
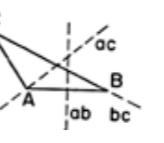


Triple junctions are places where three plates (and three boundaries) meet. E.g. at a ridge-ridge-ridge junction all the plates are separating, and all three are moving relative to the junction itself.

How do we calculate the velocity of the junction (over the "fixed" mantle) ?

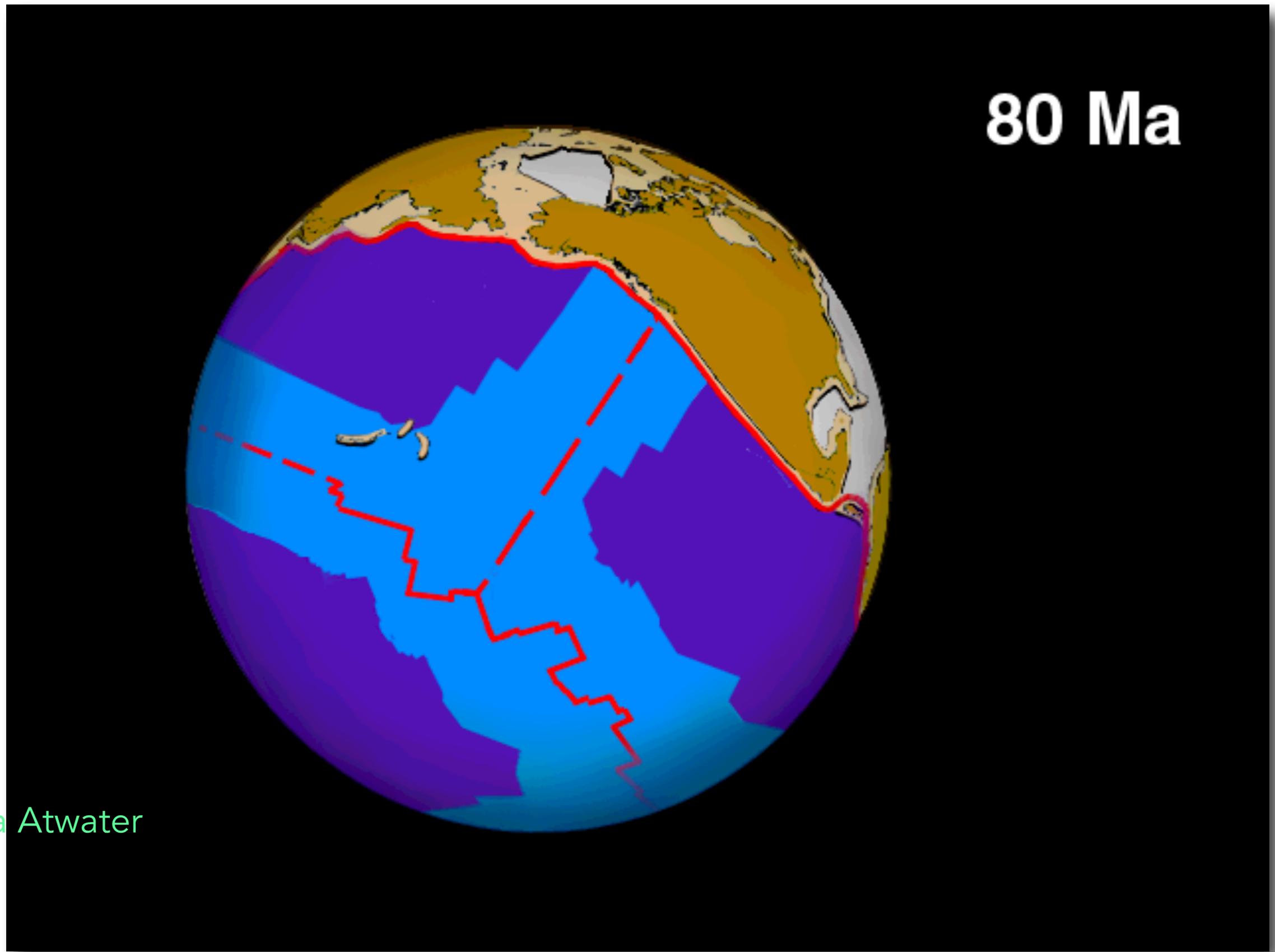
Note  ${}_A\mathbf{V}_B + {}_B\mathbf{V}_C + {}_C\mathbf{V}_A = 0$

# Triple junction rules can be complicated !

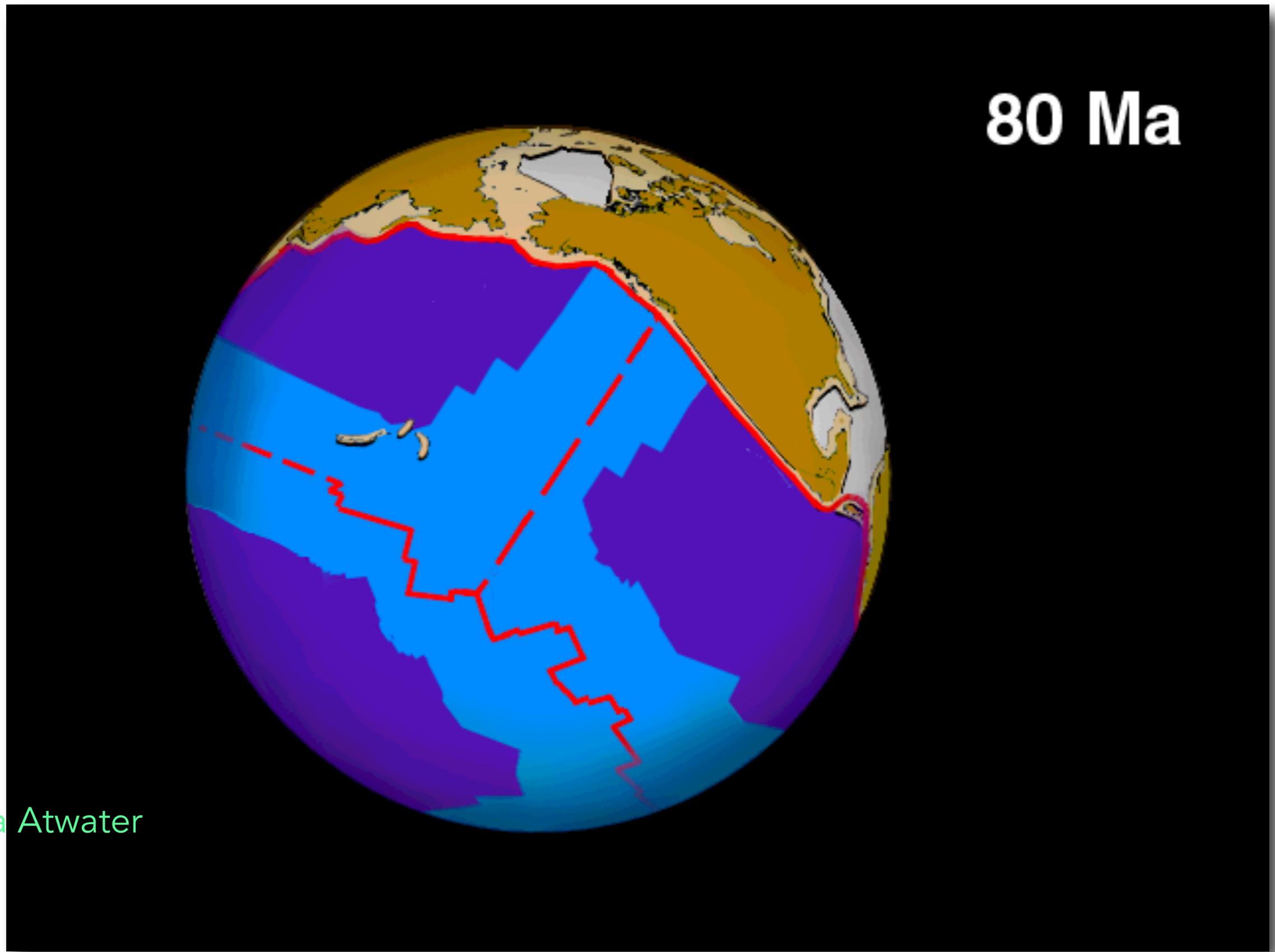
Type	Geometry	Velocity triangle	Stability	Examples	Type	Geometry	Velocity triangle	Stability	Examples
RRR			All orientations stable	East Pacific Rise and Galapagos Rift Zone <sup>17,18</sup> , Great Magnetic Bight <sup>19,20,22,23</sup>	TTR(c)			Stable if the angles between ab and ac, bc, respectively, are equal, or if ac, bc form a straight line	
TTT(a)			Stable if ab, ac form a straight line, or if bc is parallel to the slip vector CA	Central Japan <sup>3,21</sup>	TTF(a)			Stable if ac, bc form a straight line, or if C lies on ab	Intersection of the Peru-Chile trench and the West Chile Ridge <sup>10</sup>
TTT(b)			Stable if the complicated general condition for ab, bc and ac to meet at a point is satisfied		TTF(b)			Stable if bc, ab form a straight line, or if ac goes through B	
FFF			Unstable		TTF(c)			Stable if ab, ac form a straight line, or if ab, bc do so	
RRT			ab must go through centroid of ABC		FFR			Stable if C lies on ab, or if ac, bc form a straight line	Owen fracture zone and the Carlsberg Ridge <sup>24,25</sup> , West Chile Ridge and the East Pacific Rise <sup>10,26</sup>
RRF			Unstable, evolves to FFR		FFT			Stable if ab, bc form a straight line, or if ac, bc do so	San Andreas fault and Mendocino fracture zone <sup>3,4</sup>
TTR(a)			Stable if ab goes through C, or if ac, bc form a straight line		RTF(a)			Stable if ab goes through C, or if ac, bc form a straight line	Mouth of the Gulf of California <sup>3,27</sup>
TTR(b)			Stable if complicated general conditions are satisfied		RTF(b)			Stable if ac, ab cross on bc	

McKenzie  
& Parker  
1967

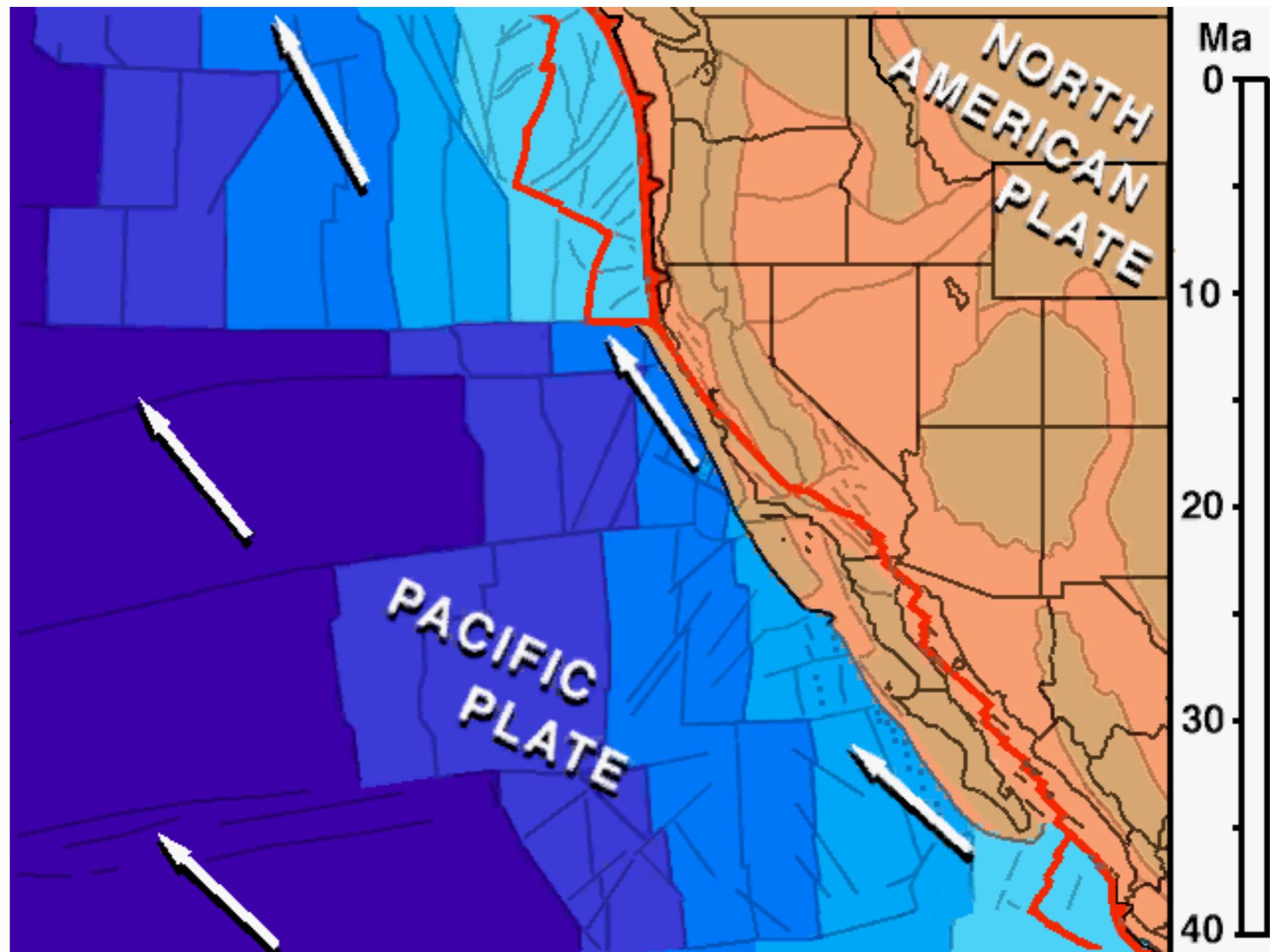
# Reconstructing past plates / boundaries



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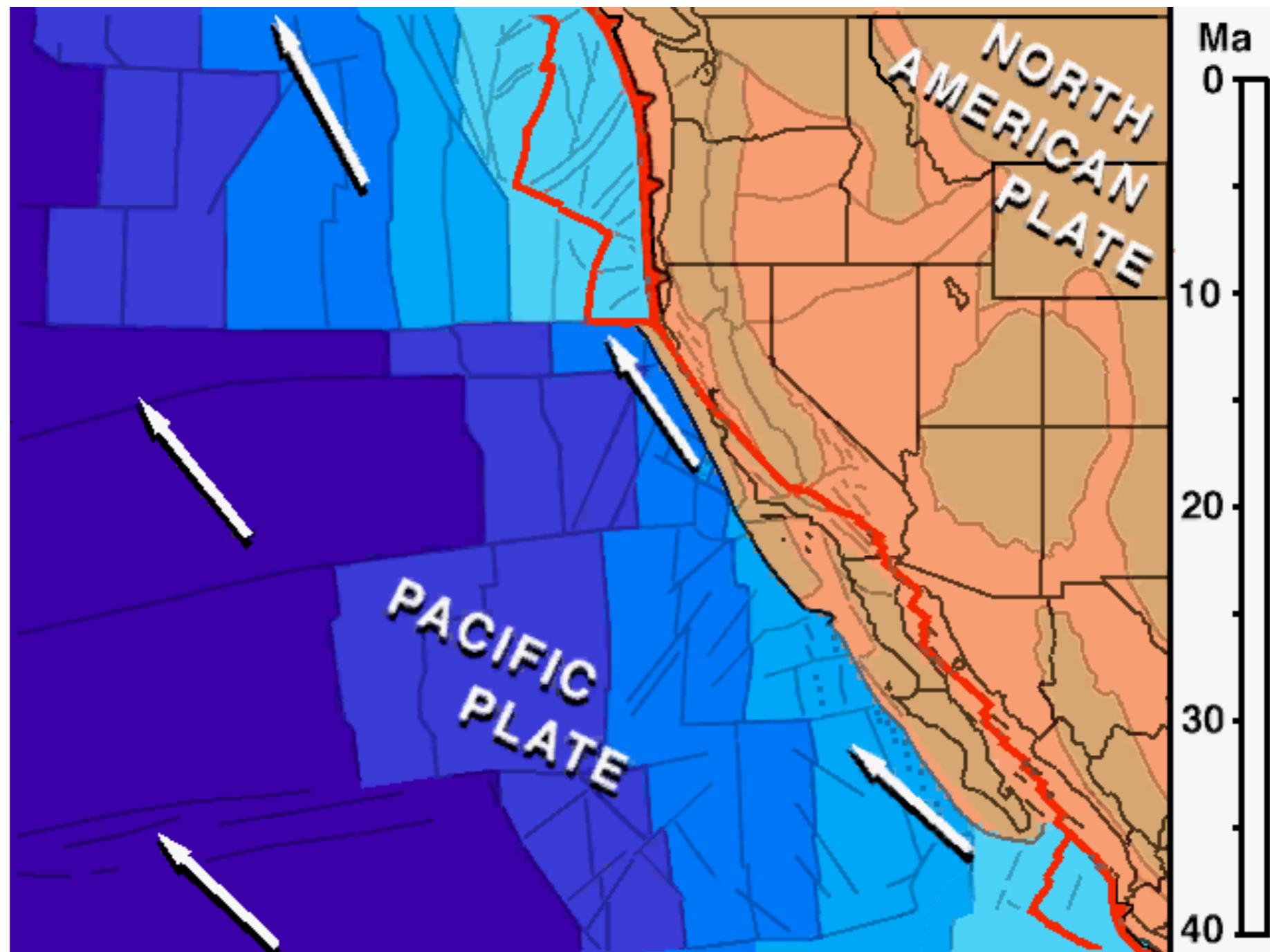
# Reconstructing past reconfigurations



How do we know there was a Farallon plate ?

When does the San Andreas fault system appear ?

# Reconstructing past reconfigurations



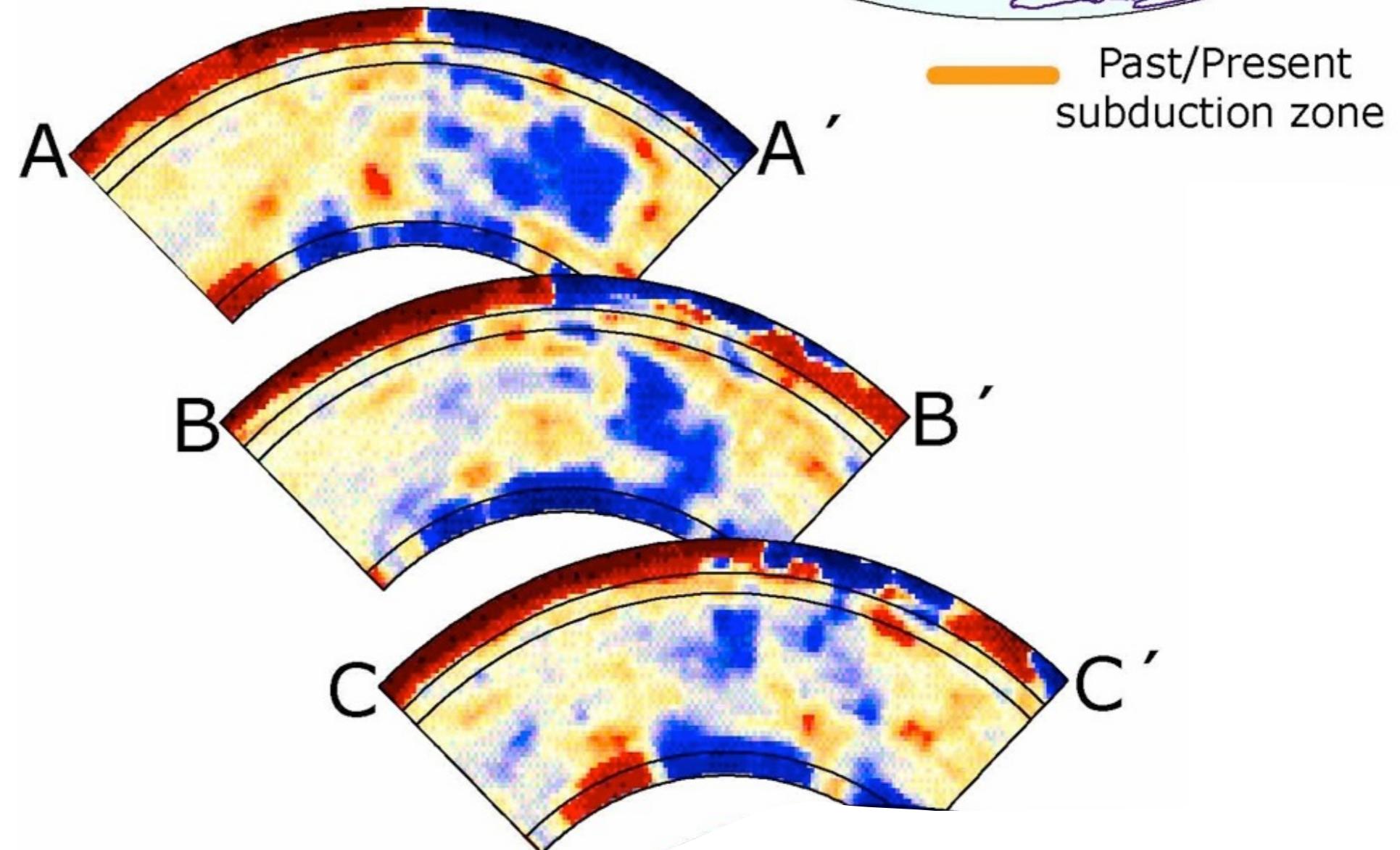
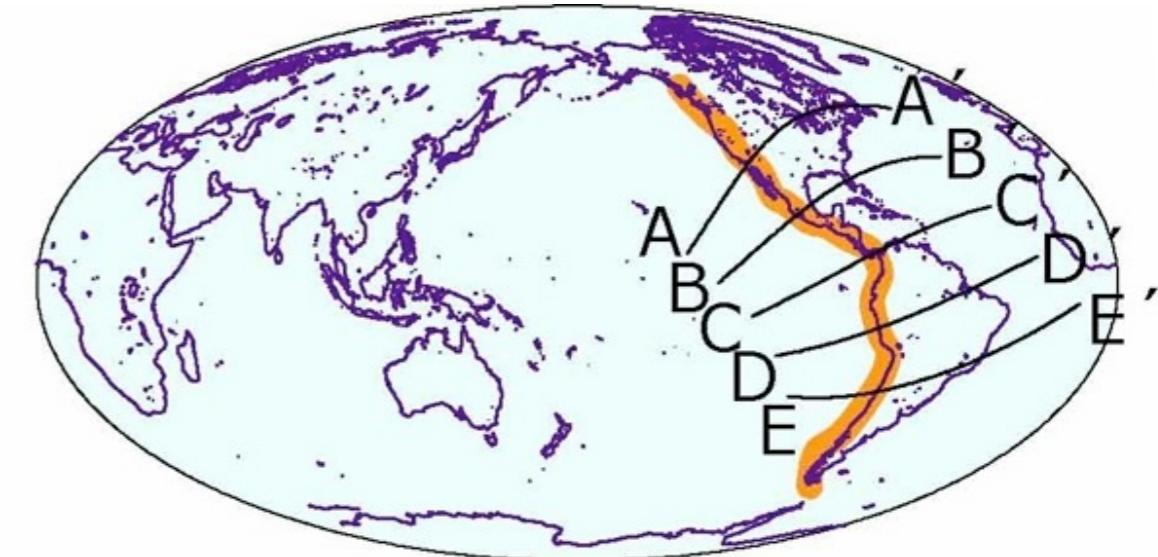
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# The Farallon slab

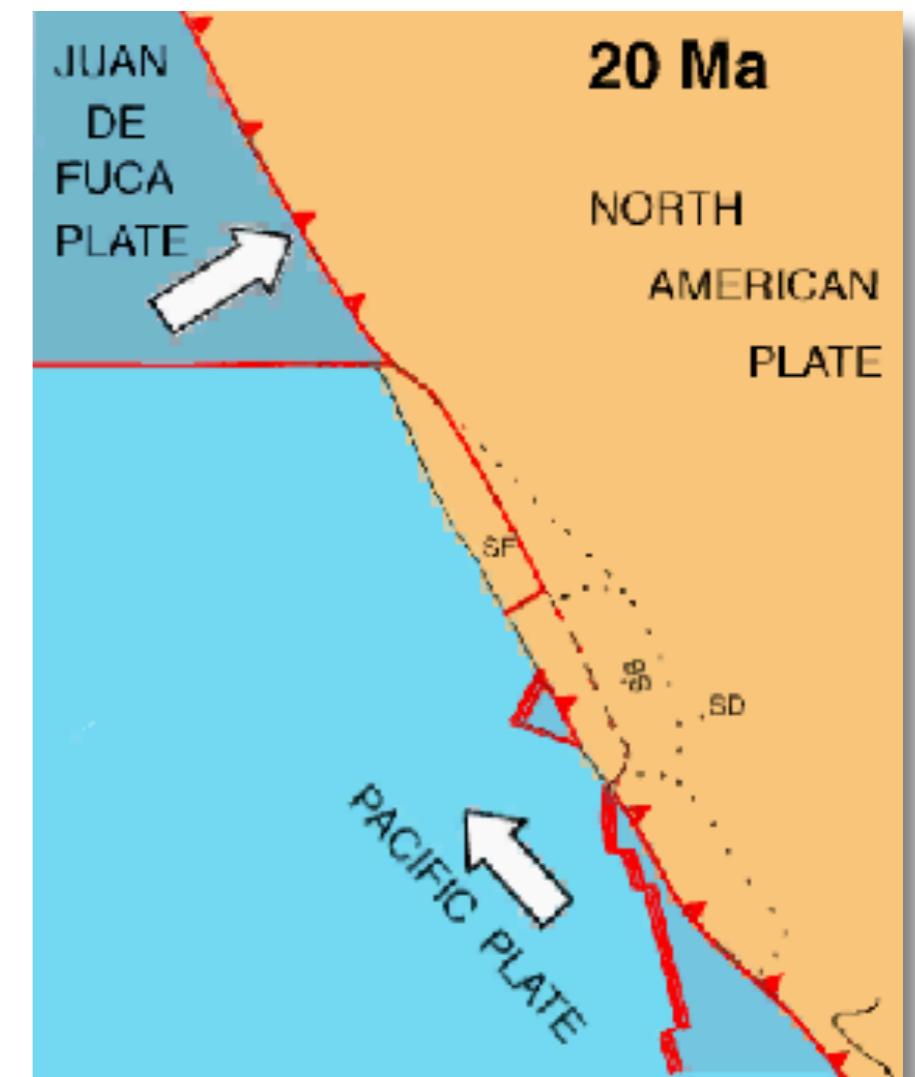
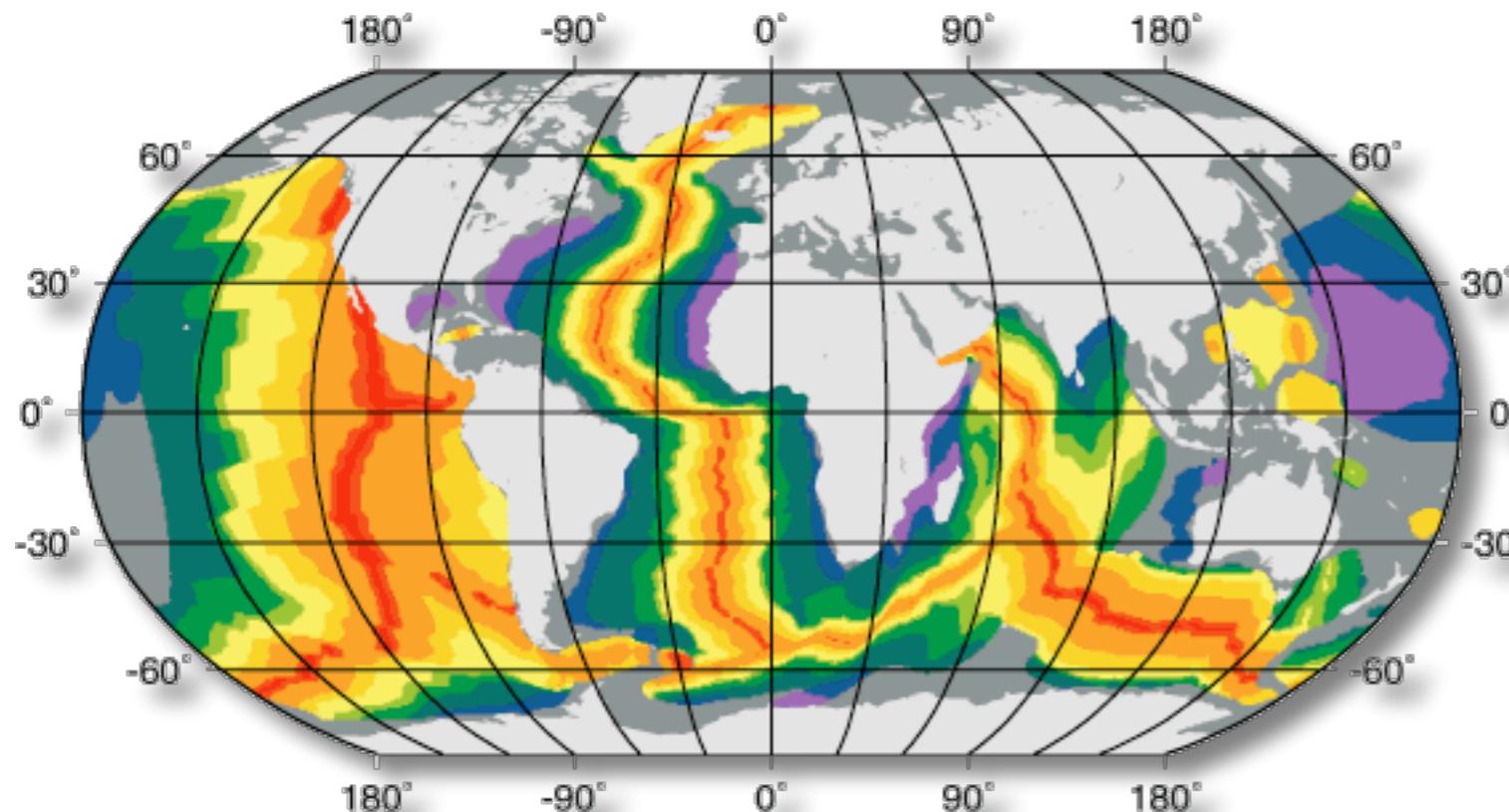
Still very obvious in tomographic images

- Clearly detached from surface where mid-ocean ridge was subducted



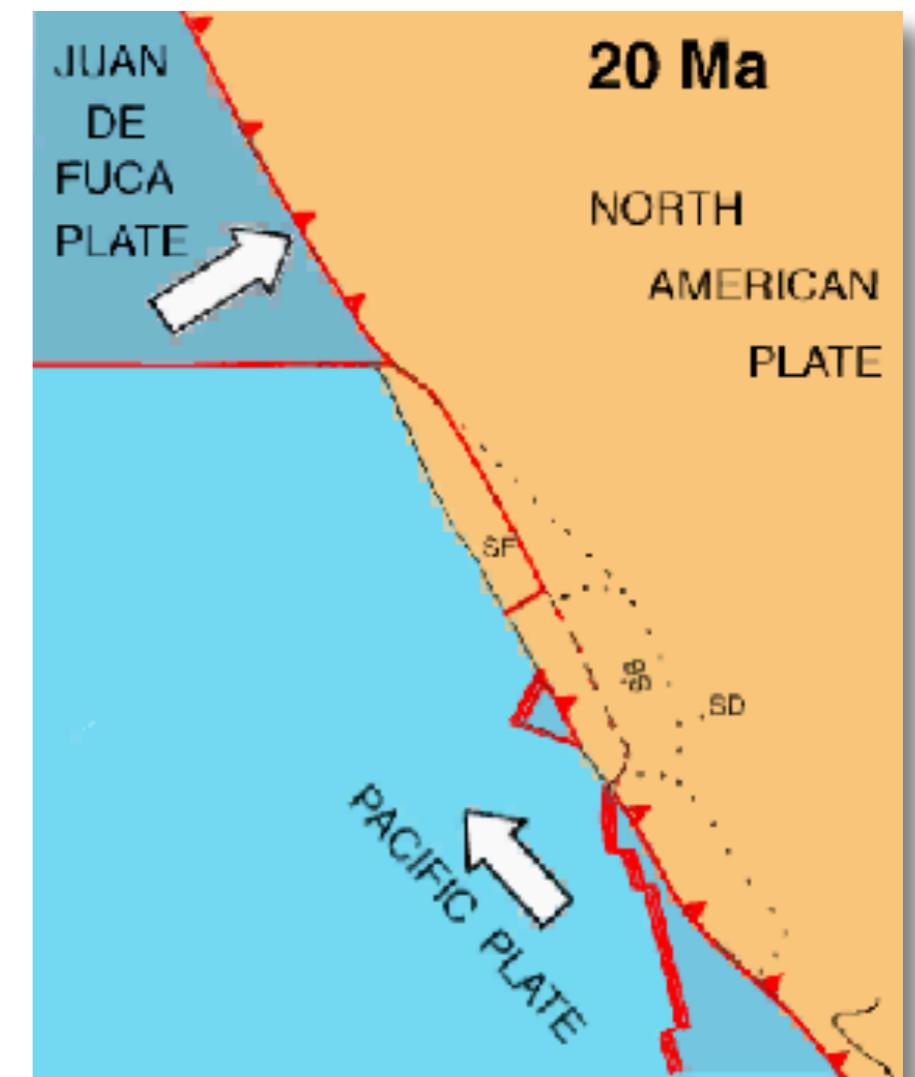
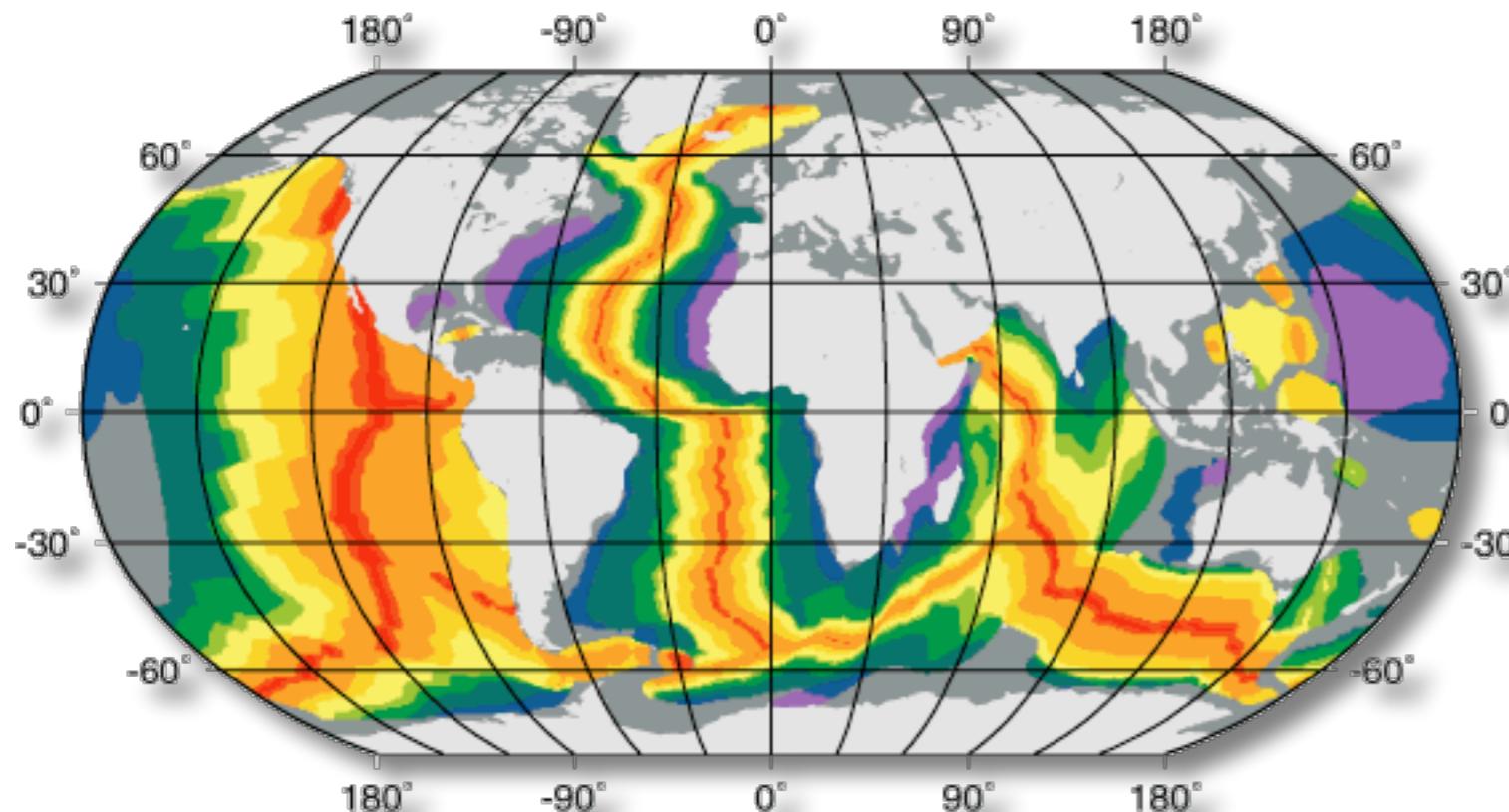
Past/Present  
subduction zone

# Plate boundary effects in the continent



The continental crust records the changes in the plate boundary but a lot more ambiguity than in the sea floor stripes

# Plate boundary effects in the continent

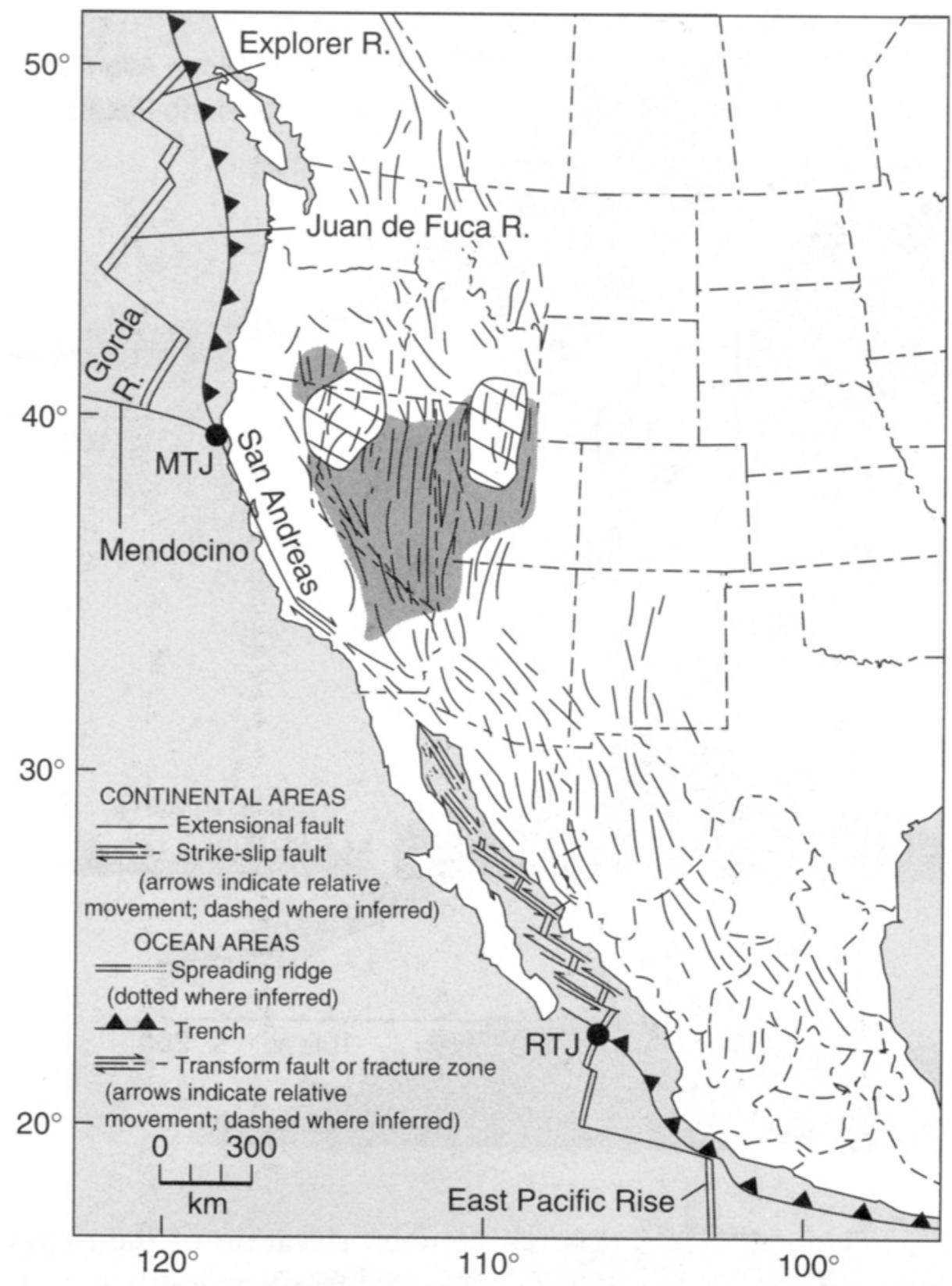
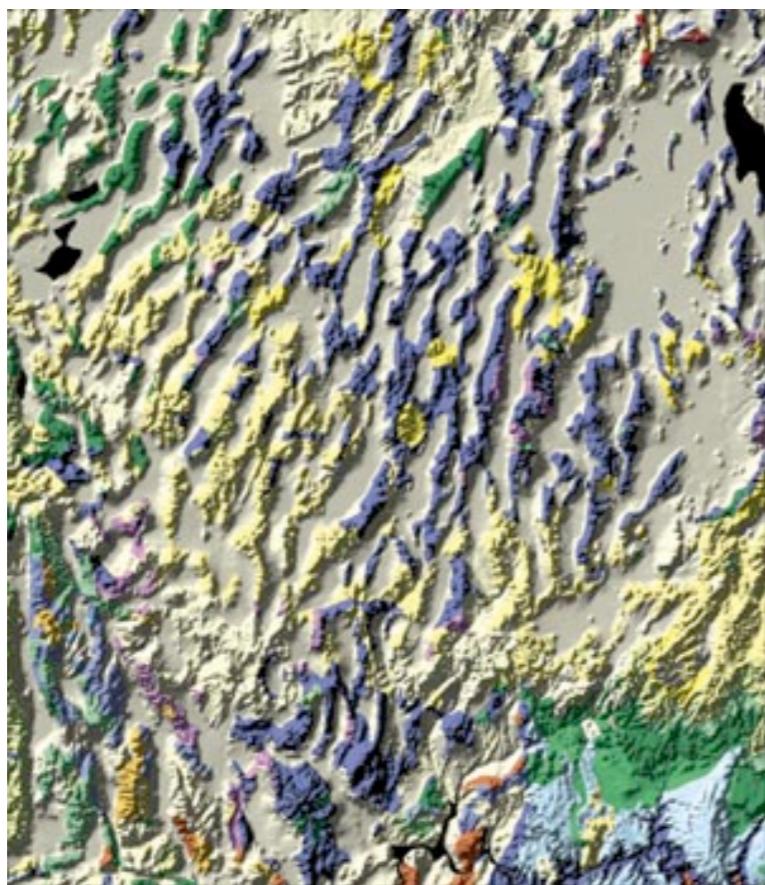


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# Basin and range

## Extensional tectonics

- Change of plate boundary forces
- Coupling to Pacific plate
- Slab detachment / thermal effects



Moores & Twiss, 1995

# Lava Lake Tectonics



- Note how spreading centres move across the lake as spreading progresses
- Different rates for different plates, rearrangements.

# Lava Lake Tectonics

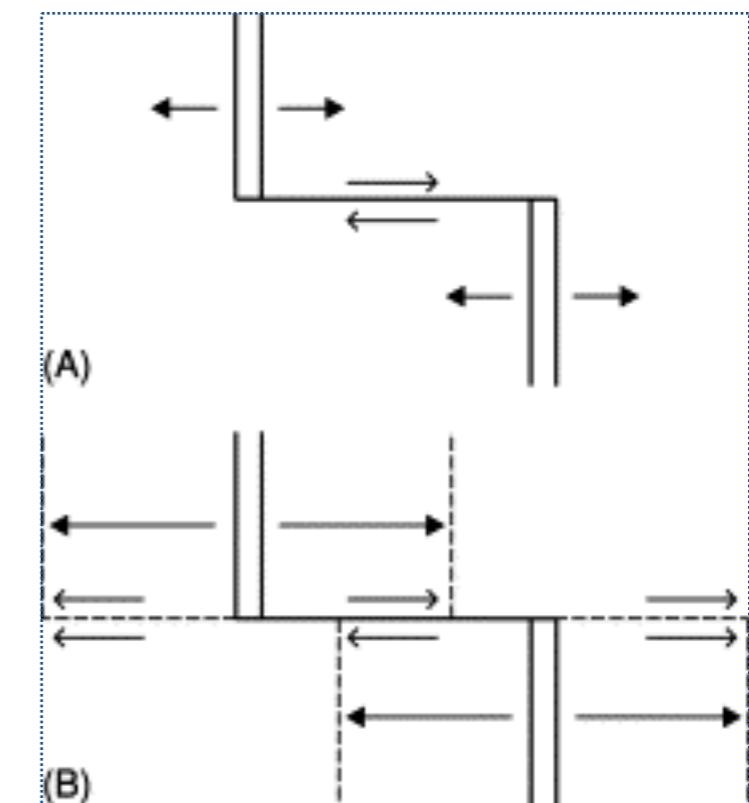
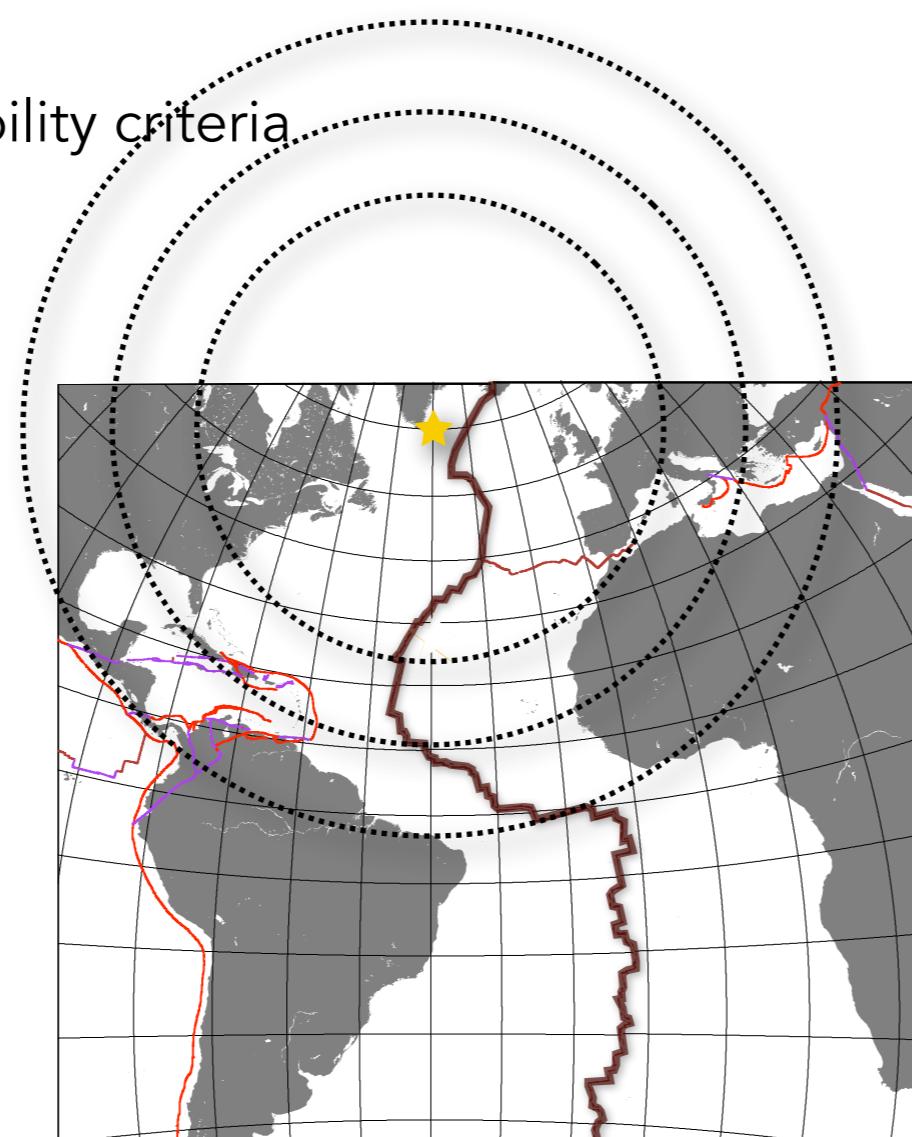


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- Different rates for different plates, rearrangements.

# How do we evolve plate boundaries ?

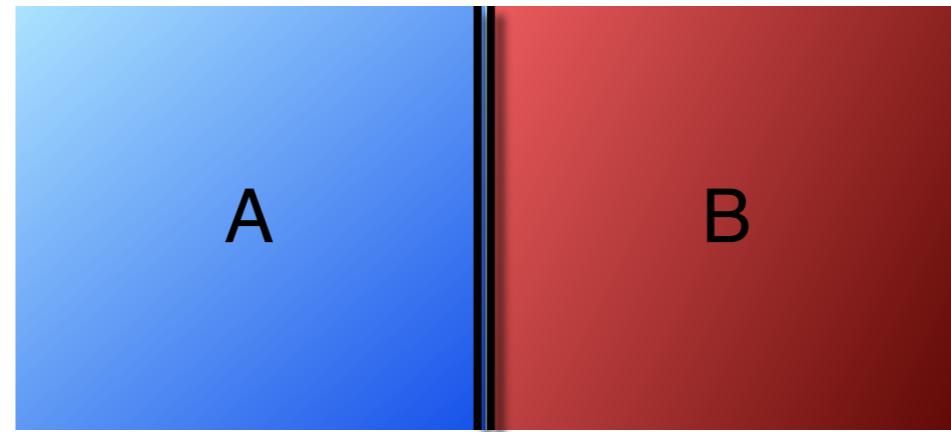
The “rules” of plate kinematics work well for oceanic plate boundaries under most circumstances.  
To apply them we need to look at:

- Relative nature of plate motion
- Addition of plate motion vectors
- Hotspot tracks
- Triple junctions & stability criteria

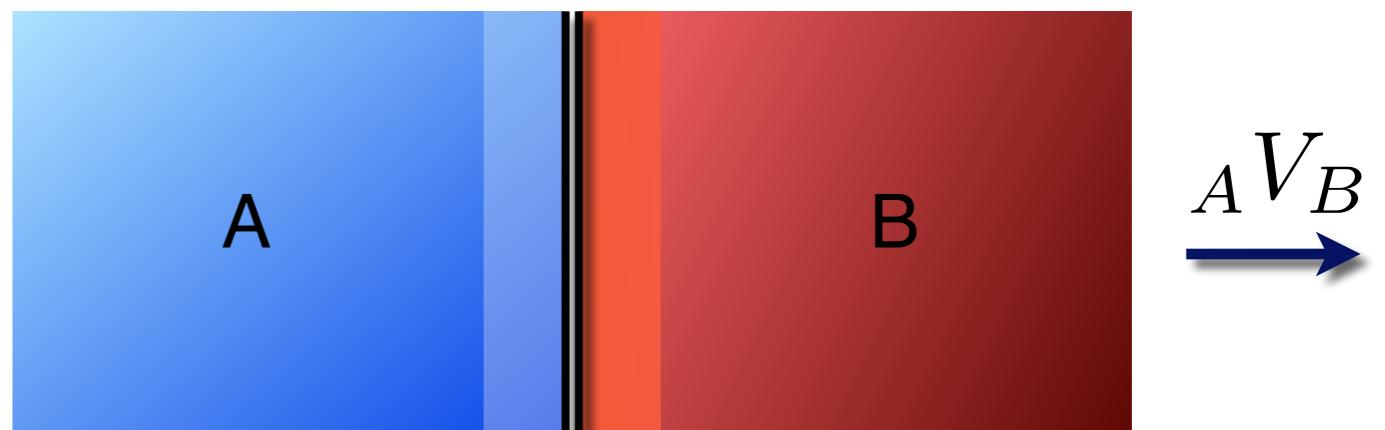


# Relative velocities

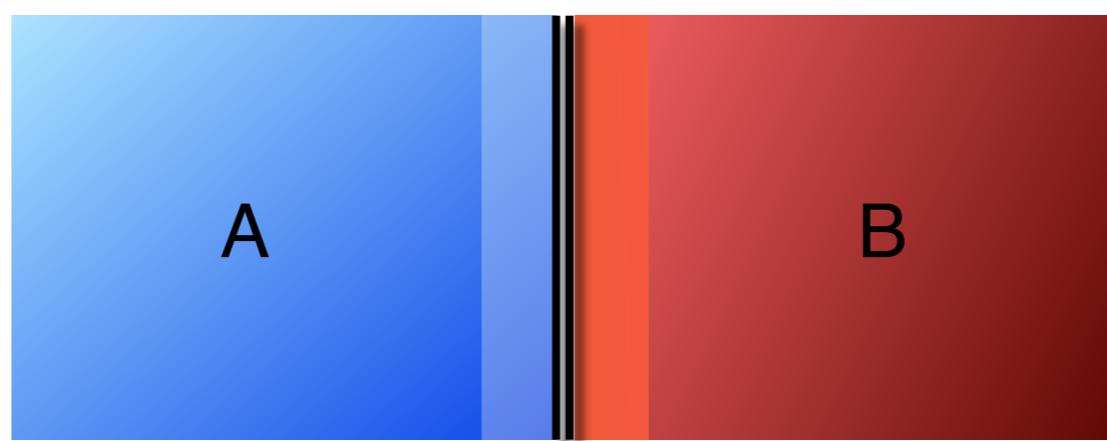
Today



Some time later...

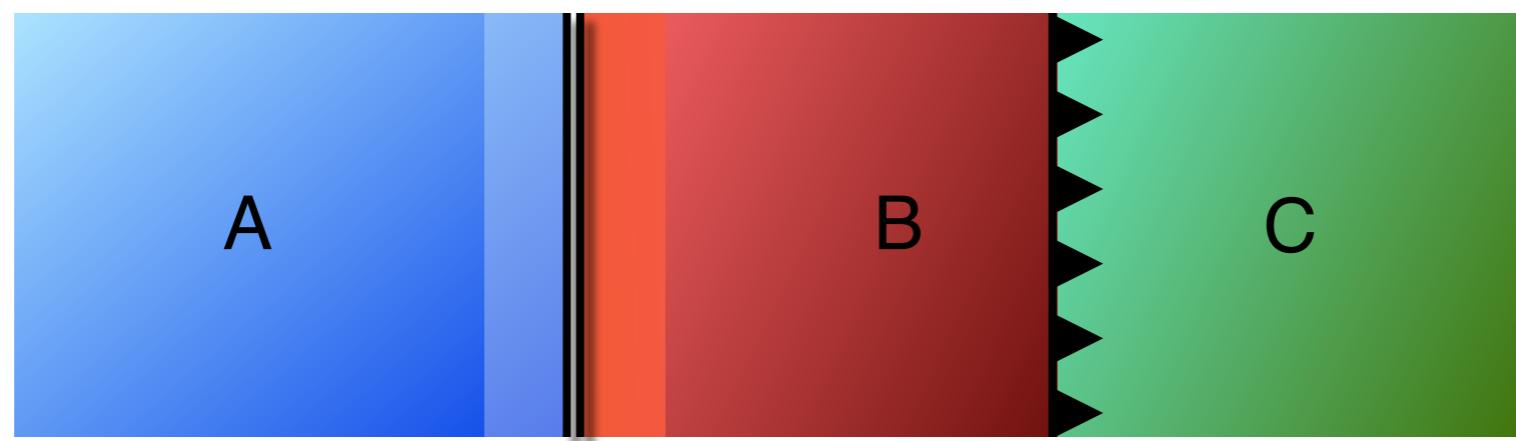
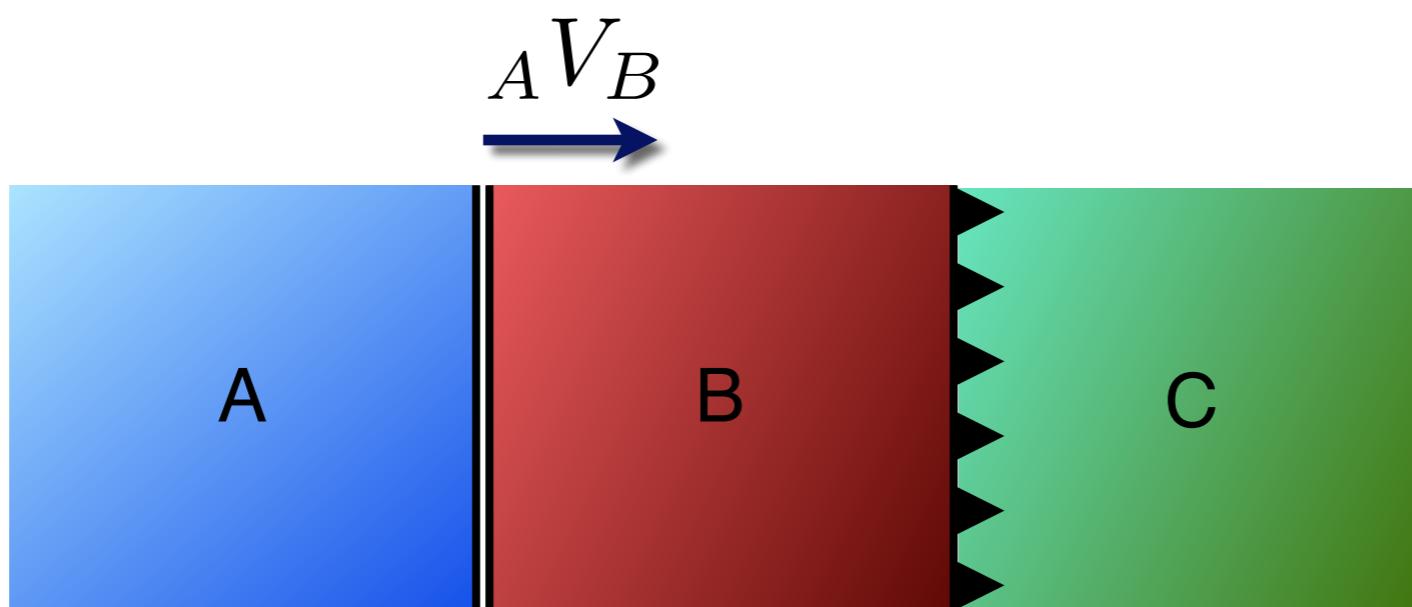


$$B V_A$$

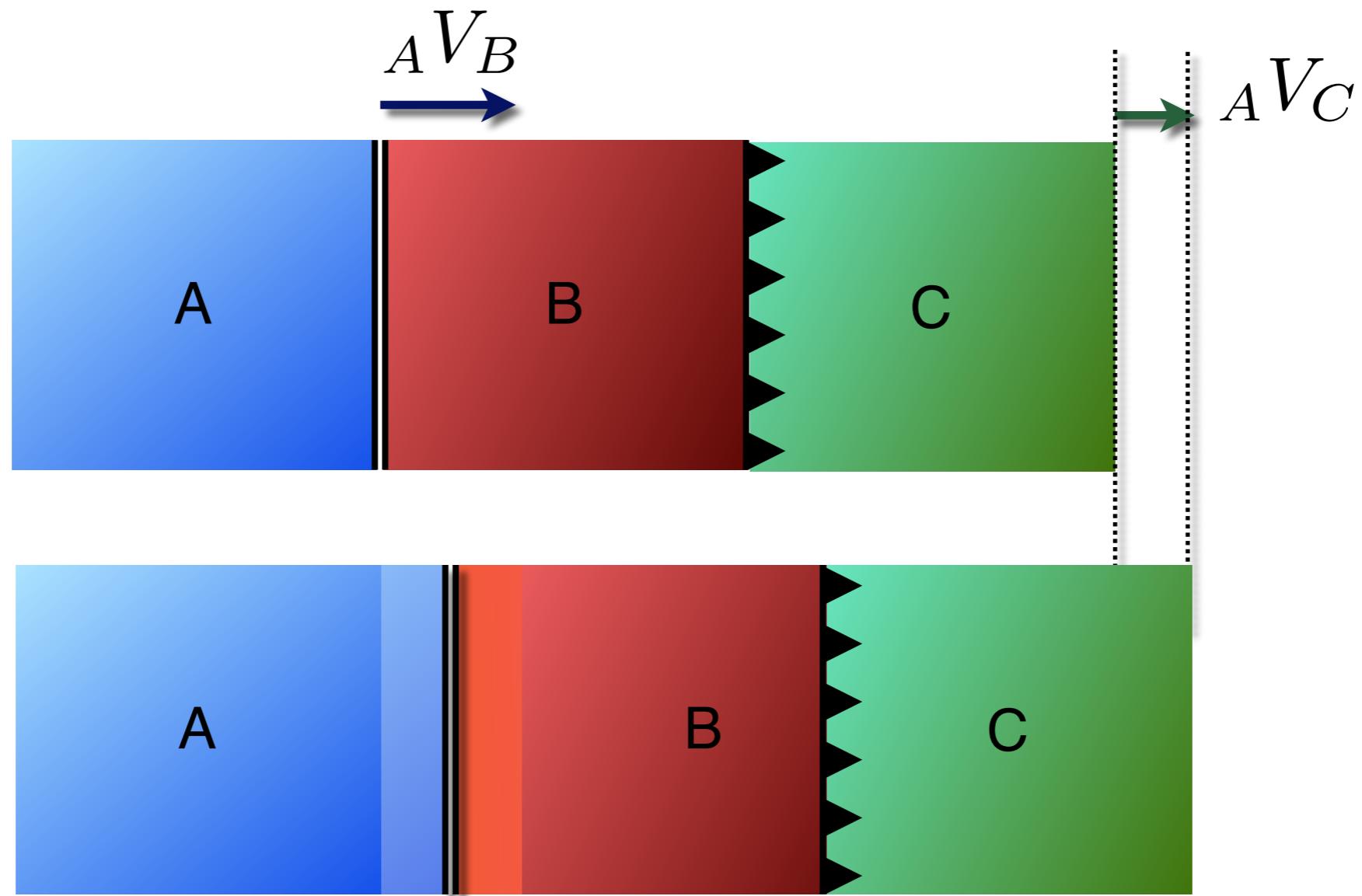


$$B V_A = -A V_B$$

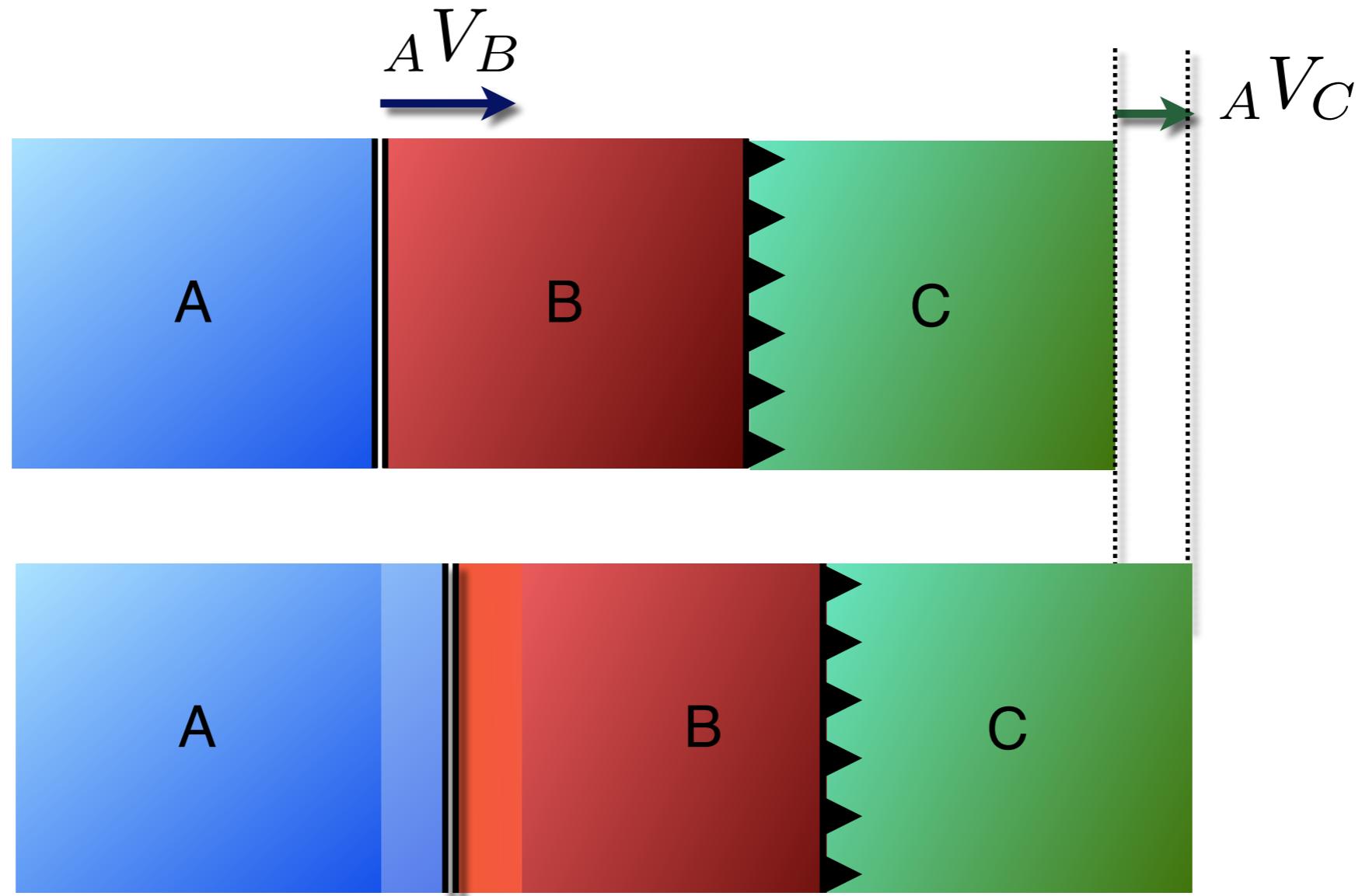
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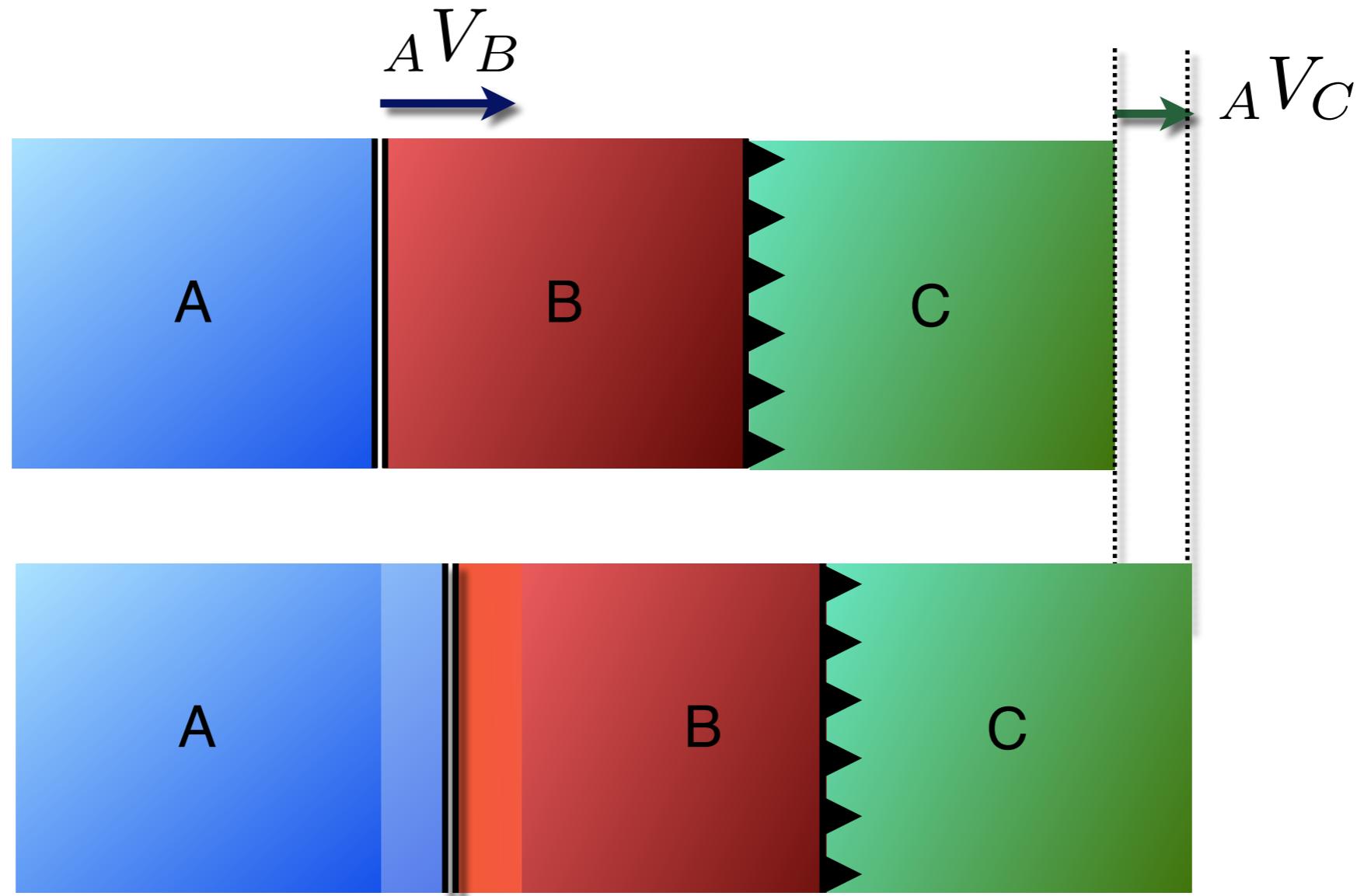
# Relative velocities



$${}_A V_C = {}_A V_B + {}_B V_C$$

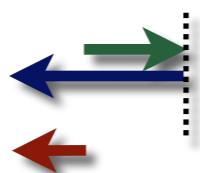
$${}_B V_C = {}_A V_C - {}_A V_B = {}_A V_C + {}_B V_A$$

# Relative velocities



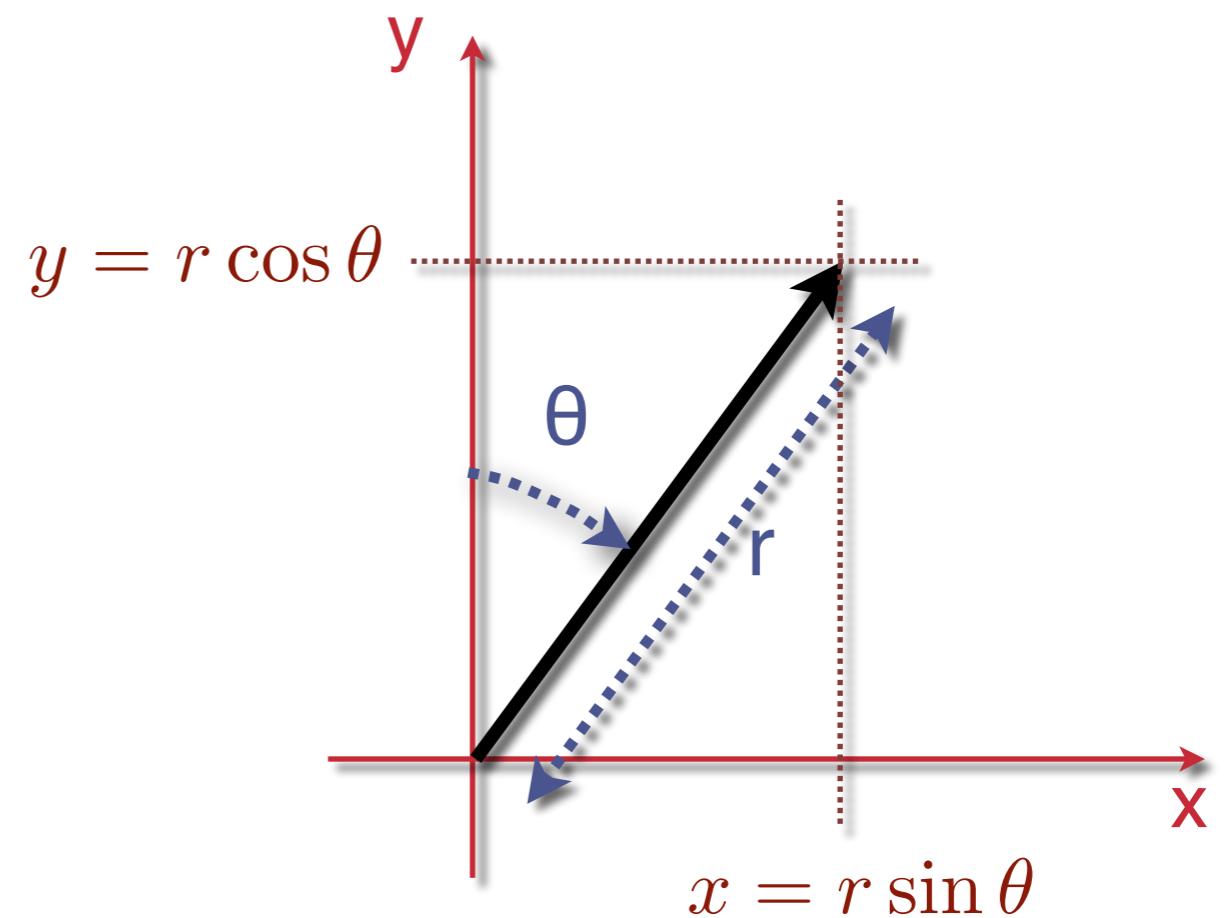
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## Detour — vectors

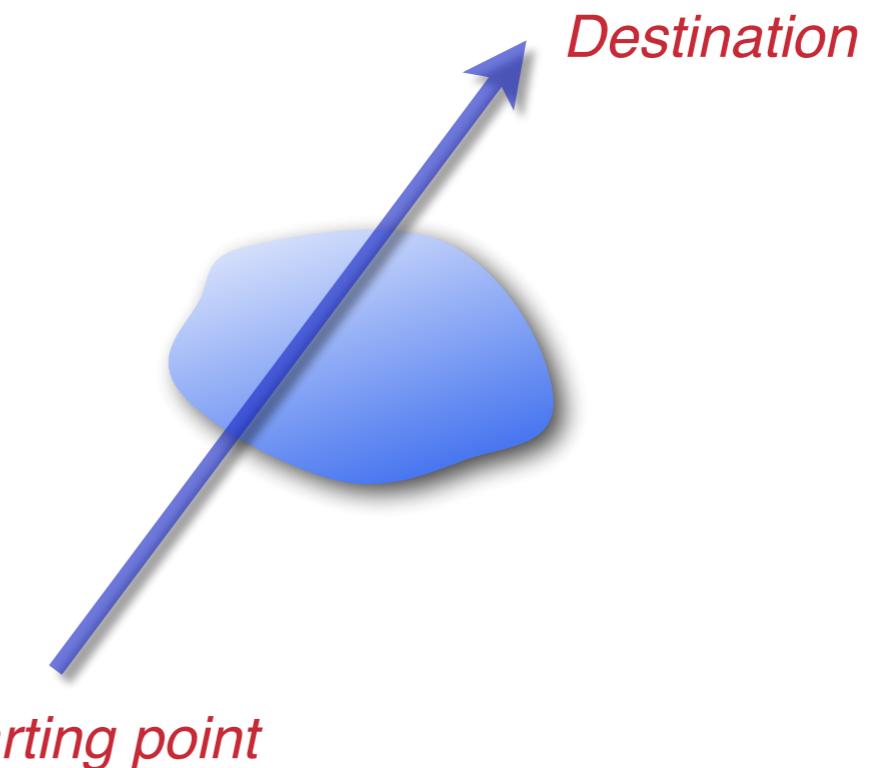
- Have magnitude and direction
- Examples:
  - Velocity (speed in given direction)
  - Acceleration
  - Displacement (offset and direction)
- Described in terms of
  - Length and Direction ( $r, \theta$ )
  - Cartesian offset ( $x, y$ )



$$\mathbf{d} = (d_1, d_2) = (r \sin \theta, r \cos \theta)$$

Think of giving someone directions by compass bearing “to get to the pub from here, walk one hundred metres in a roughly north-easterly direction ...”

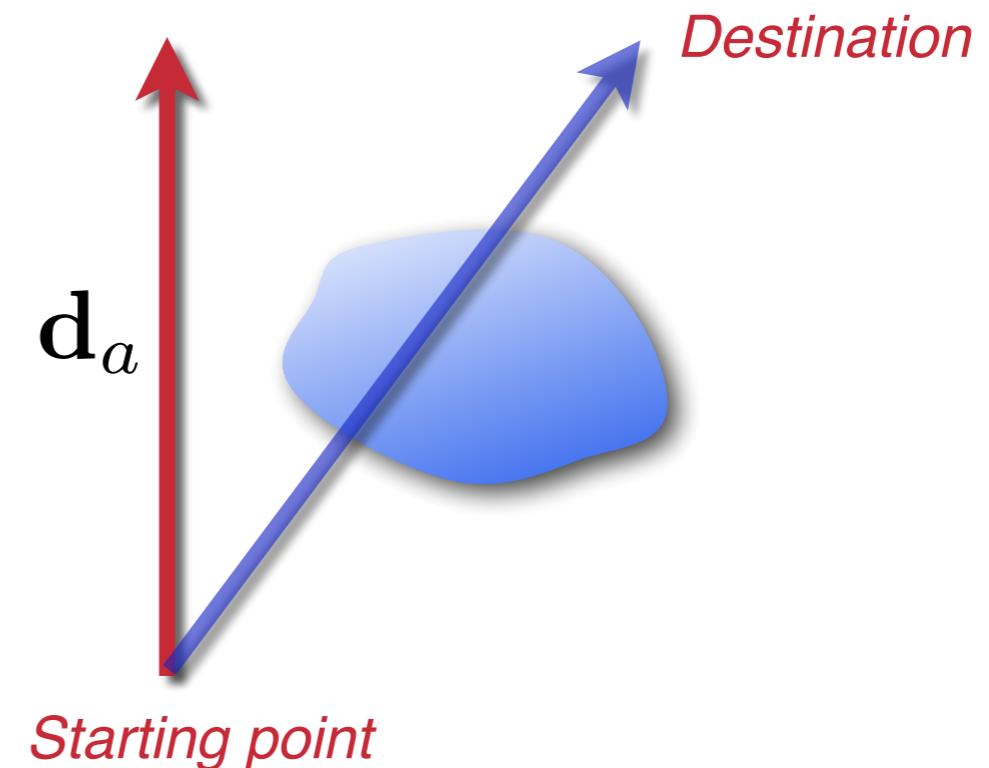
## Detour — vector addition



To add vectors we can think again of “adding” compass bearings

“To get to the pub (without falling in the lake) walk 80 metres North and then 60 metres East ... ”

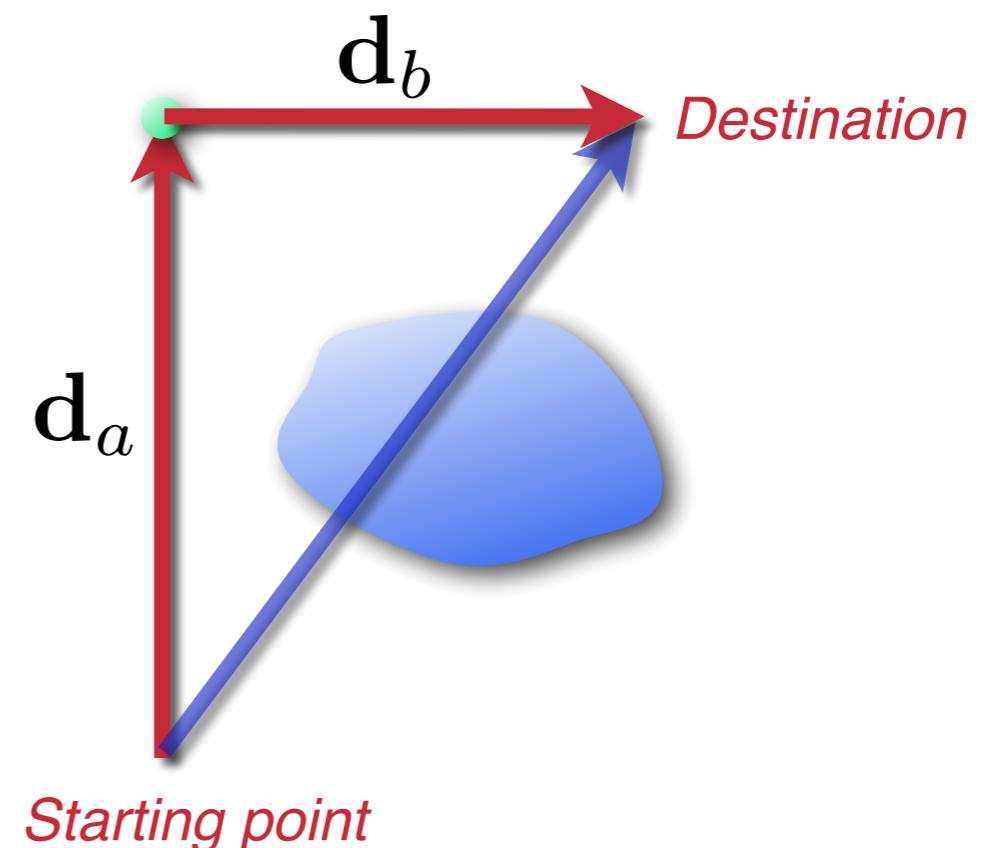
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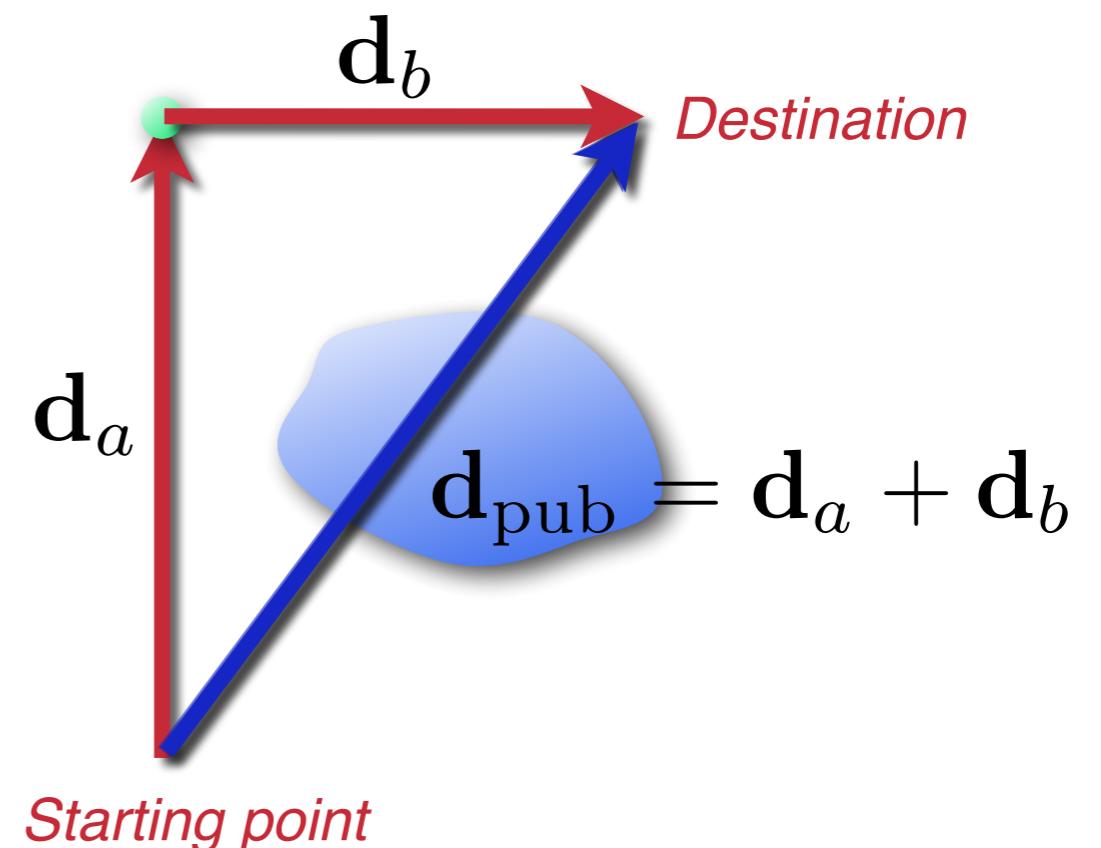
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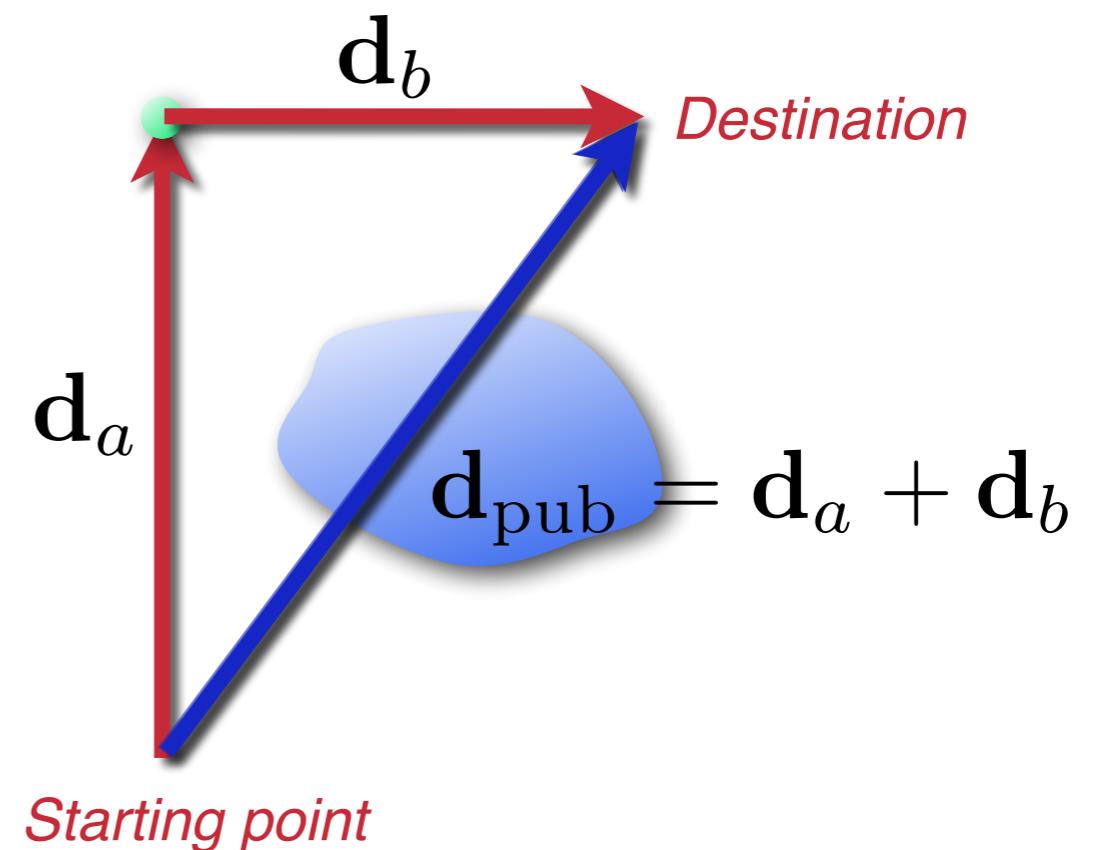
## Detour — vector addition

$$\mathbf{d}_a = (0, 80)$$

$$\mathbf{d}_b = (60, 0)$$

$$\mathbf{d}_{\text{pub}} = (60, 80)$$

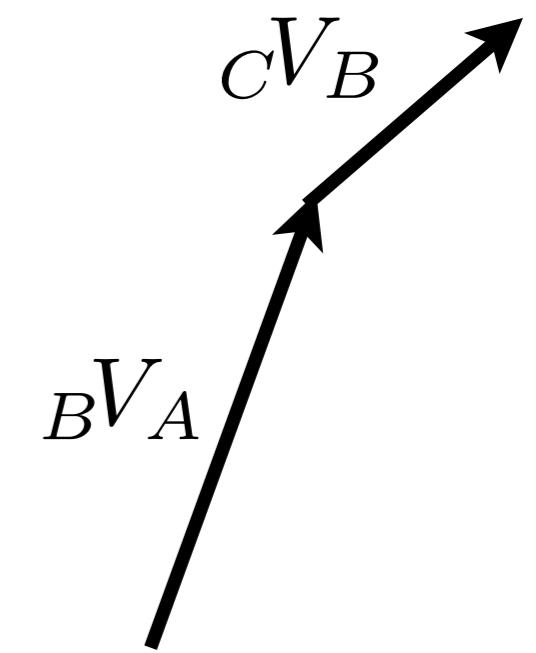
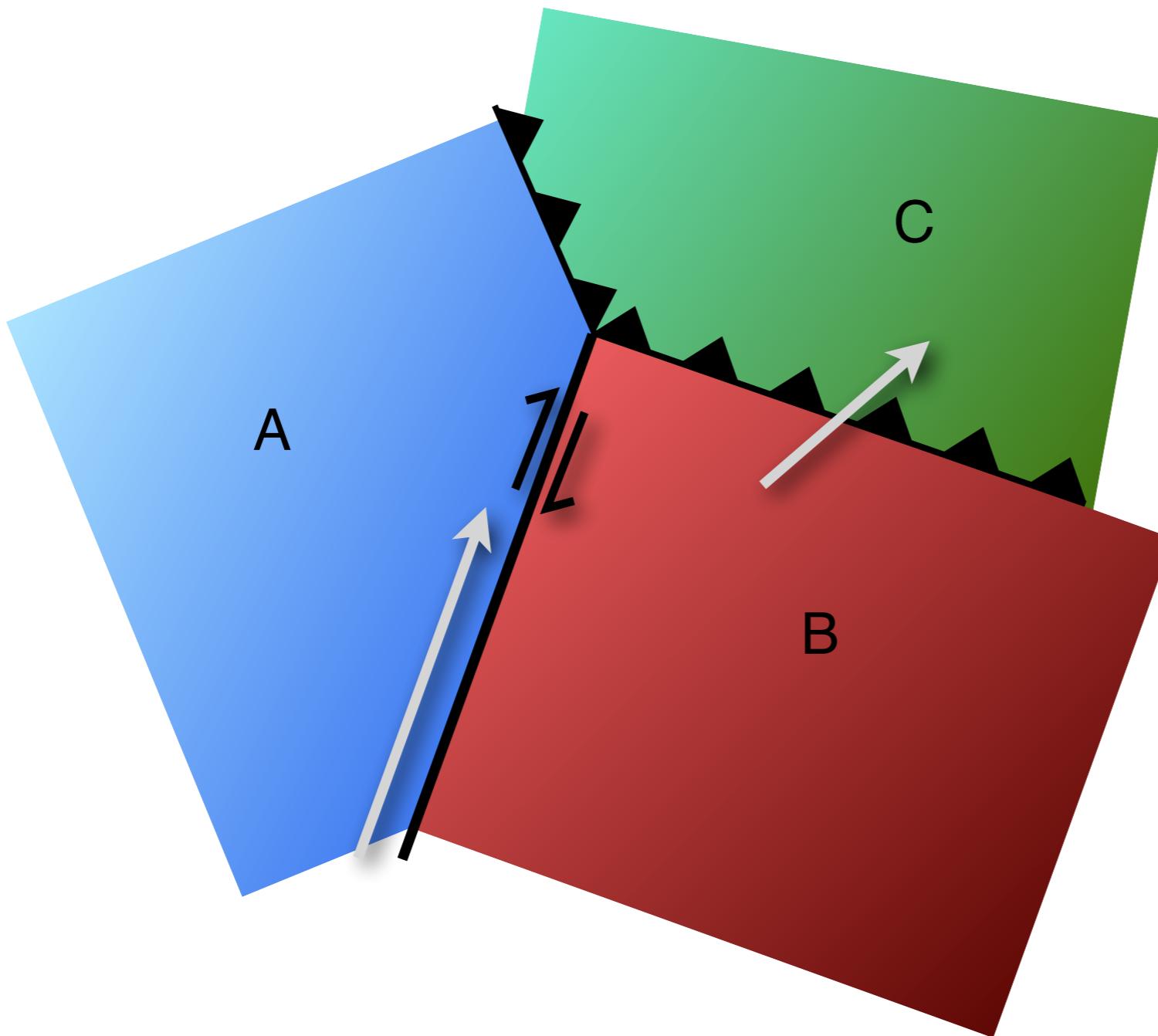
$$|\mathbf{d}_{\text{pub}}| = \sqrt{60^2 + 80^2}$$



To add vectors we can think again of “adding” compass bearings

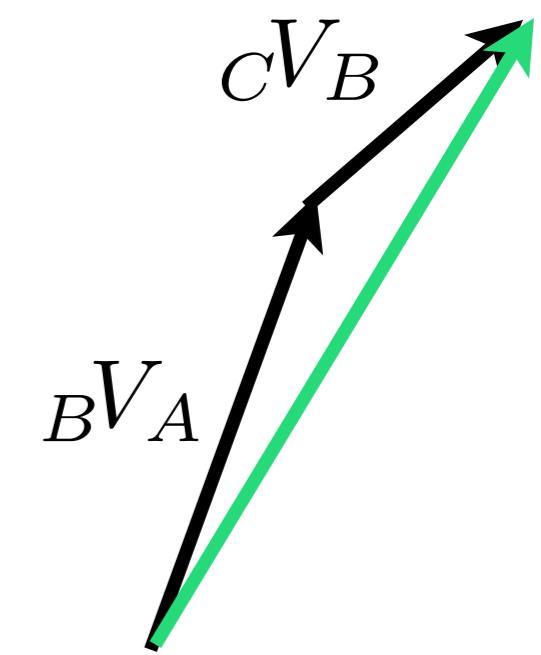
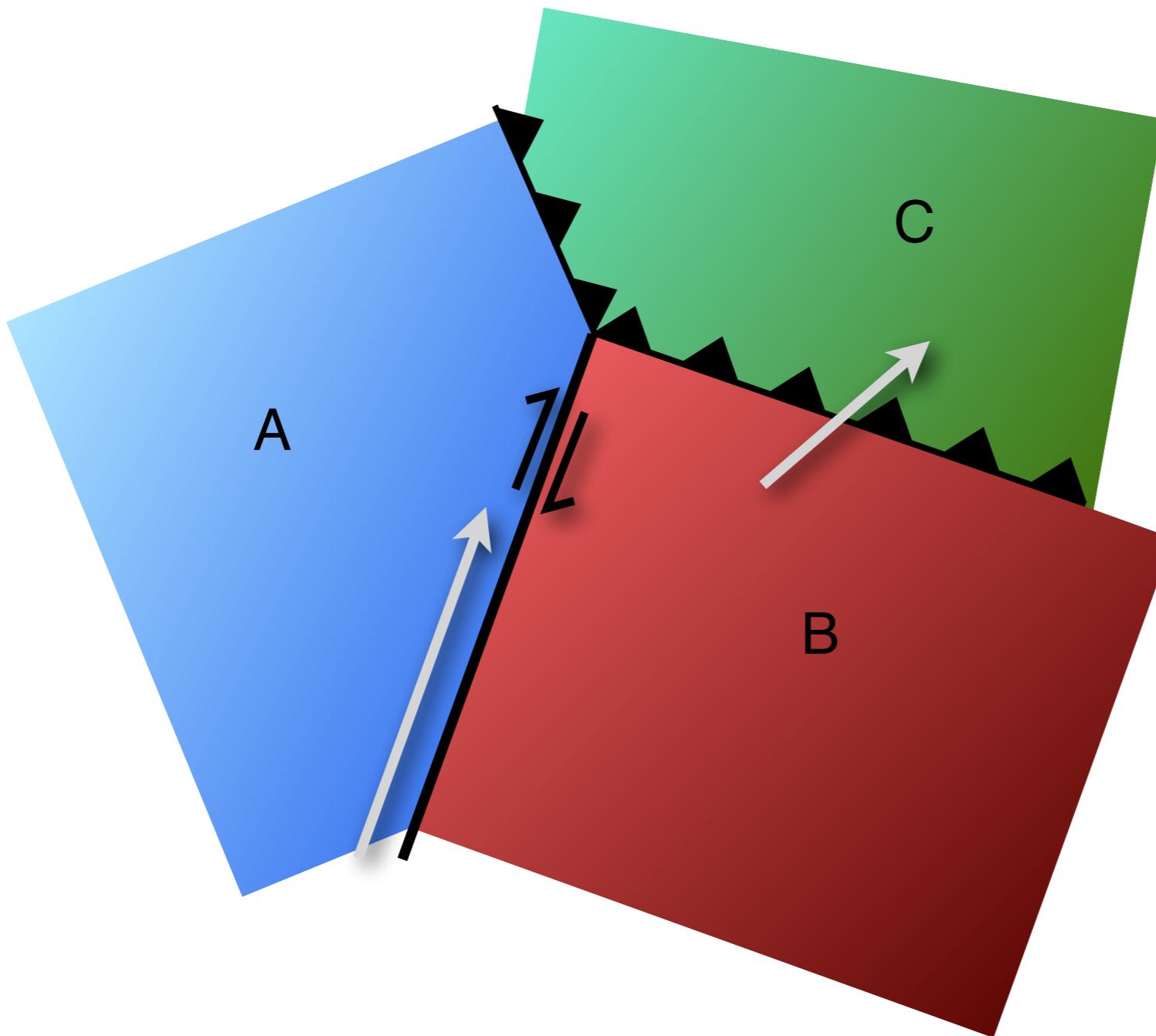
“To get to the pub (without falling in the lake) walk 80 metres North and then 60 metres East ... ”

# Non-orthogonal boundaries



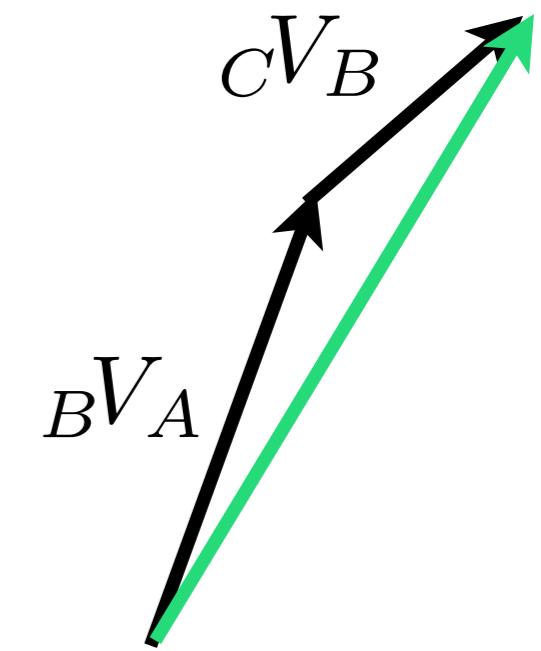
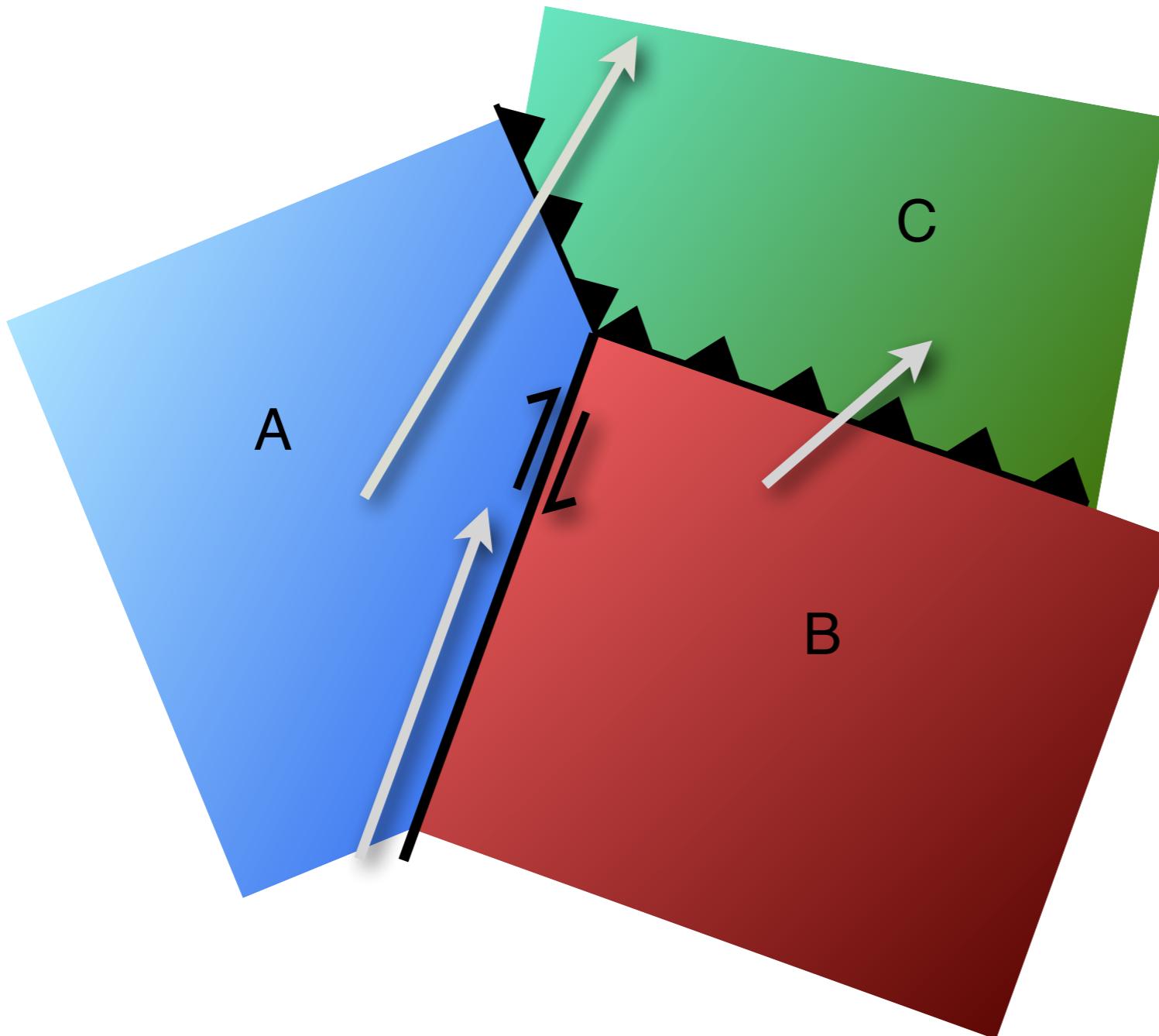
$$CV_A = CV_B + BV_A$$

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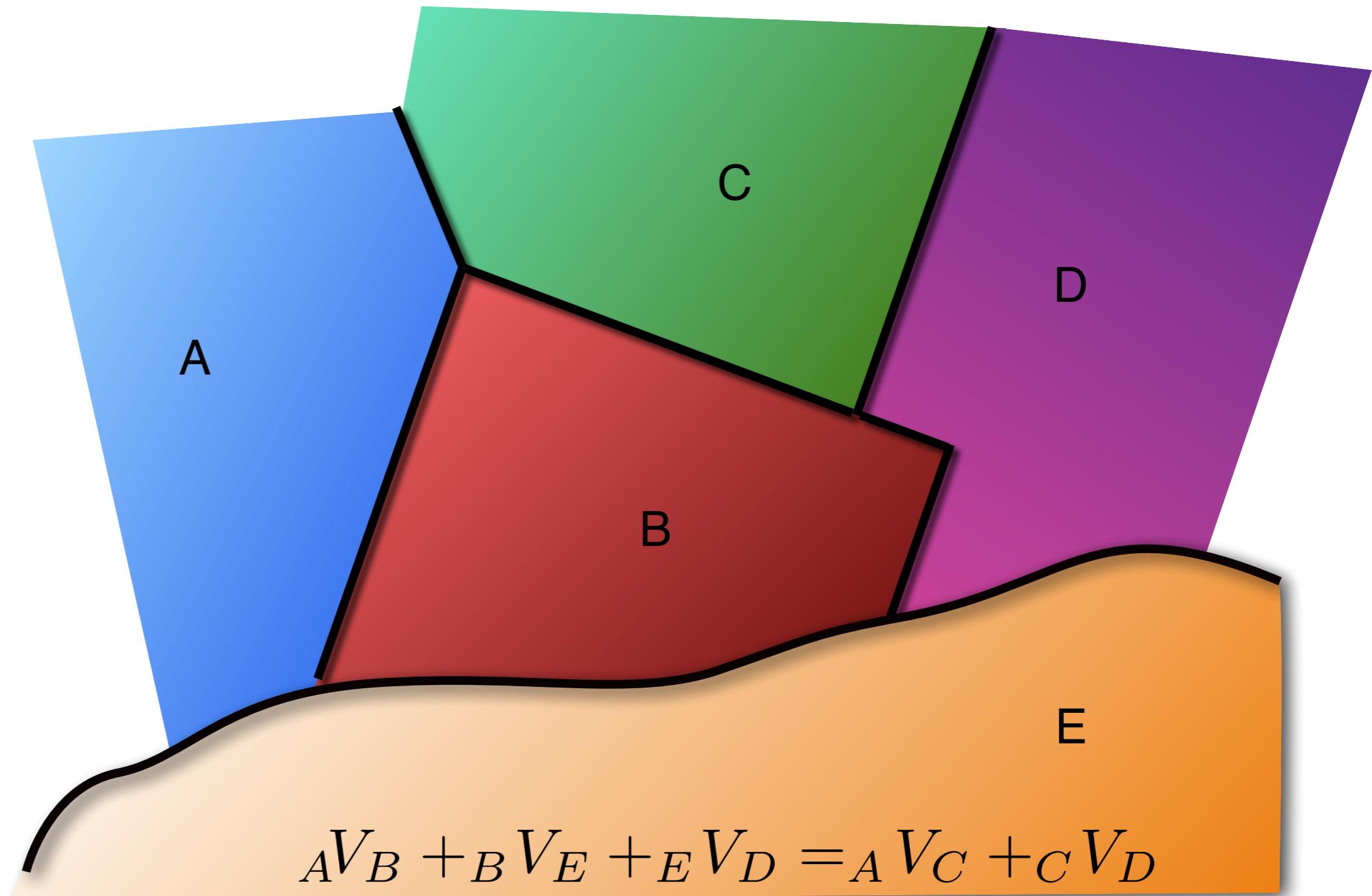
# Non-orthogonal boundaries



$${}_C V_A = {}_C V_B + {}_B V_A$$

## Plate circuits

Generalize the previous example — no matter what the plate boundary types ...



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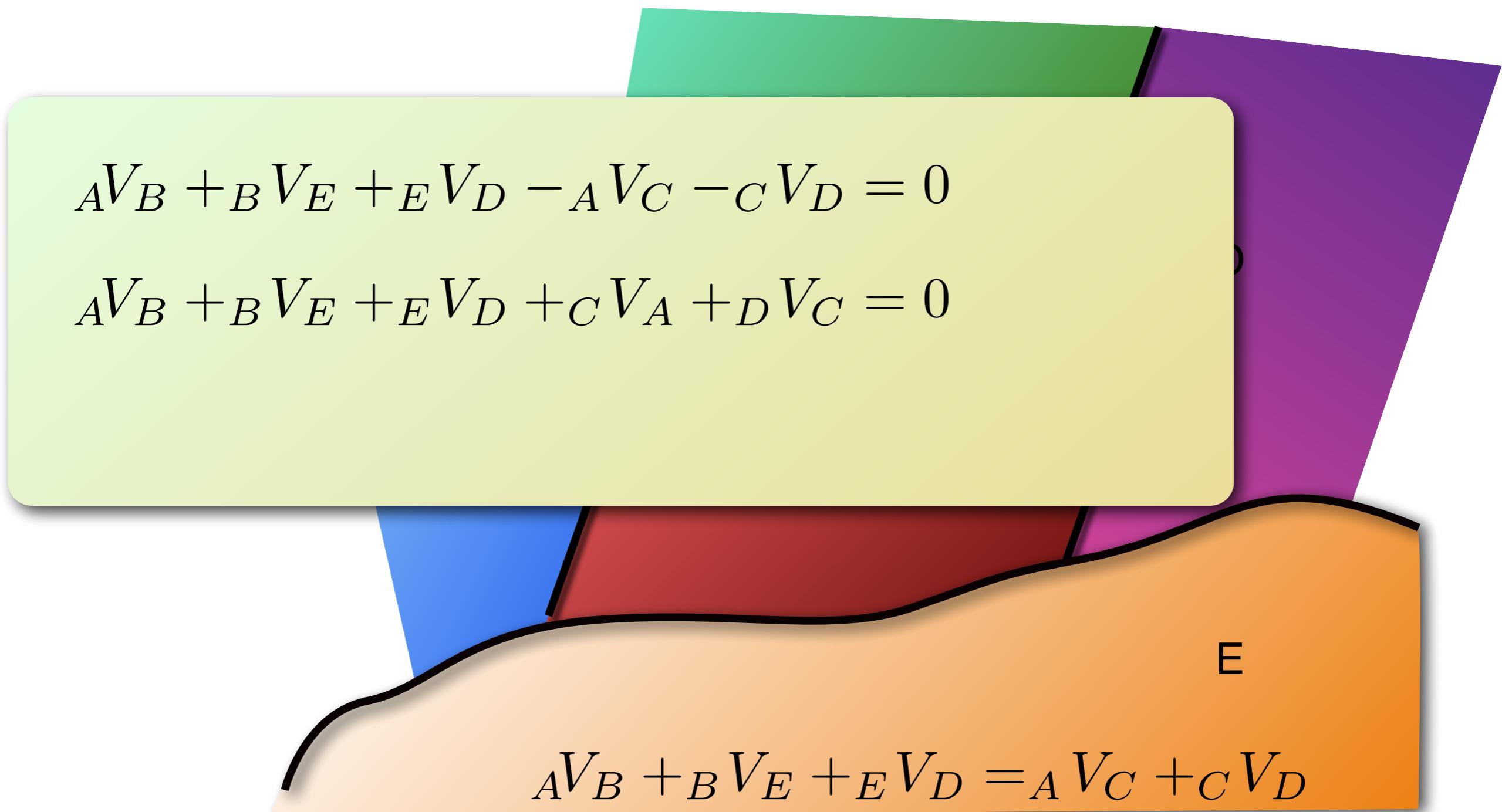
$$_A V_B + _B V_E + _E V_D - _A V_C - _C V_D = 0$$

E

$$_A V_B + _B V_E + _E V_D = _A V_C + _C V_D$$

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$$_A V_B + _B V_E + _E V_D - _A V_C - _C V_D = 0$$

$$_A V_B + _B V_E + _E V_D + _C V_A + _D V_C = 0$$

$$_A V_B + _B V_E + _E V_D + _D V_C + _C V_A = _A V_A = 0$$

E

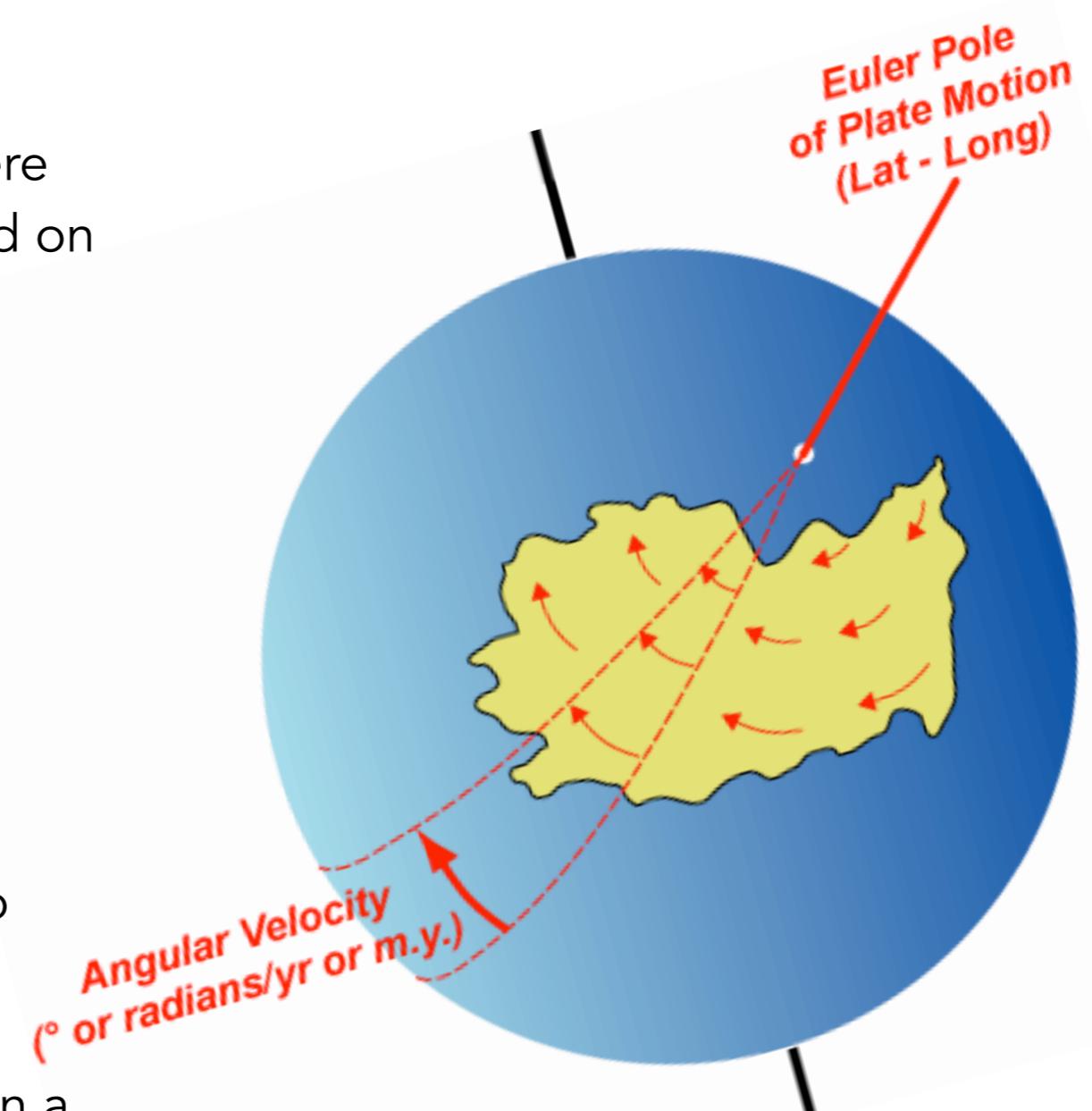
$$_A V_B + _B V_E + _E V_D = _A V_C + _C V_D$$

# Motions on a sphere

So far we have looked at everything as though it were happening on a flat Earth ... This is not the case, and on a plate scale, the curvature cannot be ignored.

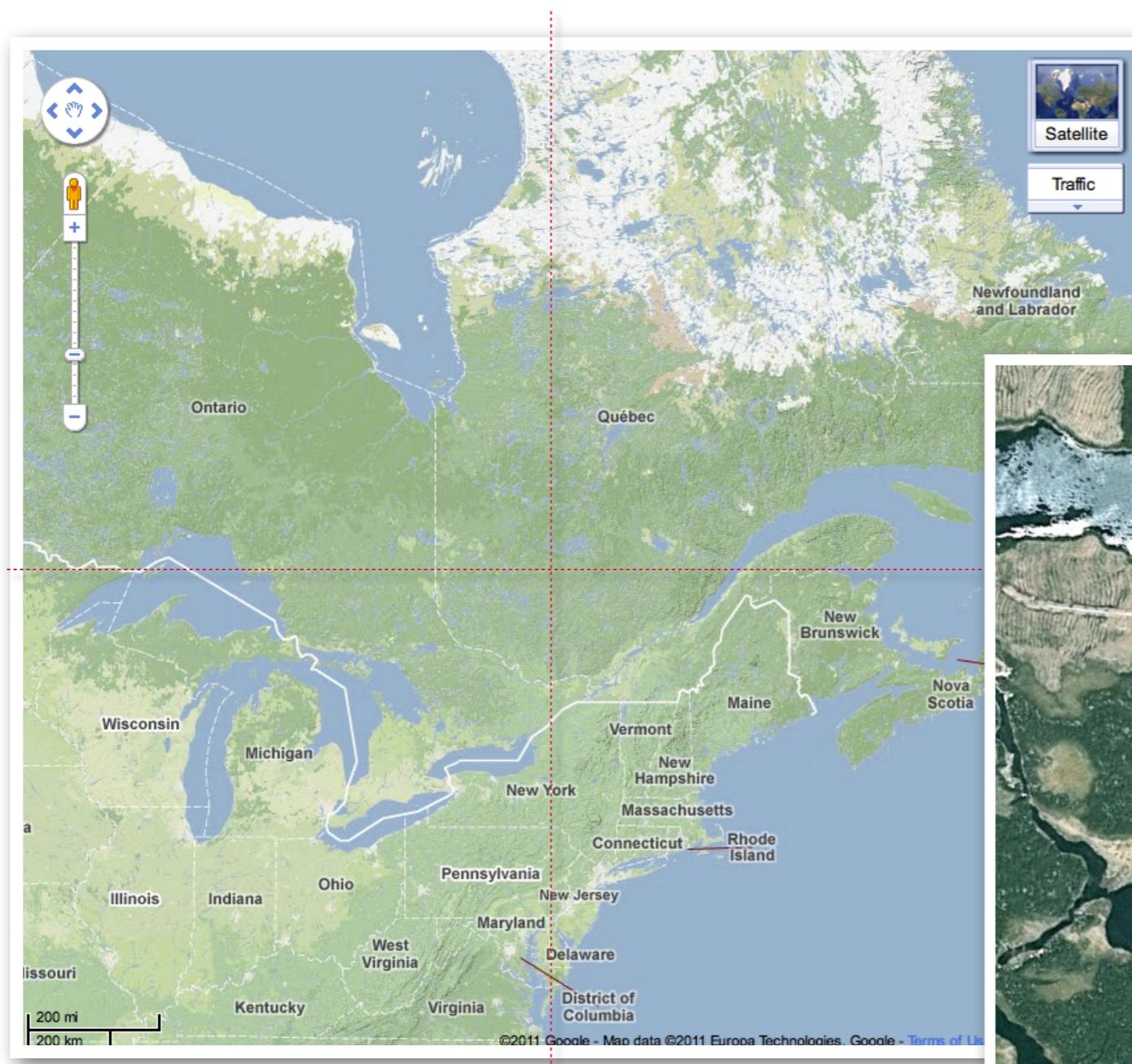
Consequences:

- The (relative) motion of plates is described by rotation pole and angular velocity
- Transform faults lie along small circles relative to this pole
- The velocity (magnitude & direction) of points on a plate varies systematically over the plate

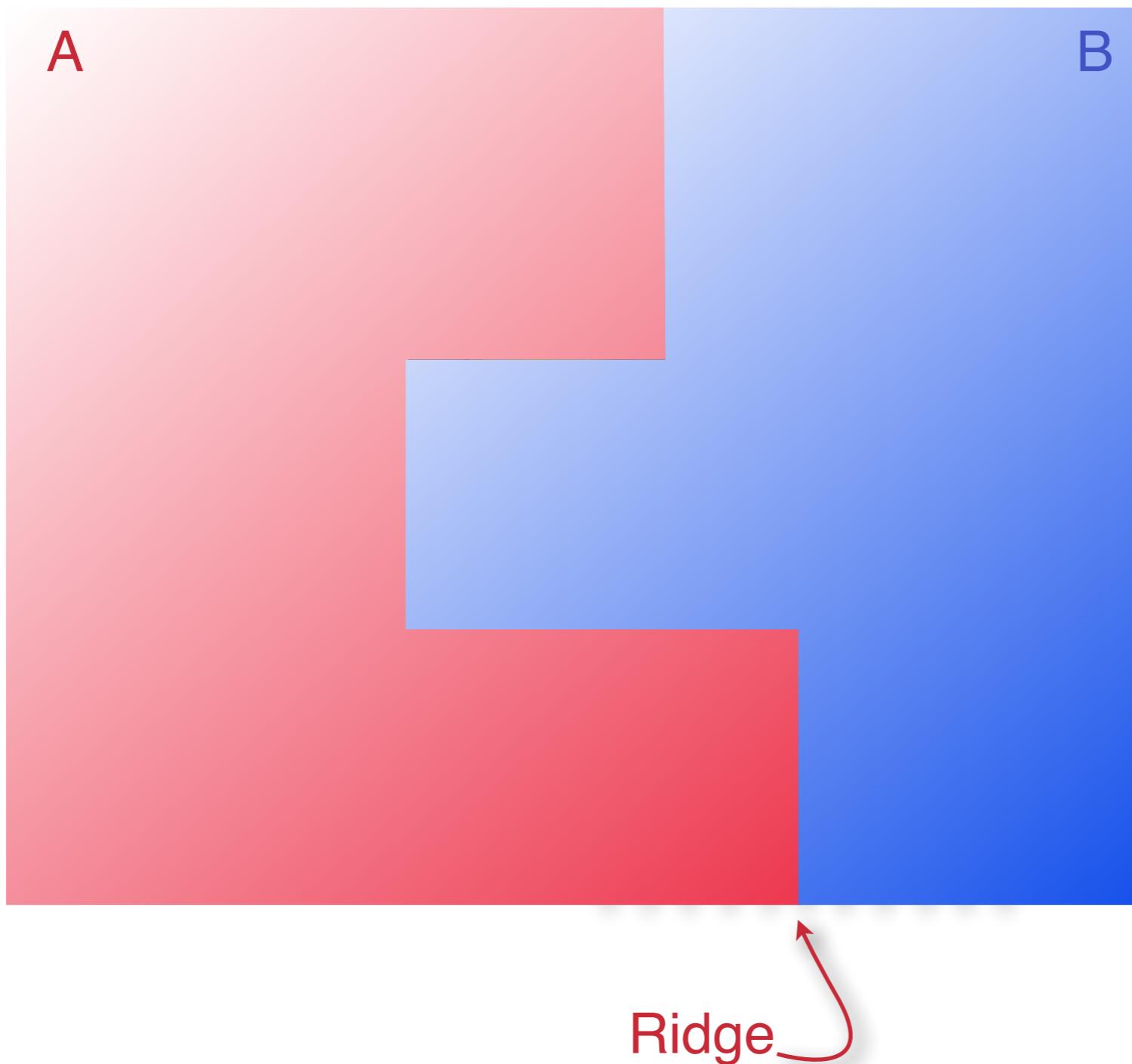


To describe plate motions and do reconstructions we need to understand how to move plates on the surface of a sphere. We also need to understand how to do this quantitatively.

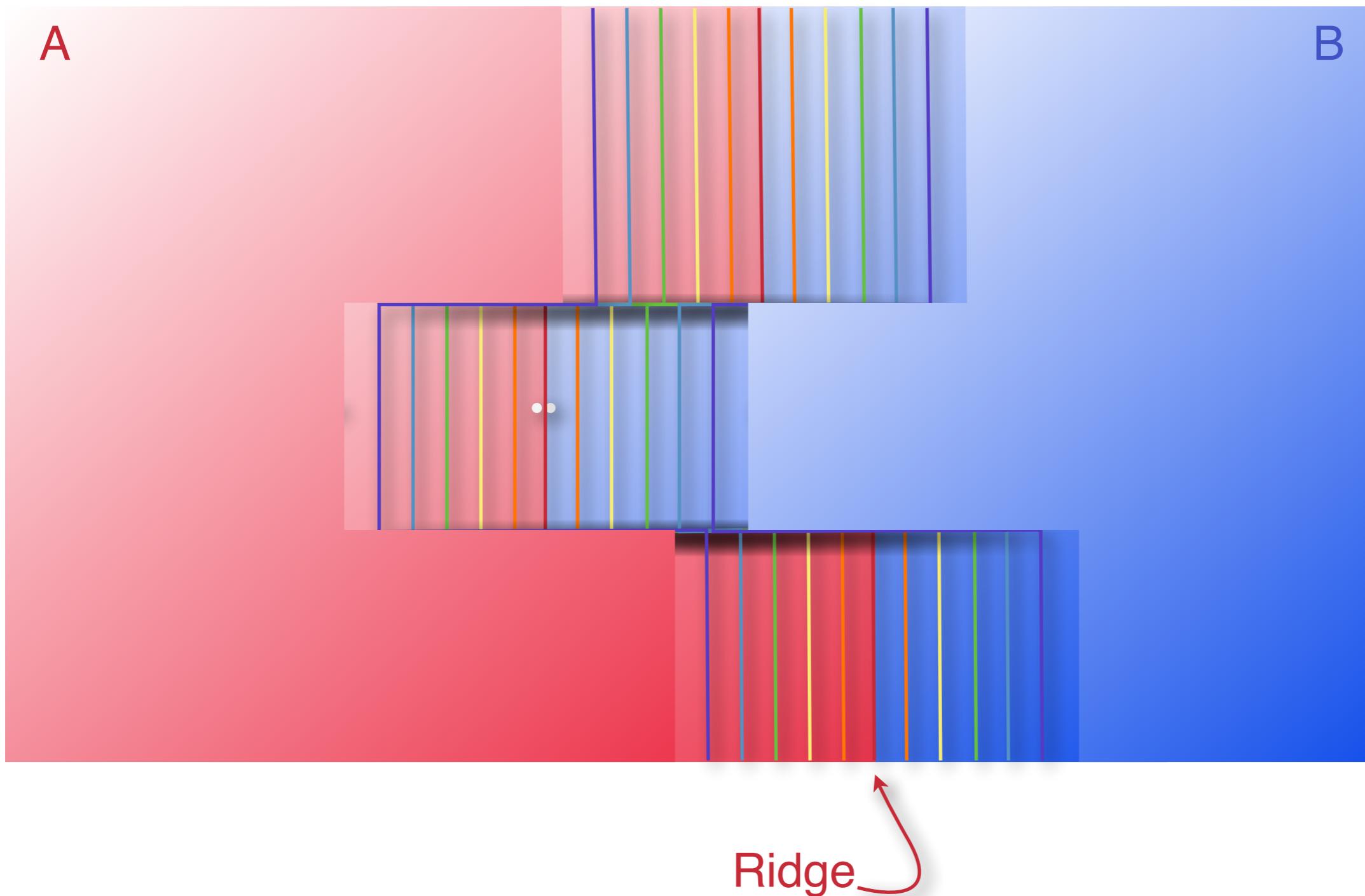
# Pacific / North America Rotation Pole



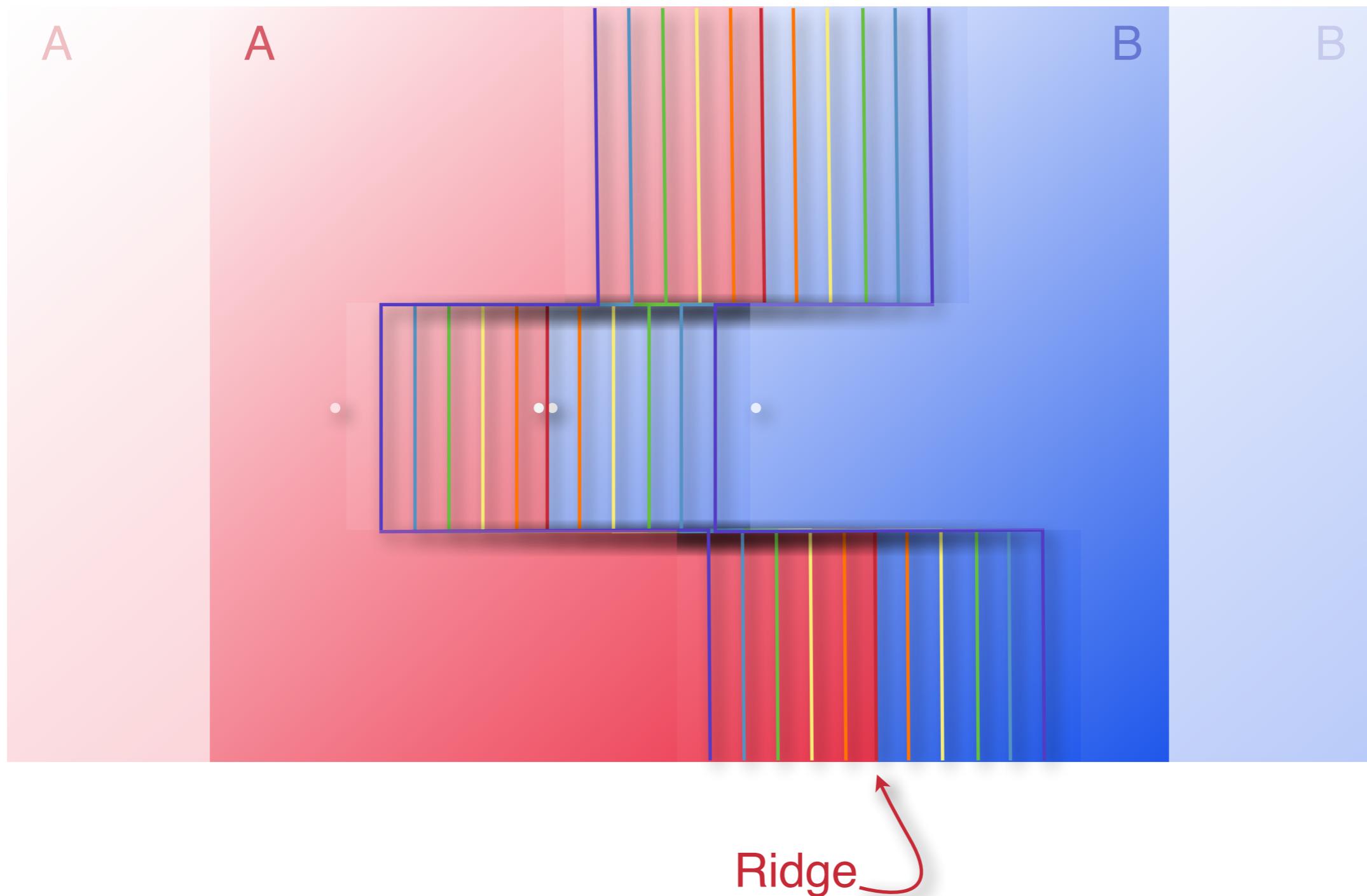
# Transform faults v. Fracture zones



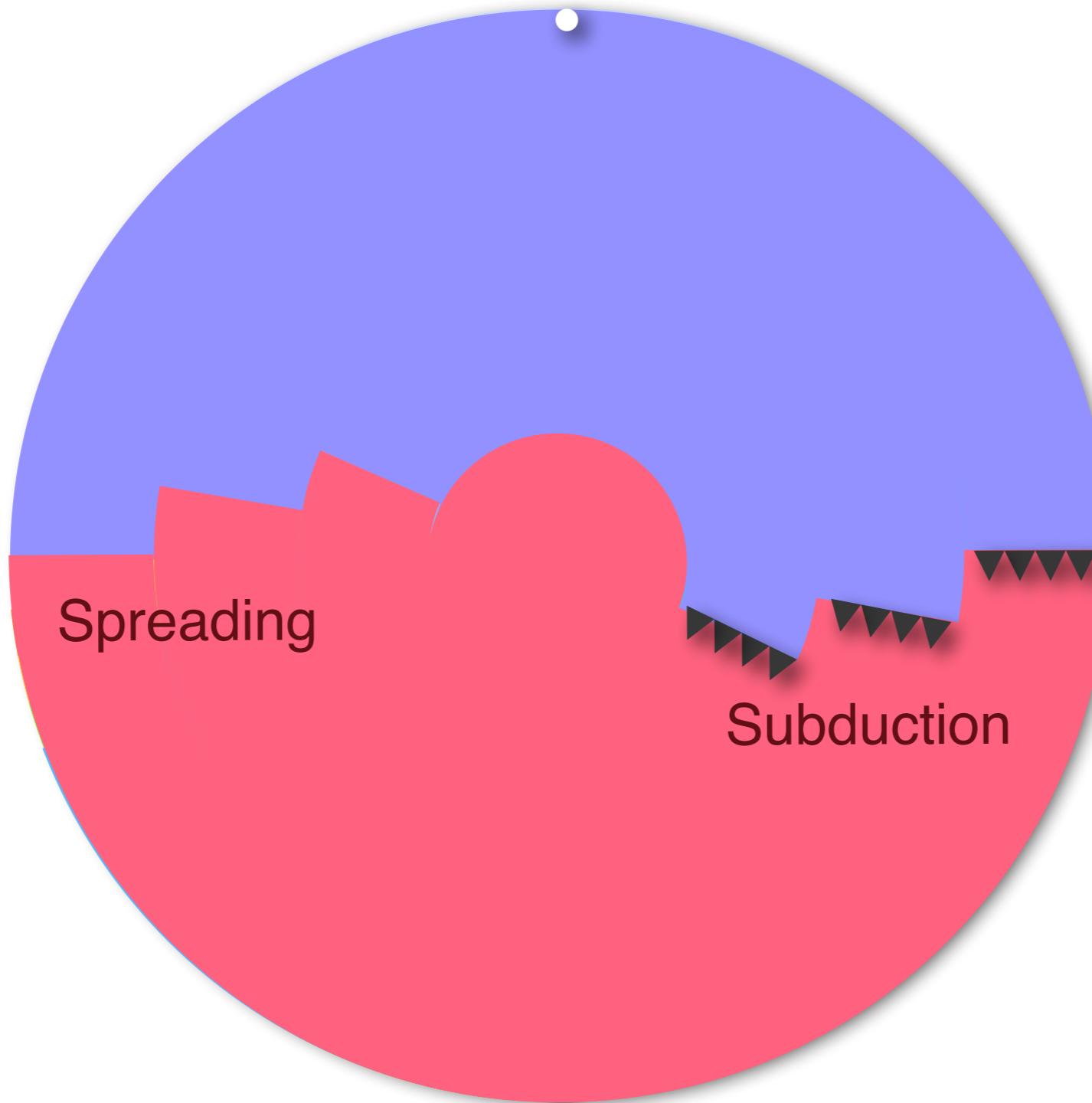
# Transform faults v. Fracture zones



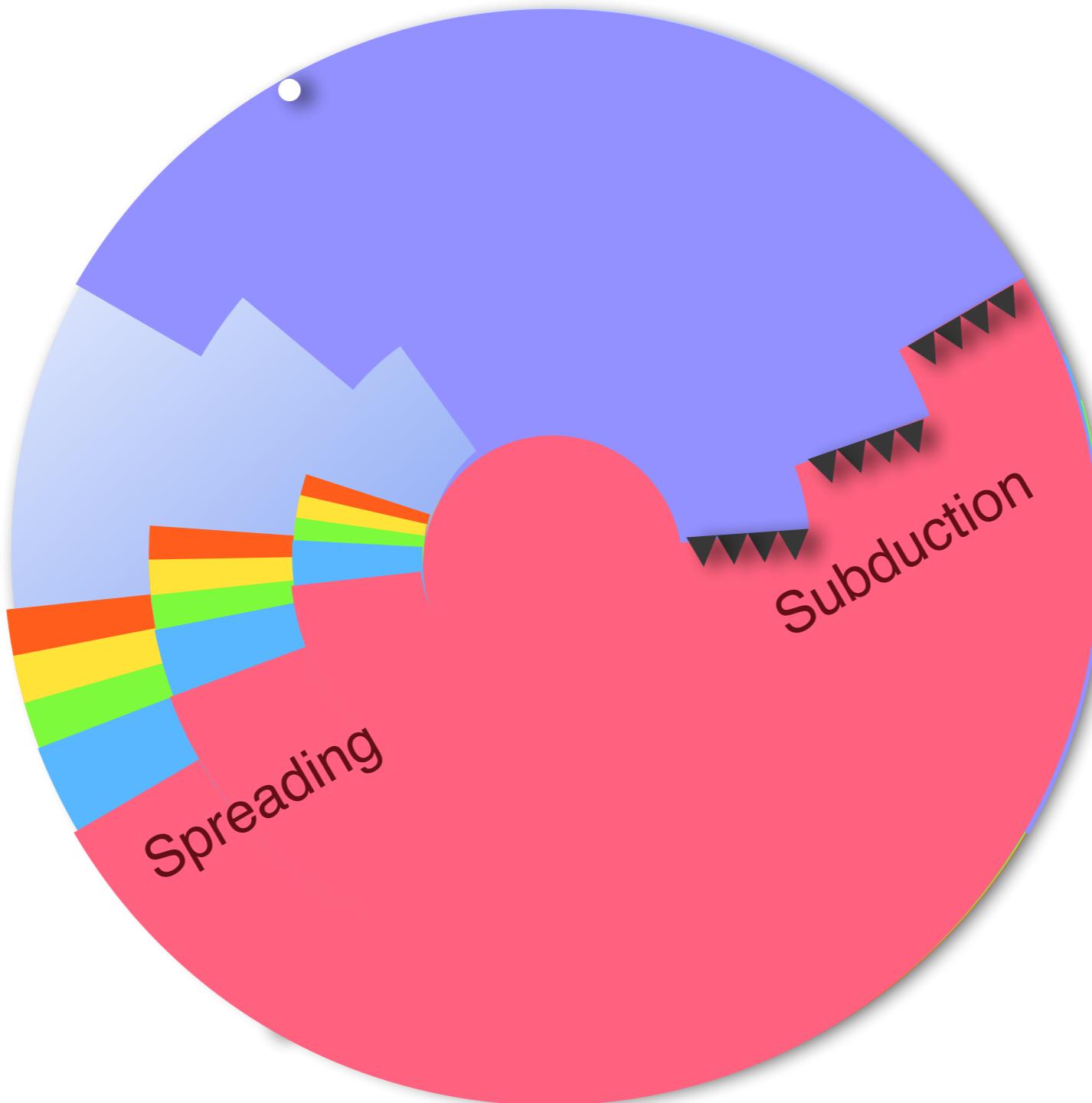
# Transform faults v. Fracture zones



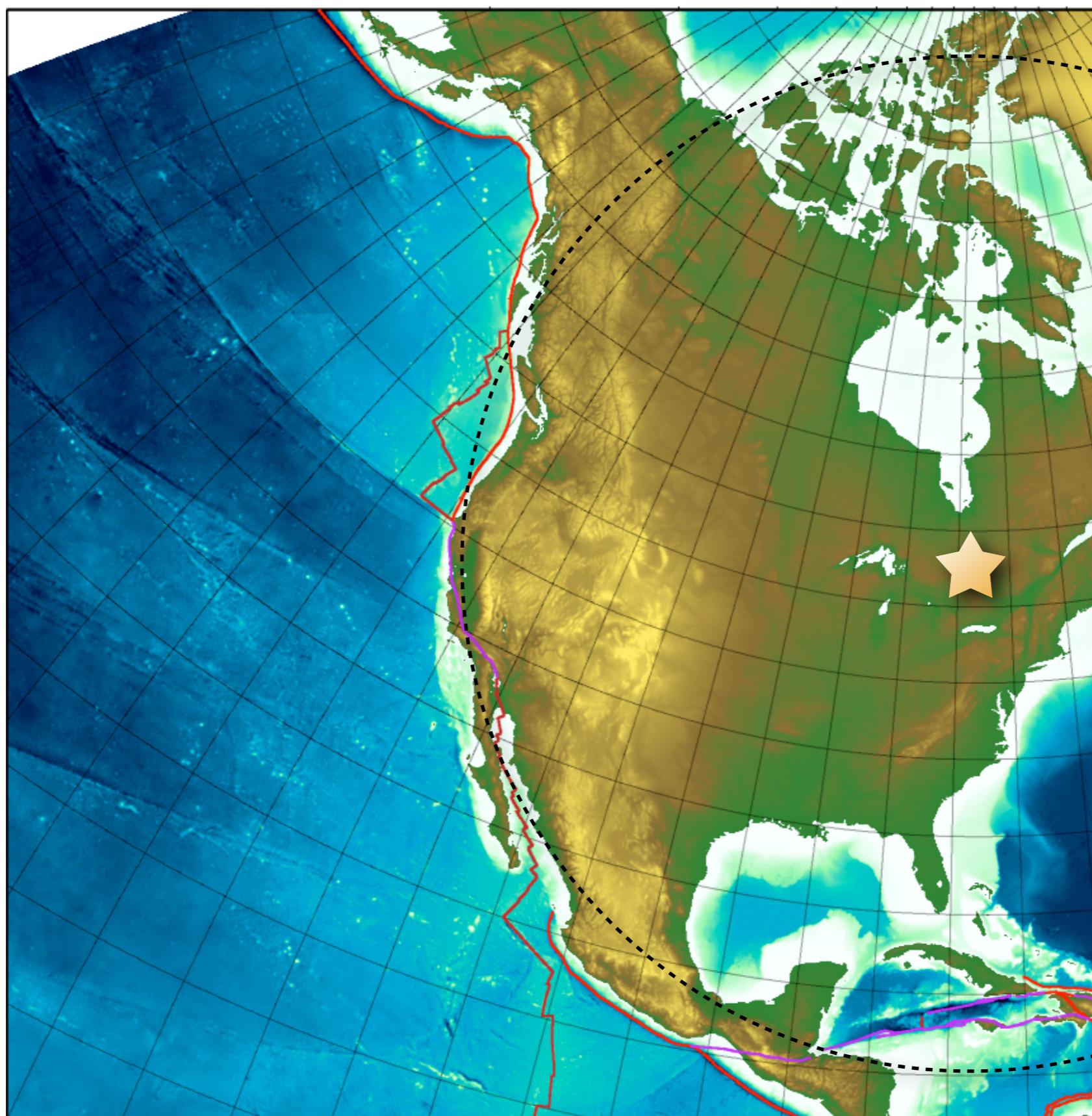
# Plate motions on a sphere



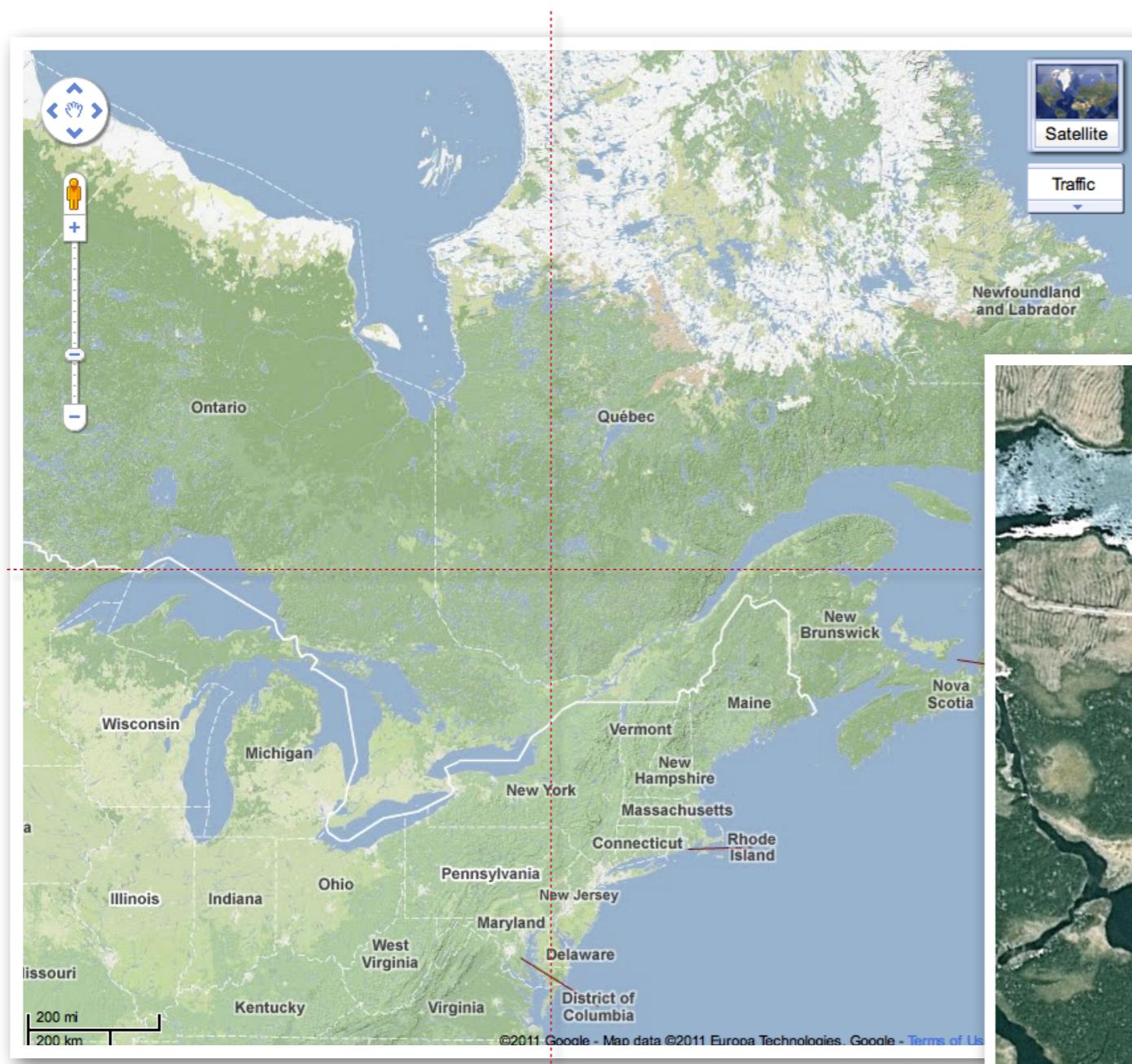
# Plate motions on a sphere



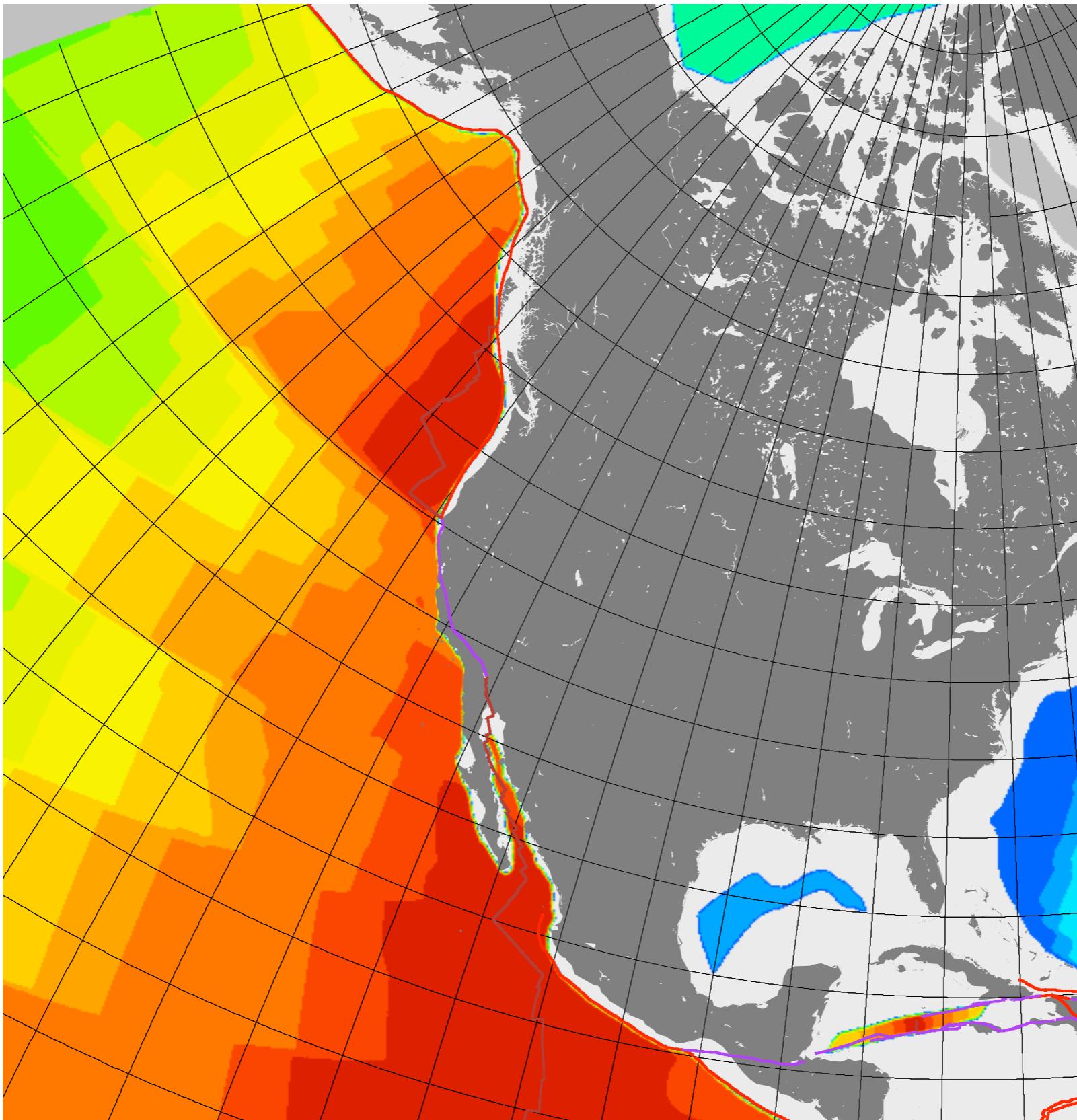
# North America / Pacific elevation

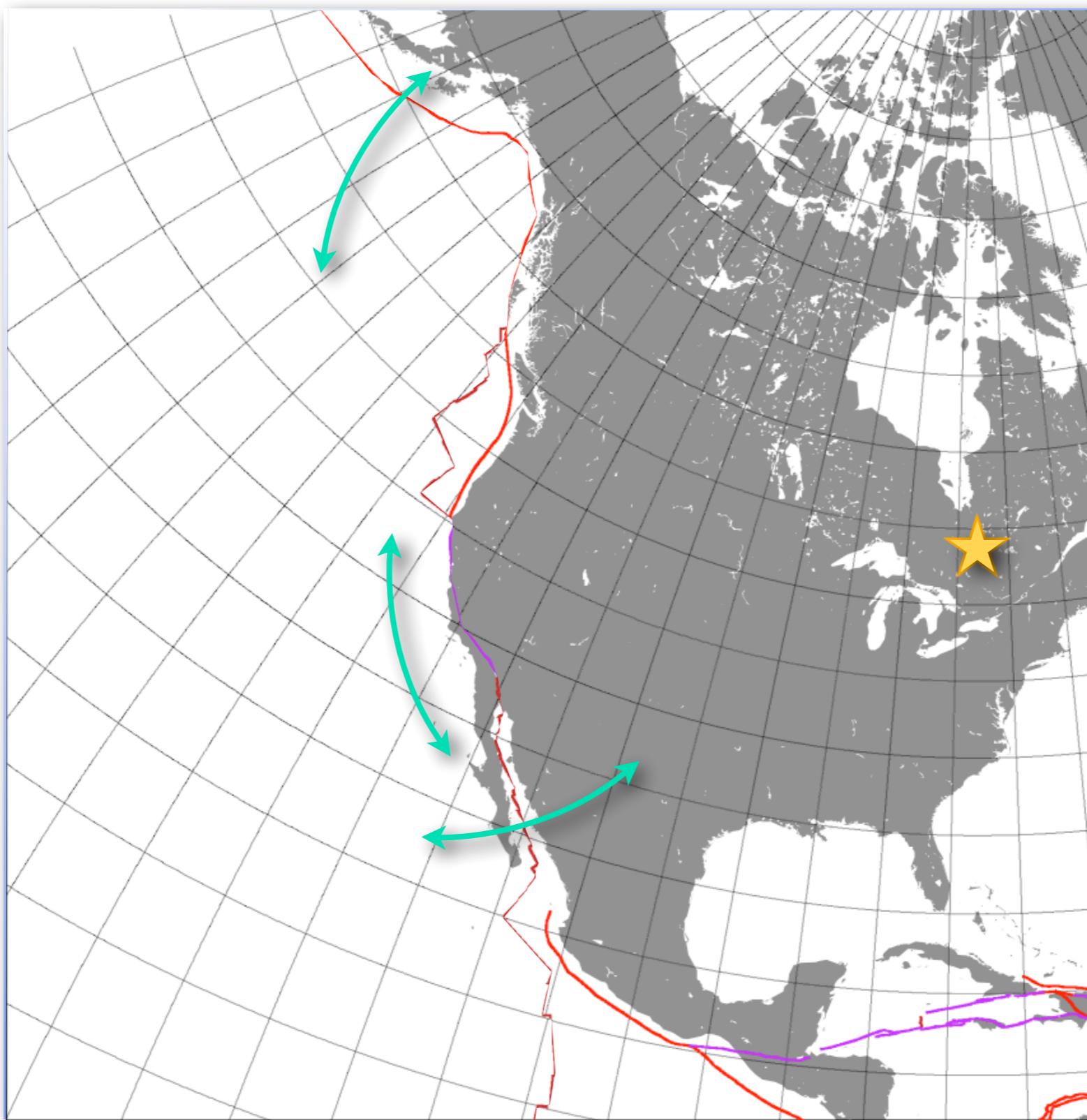


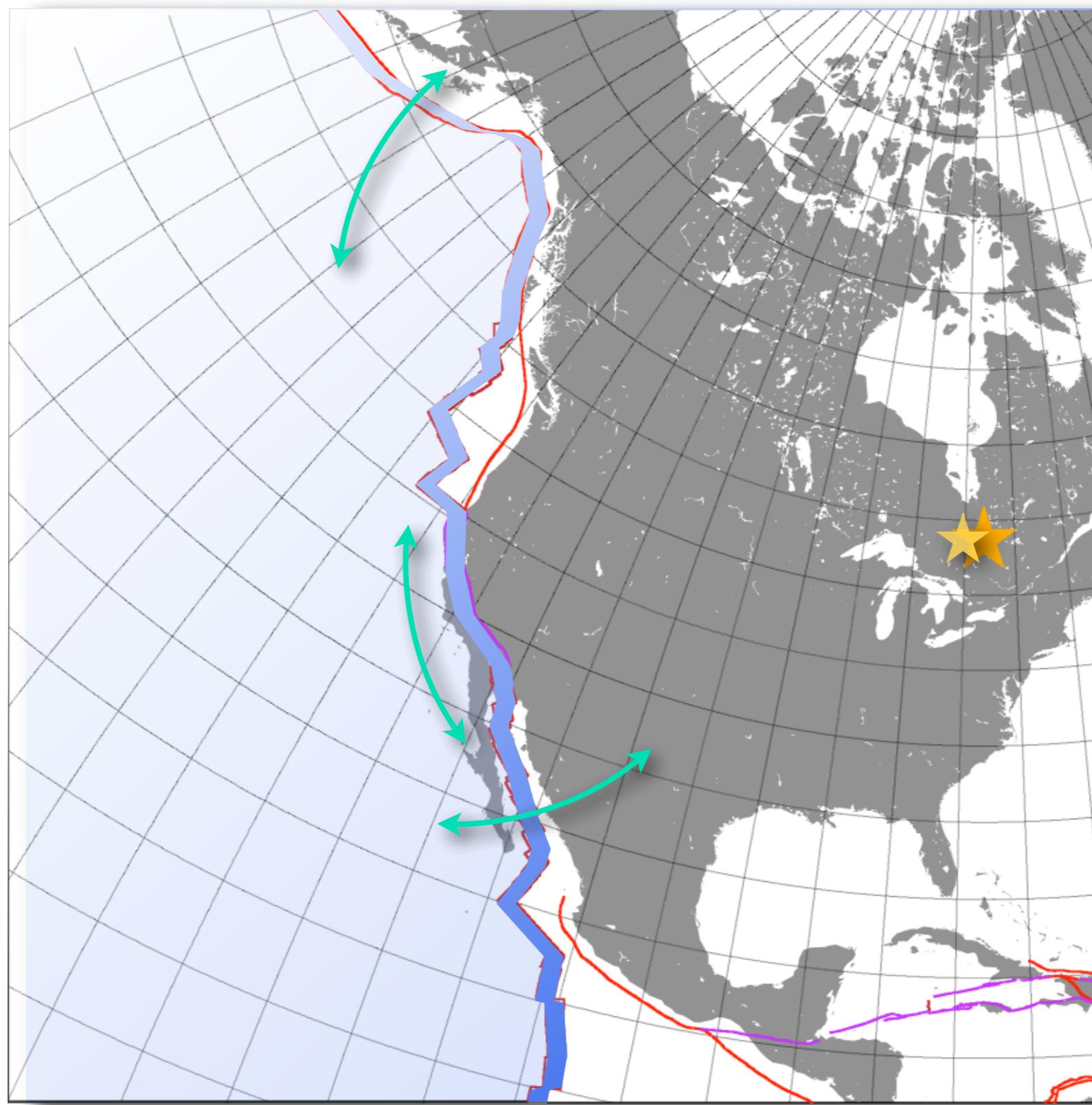
# Pacific / North America Rotation Pole



# Pacific age grid









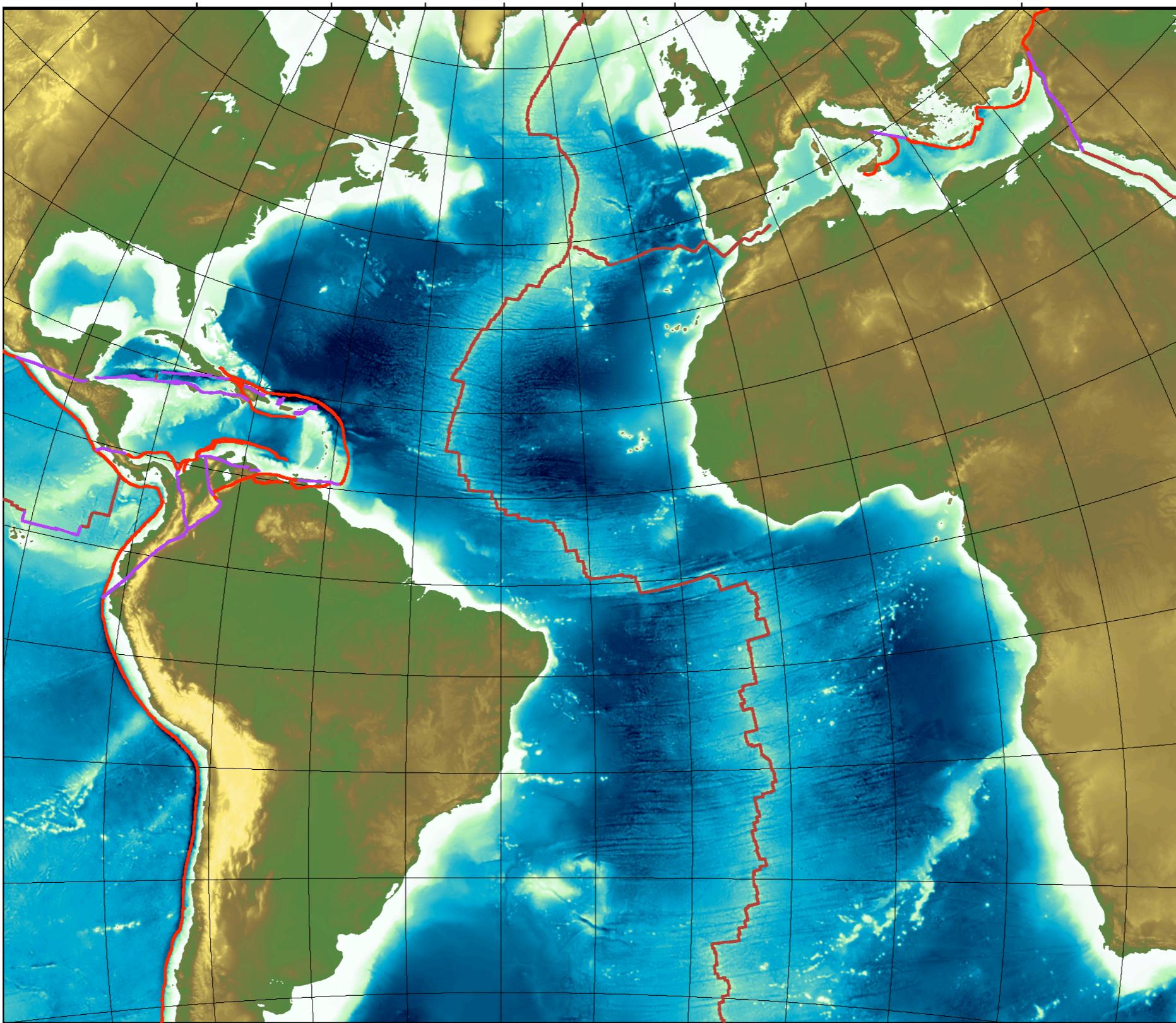




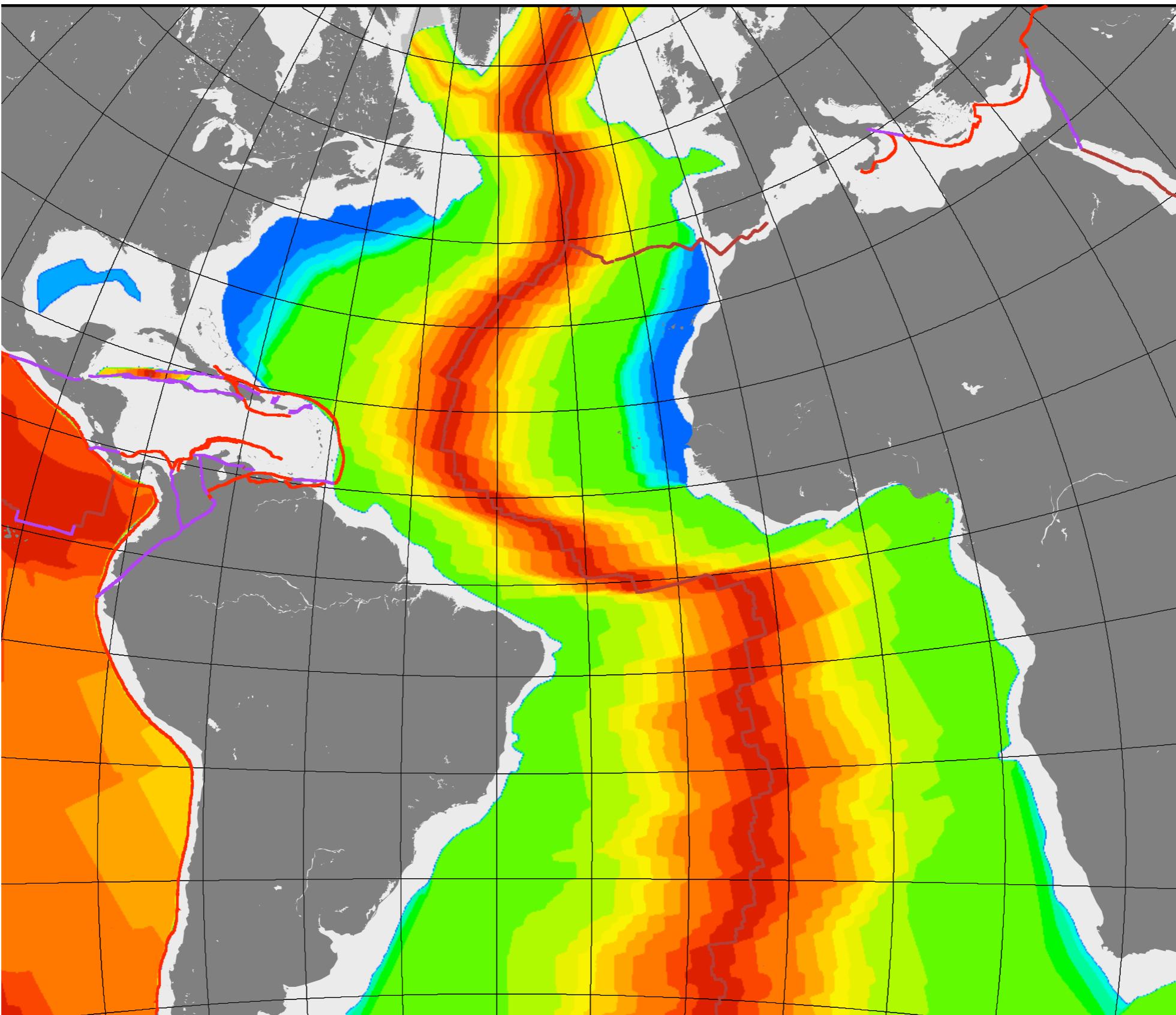


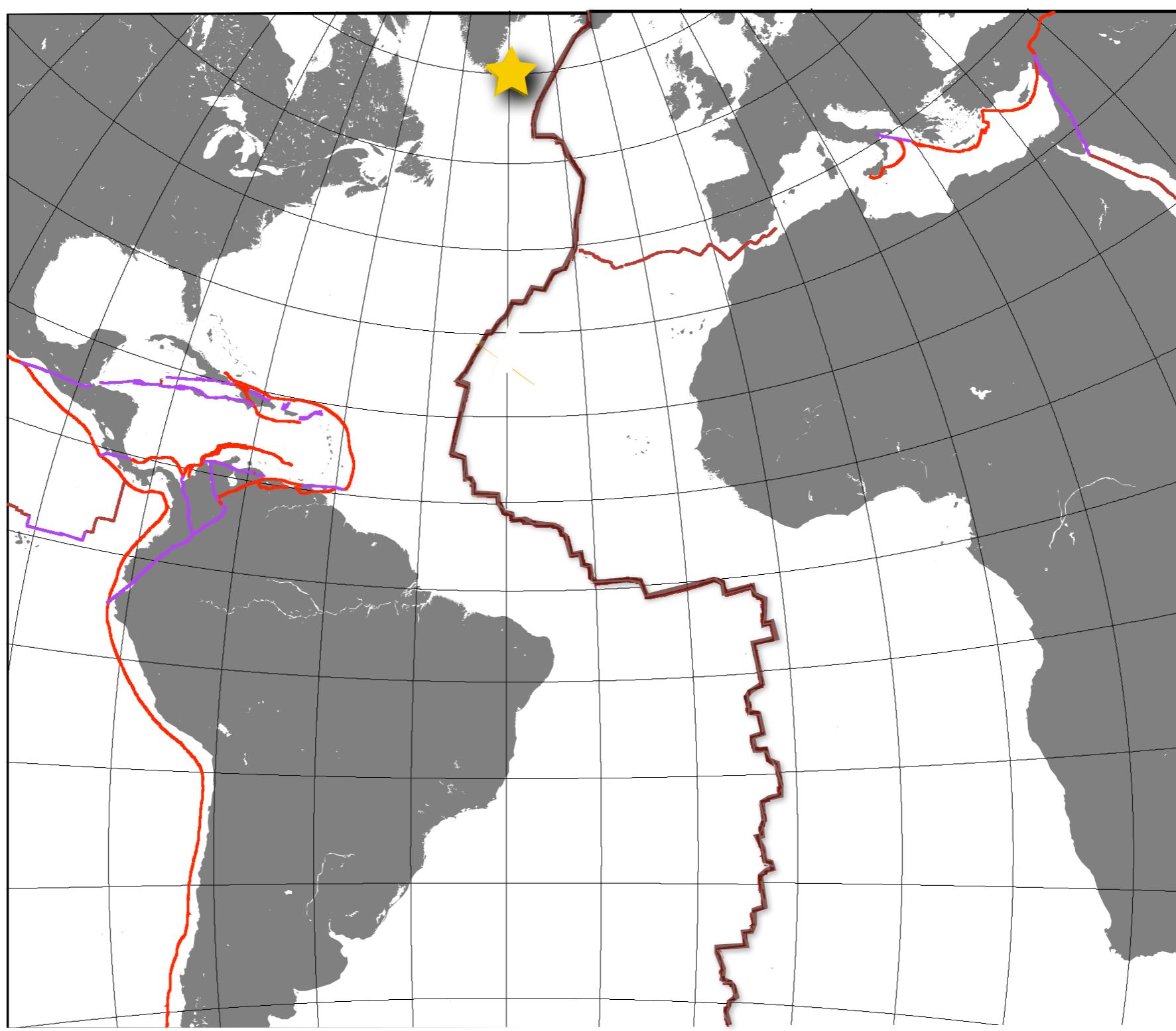


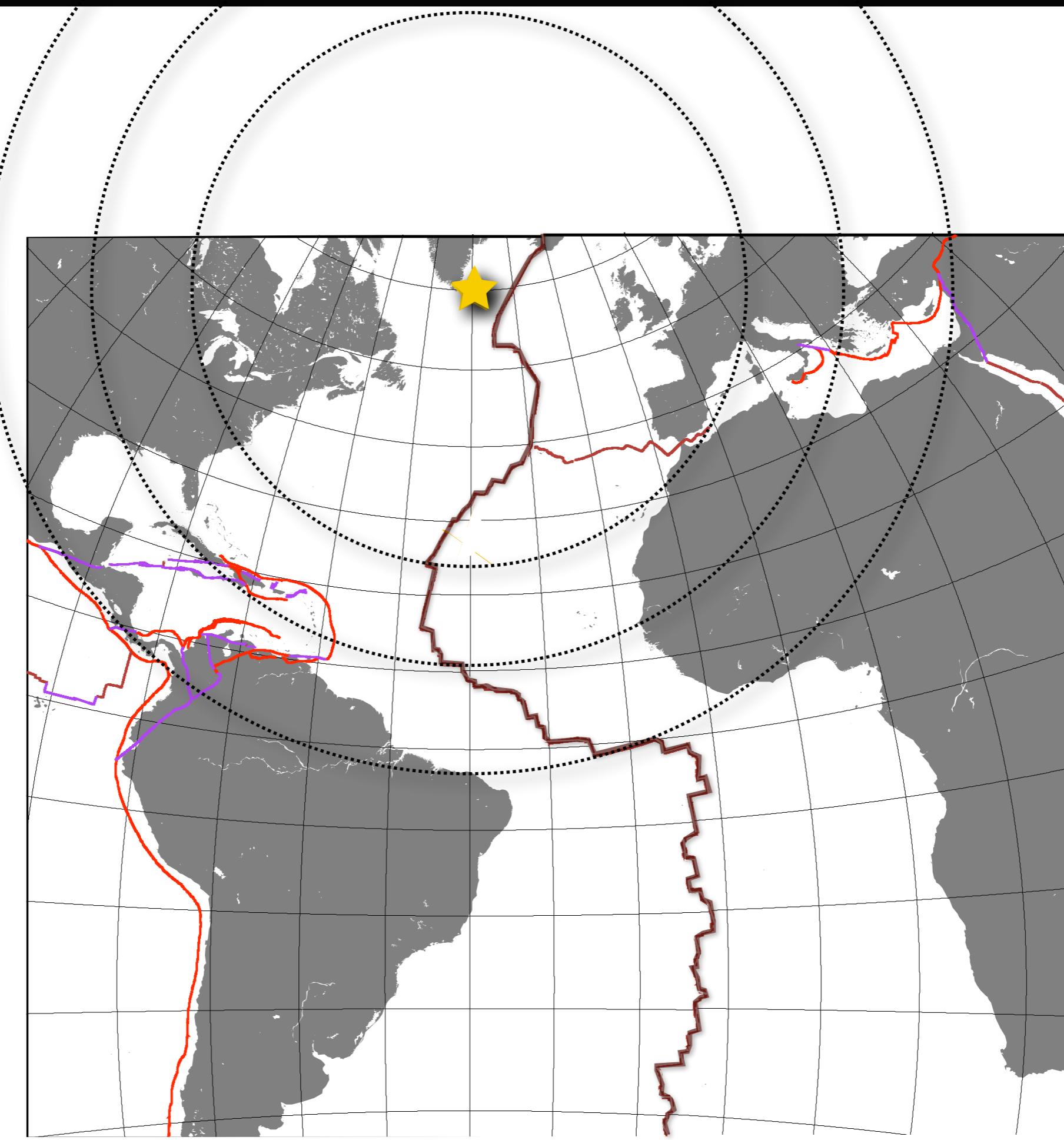
# Africa / South America elevation

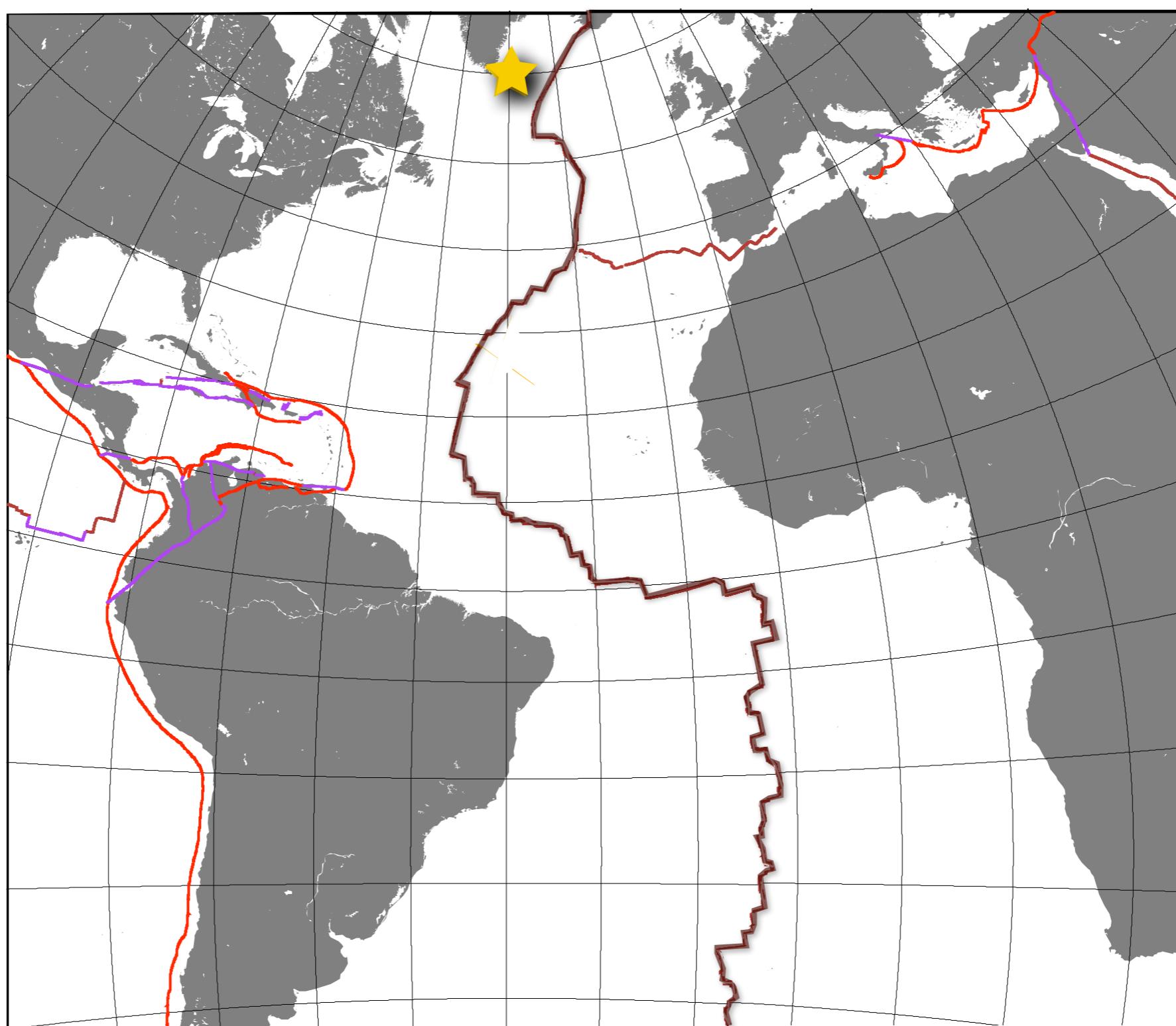


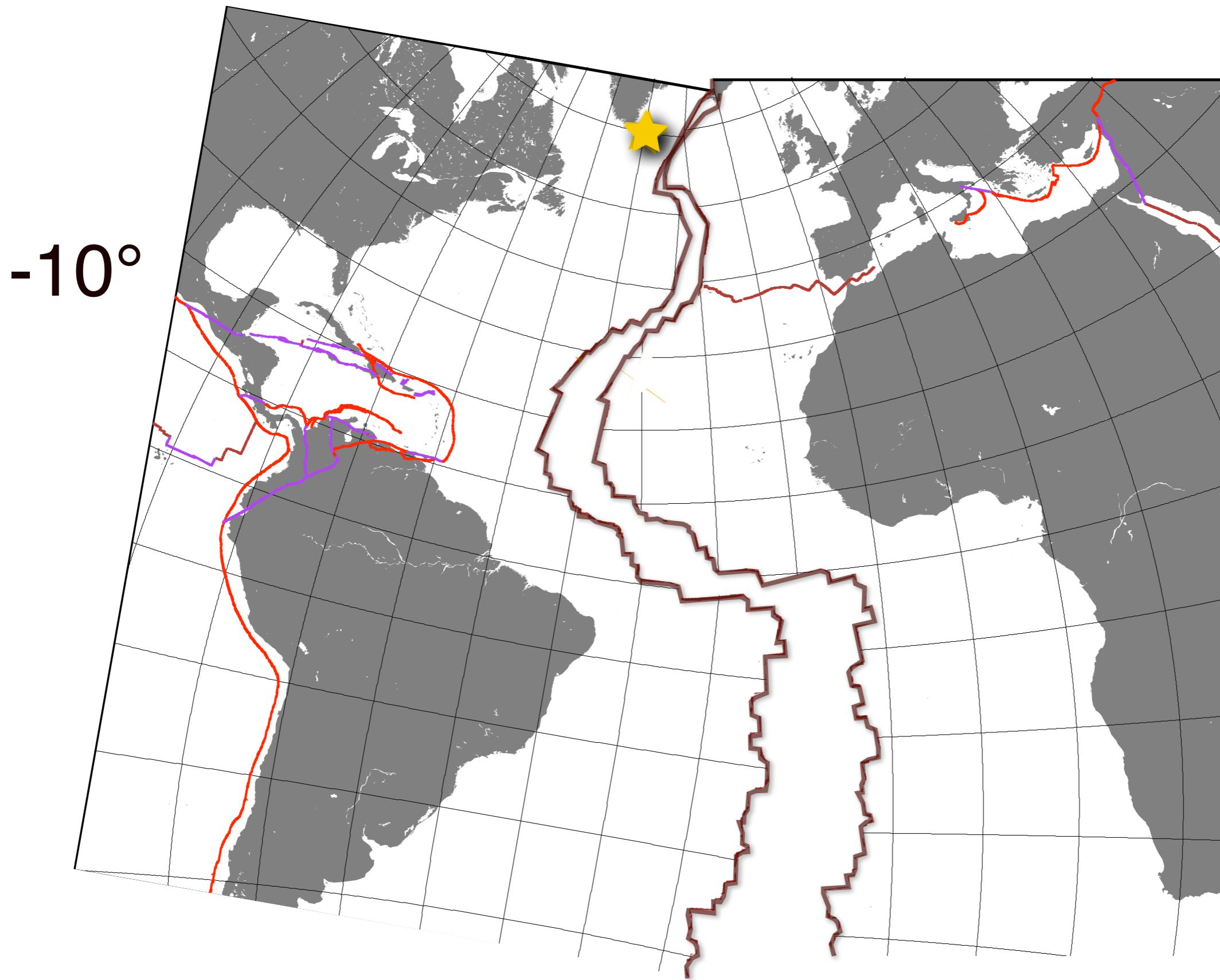
# Atlantic age grid



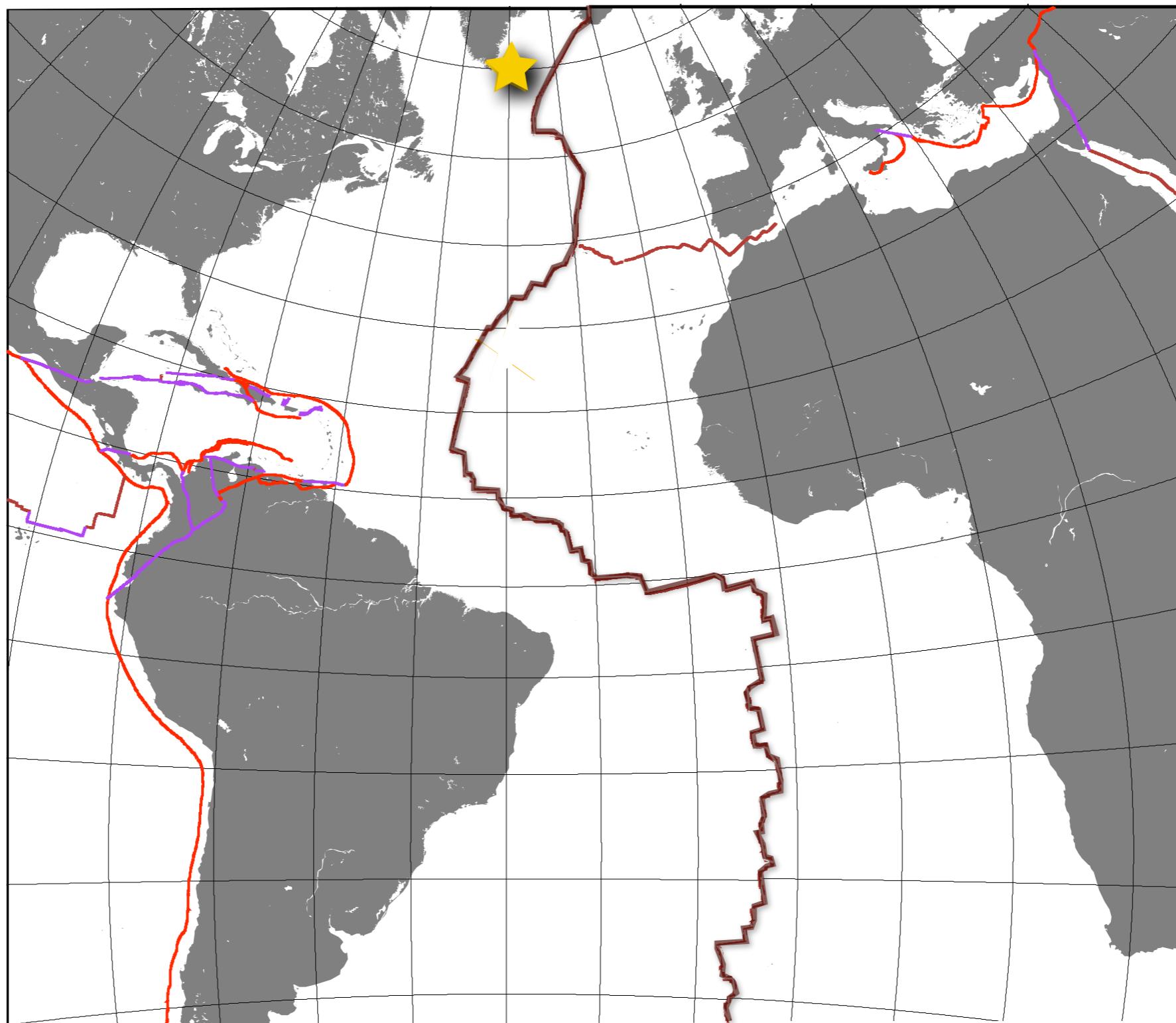




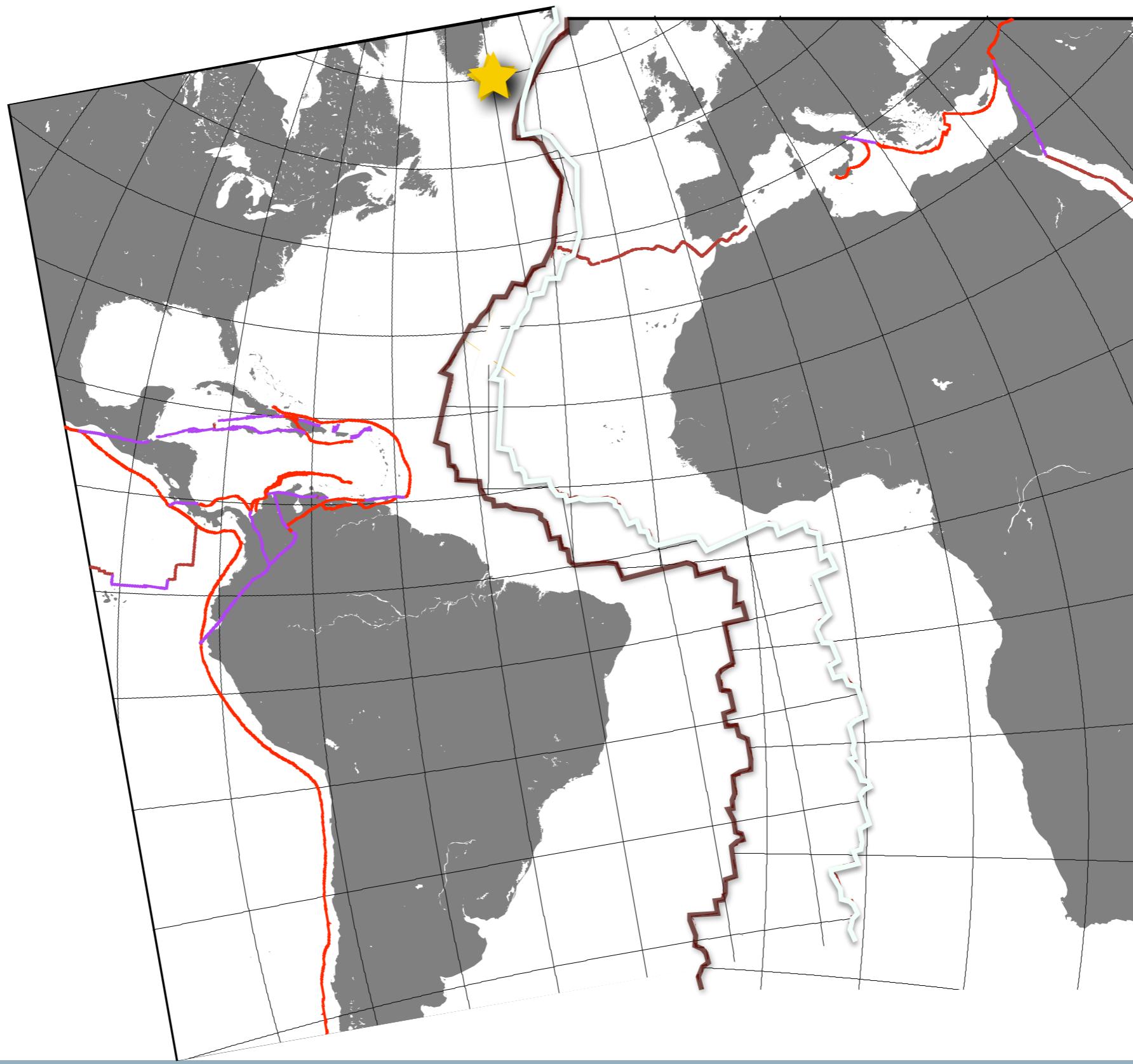




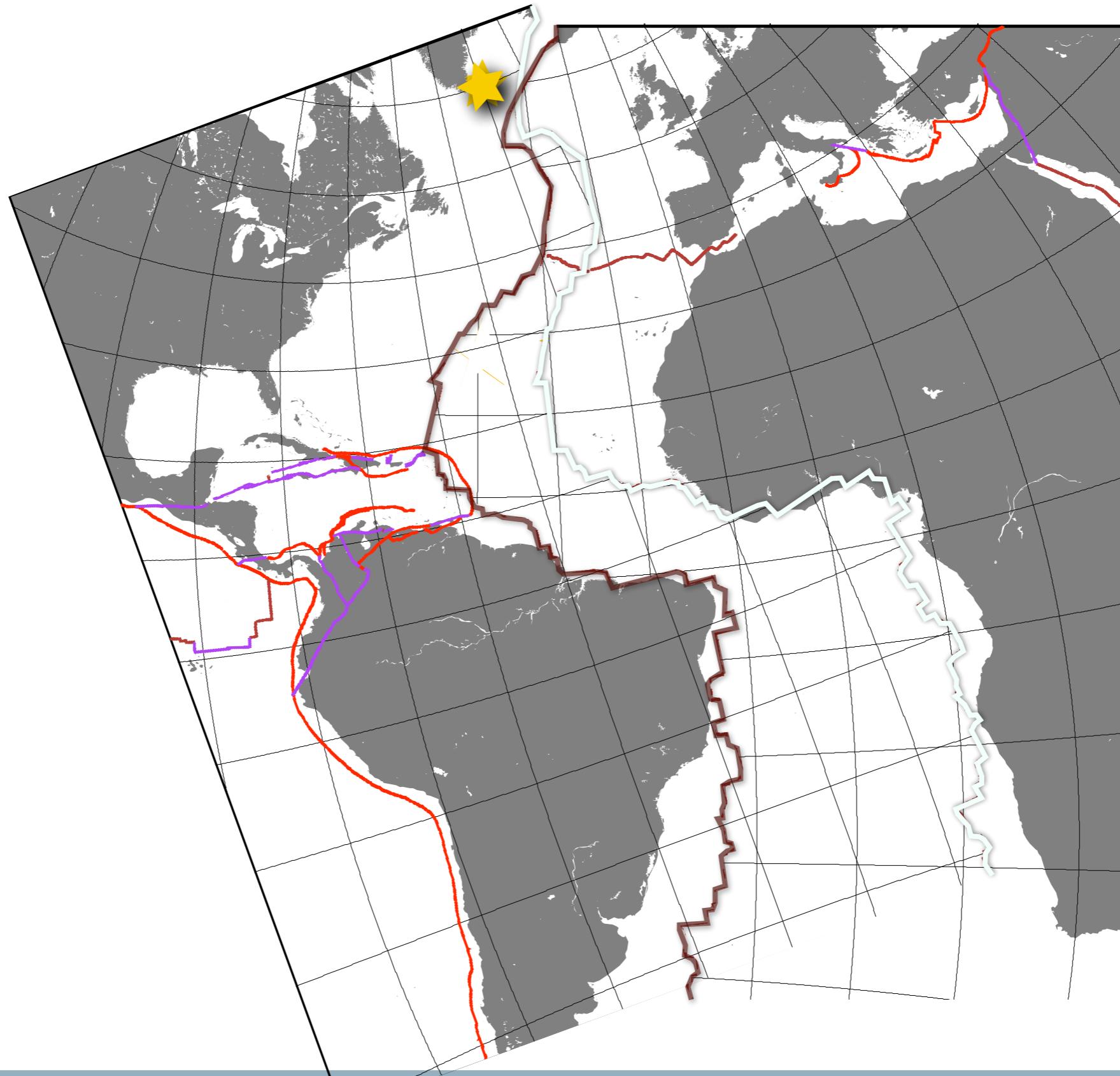
$0^\circ$



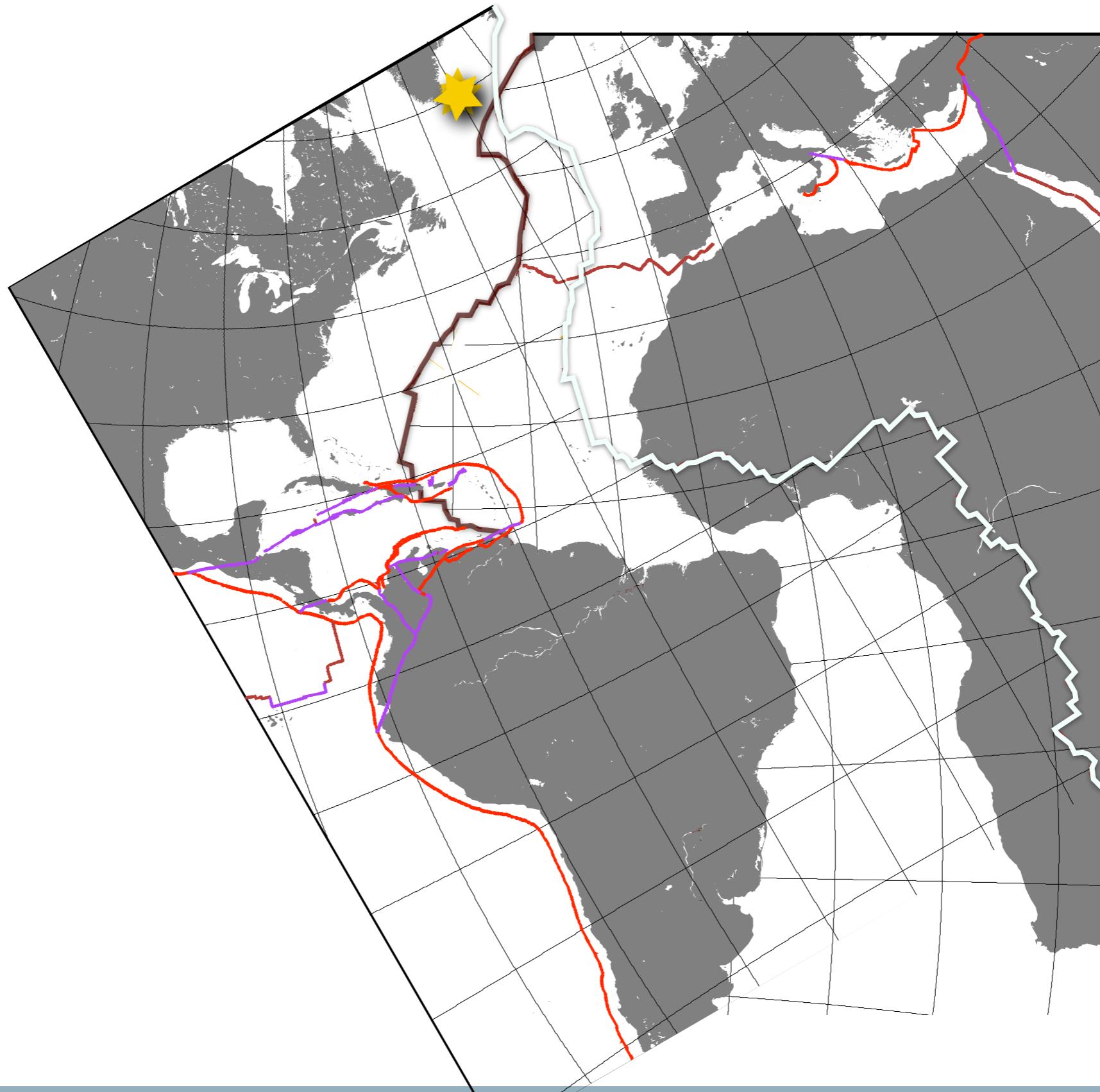
$10^\circ$



$20^\circ$



$30^\circ$



$40^\circ$

