

Recap: Hedge

$$L_{t-1}(i) = \sum_{s=1}^{t-1} l_s(i) \quad W_t(i) = e^{-\eta L_{t-1}(i)}$$

$$W_t = \sum_i W_t(i) \quad p_t(i) = \frac{W_t(i)}{W_t}$$

$$R_T = \sum_{t=1}^T l_t(i) p_t(i) - \sum_{t=1}^T l_t(k_t^*) \leq \frac{\ln K}{\eta} + \frac{\eta}{2} \sum_{t=1}^T \sum_i l_t(i)^2 p_t(i)$$

This inequality holds for $l_t(i) \geq 0$

If $l_t(i) \in [0, 1]$ then $R_T \leq \sqrt{T \ln K}$

Bandit setting

For $t = 1, 2, \dots$

Draw $I_t \sim p_t$

Pay $l_t(I_t)$

Observe $l_t(I_t)$

Update $p_t \rightarrow p_{t+1}$

Cannot compute $L_t(i) = \sum_{s=1}^t l_s(i)$

Trick: importance weighted estimates

$$\hat{l}_t(i) = \begin{cases} l_t(i)/p_t(i) & \text{if } I_t = i \\ 0 & \text{otherwise} \end{cases}$$

Exp3 is Hedge run w/ $\hat{l}_t(i)$ instead of $l_t(i)$

Note: $p_t(i)$ are now random

Fix I_1, \dots, I_T and do Hedge analysis using $\hat{l}_t \geq 0$

$$K_T^* = \operatorname{argmin}_{i=1, \dots, K} \sum_{t=1}^T l_t(i) \quad \hat{R}_T = \sum_t \hat{l}_t(i) p_t(i) - \sum_t \hat{l}_t(K_T^*)$$

$$\hat{R}_T \leq \frac{\ln K}{\eta} + \frac{\eta}{2} \sum_t \sum_i \hat{l}_t(i)^2 p_t(i) \quad (*)$$

\mathcal{F}_{t-1} = σ -algebra generated by I_1, \dots, I_{t-1}

$$\mathbb{E}[\hat{l}_t(i) | \mathcal{F}_{t-1}] = \frac{l_t(i)}{p_t(i)} \underbrace{\mathbb{P}(I_t=i | \mathcal{F}_{t-1})}_\rightarrow p_t(i) + 0 = l_t(i)$$

$$\mathbb{E}[\hat{l}_t(i)^2 | \mathcal{F}_{t-1}] = \frac{l_t(i)^2}{p_t(i)^2} \underbrace{\mathbb{P}(I_t=i | \mathcal{F}_{t-1})}_\rightarrow p_t(i) + 0 \leq \frac{1}{p_t(i)} \rightarrow l_t(i) \in [0, 1]$$

$$\begin{aligned} \mathbb{E}[\hat{R}_T] &= \mathbb{E}\left[\sum_t l_t(i) p_t(i)\right] - \sum_t l_t(K_T^*) \\ &= \mathbb{E}\left[\sum_t l_t(I_t)\right] - \sum_t l_t(K_T^*) \quad \text{regret } \checkmark \end{aligned}$$

From (*)

$$\mathbb{E}[\hat{R}_T] \leq \frac{\ln K}{\eta} + \frac{\eta}{2} \mathbb{E}\left[\sum_t \sum_i \mathbb{E}[\hat{l}_t(i)^2 | \mathcal{F}_{t-1}] p_t(i)\right]$$

$$\leq \frac{\ln K}{\eta} + \frac{\eta}{2} \mathbb{E} \left[\sum_t \sum_i \frac{1}{P_t(i)} P_t(i) \right] = \frac{\ln K}{\eta} + \frac{\eta}{2} K T$$

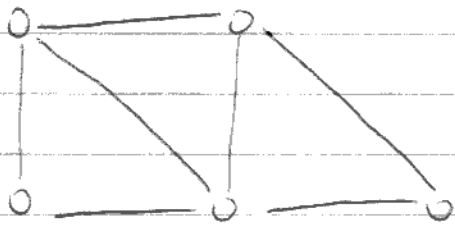
By tuning η , regret is bounded as $\sqrt{K T \ln K}$

We lose \sqrt{K} w.r.t. case when I_t is fully observable

Tuning $\eta_t \approx \sqrt{\frac{K \ln K}{t}}$ gives same bound (up to constants) uniformly over time

Interpolating experts & bandits

View actions as nodes of an undirected graph $G=(V, E)$



If $I_t = i$, then we observe the losses of $\mathcal{N}_i = \{i\} \cup \{j \in V : (i, j) \in E\}$

Experts: G is a clique, Bandits: G has no edges

$$\hat{\ell}_t(i) = \begin{cases} \ell_t(i) / P_t(i) & \text{if } I_t \in \mathcal{N}_i \text{ (}\ell_t(i) \text{ is observed)} \\ 0 & \text{otherwise} \end{cases}$$

$$P_t(i) = \mathbb{P}(I_t \in \mathcal{N}_i | \mathcal{F}_{t-1})$$

As before: ~~$\mathbb{E}[\hat{\ell}_t(i)] = \ell_t(i)$~~ $\mathbb{E}[\hat{\ell}_t(i) | \mathcal{F}_{t-1}] = \ell_t(i)$

$$\text{Also: } \mathbb{E}[\hat{\ell}_t(i)^2 | \mathcal{F}_{t-1}] \leq 1 / P_t(i)$$

Thus:
$$\mathbb{E}[\hat{R}_T] \leq \frac{\ln k}{\eta} + \frac{\eta}{2} \mathbb{E} \left[\sum_t \sum_i \underbrace{\frac{1}{Q_t(i)} p_t(i)}_{(*)} \right]$$

$$(*) = \sum_i \frac{p_t(i)}{\sum_{j \in N_i} p_t(j)} \leq \alpha \quad \text{for any } \{p_t(1), \dots, p_t(k)\}$$

 \hookrightarrow independence number of G

Hence:
$$\mathbb{E}[\hat{R}_T] \leq \frac{\ln k}{\eta} + \frac{\eta}{2} \alpha T \ln k \leadsto \sqrt{\alpha T \ln k}$$

 \hookrightarrow Tuning η

$G = \text{clique (experts)} \quad \boxed{\alpha=1} \Rightarrow \mathbb{E}[\hat{R}_T] \leq \sqrt{T \ln k} \quad \checkmark$

$G = \text{edgeless (bandits)} \quad \boxed{\alpha=k} \Rightarrow \mathbb{E}[\hat{R}_T] \leq \sqrt{k T \ln k} \quad \checkmark$

Exercise: $G = (V, E)$ undirected graph

$$\forall i \in V \quad N_i = \{i\} \cup \{j : (i, j) \in E\}$$

Then
$$\sum_{i \in V} \frac{1}{|N_i|} \leq \alpha \quad \leftarrow \text{Prove it}$$

Online Convex Optimization

S is a convex subset of a linear space

For $t = 1, 2, \dots$

- Play $w_t \in S$
- Observe convex loss $l_t: S \rightarrow \mathbb{R}$
- Pay $l_t(w_t)$
- Update $w_t \rightarrow w_{t+1} \in S$

$$\text{Regret } R_T(u) = \sum_{t=1}^T (l_t(w_t) - l_t(u)) \quad \forall u \in S$$

Experts: $w_t = p_t$ $S = \text{simplex}$ $l_t(p) = p_t^T p$
linear loss

$$R_T(q) = \sum_t (p_t^T l_t - q^T l_t) \quad \text{best } q \text{ always a corner of the simplex}$$

Follow the leader (FTL)

$$w_{t+1} = \underset{w \in S}{\operatorname{argmin}} \sum_{s=1}^t l_s(w) \quad \text{has linear regret in the worst case!}$$

$$S = [-1, 1] \quad l_1(w) = \frac{w}{2} \quad l_t(w) = \begin{cases} -w & t \text{ even} \\ w & t \text{ odd} \end{cases}$$

$$\text{Then } \sum_{s=1}^t l_s(w) = \begin{cases} -w/2 & t \text{ even} \\ w/2 & t \text{ odd} \end{cases}$$

Therefore $w_{t+1} = \begin{cases} 1 & t \text{ even} \\ -1 & t \text{ odd} \end{cases} \Rightarrow \forall b, l_{t+1}(w_{t+1}) = 1$

FTL \nearrow

Introduce regularization to add stability

Follow the regularized leader (FTRL)

$$w_{t+1} = \arg \min_{w \in S} \left[\eta \sum_{s=1}^t l_s(w) + \Phi(w) \right]$$

\uparrow strongly convex function

$\Phi: S \rightarrow \mathbb{R}$ is β -s.c. w.r.t. a norm $\|\cdot\|$ if $\forall U, V \in S$

$$\Phi(V) \geq \Phi(U) + \nabla \Phi(U)^T (V - U) + \frac{\beta}{2} \|U - V\|^2$$

- Euclidean norm is 1-sc w.r.t. $\|\cdot\|_2$

- Entropy $\sum_i p_i \ln p_i$ is 1-sc w.r.t. $\|\cdot\|_1$ (p in the simplex)

$\hookrightarrow \frac{1}{2} \|\cdot\|_2^2$

Linearization trick (using convexity of losses)

$$l_t(w_t) - l_t(u) \leq \underbrace{\nabla l_t(w_t)}_{\nabla_t}^T (w_t - u)$$

FTRL w/ linearized losses

$$W_{t+1} = \underset{W \in S}{\operatorname{argmin}} \left[\eta \sum_{s=1}^t \nabla_s^T W + \Phi(W) \right] \quad \Theta_{t+1} = -\eta \sum_{s=1}^t \nabla_s$$

$$= \underset{W \in S}{\operatorname{argmax}} \left[\Theta_{t+1}^T W - \Phi(W) \right] = \nabla \Phi^*(\Theta_{t+1})$$

$$\Phi^*(\theta) = \max_{W \in S} (\theta^T W - \Phi(W)) \quad \text{is convex dual of } \Phi$$

If Φ is sc. then Φ^* is convex and differentiable

Online Mirror Descent (OMD)

$$\Theta_t = (\theta_1, \dots) \in \mathbb{R}^d$$

For $t = 1, 2, \dots$

$$\text{Play } w_t = \nabla \Phi^*(\Theta_t) \quad (\text{mirror step})$$

$$\text{Pay } \ell_t(w_t)$$

$$\text{Observe } \nabla_t = \nabla \ell_t(w_t)$$

$$\text{Update } \Theta_{t+1} = \Theta_t - \eta \nabla_t \quad (\text{gradient step})$$

$$\text{Entropic regularization } \Phi(p) = \sum_i p_i \ln p_i$$

$$\Phi^*(\theta) = \ln \sum_i e^{\theta_i} \quad \nabla \Phi^*(\theta)_i = e^{\theta_i} / \sum_j e^{\theta_j}$$

$$\text{Recall } \Theta_t = -\eta \sum_{s=1}^{t-1} \nabla_s \quad \text{if } \ell_t \text{ are linear then OMD} \equiv \text{Hedge}$$