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ile.mlx

CASE1234.mlx

MainDoc1.mlx

MainDoc1234.mlx

Research13d.mlx

GeoPosi

Name

MainDoc1.pdf ...

MainDoc12.pdf ...

MainDoc1234.r ...

MainDoc1234.p ...

Mainfile.docx ...

Mainfile.mlx ...

Mainfile.pdf ...

Mainfile1.pdf ...

Mainfile1234.p ...

matlab.mat ...

Minimum.mlx ...

minmaxloop.ml ...

movingRectang ...

Relative.mlx ...

Relative.slx ...

Research13d.n ...

rough.pdf ...

RV_1.asv ...

RV_1.m ...

Scrip.m ...

signal_time.mlx ...

TAV_case1.pdf ...

TAV_case2.pdf ...

TAV_case3.pdf ...

TAV_case4.mlx ...

TAV.mat ...

1

function Rv = RV_1(vt,v1)

2

Rv=abs(vt-v1);

3

end

4

5

function combs = Combinations(vt,v1)

6

[m,n] = ndgrid(vt,v1);

7

combs = [m(:),n(:)];

8

end

9

10

function Ancombsind = AngleCombinations(vt,f)

11

[m,n] = ndgrid(vt,f);

12

Anvalue = [m(:),n(:)];

13

a=Anvalue(:,1);

14

b=Anvalue(:,2);

15

c=sind(b);

16

Ancombsind = a.*c;

17

end

18

|

19

% CASE 1

20

% Fix values

21

vt=40:60;

22

v1=0;

23

V2=60:130;

24

V3=60:130;

25

V4=0;

26

f2=30:90;

27

f4=30:90;

28

29

% %car1

30

% combs = Combinations(vt,v1);

31

% a= combs(:,1);

32

% b= combs(:,2);

33

% if a==b

34

% Rv1=0;

35

% else

36

COMMAND WINDOW