

t-SNE Notes

Pavlin Poličar

1 Fast KL Divergence

During computation of negative gradients, we do not know the value of the normalization term Z during intermediate steps. Therefore, in order to compute the KL divergence of the embedding, we would need to iterate over all the p_{ij} s again, at the end of the gradient computation step. By rewriting the KL divergence in terms of unnormalized q_{ij} s, we can save on computation time.

$$\begin{aligned} KL(P || Q) &= \sum_{ij} p_{ij} \log \frac{p_{ij}}{q_{ij}} \\ &= \sum_{ij} p_{ij} \log \left(p_{ij} \frac{Z}{\hat{q}_{ij}} \right) \end{aligned}$$

where \hat{q}_{ij} denotes the unnormalized values q_{ij}

$$= \sum_{ij} p_{ij} \log \frac{p_{ij}}{\hat{q}_{ij}} + \sum_{ij} p_{ij} \log Z$$

2 KL Divergence with exaggeration

The implemented optimization methods don't have a notion of exaggeration, they simply take an affinity matrix P containing the probabilities of points j appearing close to i . Exaggeration is used to scale P by some constant factor α to help separate clusters in the beginning of the optimization. These methods also compute the KL divergence, and as such, it is incorrect because we don't account for α .

This section derives a quick and simple correction for the KL divergence error term so we can get the true error of the embedding even when P is exaggerated.

$$KL(P || Q) = \sum_{ij} p_{ij} \log \frac{p_{ij}}{q_{ij}} \tag{1}$$

We need to introduce the scaling i.e. exaggeration factor α

$$= \sum_{ij} \frac{\alpha}{\alpha} p_{ij} \log \frac{\alpha p_{ij}}{\alpha q_{ij}} \tag{2}$$

Exaggeration means that the p_{ij} terms get multiplied by α , so we need to find an expression for the KL divergence that includes only αp_{ij} and q_{ij} and some other factor that will correct for α .

$$= \frac{1}{\alpha} \sum_{ij} \alpha p_{ij} \left(\log \frac{\alpha p_{ij}}{q_{ij}} - \log \alpha \right) \quad (3)$$

$$= \frac{1}{\alpha} \left(\sum_{ij} \alpha p_{ij} \log \frac{\alpha p_{ij}}{q_{ij}} - \sum_{ij} \alpha p_{ij} \log \alpha \right) \quad (4)$$

The first term is computed by the negative gradient method (since it only knows about the scaled P), the second term can easily be computed post-optimization, allowing us to get the correct KL divergence.