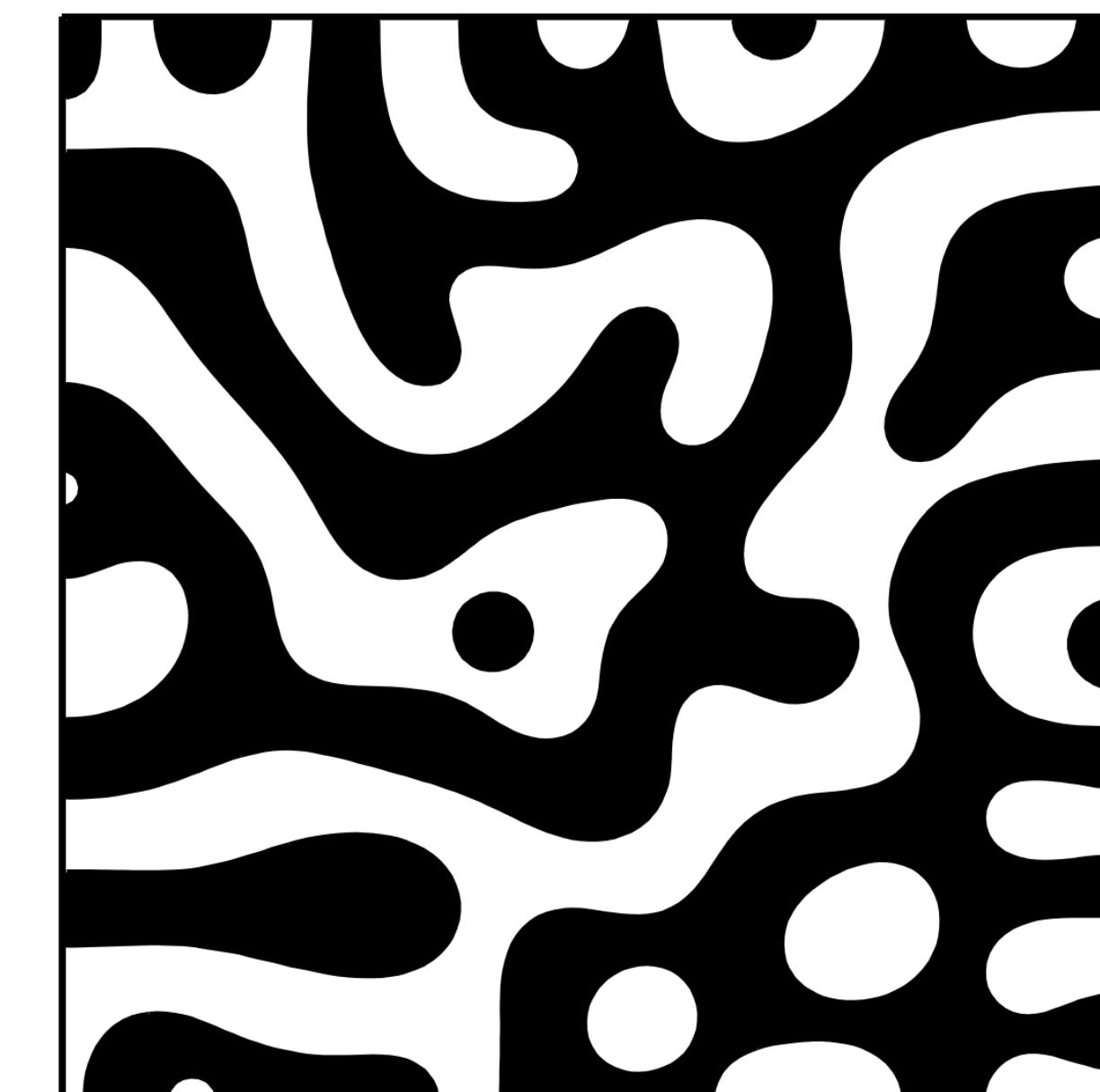
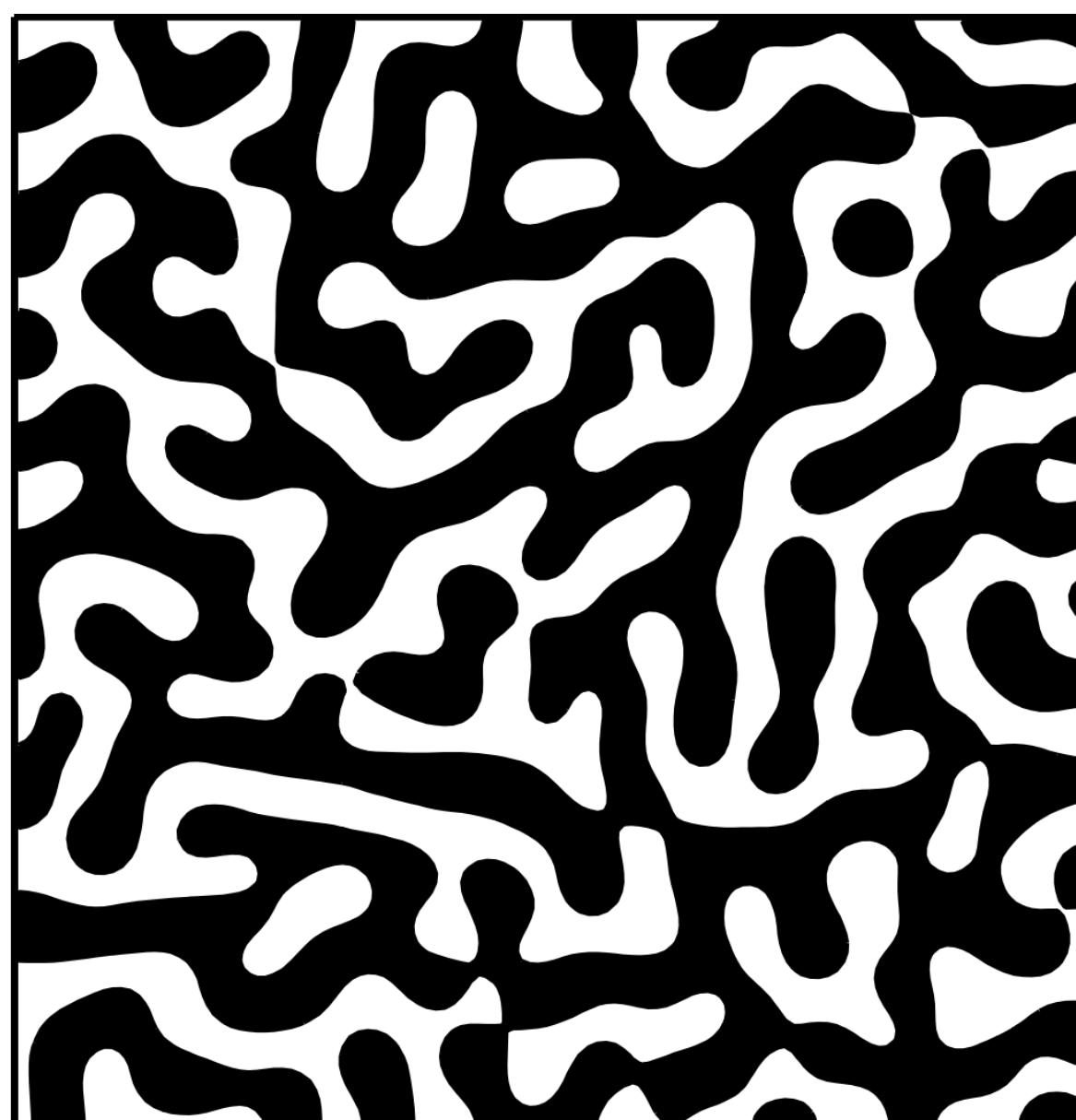
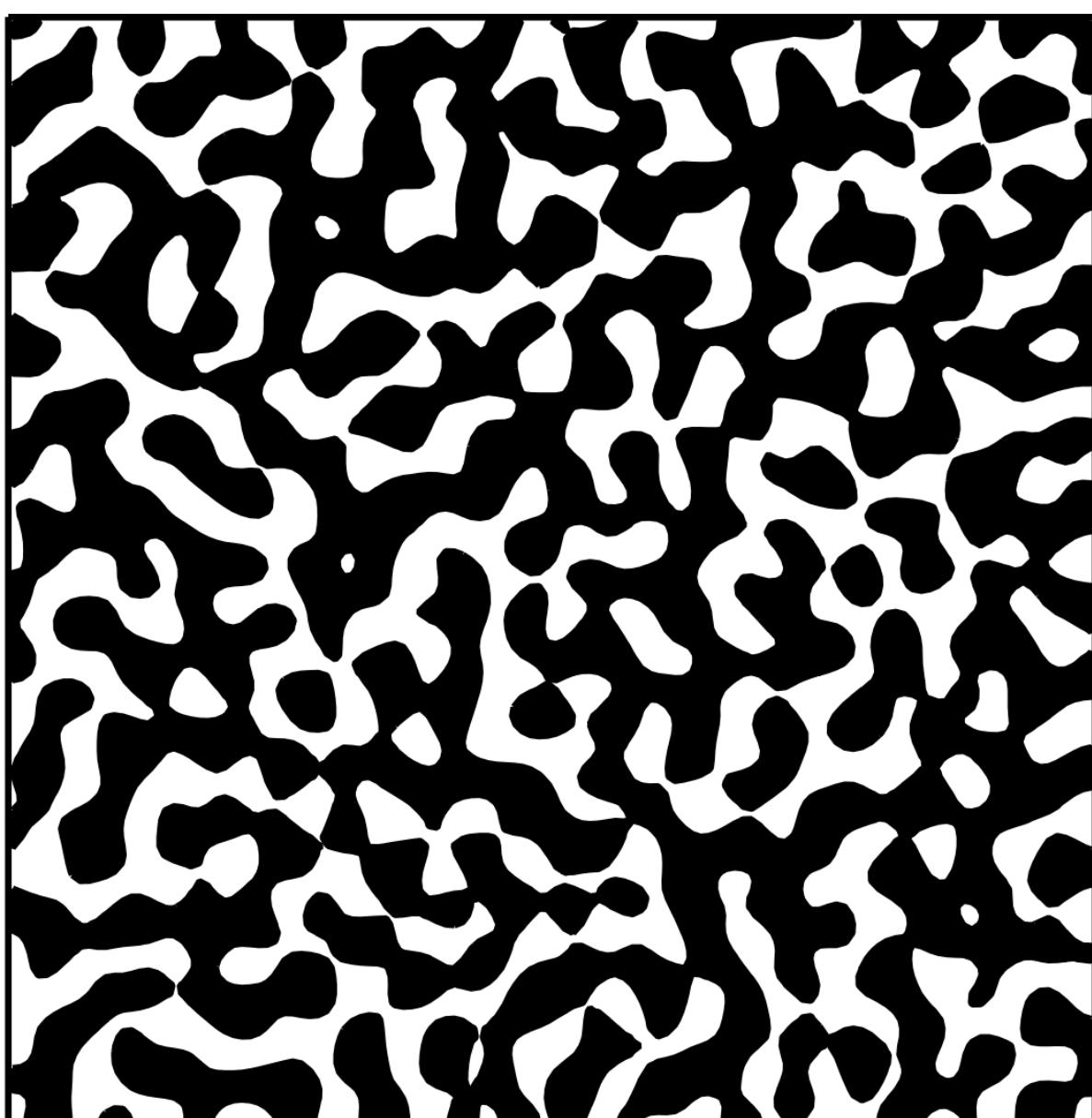


Numerical Analysis of the Cahn-Hilliard Equation with Runge-Kutta Methods

APC 523 Final Project

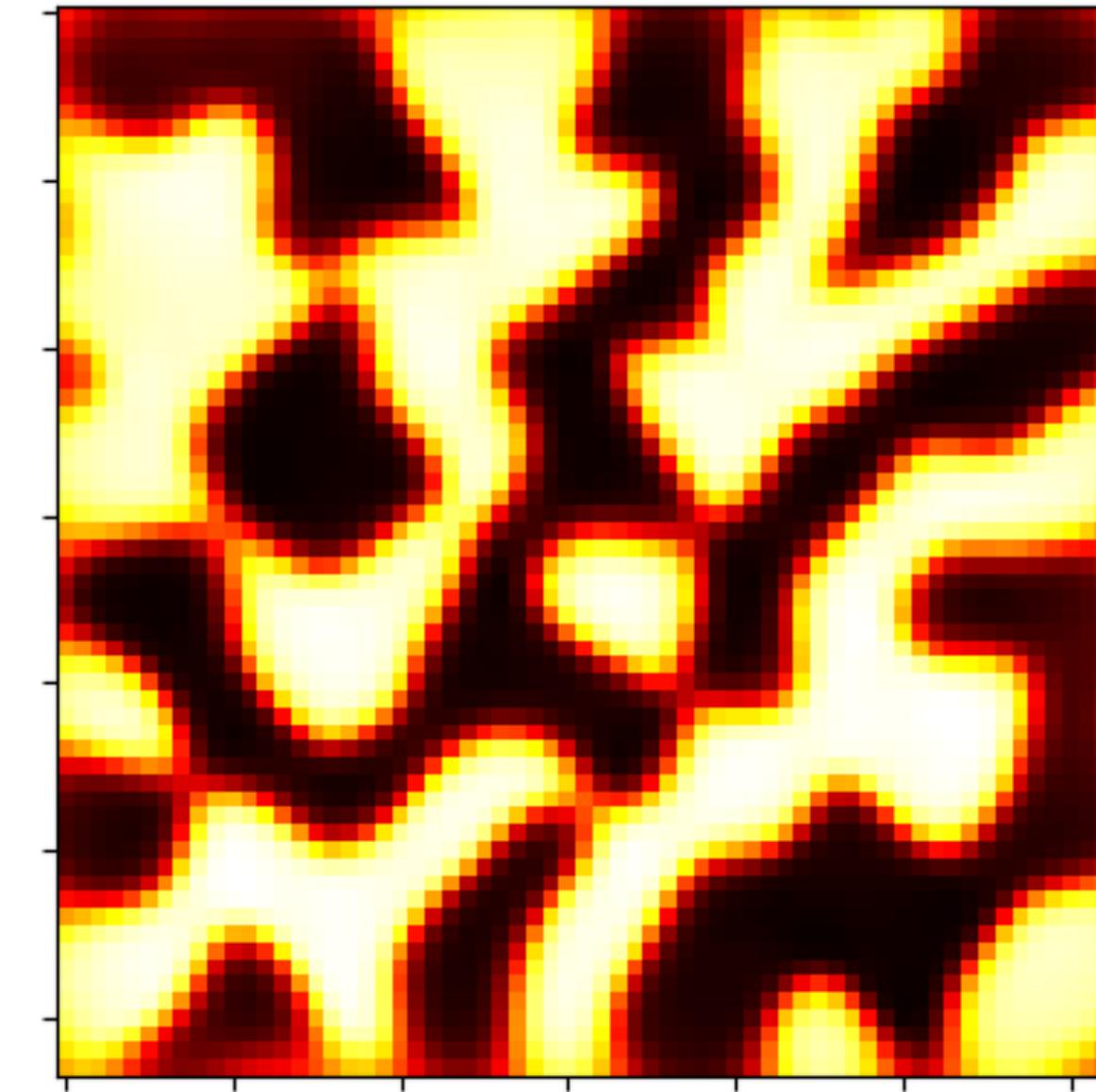
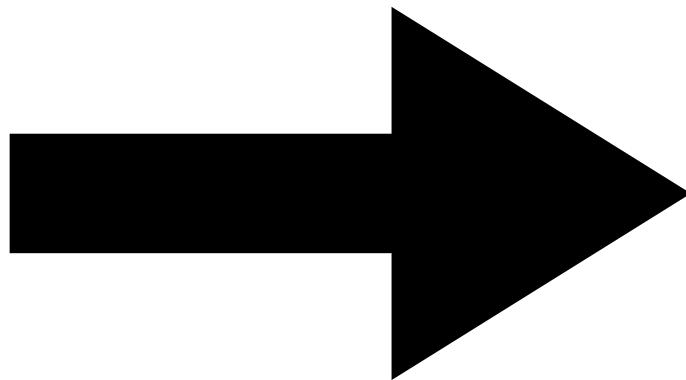
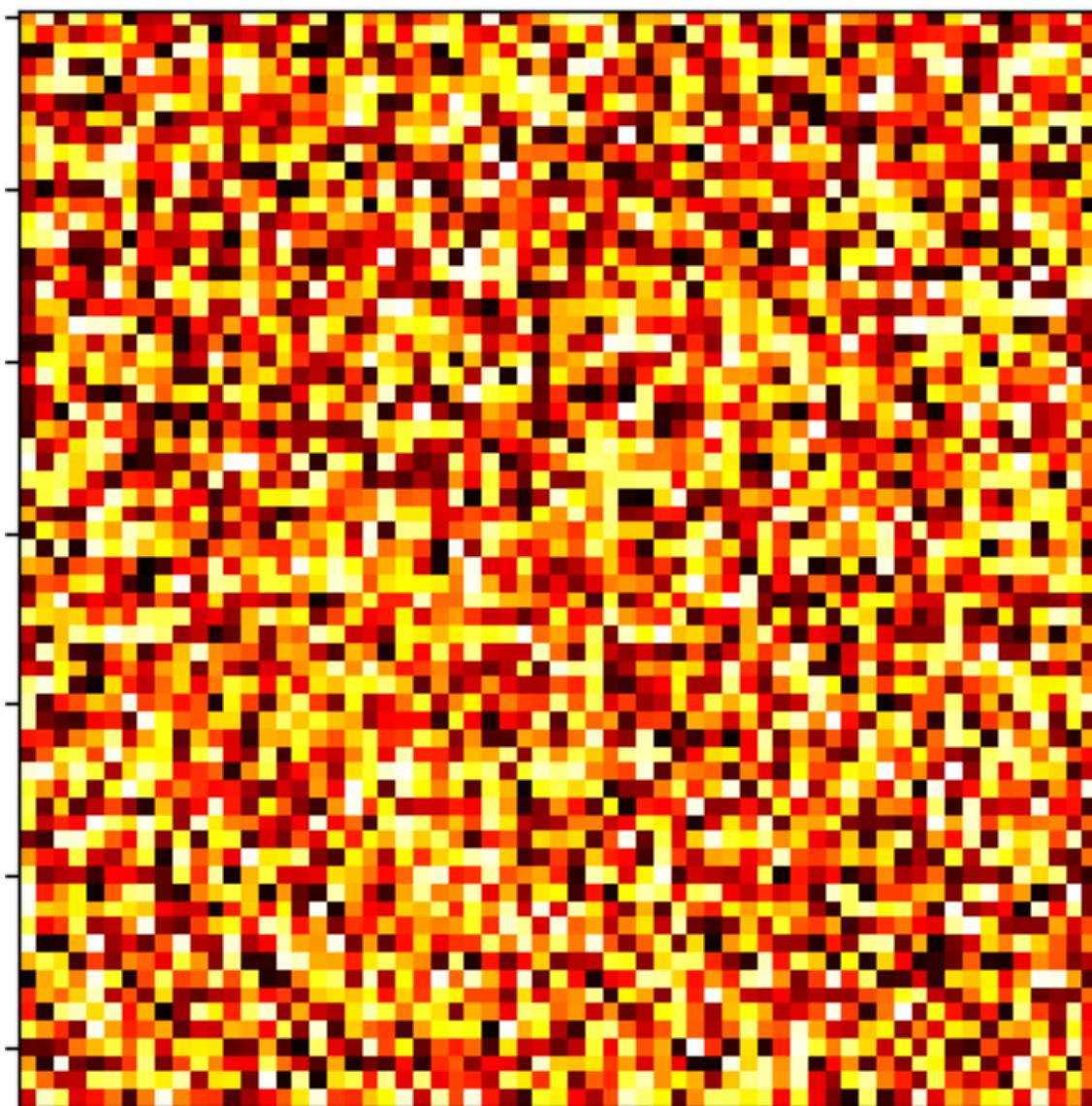
Jeremiah Coleman



Spinodal Decomposition

Introduction to Highly Disordered Materials

- Spontaneous phase transition in binary materials from homogenous mix to islands rich in one component and matrix rich in the other



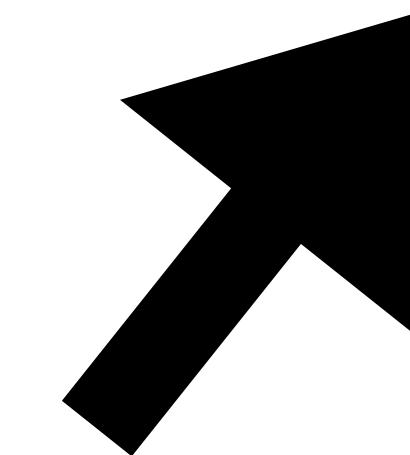
- Governed by the Cahn-Hilliard Equation

$$\frac{\partial \mathbf{c}}{\partial t}(\mathbf{x}, t) = \nabla \cdot [M(\mathbf{c}) \cdot \nabla \mu(\mathbf{c})], \quad \mathbf{c} \in \Omega, \quad t > 0$$

Intuition of Cahn-Hilliard Equation

Reduces total energy of the system

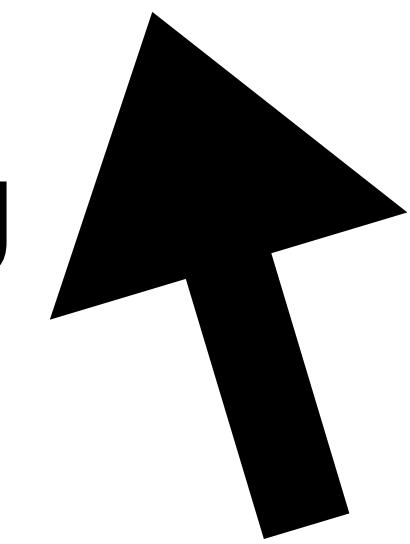
$$E(c, t) = \int_{\Omega} \frac{\kappa}{2} |\nabla c|^2 + f(c, t) d\mathbf{x}$$



Coarsening

Reduce the number of interfaces between the two components

System will reduce energy by minimizing these values



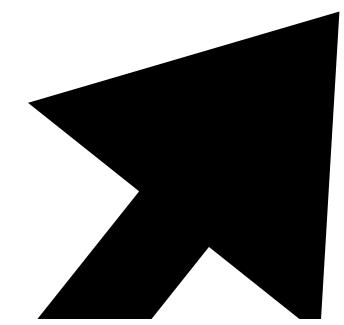
Separation

Find concentrations that minimize the local atomic energy

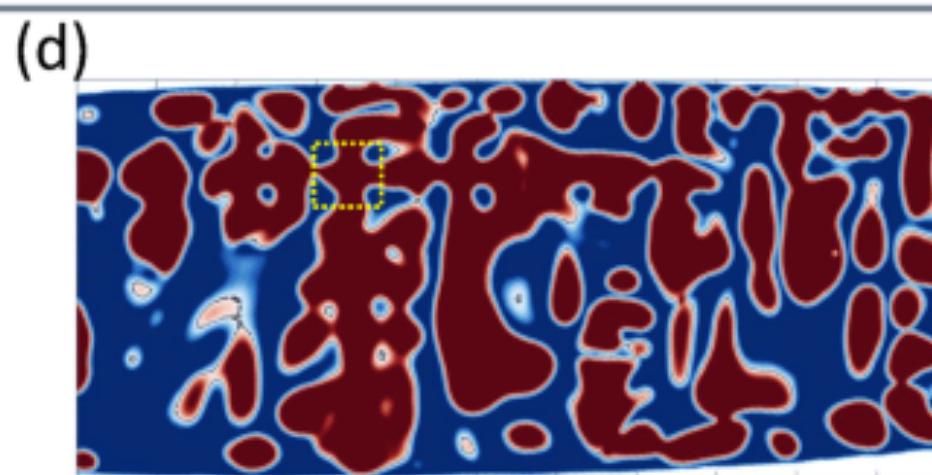
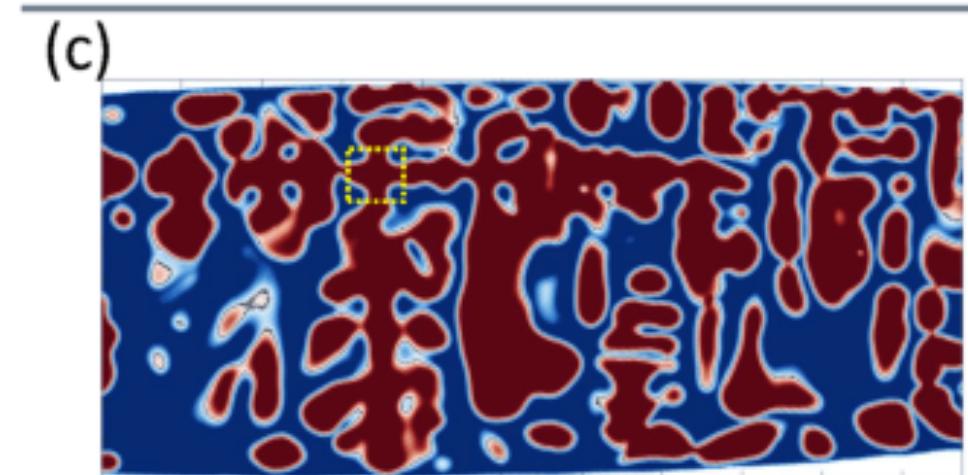
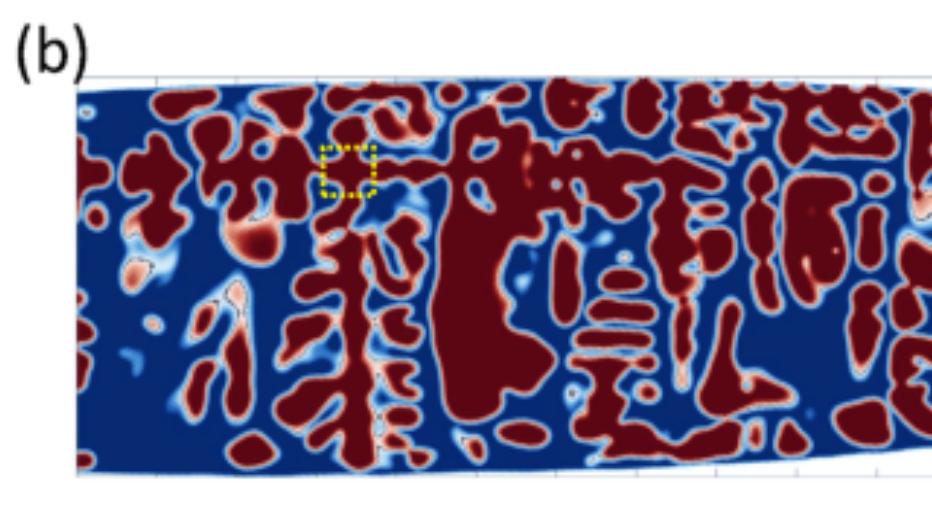
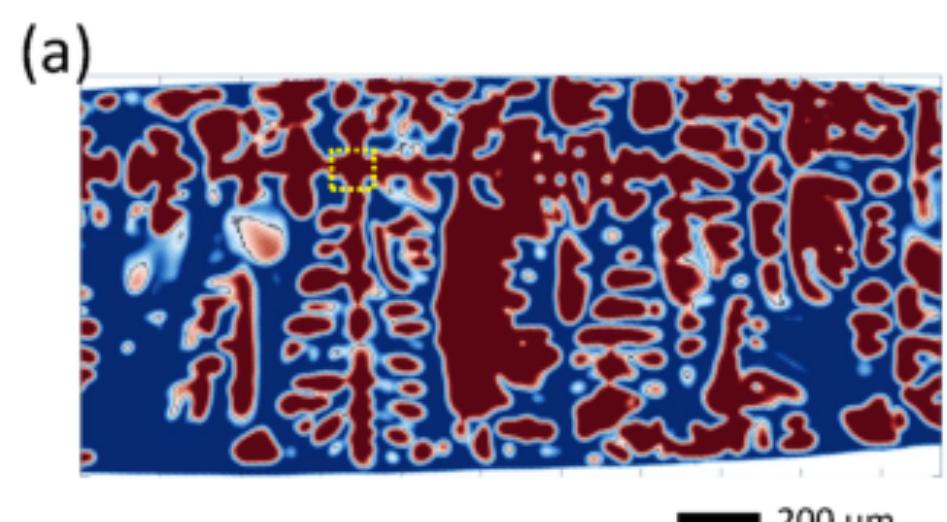
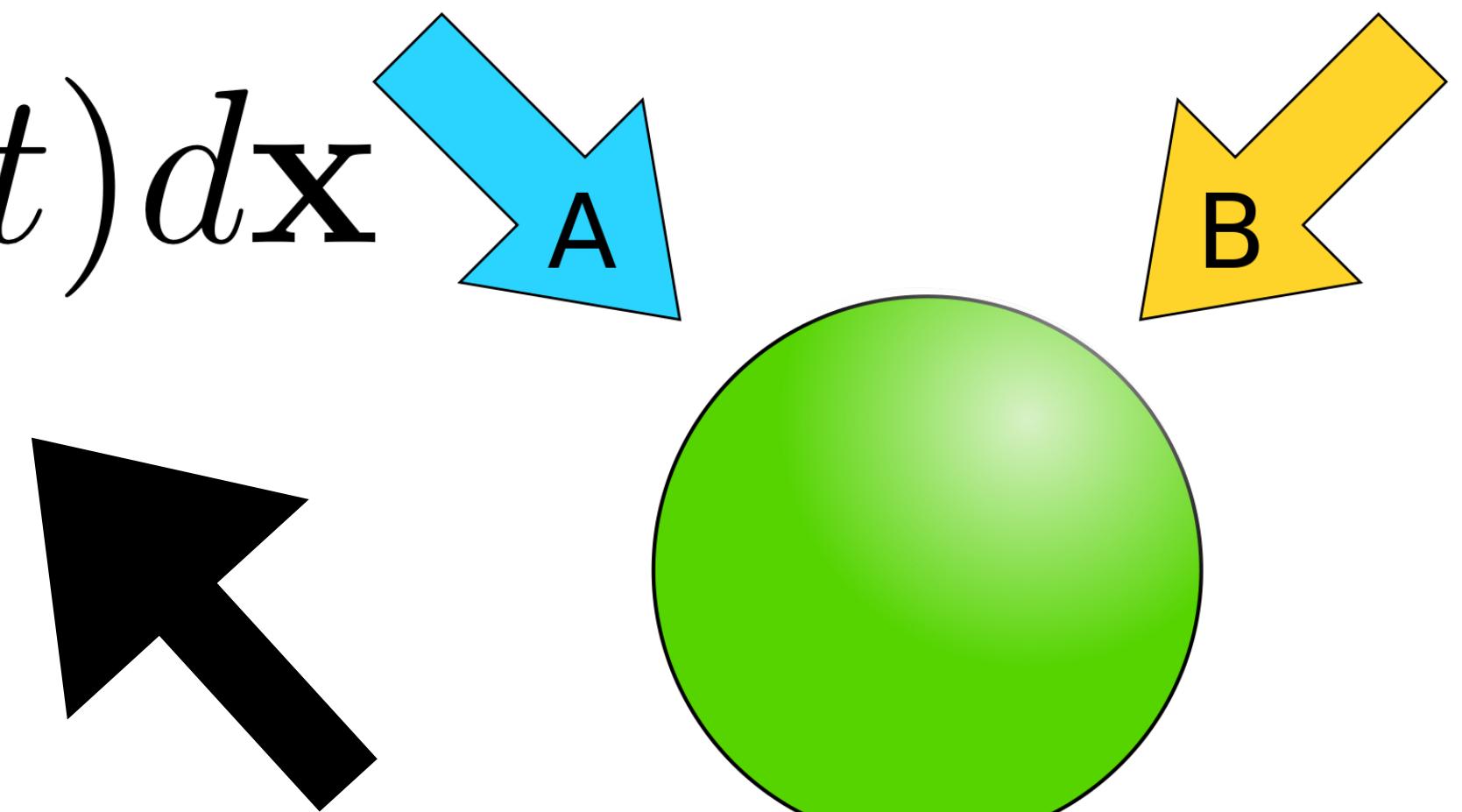
Intuition of Cahn-Hilliard Equation

Reduces total energy of the system

$$E(c, t) = \int_{\Omega} \frac{\kappa}{2} |\nabla c|^2 + f(c, t) d\mathbf{x}$$



System will reduce
energy by minimizing
these values



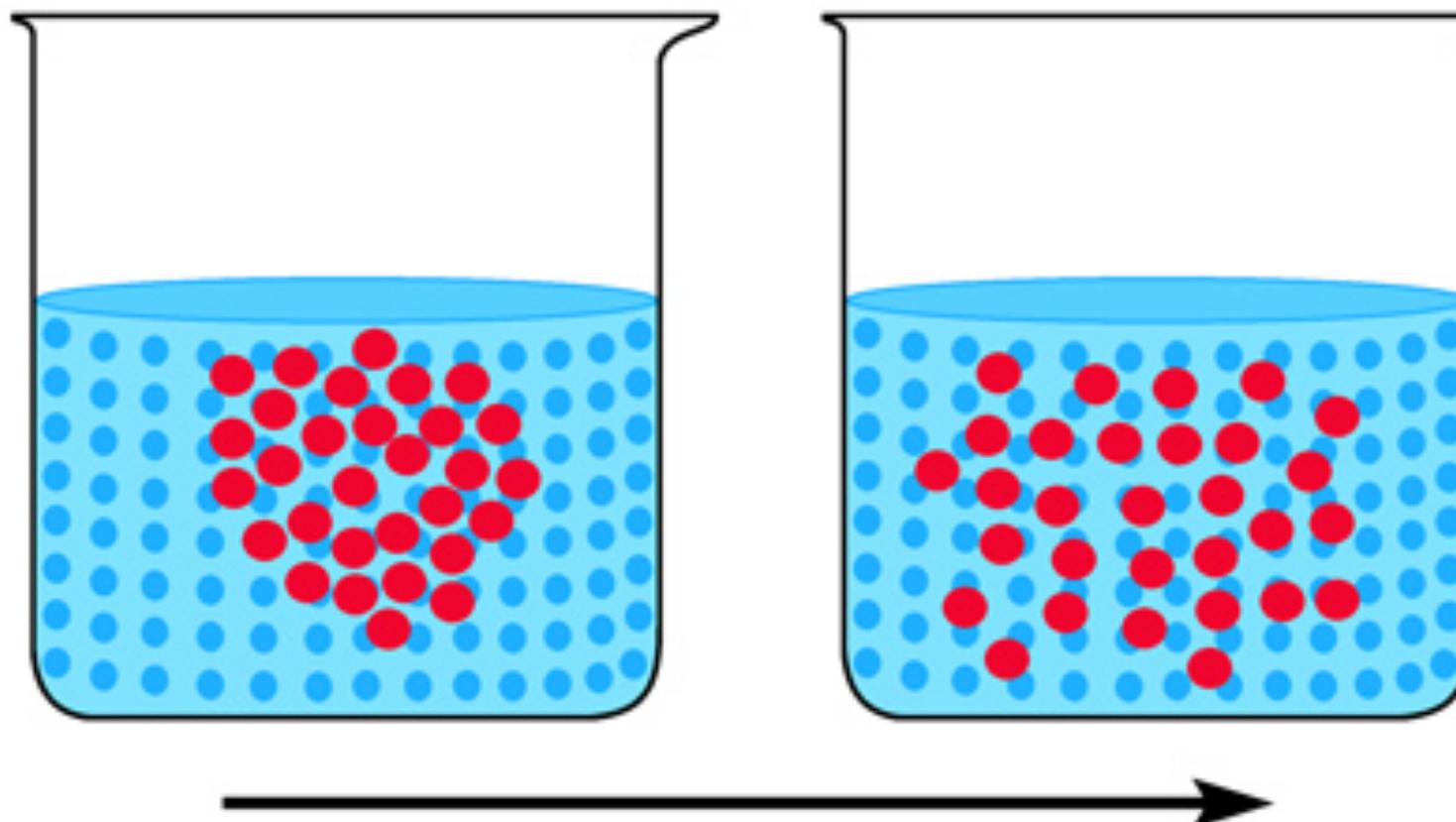
Derivation of Cahn-Hilliard Equation

Frick's First and Second Laws

Movement of a component (diffusive flux) is related to concentration gradient.

Isolated systems chemical potential drives configuration change

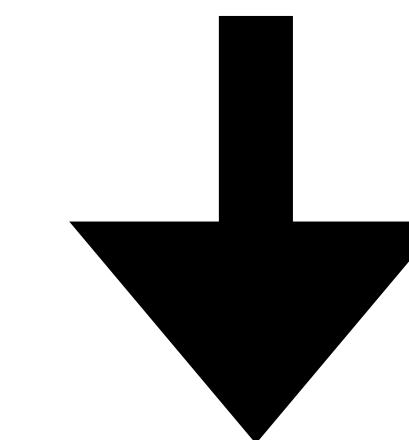
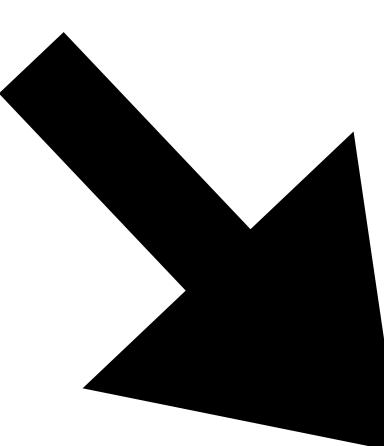
$$J = -M(\mathbf{x}, t) \cdot \nabla \mu(\mathbf{c}, t)$$



Particles diffusing from high to low concentration

Diffusing component must obey the *conservation of mass* and the continuity equation

$$0 = \frac{\partial \mathbf{c}}{\partial t}(\mathbf{x}, t) + \nabla J$$



$$\frac{\partial \mathbf{c}}{\partial t}(\mathbf{x}, t) = \nabla \cdot [M(\mathbf{c}) \cdot \nabla \mu(\mathbf{c})]$$

Derivation of *Modified Cahn-Hilliard* Equation

Chemical potential is the rate of change of energy!

$$\frac{\partial \mathbf{c}}{\partial t}(\mathbf{x}, t) = \nabla \cdot [M(\mathbf{c}) \cdot \nabla \mu(\mathbf{c})].$$

$$0 = \frac{\partial \mathbf{c}}{\partial t}(\mathbf{x}, t) - \nabla \left(M(\mathbf{x}, t) \cdot \nabla \frac{\partial E(\mathbf{c}, t)}{\partial \mathbf{c}} \right)$$

$$0 = \frac{\partial \mathbf{c}}{\partial t}(\mathbf{x}, t) - \nabla \left(M(\mathbf{x}, t) \cdot \nabla \left(-\kappa \nabla^2 \mathbf{c} + \frac{df(\mathbf{c}, t)}{d\mathbf{c}} \right) \right)$$

$$\frac{\partial \mathbf{c}}{\partial t}(\mathbf{x}, t) = \nabla \left(M(\mathbf{x}, t) \cdot \nabla \left(\frac{\partial f(\mathbf{c}, t)}{\partial \mathbf{c}} - \kappa \nabla^2 \mathbf{c} \right) \right)$$

Equilibrium of *Modified* Cahn-Hilliard Equation

Minimize total energy by coarsening and minimize $f(c)$

$$\frac{\partial c}{\partial t}(\mathbf{x}, t) = \nabla \left(M(\mathbf{x}, t) \cdot \nabla \left(\frac{\partial f(c, t)}{\partial c} - \kappa \nabla^2 c \right) \right)$$

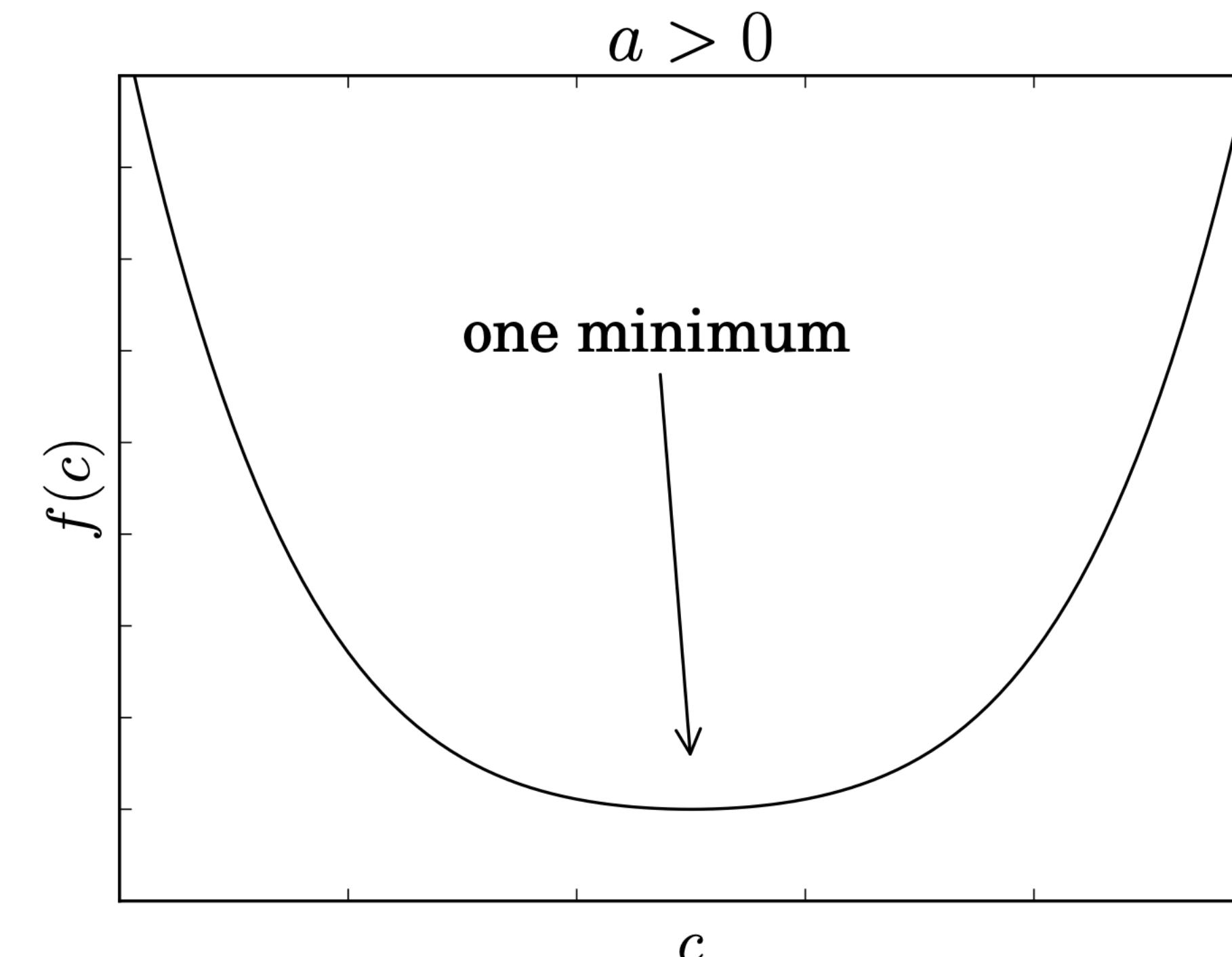
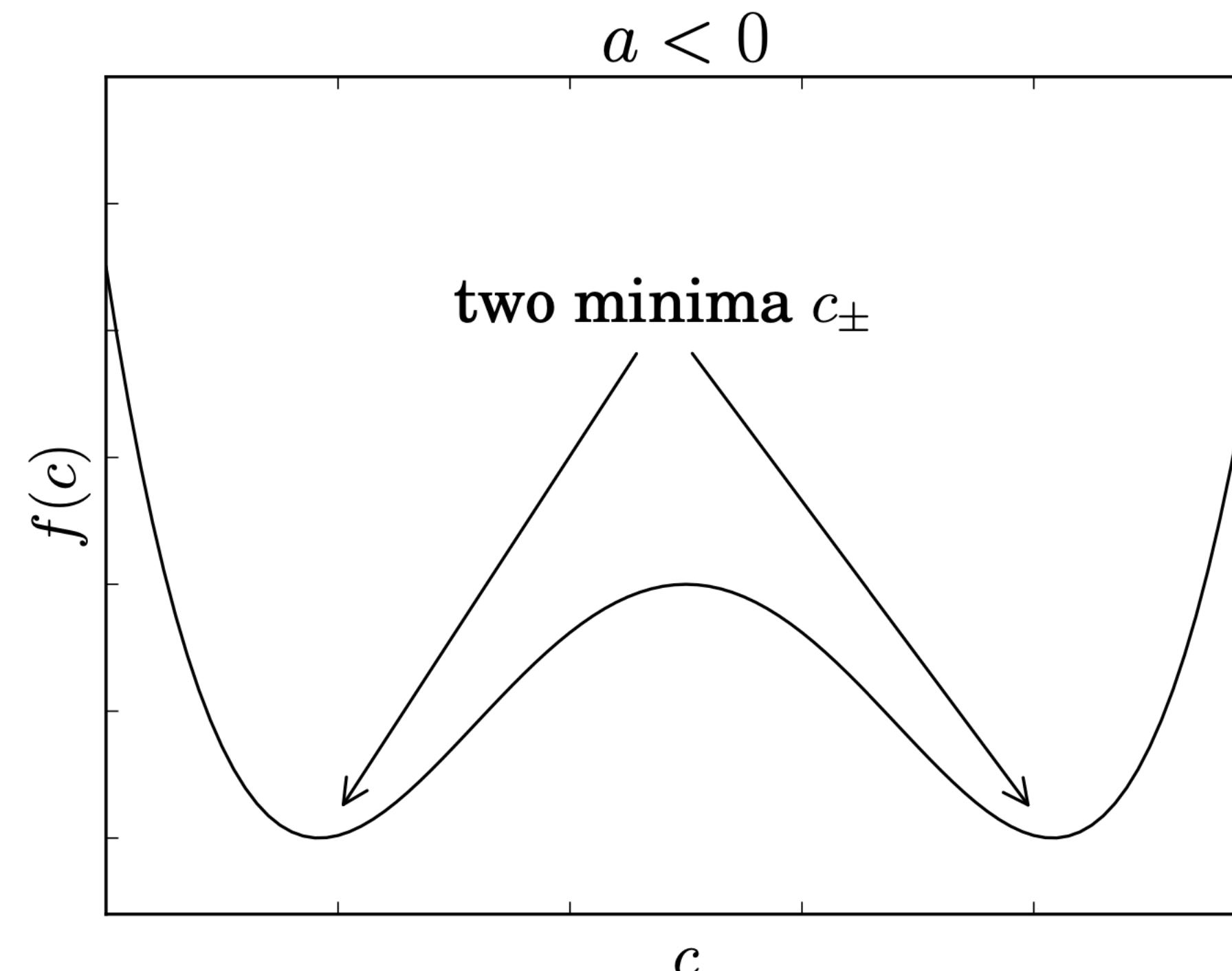
Reasonable approximation of real local energy binary system is a polynomial double well potential

$$f(c, t) = \frac{a(t)c^2}{2} + \frac{b(t)c^4}{4}$$

Equilibrium of *Modified Cahn-Hilliard* Equation

Spinodal Decomposition occurs when $a < 0$

$$f(c, t) = \frac{a(t)c^2}{2} + \frac{b(t)c^4}{4}$$



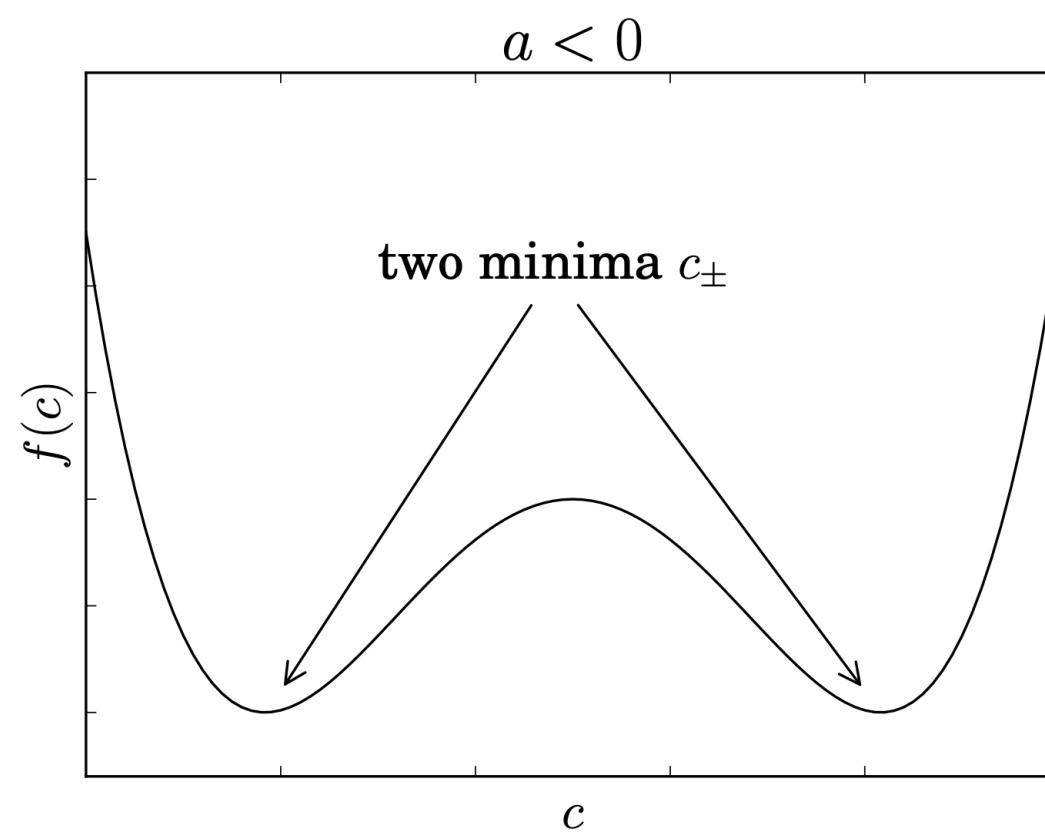
Simple *Modified* Cahn-Hilliard Equation

System will quickly separate and slowly coarsen

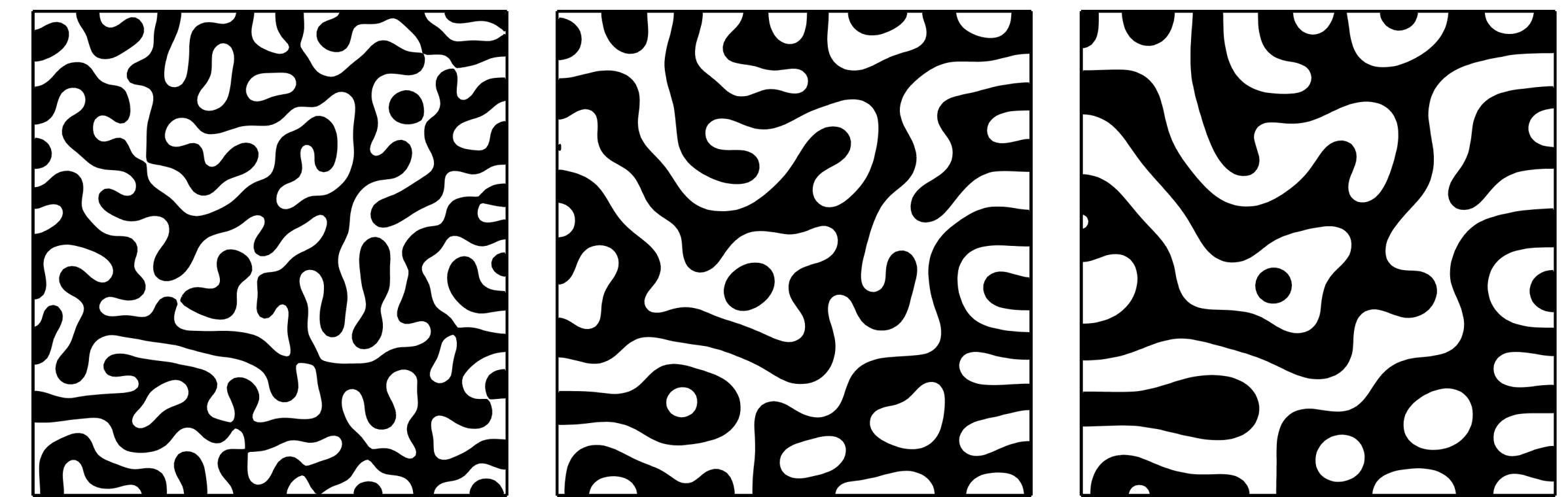
$$\frac{\partial c}{\partial t}(\mathbf{x}, t) = \nabla(M_0(\mathbf{x}, t) \cdot \nabla \mu(c, t))$$

$$\mu(c, t) = bc^3 + ac - \kappa \nabla^2 c$$

Quickly system
separates into two
minima at -1 and 1



Slowly the system will
reduce barriers via
coarsening



Numerical Scheme Methodology for Cahn-Hilliard Equation

Stiff non-linear fourth order partial differential equation

Need schemes with following traits:

- *Symplectic* inheriting decreasing energy
- *Time adaptivity* due to the drastically different time scales of separation and coarsening
- Ideally be *L-stable*

Finite Difference Spatial Discretization

2nd Order Central Finite Difference for Simplicity

$$\frac{\partial \mathbf{c}}{\partial t}(\mathbf{x}, t) = M_0 \Delta_h f'(\mathbf{c}) - M_0 \kappa \Delta_h^2 \mathbf{c} \quad (17)$$

where

$$\Delta_h f'(\mathbf{c}) = \frac{f'(\mathbf{c}_{i-1,j}) - 2f'(\mathbf{c}_{i,j}) + f'(\mathbf{c}_{i+1,j})}{h^2} + \frac{f'(\mathbf{c}_{i,j-1}) - 2f'(\mathbf{c}_{i,j}) + f'(\mathbf{c}_{i,j+1})}{h^2} \quad (18)$$

$$\Delta_h \mathbf{c} = \frac{\mathbf{c}_{i-1,j} - 2\mathbf{c}_{i,j} + \mathbf{c}_{i+1,j}}{h^2} + \frac{\mathbf{c}_{i,j-1} - 2\mathbf{c}_{i,j} + \mathbf{c}_{i,j+1}}{h^2} \quad (19)$$

$$\Delta_h^2 \mathbf{c} = \frac{\mathbf{c}_{i-2,j} - 4\mathbf{c}_{i-1,j} + 6\mathbf{c}_{i,j} - 4\mathbf{c}_{i+1,j} + \mathbf{c}_{i+2,j}}{h^4} + \frac{\mathbf{c}_{i,j-2} - 4\mathbf{c}_{i,j-1} + 6\mathbf{c}_{i,j} - 4\mathbf{c}_{i,j+1} + \mathbf{c}_{i,j+2}}{h^4} \quad (20)$$

Benefit: Preserves the non-linearity of functional f

Finite Difference Spatial Discretization

Von Neumann Stability Analysis

Assume linear solution requiring
linearization of $f(c)$ around a minima

$$c(x, t) = c_0 e^{ikx} e^{\Omega_r t} e^{i\Omega_i t}$$

$$\Omega = -\frac{8M_0}{h^2} \sin^2\left(\frac{kh}{2}\right) - \frac{16M_0\kappa}{h^4} \sin^4\left(\frac{kh}{2}\right)$$

**Always negative! Not producing
periodic oscillations and
decreasing**

Runge Kutta Temporal Schemes

A Family of Multi-Stage Explicit and Implicit Schemes

Recall given a Butcher table, we have

c_1	a_{11}	a_{12}	\dots	a_{1s}
c_2	a_{21}	a_{22}	\dots	a_{2s}
\vdots	\vdots	\vdots	\ddots	\vdots
c_s	a_{s1}	a_{s2}	\dots	a_{ss}
	b_1	b_2	\dots	b_s

$$y_{n+1} = y_n + h \sum_{i=1}^s b_i k_i$$

$$k_1 = f(t_n, y_n),$$

$$k_2 = f(t_n + c_2 h, y_n + h(a_{21} k_1)),$$

$$k_3 = f(t_n + c_3 h, y_n + h(a_{31} k_1 + a_{32} k_2)),$$

$$\vdots$$

$$k_i = f\left(t_n + c_i h, y_n + h \sum_{j=1}^{i-1} a_{ij} k_j\right).$$

Explicit 1 Stage Runge Kutta

Stability of Forward Euler Scheme + FD

$$\frac{\partial \mathbf{c}}{\partial t} = \frac{\mathbf{c}_{ij}^{n+1} - \mathbf{c}_{ij}^n}{\Delta t}$$

$$\frac{\partial \mathbf{c}}{\partial t}(\mathbf{x}, t) = M_0 \Delta_h f'(\mathbf{c}) - M_0 \kappa \Delta_h^2 \mathbf{c}$$

The stability condition for the FE scheme is $(1 + \Omega_r \Delta t)^2 + \Omega_i^2 \Delta t^2 < 1$

$$\Omega_r \Delta t = -16C_1 \sin^4\left(\frac{kh}{2}\right) - 8C_2 \sin^2\left(\frac{kh}{2}\right) > -16C_1 - 8C_2 > -2$$

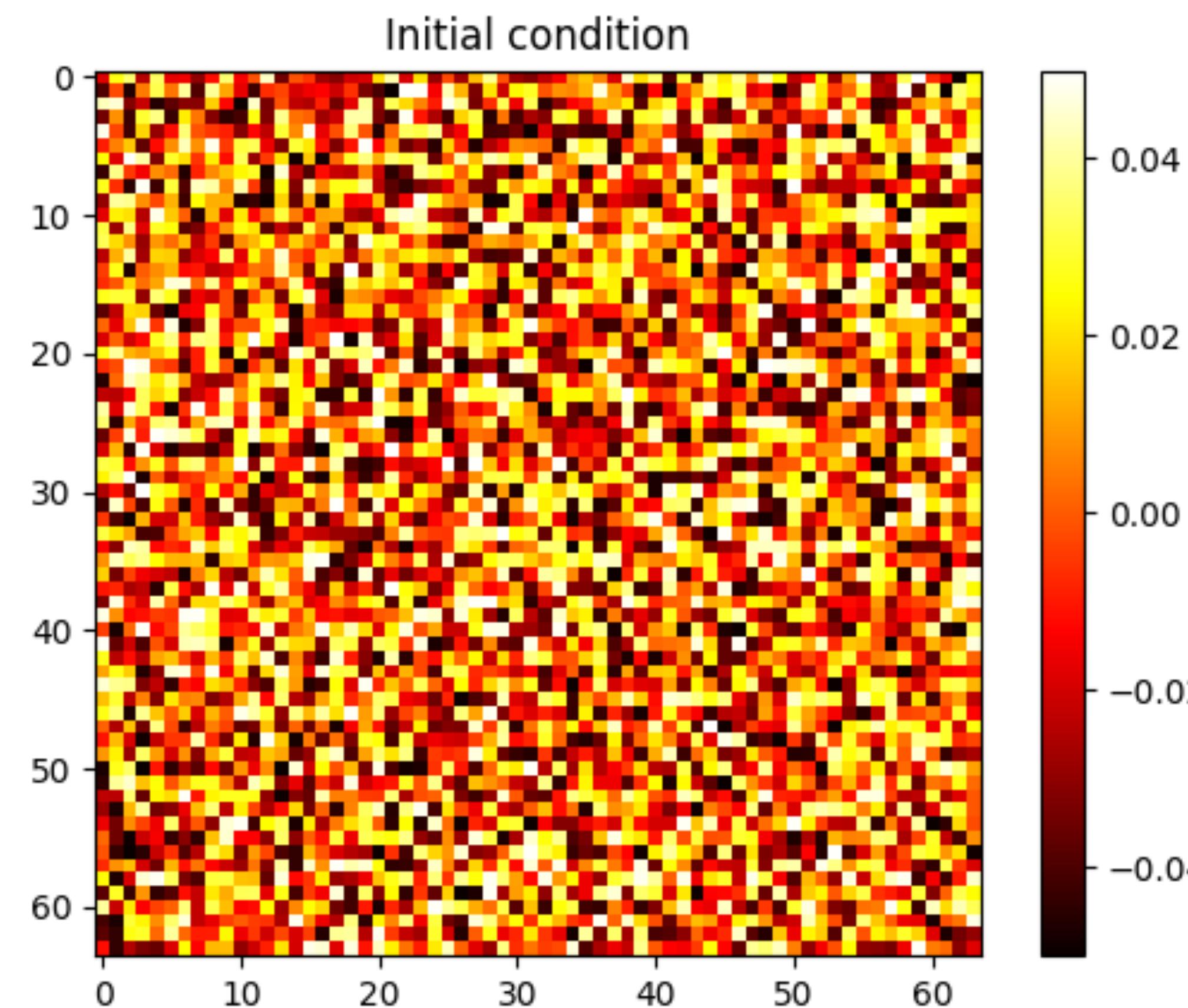
$$2C_1 + C_2 < \frac{1}{4}$$

Extremely restrictive conditions due to stiffness! Doubling spatial mesh requires time step to increase by 16!

Initial Condition for ALL Schemes

Implement Periodic Neumann Boundary Conditions

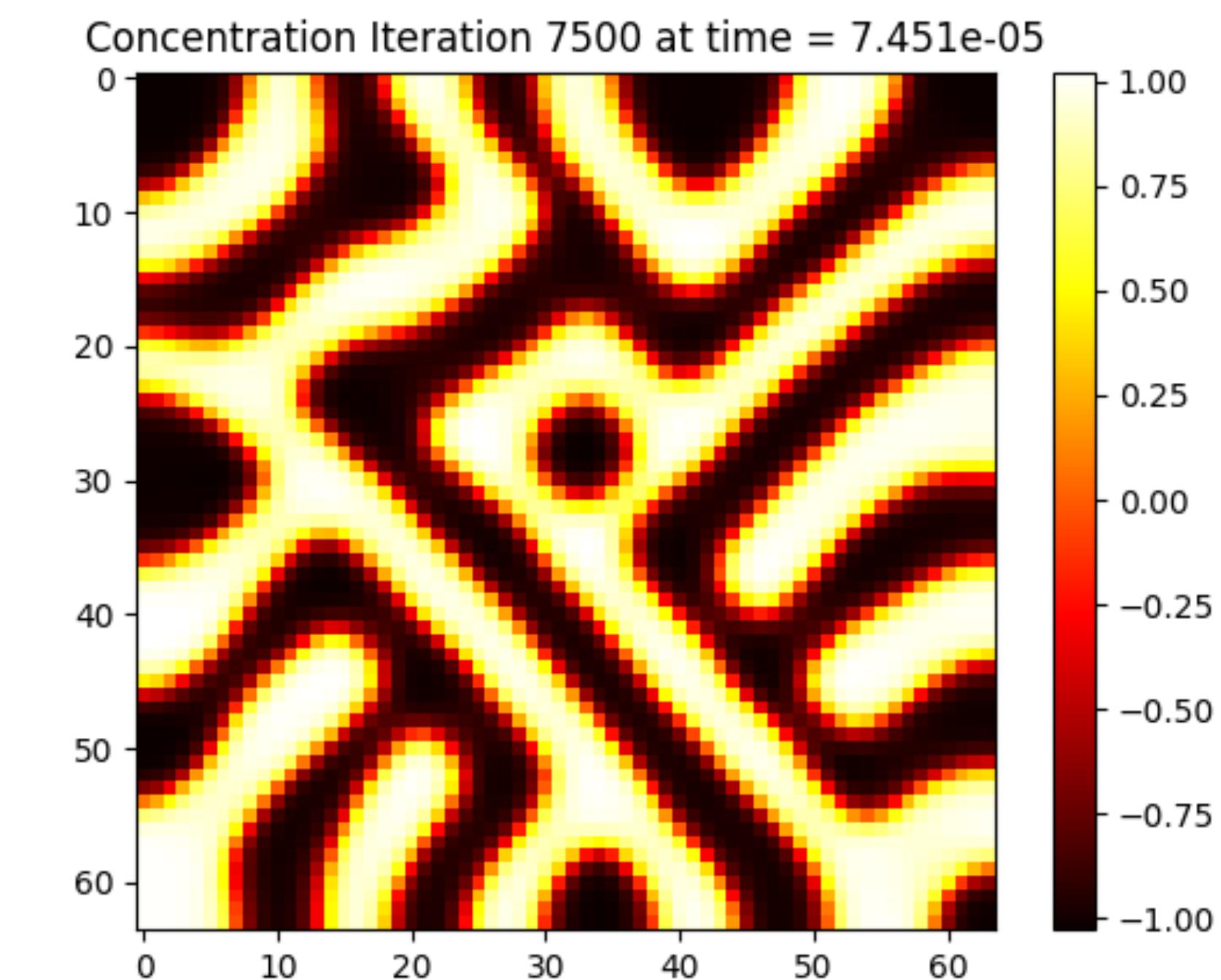
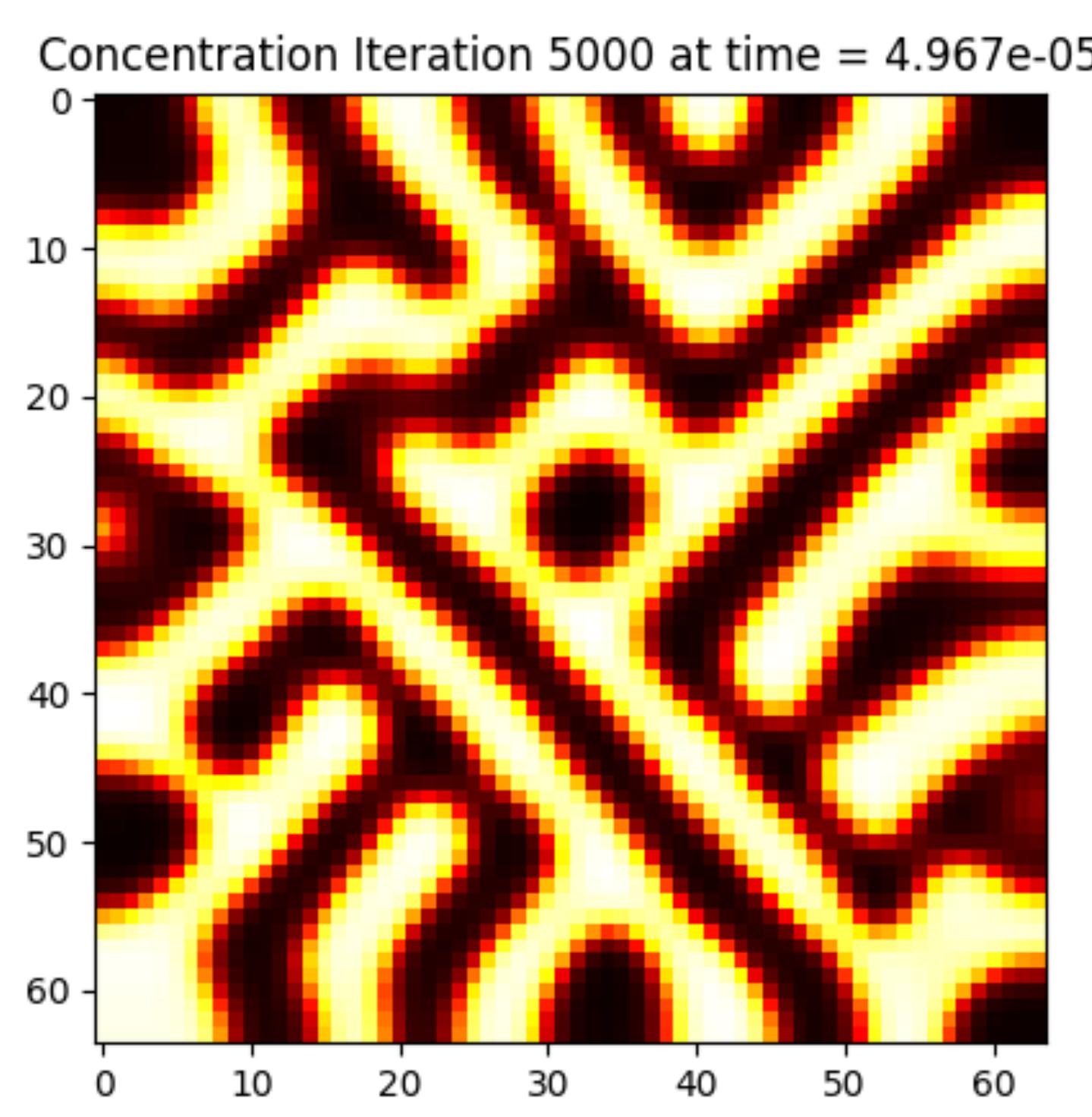
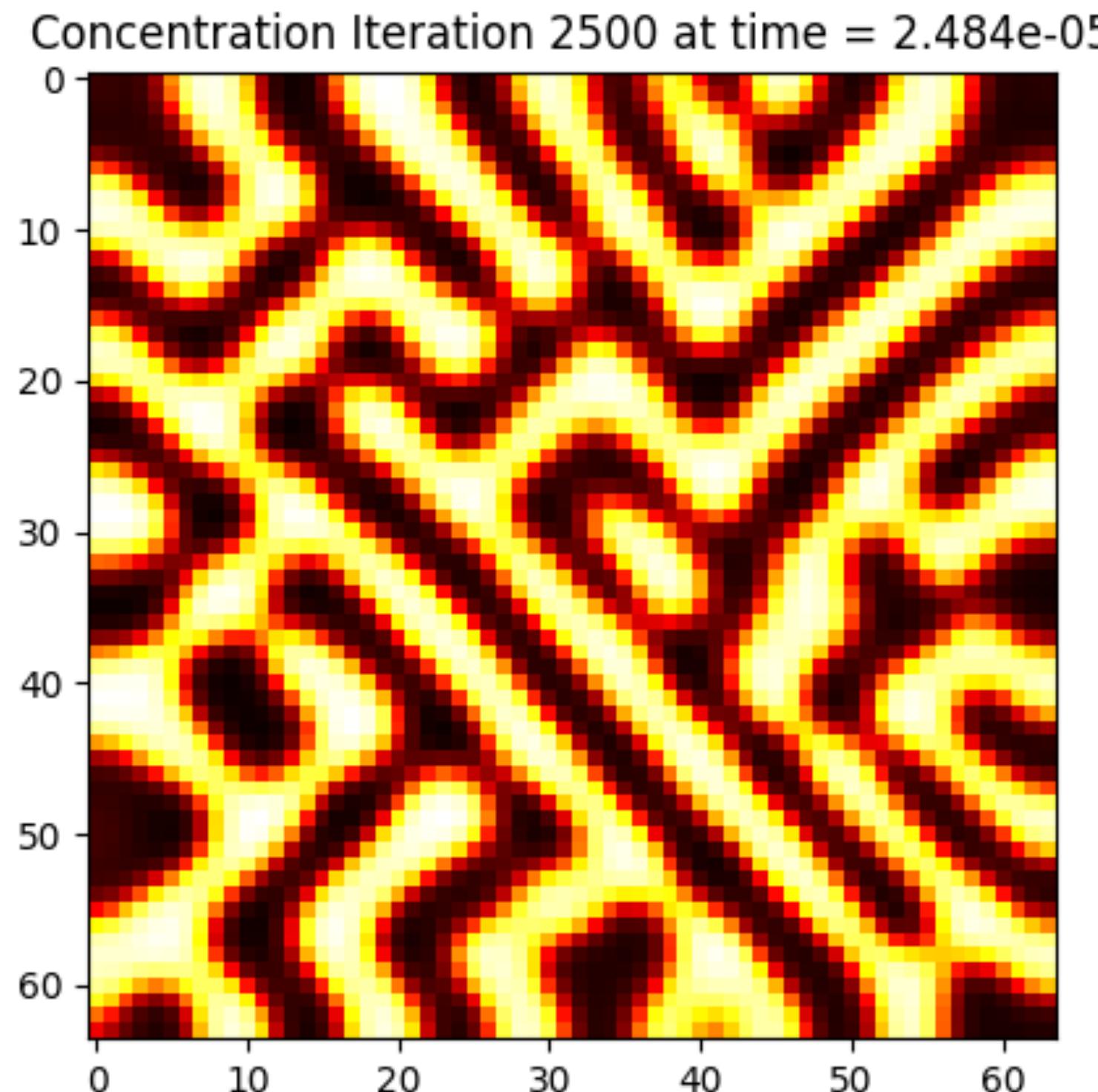
Uniformly random distribution around 0



Explicit 1 Stage Runge Kutta Results

Dynamics of Cahn-Hilliard with Forward Euler Scheme + FD

Restricted simulation to 1000 time steps/iterations. Time steps must be 10% of Courant for stability

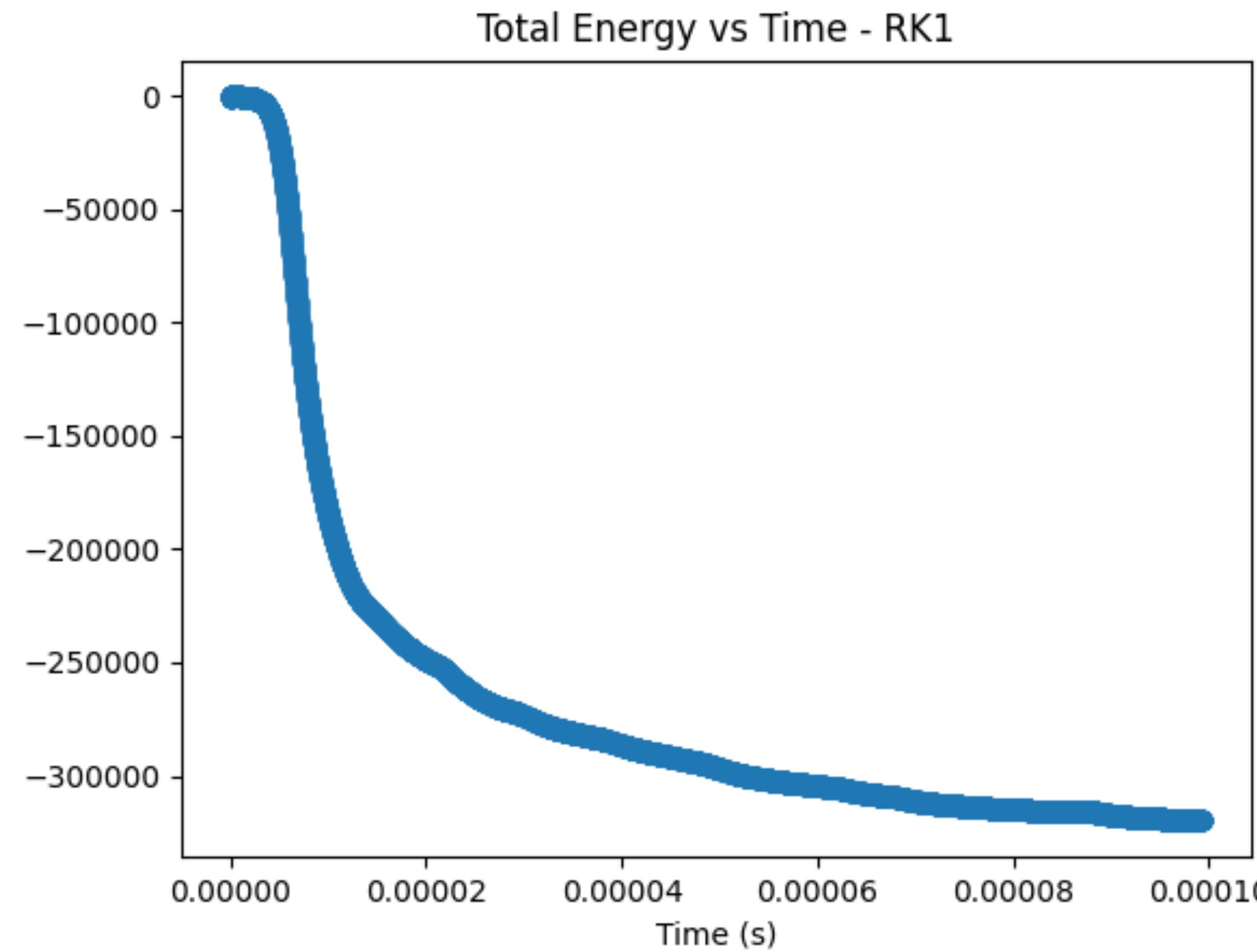


Dynamics are correct but time steps are too small for slow coarsening process

Explicit 1 Stage Runge Kutta Results

Dynamics of Cahn-Hilliard with Forward Euler Scheme + FD

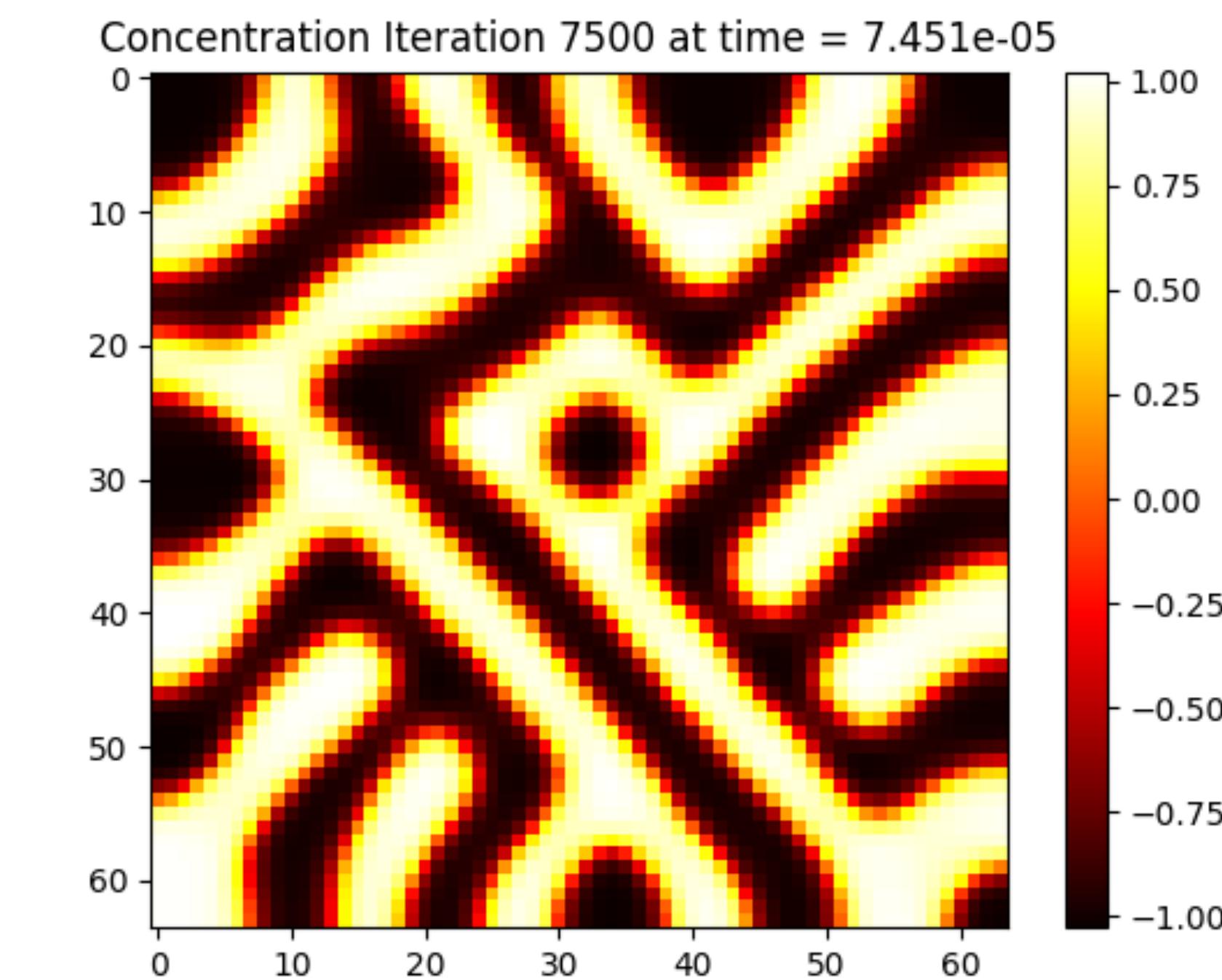
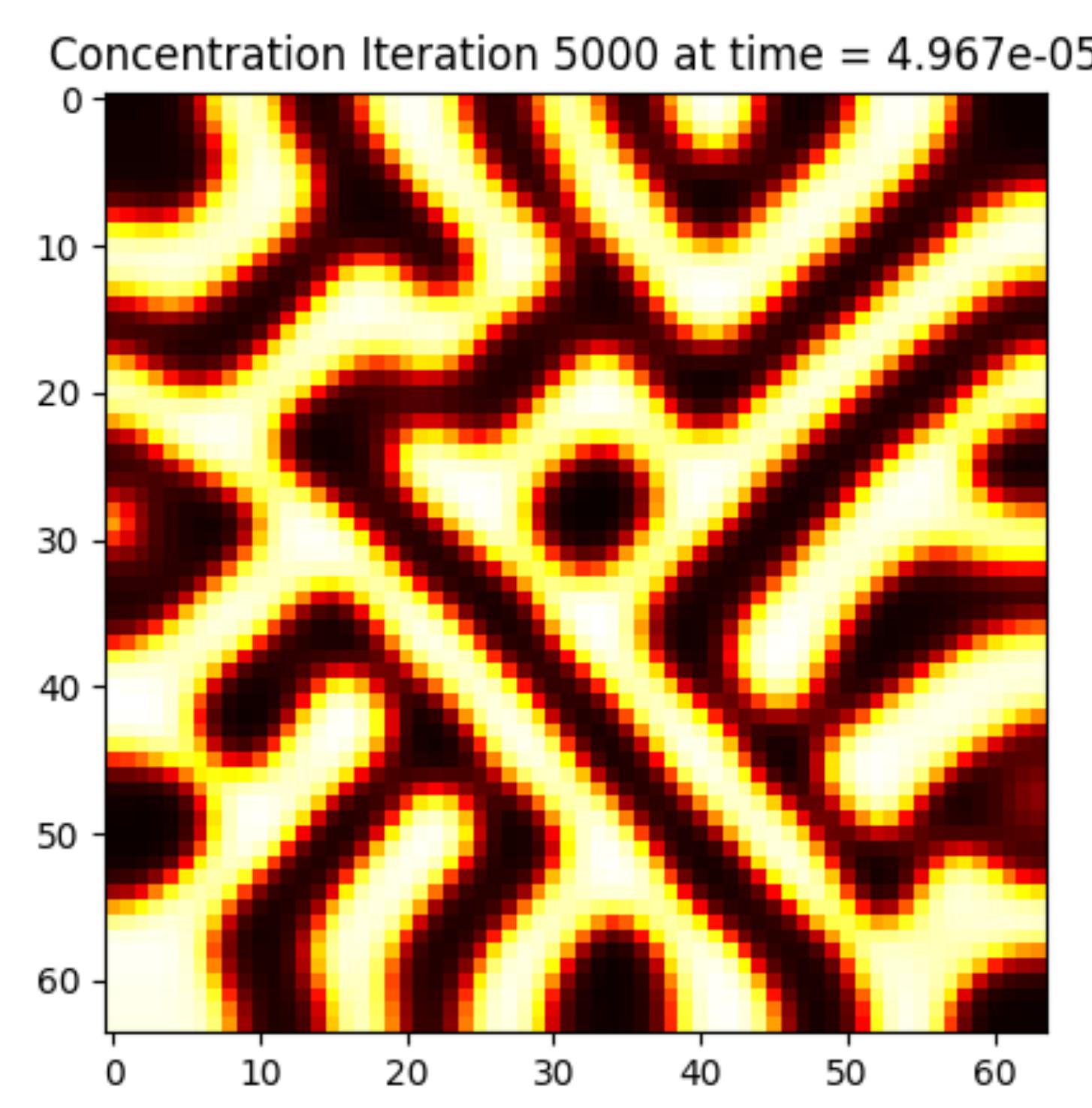
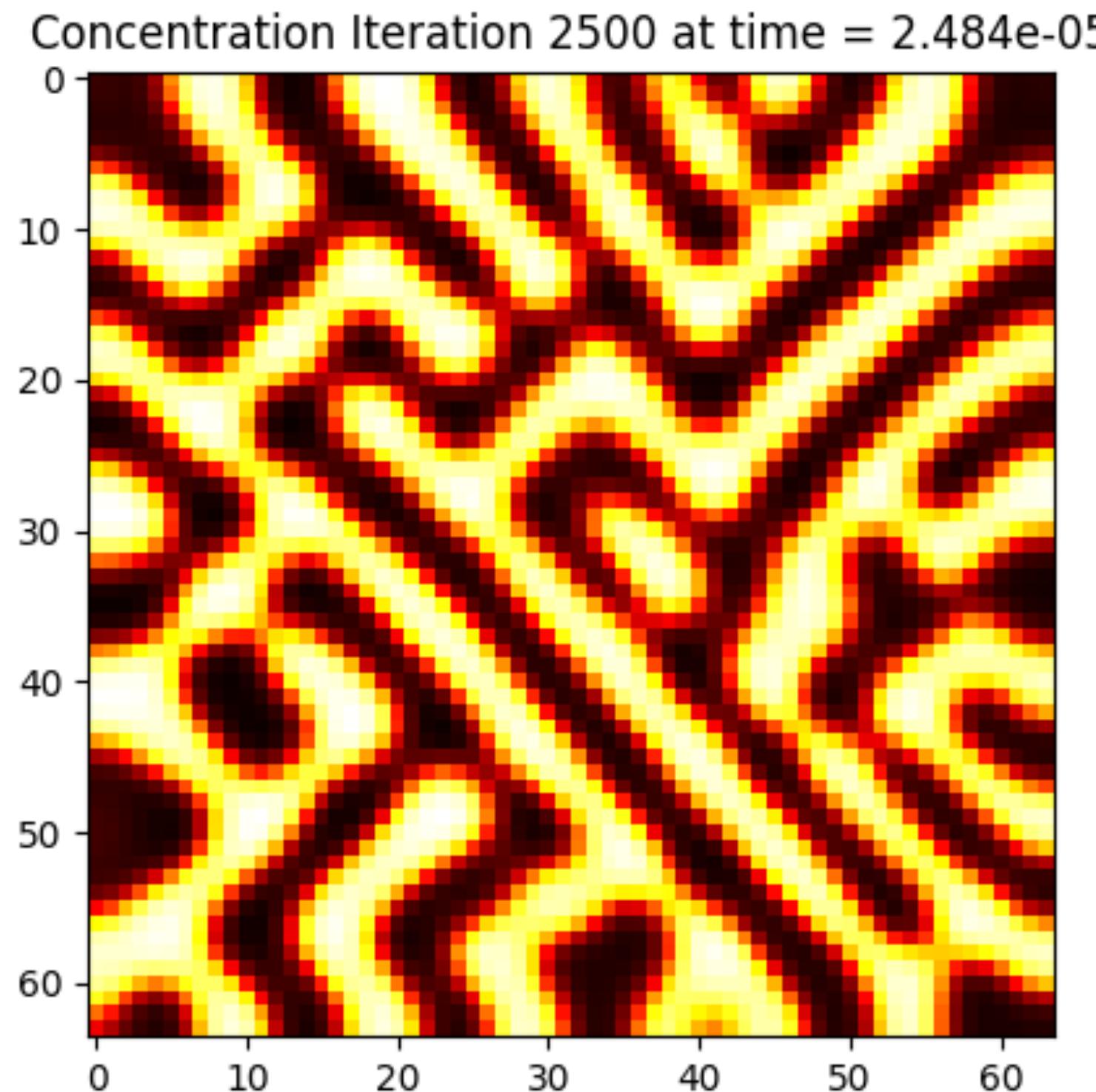
Inherits Decreasing Energy as Expected



Explicit 4 Stage Runge Kutta Results

Dynamics of Cahn-Hilliard with THE Range Kutta Scheme + FD

Restricted simulation to 1000 time steps/iterations. Time steps must be 30% of Courant for stability

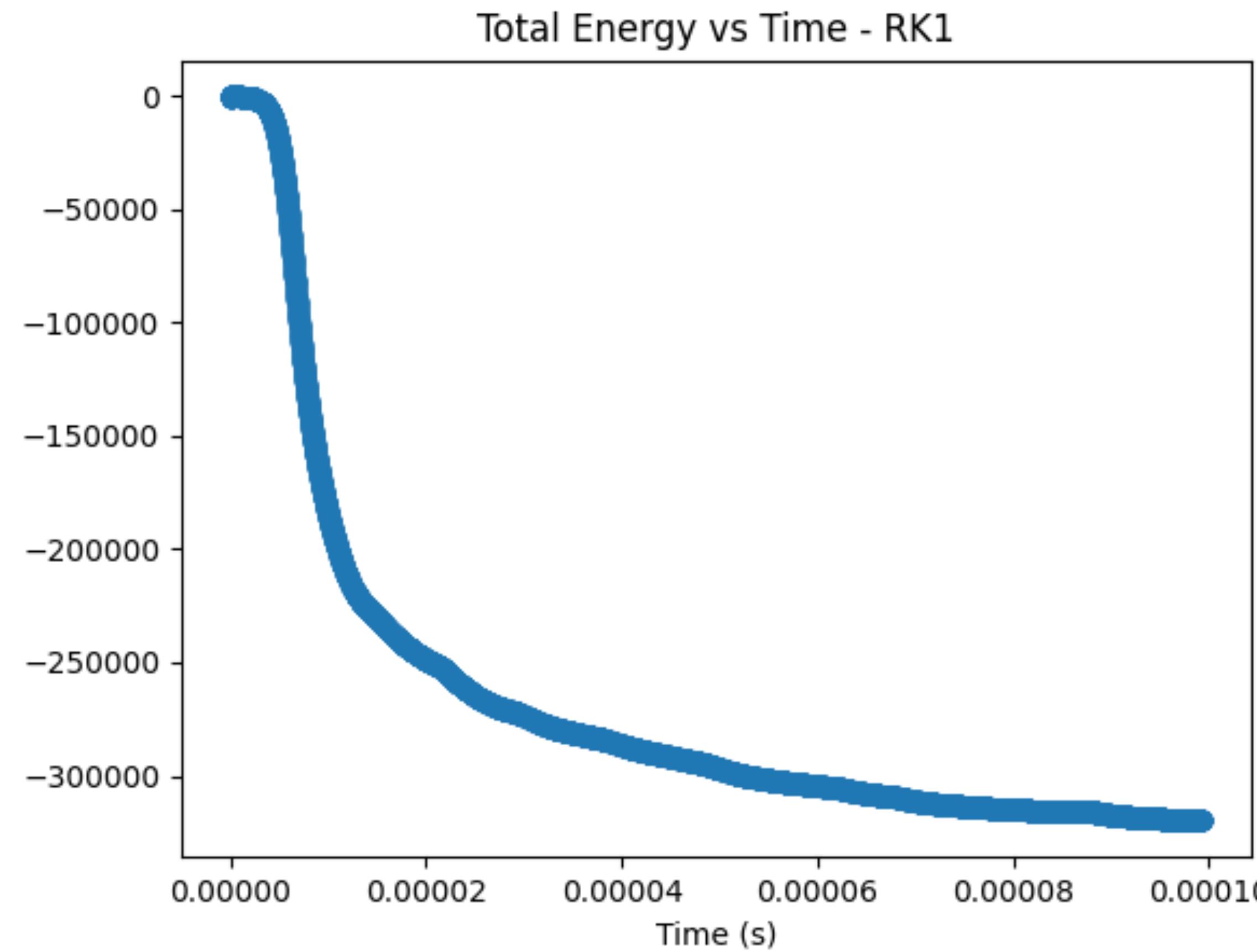


Dynamics are identical to RK1 but slightly larger time steps

Explicit 1 Stage Runge Kutta Results

Dynamics of Cahn-Hilliard with Forward Euler Scheme + FD

Inherits Decreasing Energy as Expected



Implicit 1 Stage Runge Kutta

Stability of Backward Euler Scheme + FD

$$\frac{\partial \mathbf{c}^{n+1}}{\partial t} = \frac{\mathbf{c}_{ij}^{n+1} - \mathbf{c}_{ij}^n}{\Delta t}.$$

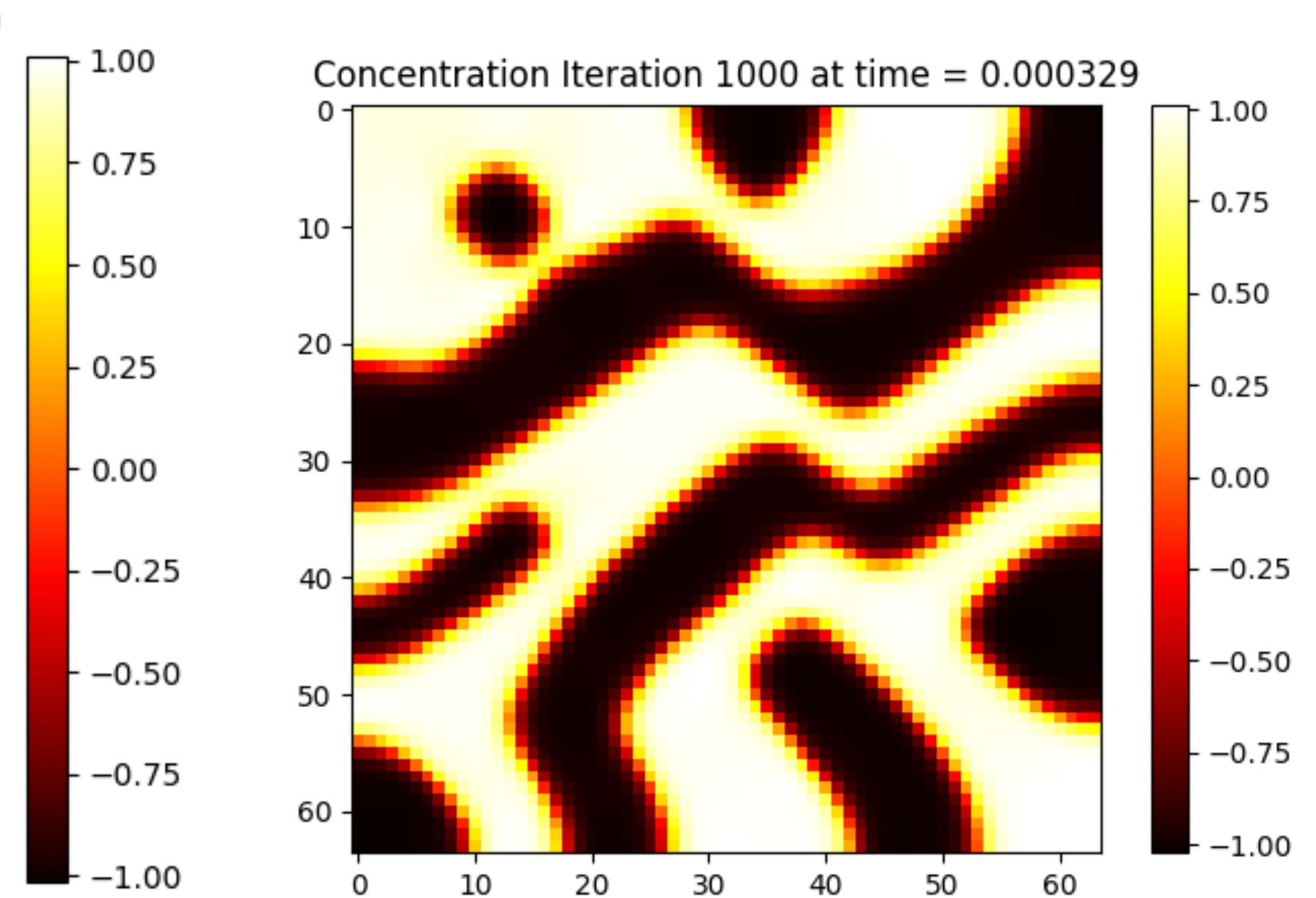
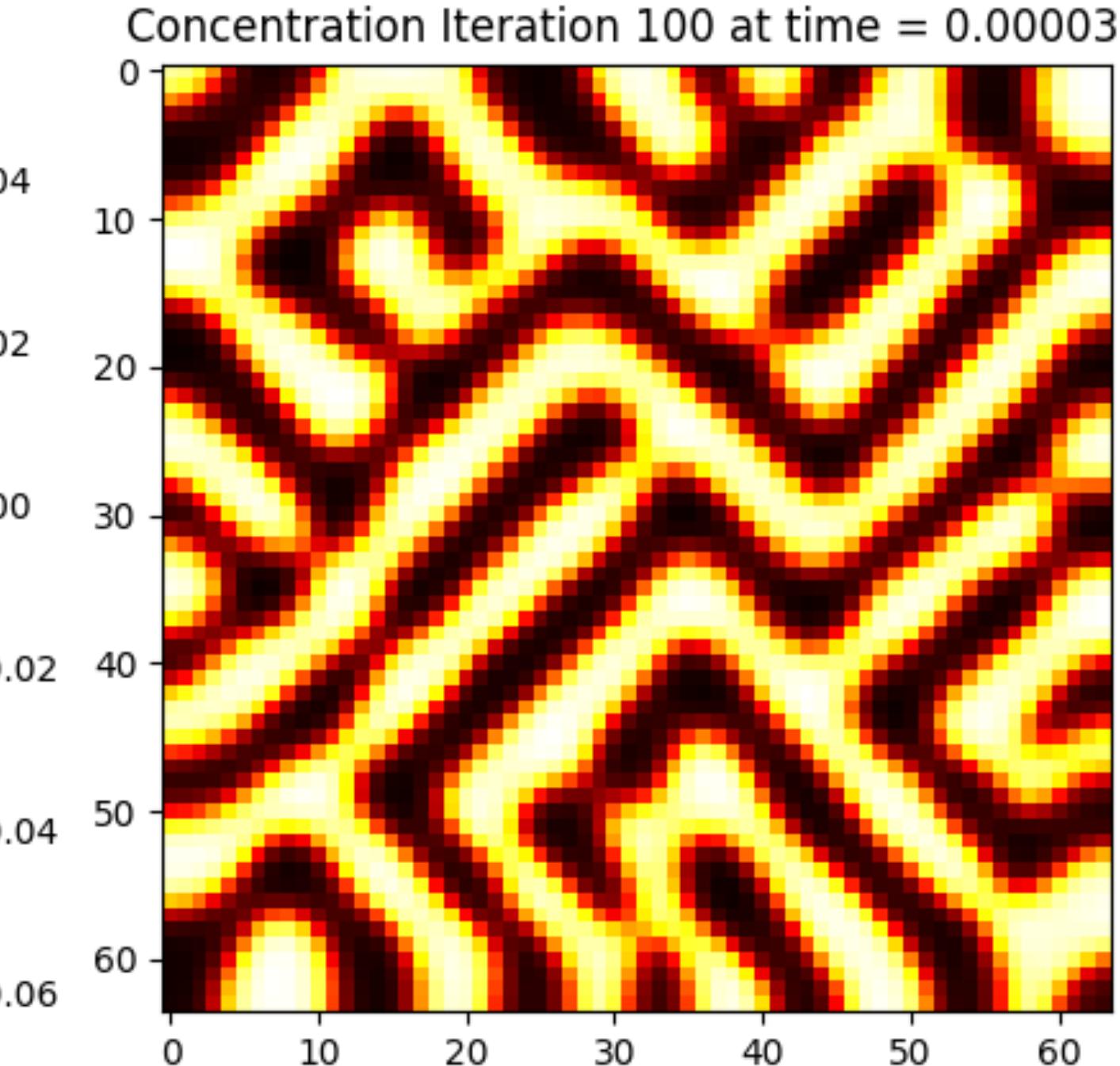
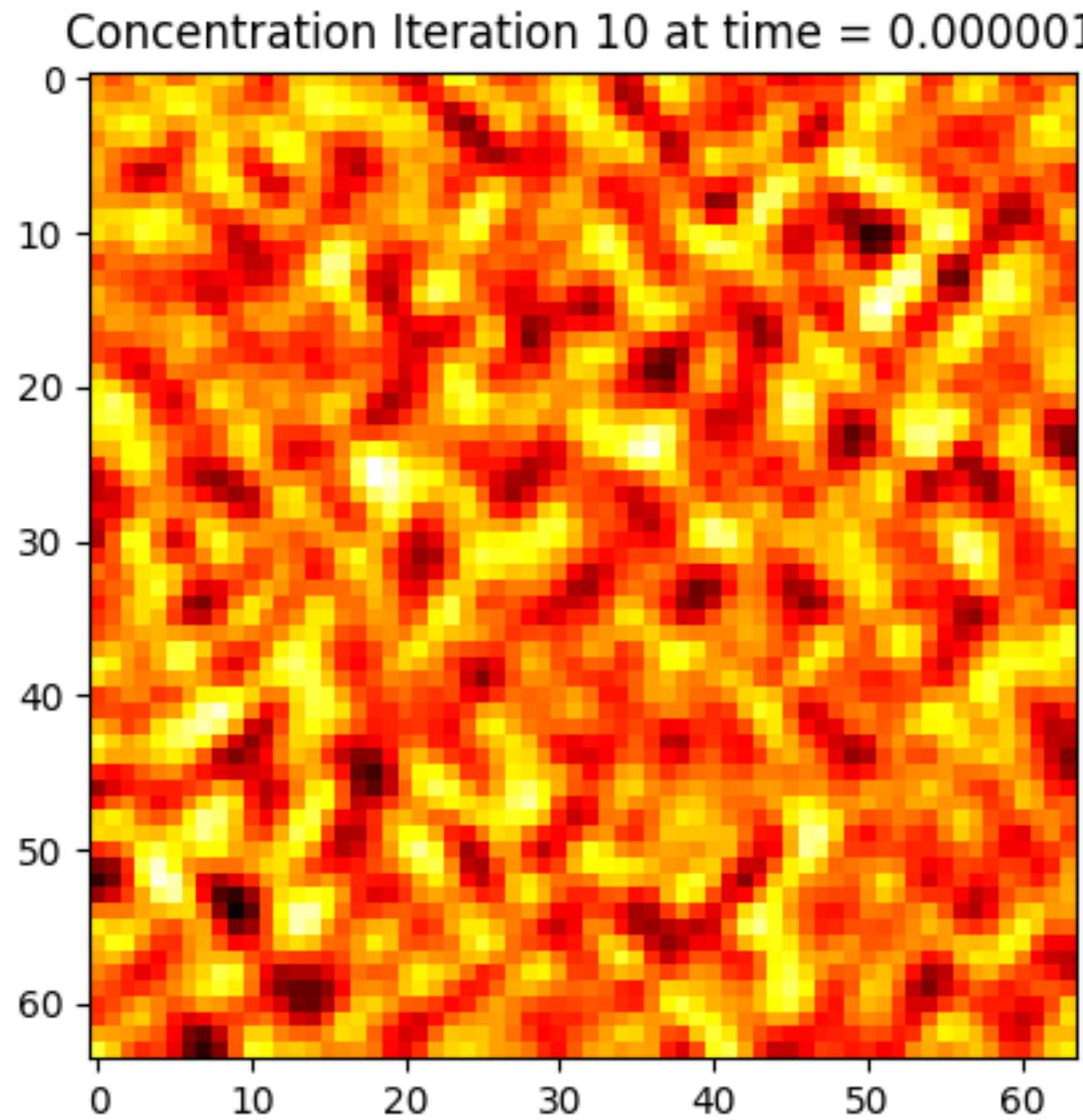
**Generally L-stable but requires linearized Raphson-Newton method
(nonlinear solvers) at each stage**

**Able to include time adaptivity! Double time steps if less than 10%
change between solutions**

Implicit 1 Stage Runge Kutta Results

Dynamics of Cahn-Hilliard with Backward Euler Scheme + FD

Restricted simulation to 1000 time steps/iterations. Time steps are dynamics

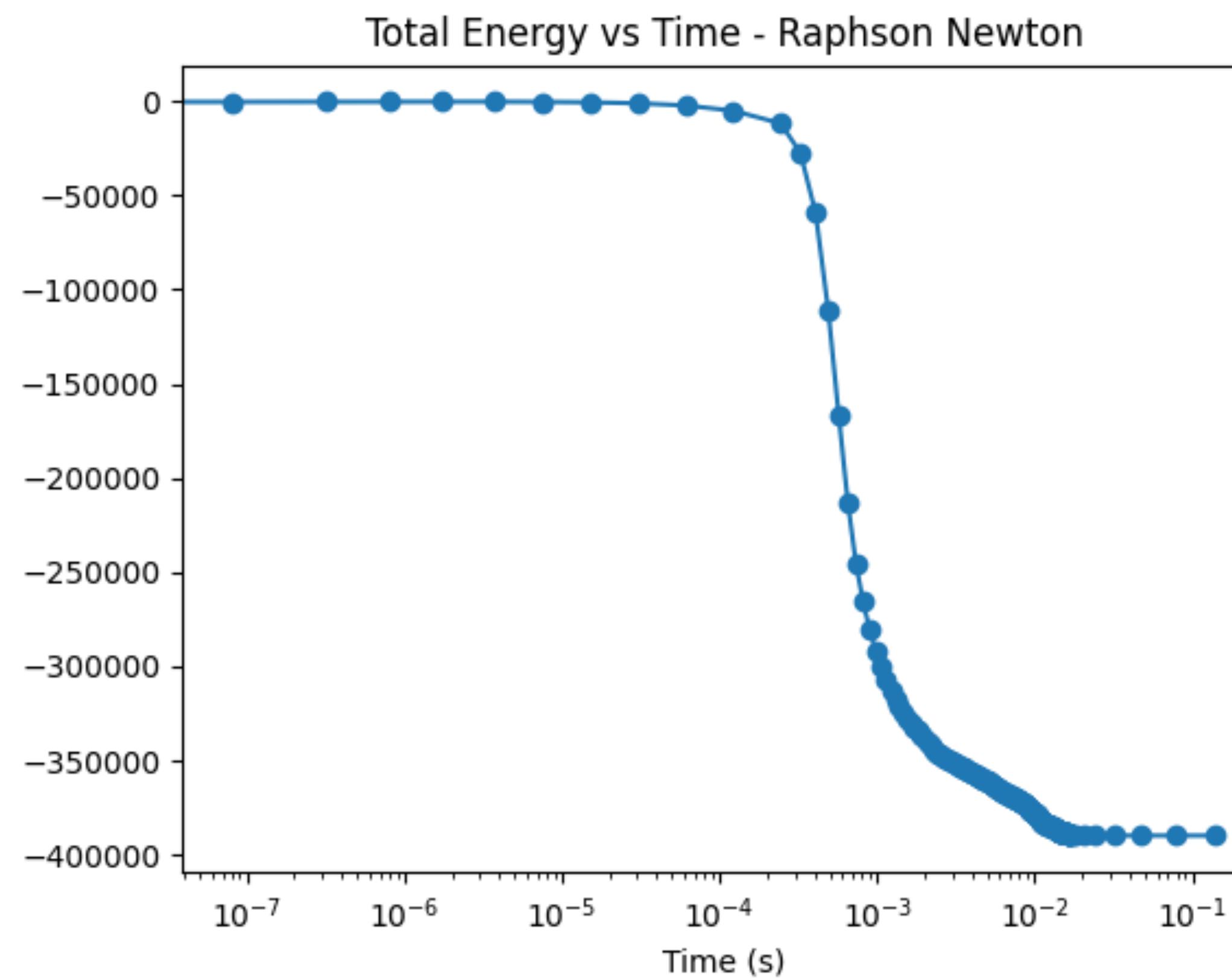


Dynamics are correct and can cover larger time scales!

Implicit 1 Stage Runge Kutta Results

Dynamics of Cahn-Hilliard with Forward Euler Scheme + FD

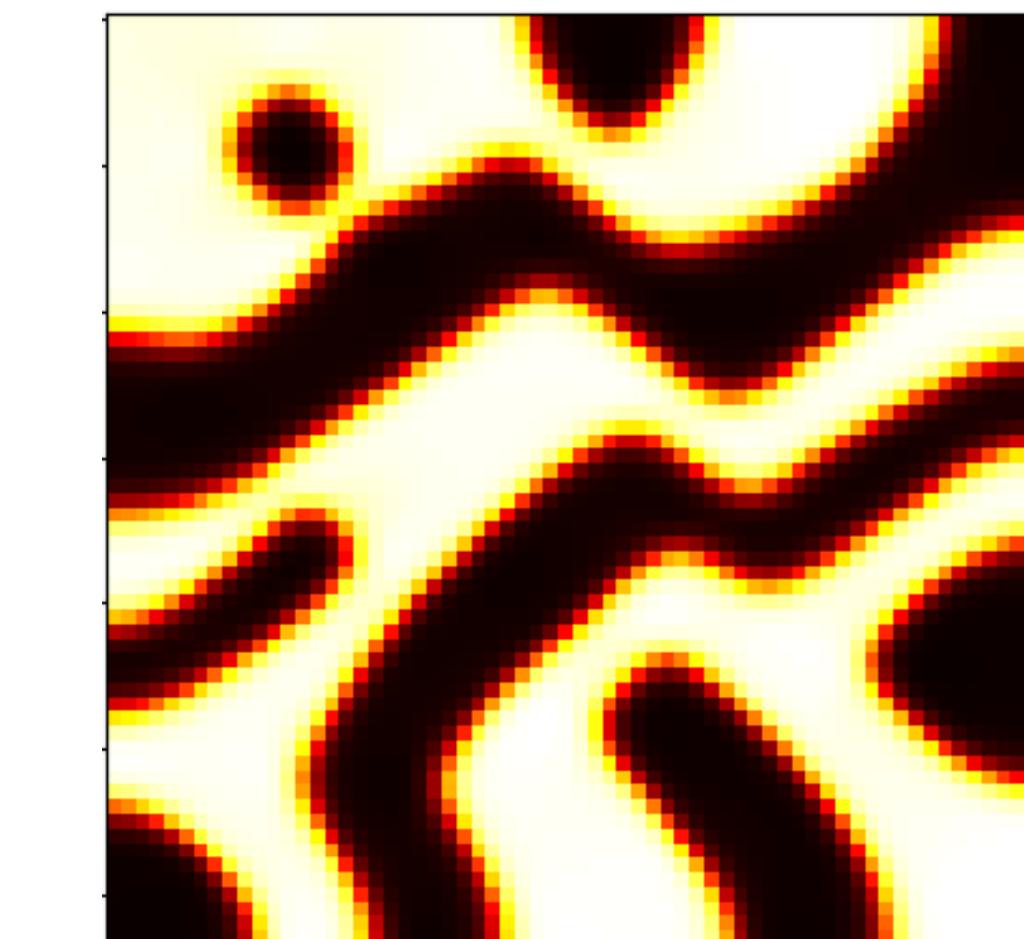
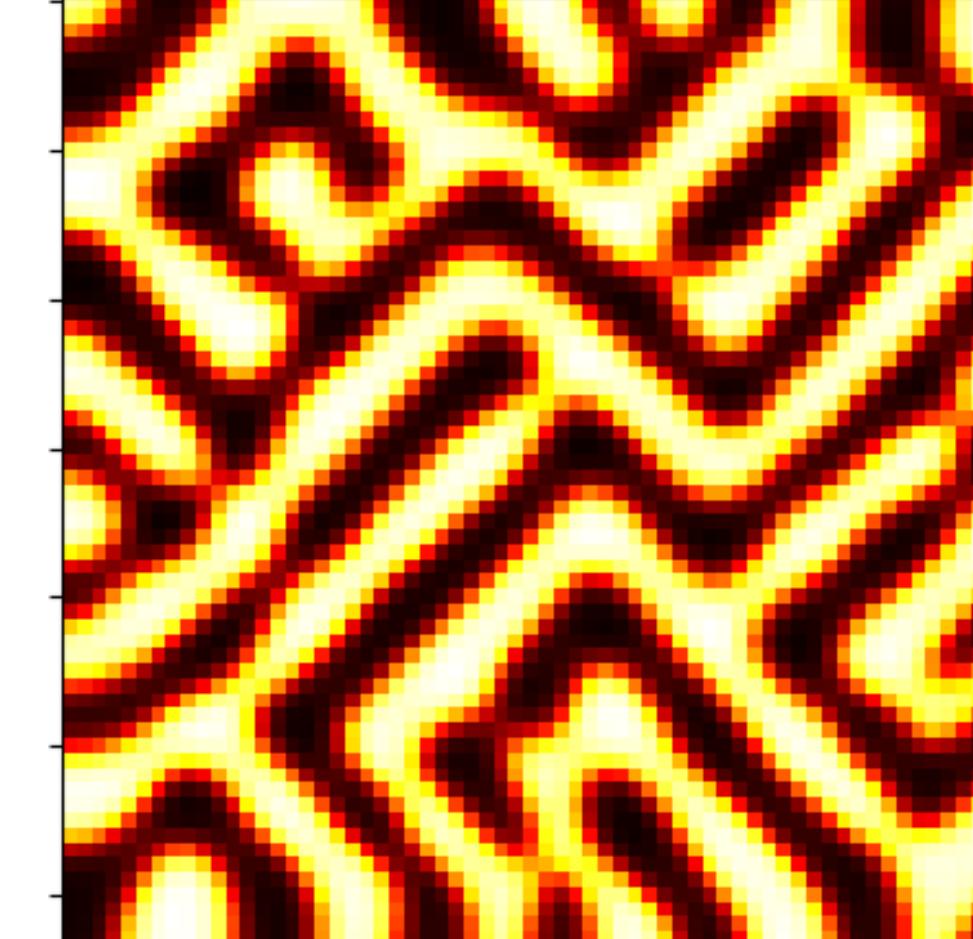
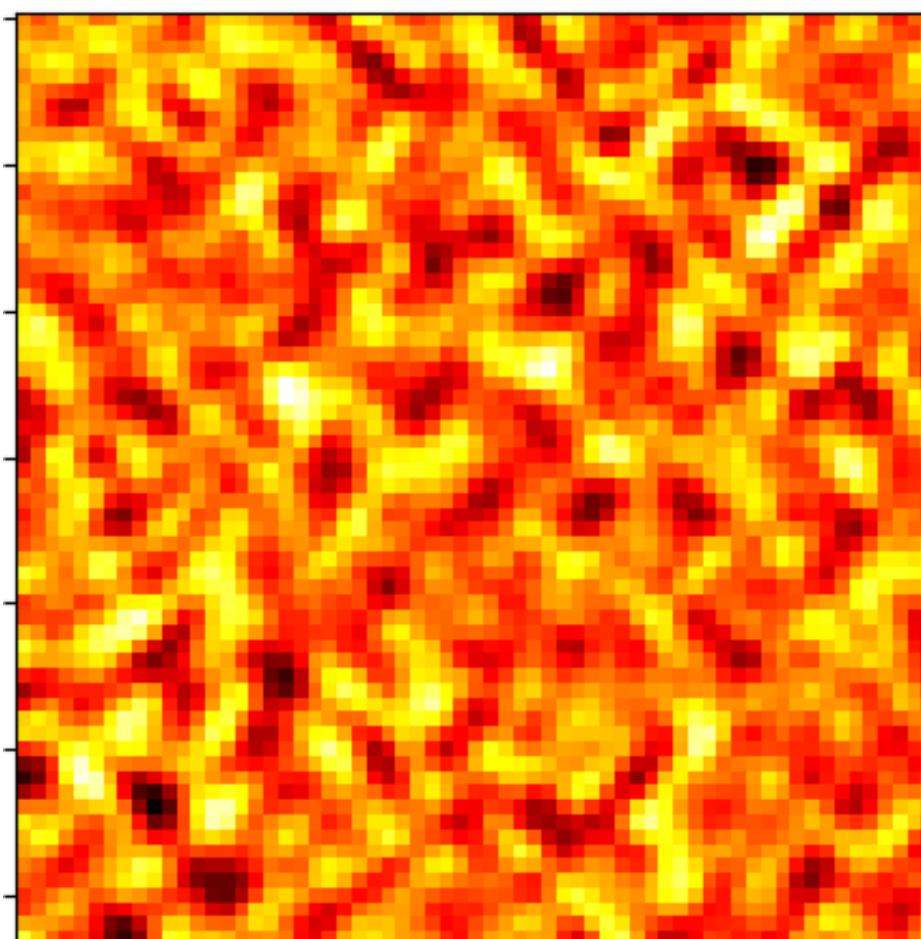
Inherits Decreasing Energy as Expected and covers orders of magnitudes to time



TakeAways and Next Steps

Cahn-Hilliard Equation Requires Adaptable Schemes

- Explicit schemes cannot capture long time dynamics due to stiffness
- Implicit schemes are more flexible but require non-linear solvers
- Form of Cahn-Hilliard equation determines time dynamics and which numerical schemes to use
- Adding complexities such as new geometries, non periodic boundary conditions, and temporal constants requires a mix of numerical schemes



References

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