# STA 3180 Statistical Modelling: Markov Chain Monte Carlo

# STA 3180 Statistical Modelling - Lecture Notes on Markov Chain Monte Carlo

#### ## Introduction

Markov Chain Monte Carlo (MCMC) is a powerful tool for statistical modelling. It is a type of computational algorithm used to sample from a probability distribution. MCMC algorithms are used to simulate complex systems and to estimate parameters in statistical models. MCMC algorithms are based on the Markov Chain, which is a stochastic process that has the property of memorylessness. This means that the future state of the system depends only on its current state, not on the states that preceded it.

#### ## Key Concepts

The key concepts of MCMC include:

- Markov Chains: A stochastic process with the property of memorylessness.
- Monte Carlo Simulation: A technique for estimating the value of a function by randomly sampling from its domain.
- Metropolis-Hastings Algorithm: An MCMC algorithm for sampling from a probability distribution.
- Gibbs Sampling: An MCMC algorithm for sampling from a multivariate probability distribution.

#### ## Definitions

- \*\*Markov Chain\*\*: A stochastic process in which the future state of the system depends only on its current state, not on the states that preceded it.
- \*\*Monte Carlo Simulation\*\*: A technique for estimating the value of a function by randomly sampling from its domain.
- \*\*Metropolis-Hastings Algorithm\*\*: An MCMC algorithm for sampling from a probability distribution. It works by proposing a new state for the system and accepting or rejecting it based on a

#### probability.

- \*\*Gibbs Sampling\*\*: An MCMC algorithm for sampling from a multivariate probability distribution. It works by iteratively sampling from the conditional distributions of each variable given the values of the other variables.

### ## Coding Examples

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This code implements the Metropolis-Hastings algorithm. The function takes four arguments: `x`, which is the current state of the system; `pdf`, which is the probability density function of the target distribution; `proposal pdf`, which is the probability density function of the proposal distribution; and `num samples`, which is the number of samples to generate. The function returns a list of samples from the target distribution.

## ### Example 2: Gibbs Sampling

This code implements the Gibbs Sampling algorithm. The function takes three arguments:  $\hat{x}$ , which is the current state of the system;  $\hat{p}$ df, which is the joint probability density function of the target distribution; and  $\hat{n}$ num samples, which is the number of samples to generate. The function returns a list of samples from the target distribution.