

ALGORITHM ANALYSIS AND DESIGN

Module 2 | **Part** **2**

CST306

GRAPH TRAVERSAL ALGORITHMS:



- Graph traversal algorithms visit the vertices of a graph, according to some strategy.

Different graph traversal algorithms are:

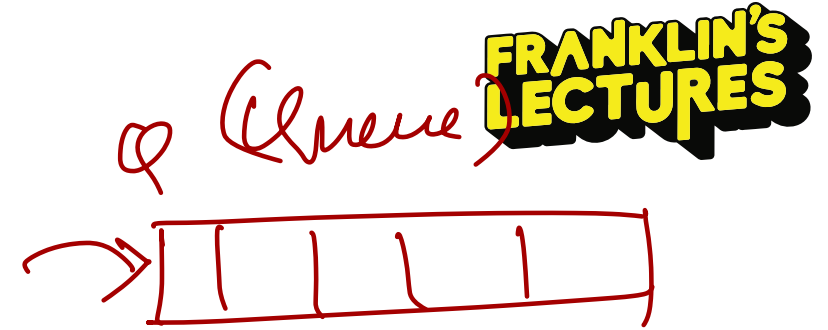
- ✓ - Breadth First Search(BFS)
- ✓ - Depth First Search(DFS)



BREADTH FIRST SEARCH(BFS)

Algorithm BFS(G, u)

1. Set all nodes are unvisited
2. Mark the starting vertex u as visited and put it into an empty Queue Q
3. While Q is not empty
 - 3.1 Dequeue v from Q
 - 3.2 While v has an unvisited neighbor w



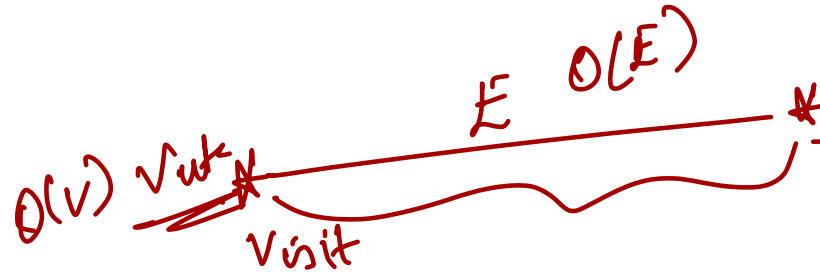
3.2.1 Mark w as visited

3.2.2 Enqueue w into Q

4. If there is any unvisited node x

4.1 Visit x and Insert it into Q . Goto step 3

COMPLEXITY



- If the graph is represented as an adjacency list
 - Each vertex is enqueued & dequeued atmost once. Each queue operation take $O(1)$ time. So the time devoted to the queue operation is $O(V)$.
 - The adjacency list of each vertex is scanned only when the vertex is dequeued. Each adjacency list is scanned atmost once. Sum of the lengths of all adjacency list is $|E|$. Total time spend in scanning adjacency list is $O(E)$.
 - Time complexity of BFS = $O(V) + O(E) = O(V + E)$.

- In a dense graph:

$$E = O(V^2)$$

$$\text{Time complexity} = O(V) + O(V^2) = O(V^2)$$

- If the graph is represented as an adjacency matrix
 - There are V^2 entries in the adjacency matrix. Each entry is checked once.
 - Time complexity of BFS = $O(V^2)$

$$T(\text{BFS}) = O(V^2)$$

APPLICATIONS OF BFS



- Finding shortest path between 2 nodes u and v , with path length measured by number of edges
- Testing graph for bipartiteness
- Minimum spanning tree for unweighted graph
- Finding nodes in any connected component of a graph
- Serialization/deserialization of a binary tree
- Finding nodes in any connected component of a graph

DEPTH FIRST SEARCH(DFS)



Algorithm DFS(G, u)

1. Mark vertex u as visited
2. For each adjacent vertex v of u
 - 2.1 if v is not visited
 - 2.1.1 DFS(G, v)



Algorithm main(G,u)

1. Set all nodes are unvisited.

2. DFS(G, u) ~~visit~~

3. For any node x which is not yet visited

3.1 DFS(G, x)



COMPLEXITY

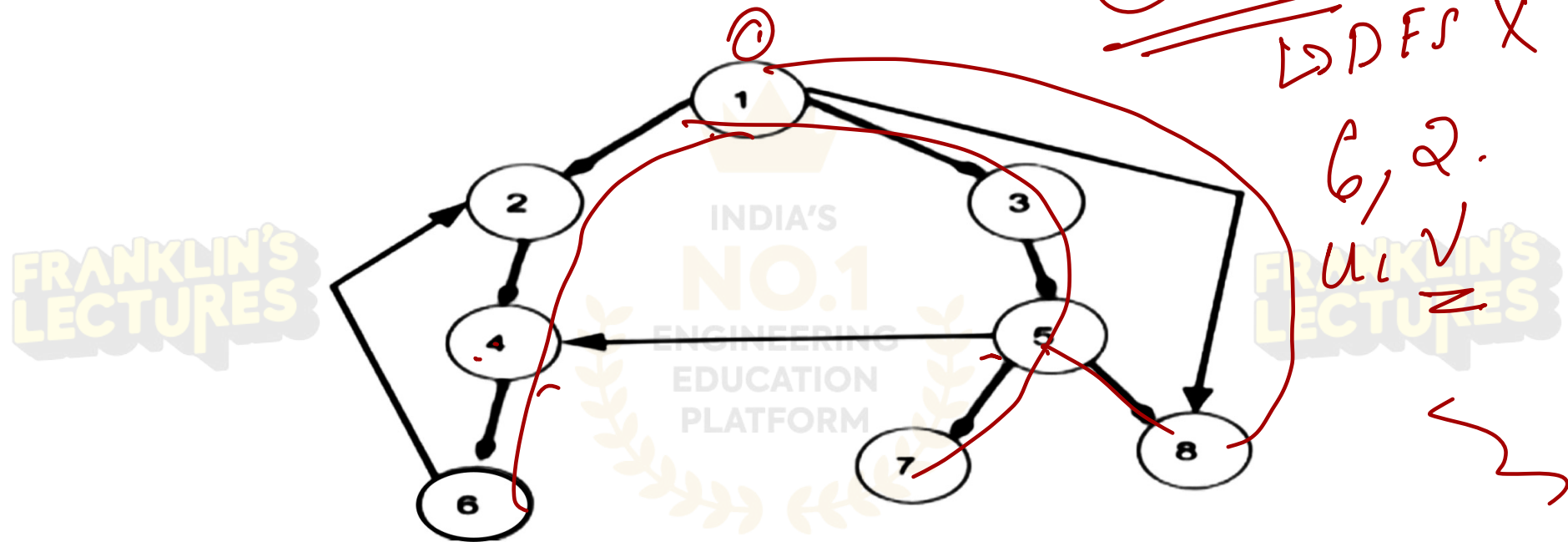


- If the graph is represented as an adjacency list
 - Each vertex is visited atmost once. So the time devoted is $O(V)$
 - Each adjacency list is scanned atmost once. So the time devoted is $O(E)$
 - Time complexity of DFS = $O(V + E)$
- If the graph is represented as an adjacency matrix
 - There are V^2 entries in the adjacency matrix. Each entry is checked once.
 - Time complexity of DFS = $O(V^2)$

$$T(DFS) = O(V^2)$$

CLASSIFICATION OF EDGES

FRANKLIN'S
LECTURES



The DFS traversal of the above graph is 1 2 4 6 3 5 7 8

- Tree Edge: It is a edge in tree obtained after applying DFS on the graph

Eg:- (1,2), (2,4), (4,6), (1,3), (3,5), (5,7) and (5,8)

- Forward Edge:

It is an edge (u, v) such that v is descendant but not part of the DFS tree eg:- ~~(6,2)~~ (1,8) -

- Backward Edge

It is an edge (u, v) such that v is ancestor of edge u but not part of DFS tree.

Eg: (6,2)

2 was visited before 6.
 \therefore 2 is an ancestor of 6.

- Cross Edge



It is a edge which connects two node such that they do not have any ancestor and a descendant relationship between them.

Eg: (5,4)



APPLICATIONS OF DFS



- Finding connected components in a graph
- Topological sorting in a DAG
- Scheduling problems
- Cycle detection in graphs
- Finding 2-(edge or vertex)-connected components
- Finding 3-(edge or vertex)-connected components
- Finding the bridges of a graph
- Finding strongly connected components



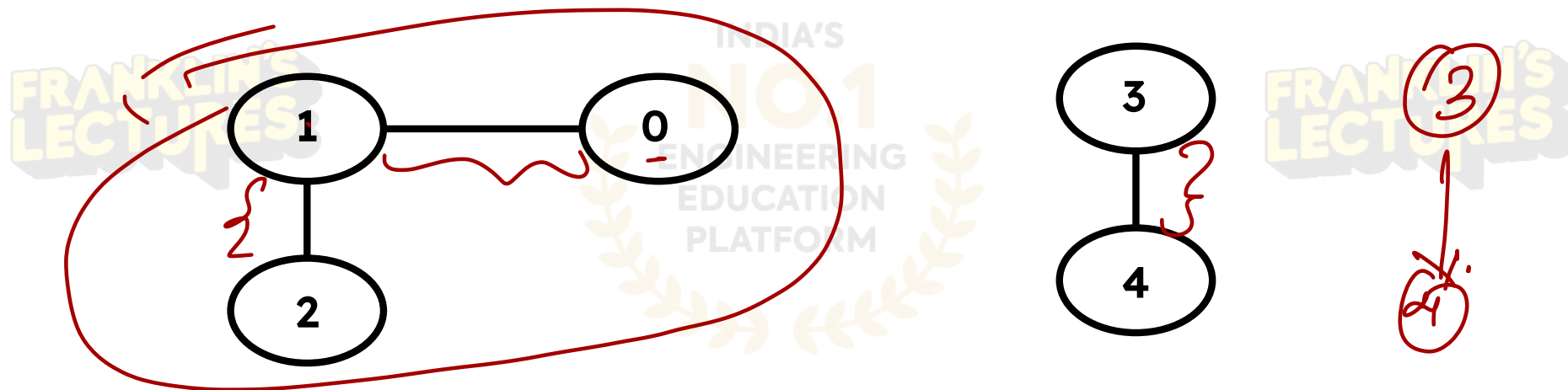
- Solving puzzles with only one solution, such as mazes
- Finding biconnectivity in graphs



Connected Components:



- Connected component of a graph G is a connected subgraph of G of maximum size
- A graph may have more than one connected components.



There are two connected components in above undirected graph

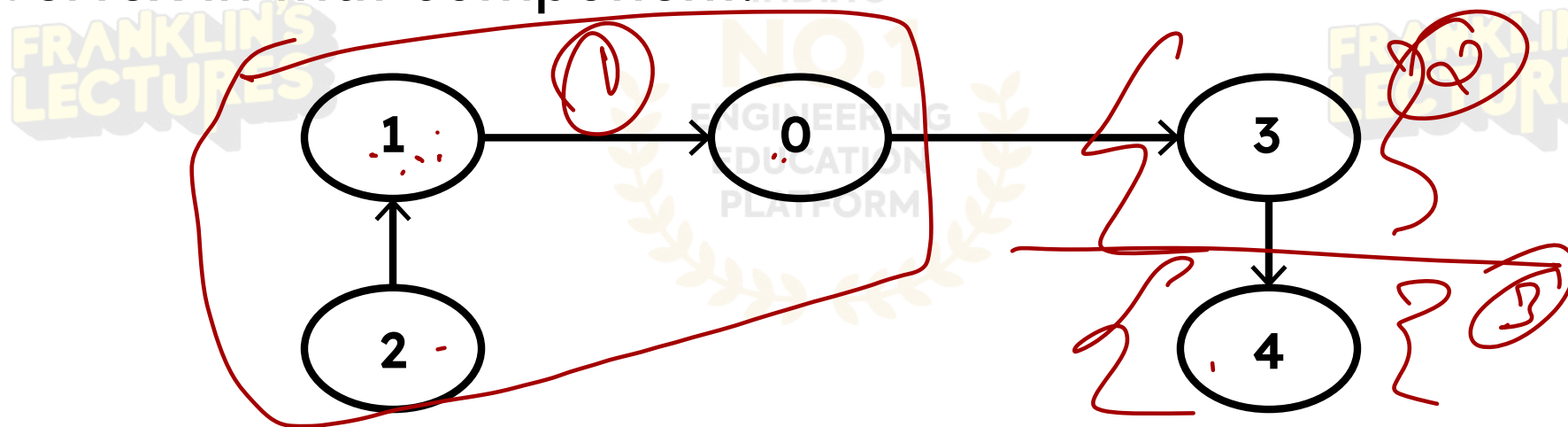
0, 1, 2

3, 4

Strongly Connected Components(SCC)



- Strong Connectivity applies only to directed graphs.
- A strongly connected component of a directed graph is a complement such that all the vertices in that component are reachable from every other vertex in that component.



Here we have 3 SCCs: {0,1,2}, {3}, {4}

THANK YOU