

**Updated 9/12/2013:**

60000 total trajectories

12000 at each of 5 z-beam positions (-250, -125, 0, 125, 250 mm)

z beam	$-0.045 < \delta < -0.04$	$-0.04 < \delta < -0.03$	$-0.03 < \delta < -0.02$	$-0.02 < \delta < -0.01$	$-0.01 < \delta < 0.00$	$0.00 < \delta < 0.01$	$0.01 < \delta < 0.02$	$0.02 < \delta < 0.03$	$0.03 < \delta < 0.04$	$0.04 < \delta < 0.045$
z = 0.25	2.27	3.26	3.30	3.36	3.41	3.47	3.51	3.40	3.25	2.85
z = 0.125	2.90	3.88	3.98	4.00	4.05	4.15	4.17	4.08	3.89	3.38
z = 0	3.89	4.02	4.15	4.13	4.25	4.32	4.31	4.26	3.99	3.65
z = -0.125	3.86	4.14	4.16	4.24	4.18	4.30	4.27	4.33	4.21	3.60
z = -0.25	3.64	4.20	4.21	4.24	4.20	4.18	4.19	4.15	4.11	3.35



