

PERSONAL PROFILE

I am a M.S. student in Robotics at NCTU, I am interested in manipulation, especially building an intelligent system that can automatically put products on the shelf and checkout in retail industry!

CONTACT

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EDUCATION

MS of Graduate Degree Program of Robotics, Nation Chiao Tung University

2018-Present

SKILLS

- Develop Tools
 - ROS (Robot Operating System)
 - PyTorch
- Programming
 - C/C++
 - Python
 - Matlab
- Language
 - Chinese
 - English

PROJECTS AND PROFESSIONAL EXPERIENCE

PICK AND PLACE SYSTEM

- We are aimed to building a system which can automatically pick the object and place it in the shelf with the cue of brand name. We used brandnamebased fully convolutional network to find the affordance of the product. The system consists of two robot arms, one with suction gripper and the other with parallel-jaw gripper, the former can pick the target from cluttered environment and the latter is for putting target on the shelf.
- In the team, I am responsible for manipulation of dual robot arms.

• DARPA SUBTERRANEAN CHALLENGE, 2019

- The "SubT" Challenge aimed to seeks a novel approaches to rapidly map, navigate, and search in underground environment automatically.
- In the team, I am responsible for navigation of AGV.