### **Curriculum Vitae**

Name : Timothius Victorio Yasin (賴德強)

Country of origin : Indonesia

City / Province : Surabaya, East Java Email : timovictorio@gmail.com Status : Second year graduate student

Address in Taiwan : Assistive Robotics Lab (EE-627), Engineering

Building 5

Institute of Electrical and Control Engineering,

National Chiao Tung University

No. 1001, Daxue Rd, East District, Hsinchu City, 300, Taiwan.

### **Education:**

M.Sc (cand.) in Electrical Engineering,

National Chiao Tung University. 2016-....

S.T. (B.Sc.) in Electrical Engineering,

Petra Christian University, Indonesia. 2012-2016

#### **Research Interest:**

Automatic Control Systems, Computer Vision, Robotics

### **Technical Skills:**

C/C++ Programming, Matlab, Siemens PLC Programming, Ladder Diagram Programming

#### **Research Experience:**

Project: Mobile Robot Movement using EEG Sensor Emotiv Epoc

The main purpose of this project is mobile robot movement using human expressions through EEG sensor, and study of human brain activity while expressing some expression. I used the commercial EEG sensor (Emotiv Epoc) to control mobile robot by capturing expressions which already initialized as a direction command. In order to reach the optimal configuration to control the mobile robot, there are two sets of configuration. These two sets of configuration tested by finding which set is faster to control the mobile robot. Though a certain set of configuration chosen, the testing continues using some threshold value, which function as a validation to the true value of certain expression. These tests come with eight configurations of threshold value and tested based on response time for the mobile robot to reach the goal. The first configuration until seventh configuration are showing response time, which getting faster, then after the eighth configuration tested, the response time was slower than the seventh configuration. In conclusion the seventh configuration was chosen as the optimal configuration to control mobile robot.



## **Awards & Organizations**

Description	Place	Year
Petra Automotive Challenge	Third Place Winner	2011
2011		
Junior Assistant	Laboratory of System and	2013
	Control	
Member of Caring	Petra Electrical Student Council	2013/2014
Department		
Leader of Electrical Student	Petra Electrical Student Council	2014/2015
Council		
Member of Faculty	Petra Faculty Legislative Board	2015/2016
Legislative Board	2	
Vice-Leader of Student	Petra Student Legislative Board	2015/2016
Legislative Board		
Senior Assitant	Laboratory of System and	2014-2016
	Control	
Most Active Student	Student Activity Points: 325.9	2016
Achievement		
Conference Workshop	International Conference on	2017 (September)
Speaker	Electrical Systems, Technology	
	and Information (ICESTI 2017)	
Outreach Assistant of	Visiting scholar to give lecture	2017 (July – September)
Assistive Robotics Group	on Mobile Robot Design and	
	Robotics Course in Petra	
	Christian University	

# **Working Experiences**

Description	Place	Year
Electrical Internship	KONE INDO ELEVATOR	2015 ( June – July )
Duckietown Summer School	National Chiao Tung	2017 (July)
Program	University	
International Duckietown	Petra Christian University	2017 (July – September)
Summer Program		
Sound man	Trinity Church (Surabaya,	2014-2015
	Indonesia)	
Sound man	Victory English Fellowship	2017-now
	(Hsinchu, Taiwan)	

## **Projects**

Name	Course	Year	Things Learned
Library Circulation	Web	3 <sup>rd</sup> Semester	HTML5, PHP, Database
System	Programming	(2013/2014)	

Current Sensor	Sensor and	4 <sup>th</sup> Semester	Op Amp, ACS712 Sensor, Arduino
ACS712	Actuator	(2013/2014)	Programming
Energy Meter Using	Sensor and	4 <sup>th</sup> Semester	Op Amp, ACS712 Sensor, Arduino
ACS712 Current	Actuator	(2013/2014)	Programming, AC measuring
Sensor based on			
Arduino			
Quadruple Crawling	Robot	6 <sup>th</sup> Semester	Servos, Arduino Programming
Robot	Engineering	(2014/2015)	
Stamping Machine	Automation I	6 <sup>th</sup> Semester	Siemens PLC Module, Ladder
using TIA Portal		(2014/2015)	Diagram, TIA Portal
(Siemens PLC)			
Mobile Robot	Thesis	8 <sup>th</sup> Semester	EEG Sensor (Emotiv Epoc+), Brain
Movement Using		(2015/2016)	Theory, Arduino Programming,
EEG Sensor Emotiv			Bluetooth Module, Driver Control
Robo-Cleaner	Robotic	2 <sup>nd</sup> Semester	ROS, OpenCV, Gripper, Python
	Vision	of Master	
		Degree	
		(2017)	

### **Personal Skills**

#### 1. Language:

• Indonesia : Native in Writing, Listening, Speaking

• English: Fluent in Writing, Listening, Speaking

• Chinese: Fair in Writing, Listening, Speaking

### 2. Computer:

- PLC Programming (Siemens)
- HMI Interface (Wonderware Invensys)
- Ms. Office (Word, Excel, Powerpoint)
- Programming:
  - o Assembly
  - o C programming language
  - o Matlab
  - o Arduino

### Some project references:

Name	Description
Current Sensor ACS712	https://www.youtube.com/watch?v=2
	<u>wpLzZCguBY</u>
Energy Meter Using ACS712 Current Sensor based on	https://www.youtube.com/watch?v=va
Arduino	<u>Ic5n-ICCg</u>
Quadruple Robot	https://www.youtube.com/watch?v=pj
	<u>WizaALZaU</u>
Stamping Machine using TIA Portal (Siemens PLC)	https://www.youtube.com/watch?v=2
	mhTmydvE_I
Mobile Robot Movement Using EEG Sensor Emotiv	https://youtu.be/eZAQMJgyWOo