





Hao Wei Hsu

Robotics and Automation

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 1990-08-18

Software Engineer with 2+ years of experience designing PC-based motor/robot controller projects. An autonomous worker committed to providing high quality product. Proficient in Industrial Automation and in possession of a master degree of Electrical and Control Engineering in NCTU.



Experience

2015-07 - present **Software Engineer**

MOTORCON INC.

Responsibilities

- Research and design motion control algorithms.
- Low-level device driver development W/Windows, Linux.

Achievements

- Generic motion control platform MDH1K/MDH1K5.
- Industrial robot controller: SCARA/Delta/Articulated/UR5/Custom type W/EtherCAT interface.
- Industrial trackless AGV system.

2018-02 - present **On-Job PhD.**

ARG-NCTU



Education

2012-07 - 2015-05 **National Chiao-Tung University, 1001 University Road, Hsinchu 300, Taiwan, R.O.C., Institute of Electrical Control Engineering**

Implementation of a four-joint robot to bat a flying ball into a designated location.

- GPU-based image processing W/binocular camera to identify a flying ball.
- An optimization problem for accomplishing the ball-batting task.
- Dynamic model based controller implemented on DSP board.



Skills

Coding Skills



C/C++/C#, Assembly, Script Language (MATLAB, Python)

Operating Systems



Windows/Linux (API, Device Driver)

Embedded Development Platform



DSP F28335, Jetson Tx1, Raspberry Pi3, 8051

Middle Ware



Robot Operating System