

Arm® BSA Architecture Compliance

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User Guide

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User Guide

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1. Introduction

1.1 Conventions

The following subsections describe conventions used in Arm documents.

Glossary

The Arm® Glossary is a list of terms used in Arm documentation, together with definitions for those terms. The Arm Glossary does not contain terms that are industry standard unless the Arm meaning differs from the generally accepted meaning.

See the Arm Glossary for more information: developer.arm.com/glossary.

Convention	Use	
italic	Citations.	
bold	Terms in descriptive lists, where appropriate.	
monospace	Text that you can enter at the keyboard, such as commands, file and program names, and source code.	
monospace <u>underline</u>	A permitted abbreviation for a command or option. You can enter the underlined text instead of the full command or option name.	
<and></and>	Encloses replaceable terms for assembler syntax where they appear in code or code fragments. For example:	
	MRC p15, 0, <rd>, <crn>, <crm>, <opcode_2></opcode_2></crm></crn></rd>	
SMALL CAPITALS	Terms that have specific technical meanings as defined in the Arm® Glossary. For example, IMPLEMENTATION DEFINED, IMPLEMENTATION SPECIFIC, UNKNOWN, and UNPREDICTABLE.	



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Your system requires the following. If you do not follow these requirements your system will not work.



You are at risk of causing permanent damage to your system or your equipment, or of harming yourself.



This information is important and needs your attention.



This information might help you perform a task in an easier, better, or faster way.



This information reminds you of something important relating to the current content.

1.2 Useful resources

This document contains information that is specific to this product. See the following resources for other useful information.

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Each document link in the tables below provides direct access to the online version of the document.

Arm product resources	Document ID	Confidentiality
GICv3 and GICv4 Software Overview	DAI0492	Non-Confidential
Arm® Base System Architecture 1.0	DEN0094C	Non-Confidential

Arm architecture and specifications	Document ID	Confidentiality
Arm® Architecture Reference Manual for A-profile architecture	DDI0487	Non-Confidential
Arm® Generic Interrupt Controller Architecture Specification for GIC architecture version 3.0 and version 4.0	IHI0069	Non-Confidential



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See the Arm® website for other relevant information.

- Arm® Developer.
- Arm® Documentation.
- Technical Support.
- Arm® Glossary.

2. Overview

This chapter provides an overview of the BSA tests and the test IDs.

2.1 Abbreviations

This section lists the abbreviations used in this document.

Table 2-1: Abbreviations and expansions

Abbreviation	Expansion
ACPI	Advanced Configuration and Power Interface
BSA	Base System Architecture
DT	Device Tree
GIC	Generic Interrupt Controller
HVC	HyperVisor Call
PAL	Platform Abstraction Layer
PCle	Peripheral Component Interconnect express
PE	Processing Element
PSCI	Power State Coordination
SMC	Secure Monitor Call
SMMU	System Memory Management Unit
UEFI	Unified Extensible Firmware Interface

2.2 Overview of test suites

The following table describes the general divisions of Base System Architecture (BSA) tests between Unified Extensible Firmware Interface (UEFI) shell application and Linux application.

Table 2-2: Test environment and modules

Test environment	Modules
UEFI shell	PE, GIC, Timers, Watchdog, Wakeup and Power, PCIe, Memory map, Exerciser, Peripheral, and SMMU
Linux command line	PCIe, Memory map, and Peripheral

2.3 Test IDs

This section provides information on module names and module IDs.

The test ID of each test is generated as an addition to the module ID and unit test ID. For a given module, the unit test ID begins from 1.

The following table lists the module name and module IDs.

Table 2-3: Module name and Module ID

Module name	Module ID
PE	0
Memory Map	100
GIC	200
SMMU	300
Timer	400
Wakeup and Power	500
Peripheral	600
Watchdog	700
PCle	800
Exerciser	900



Each module has tests classified as operating system, hypervisor, and platform security as defined by the BSA v1.0 (C) specification.

3. UEFI shell application

This chapter provides information on executing tests from the UEFI shell application and the PAL API implementation.

3.1 UEFI shell application arguments

This section provides information on the UEFI shell application arguments.

Run the UEFI shell application with the following set of arguments:

```
uefi shell> bsa.efi [-v <n>] [-skip <x,y,z, ...>] [-f <file name>] [-os] [-hyp] [-ps] [-dtb <file name>] -t <x,y,z> [-m <x,y,z>] [-mmio] [-sbsa] [-timeout <wakeup test timeout multiple>] [-p2p] [-cache] [-el1physkip] [-l <n>] [-only] [-fr]
```



The shell session becomes unusable after all the BSA tests are run and the test results are printed on the UEFI console.

```
uefi shell> Acs.efi [-v <n>] [-skip <x,y,z, ...] [-f <file name>] [-os] [-hyp] [-
ps] [-dtb <file name>]
-t <x,y,z> [-m <x,y,z>] [-mmio] [-sbsa] [-timeout <wakeup test timeout multiple>]
[- p2p] [-cache] [-el1physkip] [-l <n>] [-only] [-fr]
```



By default, only BSA tests run. To run SBSA tests, pass the -sbsa parameter.

The following table provides descriptions to the arguments.

Table 3-1: Description of UEFI application arguments

Argument	Description	
-A	Print level	
	 INFO and above. DEBUG and above. TEST and above. WARN and ERROR. ERROR. 	

Argument	Description	
-skip	Overrides the suite to skip the execution of a particular test(s) or/and module(s).	
	For example, 302 skips test case with ID = 302.	
	200 skips all tests in module with ID = 200.	
	For more information on module IDs, see the 2.3 Test IDs on page 9.	
-f	File name to which the output log is written.	
-os	By default, all the operating system, hypervisor, and platform security view tests are run.	
-hyp	To run specific tests, add the following options:	
-ps	-osRun the operating system view testshypRun the hypervisor view testspsRun the platform security view tests.	
-dtb	Dumps the board Device Tree (DT) blob into the specified file.	
-t	To run only multiple selected tests.	
-m	To run only multiple selected modules.	
	Note: -m will override -t if used on the same module.	
-sbsa	Flag to pass to run bsa tests as per SBSA requirements.	
-timeout	Timeout value for wakeup test.	
-p2p	Pass this flag to indicate system support PCIe p2p.	
-cache	Pass this flag to indicate system support PCle address translation cache.	
-mmio	Enables all the mmio read or write prints.	
	Note: • To enable pal_mmio_read or write prints, use with -v 1. • Enables prints from specific module by using module id. For example, -mmio 200, enables for GIC module, and -mmio 0, enables for PE module.	
-el1physkip	Skips EL1 register checks.	
-1	Level of compliance to be tested for. The default value is 1.	
-only	Runs tests of a selected level. This option needs to be passed along with -I (level) option.	
-fr	To run BSA future requirements tests.	



-dtb option is for platforms that present DT files only.

Examples

The following examples show how to run the UEFI shell application using arguments:

```
shell > bsa.efi -v 2 -skip 200,302 -f acs.txt -os -dtb platform.dtb
```

The set of parameters shown in the code block:

- Prints messages with verbosity of 2 and above.
- Tests for compliance against operating system view tests.
- Skips execution of all tests belonging to Generic Interrupt Controller (GIC) module and test number 302.
- Stores the log messages to the acs.txt file.
- Saves the firmware DT into the platform.dtb file.

```
shell > bsa.efi -m 200 -skip 202
```

The set of parameters shown in the code block:

- Runs only GIC module.
- Skips GIC test 202.

3.2 UEFI shell implementation of PAL APIs

This section provides information on infrastructure APIs and module-specific APIs.

Booting to a UEFI shell is a prerequisite for running a BSA test.

Infrastructure APIs

The following table describes the Platform Abstraction Layer (PAL) APIs and UEFI interfaces.

Table 3-2: PAL APIs and UEFI interfaces

PAL API	UEFI interface
pal_print	AsciiPrint
mem_alloc	gBS->AllocatePool
mem_free	gBS->FreePool
mem_alloc_shared	gBS->AllocatePool
mem_free_shared	gBS->FreePool
aligned_alloc	gBS->AllocatePool
mem_free_aligned	gBS->FreePool
mem_get_shared_addr	None
mmio_read	None
mmio_write	None

Module-specific APIs

The following table represents the mapping of PAL API to Advanced Configuration and Power Interface (ACPI), if the system firmware presents platform configuration through ACPI tables.

Table 3-3: PAL APIs, UEFI interfaces, and ACPI tables consumed

PAL APIs	UEFI interfaces	ACPI tables consumed
pe_create_info_table	gST->ConfigurationTable	MADT Table
	CompareGuid	
	IndustryStandard/Acpi61.h	
call_smc	-	-
pe_execute_payload	-	-
pe_install_esr	gEfiCpuArchProtocolGuid	-
	Cpu->RegisterInterruptHandler	
gic_create_info_table	gST->ConfigurationTable	MADT table
	CompareGuid	
	IndustryStandard/Acpi61.h	
gic_install_isr	gHardwareInterruptProtocolGuid	-
	RegisterInterruptSource	
	EnableInterruptSource	
timer_create_info_table	gST->ConfigurationTable	GTDT table
	CompareGuid	
	IndustryStandard/Acpi61.h	
wd_create_info_table	gST->ConfigurationTable	GTDT table
	CompareGuid	
	IndustryStandard/Acpi61.h	
pcie_create_info_table	gST->ConfigurationTable	MCFG table
	CompareGuid	
	IndustryStandard/Acpi61.h	
pcie_get_mcfg_ecam	gST->ConfigurationTable	MCFG table
	CompareGuid, IndustryStandard/Acpi61.h	
	IndustryStandard/ MemoryMappedConfigurationSpaceAccessTable.h	
iovirt_create_info_table	gST->ConfigurationTable	IORT table
	CompareGuid	
	IndustryStandard/Acpi61.h	
peripheral_	gEfiPciloProtocolGuid	-
create_info_table	Pci->GetLocation	
	Pci->Pci.Read	
memory_create_info_table	gBS->GetMemoryMap	-

The following table represents the mapping of PAL API to DT node, if the system firmware presents platform configuration through DT nodes.

Table 3-4: PAL APIs, UEFI interfaces, and DT nodes consumed

PAL APIs	UEFI interfaces	DT nodes consumed
pe_create_info_table	• gST-	cpu, pmu, interrupt-controller node
gic_create_info_table	>ConfigurationTable • CompareGuid	interrupt-controller, v2m and its nodes
timer_create_info_table		systimer and memory mapped timer nodes
wd_create_info_table		watchdog nodes
pcie_create_info_table		pcie node
iovirt_create_info_table		smmu node
peripheral_create_info_table		usb, uart, and sata node
memory_create_info_table	gBS->GetMemoryMap	-

4. Linux application

This chapter provides information on executing tests from the Linux application.

4.1 Linux application arguments

This section provides information on the Linux application arguments.

Run the Linux application with the following set of arguments.

```
shell> bsa [--v < n>] [--skip < x, y, z>] [-l < n>] [-only] [-fr]
```

Table 4-1: Description of Linux application arguments

Argument	Description	
v	Print level	
	 1 INFO and above 2 DEBUG and above 3 TEST and above 4 WARN and ERROR 5 ERROR 	
skip	Overrides the suite to skip the execution of a particular test.	
	For example, 53 skips test case with ID = 53.	
-1	Level of compliance to be tested for. The default value is 1.	
-only	Runs tests of a selected level. This option needs to be passed along with -I (level) option.	
-fr	To run BSA future requirements tests.	

Example

In the following example, the set of parameters tests for compliance against BSA with print verbosity set to 3, and skips the test number 57.

```
shell> bsa --v 3 --skip 57
```

Loading the kernel module

Before running the BSA ACS Linux application, load the BSA ACS kernel module using the insmod command.

```
shell> insmod bsa_acs.ko
```

Appendix A Revisions

This appendix describes the technical changes between released issues of this book.

A.1 Revisions

This section consists of all the technical changes between different versions of this document.

Table A-1: Issue 0005-01

Change	Location
First release	-

Table A-2: Differences between Issue 0005-01 to Issue 0009-02

Change	Location
Added the abbreviation for SMMU in the list.	See, 2.1 Abbreviations on page 9.
Added a UEFI shell argument with its description.[-dtb <file name="">]</file>	See, 3.1 UEFI shell application arguments on page 11.

Table A-3: Differences between Issue 0009-02 to Issue 0100-01

Change	Location
Added sata to the PAL APIs, UEFI interfaces, and DT nodes consumed table.	See, 3.2 UEFI shell implementation of PAL APIs on page 13.

Table A-4: Differences between Issue 0100-01 to Issue 0100-02

Change	Location
Added abbreviations for HVC and PSCI in the list.	See, 2.1 Abbreviations on page 9.
Added [-dtb [-t <test id="">], [-m <module id="">], [-sbsa], [-timeout <wakeup multiple="" test="" timeout="">], [-p2p], [-cache] to UEFI shell application arguments</wakeup></module></test>	See, 3.1 UEFI shell application arguments on page 11.
Added one more example for UEFI shell application usage.	See, 3.1 UEFI shell application arguments on page 11.

Table A-5: Differences between Issue 0100-02 to Issue 0100-03

Change	Location
Added the parameter bsa.efi to UEFI shell arguments.	See, 3.1 UEFI shell application arguments on page 11.
Added PAL APIs.	See, 3.2 UEFI shell implementation of PAL APIs on page 13.

Table A-6: Differences between Issue 0100-03 to Issue 0100-04

Change	Location
Updated the UEFI shell application set of arguments and their descriptions.	See, 3.1 UEFI shell application arguments on page 11.

Table A-7: Differences between Issue 0100-04 to Issue 0100-05

Change	Location
No technical changes.	-

Table A-8: Differences between Issue 0100-05 to Issue 0100-06

Change	Location
Added UEFI shell argument with its description [-l <n>] [-only] [-fr] .</n>	See, 3.1 UEFI shell application arguments on page 11.
Added Linux application argument with its description [-I <n>] [-only] [-fr] .</n>	See, 4.1 Linux application arguments on page 16.

Table A-9: Differences between Issue 0100-06 to Issue 0100-07

Change	Location
Added the UEFI shell application arguments.	See, 3.1 UEFI shell application arguments on page 11.