

# mbed OS

## Introduction to peripheral testing

**ARM**

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# Agenda

- Goals & project overview
- What can we test?
- Hardware requirements
- How to run automated tests

# Goals

- Increase test coverage of mbed OS & supported platforms
- Extend tests to external signals (first step to hardware-in-the-loop)
- Improve user experience

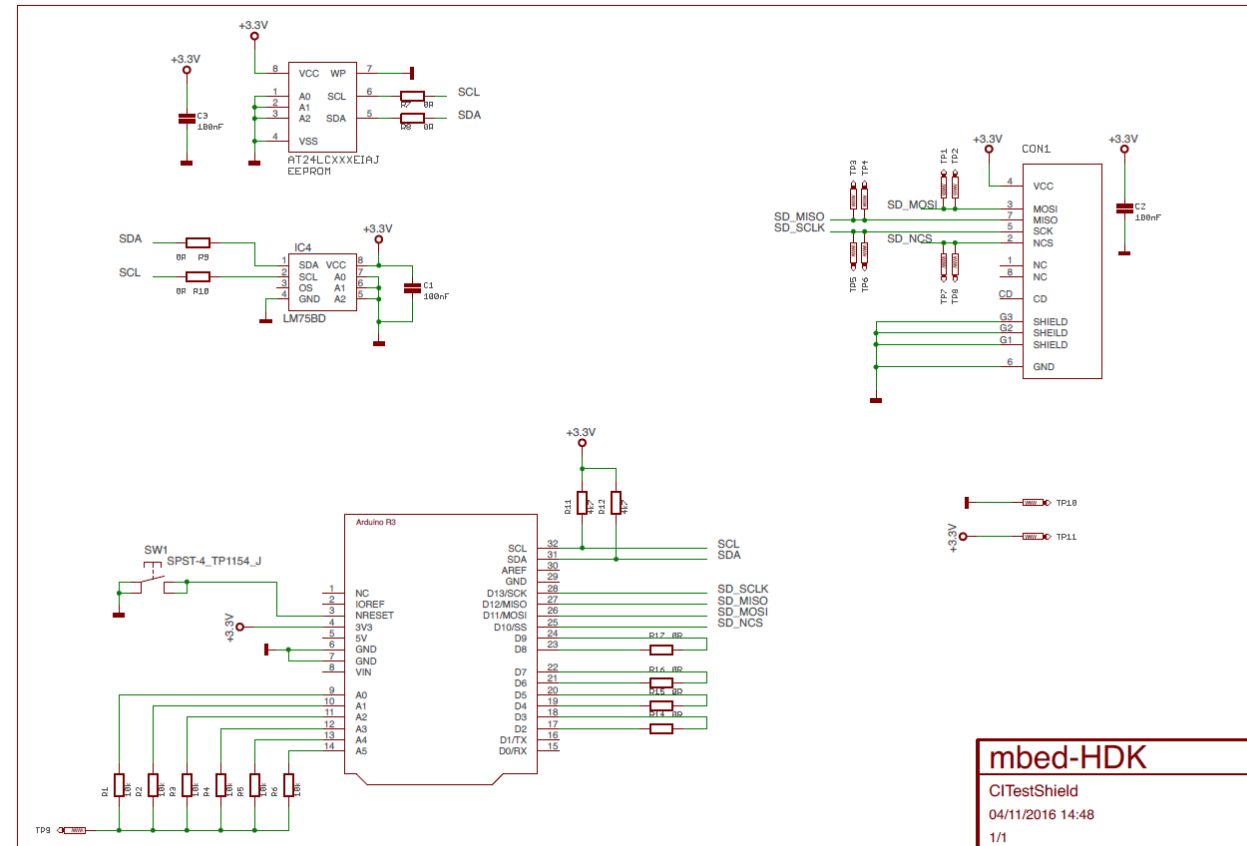
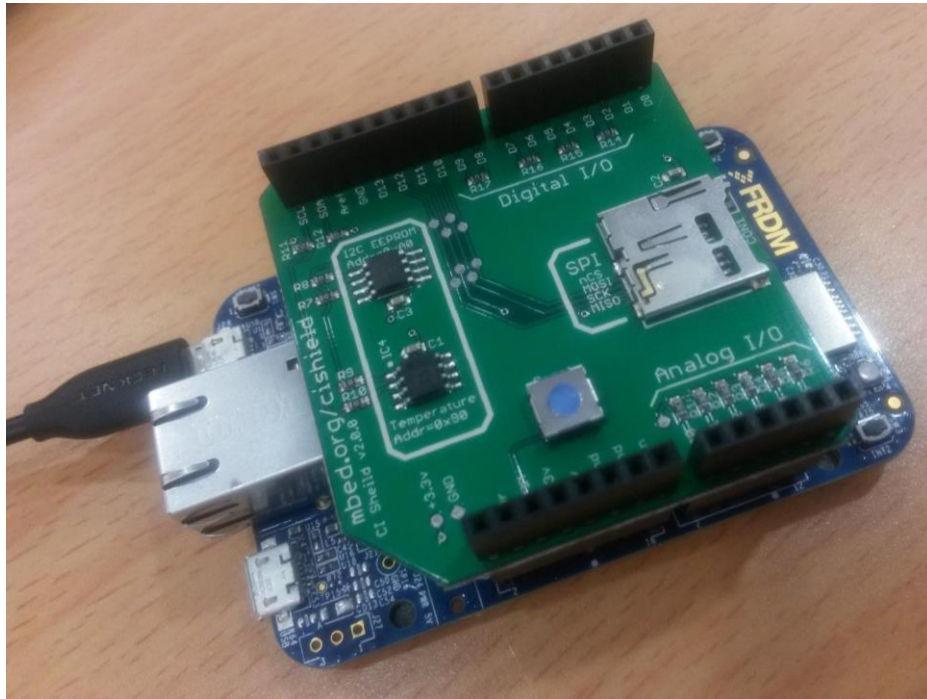
# Project Overview

- Test peripheral drivers and verify Basic Expected behavior
  - Drivers may not be fully implemented
  - Timing issues (e.g. limitation on frequency, clocks, etc)
  - Concurrency usage: multiple instances of same driver may have issues
  - Corner cases (e.g. pin resources may not be correctly initialized/de-initialized)
- Catch regressions as more features are being added and refactoring is happening
- Prepare for Continuous Integration testing on github contributions
- To become standard requirement of mbed Enabled
- Documentation and examples available here:  
<https://github.com/ARMmbed/ci-test-shield>

# Arduino headers - CI Test Shield

- The CI shield wiring diagram:

[https://github.com/ARMmbed/mbed-HDK/blob/master/Production%20Design%20Projects/CItestShield/v2.0.0/CItestShield%20V\\_2\\_0\\_0%20SCH.pdf](https://github.com/ARMmbed/mbed-HDK/blob/master/Production%20Design%20Projects/CItestShield/v2.0.0/CItestShield%20V_2_0_0%20SCH.pdf)

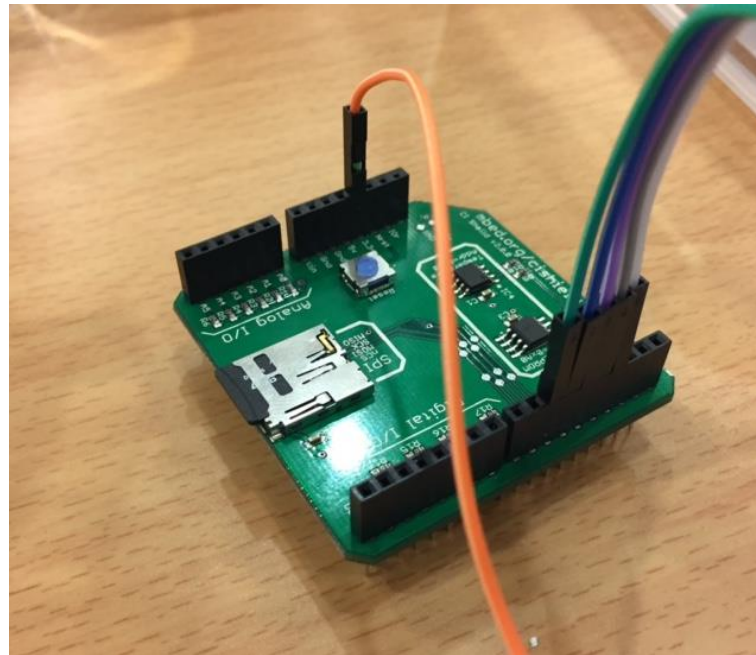


# What can be tested today?

- Peripheral drivers
  - DigitalIO, BusInOut, InterruptIn, PwmOut - tested by loopback on pins D2-9
  - AnalogIO - tested by resistor star network
  - I2C - tested with temperature sensor and EEPROM memory
  - SPI – tested with SD Card
  - UART – indirectly tested by the test framework

# Testing without Arduino headers

- Testing is still possible but need to wire hardware
- Make sure wiring is done prior to running to tests



# Testing Level I: Assumptions

- Assumptions = Behaviours required to run the tests
  - Can instantiate object for interface class?
  - Is pin connected?
  - Special test requirements / limitations of CI Test Shield
    - To run the AnalogIn test, the pins are required to have DigitalOut capability



# Testing Level 2 :API

- API Tests = Testing peripheral driver interfaces
  - Reading / writing data
  - Verify signal levels
  - Verify interrupts
  - Check timing
  - Basic measurements

# Getting started

- Download the CI tests, compile and run!

```
$ mbed import https://github.com/ARMmbed/ci-test-shield  
$ cd ci-test-shield  
$ mbed test -t <toolchain> -m <target> -n tests-*
```

# Example Test Results

target	platform_name	test suite	test case	passed	failed	result	elapsed_time (sec)
K64F-GCC_ARM	K64F	tests-api-digitalio	Digital I/O on DIO_2/DIO_3	1	0	OK	0.05
K64F-GCC_ARM	K64F	tests-api-digitalio	Digital I/O on DIO_3/DIO_2	1	0	OK	0.05
K64F-GCC_ARM	K64F	tests-api-digitalio	Digital I/O on DIO_4/DIO_5	1	0	OK	0.06
K64F-GCC_ARM	K64F	tests-api-digitalio	Digital I/O on DIO_5/DIO_4	1	0	OK	0.06
K64F-GCC_ARM	K64F	tests-api-digitalio	Digital I/O on DIO_6/DIO_7	1	0	OK	0.06
K64F-GCC_ARM	K64F	tests-api-digitalio	Digital I/O on DIO_7/DIO_6	1	0	OK	0.06
K64F-GCC_ARM	K64F	tests-api-digitalio	Digital I/O on DIO_8/DIO_9	1	0	OK	0.06
K64F-GCC_ARM	K64F	tests-api-digitalio	Digital I/O on DIO_9/DIO_8	1	0	OK	0.05
K64F-GCC_ARM	K64F	tests-api-i2c	I2C - EEPROM 2nd WR 10 Bytes	1	0	OK	0.06
K64F-GCC_ARM	K64F	tests-api-i2c	I2C - EEPROM 2nd WR 100 Bytes	1	0	FAIL	0.08
K64F-GCC_ARM	K64F	tests-api-i2c	I2C - EEPROM 2nd WR 2 Bytes	1	0	OK	0.05
K64F-GCC_ARM	K64F	tests-api-i2c	I2C - EEPROM 2nd WR Single Byte	1	0	OK	0.06
K64F-GCC_ARM	K64F	tests-api-i2c	I2C - EEPROM WR 10 Bytes	1	0	OK	0.06
K64F-GCC_ARM	K64F	tests-api-i2c	I2C - EEPROM WR 100 Bytes	1	0	FAIL	0.07
K64F-GCC_ARM	K64F	tests-api-i2c	I2C - EEPROM WR 2 Bytes	1	0	OK	0.05
K64F-GCC_ARM	K64F	tests-api-i2c	I2C - EEPROM WR Single Byte	1	0	OK	0.06
K64F-GCC_ARM	K64F	tests-api-i2c	I2C - Instantiation of I2C Object	1	0	OK	0.07
K64F-GCC_ARM	K64F	tests-api-i2c	I2C - LM75B Temperature Read	1	0	OK	0.06

# Handling pin name / location differences

- If your platform is Arduino-compatible follow Arduino-style pin naming / pin functions
- Add deviations to mbed\_app.json

```
"target_overrides": {  
  "NUCLEO_L476RG": {  
    "AOUT": "A2"  
  },  
  "K64F": {  
    "AOUT": "DAC0_OUT",  
    "DIO_8": "PTC12",  
    "DIO_9": "PTC4"  
  }  
}
```

# Example: run selective tests

```
$ mbed test -t GCC_ARM -m K64F -n tests-api-digitalio
```

```
mbedgt: test case report:
```

target	platform_name	test suite	test case	passed	failed	result	elapsed_time (sec)
K64F-GCC_ARM	K64F	tests-api-digitalio	Digital I/O on DIO_2/DIO_3	1	0	OK	0.0
K64F-GCC_ARM	K64F	tests-api-digitalio	Digital I/O on DIO_3/DIO_2	1	0	OK	0.07
K64F-GCC_ARM	K64F	tests-api-digitalio	Digital I/O on DIO_4/DIO_5	1	0	OK	0.05
K64F-GCC_ARM	K64F	tests-api-digitalio	Digital I/O on DIO_5/DIO_4	1	0	OK	0.05
K64F-GCC_ARM	K64F	tests-api-digitalio	Digital I/O on DIO_6/DIO_7	1	0	OK	0.05
K64F-GCC_ARM	K64F	tests-api-digitalio	Digital I/O on DIO_7/DIO_6	1	0	OK	0.06
K64F-GCC_ARM	K64F	tests-api-digitalio	Digital I/O on DIO_8/DIO_9	1	0	OK	0.07
K64F-GCC_ARM	K64F	tests-api-digitalio	Digital I/O on DIO_9/DIO_8	1	0	OK	0.06

```
mbedgt: test case results: 8 OK
```

```
mbedgt: completed in 17.86 sec
```

# Next Steps

- Test your platforms
- Provide your feedback
- Contributions are welcome

# Questions?