



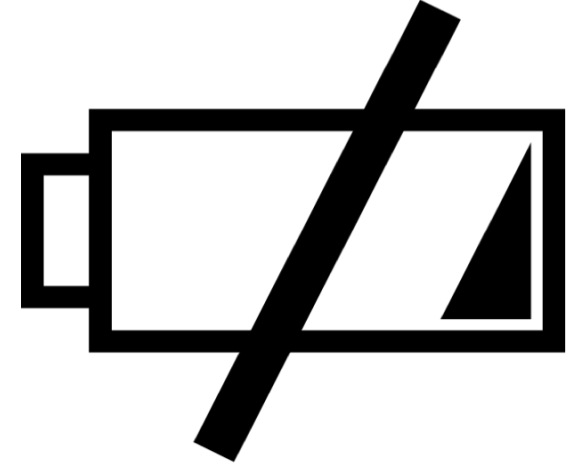
# arm

Mbed Silicon Partner Workshop

# HAL Improvements Sleep

# Introduction

- Sleep behavior
  - How does an application invoke sleep
  - How smart wait works
  - Idle loop
  - Wake up sources and latency
- Sleep manager
  - `DeepSleepLock` object
  - Lock/unlock deep sleep



# When and how your application sleeps

# Sleep modes

- Two sleep modes
  - Sleep
  - Deep sleep
- Historically
  - Explicitly selected and entered by the user
- Since Mbed OS 5.6
  - RTOS Idle loop invokes sleep

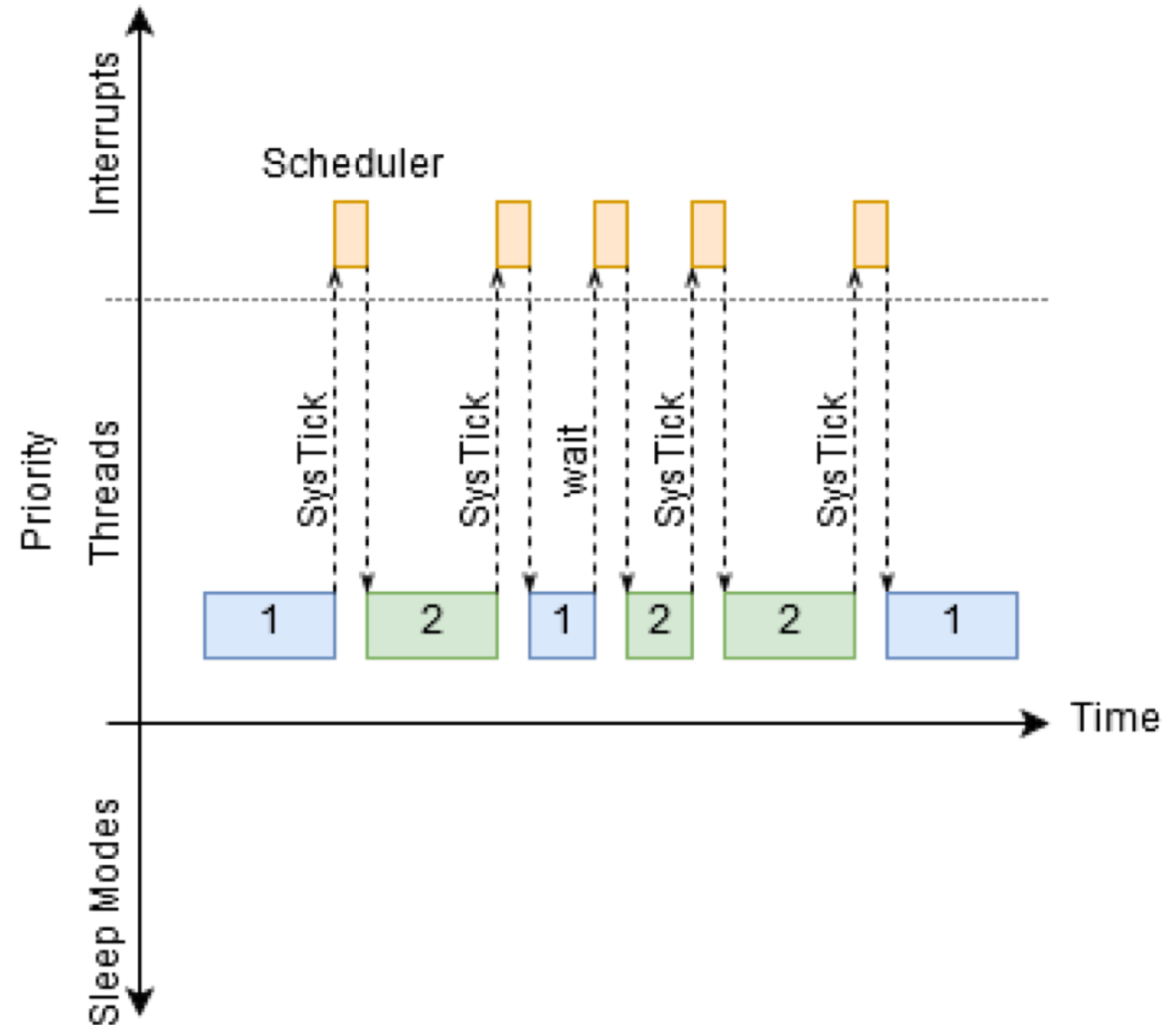


# Differences in HW/SW

- What is active during the sleep?
  - Clocks
  - Peripherals
    - SPI, UART, I2C, ...
- Wake up sources:
  - GPIO
  - RTC
  - ...
- How long does it take for the board to wake up?
  - The deeper the sleep, the longer it can take to wake up

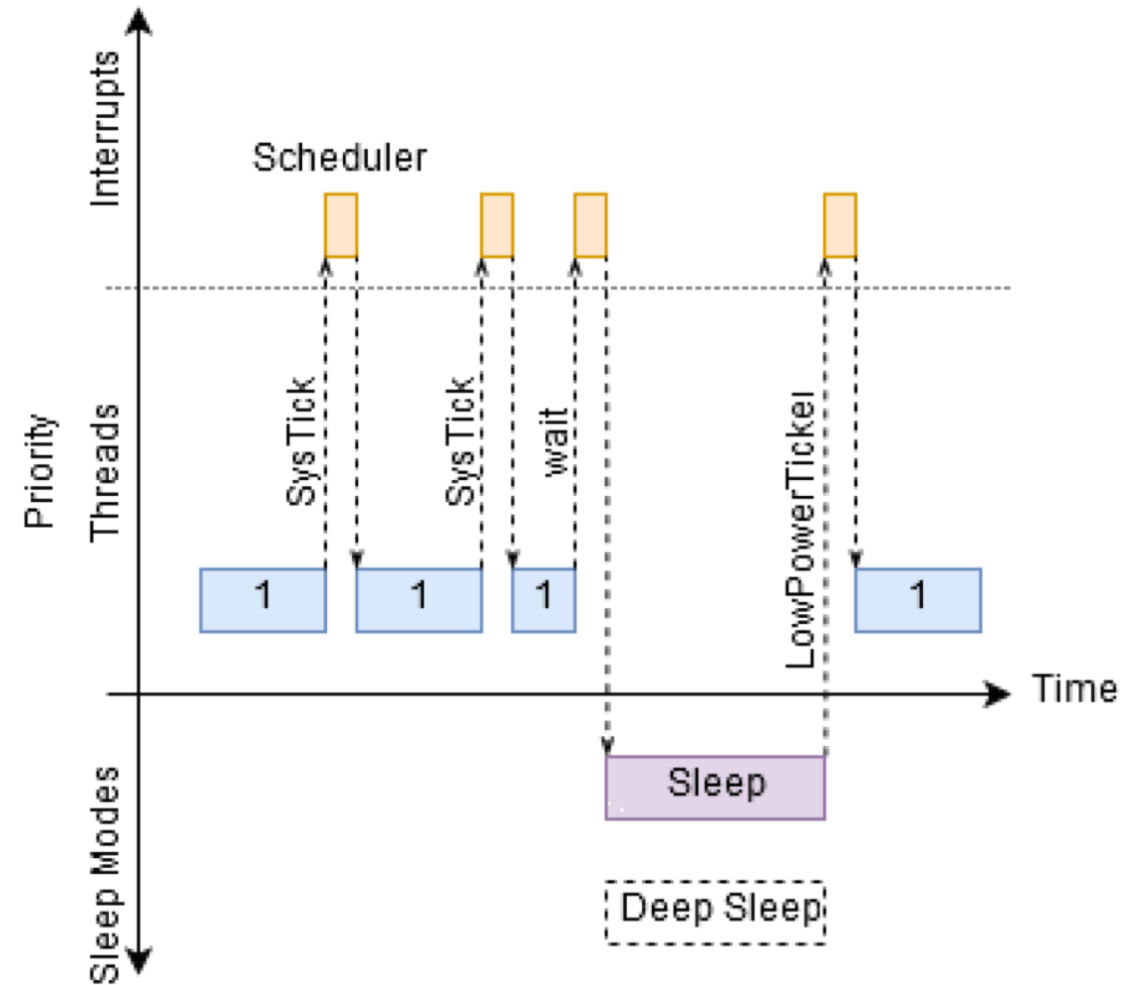
# Wait functionality

- Preemptive waiting loop
  - Tasks of the same priority are time sliced with each other
- `wait()`
  - Calls `Thread::wait(ms)`
  - Pauses execution of this thread and allows other threads to run

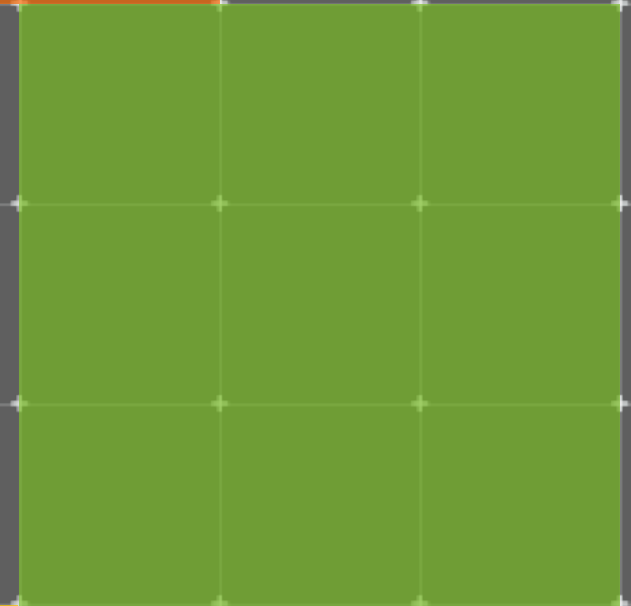


# RTOS Idle loop

- No threads ready for running – invoke idle loop
- Idle loop then enters sleep by default
  - No action is required by the application code
  - Application hook to customize the idle loop
  - `rtos_attach_idle_hook(void (*fptr)(void))`

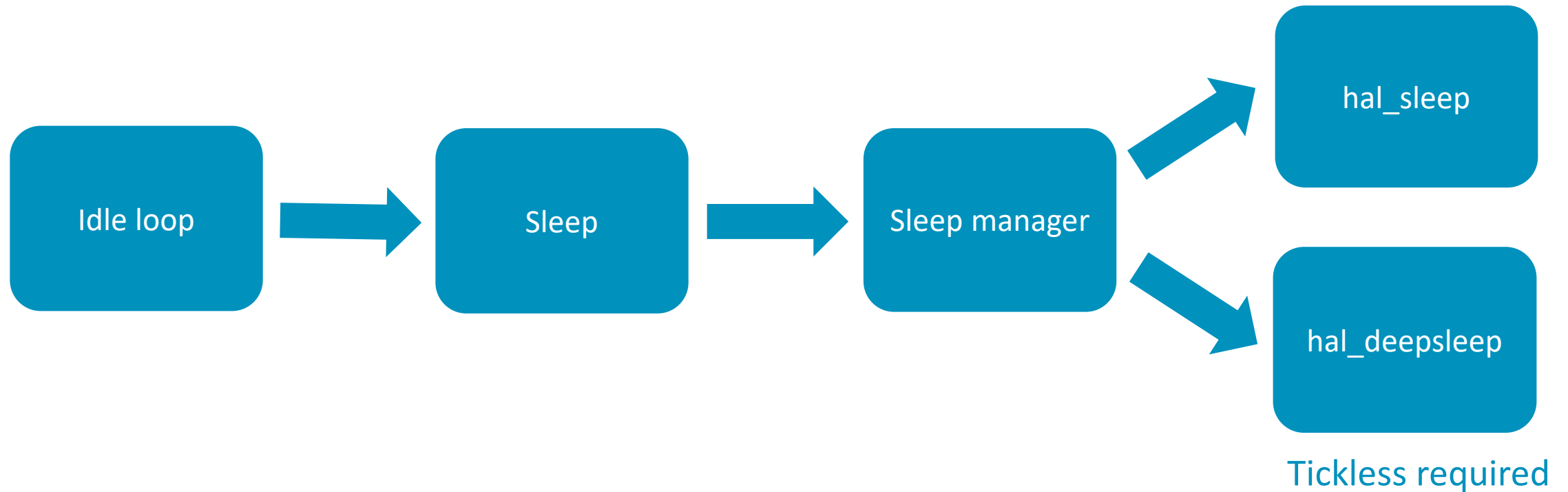


# Improved HAL Sleep



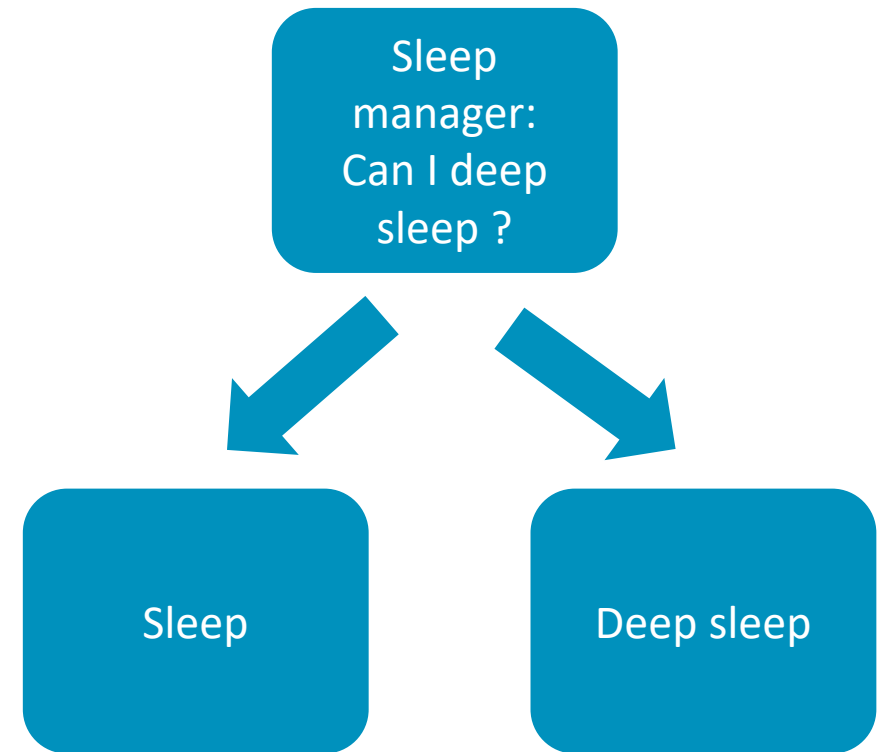


# New architecture (Mbed OS 5.6)

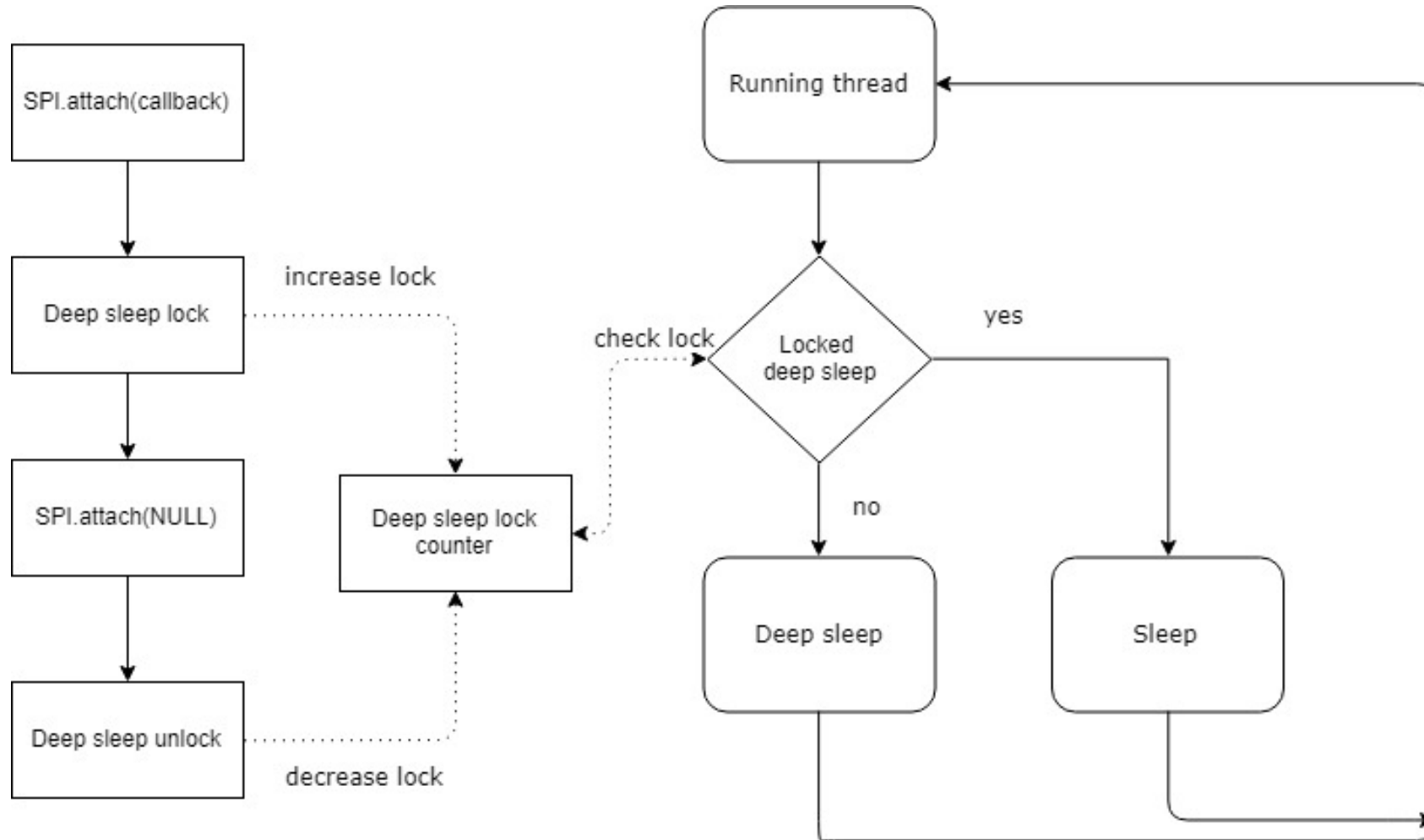


# Sleep manager

- Lock/unlock deep sleep
  - Deep sleep internal counter
- Auto sleep function
  - Chooses the best sleep mode available
  - Invoked in the sleep function



# Sleep decision flow



# DeepSleepLock

- RAI object for disabling, then restoring the deep sleep mode
  - Lock object unlocks deep sleep during destruction

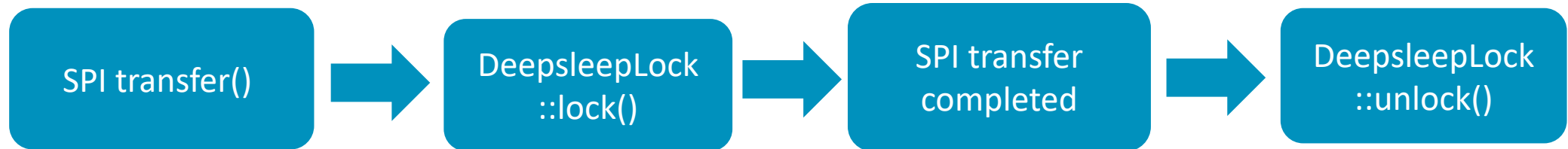
```
void pressure_measurement(SensorPressure &sensor)
{
    DeepSleepLock lock;
    sensor.attach(callback);
    sensor.start_measurement();

    // measurement takes some time, release this thread
    wait(500ms);
    result[current_reading++] = sensor.read();
}
```

# DeepSleepLock

- Provides also lock/unlock methods (useful for asynchronous objects)

`SPI::transfer(tx buff, rx buff)` - asynchronous method



# Changes to HAL

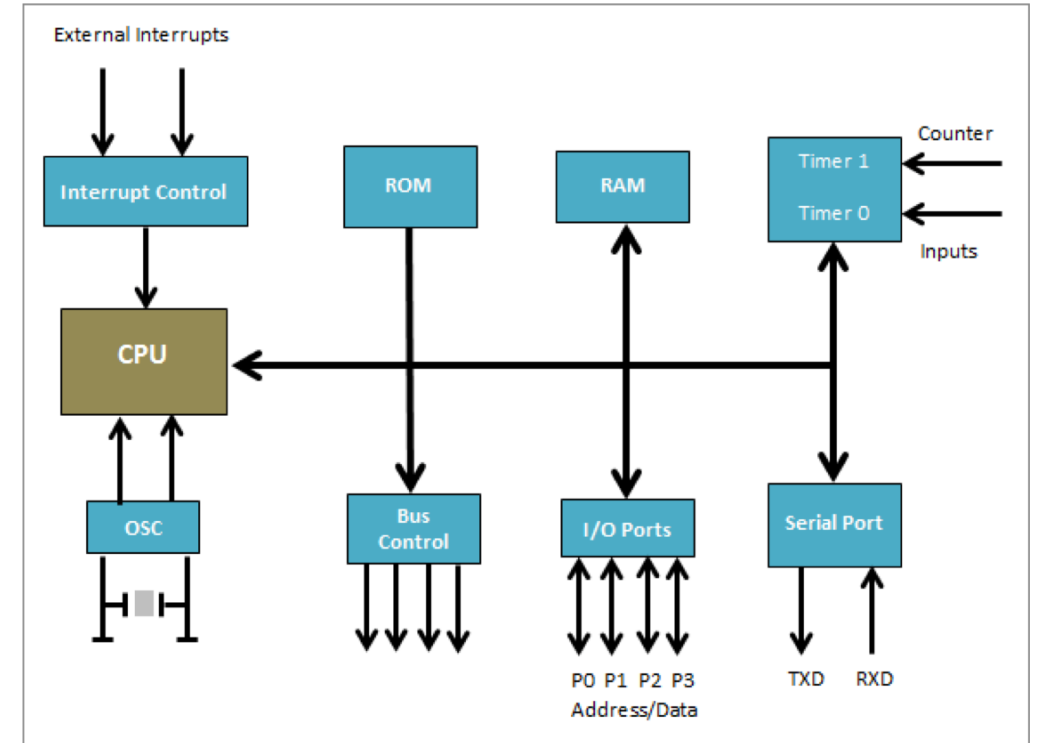
- Specification for both sleep modes
  - Status of peripherals
  - Wakeup latency
  - Wakeup sources
- Tests
- Porting guide

All of these will be discussed in detail in later slides ...



# Peripherals status during sleep

- Core system clock is disabled
- RAM is retained
- Sleep
  - Low- and high-frequency clocks are active
- Deep Sleep
  - Only low-frequency clocks are active
  - Target should disable high speed frequency clocks



# Drivers – deep sleep locked

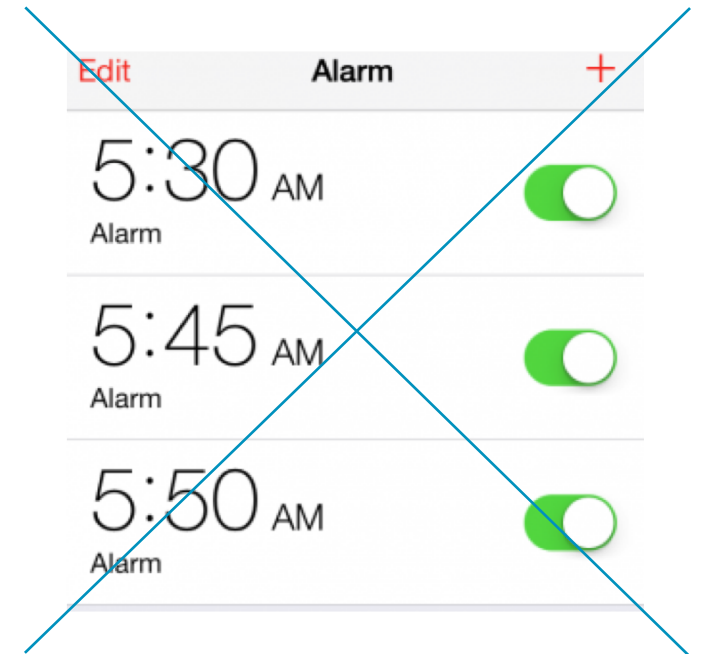
- CAN
  - I2C
  - PWMOut
  - SerialBase
  - SPI
  - Ticker
  - Timer
- 
- Custom drivers – if depends on high speed frequency clock, should lock





# Wakeup latency

- Device has to wake up and return to application within a given time
- Sleep
  - 10  $\mu$ s
- Deep sleep
  - 10 ms

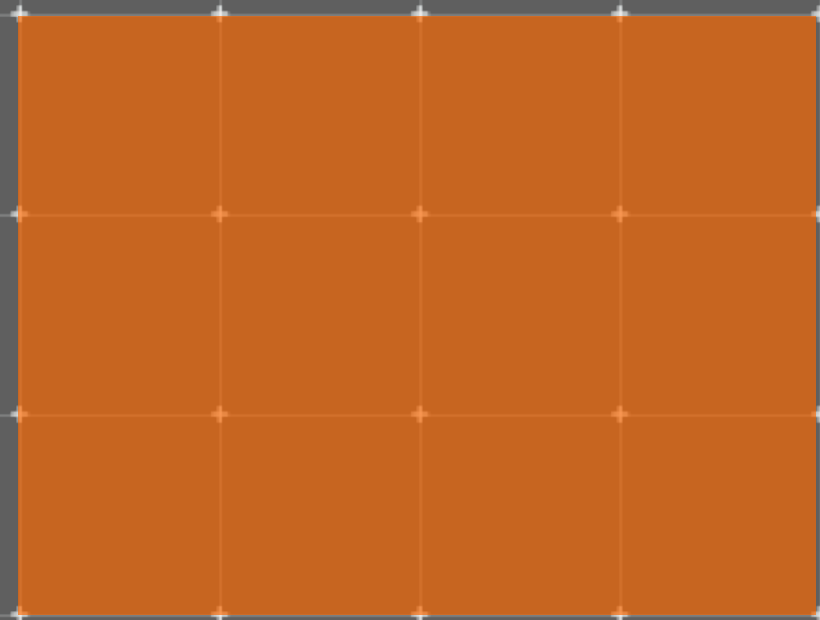


# Wakeup Sources

- Target must be able to wake up from specified sources
- Sleep:
  - Any interrupt
- Deep Sleep:
  - Watchdog
  - Low power ticker
  - GPIO



# Porting Sleep



# Sleep target support

- Add `SLEEP` to `device\_has` in targets.json

<https://github.com/ARMmbed/mbed-os/blob/master/targets/targets.json>

```
"LPC1768": {  
    "inherits": ["LPCTarget"],  
    "core": "Cortex-M3",  
    "extra_labels": ["NXP", "LPC176X", "MBED_LPC1768"],  
    "supported_toolchains": ["ARM", ..., "GCC_CR", "IAR"],  
    "detect_code": ["1010"],  
    "device_has": ["ANALOGIN", ..., "SLEEP"],  
    "release_versions": ["2", "5"],  
    "features": ["LWIP"],  
    "device_name": "LPC1768",  
    "bootloader_supported": true  
},
```

- Implement sleep functions:

[https://github.com/ARMmbed/mbed-os/blob/master/hal/sleep\\_api.h](https://github.com/ARMmbed/mbed-os/blob/master/hal/sleep_api.h)

# Implement sleep HAL

```
void hal_sleep(void);
```

- Send the microcontroller to sleep
- System clock to the core is stopped
- The processor, peripheral and memory state are maintained
- Peripherals continue to work and can generate interrupts
- Can be woken up by any internal peripheral interrupt or external pin interrupt
- Needs to resume app within 10 us

# Implement deep sleep HAL

```
void hal_deepsleep(void);
```

- Send the microcontroller to deep sleep
- System clock to the core is stopped
- The processor and memory state are maintained
- Peripherals and high frequency clocks are powered down
- Can only be woken up by low power ticker, RTC, external pin interrupt or a watchdog timer
- Needs to resume app within 10 ms
- Target should select the best deep sleep mode

# Implement sleep/deep sleep

<code>void hal_sleep(void) ;</code>	<code>void hal_deepsleep(void) ;</code>
Send the microcontroller to sleep	Send the microcontroller to deep sleep
System clock to the core is stopped	System clock to the core is stopped
The processor, peripheral and memory state are maintained	The processor and memory state are maintained (peripherals are not)
Peripherals continue to work and can generate interrupts	Peripherals and high frequency clocks are powered down
Can be woken up by any internal peripheral interrupt or external pin interrupt	Can only be woken up by low power ticker, RTC, external pin interrupt or a watchdog timer
Needs to resume app within 10 <b>us</b>	Needs to resume app within 10 <b>ms</b>

# What tests to pass?

- HAL Sleep validation suite:

```
$ git checkout feature-hal-spec-sleep  
$ mbed test -t <toolchain> -m <target> -n "tests-mbed_hal-sleep*"
```



# Hands-on workshop

- Sleep
  - Use branch - `feature-hal-spec-sleep`
  - HAL API & Testing - [https://os.mbed.com/docs/v5.7/feature-hal-spec-sleep-dox/group\\_\\_hal\\_\\_sleep.html](https://os.mbed.com/docs/v5.7/feature-hal-spec-sleep-dox/group__hal__sleep.html)
  - Porting - <https://os.mbed.com/docs/v5.7/reference/contributing-target.html#sleep>
- Workshop materials - <https://github.com/ARMmbed/mbed-sip-workshop-2018q1>

The word "arm" in a white, lowercase, sans-serif font, positioned on the right side of a solid blue background.

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