# ELCT 404 Final Presentation

Team:Smoaking Hot 4/14/2024



## Meet The Team: Smoaking Hot







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## Project Overview

The objective of this project is to create a waystation that collects data from the sensors packages on a bridge via wireless communication. This data should then be processed and converted into a csv file with various forms of information such as standard Deviation, mean, and Fast Fourier Transformations (FFT's) to provide insight of the bridges structural integrity.



## Design Philosophy

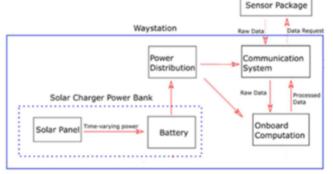
Our team's vision is to provide smoking hot products that are innovative and reliable. This is achieved by our philosophy that centers around ease and scalability.

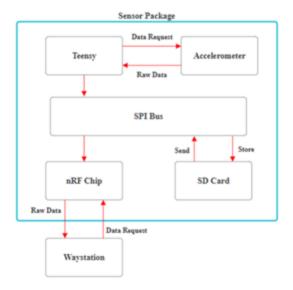
- Affordable and reusable materials
  - Flexible
  - Repeatability
- Stability
  - Hazardous conditions
  - Risk Mitigation



## System Requirements

- Wireless communication
- Onboard Processing
- Power Management
- Storage Capacity
- Low Cost







#### Achievements

- Wireless communication has been accomplished
  - Teensy to Teensy/PI
- PCB Design
  - Different Variations
  - Tested First PCB
  - Designed Second PCB
- Onboard Processing has been finished and successfully shows data
- Team has accomplished the scope of the project



#### **Financials**

A large goal for this project is repeatability and low cost. Due to this we have resorted to recycling materials and finding cost effective materials.

Material	Cost	Amount	
Recycled M	<b>Materials</b>		
Teensy 4.0	33	2	
nRF24L01 (4 pack)	10	1	
HDMI Cable	7	1	
SD cards (8GB)	10	2	
Parts We 0	Ordered		
Rasberry Pi Model 4B	50	1	
Micro USB (3 pack)	8	1	
First PCB	20	1	
To Be Ordered	d/Recycled		
<b>Buck Converter</b>	8	2	
Solar Panel	60	1	
Solar Panel Power Bank	60	1	
Waystation Cover	10	1	
Total:	3	327	



#### **Problems Faced**

- Understanding nRF chips
  - Research
- Transmitter Issues
  - o Minimum powerline code
  - Range restrictions
- Raspberry Pi Issues
  - Inexperience
  - Wireless communication
- PCB issues
  - Inexperience



#### Individual Contributions:

- Project Planning
  - o Determine Project scope and deliverables
- Team Coordination
  - Build and lead a high-performing team by assigning achievable tasks and responsibilities
- Resource Management
  - Ensure that the team has the necessary equipment to perform their tasks
- Communication
  - Planned Meeting Times with Sponsor and Team
  - Ensured everyone communicated regarding the interconnects of subsystems



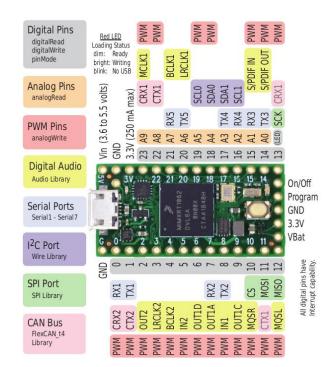
## Sensor Package Functionality

- Gather accelerometer data
  - Measures intensity of a vibration at the point it is attached to on the structure
- Store data on SD card
  - Allows for manual data retrieval if needed
- Transmit Data to waystation
  - Send accelerometer data to waystation for computation



#### Teensy 4.0

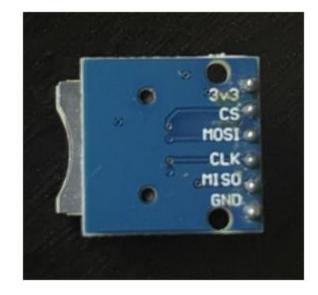
- Programmable microcontroller used for prototyping
- SPI bus
  - o 2 subsystems
- Digital pins





#### SD Card Module

- Interfaces with micro SD card
- Uses SPI bus
  - O Has its own unique chip select pin
- SD card data stored in a .csv file





### MPU6050 Accelerometer

- Multipurpose sensor
  - Accelerometer
  - Gyroscope
  - Internal thermometer
- Accelerometer measures in magnitudes of gravity

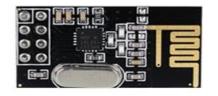




#### **NRF24L01**

- Device that uses radio frequency to achieve wireless communication
- SPI bus
  - Has its own chip select pin
- Range limitations
  - Small antennae
  - Teensy to Teensy currently working at ~2ft apart

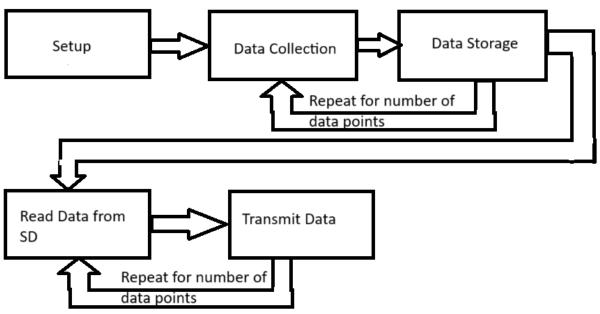




nRF24L01 Pinout



## Sensor Package Code Flow Chart





## Sensor Package Future Iterations

- Turn it into a transceiver
  - Will be prompted by the waystation to record and transmit data
  - O Achievable by transmitting a basic true/false message to the sensor package



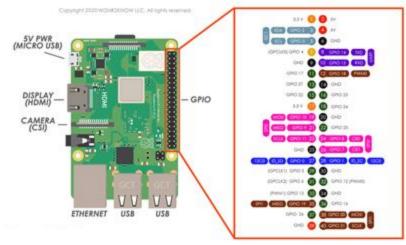
# Onboard Processing

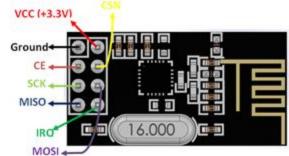
By: Steve Howard



## Raspberry Pi Setup

- Raspberry Pi Setup
  - Downloaded Raspberry OS
  - Troubleshooted setup for Pi due to network issues at UofSC
  - Wired nRF chip to Raspberry Pi
  - Setup Libraries







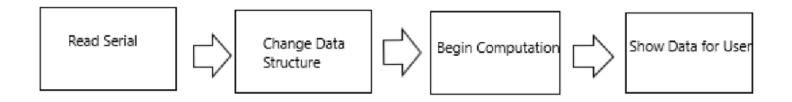
## Onboard Processing

Once the Data is on the PI then it needs to be processed into information for the user to access bridge infrastructure.

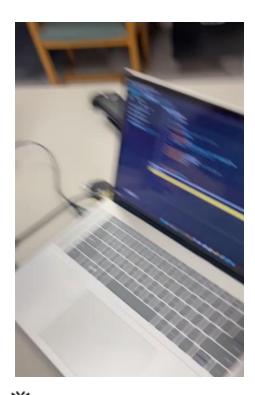
- Accessible Data:
  - Mean
  - Standard Deviation
  - Fast Fourier Transformations



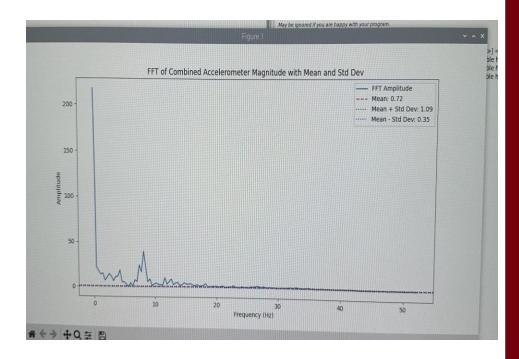
## Onboard Processing Code







#### **Demonstration**





#### What's Next

- Turn the PI into a transceiver
  - o Remove extra teensy
- Order the new set of PCB's
- Begin testing with the new nRF modules
- Design Physical Waystation
  - Weatherproof
  - Easily accessible
  - Secure



## Special Thanks:

We would like to express our sincere gratitude to the following individuals for their invaluable contributions and unwavering support:

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- Joe Gucwa

