

```

Lorenz
at-
trac-
tor
y-
dimension
un-
ob-
served
True
ODE
pa-
ram-
eters:
simulation.ode_param = [10,28,8/3];
Final
time
for
sim-
u-
la-
tion:
simulation.final_time = 20;
Observation
noise:
simulation.state_obs_variance = @(mean)(bsxfun(@times,[2,2],ones(size(mean)))));
Time
in-
ter-
val
be-
tween
ob-
ser-
vations
simulation.interval_between_observations = 0.1;
Kernel
pa-
ram-
eters
 $\phi$ 
kernel.param = [10,0.2];
Error
variance
on
state
derivatives
(i.e.
 $\gamma$ )
state.derivative_variance = [6,6,6];
Estimation
times
time.est = 0:0.1:20;
close all; clc; addpath('VGM_functions')
[symbols,simulation,ode,odes_path,coupling_idx,opt_settings,plot_settings] = ...
preprocessing_Lorenz_Attractor (simulation);
ODEs:

```

$$\begin{array}{l}
 / \quad d \, x \quad \backslash \\
 | \quad \text{---} == -\text{sigma} \, (x - y) \quad | \\
 | \quad dt \quad | \\
 | \quad | \quad | \\
 | \quad d \, y \quad | \\
 | \quad \text{---} == \text{rho} \, x - y - x \, z \quad | \\
 | \quad dt \quad | \\
 | \quad | \quad | \\
 | \quad d \, z \quad | \\
 | \quad \text{---} == x \, y - \text{lambda} \, z \quad | \\
 \backslash \quad dt \quad /
 \end{array}$$

$$\begin{array}{l}
 K \\
 \theta \in \\
 \mathcal{R}^d \\
 K \\
 \mathbf{x}(t) = \\
 [x_1(t), \dots, x_K(t)]^T \\
 \dot{\mathbf{x}}(t) = \\
 \frac{d\mathbf{x}(t)}{dt} = \\
 \mathbf{f}(\mathbf{x}(t), \theta)(1) \\
 \mathbf{y}(t) \\
 K \\
 \mathbf{E} \sim \\
 \mathcal{N}(\mathbf{E}; \mathbf{0}, \mathbf{D}) \\
 \mathbf{D}_{jk} = \\
 \sigma_k^2 \delta_{jk} \\
 N \\
 \mathbf{Y} = \\
 \mathbf{X}_+ \\
 \mathbf{E} \\
 \mathbf{X} =
 \end{array}$$