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Folder: Al
File: 8puzzle.py
Documented code for 8puzzle.py:
import heapq
class PuzzleNode:
  def __init__(self, state, parent=None, move="Initial"):
     self.state = state
     self.parent = parent
     self.move = move
     self.depth = 0
     if parent:
       self.depth = parent.depth + 1
  def __lt__(self, other):
     return self.depth < other.depth
  def __eq__(self, other):
     return self.state == other.state
  def __hash__(self):
     return hash(str(self.state))
  def __str__(self):
     return str(self.state)
  def get_blank_position(self):
     for i, row in enumerate(self.state):
       if 0 in row:
          return (i, row.index(0))
  def expand(self):
     blank_pos = self.get_blank_position()
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moves = [(0, 1), (0, -1), (1, 0), (-1, 0)] # right, left, down, up
     for move in moves:
        new_row, new_col = blank_pos[0] + move[0], blank_pos[1] + move[1]
       if 0 \le \text{new\_row} < 3 and 0 \le \text{new\_col} < 3:
          new_state = [row[:] for row in self.state]
          new_state[blank_pos[0]][blank_pos[1]] = new_state[new_row][new_col]
          new_state[new_row][new_col] = 0
          children.append(PuzzleNode(new_state, self, move))
     return children
  def is_goal(self):
     return self.state == [[0, 1, 2],
                   [3, 4, 5],
                   [6, 7, 8]
  def heuristic(self):
     # Manhattan distance heuristic
     distance = 0
     for i in range(3):
       for j in range(3):
          if self.state[i][j] != 0:
             row, col = divmod(self.state[i][j], 3)
             distance += abs(row - i) + abs(col - j)
     return distance + self.depth
def a_star_search(initial_state):
  initial_node = PuzzleNode(initial_state)
  frontier = []
  heapq.heappush(frontier, initial_node)
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children = []

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explored = set()
  while frontier:
     current_node = heapq.heappop(frontier)
     if current_node.is_goal():
       return current_node
     explored.add(current_node)
     for child in current_node.expand():
       if child not in explored:
          heapq.heappush(frontier, child)
  return None
def print_solution(solution_node):
  path = []
  current_node = solution_node
  while current_node:
     path.append(current_node)
     current_node = current_node.parent
  path.reverse()
  for i, node in enumerate(path):
     print("Step:", i, "Move:", node.move)
     print(node.state)
if __name__ == "__main__":
  initial_state = [[1, 2, 3], [0, 4, 6], [7, 5, 8]]
  solution_node = a_star_search(initial_state)
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if solution_node:
     print("Solution found!")
     print_solution(solution_node)
  else:
     print("No solution found!")
Folder: CSS
File: exp6.py
Documented code for exp6.py:
import hashlib
import secrets
import string
class SaltPepperHash:
  def __init__(self):
     self.users = {}
  def add_user(self, username, password):
     if username in self.users:
       raise ValueError("Username already exists.")
     salt = self.generate_salt()
     pepper = "9609Emmanuel2003"
     hashed_password = self.hash_password(password, salt, pepper)
     self.users[username] = {'salt': salt, 'pepper': pepper, 'hashed_password': hashed_password}
  def authenticate_user(self, username, password):
     if username in self.users:
       user_data = self.users[username]
       hashed_password = self.hash_password(password, user_data['salt'], user_data['pepper'])
       return hashed_password == user_data['hashed_password']
     else:
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def hash_password(self, password, salt, pepper):
     hashed_password = hashlib.md5(password.encode()).hexdigest()
     password_peppered = hashed_password + salt + pepper
    final_hashed_password = hashlib.md5(password_peppered.encode()).hexdigest()
     return final_hashed_password
  def display(self):
     print(self.users)
  def generate_salt(self):
     return ".join(secrets.choice(string.ascii_letters + string.digits) for _ in range(8))
password_manager = SaltPepperHash()
def create_user():
  username = input("Enter your username: ")
  password = input("Enter your password: ")
  password_manager.add_user(username, password)
  print("User created successfully.")
def display_dict():
  password_manager.display()
create_user()
create_user()
create_user()
display_dict()
def authenticate_user():
  username = input("Enter your username: ")
  password = input("Enter your password: ")
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if password_manager.authenticate_user(username, password):
     print("Authentication successful.")
  else:
     print("Authentication failed.")
authenticate_user()
authenticate_user()
File: md5.py
Documented code for md5.py:
import hashlib
import time
st = time.time()
file = open("random.txt", "r")
inputstring = file.read()
file.close()
output = hashlib.md5(inputstring.encode())
print("Hash of the input string MD5 Algorithm:")
print(output.hexdigest())
# Get Time
et = time.time()
elapsed_time = et - st
print('Execution time:', elapsed_time, 'seconds')
File: sha1.py
Documented code for sha1.py:
import hashlib
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```
import time
st = time.time()
file = open("random.txt", "r")
inputstring = file.read()
file.close()
output = hashlib.sha1(inputstring.encode())
print("Hash of the input string using SHA1 Algorithm:")
print(output.hexdigest())
# Get Time
et = time.time()
elapsed_time = et - st
print('Execution time:', elapsed_time, 'seconds')
Folder: MC
File: mc_exp3.py
Documented code for mc_exp3.py:
#!/usr/bin/python
from math import *
# import everything from Tkinter module
from tkinter import *
# Base class for Hexagon shape
class Hexagon(object):
def __init__(self, parent, x, y, length, color, tags):
 self.parent = parent
 self.x = x
 self.y = y
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self.length = length
self.color = color
self.size = None
self.tags = tags
self.draw_hex()
# draw one hexagon
def draw_hex(self):
start_x = self.x
start_y = self.y
angle = 60
coords = []
for i in range(6):
 end_x = start_x + self.length * cos(radians(angle * i))
 end_y = start_y + self.length * sin(radians(angle * i))
 coords.append([start_x, start_y])
 start_x = end_x
 start_y = end_y
self.parent.create_polygon(coords[0][0],
    coords[0][1],
    coords[1][0],
    coords[1][1],
    coords[2][0],
    coords[2][1],
    coords[3][0],
    coords[3][1],
    coords[4][0],
    coords[4][1],
    coords[5][0],
    coords[5][1],
    fill=self.color,
    outline="black",
    tags=self.tags)
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# class holds frequency reuse logic and related methods
class FrequencyReuse(Tk):
CANVAS_WIDTH = 800
CANVAS_HEIGHT = 650
TOP_{LEFT} = (20, 20)
BOTTOM_LEFT = (790, 560)
TOP_RIGHT = (780, 20)
BOTTOM_RIGHT = (780, 560)
def __init__(self, cluster_size, columns=16, rows=10, edge_len=30):
 Tk.__init__(self)
 self.textbox = None
 self.curr_angle = 330
 self.first click = True
 self.reset = False
 self.edge_len = edge_len
 self.cluster_size = cluster_size
 self.reuse_list = []
 self.all_selected = False
 self.curr_count = 0
 self.hexagons = []
 self.co_cell_endp = []
 self.reuse_xy = []
 self.canvas = Canvas(self,
    width=self.CANVAS_WIDTH,
    height=self.CANVAS_HEIGHT,
    bg="#4dd0e1")
 self.canvas.bind("<Button-1>", self.call_back)
 self.canvas.focus_set()
 self.canvas.bind('<Shift-R>', self.resets)
 self.canvas.pack()
 self.title("Frequency reuse and co-channel selection")
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self.create_grid(16, 10)
self.create_textbox()
self.cluster_reuse_calc()
# show lines joining all co-channel cells
def show_lines(self):
# center(x,y) of first hexagon
approx_center = self.co_cell_endp[0]
self.line_ids = []
for k in range(1, len(self.co_cell_endp)):
 end_xx = (self.co_cell_endp[k])[0]
 end_yy = (self.co_cell_endp[k])[1]
 # move i^th steps
 L_id = self.canvas.create_line(approx_center[0], approx_center[1],
     end_xx, end_yy)
 if j == 0:
 self.line_ids.append(l_id)
 dist = 0
 elif i \ge j and j != 0:
 self.line_ids.append(l_id)
 dist = j
 # rotate counter-clockwise and move j^th step
 I_id = self.canvas.create_line(
  end_xx, end_yy, end_xx + self.center_dist * dist *
  cos(radians(self.curr_angle - 60)),
  end_yy + self.center_dist * dist *
  sin(radians(self.curr_angle - 60)))
 self.line_ids.append(l_id)
 self.curr_angle -= 60
def create_textbox(self):
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txt = Text(self.canvas,
 width=80,
 height=1,
 font=("Helvatica", 12),
 padx=10,
 pady=10)
txt.tag_configure("center", justify="center")
txt.insert("1.0", "Select a Hexagon")
txt.tag_add("center", "1.0", "end")
self.canvas.create_window((0, 600), anchor='w', window=txt)
txt.config(state=DISABLED)
self.textbox = txt
def resets(self, event):
if event.char == 'R':
 self.reset_grid()
# clear hexagonal grid for new i/p
def reset_grid(self, button_reset=False):
self.first_click = True
self.curr_angle = 330
self.curr_count = 0
self.co_cell_endp = []
self.reuse_list = []
for i in self.hexagons:
 self.canvas.itemconfigure(i.tags, fill=i.color)
try:
 self.line_ids
except AttributeError:
 pass
else:
 for i in self.line_ids:
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self.canvas.after(0, self.canvas.delete, i)
 self.line_ids = []
if button_reset:
 self.write_text("Select a Hexagon")
# create a grid of Hexagons
def create_grid(self, cols, rows):
size = self.edge_len
for c in range(cols):
 if c \% 2 == 0:
 offset = 0
 else:
 offset = size * sqrt(3) / 2
 for r in range(rows):
 x = c * (self.edge_len * 1.5) + 50
 y = (r * (self.edge\_len * sqrt(3))) + offset + 15
 hx = Hexagon(self.canvas, x, y, self.edge_len, "#fafafa",
    "{},{}".format(r, c))
 self.hexagons.append(hx)
# calculate reuse distance, center distance and radius of the hexagon
def cluster_reuse_calc(self):
self.hex_radius = sqrt(3) / 2 * self.edge_len
self.center_dist = sqrt(3) * self.hex_radius
self.reuse_dist = self.hex_radius * sqrt(3 * self.cluster_size)
def write_text(self, text):
self.textbox.config(state=NORMAL)
self.textbox.delete('1.0', END)
self.textbox.insert('1.0', text, "center")
self.textbox.config(state=DISABLED)
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```
#check if the co-channels are within visible canvas
def is within bound(self, coords):
if self.TOP_LEFT[0] < coords[0] < self.BOTTOM_RIGHT[0] \
and self.TOP_RIGHT[1] < coords[1] < self.BOTTOM_RIGHT[1]:
 return True
return False
#gets called when user selects a hexagon
#This function applies frequency reuse logic in order to
#figure out the positions of the co-channels
def call_back(self, evt):
selected_hex_id = self.canvas.find_closest(evt.x, evt.y)[0]
hexagon = self.hexagons[int(selected_hex_id - 1)]
s_x, s_y = hexagon.x, hexagon.y
approx_center = (s_x + 15, s_y + 25)
if self.first_click:
 self.first_click = False
 self.write_text(
 """Now, select another hexagon such
 that it should be a co-cell of
 the original hexagon."""
 )
 self.co_cell_endp.append(approx_center)
 self.canvas.itemconfigure(hexagon.tags, fill="green")
 for _ in range(6):
 end_xx = approx_center[0] + self.center_dist * i * cos(
  radians(self.curr_angle))
 end_yy = approx_center[1] + self.center_dist * i * sin(
  radians(self.curr_angle))
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reuse_x = end_xx + (self.center_dist * j) * cos(
 radians(self.curr_angle - 60))
 reuse_y = end_yy + (self.center_dist * j) * sin(
 radians(self.curr_angle - 60))
 if not self.is_within_bound((reuse_x, reuse_y)):
 self.write_text(
  """co-cells are exceeding canvas boundary.
  Select cell in the center"""
 self.reset_grid()
 break
 if i == 0:
 self.reuse_list.append(
  self.canvas.find_closest(end_xx, end_yy)[0])
 elif i \ge j and j != 0:
 self.reuse_list.append(
  self.canvas.find_closest(reuse_x, reuse_y)[0])
 self.co_cell_endp.append((end_xx, end_yy))
 self.curr_angle -= 60
else:
curr = self.canvas.find_closest(s_x, s_y)[0]
if curr in self.reuse list:
 self.canvas.itemconfigure(hexagon.tags, fill="green")
 self.write_text("Correct! Cell {} is a co-cell.".format(
 hexagon.tags))
 if self.curr_count == len(self.reuse_list) - 1:
 self.write_text("Great! Press Shift-R to restart")
 self.show_lines()
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self.curr_count += 1
  else:
  self.write_text("Incorrect! Cell {} is not a co-cell.".format(
   hexagon.tags))
  self.canvas.itemconfigure(hexagon.tags, fill="red")
if __name__ == '__main__':
print(
 """Enter i & j values. common (i,j) values are:
 (1,0), (1,1), (2,0), (2,1), (3,0), (2,2)"""
i = int(input("Enter i: "))
j = int(input("Enter j: "))
if i == 0 and j == 0:
 raise ValueError("i & j both cannot be zero")
elif j > i:
 raise ValueError("value of j cannot be greater than i")
else:
 N = (i^{**}2 + i^{*}j + j^{**}2)
 print("N is {}".format(N))
freqreuse = FrequencyReuse(cluster_size=N)
freqreuse.mainloop()
```

Folder: SPCC

Folder: aws