



# EMIMEO : E(rasmus) Mundus on Innovative Microwave Electronics and Optics Master

## Foundations of Electromagnetic Wave Propagation – 2<sup>nd</sup> part

Contributors:

Olivier Tantot  
Guillaume Neveux  
Serge Verdeyme



Université  
de Limoges



UNIVERSITÀ  
DEGLI STUDI  
DI BRESCIA



Aston University



Universidad del País Vasco  
Euskal Herriko Unibertsitatea  
The University of the Basque Country



UNIVERSITATEA TEHNICĂ  
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### Foundations of electromagnetic wave propagation

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### Chapters:

#### 0. Microwave domain

#### 1. S-parameters and transmission line

- Microwave signals - time and frequency domains
- Description of microwave devices by scattering parameters
- Exercices on the parameters S
- Description of microwave devices by chain matrix

#### 2. Theory of transmission lines

#### 3. Smith Chart and impedance matching

- Introduction, uses and principles
- Movement along the line
- Different methods for impedance matching
- Matching by a stub
- Matching by double stubs

### Foundations of electromagnetic wave propagation

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## 2. Transmission line

## 22. Theory of lines - line ended by a short-circuit

Short-circuited line  $\underline{Z}_R = 0$

simplified calculations if the origin is considered at the load

as

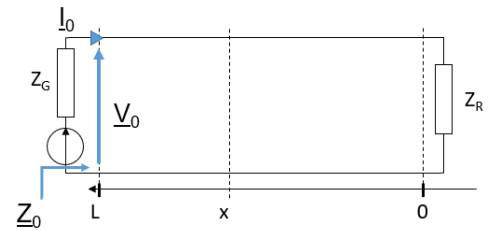
$$\underline{V}(x = L) = \underline{V}_R = 0 \quad \text{and} \quad \underline{Z}(x = L) = \underline{Z}_R = 0$$

then

$$\underline{V}(x) = \underline{Z}_C \underline{I}_R \operatorname{sh} \gamma x$$

$$\underline{I}(x) = \underline{I}_R \operatorname{ch} \gamma x$$

$$\underline{Z}(x) = \underline{Z}_C \operatorname{th} \gamma x$$



In the case of LWL:

$$\underline{V}(x) = j \underline{Z}_C \underline{I}_R \sin \beta x$$

$$\underline{I}(x) = \underline{I}_R \cos \beta x$$

$$\underline{Z}(x) = j \underline{Z}_C \operatorname{tg} \beta x$$

## 2. Transmission line

## 23. Theory of lines - line ended by a short-circuit

Short-circuited line  $\underline{Z}_R = 0$

In instantaneous values :

$$v(x, t) = Z_C I_R \sin \beta x \cdot \cos(\omega t + \varphi + \frac{\pi}{2})$$

$$i(x, t) = I_R \cos \beta x \cdot \cos(\omega t + \varphi)$$

$\underline{Z}_C$ : is considered real, which is almost always the case



- .....
- .....

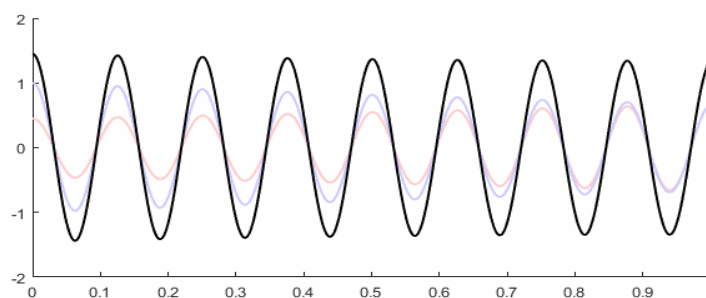
2. Transmission line

24. Theory of lines - line ended by a short-circuit

General case

Superposition of waves ( $V(x) = \underline{V}_i \cdot e^{-\gamma x} + \underline{V}_r \cdot e^{\gamma x}$ ) :

Semi-stationary wave



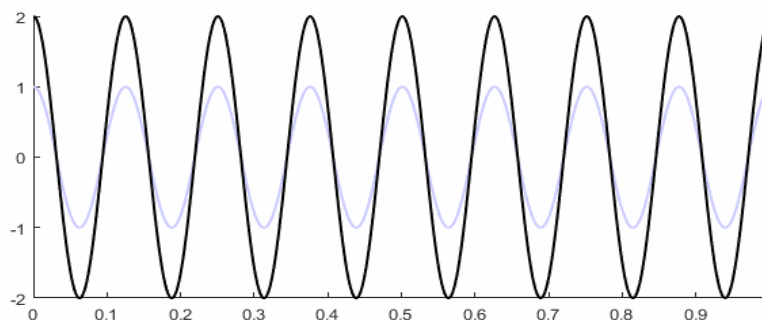
2. Transmission line

25. Theory of lines - line ended by a short-circuit

Case of the line without losses

Superposition of the waves ( $V(x) = \underline{V}_i \cdot e^{-j\beta x} + \underline{V}_r \cdot e^{j\beta x}$ ):

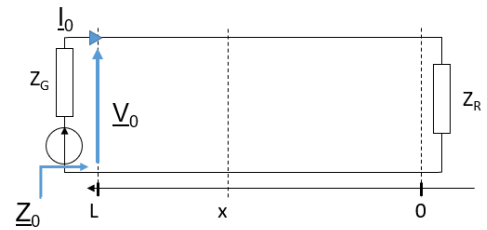
Stationary wave



2. Transmission line

26. Theory of lines - line ended by a short-circuit

Short-circuited line  $\underline{Z}_R=0$



Under these conditions the input impedance  $\underline{Z}_G$  becomes:

$$\underline{Z}_G = \underline{Z}(L) = j\underline{Z}_C \operatorname{tg} \beta L = j\underline{Z}_C \operatorname{tg} \frac{2\pi}{\lambda} L$$

$\underline{Z}_C$ : is considered real, which is almost always the case

2. Transmission line

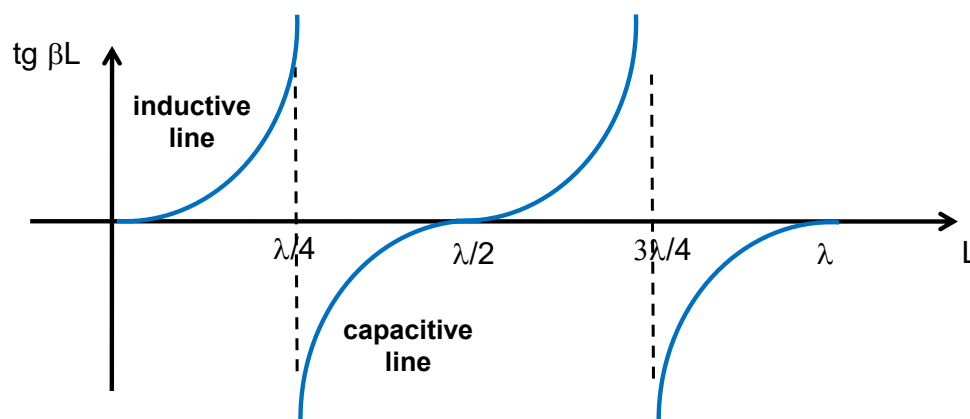
27. Theory of lines - line ended by a short-circuit

Short-circuited  $\underline{Z}_R=0$

Evolution of  $\underline{Z}_G$  as a function of  $\operatorname{tg} \beta L$  :

$$\underline{Z}_G = \underline{Z}(L) = j\underline{Z}_C \operatorname{tg} \beta L = j\underline{Z}_C \operatorname{tg} \frac{2\pi}{\lambda} L$$

Considering real  $\underline{Z}_C$ , which is almost always the case, we draw:



## 2. Transmission line

## 28. Theory of lines - line ended by a short-circuit

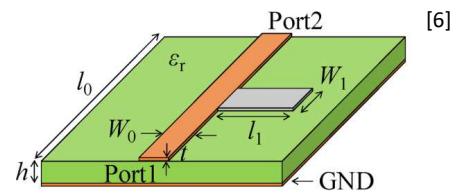
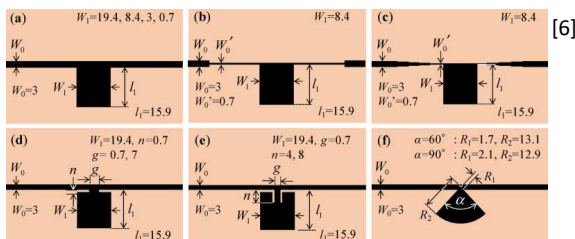
### Short-circuited $\underline{Z}_R=0$

Evolution of  $\underline{Z}_G$  as a function of  $\text{tg } \beta L$  :

.....



The stub is a direct application of this property. It is a short-circuited line of variable length used to adjust its input impedance (to bring a given impedance in a plane)



[6] Y. Kusama and R. Isozaki, "Compact and Broadband Microstrip Band-Stop Filters with Single Rectangular Stubs", Applied Sciences, vol. 9, n0 248, 2019, doi: 10.3390/app9020248

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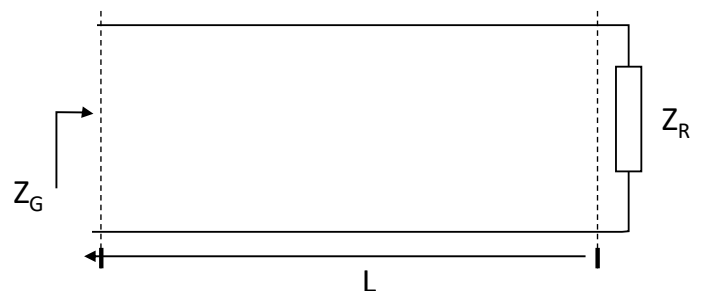
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## 2. Transmission line

## 29. Theory of lines - line ended by a short-circuit

### Short-circuited $\underline{Z}_R=0$

Other remarks:



➤ A quarter-wave line short-circuited at one end, brings back an open circuit at the other end (HF isolator)

.....



➤ A half-wave line short-circuited at one end, brings back a short-circuit at the other end

### Foundations of electromagnetic wave propagation

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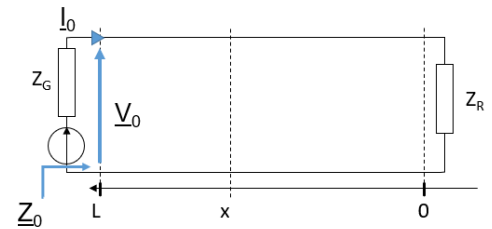
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## 2. Transmission line

## 30. Theory of lines - line ended by a open circuit

### Open circuit line (infinite $Z_R$ )

- simplified calculations if the origin of the axis is considered at the load  $I(x=0) = I_R = 0$  et  $Z(x=0) = Z_R = \infty$
- we write at th origin:



We then obtain:

In the case of LWL :

$$\underline{V}(x) = \underline{V}_R \operatorname{ch} \gamma x$$

$$\underline{I}(x) = \frac{\underline{V}_R}{\underline{Z}_C} \operatorname{sh} \gamma x$$

$$\underline{Z}(x) = \frac{\underline{V}(x)}{\underline{I}(x)} = \frac{\underline{Z}_C}{\operatorname{th} \gamma x}$$

$$\underline{V}(x) = \underline{V}_R \cos \beta x$$

$$\underline{I}(x) = j \frac{\underline{V}_R}{\underline{Z}_C} \sin \beta x$$

$$\underline{Z}(x) = \frac{\underline{V}(x)}{\underline{I}(x)} = -j \frac{\underline{Z}_C}{\operatorname{th} \beta x}$$

## 2. Transmission line

## 31. Theory of lines - line ended by a open circuit

### Open circuit line (infinite $Z_R$ )

Consider the voltage-current waves in space and time:

$$\begin{cases} \underline{v}(x, t) = V_R e^{j\varphi} e^{j\omega t} \cos \beta x \\ \underline{i}(x, t) = e^{j\frac{\pi}{2}} \frac{V_R}{\underline{Z}_C} e^{j\varphi} e^{j\omega t} \sin \beta x \end{cases}$$

Either in instantaneous values ( $\underline{Z}_C$ : est considered as real):

$$\begin{cases} v(x, t) = V_R \cos \beta x \cdot \cos(\omega t + \varphi) \\ i(x, t) = \frac{V_R}{Z_C} \sin \beta x \cdot \cos(\omega t + \varphi + \frac{\pi}{2}) \end{cases}$$



.....  
.....

2. Transmission line

32. Theory of lines – half and quarter wavelength

Quarter wave line. Half wave line

We have shown:

$$\underline{Z}_0 = \underline{Z}_C \frac{\underline{Z}_R + j\underline{Z}_C \operatorname{tg} \beta L}{\underline{Z}_C + j\underline{Z}_R \operatorname{th} \beta L} \quad \text{For LWL}$$

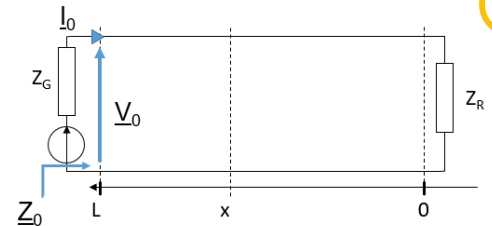
$$\text{if } \beta L = \frac{(2k+1)\pi}{2} \Rightarrow L = (2k+1) \frac{\lambda}{4} \Rightarrow \operatorname{tg} \beta L \rightarrow \infty$$

then

.....



.....



2. Transmission line

33. Theory of lines – half and quarter wavelength

Quarter wave line. Half wave line

We have shown:

$$\underline{Z}_0 = \underline{Z}_C \frac{\underline{Z}_R + j\underline{Z}_C \operatorname{tg} \beta L}{\underline{Z}_C + j\underline{Z}_R \operatorname{th} \beta L} \quad \text{For LWL}$$

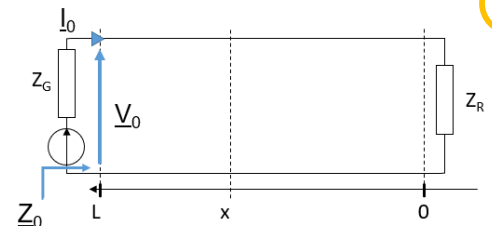
$$\text{if } \beta L = k\pi \Rightarrow L = \frac{k\lambda}{2} \Rightarrow \operatorname{tg} \beta L \rightarrow 0$$

then

$$\underline{Z}_0 = \underline{Z}_R$$



.....



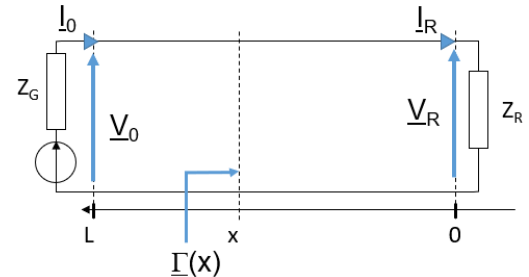
## 2. Transmission line

## 34. Theory of lines – reflection coefficient

### Reflection coefficient

the origin of the axis is considered at the charge

We define the reflection coefficient at a point as the ratio of the reflected wave to the incident wave:



given:

$$\text{with: } \underline{V}_r = \frac{1}{2} (\underline{V}_R - \underline{Z}_C \underline{I}_R)$$

$$\underline{V}_i = \frac{1}{2} (\underline{V}_R + \underline{Z}_C \underline{I}_R)$$

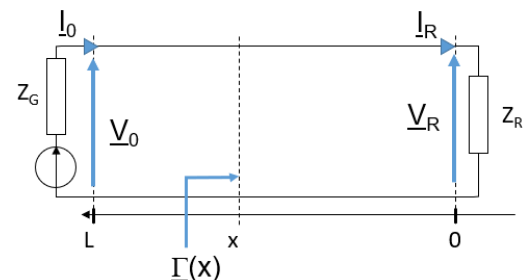
## 2. Transmission line

## 35. Theory of lines – reflection coefficient

### Reflection coefficient

the origin of the axis is considered at the charge

We define the reflection coefficient at a point as the ratio of the reflected wave to the incident wave:



$$\text{then: } \underline{\Gamma}(x) = \frac{(\underline{V}_R - \underline{Z}_C \underline{I}_R) e^{-2\gamma x}}{\underline{V}_R + \underline{Z}_C \underline{I}_R}$$

therefore:

$$\underline{\Gamma}(x) = \frac{(\underline{Z}_R - \underline{Z}_C) e^{-2\gamma x}}{\underline{Z}_R + \underline{Z}_C}$$



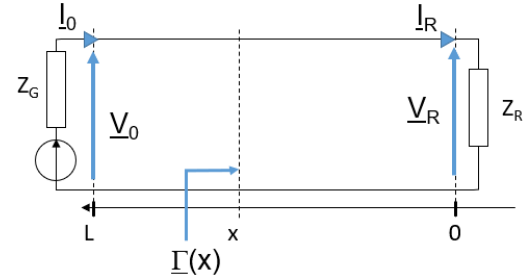
## 2. Transmission line

## 36. Theory of lines – reflection coefficient

### Reflection coefficient

At the origin, therefore at the level of the load, the reflection coefficient is equal to:

the origin of the axis is considered at the charge



Therefore:  $\underline{\Gamma}_R = \underline{\Gamma}_R e^{j\theta_R}$  ← Phase shift term introduced by the reflection

## 2. Transmission line

## 37. Theory of lines – reflection coefficient in particular case

### Reflection coefficient

the origin of the axis is considered at the charge

$$\underline{\Gamma}_R = \frac{\underline{Z}_R - \underline{Z}_C}{\underline{Z}_R + \underline{Z}_C}$$

Interesting cases:



2. Transmission line

38. Theory of lines - reflection coefficient

Line with arbitrary reflection coefficient

the origin of the axis is considered at the charge

given:  $\underline{V}(x) = \underline{V}_i e^{\gamma x} + \underline{V}_r e^{-\gamma x}$

$$\underline{V}(x) = \underline{V}_i e^{\gamma x} \left(1 + \frac{\underline{V}_r}{\underline{V}_i} e^{-2\gamma x}\right)$$

then:  $\underline{V}(x) = \underline{V}_i e^{\gamma x} (1 + \underline{\Gamma}_R e^{-2\gamma x})$

2. Transmission line

39. Theory of lines – reflection coefficient

Line with arbitrary reflection coefficient

the origin of the axis is considered at the charge

given:  $\underline{I}(x) = \underline{I}_i e^{\gamma x} + \underline{I}_r e^{-\gamma x}$

$$\underline{I}(x) = \underline{I}_i e^{\gamma x} \left(1 + \frac{\underline{I}_r}{\underline{I}_i} e^{-2\gamma x}\right)$$

with  $\frac{\underline{V}_i}{\underline{I}_i} = \underline{Z}_C = -\frac{\underline{V}_r}{\underline{I}_r}$

Then:  $\underline{I}(x) = \underline{I}_i e^{\gamma x} (1 - \underline{\Gamma}_R e^{-2\gamma x})$

2. Transmission line

40. Theory of lines – reflection coefficient

Line with arbitrary reflection coefficient

the origin of the axis is considered at the charge

$$\text{given: } \underline{Z}(x) = \frac{V(x)}{I(x)} = \frac{V_i e^{\gamma x} (1 + \Gamma_R e^{-2\gamma x})}{I_i e^{\gamma x} (1 - \Gamma_R e^{-2\gamma x})}$$

$$\text{then: } \underline{Z}(x) = \underline{Z}_C \frac{1 + \Gamma_R e^{-2\gamma x}}{1 - \Gamma_R e^{-2\gamma x}}$$

2. Transmission line

41. Theory of lines – reflection coefficient

Line with arbitrary reflection coefficient

the origin of the axis is considered at the charge

We consider the line without losses, we obtain then:

$$\left\{ \begin{array}{l} |V(x)| = |V_i e^{j\beta x}| (1 + \Gamma_R e^{j(\theta_R - 2\beta x)}) \\ |I(x)| = |I_i e^{j\beta x}| (1 - \Gamma_R e^{j(\theta_R - 2\beta x)}) \\ |Z(x)| = |Z_C| \frac{|1 + \Gamma_R e^{j(\theta_R - 2\beta x)}|}{|1 - \Gamma_R e^{j(\theta_R - 2\beta x)}|} \end{array} \right.$$

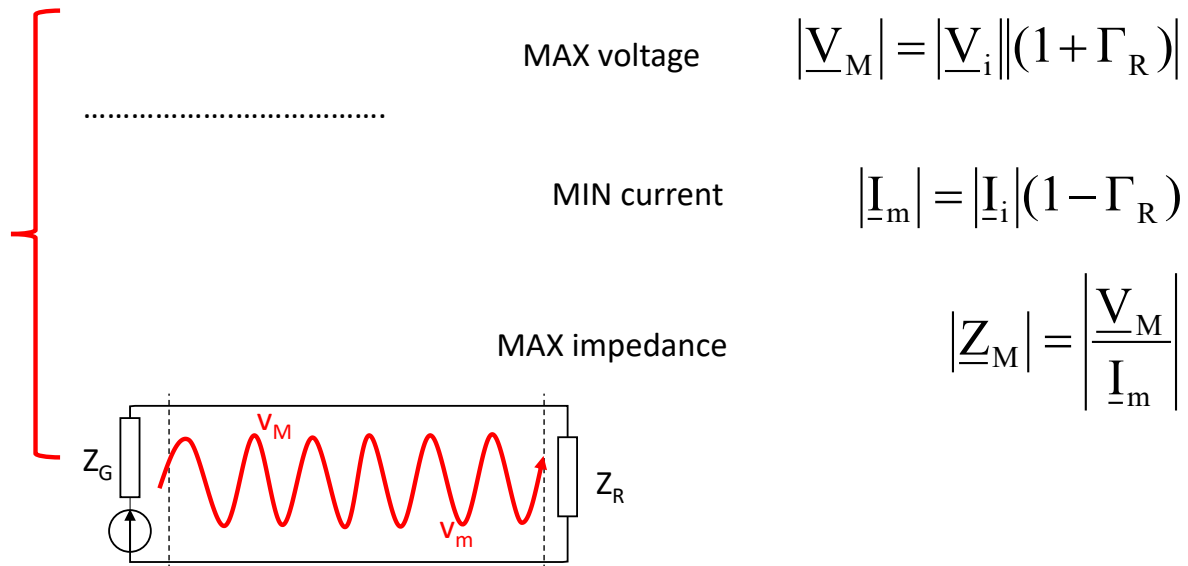
2. Transmission line

42. Theory of lines – min and max impedance along the line

Line with arbitrary reflection coefficient

the origin of the axis is considered at the charge

We are interested in the amplitudes:



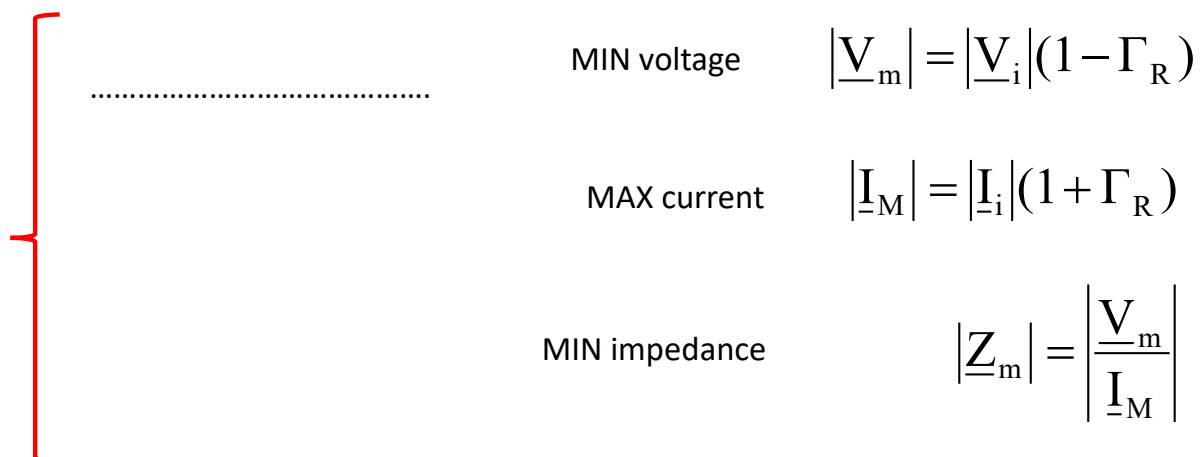
2. Transmission line

43. Theory of lines – min and max impedance along the line

Line with arbitrary reflection coefficient

the origin of the axis is considered at the charge

We are interested in the amplitudes:



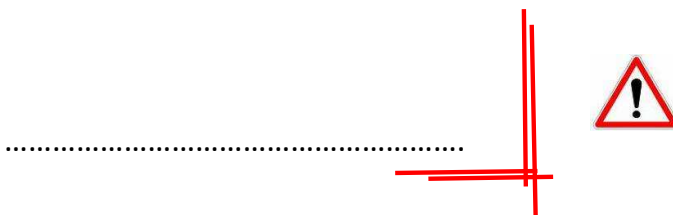


### Line with arbitrary reflection coefficient

Two consecutive maxima or minima of voltage or current are separated by:

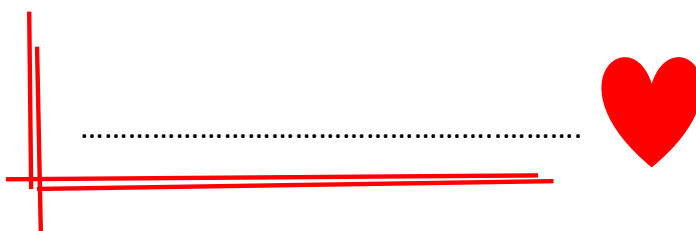
$$(\theta_R - 2\beta x_n) - (\theta_R - 2\beta x_{n+1}) = 2\beta(x_n - x_{n+1})$$

$$2n\pi - 2(n+1)\pi = -2\pi$$



### Line with arbitrary reflection coefficient

Voltage Standing Wave Ratio is defined as thge term VSWR or s:



and as  $0 \leq \Gamma_R \leq 1$   $1 \leq s \leq \infty$

$\Gamma$ dB	$ \Gamma $	s
0	1	$\infty$
-5	0,562	3,6
-10	0,316	1,9
-20	0,1	1,22
-26,4	0,048	1,1
-30	0,032	1,07
-32,3	0,024	1,05
-40	0,01	1,02
-80	0,0001	1,0002

2. Transmission line

46. Theory of lines - review

**LWL**

$$\alpha = 0$$

$$\beta = \omega \cdot \sqrt{L \cdot C}$$

$$v_{\varphi} = \frac{1}{\sqrt{L \cdot C}}$$

Neither  $\alpha$  nor  $v_{\varphi}$   
depend on  $f$   
→ **No distortion**

**Low losses**

$$\alpha = \frac{1}{2} \left( R \sqrt{\frac{C}{L}} + G \sqrt{\frac{L}{C}} \right)$$

$$\beta \cong \omega \cdot \sqrt{L \cdot C}$$

$$v_{\varphi} \cong \frac{1}{\sqrt{L \cdot C}}$$

Neither  $\alpha$  nor  $v_{\varphi}$   
depend on  $f$   
→ **No distortion**

**Losses of any kind**

Heaviside **GL=RC**

Heaviside

→ loss minimization

→  $\alpha$  as low as possible  
(but neither null nor very weak)

$$\alpha = \sqrt{R \cdot G}$$

$$\beta = \omega \cdot \sqrt{L \cdot C}$$

$$v_{\varphi} = \frac{1}{\sqrt{L \cdot C}}$$

Neither  $\alpha$  nor  $v_{\varphi}$   
depend on  $f$   
→ **No distortion**

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2. Transmission line

47. Theory of lines - review

**Losses of any kind**

**Low loss**

$$\alpha = \frac{1}{2} \left( R \sqrt{\frac{C}{L}} + G \sqrt{\frac{L}{C}} \right)$$

$$\beta \cong \omega \cdot \sqrt{L \cdot C}$$

$$v_{\varphi} \cong \frac{1}{\sqrt{L \cdot C}}$$

Neither  $\alpha$  nor  $v_{\varphi}$   
depend on  $f$   
→ **No distortion**

Heaviside **GL=RC**

Heaviside

→ loss minimization

→  $\alpha$  as low as possible  
(but neither null nor very weak)

$$\alpha = \sqrt{R \cdot G}$$

$$\beta = \omega \cdot \sqrt{L \cdot C}$$

$$v_{\varphi} = \frac{1}{\sqrt{L \cdot C}}$$

Neither  $\alpha$  nor  $v_{\varphi}$   
depend on  $f$   
→ **No distortion**

Heaviside

$\alpha$  and  $v_{\varphi}$

depend on  $f$  !!

→ **Distortion !!**

$\alpha = \alpha(f)$

Amplitude distortion

→ slope correction filter

$v_{\varphi} = v_{\varphi}(f)$

Phase distortion

→ tend towards

Heaviside conditions

(→ L++)

• pupinization

• krarupization

Foundations of electromagnetic wave propagation

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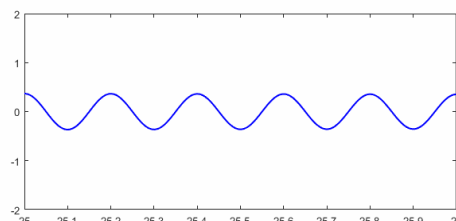
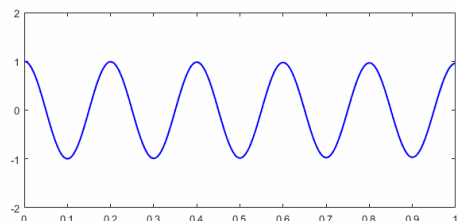
2. Transmission line

48. Theory of lines - review

Amplitude distortion (when  $\alpha$  DOES NOT depend on  $f$ )

input

f1

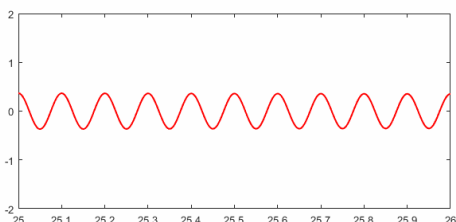
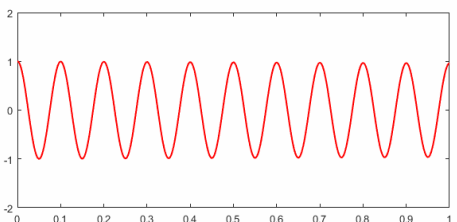


output

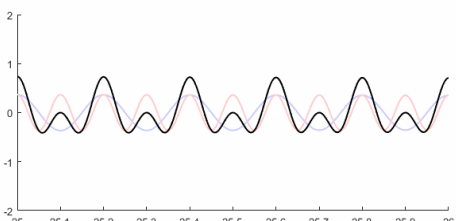
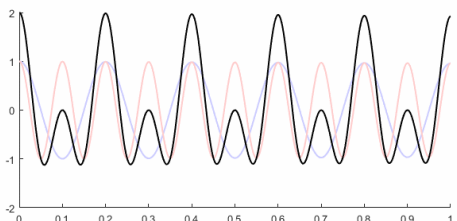
$\alpha = \text{const}$

$V\varphi = \text{const}$

f2



Superposition of signals



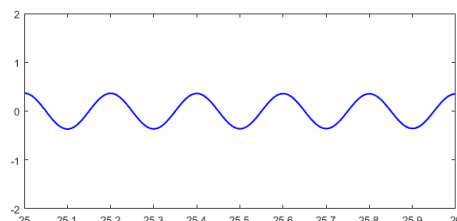
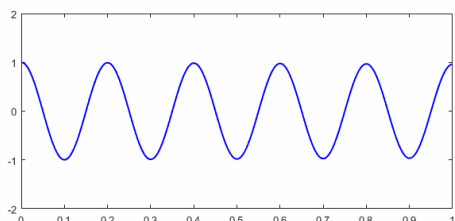
2. Transmission line

49. Theory of lines - review

Amplitude distortion (when  $\alpha$  depend on  $f$ )

input

f1



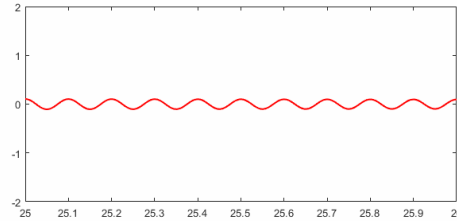
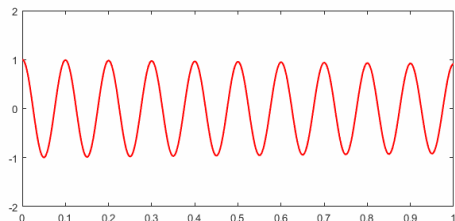
output

$\alpha = \text{const}$

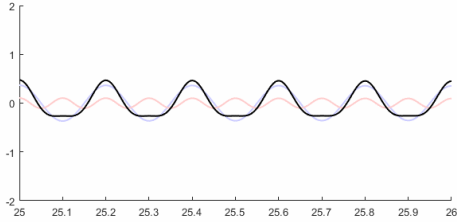
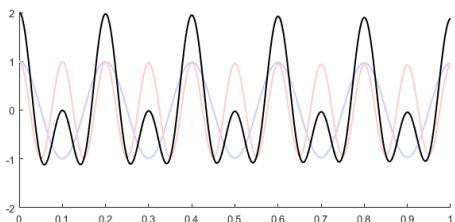
$\alpha_2 = 3 \cdot \alpha_1$

$V\varphi = \text{const}$

f2



Superposition of signals



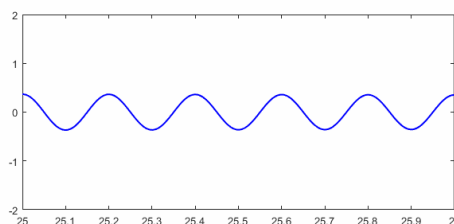
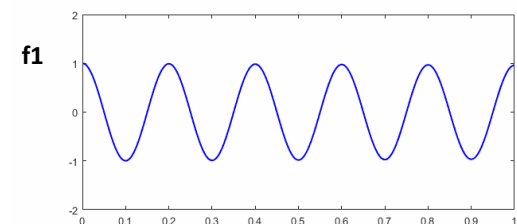
## 2. Transmission line

## 50. Theory of lines - review

Phase distortion (when  $v_\phi$  **DOES NOT** depend on  $f$ )

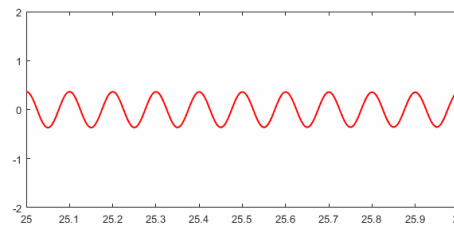
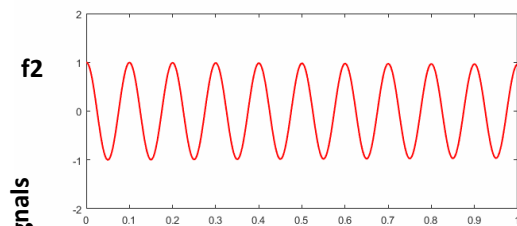
input

output

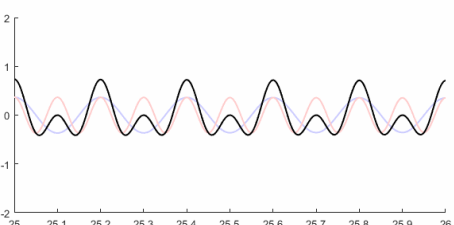
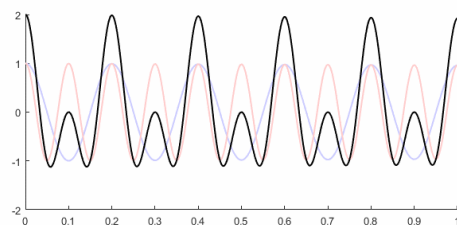


$$\alpha = \text{const}$$

$$V_\phi = \text{const}$$



Superposition of signals



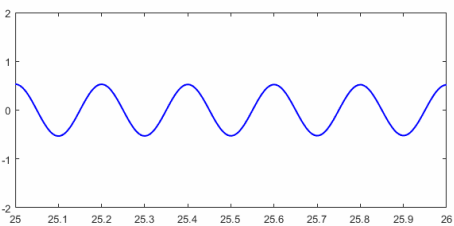
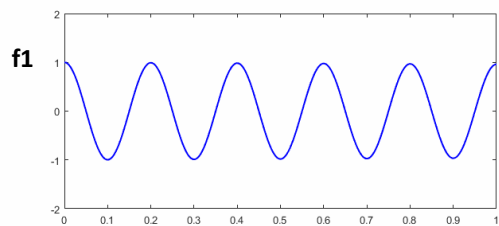
## 2. Transmission line

## 51. Theory of lines - review

Phase distortion (when  $v_\phi$  depend on  $f$ )

input

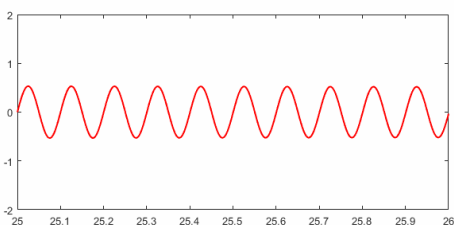
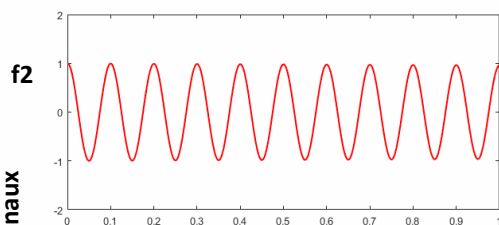
output



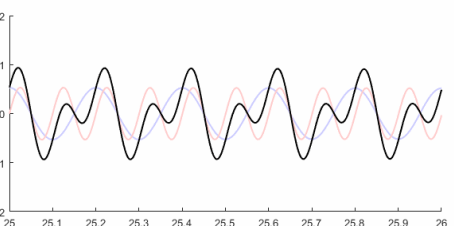
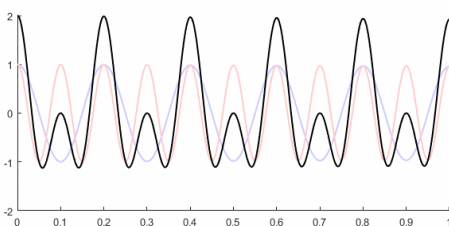
$$\alpha = \text{const}$$

$$V_\phi = \text{const}$$

$$V_{\phi 1} = 1.001 \cdot V_{\phi 2}$$



Superposition des signaux

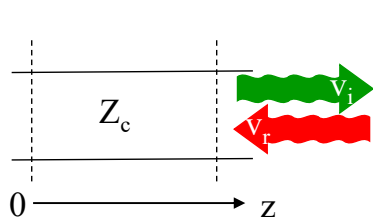




## 2. Transmission line

### 1. Reminder : theory of transmission lines

For a line with a characteristic impedance  $Z_c$ , excited by a sinusoidal wave of pulsation  $\omega$ , the solutions of telegraphers equations take the form:



$$\begin{aligned} \underline{V}(z,t) &= \underline{V}_i e^{-\alpha z} \cdot e^{-j\beta z} \cdot e^{j\omega t} + \underline{V}_r e^{\alpha z} \cdot e^{j\beta z} \cdot e^{j\omega t} \\ \underline{I}(z,t) &= \frac{\underline{V}_i}{Z_c} e^{-\alpha z} \cdot e^{-j\beta z} \cdot e^{j\omega t} - \frac{\underline{V}_r}{Z_c} e^{\alpha z} \cdot e^{j\beta z} \cdot e^{j\omega t} \end{aligned}$$

The wave is the sum of :  
 - an incident wave of complex amplitude  $\underline{V}_i$   
 - a reflected wave of complex amplitude  $\underline{V}_r$

### $\gamma$ wave propagation constant

$$\gamma = \alpha + j\beta$$

$\alpha$  : attenuation constant per unit length  
 $\beta$  : phase constant per unit length

In the case of Loss-Less transmission Line (LLL),  $\alpha = 0$ .

$\alpha$  in Np/m or dB/m with 1 dB = 0.1151 Np (Nepers)

$\beta$  in rad/m

## 2. Transmission line

### 1. Reminder : theory of transmission lines

Incident and reflected waves have a double periodicity

- temporal  $\omega = \frac{2\pi}{T}$   
 - spatial  $\beta = \frac{2\pi}{\lambda}$

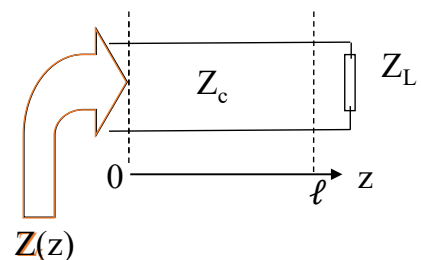
### Characteristic impedance $Z_c$ :

In the case of a lossless line (LLL),  $Z_c$  is real

### Impédance at a point on the line :

$$Z(z) = \frac{V(z)}{I(z)} = Z_c \frac{\underline{V}_i e^{-\alpha z} \cdot e^{-j\beta z} + \underline{V}_r e^{\alpha z} \cdot e^{j\beta z}}{\underline{V}_i e^{-\alpha z} \cdot e^{-j\beta z} - \underline{V}_r e^{\alpha z} \cdot e^{j\beta z}}$$

Input impedance of a line of length  $\ell$  loaded by  $Z_L$



$$Z_i = Z_c \frac{Z_L + Z_c \tanh \gamma \ell}{Z_c + Z_L \tanh \gamma \ell}$$

for LLL :  
 $\alpha = 0$

$$Z_i = Z_c \frac{Z_L + j Z_c \tan \beta \ell}{Z_c + j Z_L \tan \beta \ell}$$

## 2. Transmission line

## 1. Reminder : theory of transmission lines

### Reflection coefficient of a LLL

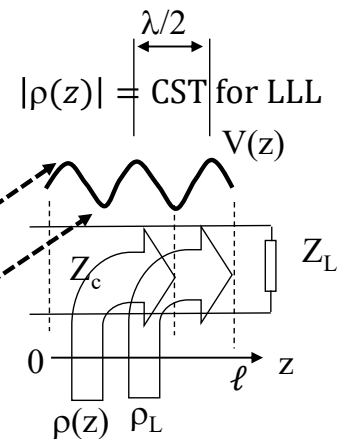
$$\rho(z) = \frac{\text{onde réfléchi}}{\text{onde incidente}} = \frac{V_r \cdot e^{j\beta z}}{V_i \cdot e^{-j\beta z}} = -\frac{I_r e^{j\beta z}}{I_i e^{-j\beta z}}$$

### Load reflection coefficient :

$$\rho_L = \rho(z = \ell) = \frac{Z_L - Z_c}{Z_L + Z_c}$$

### Voltage Standing Wave Ratio :

$$\text{VSWR} = s = \frac{V_{\max}}{V_{\min}} = \frac{I_{\max}}{I_{\min}} = \frac{1 + |\rho_L|}{1 - |\rho_L|}$$



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