

Chapter 4 Oversimplified



Please use this only as a reference and as up to your own interpretation.

Space



The **space** R^n consists of all column vectors v with n components.

Just imagine a box (three components) any point inside that box is some kind of vector.

Vector space is a set of vectors together with rules for vector addition and scalar multiplication.

e.g.

$v = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ is in R^3 as it has 3 components

Subspace



A **subspace** is a set of vectors that (including the zero vector) that satisfies:

- $v + w$ is in the subspace (given that v and w are in the subspace)
- cv is in the subspace (any scalar multiplication of v)
- which also means $cv + dw$ is in the subspace (all linear combinations of v and w)

It is important to remember that a subspace **must contain the zero vector (the origin)**, otherwise it is not a subspace.

Subspace of V containing vectors \vec{v} and \vec{w} must contain all their linear combinations.

- $C(A)$ is a subspace of R^n and null space $N(A)$ is subspace of R^n .
- Subspace of V spanned by a set of vectors:
 - let SS be the set containing all combinations of vectors in S , then SS is a subspace of V spanned by S , which is the smallest subspace of V containing S .
 - The smallest subspace is the all combinations of vectors in a set

Column Space



Column space (of a matrix) is all the possible linear combinations of the columns (of the matrix).

The system

$Ax = b$ is solvable only if b is in the column space of A

How to find the Column Space

- To find the column space, you must row reduce (elimination) the matrix. (In order to acquire the pivots, all components under the pivots must be zero).

$$e.g. A = \begin{bmatrix} 2 & 4 & 6 & 4 \\ 2 & 5 & 7 & 6 \\ 2 & 3 & 5 & 2 \end{bmatrix}$$

$$(\text{row } 2 - \text{row } 1) \ \& \ (\text{row } 3 - \text{row } 1) \rightarrow \begin{bmatrix} 2 & 4 & 6 & 4 \\ 0 & 1 & 1 & 2 \\ 0 & -1 & -1 & -2 \end{bmatrix}$$

$$(\text{row } 3 + \text{row } 2) \rightarrow U = \begin{bmatrix} 2 & 4 & 6 & 4 \\ 0 & 1 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

- From here you can see that there is only **two pivots (col 1 and col 2)**, meaning that out of the 4 columns, only two of them make up a space.
- The rest can be expressed in terms of the first two (meaning that they are dependent and free columns).
- Hence, the column space of the matrix is the span (all scalar multiple) of the first two columns:

$$C(A) = \text{span} \left\{ \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix}, \begin{bmatrix} 4 \\ 5 \\ 3 \end{bmatrix} \right\}$$

- Check:

$$\begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix} + \begin{bmatrix} 4 \\ 5 \\ 3 \end{bmatrix} = \begin{bmatrix} 6 \\ 7 \\ 5 \end{bmatrix} \text{ (col 3)}$$

$$(-2) \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix} + (2) \begin{bmatrix} 4 \\ 5 \\ 3 \end{bmatrix} = \begin{bmatrix} 6 \\ 7 \\ 5 \end{bmatrix} \text{ (col 4)}$$

Null space



A null space is a space that contains all solutions x that produces $Ax = 0$.

Basically, space of vectors (in

\mathbb{R}^n) that multiplies the matrix and produces 0.

How to find the Null space

$$Ax = 0$$

- The null space is simply the (all the possible) solutions to the x 's that produce the zero vector.

$$e.g. \quad A = \begin{bmatrix} 1 & 2 & 2 & 4 & 6 \\ 1 & 2 & 3 & 6 & 9 \\ 0 & 0 & 1 & 2 & 3 \end{bmatrix}$$

- Similar to finding the column space, we must first turn the matrix into an echelon form.

$$\begin{bmatrix} 1 & 2 & 2 & 4 & 6 \\ 1 & 2 & 3 & 6 & 9 \\ 0 & 0 & 1 & 2 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 2 & 4 & 6 \\ 1 & 2 & 3 & 6 & 9 \\ 0 & 0 & 1 & 2 & 3 \end{bmatrix}$$

$$(\text{row 2} - \text{row 1}) \rightarrow \begin{bmatrix} 1 & 2 & 2 & 4 & 6 \\ 0 & 0 & 1 & 2 & 3 \\ 0 & 0 & 1 & 2 & 3 \end{bmatrix}$$

$$(\text{row 3} - \text{row 2}) \rightarrow U = \begin{bmatrix} 1 & 2 & 2 & 4 & 6 \\ 0 & 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

- Here, you can see that there is only two pivots (col 1 and col 3, or the variables x_1 and x_3). The rest of the variables (x_2, x_4, x_5) are **free variables**.
- With $r = 2$ (number of pivots) there are $n - r = 3$ free variables (n : number of columns), or in other words, the basis for the null space is 3.
- Each free variable leads to a special solution to $A\vec{x} = \vec{0}$, $R\vec{x} = \vec{0}$.
- When finding the null space, you must find the **Row Reduced Echelon Form** (RREF) of the matrix (condition that all pivots are 1's with zeros above and below).

$$U = \begin{bmatrix} 1 & 2 & 2 & 4 & 6 \\ 0 & 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$(\text{row 1} - (2) \text{ row 2}) \rightarrow R = \begin{bmatrix} 1 & 2 & 0 & 0 & 0 \\ 0 & 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 0 & 0 & 0 \\ 0 & 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

- Now, you need to express the pivot variables in terms of the free variables, similar to $Ax = b \rightarrow x = A^{-1}b$

$$\begin{aligned}x_1 + 2x_2 &= 0 \\x_3 + 2x_4 + 3x_5 &= 0\end{aligned}$$

$$\begin{aligned}x_1 &= -2x_2 \\ \rightarrow x_3 &= -2x_4 - 3x_5\end{aligned}$$

- The free variables can be expressed in terms of themselves since they are dependent on the pivot variables, and do not have their own solutions.

$$\begin{aligned}x_1 &= -2x_2 \\ x_2 &= x_2 \\ x_3 &= -2x_4 - 3x_5 \\ x_4 &= x_4 \\ x_5 &= x_5\end{aligned} \rightarrow \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 0 \\ 0 \\ -2 \\ 1 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} 0 \\ 0 \\ -3 \\ 0 \\ 1 \end{bmatrix}$$

- The null space is the columns made up by the free variables, or in other words, the special solutions:

$$N(A) = \text{span} \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ -3 \\ 0 \\ 1 \end{bmatrix} \right\}$$

- Any one of these columns (or vectors) multiply matrix A to produce the zero vector. (You can check).
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Complete Solution

$$x = x_p + x_n$$

- where x_p is particular solution for $Ax_p = b$ and x_n is special solution (null space) for $Ax_n = 0$.
- You can reason that when a matrix does not have a full set of pivots, in other words, there are free variables **dependent** on the pivot variables, the free variables do not contribute to the final answer (b). So they are assumed to produce 0.
- Finding the Complete Solution is similar to finding the null space. Only you need to substitute the zero vector with the final answer.
- In fact, the complete solution to $A\vec{x} = \vec{b}$ is $\vec{x} = \text{particular solution} + \text{all null space solutions}$.

$$Ax = b$$

$$\begin{bmatrix} 2 & 4 & 6 & 4 \\ 2 & 5 & 7 & 6 \\ 2 & 3 & 5 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 4 \\ 3 \\ 5 \end{bmatrix}$$

- You should augment A and b for easier elimination to the Row Reduced Echelon Form.

$$\begin{bmatrix} 2 & 4 & 6 & 4 & 4 \\ 2 & 5 & 7 & 6 & 3 \\ 2 & 3 & 5 & 2 & 5 \end{bmatrix}$$

$$(\text{row } 2 - \text{row } 1) \ \& \ (\text{row } 3 - \text{row } 1) \rightarrow \begin{bmatrix} 2 & 4 & 6 & 4 & 4 \\ 0 & 1 & 1 & 2 & -1 \\ 0 & -1 & -1 & -2 & 1 \end{bmatrix}$$

$$(\text{row } 3 + \text{row } 2) \rightarrow U = \begin{bmatrix} 2 & 4 & 6 & 4 & 4 \\ 0 & 1 & 1 & 2 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\left(\frac{1}{2} \text{ row } 1\right) \rightarrow \begin{bmatrix} 1 & 2 & 3 & 2 & 2 \\ 0 & 1 & 1 & 2 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$(\text{row } 1 - (2) \text{ row } 2) \rightarrow R = \begin{bmatrix} 1 & 0 & 1 & -2 & 4 \\ 0 & 1 & 1 & 2 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

- Here x_1 and x_2 are pivot variables, while the rest are free variables.
- Now similar to finding the null space, express the pivot variables in terms of the free variables and the real numbers (components of b).

$$\begin{array}{rcl} x_1 + x_3 - 2x_4 = 4 & & x_1 = 4 - x_3 + 2x_4 \\ x_2 + x_3 + 2x_4 = -1 & \rightarrow & x_2 = -1 - x_3 - 2x_4 \end{array}$$

$$\begin{array}{l} x_1 = 4 - x_3 + 2x_4 \\ x_2 = -1 - x_3 - 2x_4 \\ x_3 = x_3 \\ x_4 = x_4 \end{array} \rightarrow x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 4 \\ -1 \\ 0 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ -1 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 2 \\ -2 \\ 0 \\ 1 \end{bmatrix}$$

and this is the complete solution for x where $\begin{bmatrix} 4 \\ -1 \\ 0 \\ 0 \end{bmatrix}$ is the x_p , and $x_3 \begin{bmatrix} -1 \\ -1 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 2 \\ -2 \\ 0 \\ 1 \end{bmatrix}$ is the x_n

Independence



The columns of a matrix are **linearly independent** when only $x = 0$ produces $Ax = 0$.

Rank of A = number of pivots = number of nonzero rows in \mathbb{R} .

Or the matrix has a Full Rank, or in other words, a full set of pivots and **no free variables**.

That is, simply, when all the columns of a matrix are independent of one another. Every column is included in the Column Space.

Basis



A basis for V is sequence of vectors which are independent and span V .

$$e.g. N(A) = \text{span} \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ -3 \\ 0 \\ 1 \end{bmatrix} \right\}$$

$$\text{basis} = \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ -3 \\ 0 \\ 1 \end{bmatrix}$$

- this null space has the following basis (the fundamental or the rudimentary vectors of a space, or in other words, just the vectors in a given space).
- the word "span" just refers to the all possible scalar multiples of the basis vectors.

Dimension



The dimension of a space is the number of vectors in every basis.

$$e.g. C(A) = \text{span} \left\{ \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix}, \begin{bmatrix} 4 \\ 5 \\ 3 \end{bmatrix} \right\}$$

- this column space has a dimension of 2 (number of vectors) in a \mathbb{R}^3 (number of components) space.

- **The dimension of $C(A)$ equals the rank of A , with the r pivot columns being a basis.**
- **The dimension of $N(A)$ is $n - r$ with the $n - r$ special solutions to $A\vec{x} = \vec{0}$ for a basis.**