Chapter 4 Oversimplified



Please use this only as a reference.

Everything is up to your own interpretation, and they are all based from the book and the homework assignments.

Space



The **space** \mathbb{R}^n consists of all column vectors v with n components.

Just imagine a box (three components) any point inside that box is some kind of vector.

e.g.

$$v = egin{bmatrix} 1 \ 2 \ 3 \end{bmatrix}$$
 is in R^3 as it has 3 components

Subspace

Chapter 4 Oversimplified 1



A **subspace** is a set of vectors that (including the zero vector) that satisfies:

- v+w is in the subspace (given that v and w are in the subspace)
- cv is in the subspace (any scalar multiplication of v)
- which also means cv + dw is in the subspace (all linear combinations of v and w)

It is important to remember that a subspace **must contain the zero vector (the origin)**, otherwise it is not a subspace.

Column Space



Column space (of a matrix) is all the possible linear combinations of the columns (of the matrix).

The system

Ax=b is solvable only if b is in the column space of A

How to find the Column Space

• To find the column space, you must row reduce (elimination) the matrix. (In order to acquire the pivots, all components under the pivots must be zero).

$$e.g. \ A = egin{bmatrix} 2 & 4 & 6 & 4 \ 2 & 5 & 7 & 6 \ 2 & 3 & 5 & 2 \end{bmatrix}
ightarrow egin{bmatrix} 2 & 4 & 6 & 4 \ 0 & 1 & 1 & 2 \ 0 & -1 & -1 & -2 \end{bmatrix}$$

$$ightarrow U = egin{bmatrix} 2 & 4 & 6 & 4 \ 0 & 1 & 1 & 2 \ 0 & 0 & 0 & 0 \end{bmatrix}$$

- from here you can see that there is only **two pivots (col 1 and col 2)**, meaning that out of the 4 columns, only two of them make up a space.
- The rest of the two can be expressed in terms of the first two.
- Hence, the column space of the matrix is the span of the first two columns:

$$\operatorname{Col}(A) = \operatorname{span} \left\{ egin{bmatrix} 2 \ 2 \ 2 \end{bmatrix}, egin{bmatrix} 4 \ 5 \ 3 \end{bmatrix}
ight\}$$

· Check:

$$egin{bmatrix} 2 \ 2 \ 2 \ \end{bmatrix} + egin{bmatrix} 4 \ 5 \ 3 \ \end{bmatrix} = egin{bmatrix} 6 \ 7 \ 5 \ \end{bmatrix} \ (\operatorname{col}\ 3)$$

$$(-2)egin{bmatrix}2\\2\\2\end{bmatrix}+(2)egin{bmatrix}4\\5\\3\end{bmatrix}=egin{bmatrix}6\\7\\5\end{bmatrix}(\operatorname{col}4)$$

Nullspace



A nullspace is a space that contains all solutions x that produces Ax=0.

Basically, space of vectors (in \mathbb{R}^n) that multiplies the matrix and produces 0.

How to find the Nullspace

• The nullspace is simply the (possible) solutions to the x's that produce the zero vector.

$$Ax = 0$$

Chapter 4 Oversimplified 3

$$egin{bmatrix} 1 & 2 & 2 & 4 & 6 \ 1 & 2 & 3 & 6 & 9 \ 0 & 0 & 1 & 2 & 3 \end{bmatrix} egin{bmatrix} x_1 \ x_2 \ x_3 \ x_4 \ x_5 \end{bmatrix} = egin{bmatrix} 0 \ 0 \ 0 \end{bmatrix}$$

• Similar to finding the column space, we must first turn the matrix into an echelon form.

$$\begin{bmatrix} 1 & 2 & 2 & 4 & 6 \\ 1 & 2 & 3 & 6 & 9 \\ 0 & 0 & 1 & 2 & 3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 2 & 4 & 6 \\ 0 & 0 & 1 & 2 & 3 \\ 0 & 0 & 1 & 2 & 3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 2 & 4 & 6 \\ 0 & 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

- Here, you can see that there is only two pivots (col 1 and col 3, or the variables x_1 and x_3). The rest of the variables (x_2, x_4, x_5) are **free variables**.
- When finding the nullspace, it is better to find the Row Reduced Echelon Form of the matrix (condition that all pivots are 1's with zeros above and below)

$$U = egin{bmatrix} 1 & 2 & 2 & 4 & 6 \ 0 & 0 & 1 & 2 & 3 \ 0 & 0 & 0 & 0 & 0 \end{bmatrix}
ightarrow R = egin{bmatrix} 1 & 2 & 0 & 0 & 0 \ 0 & 0 & 1 & 2 & 3 \ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$egin{bmatrix} 1 & 2 & 0 & 0 & 0 \ 0 & 0 & 1 & 2 & 3 \ 0 & 0 & 0 & 0 & 0 \end{bmatrix} egin{bmatrix} x_1 \ x_2 \ x_3 \ x_4 \ x_5 \end{bmatrix} = egin{bmatrix} 0 \ 0 \ 0 \end{bmatrix}$$

• Now, you need to express the pivot variables in terms of the free variables, similar to $Ax=b
ightarrow x=A^{-1}b$

$$egin{aligned} x_1 + 2x_2 &= 0 \ x_3 + 2x_4 + 3x_5 &= 0 \end{aligned}$$

$$x_1=-2x_2 \
ightarrow x_3=-2x_4-3x_5$$

 The free variables can be expressed in terms of themselves since they are dependent on the pivot variables, and do not have their own solutions.

$$egin{array}{lll} x_1 &= -2x_2 \ x_2 &= x_2 \ x_3 &= -2x_4 - 3x_5 &
ightarrow & egin{bmatrix} x_1 \ x_2 \ x_3 \ x_4 &= x_4 \ x_5 &= x_5 \end{array} &
ightarrow & egin{bmatrix} x_1 \ x_2 \ x_3 \ x_4 \ x_5 \ \end{bmatrix} = x_2 egin{bmatrix} -2 \ 1 \ 0 \ 0 \ -2 \ 1 \ 0 \ \end{bmatrix} + x_4 egin{bmatrix} 0 \ 0 \ -2 \ 1 \ 0 \ \end{bmatrix} + x_5 egin{bmatrix} 0 \ 0 \ -3 \ 0 \ 1 \ \end{bmatrix}$$

• The nullspace is the columns of the free variables:

$$\operatorname{Null}(A) = \operatorname{span} \left\{ egin{bmatrix} -2 \ 1 \ 0 \ 0 \ \end{bmatrix}, egin{bmatrix} 0 \ 0 \ -2 \ 1 \ 0 \end{bmatrix}, egin{bmatrix} 0 \ 0 \ -3 \ 0 \ 1 \end{bmatrix}
ight\}$$

ullet Any one of these columns (or vectors) multiply matrix A to produce the zero vector. (You can check).

Complete Solution

$$x = x_p + x_n$$

- ullet where x_p is particular solution for $Ax_p=b$ and x_n is special solution (nullspace) for $Ax_n=0.$
- You can reason that when a matrix does not have a full set of pivots, in other
 words, there are free variables dependent on the pivot variables, the free
 variables do not contribute to the final answer (b). So they are assumed to
 produce 0.
- Finding the Complete Solution is similar to finding the nullspace. Only you need to substitute the zero vector with the final answer.

$$Ax = b$$

$$egin{bmatrix} 2 & 4 & 6 & 4 \ 2 & 5 & 7 & 6 \ 2 & 3 & 5 & 2 \end{bmatrix} egin{bmatrix} x_1 \ x_2 \ x_3 \ x_4 \end{bmatrix} = egin{bmatrix} 4 \ 3 \ 5 \end{bmatrix}$$

ullet You should augment A and b for easier elimination to the Row Reduced Echelon Form.

$$\begin{bmatrix} 2 & 4 & 6 & 4 & 4 \\ 2 & 5 & 7 & 6 & 3 \\ 2 & 3 & 5 & 2 & 5 \end{bmatrix} \rightarrow \begin{bmatrix} 2 & 4 & 6 & 4 & 4 \\ 0 & 1 & 1 & 2 & -1 \\ 0 & -1 & -1 & -2 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 2 & 4 & 6 & 4 & 4 \\ 0 & 1 & 1 & 2 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$
$$\rightarrow \begin{bmatrix} 1 & 2 & 3 & 2 & 2 \\ 0 & 1 & 1 & 2 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1 & -2 & 4 \\ 0 & 1 & 1 & 2 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

- Here x_1 and x_2 are pivot variables, while the rest are free variables.
- Now similar to finding the nullspace, express the pivot variables in terms of the free variables and the real numbers (components of b)

$$x_1 + x_3 - 2x_4 = 4$$

 $x_2 + x_3 + 2x_4 = -1$

and this is the complete solution for x where $\begin{bmatrix} 4 \\ -1 \\ 0 \\ 0 \end{bmatrix}$ is the x_p , and $x_3 \begin{bmatrix} -1 \\ -1 \\ 1 \\ 0 \end{bmatrix} +$

$$x_4 egin{bmatrix} 2 \ -2 \ 0 \ 1 \end{bmatrix}$$
 is the x_n

Independence



The columns of a matrix are **linearly independent** when only x=0 produces Ax=0.

Or the matrix has a Full Rank, or in other words, a full set of pivots and **no free variables**.

That is, simply, when all the columns of a matrix are independent of one another. Every column is included in the Column Space.

Chapter 4 Oversimplified 7