Chapter 5.1 Oversimplified



Please use this only as a reference and up to your own interpretation.

Eigenvectors



Eigenvectors are vectors that do not change direction (same direction means a multiple of a scalar) when multiplied by a matrix, say A.

$$e.g. \ A = egin{bmatrix} -2 & 2 \ 0 & 2 \end{bmatrix}, \quad v = egin{bmatrix} 3 \ 1 \end{bmatrix}, \quad w = egin{bmatrix} 1 \ 2 \end{bmatrix}$$

$$Av = egin{bmatrix} 1 \ 2 \end{bmatrix} \qquad Aw = egin{bmatrix} 2 \ 4 \end{bmatrix}$$

• Here Aw is a scalar multiple of w (a multiple of 2 to be exact), hence the vector w is an **eigenvector** of matrix A.

Eigenvalues



From the equation $Ax = \lambda x$ the eigenvalues are the possible values of the λ .

In the example above, one of the λ is equal to 2.

Basically, eigenvalues are the magnitude for scalar multiples of the eigenvectors.

How to Find the Eigenvalues

- There is a condition that the number λ is an eigenvalue if and only if $A-\lambda I$ is singular.
- In other words, $\det(A-\lambda I)=0$ (must be).
- So use the equation:

$$\det(A - \lambda I) = 0$$

$$e.g. \ \ A = egin{bmatrix} -1 & 3 \ 2 & 0 \end{bmatrix}$$

• First find the matrix $A - \lambda I$:

$$A-\lambda I = egin{bmatrix} -1 & 3 \ 2 & 0 \end{bmatrix} - egin{bmatrix} \lambda & 0 \ 0 & \lambda \end{bmatrix} = egin{bmatrix} -1-\lambda & 3 \ 2 & -\lambda \end{bmatrix}$$

• Next find the determinant of $A - \lambda I$:

$$\detegin{pmatrix} a & b \ c & d \end{pmatrix} o \det = ad - bc$$
 $\detegin{pmatrix} -1 - \lambda & 3 \ 2 & -\lambda \end{pmatrix} o (-1 - \lambda)(-\lambda) - (3)(2)$ $(\lambda + \lambda^2) - (6) = \lambda^2 + \lambda - 6$

• Now there is a quadratic equation to be solved:

$$\lambda^2 + \lambda - 6 = (\lambda + 3)(\lambda - 2)$$
 $\lambda = -3, \quad \lambda = 2$

• The solutions to the λ are the **eigenvalues**.

How to find the Eigenvectors

- To find the Eigenvectors using the Eigenvalues we use the formula $(A-\lambda I)x=0.$
- Using the previous example Eigenvalues:

$$\lambda_1=-3 \ ext{ and } \ \lambda_2=2$$
 $A=egin{bmatrix} -1 & 3 \ 2 & 0 \end{bmatrix}, \ \ \lambda_1 I=egin{bmatrix} -3 & 0 \ 0 & -3 \end{bmatrix}$ $A-\lambda_1 I=egin{bmatrix} 2 & 3 \ 2 & 3 \end{bmatrix}$

ullet We equal the matrix to 0 and solve, just like finding the null space. In fact, the eigenvectors are in null space:

$$A-\lambda_1 I = egin{bmatrix} 2 & 3 \ 2 & 3 \end{bmatrix} egin{bmatrix} x_1 \ x_2 \end{bmatrix} = egin{bmatrix} 0 \ 0 \end{bmatrix}$$

- ullet From here you can obviously just eyeball and say that $x_1=3$ and $x_2=-2$, which is true and correct.
- However, if you want a more robust approach then finding the Null space is better:

$$(\operatorname{row} 2 - \operatorname{row} 1)
ightarrow egin{bmatrix} 2 & 3 \ 0 & 0 \end{bmatrix} \
ightarrow & 2x_1 + 3x_2 = 0 & x_1 = -rac{3}{2} \ x_2 = x_2 & x_2 = x_2 \end{pmatrix} \
ightarrow & x_2 = x_2 \
ightarrow & x_2 = x_2 \end{pmatrix} \
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ightarrow & X = X_2 =$$

• Which means any **scalar multiple** of the null space basis $igg[-rac{3}{2}\higg]$ is an eigenvector when $\lambda=-3$.

$$\bullet \ \ \mathsf{For} \ \lambda = 2 \mathsf{:}$$

$$A-\lambda_2 I = egin{bmatrix} -3 & 3 \ 2 & -2 \end{bmatrix} egin{bmatrix} x_1 \ x_2 \end{bmatrix} = egin{bmatrix} 0 \ 0 \end{bmatrix} \
ightarrow egin{bmatrix} -3x_1 + 3x_2 = 0 \ x_2 = x_2 \end{bmatrix} \
ightarrow egin{bmatrix} x_1 = x_2 \ x_2 = x_2 \end{bmatrix}
ightarrow egin{bmatrix} x_1 \ x_2 \end{bmatrix} = x_2 egin{bmatrix} 1 \ 1 \end{bmatrix} \ N(A) = ext{span} iggl\{ egin{bmatrix} 1 \ 1 \end{bmatrix} iggr\} \
ightarrow ext{eigenvector} = egin{bmatrix} 1 \ 1 \end{bmatrix} ext{ when } \lambda = 2 \ \end{cases}$$

Determinant and Trace



• The product of the eigenvalues is equals the determinant.

$$\lambda_1 imes \lambda_2 imes \ldots imes \lambda_n = ext{determinant}$$

• The sum of the n eigenvalues equals the sum of the n diagonal entries (which is also called the **trace**)

$$\lambda_1+\lambda_2+\ldots+\lambda_n=a_{11}+a_{22}+\ldots a_{nn}$$