# Recommender Systems in Large Scale ML

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# Recommender Systems

Introduction

### RS [16]

Recommender Systems (RSs) are software tools and techniques that provide suggestions for <u>items</u> that are most likely of interest to a particular <u>user</u>

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#### **Notations**

- ► *U* set of subjects (users)
- ► I set of objects (items)
- ▶  $D = \{(u_t, i_t, y_t)\}_{t=1}^m \subset U \times I \times Y$  transactions, where Y set of transactions descriptions

# **Applications**

- E-commerce
  - ▶ *U* clients of online shop
  - ► *I* products (books, movies, music, etc)
  - $ightharpoonup r_{ui} = \mathbb{1}\{u \text{ bought } i\}$

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- Social network
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  - ► *I* posts, communities
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- Movies recommendation
  - U clients of the platform
  - ▶ I movies
  - $ightharpoonup r_{ui} = \mathsf{rating}\; u \; \mathsf{gave} \; \mathsf{to} \; i$

	Explicit	Implicit
$r_{ui}$	explicit rating for item $i$ by user $u$	fact (number of times) that $\boldsymbol{u}$ interacted with $\boldsymbol{i}$

Users transactions (feedback)  ${\it D}$  can be devided into two types

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Gathering		

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### Remark

It is straighforward to conver explicit to implicit, for example:

lacksquare if  $r_{ui}$  is a movie rating then  $p_{ui}=\mathbb{1}\{r_{ui}\geq 3\}$  - implicit feedback

If not stated otherwise we assume explicit feedback

### **Table of Contents**

- 1. Evaluation
- 2. Matrix Completion
- 3. Link Prediction
- 4. Session-based Recommendations
- 5. Learning to Rank
- 6. Resume
- 7. RecSys at VK

### Requirements

- System should be able to compute  $\rho(u,i), \rho(u,u'), \rho(i,i')$ , where  $\rho$  similarity (relevance) function
- ▶ Given user u system should be able to rank I according to  $\rho(u,\cdot)$

# Evaluation Gloal

- We have different formulations of RS problem thus different solutions
- ▶ Main goal is to compare different solutions

Scenario 1

#### Protocol

- 1. Order all transactions D by time
- 2. Split D into  $D_{train}$  /  $D_{valid}$  /  $D_{test}$  sets by timestamp
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#### Common solutions

Leave only users and items which appear in all sets

Scenario 2

#### Protocol

- 1. Split D into set of sessions  $S = \{S_u\}_{u \in U}$
- 2. For each user u split  $S_u$  into  $S_{u,train}, S_{u,valid}, S_{u,test}$  (using timestamp)
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#### **Problems**

Peeking into the future

#### Common solutions

Use previous scenario instead

- For each user u we have a set of  $N_u$  ground truth relevant items  $D_u = \{i_1, i_2, \ldots, i_{N_u}\}$  and
- List of  $Q_u$  recommended items (according to  $\rho(u,\cdot)$ )  $R_u = \{r_1, r_2, \dots, r_{Q_u}\}$ , in order of decreasing relevance

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https://en.wikipedia.org/wiki/Evaluation measures (information retrieval)

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Precision@k	$rac{1}{ U }\sum_{u\in U}rac{1}{k}\sum_{i=1}^{\min(k,Q_u)}\mathbb{1}\{r_i\in D_u\}$	(# of recommended items @k that are relevant) / (# of recommended items @k)

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NDCG		

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### Metrics Remarks

- Precision@k, Recall@k, HR@k the order of the recommendations is not taken into account
- MAP, NDCG metric takes into account the order of the recommendations

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Q: Why not to use ROC AUC?

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   Large Scale Matrix Factorization
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### Aggregated data:

- $ightharpoonup R = (r_{ui})_{u \in U, i \in I}$  cross-tabulation matrix, where
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### Examples of $r_{ui}$ :

- rating from user u to movie i
- number of times user u visited page i

Popular Solutions

- Content-based methods
- Collaborative filtering
  - User/Item based
  - Matrix Factorizations (SVD, PMF [12], ALS [8, 9])
- ► Neural Architectures (NCF [7], CB2CF [1])

### Definition (Latent Factor Model via Matrix Factorization)

Given data D, our goal is to find matrices  $P=(p_{ut})_{|U|\times |T|}$  and  $Q=(q_{it})_{|I|\times |T|}$ , where T - set of latent factors ( $|T|\ll |U|,|T|\ll |I|$ ) such that

$$R = P\Delta Q^T,$$

$$\Delta = diag(\pi_1, \dots, \pi_{|T|})$$

# Singular Value Decomposition (SVD)

Model

Low-rank approximation

$$R_k \equiv P_k \Sigma_k Q_k^T$$
 :  $||R - R_k||_F \to \min$ ,

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**Q:** Before we apply SVD we need to fill unobserved values in R. How to do that?

A: Popular choices

 $ightharpoonup r_{ui} = 0$  if value is unobserved



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- **Q:** Suppouse that  $R_k = R$ . Is this model useful for recommendations? **A:** No, therefore we need regularization

## Probabilistic Matrix Factorization [12]

#### Likelihood of data

$$\mathbb{P}\left\{R \mid P, Q, \sigma^{2}\right\} = \prod_{u \in U} \prod_{i \in I} \left[\mathcal{N}\left(r_{ui} \mid \mathbf{p}_{u}\mathbf{q}_{i}, \sigma^{2}\right)\right]^{I_{ui}},$$

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#### **Priors**

$$\mathbb{P}\left\{P\mid\sigma_{P}^{2}\right\} = \prod_{u\in U}\mathcal{N}\left(\mathbf{p}_{u}\mid0,\sigma_{P}^{2}\mathbf{I}\right) \quad \mathbb{P}\left\{Q\mid\sigma_{Q}^{2}\right\} = \prod_{i\in I}\mathcal{N}\left(\mathbf{q}_{i}\mid0,\sigma_{Q}^{2}\mathbf{I}\right)$$

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#### **Posterior**

$$\begin{split} & \ln \mathbb{P}\left\{P,Q \mid R,\sigma^2,\sigma_P^2,\sigma_Q^2\right\} \to \max \quad \iff \\ & \mathcal{L} = \frac{1}{2} \underbrace{\sum_{u \in U, i \in I} \mathbf{I}_{ui} (r_{ui} - \mathbf{p}_u \mathbf{q}_i)^2}_{\text{sum over observer } r_{ui}} + \underbrace{\frac{\lambda_P}{2} \sum_{u \in U} \|\mathbf{p}_u\|_F^2}_{\mathbf{L}_2 \text{ reg}} + \underbrace{\frac{\lambda_Q}{2} \sum_{i \in I} \|\mathbf{q}_i\|_F^2}_{\mathbf{L}_2 \text{ reg}} \to \min \end{split}$$

$$\phi_{FM}(\mathbf{w}, \mathbf{x}) = \phi_{LM}(\mathbf{w}, \mathbf{x}) + \sum_{j_1=1}^n \sum_{j_2=j_1+1}^n (\mathbf{w}_{j_1} \cdot \mathbf{w}_{j_2}) x_{j_1} x_{j_2},$$

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Therefore, if we skip LM term(Q: what if not?) we will get

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If we plug it in sqare-loss and add  $L_2$  reg. we will obtain exactly loss for PMF

### PMF via SGD

- Slow to train when number of observations is very large, therefore
- Slow convergence rate

# Alternating Least Squares (ALS) [9]

Let K be a set of (u,i) pairs for which  $r_{ui}$  is known, therefore

$$\mathcal{L} = \frac{1}{2} \sum_{(u,i) \in \mathcal{K}} (r_{ui} - \mathbf{p}_u \mathbf{q}_i)^2 + \lambda (\|\mathbf{p}_u\|_F^2 + \|\mathbf{q}_i\|_F^2)$$

Optimization of  $\mathcal L$  can be done more efficiently due to the following

#### Observation

If during optimization we fix P in  $\mathcal L$  then optimization problem becomes convex wrt to Q and vice versa. Therefore can be solved in closed-form

Faster than SGD convergence

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#### Popular choices for confidence $c_{ui}$

- $ightharpoonup 1 + \alpha r_{ui}$
- $ightharpoonup 1 + \alpha \log(1 + r_{ui}/\epsilon)$

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We obtain following loss

$$\mathcal{L} = \frac{1}{2} \sum_{(u,i) \in U \times I} c_{ui} (p_{ui} - \mathbf{p}_u \mathbf{q}_i)^2 + \frac{\lambda_P}{2} \sum_{u \in U} \|\mathbf{p}_u\|_F^2 + \frac{\lambda_Q}{2} \sum_{i \in I} \|\mathbf{q}_i\|_F^2$$

Can be solved via ALS (see [9] for details)

**Q:** How do we usually scale SGD?

**Q:** How do we usually scale SGD?

A: Parameter Server, Data/Model Parallelism

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A: Parameter Server, Data/Model Parallelism

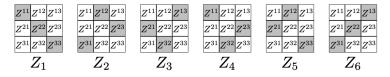
Q: How can we apply them to SGD MF?

Q: How do we usually scale SGD?

A: Parameter Server, Data/Model Parallelism

Q: How can we apply them to SGD MF?

A:



Puc.: Blocks in grey can be processed independently.  $Z_i-i$ -th sub-epoch.  $Z_1,\dots,Z_6$  — single epoch

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  Formulation
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#### Aggregated data:

- $ightharpoonup G = \langle U \cup I, E \rangle, w \colon E \to \mathbb{R}$  weighted bipartite graph, where
- $E = \{(u,i) \mid \exists t \colon (u_t,i_t,y_t) \in D \land u_t = u \land i_t = i\} \subset U \times I$
- $w(u,i) = r_{ui} = agg\{(u_t,i_t,y_t) \in D \mid u_t = u \land i_t = i\}$

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#### Task:

▶ Predict weight w(u,i) of non-existing edge (u,i)

In more general case G is a Heterogeneous Information Network (HIN)

## Definition (Heterogeneous Information Network)

 $G=\langle V,E,\Phi,\Psi,w \rangle$  is a Heterogeneous Information Network (HIN), where  $\Phi\colon V \to A$  — mapping from vertex to its type,  $\Psi\colon E \to X$  — mapping from edge to its type, such that |A|>1 or |X|>1.

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#### HIN example (movies recommendations):

- ▶  $V = Actors \cup Movies \cup Users \cup Genres$ , verticies types  $A = \{actor, movie, user, genre\}$
- Edges types X = {starred\_in, rated, belongs\_to}

**Popular Solutions** 

- ▶ DeepWalk [13], Node2Vec [6]
- Graph Representation Learning (GCMC [2])
- ► HINs (metapath2vec [3], HIN2vec [4])

# Large Scale LP

- Pytorch BigGraph [10]
- GraphVite [21]

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- 4. Session-based Recommendations

### Session-based Recommendations

#### Aggregated data:

 $ightharpoonup S_u = \langle (i_1, y_1), (i_2, y_2), \dots, (i_{n_u}, y_{n_u}) \rangle$  — u-th user session chronologically ordered

### Session-based Recommendations

#### Aggregated data:

 $S_u = \langle (i_1, y_1), (i_2, y_2), \dots, (i_{n_u}, y_{n_u}) \rangle$  — u-th user session chronologically ordered

#### Task:

 $ightharpoonup P(i_{n_u+1}=i\mid S_u)$  — probability of the next event given user session  $S_u$ 

## Session-based Recommendations

**Popular Solutions** 

RNN based [18], BERT2Rec [17]

## Session-based Recommendations

**Popular Solutions** 

► RNN based [18], BERT2Rec [17]

#### Remark

But be careful! Most neural achitectures can not outperform simple solutions. See [11].

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# Learning to Rank

# Learning to Rank

Popular Solutions

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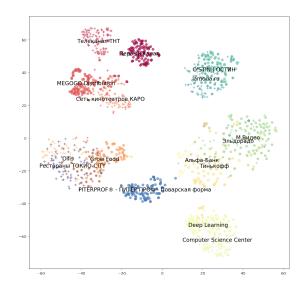
#### Resume

- 1. There are many ways to formulate RecSys problem as ML problem
  - Matrix Completion
  - Link Prediction
  - Session-based
  - Learning to Rank
- Additionaly each formulation can be foother adjusted to deal with different kinds of user feedback
  - Explicit
  - Implicit
- 3. Evaluation (Protocols, Metrics)

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### Similar Communities and Domains Search



## Тематические Ленты<sup>2</sup>

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