```
depth_clustering::Identifiable
   kld
# UniqueIdCounter
+ Identifiable()
+ ~Identifiable()
+ id()
+ guess_class_name()
+ get_current_id_counter()
# DemangleName()
                    depth_clustering::Abstract
                      Sender< ObjSendType >
                      _clients
                    # _type
                    + AbstractSender()
                    + ~AbstractSender()
                    + type()
                    + AddClient()
                    + RemoveClient()
                    + RemoveClient()
                    + client_count()
                    + ShareDataWithAllClients()
                          < Cloud >
 depth_clustering::Abstract
Sender< Cloud >
   _clients
 # _type
 + AbstractSender()
 + ~AbstractSender()
 + type()
 + AddClient()
 + RemoveClient()
 + RemoveClient()
 + client_count()
 + ShareDataWithAllClients()
               Δ
depth_clustering::CloudOdom
        RosSubscriber
#_node_handle
#_subscriber_clouds
# _subscriber_odom
# _sync
# _topic_clouds
# _topic_odom
# _params
# _msg_queue_size
+ CloudOdomRosSubscriber()
+ ~CloudOdomRosSubscriber()
+ Callback()
+ Callback Velodyne()
+ StartListeningToRos()
# RosOdomToPose()
```

RosCloudToCloud()