```
depth_clustering::Identifiable
# UniqueIdCounter
+ Identifiable()
+ ~Identifiable()
+ id()
+ guess_class_name()
+ get_current_id_counter()
# DemangleName()
             Д
                   depth_clustering::Abstract
                     Sender< ObjSendType >
                   # clients
                   #_type
                   + AbstractSender()
                   + ~AbstractSender()
                   + type()
                   + AddClient()
                   + RemoveClient()
                   + RemoveClient()
                   + client_count()
                   + ShareDataWithAllClients()
                            < Cloud >
                                     depth_clustering::Projection
                                               Params
                                     + ProjectionParams()
                                     + ~ProjectionParams()
                                     + SetSpan()
                                     + SetSpan()
                                     + v_start_angle()
 depth_clustering::Abstract
                                     + v_end_angle()
                                     + v_span()
      Sender< Cloud >
                                     + h_start_angle()
 # _clients
                                     + h_end_angle()
 #_type
                                     + h_span()
                                     + rows()
 + AbstractSender()
                                     + cols()
 + ~AbstractSender()
                                     + size()
 + type()
                                     + AngleFromRow()
 + AddClient()
                                     + AngleFromCol()
 + RemoveClient()
                                     + RowFromAngle()
 + RemoveClient()
                                     + ColFromAngle()
 + client_count()
                                     + RowAngleCosines()
 + ShareDataWithAllClients()
                                     + ColAngleCosines()
                                     + RowAngleSines()
                                     + ColAngleSines()
                                     + valid()
                                     + VLP_16()
                                     + HDL_32()
                                     + HDL_64()
+ HDL_64_EQUAL()
                                     + FromConfigFile()
                                     + FullSphere()
                                        #_params
                 depth_clustering::CloudOdom
                         RosSubscriber
                 # _node_handle
                 #_subscriber_clouds
#_subscriber_odom
                 # _sync
                 # _topic_clouds
                 # _topic_odom
                 # msg queue size
                 + CloudOdomRosSubscriber()
                 + ~CloudOdomRosSubscriber()
                 + Callback()
                 + Callback Velodyne()
                 + StartListeningToRos()
                 # RosOdomToPose()
                 # RosCloudToCloud()
```