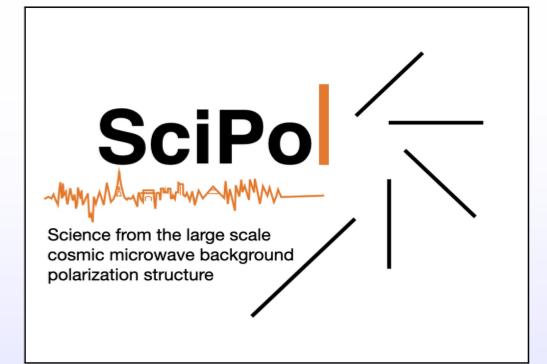


# A Novel Approach to Optimize Clustering of Parametric Map-Based Component Separation for Upcoming CMB Polarization Satellites

Wassim Kabalan<sup>1</sup>, Wuhyun Sohn<sup>1</sup>, Benjamin Beringue<sup>1</sup>, Artem Basyrov<sup>1</sup>, Pierre Chanial<sup>1</sup>, Alexandre Boucaud<sup>1</sup>, Josquin Errard<sup>1</sup>

<sup>1</sup>Université Paris Cité, CNRS, Astroparticule et Cosmologie, F-75013 Paris, France



## Tensor-to-Scalar Ratio & Foreground Removal

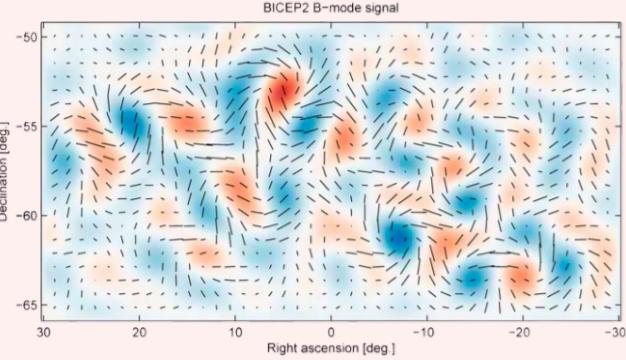


Figure 1: CMB B-mode polarization signal from primordial gravitational waves

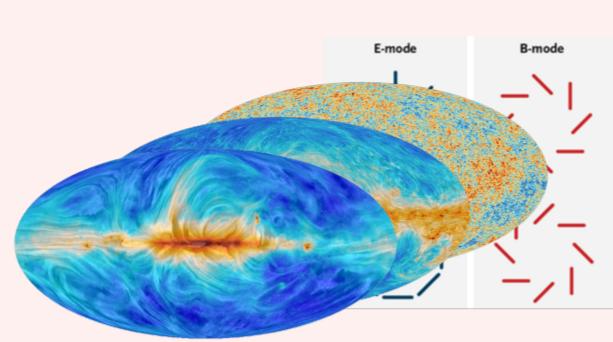


Figure 2: Galactic foreground contamination

### The Challenge:

- Measuring tensor-to-scalar ratio  $r$  requires detecting faint B-mode polarization
- Galactic foregrounds dominate CMB signal by orders of magnitude
- Accurate foreground removal is critical for  $r < 0.001$  detection

## Parametric Component Separation

### Data Model:

$$\mathbf{d} = \mathbf{A}(\boldsymbol{\beta}) \mathbf{s} + \mathbf{n} \quad (1)$$

where  $\mathbf{d}$  is observed data,  $\mathbf{s}$  are sky components,  $\mathbf{A}(\boldsymbol{\beta})$  encodes spectral dependencies, and  $\mathbf{n}$  is noise.

### Generalized Least Squares Solution:

$$\hat{\mathbf{s}} = (\mathbf{A}^\top \mathbf{N}^{-1} \mathbf{A})^{-1} \mathbf{A}^\top \mathbf{N}^{-1} \mathbf{d} \quad (2)$$

### Spectral Likelihood:

$$\ln \mathcal{L}_{\text{spec}}(\boldsymbol{\beta}) \propto (\mathbf{A}^\top \mathbf{N}^{-1} \mathbf{d})^\top (\mathbf{A}^\top \mathbf{N}^{-1} \mathbf{A})^{-1} (\mathbf{A}^\top \mathbf{N}^{-1} \mathbf{d}) \quad (3)$$

**Key Innovation:** Data-driven optimization of spatial clustering rather than fixed patching schemes.

### FURAX Implementation:

```
cmb = CMBoperator(nu, ...)
dust = DustOperator(nu, temp=params["T_d"],
                    beta=params["beta_d"], ...)
synchrotron = SynchrotronOperator(nu,
                                  beta=params["beta_pl"], ...)
A = MixingMatrixOperator(cmb, dust, synchrotron)
AND = (A.T @ N.I)(d)
s = (A.T @ N.I @ A).I(AND)
likelihood = AND @ s
```

## Spatial Variability

### Foreground Spectral Parameters Vary Across Sky:

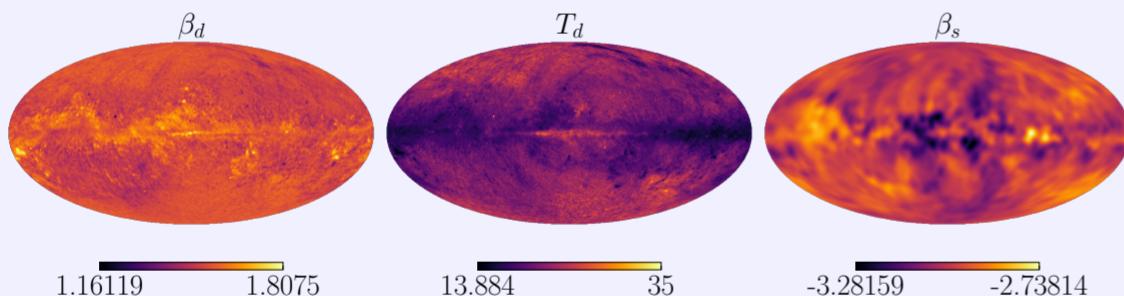


Figure 3: Modified blackbody spectral index map showing spatial variability in dust emission properties across the sky

### Clustering Approach:

- Spherical K-means clustering groups pixels with similar spectral properties
- Balances statistical uncertainty with modeling flexibility

### Optimized K-means Parameters:

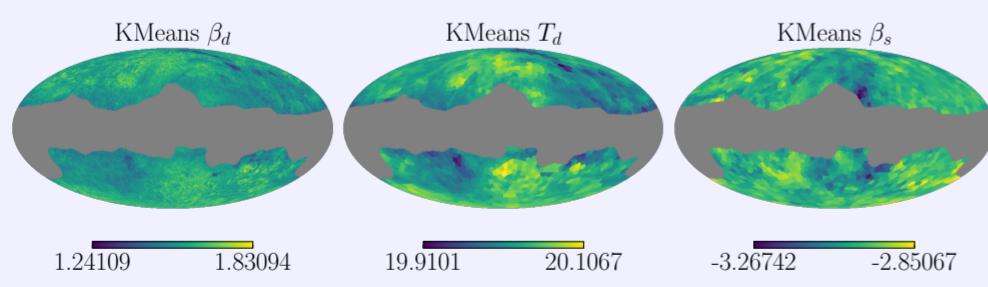


Figure 4: Optimized spectral parameter distributions from K-means clustering showing data-driven adaptation to foreground complexity

## The FURAX Framework

- **JAX-Native:** Differentiable & GPU accelerated
- **Modular Design:** Composable algebraic operators
- **Memory Efficient:** Matrix-free linear operators
- **Scalable:** Multi-GPU execution

**Grid Search:** Configuration space  $\mathcal{G} = \{K_{\beta_d}\} \times \{K_{T_d}\} \times \{K_{\beta_s}\}$  evaluated across 1.92M component separation runs.

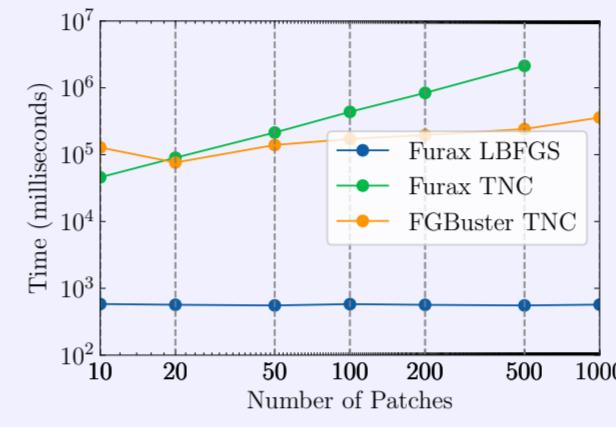


Figure 5: Runtime comparison of FURAX Component Separation

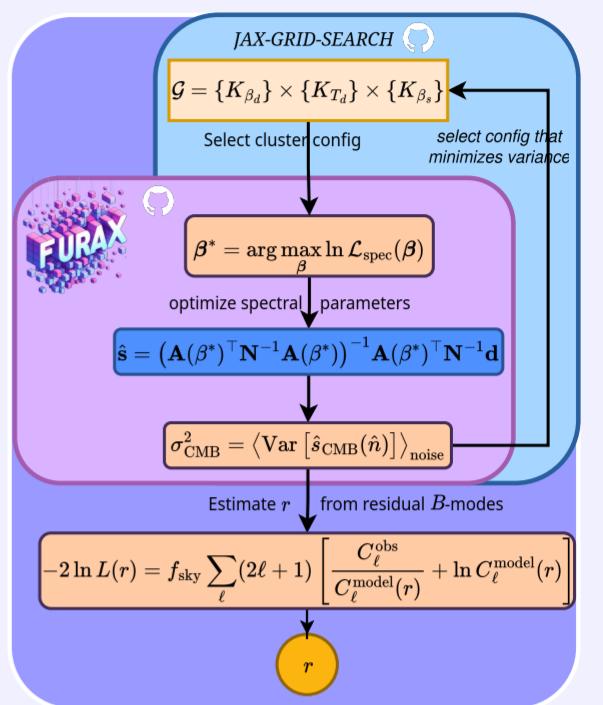


Figure 6: FURAX pipeline: Grid search over clustering configurations, spectral parameter optimization, and CMB variance minimization for model selection

## Likelihood and Variance Analysis

### Selection Criterion - CMB Variance Minimization:

$$\sigma_{\text{CMB}}^2 = \langle \text{Var}_i [\hat{s}_{\text{CMB}}^{(i)}] \rangle_{\text{pixels}} \quad (4)$$

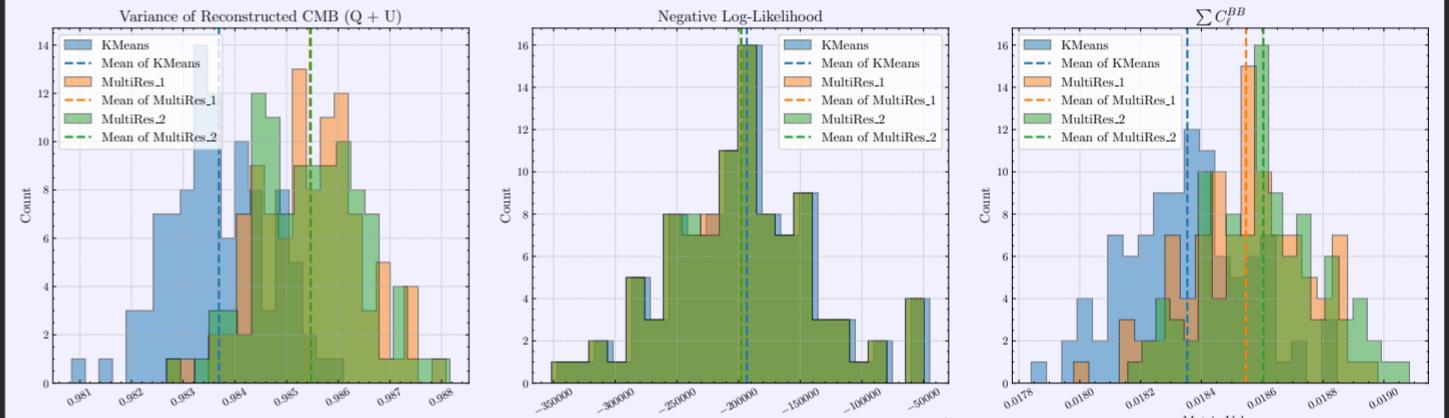


Figure 7: Distribution of CMB variance, spectral likelihood, and B-mode power for different spatial modeling approaches. K-means clustering achieves optimal balance.

**Key Insight:** Variance minimization acts as proxy for residual foreground contamination, leading to more robust cosmological constraints.

## Results

### Tensor-to-Scalar Ratio Constraints:

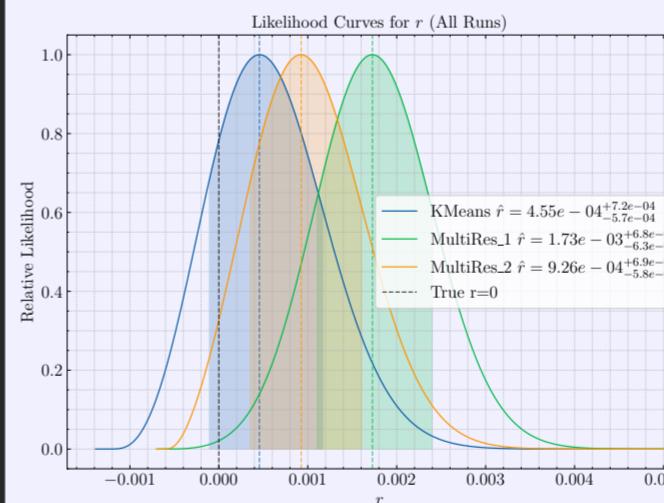


Figure 8:  $r$  likelihood distributions: K-means clustering (blue) yields  $\hat{r} = 4.55 \times 10^{-4}$  with lowest bias and tightest constraints compared to multi-resolution approaches

### Residual B-mode Spectra:

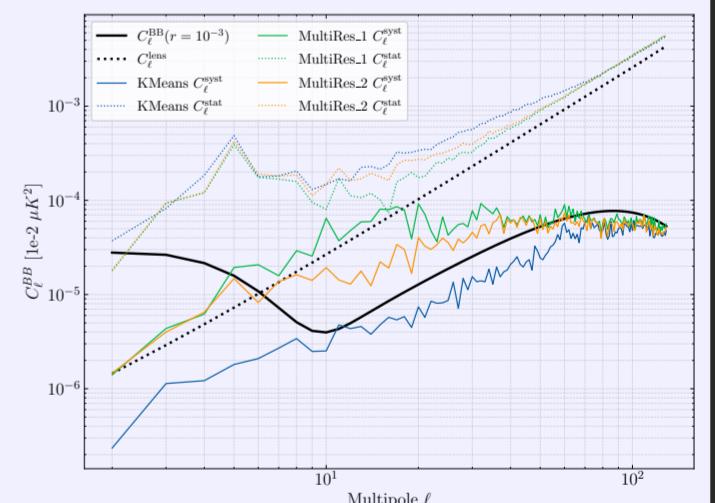


Figure 9: Residual B-mode power spectra: K-means clustering (blue) achieves significantly lower systematic residuals compared to multi-resolution approaches, falling below target sensitivity levels

## References & Acknowledgements

### Key References:

- FURAX framework & component separation methodology: Kabalan et al. (2024), arXiv:2024.xxxxxx
- LiteBIRD collaboration forecasts: LiteBIRD Collaboration (2022), PTEP 2023
- JAX ecosystem for scientific computing: Bradbury et al. (2018), JAX library

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