

# Chapter 3. Spline smoothing and semi-parametric Models (II)

## Part 2

March 14, 2007

### 1 The generalized additive model

Suppose we have response variable  $Y$  and a number of predictors (independent variables)  $\mathbf{x}_1, \dots, \mathbf{x}_p$ . We are interested in

$$m(x_1, \dots, x_p) = E(Y | \mathbf{x}_1 = x_1, \dots, \mathbf{x}_p = x_p)$$

The goal is to estimate  $m(\cdot)$ . Because of the “curse of dimensionality”, the estimation is very unreliable if  $p$  is large ( $> 2$ ).

One way to approximate  $m(\cdot)$  is by the summation of functions of each variable

$$m(x_1, \dots, x_p) \approx g_1(x_1) + \dots + g_p(x_p)$$

If the equality hold, we call the model additive model,

$$Y = g_1(\mathbf{x}_1) + \dots + g_p(\mathbf{x}_p) + \varepsilon$$

where  $E(\varepsilon | \mathbf{x}_1 = x_1, \dots, \mathbf{x}_p = x_p) = 0$ .

**Identification of the model** Up to a constant difference, each component is identifiable. That is if there is another functions

$$Y = f_1(\mathbf{x}_1) + \dots + f_p(\mathbf{x}_p) + \varepsilon$$

Then there is a constant  $c_k$  such that

$$f_k(\mathbf{x}_k) = c_k + g_k(\mathbf{x}_k), \quad k = 1, 2, \dots, p$$

We can rewrite the model as

$$Y = \beta_0 + g_1(\mathbf{x}_1) + \dots + g_p(\mathbf{x}_p) + \varepsilon$$

where  $E\{g_1(\mathbf{x}_1)\} = 0$ .

Most of the time, we have some knowledge about the relation between  $Y$  and some independent variables. For example, we know the relation between  $Y$  and  $\mathbf{x}_1, \dots, \mathbf{x}_q$  are linear. Thus we have the following **Generalized Additive model**

$$Y = \beta_0 + \beta_1\mathbf{x}_1 + \dots + \beta_q\mathbf{x}_q + g_{q+1}(\mathbf{x}_{q+1}) + \dots + g_p(\mathbf{x}_p) + \varepsilon$$

For identification purpose, we further constrain that  $E\{g_k(\mathbf{x}_k)\} = 0, k = q+1, \dots, p$ . In the model  $\mathbf{x}_1, \dots, \mathbf{x}_q$  are the linear part, and  $g_{q+1}(\mathbf{x}_{q+1}), \dots, g_p(\mathbf{x}_p)$  are the nonlinear components.

Note that the partially linear regression model is a special case of GAM.

## 1.1 Estimation of the GAM model

One way to estimate the GAM model is assuming the nonlinear components have the spline form, i.e.

$$g_k(x) = \sum_{j=1}^{J_k+4} \theta_{k,j} B_{k,j}(x)$$

where  $B_{k,j}, j = 1, \dots, J_k + 4$  is the spline basis for function  $g_k$ . Thus the model can be written as

$$Y = \beta_0 + \beta_1\mathbf{x}_1 + \dots + \beta_q\mathbf{x}_q + \sum_{k=q+1}^p \sum_{j=1}^{J_k+4} \theta_{k,j} B_{k,j}(\mathbf{x}_k) + \varepsilon$$

Suppose that  $(\mathbf{x}_{i1}, \dots, \mathbf{x}_{ip}, Y_i), i = 1, \dots, n$  are samples from the model. (How to estimate the model?)

**R package: gam** (please install it in your computer)

**Example 1.1 (simulation)** 100 samples are drawn from the following model

$$Y = 2.5 + 0.5\mathbf{x}_1 - 0.4\mathbf{x}_2 + \sin(2\pi\mathbf{x}_3) + \exp(-20(\mathbf{x}_4 - 0.5)^2) + 0.2 * \varepsilon$$

where  $\mathbf{x}_1, \mathbf{x}_2$  and  $\varepsilon$  are IID  $N(0, 1)$  and  $\mathbf{x}_3, \mathbf{x}_4$  IID uniformly on  $[0, 1]$

The estimated coefficients are

$$\hat{\beta}_0 = 3.8281922, \hat{\beta}_1 = 0.4876495, \hat{\beta}_2 = -0.3898373$$

and the estimated nonlinear components are shown in figure 1

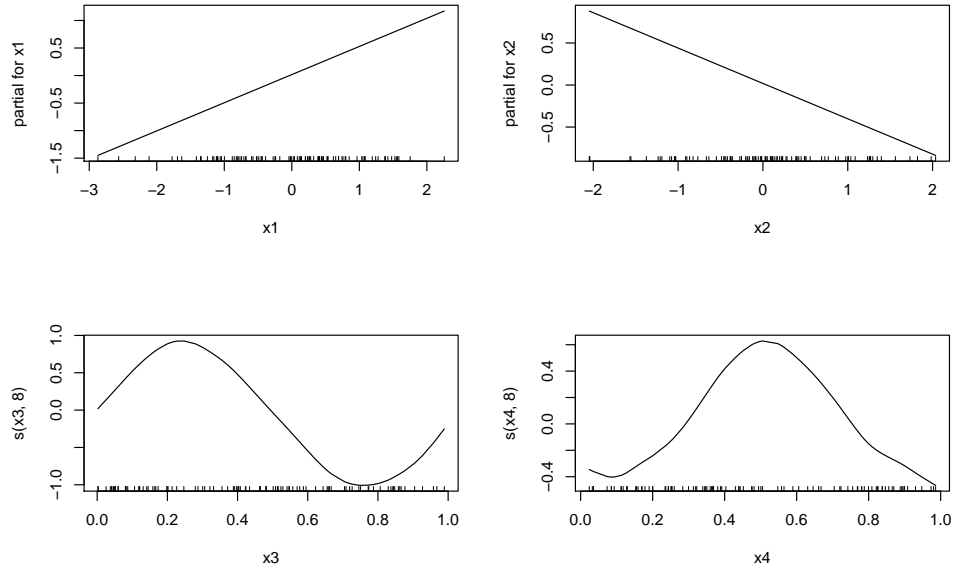


Figure 1: The estimated GAM model [\(code\)](#)

**Example 1.2 (ozone) [\(data\)](#)** *The level of ozone might be affected by radiation, temperature and wind. consider model*

$$ozone^{1/3} = g_1(rad.) + g_2(temp.) + g_3(wind) + \varepsilon$$

*there are 111 observations*

*If we need to select one model amongst the following 5 models*

- (0)  $ozone^{1/3} = g_1(rad.) + g_2(temp.) + g_3(wind) + \varepsilon$
- (I)  $ozone^{1/3} = \beta_0 + \beta_1 * rad + g_2(temp.) + g_3(wind) + \varepsilon$
- (II)  $ozone^{1/3} = \beta_0 + g_1(rad) + \beta_2 * temp + g_3(wind) + \varepsilon$
- (III)  $ozone^{1/3} = \beta_0 + g_1(rad) + g_2(temp) + \beta_3 * wind + \varepsilon$
- (I)  $ozone^{1/3} = \beta_0 + \beta_1 * rad + \beta_2 * temp + \beta_3 * wind + \varepsilon$

*Their CV values are 0.2380925, 0.2390885, 0.2496370, 0.2531100, 0.2730964 respectively. thus, model (0) is selected*

*For a new set of predictors  $rad = 100, temp = 80, wind = 10$ , predict its ozone level.*

*The predicted ozone is  $\exp(2.95195) = 19.14325$*

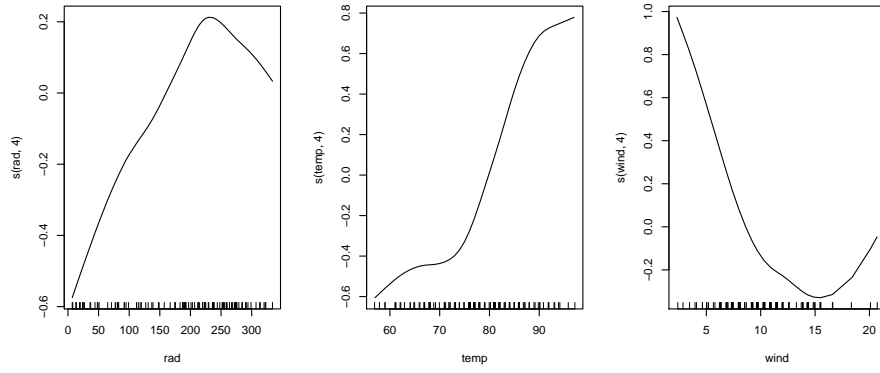


Figure 2: The estimated Additive model ([code](#))

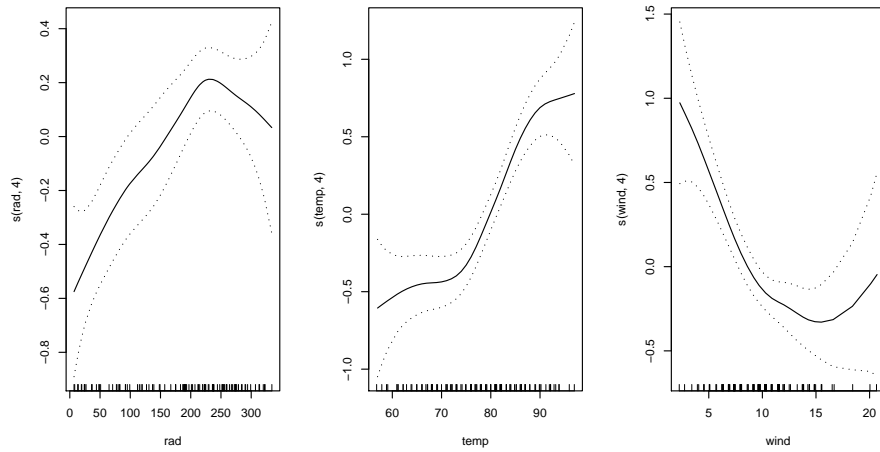


Figure 3: The estimated GAM model and its 95% confidence bands. ([code](#))

## References

Hastie, T. and Tibshirani, R. (1990) *Generalized Additive Models* London: Chapman and Hall.