Review ST3233: Applied time series analysis

- Overview of material:
 - ► Time series processes, stationarity, (sample) ACF and PACF.
 - (Seasonal) ARIMA processes, parameter estimation, forecasting, model building.
 - ► Cross-correlation/dynamic regression modeling, GARCH.
- Review is focused on material after midterm (Ch. 10-12): Seasonal models, Model building, Cross-correlation/dynamic regression modeling, GARCH.
 And (on property) a province of "property of the property of the pro
 - And (on request) a review of "mean" parameters.

Review of ARIMA "mean" parameters

Motivating example for review on mean parameters:

- ▶ Suppose Y_t follows an ARIMA(p, 1, q) model, and $W_t = Y_t Y_{t-1}$.
- ▶ If $E(W_t) = \mu \neq 0$, what does that imply for Y_t ?
- ► To discuss:
 - ▶ Review: How to formulate/interpret/simulate/estimate/forecast ARMA(p, q) models with non-zero mean μ ,
 - ▶ How to formulate/interpret/simulate/estimate/forecast ARIMA(p, 1, q) models with non-zero mean μ for $(Y_t Y_{t-1})$.

ARMA(p,q) models constant term θ_0

▶ A stationary ARMA(p, q) model can be written compactly as

$$\phi(B)Y_t = \theta_0 + \theta(B)e_t,$$

with constant term θ_0 and AR and MA characteristic polynomials

$$\phi(x) = 1 - \phi_1 x - \phi_2 x^2 - \dots - \phi_p x^p,$$

$$\theta(x) = 1 - \theta_1 x - \theta_2 x^2 - \dots - \theta_q x^q.$$

Or equivalently

$$Y_{t} = \theta_{0} + \phi_{1}Y_{t-1} + \phi_{2}Y_{t-2} + \dots + \phi_{p}Y_{t-p} + e_{t} -\theta_{1}e_{t-1} - \theta_{2}e_{t-2} - \dots - \theta_{q}e_{t-q}.$$

▶ With $E(e_t) = 0$, it follows that

$$E(Y_t) = E(\theta_0 + \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + \ldots + \phi_p Y_{t-p})$$

and because Y_t is stationary, $E(Y_t) = \mu$, a constant given by:

$$\mu = \theta_0/(1 - \phi_1 - \ldots - \phi_p).$$

Rewriting ARMA(p,q) models with constant term θ_0

Instead of

$$Y_{t} = \theta_{0} + \phi_{1}Y_{t-1} + \phi_{2}Y_{t-2} + \dots + \phi_{p}Y_{t-p} + e_{t} \\ -\theta_{1}e_{t-1} - \theta_{2}e_{t-2} - \dots - \theta_{q}e_{t-q},$$

we can also write the ARMA model as

$$Y_{t} - \mu = \phi_{1}(Y_{t-1} - \mu) + \phi_{2}(Y_{t-2} - \mu) + \dots + \phi_{p}(Y_{t-p} - \mu) + e_{t} -\theta_{1}e_{t-1} - \theta_{2}e_{t-2} - \dots - \theta_{q}e_{t-q}.$$

- ► Two ways to verify that this expression is correct:
 - Just plug in $\theta_0 = \mu(1 \phi_1 \dots \phi_p)$ in the first expression
 - ▶ Start with $X_t \sim ARMA(p,q)$ with $E(X_t) = 0$:

$$\phi(B)X_t = \theta(B)e_t,$$

and define $Y_t = X_t + \mu$:

$$\phi(B)(Y_t - \mu) = \theta(B)e_t.$$

▶ How to estimate μ for a given time series?

Estimating μ and forecasting Y_t for the ARMA(p,q) model

- ▶ If $E(Y_t) = \mu \neq 0$, μ is included in the likelihood function, and we can obtain the MLE for μ (see Ch.7).
- ▶ The MLE for μ is used for forecasting Y_{t+g} (see Ch.9).
- ► A note on reading R output:

▶ Does "intercept" refer to μ or θ_0 ? > theta0 <- mu*(1-sum(phis)); theta0 [1] 1.5 > mu [1] 3

ARIMA(p, d, q) models constant term θ_0

▶ An ARIMA(p, d, q) model can be written compactly as

$$\phi(B)(1-B)^d Y_t = \theta_0 + \theta(B)e_t,$$

with constant term θ_0 and AR and MA characteristic polynomials

$$\phi(x) = 1 - \phi_1 x - \phi_2 x^2 - \dots - \phi_p x^p, \theta(x) = 1 - \theta_1 x - \theta_2 x^2 - \dots - \theta_q x^q.$$

• Or equivalently, for $W_t = (1 - B)^d Y_t$

$$W_{t} = \theta_{0} + \phi_{1}W_{t-1} + \phi_{2}W_{t-2} + \dots + \phi_{p}W_{t-p} + e_{t} -\theta_{1}e_{t-1} - \theta_{2}e_{t-2} - \dots - \theta_{q}e_{t-q},$$

It follows that

$$E(W_t) = E(\theta_0 + \phi_1 W_{t-1} + \phi_2 W_{t-2} + \ldots + \phi_p W_{t-p})$$

and because W_t is stationary, $E(W_t) = \mu = \theta_0/(1 - \phi_1 - \ldots - \phi_p)$.

• What is $E(Y_t)$ if $E(W_t) = \mu$?

Example: $E(Y_t)$ for IMA(1,1) model with $\theta_0 \neq 0$

▶ For the IMA(1,1) model, if $E(W_t) = E(Y_t - Y_{t-1}) = \mu$

$$(1-B)Y_{t} = \theta_{0} + e_{t} - \theta e_{t-1},$$

$$Y_{t} - Y_{t-1} = \mu + e_{t} - \theta e_{t-1},$$

$$Y_{t} = \mu + e_{t} - \theta e_{t-1} + Y_{t-1}.$$

▶ Substituting the expression for Y_{t-1} , Y_{t-2} , etc we find

$$Y_{t} = \mu + e_{t} - \theta e_{t-1} + Y_{t-1},$$

$$= \mu + e_{t} - \theta e_{t-1} + (\mu + e_{t-1} - \theta e_{t-2} + Y_{t-2}),$$

$$= 2\mu + e_{t} + (1 - \theta)e_{t-1} - \theta e_{t-2} + Y_{t-2},$$

$$\dots$$

$$= t\mu + e_{t} + (1 - \theta)e_{t-1} + \dots + (1 - \theta)e_{1} - \theta e_{0} + Y_{0}.$$

▶ Suppose $Y_0 = 0$, then $E(Y_t) = t \cdot \mu$.

$E(Y_t)$ in an ARIMA(p, 1, q) model with $\theta_0 \neq 0$

More generally, for an ARIMA(p,1,q) with $W_t=Y_t-Y_{t-1}$, with $Y_0=0$, we find that if $E(W_t)=\mu$ then:

$$E(Y_{t}) = E(W_{t} + Y_{t-1}),$$

$$= \mu + E(Y_{t-1}),$$

$$= \mu + \mu + E(Y_{t-2}),$$
...
$$= t \cdot \mu + E(Y_{0}),$$

$$= t \cdot \mu.$$

Even more generally (Ch. 5), $\theta_0 \neq 0$ in an ARIMA(p, d, q) model results in a mean function for Y_t which is a deterministic polynomial of degree d.

Estimating μ and forecasting Y_t for the ARIMA(p, 1, q) model

- Maximum likelihood estimates for all ARIMA model parameters, including μ can be obtained as usual, based on the likelihood function for W_t .
- ▶ The MLE for μ is used for forecasting Y_{t+g} (see Ch.9).
 - ► E.g., for IMA(1,1) use

$$Y_t = Y_{t-1} + \mu + e_t - \theta e_{t-1}.$$

You can obtain an estimate for μ in an ARIMA(p,1,q) model using the "arima" function in R but it is less straightforward than doing so using the "Arima" function from the "forecast" package... so let's check that one out!

Example simulation/estimation/forecast for ARIMA(1,1,1) process

- ▶ How to simulate an ARIMA(1,1,1) process with $\theta_0 \neq 0$?
- Steps:
 - ▶ Get $X_t \sim ARMA(1,1)$ with mean zero.
 - Get $W_t = X_t + \mu = Y_t Y_{t-1}$.
 - Fix $Y_0 = 0$ and get $Y_t = W_t + Y_{t-1}$.

R-code for simu and estimation

```
library(forecast)
mu < -0.5
phis \leftarrow -0.8
Wzeromean <- arima.sim(mode = list(ma = -0.5, ar = phis,
 order = c(1,0,1), n=200)
W.t. <- Wzeromean + mil
Y.t <- diffinv(W.t, xi = 0) # xi is starting value Y_0
mod <- Arima(Y.t, order = c(1,1,1), include.drift = TRUE,
method="MI.")
> summary(mod)
          ar1 ma1 drift
      -0.7809 -0.4860 0.4844
```

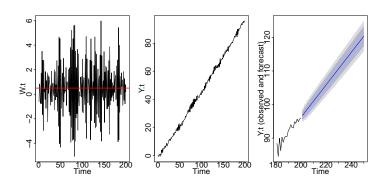
▶ The drift term refers to μ (NOT θ_0).

Forecasting in R using "forecast"

```
Nice plots with 80% and 95% Pls!
R-code (main points)
                                         r.t (observed and fore 0 40 80
mod <- Arima(Y.t.
 order = c(1,1,1),
 include.drift = TRUE,
 method="ML")
fcast <- forecast(mod, h=50)</pre>
                                                 50
                                                              200
plot(fcast)
                                                       Time
plot(fcast, include = 20)
                                         and foreca
> fcast$mean[50]-fcast$mean[49]
[1] 0.4843754
> coef(mod)['drift']
   drift
0.484378
                                                  200
                                                               240
```

Summary

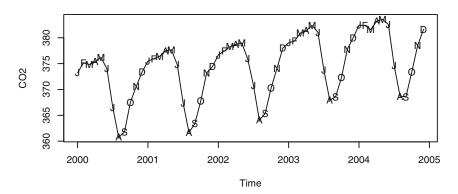
- ▶ Suppose Y_t follows an ARIMA(p, 1, q) model, and $W_t = Y_t Y_{t-1}$.
- ▶ If $E(W_t) = \mu \neq 0$, $E(Y_t)$ is a linear function of μ , which we can estimate using ML estimation, and incorporate in the forecast.
- ► However, do note the implication of including $\mu \neq 0$: decide whether a time trend should be included in the forecast or not!



Seasonal models

- Some time series Y_t have a season associated with them. For example
 - Monthly CO2 data: year (12 months)
 - ▶ Monthly airline passenger data: year (12 months)

Exhibit 10.2 Carbon Dioxide Levels with Monthly Symbols



Seasonal models

- Seasonal time series may show seasonal autocorrelation.
 - Example: $Y_t = 0.8 Y_{t-12} + e_t$,
 - ▶ there is seasonal autocorrelation in Y_t because if Y_t was "relatively low" 12 months ago, it's expected to be low this month too.
- Multiplicative seasonal ARIMA models allow for modeling such seasonal autocorrelation:
 - seasonal autocorrelations are modeled using autoregressive and moving average terms with seasonal lags,
 - non-seasonal autoregressive and moving average terms can be added to capture non-seasonal autocorrelations.
 - This is done in a parsimonious way by multiplying characteristics polynomials, explained on the next slide.
- Seasonal differencing can be applied if the time series is not seasonally stationary (has a seasonal deterministic trend), to obtain a stationary time series.

Differenced multiplicative seasonal models

 Y_t is a multiplicative ARIMA(p, d, q)x $(P, D, Q)_s$ process with

- ightharpoonup constant term θ_0 ,
- seasonal period s,
- \triangleright non-seasonal orders p, q and seasonal orders P, Q,
- ▶ AR characteristic polynomial $\phi(x)\Phi(x)$ with

$$\phi(x) = 1 - \phi_1 x - \phi_2 x^2 - \dots - \phi_p x^p,$$

$$\Phi(x) = 1 - \Phi_1 x^s - \Phi_2 x^{2 \cdot s} - \dots - \Phi_p x^{P \cdot s},$$

▶ MA characteristic polynomial $\theta(x)\Theta(x)$ with

$$\begin{array}{rcl} \theta(x) & = & 1 - \theta_1 x - \theta_2 x^2 - \ldots - \theta_q x^q, \\ \Theta(x) & = & 1 - \Theta_1 x^s - \Theta_2 x^{2 \cdot s} - \ldots - \Theta_Q x^{Q \cdot s}, \end{array}$$

if Y_t is defined as follows:

$$\phi(B)\Phi(B)(1-B^s)^D(1-B)^dY_t=\theta_0+\theta(B)\Theta(B)e_t.$$
 or equivalently $\phi(B)\Phi(B)W_t=\theta_0+\theta(B)\Theta(B)e_t,$ for
$$W_t=\nabla_s^D\nabla^dY_t=(1-B^s)^D(1-B)^dY_t.$$

Example: ARMA $(0,1)x(0,1)_{12}$

▶ The multiplicative Seasonal ARMA(0,1)x(0,1)₁₂ model is given by:

$$Y_{t} = \theta(B) \cdot \Theta(B)e_{t},$$

$$= (1 - \theta B)(1 - \Theta B^{12})e_{t},$$

$$= (1 - \theta B - \Theta B^{12} + \theta \Theta B^{13})e_{t},$$

$$= e_{t} - \theta e_{t-1} - \Theta e_{t-12} + \theta \Theta e_{t-13}.$$

- ► This is also an ARMA(0,13) model with $\theta_1 = \theta$, $\theta_{12} = \Theta$ and $\theta_{13} = -\theta\Theta$, and all other θ_i 's are fixed at zero.
- ► (P)ACFs, parameter estimation and forecasting: follow approach taken for non-seasonal ARIMA processes.
 - ▶ E.g., for process above, derive autocorrelation function as usual and find that $\rho_k = 0$ for $k \neq 0, 1, 11, 12, 13$.
- How to do model selection?

Time series model building

What are the tasks involved in selecting candidate ARIMA(p, d, q)×(P, D, Q)_s models for a time series?

- ▶ Step 1: Select the order *d* of non-seasonal and *D* of seasonal differencing.
 - ▶ Informally: does ACF decay on seasonal and non-seasonal lags?
 - Based on tests: Unit root tests (not tested on final exam).
- ▶ Step 2: Select the orders p, q, P, Q and decide whether the constant term θ_0 and/or "in-between" predictors (lagged Y's or past white noise terms) should be removed.
 - ▶ Informally: Select p, q, P, Q with ACF, PACF (and EACF).
 - Based on information criteria: AICc, BIC.
 - They combine a negative measure of model fit with a penalty for the number of parameters, thus models with lower values are preferred.
 - Models up to +2 of the minimum value are usually considered as candidate models.
- ▶ Steps 1 and 2 may result in a set of candidate models. If so, we need to compare models (diagnostics and differences in forecasts).

Cross-correlation and dynamic regression models

- Suppose we have a time series of interest Y_1, Y_2, \ldots, Y_t (e.g. changes in the unemployment rate), here denoted by Y, and we want to explore whether/how another time series X_1, X_2, \ldots, X_t , here denoted by X (e.g. depression measured in employment-related social media output), relates to Y.
 - E.g. does depression increase before or after unemployment increases? Or is there no relation at all?
 - Other examples: price and sales of an item, weather/climate and dengue outbreaks, ...
- ► Topics discussed:
 - Summarizing the correlation between X and Y using the (sample) cross-correlation function
 - ▶ Modeling *Y* using *X* while accounting for autocorrelation in *Y*: dynamic regression models

Cross-correlation function $\rho_k(X, Y)$

- For jointly stationary X and Y, we define the cross-correlation function $\rho_k(X,Y) = Corr(X_{t+k},Y_t) = Corr(X_t,Y_{t-k})$.
- ▶ The sample ccf, based on pairs $(X_1, Y_1), \dots, (X_n, Y_n)$, is given by:

$$r_k(X,Y) = \frac{\sum_{t=k+1}^n (X_t - \bar{X})(Y_{t-k} - \bar{Y})}{\sqrt{\sum_{t=1}^n (X_t - \bar{X})^2} \sqrt{\sum_{t=1}^n (Y_t - \bar{Y})^2}}.$$

▶ If X and Y are stationary processes with ACFs $\rho_k(X)$ and $\rho_k(Y)$, with X independent of Y, then approximately for large n,

$$r_k(X,Y) \sim N(0,V),$$

for all k, where $V = 1/n(1+2\sum_{k=1}^{\infty}\rho_k(X)\rho_k(Y))$.

▶ What is *V* when *X* and *Y* are independent white noise processes?

Cross-correlation function: Example

- $Y_t = \beta_0 + \beta_1 X_{t-m} + e_t$, where the X_t 's are white noise with $Var(X_t) = \sigma_X^2$, independent of e_t .
 - ightharpoonup m > 0 is referred to as X leading Y.

$$\rho_{-m}(X,Y) = \frac{Cov(X_{t-m}, Y_t)}{\sqrt{Var(X_t)Var(Y_t)}},$$

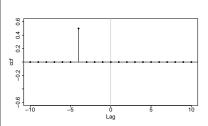
$$= \frac{Cov(X_{t-m}, \beta_0 + \beta_1 X_{t-m} + e_t)}{\sqrt{\sigma_X^2} \sqrt{\beta_1^2 \sigma_X^2 + \sigma_e^2}},$$

$$= \frac{\beta_1 \sigma_X^2}{\sigma_X \sqrt{\beta_1^2 \sigma_X^2 + \sigma_e^2}},$$

$$= \frac{\beta_1 \sigma_X}{\sqrt{\beta_1^2 \sigma_X^2 + \sigma_e^2}},$$

and $\rho_k(X, Y) = 0$ for $k \neq -m$.

Example: m = 4



The CCF $\rho_k(X, Y)$ when X_t 's are autocorrelated

▶ Do we still find that $\rho_k(X,Y) = 0$ for $k \neq -m$ in the model

$$Y_t = \beta_0 + \beta_1 X_{t-m} + Z_t,$$

where X_t and Z_t are independent from each other, but where X_t is not necessarily white noise?

Let's check:

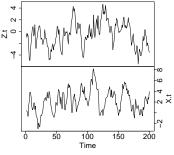
$$\rho_k(X,Y) = \frac{Cov(X_{t+k},Y_t)}{\sqrt{Var(X_t)Var(Y_t)}} = \frac{Cov(X_{t+k},\beta_0 + \beta_1 X_{t-m} + Z_t)}{\sigma_X \sigma_Y}$$

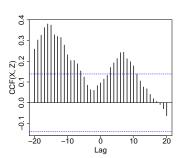
 $\rho_k(X,Y)$ can be non-zero for $k \neq -m$ if the X_t 's are autocorrelated!

▶ So how to figure out which lag *m* is important?

Another issue when trying to figure out what lag(s) to focus on...

Simulation example for the sample CCF when $Y_t = Z_t \sim AR(1)$, $X_t \sim AR(1)$ (independent of Z_t) and n = 200.





- ▶ What's going on?
- Remember: If X and Y are stationary processes with ACFs $\rho_k(X)$ and $\rho_k(Y)$, with X independent of Y, then approx. for large n, $r_k(X,Y) \sim N(0,V)$ for all k, where $V = 1/n(1+2\sum_{k=1}^{\infty}\rho_k(X)\rho_k(Y))$ can get larger than 1/n!

How to figure out whether some X_{t-m} 's are related to Y_t ?

▶ Suppose we want to decide if any X_{t-m} are related to Y_t in a model in the form of

$$Y_t = \sum_{k=-\infty}^{\infty} \beta_k X_{t+k} + Z_t,$$

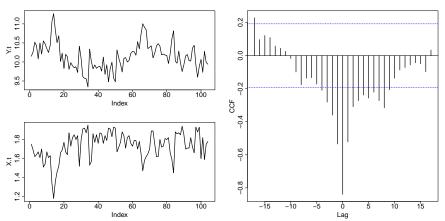
where X_t and Z_t are time series processes, how can we find out which β_k 's are non-zero?

- Approach:
 - 1. Find filter $\pi(B)$ for X_t such that $\tilde{X}_t = \pi(B)X_t$ is approximately white noise.
 - ▶ E.g., if X is an AR(p) process, then $e_t = X_t \sum_{k=1}^p \phi_k X_{t-k}$.
 - ► The filter for X is given by $\pi(B) = 1 \sum_{k=1}^{p} \overline{\phi_k} B^k$.
 - 2. Examine $r_k(\tilde{X}, \tilde{Y})$ where $\tilde{Y}_t = \pi(B)Y_t$ (assumed to be stationary):
 - ▶ $Var(r_k(\tilde{X}, \tilde{Y})) = V = 1/n(1 + 2\sum_{k=1}^{\infty} \rho_k(\tilde{X})\rho_k(\tilde{Y})) = 1/n$, thus if there is no relation between X and Y ($\beta_k = 0 \forall k$), then we expect to find mostly 'insignificant r_k ' with $|r_k(\tilde{X}, \tilde{Y})| < 1.96\sqrt{1/n}$.
 - ▶ However, if there is a $\beta_m \neq 0$, then $\rho_m(\tilde{X}, \tilde{Y}) \propto \beta_m$, thus we expect to find that r_m is significant.

Example: Q2 in tut 8

 $Y_t = \log(\text{weekly sales})$ and $X_t = \text{sales price}$, for Bluebird Lite potato chips.

Let's find out if the sales price is related to weekly sales!



First step? Get CCF for prewhitened series!

CCF prewhitened series

▶ To obtain the sample CCF for prewhitened series \tilde{X}_t and \tilde{Y}_t , the following approach was used in R (to find an ARIMA(p,d,0) model):

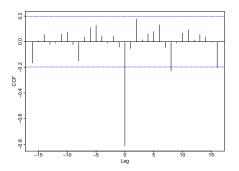
```
> auto.arima(X.t, ic = "aicc", approximation = FALSE,
stepwise = FALSE, max.q = 0)
Series: X.t
ARIMA(4,1,0)
m1=arima(X.t,order=c(4,1,0), include.mean = FALSE)
prewhiten(x=(X.t),y=(as.vector(Y.t)), x.model=m1)
```

Note that differencing doesn't change the relation between X_t and Y_t because

$$Y_t = \beta_0 + \beta_1 X_t + Z_t,$$

$$\nabla Y_t = \beta_1 \nabla X_t + \nabla Z_t.$$

CCF for whitened series



m1=arima(X.t,order=c(4,1,0), include.mean = FALSE)
prewhiten(x=(X.t),y=(as.vector(Y.t)), x.model=m1)

- ▶ Conclusion? Suggested model: $Y_t = \beta_0 + \beta_1 X_t + Z_t$.
- ▶ Can we fit a model $Y_t = \beta_0 + \beta_1 X_t + Z_t$ to try to predict Y_t , or obtain the relation between Y_t and X_t ?

Modeling Y_t using X_t

A model of the form

$$Y_t = \beta_0 + \beta_1 X_{t-m} + Z_t$$

is called a transfer-function model/distributed-lag model/dynamic regression model.

- These models may include the covariate at several lags but we discussed only the example with just one lagged covariate.
- ▶ After identifying which X_{t-m} to include, how to specify Z_t in the model $Y_t = \beta_0 + \beta_1 X_{t-m} + Z_t$?
- ▶ In order to explore the model specification for Z_t , the following approach is used:
 - (A) Regress Y_t on X_{t-m} (assume temporarily that $Y_t = \beta_0 + \beta_1 X_{t-m} + e_t$) and obtain residuals $\hat{Z}_t = Y_t \hat{Y}_t$.
 - (B) Explore \hat{Z}_t to specify a candidate model for Z_t
 - (C) Fit the complete model $Y_t = \beta_0 + \beta_1 X_{t-m} + Z_t$, where Z_t is specified by the candidate model and check model diagnostics.

Sales example continued

- ▶ Step A: Regress Y_t on X_t and obtain residuals.
- ▶ Step B: Analyze the residuals to find a candidate model for Z_t .
- ▶ Step C: Fit the complete model, here ARIMA(0,1,1) for Z_t :

- Conclusion:
 - $Y_t = \beta_1 X_t + Z_t$ where $\hat{\beta}_1 \approx -1.9$ and $\nabla Z_t = e_t \theta e_{t-1}$ where $\hat{\theta} \approx 0.7$.
 - Every one unit increase in X at time t is associated with an decrease in Y (log(sales)) at time t of appr. -1.9.
 - Interpretation for relation between X and sales, given by $\exp(Y)$?
 - Every one unit increase in X at time t is associated with a relative change of (multiplying Y by) $\exp(-1.9) \approx 0.15$ in Y.

Summary Ch. 11

- ▶ Suppose we have a time series of interest $Y_1, Y_2, ..., Y_t$ (e.g. changes in log-transformed sales), here denoted by Y, and we want to explore whether/how another time series $X_1, X_2, ..., X_t$, here denoted by X (e.g. sales price), relates to Y_t .
- ▶ We discussed:
 - ► How to summarize the correlation between *X* and *Y* using the (sample) cross-correlation function (CCF),
 - ▶ and that the sample CCF can show spurious correlation if

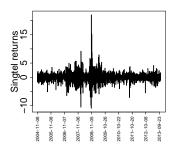
$$Y_t = \beta_0 + \beta_1 X_{t-m} + Z_t,$$

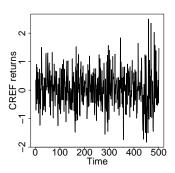
if X and Z are both autocorrelated time series.

- ► How to prewhiten X, and use the same procedure for Y, to obtain a new sample CCF which is informative of the relation between Y and X.
- ▶ How to fit a dynamic regression model to model Y using X while accounting for autocorrelation in Y.

Ch. 12: GARCH models

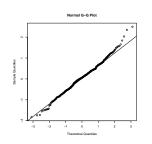
▶ The class of GARCH(p,q) models is used for estimating and forecasting volatility, which refers to the conditional variance or standard deviation $SD(r_t|r_{t-1},r_{t-2},\ldots)$ for some time series r_t (e.g. returns).

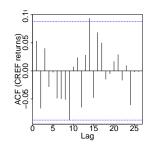


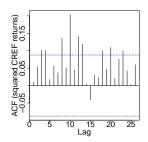


GARCH

- We can consider using a GARCH model for non-autocorrelated time series
 - with autocorrelation in squared or absolute values,
 - where normality does not hold true.







GARCH models

▶ The generalized autoregressive conditional heteroskedasticity model, GARCH(p, q), for r_t is given by:

$$r_{t} = \sigma_{t|t-1}\varepsilon_{t},$$

$$\sigma_{t|t-1}^{2} = \omega + \beta_{1}\sigma_{t-1|t-2}^{2} + \ldots + \beta_{p}\sigma_{t-p|t-p-1}^{2} + \alpha_{1}r_{t-1}^{2} + \alpha_{2}r_{t-2}^{2} + \ldots + \alpha_{q}r_{t-q}^{2}$$

where the innovations ε_t are iid and independent of the past returns, with $E(\varepsilon_t) = 0$ and constant variance.

- Examples:
 - ▶ For the ARCH(1) model:

$$\sigma_{t|t-1}^2 = \omega + \alpha r_{t-1}^2.$$

▶ For the GARCH(1,1) model:

$$\sigma_{t|t-1}^2 = \omega + \alpha r_{t-1}^2 + \beta \sigma_{t-1|t-2}^2.$$

Properties and forecasts

- We discussed how to evaluate (conditional) expectations and the variance of r_t , that r_t^2 satisfies an ARMA model, as well as how to forecast $\sigma_{t+h|t}^2$.
- ▶ For these derivations, the following notation was useful:
 - $ightharpoonup R_t$ refers to the return as a random variable and r_t to its realization,
 - ▶ $V_{t|t-1}$ refers to the conditional variance $\sigma^2_{t|t-1}$ as a random variable and $v_{t|t-1}$ to its realization.
- ▶ Example for GARCH(1,1) forecast

$$\hat{v}_{t+g|t} = E(R_{t+g}^2|R_j = r_j, j = 1, 2, \dots t),$$

$$= E(V_{t+g|t+g-1}\varepsilon_{t+g}^2|R_j = r_j, \text{ for } j = 1, \dots, t),$$

$$= E(\varepsilon_{t+g}^2)E(V_{t+g|t+g-1}|R_j = r_j, \text{ for } j = 1, \dots, t),$$

$$= E(V_{t+g|t+g-1}|R_j = r_j, \text{ for } j = 1, \dots, t),$$

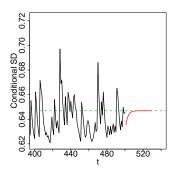
$$= E(V_{t+g|t+g-1}|R_j = r_j, \text{ for } j = 1, \dots, t),$$

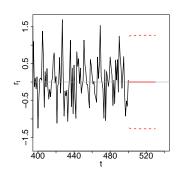
$$= E(\omega + \alpha_1 R_{t+g-1}^2 + \beta_1 V_{t+g-1|t+g-2}|R_j = r_j, \text{ for } j = \dots),$$

$$= \omega + \alpha_1 r_t^2 + \beta_1 \hat{v}_{t|t-1}, \text{ for } g = 1,$$

$$\omega + (\alpha_1 + \beta_1) \hat{v}_{t+g-1|t}, \text{ for } g > 1.$$

Example of GARCH(1,1) forecast: Conditional SD and returns





- If $r_t = \sigma_{t|t-1}\varepsilon_t$ with $\varepsilon_t \sim N(0,1)$, the forecast intervals for r_{t+h} are given by $\hat{r}_{t+h} \pm 1.96\sigma_{t+h|t}$, where $\hat{r}_{t+h} = E(r_{t+h}|r_1, \dots, r_t) = 0$.
- ▶ The conditional SD $\sigma_{t+h|t}$ converges to the unconditional SD for r_t , this follows from the (stationary) ARMA(1,1) representation for r_t ... really?

GARCH forecasts

- ▶ The conditional SD $\sigma_{t+h|t}$ converges to the unconditional SD for r_t , this follows from the (stationary) ARMA(1,1) representation for R_t :
 - ► E.g., for GARCH(1,1):

$$R_t^2 = \omega + (\beta_1 + \alpha_1)R_{t-1}^2 + \eta_t - \beta_1\eta_{t-1},$$

where the η_t 's have mean zero and not autocorrelated and not correlated with the squared returns.

- ▶ Thus for forecasting: $\hat{R}_t^2(g) \rightarrow E(R_t^2)$,
- where $\hat{R}_t^2(g) = E(R_{t+g}^2 | R_j = r_j, j = 1, 2, ... t) = \hat{v}_{t+g|t}$ and $E(R_t^2) = var(R_t)$.

Review ST3233: Applied time series analysis

- Overview of material:
 - ► Time series processes, stationarity, (sample) ACF and PACF.
 - (Seasonal) ARIMA processes, parameter estimation, forecasting, model building.
 - Cross-correlation/dynamic regression modeling, GARCH.
- ► The End!