Lecture 6: Grantational-vave search techniques

topico: Decksion yheory
type I vo. type 2 errors
detection confidence
background extination (via times) ides)
prob. of actrophysical origin

Neymon-Penson Lemmon marximm likelihood estimators matched filter SNR as maxi-like amplitude burrot MLE searches

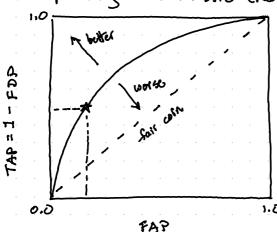
## Intro to Decision Theory

Decide what we believe based on observations

Type I error: reject will hyp. when it is true (False Alorm)

Type 2 error: fail to reject null hyp. when 11-15 false (False Dismissed)

Receiver Operating Characteristic (ROC) Curves



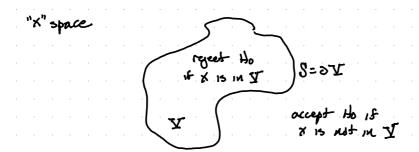
We compute some statistic of the data (X) and use that to decide whether to reject must hypothesis.

additionally, we can compile the prob. of a signal being present

This is often called "pastro" in the literature

To do this, we need to extinate p(x/sig) & p(x/noise)

Ask me offline how that's done in practice if you're interested



what decision suface maximizes the TAP at fixed FAP. This turns out to be the likelihood ratio.

whereful to the volume I (i.e., choose the best region to mak the ROC corres).

heuristically 
$$\Rightarrow x = \frac{P(x|x_ix)}{P(x|noises)}$$
 $x = \frac{P(x|x_ix)}{P(x|noises)}$ 

regions are bounded by surfaces of constant

- i. a "likelihood ratio test" (ranks events by P(XIS)/P(XIN))
  is the optimal detection statistic.
- M.b. Bayer factors are likelihood rations!

but they are often too expensive to be used in low-level processing...

=> we nearly to maximisation rather than marginalization

Now, let's consider a "realistic scenario" and derive a maximum - likelihood search

Assume Stutionone, Gravesson additive notice such that

Doserved data Norse signed with known shape he with unknown amplitude A

$$P(x|sig) = P(x|Ah)$$

$$= P(h = x-Ah) \sim exp(-\frac{1}{2}[4\int_{S}^{a}df \frac{|\tilde{x}-A\tilde{h}|^{2}}{5}])$$

$$P(x|no;x) = P(x|A=0)$$
  
=  $P(x=x) \sim exp(-\frac{1}{2}[4\int_{0}^{x}df \frac{|x|^{2}}{3}])$ 

construct log-likelihood recto

this would define our decision surface if we knew A. But, since we don't, let's maximise this will A

1.e., what is the value of A that would make us most likely to reject the null hypothests?

$$\hat{A} = \begin{bmatrix} 4 \hat{S} & \frac{Re}{3} \hat{X} + \hat{K} \\ \frac{S}{3} \end{bmatrix}$$

$$\frac{3}{4} \hat{S} & \frac{Re}{3} \hat{X} + \hat{K} \hat{S}$$

(it is conventional to define this of factors of 4) we more commonly deal of the signal-to-noise rutio

This is a likeur filter and can be compited in either the time or the frequency domatho

morting (grt160m)

Note that, if the signal model can additionably be written at " Acit h"

then it is possible to maximize over both A and &

Additionally, b/c × 15 Gaussian, we can analytically compute the behavior of leget, ; e

e non-control x-distributed w/2 degrees of freedom

Unmodeled Boxst Searches

what is we don't have a model for the signal's shape?

maximize likelihard expresent to the signal amp i phase in each freq. bon separately!

The mathematics are not exceptionally more complicated, but this is a rather under-determined problem.

and other arrangtions are typicathy needed to make progress