5 — PHY 494: Homework assignment (33 points total)

Due Thursday, Feb 20, 2020, 11:59pm.

Submission is now to your **private GitHub repository**. Follow the link provided to you by the instructor in order for the repository to be set up: It will have the name ASU-CompMethodsPhysics-PHY494/assignments-2020-YourGitHubUsername and will only be visible to you and the instructor/TA. Follow the instructions below to submit this (and all future) homework.

Read the following instructions carefully. Ask if anything is unclear.

1. git clone your assignment repository (change YourGitHubUsername to your GitHub username)

```
repo="assignments-2020-YourGitHubUsername.git"
git clone https://github.com/ASU-CompMethodsPhysics-PHY494/${repo}
```

2. run the script ./scripts/update.sh (replace YourGitHubUsername with your GitHub username):

```
cd ${repo}
bash ./scripts/update.sh
```

It should create three subdirectories assignment_05/Submission, assignment_05/Grade, and assignment_05/Work.

- 3. You can try out code in the assignment_05/Work directory but you don't have to use it if you don't want to. Your grade with comments will appear in assignment_05/Grade.
- 4. Create your solution in assignment_05/Submission. Use Git to git add files and git commit changes.

¹If the script fails, file an issue in the Issue Tracker for PHY494-assignments-skeleton and just create the directories manually.

You can create a PDF, a text file or Jupyter notebook inside the assignment_05/Submission directory as well as Python code (if required). Name your files hw05.pdf or hw05.txt or hw05.ipynb, depending on how you format your work. Files with code (if requested) should be named exactly as required in the assignment.

5. When you are ready to submit your solution, do a final git status to check that you haven't forgotten anything, commit any uncommited changes, and git push to your GitHub repository. Check on your GitHub repository web page² that your files were properly submitted.

You can push more updates up until the deadline. Changes after the deadline will not be taken into account for grading.

Homeworks must be legible and intelligible and on-time or may be returned ungraded with 0 points.

Bonus problems This assignment contains **bonus problems**. A bonus problem is optional. If you do it you get additional points that count towards this homework's total, although you can't get more than the maximum number of points. If you don't do it you can still get full points. Bonus problems and bonus points are indicated with an asterisk "*".

Included code and tests The homework comes with starter code in the
Submission directory. Edit and submit code as directed in the problems.
 The directory also includes a file test_hw5.py. You can use these tests
to check if your solutions are correct:

pytest -v test_hw5.py

(If you solved all coding problems, you should see "9 passed"; if you also solved the Bonus problem 5.3(c) you should see "7 xpassed". Otherwise you will be informed which problems failed.)

 $^{^2 \}texttt{https://github.com/ASU-CompMethodsPhysics-PHY494/assignments-2020-} Your \textit{GitHubUsername} \\$

5.1 NumPy arrays (11 points)

import numpy as np

Work through the NumPy tutorial.³ Do the examples while you read it.

- (a) How do NumPy array operations such as +, -, *, / ... differ from linear algebra operations (i.e. scalar product, vector/matrix multiplication, ...)? [2 points]
- (b) For the following, add your code to the file problem1.py. Given the three arrays

```
sx = np.array([[0, 1], [1, 0]])
sy = np.array([[0, -1j],[1j, 0]])
sz = np.array([[1, 0], [0, -1]])
```

- (i) What is the result of result1b1 = sx * sy * sz? Explain what NumPy array multiplication does to the arrays. (Note: your code should assign the result to the variable result1b1 in problem1.py.) [2 points]
- (ii) Use np.dot() to multiply the three arrays (like $\sigma_x \cdot \sigma_y \cdot \sigma_z$). Add your code to problem1.py and assign your result to variable result1b2 Show your result and explain what happened. [2 points]
- (iii) Compute the "commutator" $[\sigma_x, \sigma_y] := \sigma_x \cdot \sigma_y \sigma_y \sigma_x$ and show that it equals $2i\sigma_z$.⁴ Add your code to problem1.py, assign the result to variable result1b3. [3 points]

³Some stuff such as the ix_() function is fairly esoteric for beginners but almost everything else is what you should be familiar with for your daily work with arrays.

⁴These are the Pauli matrices that describe the three components of the spin operator for a spin 1/2 particle, $\hat{\mathbf{S}} = \frac{\hbar}{2}\boldsymbol{\sigma}$. The fact that any two components of the spin operator do *not* commute is a fundamental aspect of quantum mechanics.

(iv) Given a "state vector"

$$\mathbf{v} = \frac{1}{\sqrt{2}} \left(\begin{array}{c} 1 \\ -i \end{array} \right)$$

calculate the "expectation value" $\mathbf{v}^{\dagger} \cdot \sigma_y \cdot \mathbf{v}$ (i.e., the multiplication of the hermitian conjugate of the vector, \mathbf{v}^{\dagger} with the matrix σ_y and the vector \mathbf{v} itself) using NumPy. ⁵ Add your code to problem1.py and assign your result to variable result1b4.⁶) [2 points]

5.2 Coordinate manipulation with NumPy (16 points)

We can represent the cartesian coordinates $\mathbf{r}_i = (x_i, y_i, z_i)$ for four particles as a numpy array positions:

```
import numpy as np
positions = np.array(\
    [[0.0, 0.0, 0.0], [1.34234, 1.34234, 0.0], \
    [1.34234, 0.0, 1.34234], [0.0, 1.34234, 1.34234]])
t = np.array([1.34234, -1.34234, -1.34234])
```

and t will be a translation vector. For the following use NumPy. Add your code to file problem2.py and assign results to variables as indicated in the problems.

(a) What is the *shape* of the array **positions** and what is its *dimension*? [1 **points**]

⁵The hermitian conjugate $\mathbf{v}^{\dagger} = (v_1^*, v_2^*)$ is $\mathbf{v}.\mathsf{conjugate}().\mathsf{T}$ where $\mathbf{v}.\mathsf{T}$ is shorthand for $\mathbf{v}.\mathsf{transpose}()$. It turns out that you don't need the transposition when you use $\mathsf{np.dot}()$ but I include it here for conceptual clarity. (Including $\mathsf{transpose}()$ comes at a minor performance penalty — check with $\mathsf{%timeit}$ if you are curious.)

⁶Note for anyone having done PHY 315 (Quantum Mechanics II) that here you are calculating the quantum mechanical expectation value of the y-component of a spin $\frac{1}{2}$ particle in an eigenstate of the operator of the y-component of the spin $(\sigma_y \mathbf{v} = -\mathbf{v})$ and because \mathbf{v} is normalized, you should get the eigenvalue as the expectation value.

- (b) What is the *shape* of the array t and what is its *dimension*? [1 points]
- (c) How do you access the coordinates of the second particle in positions? Assign the result to variable result2c. [1 points]
- (d) For the second particle:
 - (i) How do you access its y-coordinate? Assign the result to variable result2d. [2 points]
 - (ii) What type of object is this output, what is its *shape* and its *dimension*? [2 points]
- (e) Write Python code to translate all particles by a vector t = (1.34234, -1.34234, -1.34234),
 t = np.array([1.34234, -1.34234, -1.34234])
 Add your code to problem2.py and assign the translated coordinates to variable result2e. [3 points]
- (f) Make your solution of (e) a function translate(coordinates, t), which translates all coordinates in the argument coordinates (an np.array of shape (N, 3)) by the translation vector in t. The function should return the translated coordinates as a numpy array. Add the function to problem2.py. Show the results of the function applied to (1) the input positions and t from above and (2) for positions2 = np.array([[1.5, -1.5, 3], [-1.5, -1.5, -3]]) and t = np.array([-1.5, 1.5, 3]). [6 points]

5.3 NumPy functions (6 points)

(a) We want to plot the function ⁷

$$\operatorname{sinc}(x) := \frac{\sin(\pi x)}{\pi x} \tag{1}$$

over the range $-6 \le x < 6$.

⁷This is the definition used in numpy.sinc function.

- Use the NumPy arange() function to generate an array X with values from -6 to 6 in steps of 0.2, excluding the upper boundary.⁸.
- Apply the NumPy sinc() function to the X array and assign it to a variable Y.
- Plot your data with matplotlib

```
import matplotlib.pyplot as plt
plt.plot(X, Y)
plt.xlabel("x")
plt.ylabel("y = sinc(x)")
plt.savefig("sinc.png")  # write plot to file
```

Submit your code as file problem3a.py together with the plot in file sinc.png. [4 points]

(b) Use the NumPy arange(), the sum(), and the sqrt() functions to calculate the sum¹⁰

$$S = \sqrt{\sum_{n=1}^{100} \frac{6}{n^2}}. (2)$$

Put your code into file problem3b.py and assign the result to a variable mypi. [2 points]

$$\sum_{k=1}^{\infty} \frac{1}{k^2} = \frac{\pi^2}{6}.$$

⁸You don't have to include the upper endpoint 6 in the range because this can be difficult to achieve with arange() and a floating point step; as an alternative you can look into using numpy.linspace().

⁹You do *not* need any loops. Try numpy.sinc(X) and embrace NumPy!

 $^{^{10}\}mathrm{You}$ can compare your result to the analytical solution

(c) Bonus: : Write a function to approximate the real-valued Riemann Zeta function

$$\zeta(s) = \sum_{k=1}^{\infty} \frac{1}{k^s} \tag{3}$$

with the finite sum up to N_{max} as

$$\zeta(s) \approx \zeta(s; N_{\text{max}}) := \sum_{k=1}^{N_{\text{max}}} \frac{1}{k^s}$$
(4)

Add your function zeta(s, Nmax=1000) to a file problem3c.py and plot $\zeta(s)$ in the range $1 < s \le 10$ and for a range of $N_{\rm max}$ and include a figure of the plot zeta.png. [bonus +4*]

You can plot multiple graphs within the same plot and add a legend with matplotlib:

```
import numpy as np
import matplotlib.pyplot as plt

def zeta(s, Nmax=1000):
    """Approximation to the real Riemann zeta function"""
    # add your code ...

s = np.arange(1, 10, 0.1)
Nmax_values = np.array([10, 100, 1000, 100000])

fig = plt.figure(figsize=(6, 6))  # new figure
ax = fig.add_subplot(111)  # add "axes", i.e., graph to figure

# plot each graph into the same axes and label by Nmax
for Nmax in Nmax_values:
    ax.plot(s, zeta(s, Nmax=Nmax), label="Nmax="+str(Nmax))
```

¹¹Note that the sum in problem (b) $\sum_{k=1}^{\infty} \frac{1}{k^2} = \frac{\pi^2}{6}$ is equal to $\zeta(2)$...

```
# finish the axes by adding labels and legend
ax.set_xlabel(r"$$$")  # fancy LaTeX typeset label
ax.set_ylabel(r"$\zeta(s)$")  # fancy LaTeX typeset label
ax.legend(loc="best")  # place legends

fig.savefig("zeta.png")

(Add the label="something" keyword to the plot() method, plot
everything into the same graph (called an "axes" in matplotlib), and
then call the legend() method and save the figure.)
```